# Program Analysis (70020)

#### Correctness of an Analysis

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#### Correctness

Questions: Is a program analysis correct? Are the results reflecting what is really happening when the program is run?

In other words: What is the relation between the (concrete) semantics of a program, i.e. the transition relation  $\Rightarrow$  and/or its transitive closure  $\Rightarrow^*$ , and the (solutions to) the program analysis  $Analysis_{\circ}$  and  $Analysis_{\bullet}$ .

For example: Is a variable *LV* identifies as 'live' indeed useful, or more importantly, is a 'non-live' variable really 'dead', i.e. is it save to eliminate it (at least locally).

# Syntax of WHILE

The labelled syntax of the language WHILE is given by the following abstract syntax:

```
a ::= x | n | a_1 op_a a_2
b ::= true | false | not b | b_1 op_b b_2 | a_1 op_r a_2
S ::= [x := a]^{\ell} 
| [skip]^{\ell} 
| S_1; S_2 
| if [b]^{\ell} then S_1 else S_2
| while [b]^{\ell} do S
```

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### Sketches of a Formal Semantics

Memory is modelled by an abstract state, i.e. functions of type

State 
$$=$$
 Var  $\rightarrow$  Z.

For boolean and arithmetic expressions we assume that we know what they "evaluate to" in a state  $s \in$  **State**. Then the semantics for **AExp** is a *total* function

$$\llbracket \cdot \rrbracket_{\mathcal{A}} \cdot : AExp \rightarrow State \rightarrow Z$$

and the semantics of boolean expressions is given by

$$\llbracket . \rrbracket_{\mathcal{B}} . : \mathsf{BExp} \to \mathsf{State} \to \{\mathsf{tt}, \mathsf{ff}\}$$

# **Evaluating Expressions**

Let us look at a program with two variables  $Var = \{x, y\}$ . Two possible states in this case could be for example:

$$s_0 = [x \mapsto 0, y \mapsto 1]$$
 and  $s_1 = [x \mapsto 1, y \mapsto 1]$ 

We can evaluate an expression like  $x + y \in AExp$ :

$$[x + y]_A s_0 = 0 + 1 = 1$$
  
 $[x + y]_A s_1 = 1 + 1 = 2$ 

or a Boolean expression like  $x + y \le 1 \in \mathbf{BExp}$ :

$$[x + y \le 1]_{\mathcal{B}} s_0 = 1 \le 1 = \mathbf{tt}$$
  
 $[x + y \le 1]_{\mathcal{B}} s_1 = 2 \le 1 = \mathbf{ff}$ 

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#### **Execution and Transitions**

The configurations describe the current state of the execution.

 $\langle S, s \rangle$  ... S is to be executed in state s, s ... a terminal state (i.e.  $\langle ., s \rangle$ ).

The transition relation ⇒ specify the (possible) computational steps during the execution starting from a certain configuration

$$\langle S, s \rangle \Rightarrow \langle S', s' \rangle$$

and at the end of the computation

$$\langle S, s \rangle \Rightarrow s'$$

# Execution Rules (SOS) [Provided in Exam]

(ass) 
$$\langle [skip]^{\ell}, s \rangle \Rightarrow s[x \mapsto [a]]_{\mathcal{A}}s]$$
  
(skip)  $\langle [skip]^{\ell}, s \rangle \Rightarrow s$   
(sq<sup>1</sup>)  $\frac{\langle S_1, s \rangle \Rightarrow \langle S_1', s' \rangle}{\langle S_1; S_2, s \rangle \Rightarrow \langle S_1'; S_2, s' \rangle}$   
(sq<sup>T</sup>)  $\frac{\langle S_1, s \rangle \Rightarrow s'}{\langle S_1; S_2, s \rangle \Rightarrow \langle S_2, s' \rangle}$   
(if<sup>T</sup>)  $\langle \text{if } [b]^{\ell} \text{ then } S_1 \text{ else } S_2, s \rangle \Rightarrow \langle S_1, s \rangle$  if  $[\![b]\!]_{\mathcal{B}}s = \text{tt}$   
(if<sup>F</sup>)  $\langle \text{if } [b]^{\ell} \text{ then } S_1 \text{ else } S_2, s \rangle \Rightarrow \langle S_2, s \rangle$  if  $[\![b]\!]_{\mathcal{B}}s = \text{ff}$   
(wh<sup>T</sup>)  $\langle \text{while } [b]^{\ell} \text{ do } S, s \rangle \Rightarrow \langle S; \text{ while } [b]^{\ell} \text{ do } S, s \rangle$  if  $[\![b]\!]_{\mathcal{B}}s = \text{tt}$   
(wh<sup>F</sup>)  $\langle \text{while } [b]^{\ell} \text{ do } S, s \rangle \Rightarrow s$  if  $[\![b]\!]_{\mathcal{B}}s = \text{ff}$ 

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# A SOS Example

Consider a (perhaps rather vacuous) program like:

$$S \equiv [z := x + y]^{\ell}$$
; while  $[true]^{\ell'}$  do  $[skip]^{\ell''}$   $s_0 = [x \mapsto 0, y \mapsto 1, z \mapsto 0]$  and  $s_1 = [x \mapsto 0, y \mapsto 1, z \mapsto 1]$ 

Then  $\langle S, s_0 \rangle$  executes as follows:

$$\begin{array}{ll} \langle \mathcal{S}, s_0 \rangle & \Rightarrow & \langle \text{while } [\textit{true}]^{\ell'} \text{ do } [\text{ skip }]^{\ell''}, s_1 \rangle \\ & \Rightarrow & \langle [\text{ skip }]^{\ell''}; \text{ while } [\textit{true}]^{\ell'} \text{ do } [\text{ skip }]^{\ell''}, s_1 \rangle \\ & \Rightarrow & \langle \text{while } [\textit{true}]^{\ell'} \text{ do } [\text{ skip }]^{\ell''}, s_1 \rangle \\ & \Rightarrow & \langle [\text{ skip }]^{\ell''}; \text{ while } [\textit{true}]^{\ell'} \text{ do } [\text{ skip }]^{\ell''}, s_1 \rangle \\ & \Rightarrow & \dots \end{array}$$

- (i) If  $\langle S, s \rangle \Rightarrow s'$  then  $final(S) = \{init(S)\}.$
- (ii) If  $\langle S, s \rangle \Rightarrow \langle S', s' \rangle$  then  $final(S) \supseteq final(S')$ .
- (iii) If  $\langle S, s \rangle \Rightarrow \langle S', s' \rangle$  then  $flow(S) \supseteq flow(S')$ .
- (iv) If  $\langle S, s \rangle \Rightarrow \langle S', s' \rangle$  then  $blocks(S) \supseteq blocks(S')$ .
- (v) If  $\langle S, s \rangle \Rightarrow \langle S', s' \rangle$  then S label consistent implies S' label consistent.

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# Lemma 1 - Proof (i) [Not for Exam]

#### Proof.

The proof is by induction on the shape of the inference tree. Consider the only three non-vacuous cases:

(ass): 
$$\langle [x := a]^{\ell}, s \rangle \Rightarrow s[x \mapsto \llbracket a \rrbracket s]$$

$$final([x := a]^{\ell}) = \{\ell\} = \{init([x := a]^{\ell})\}.$$
(skip):  $\langle [skip]^{\ell}, s \rangle \Rightarrow s$ 

$$final([skip]^{\ell}) = \{\ell\} = \{init([skip]^{\ell})\}.$$
(wh<sup>F</sup>):  $\langle while [b]^{\ell} do S, s \rangle \Rightarrow s with \llbracket b \rrbracket = false$ 

$$final(while [b]^{\ell} do S) = \{\ell\} = \{init(while [b]^{\ell} do S)\}.$$

# Lemma 1 - Proof (ii) [Not for Exam]

Proof (cont).

```
 \begin{split} (\mathsf{seq}^1) &: \ \langle S_1; S_2, s \rangle \Rightarrow \langle S_1'; S_2, s' \rangle \ \mathsf{because} \\ & \ \langle S_1, s \rangle \Rightarrow \langle S_1', s' \rangle \\ & \ \mathit{final}(S_1; S_2) = \mathit{final}(S_2) = \mathit{final}(S_1'; S_2). \\ (\mathsf{seq}^T) &: \ \ldots \\ & (\mathsf{if}^T) &: \ \langle \mathsf{if} \ [b]^\ell \ \mathsf{then} \ S_1 \ \mathsf{else} \ S_2, s \rangle \Rightarrow \langle S_1, s \rangle \\ & \ \mathsf{with} \ [\![b]\!] = \mathbf{true} &: \\ & \ \mathit{final}(\mathsf{if} \ [b]^\ell \ \mathsf{then} \ S_1 \ \mathsf{else} \ S_2) = \\ & \ \mathit{final}(S_1) \cup \mathit{final}(S_2) \supseteq \mathit{final}(S_1). \\ & (\mathsf{if}^F) &: \ \ldots \\ & (\mathsf{wh}^T) &: \ \ldots \end{aligned}
```

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# LV Equations: LV

The Live Variable Analysis is given as the solution to the following system of equations:

$$\mathsf{LV}_{\textit{exit}}(\ell) = \begin{cases} \emptyset, \text{if } \ell \in \textit{final}(S_{\star}) \\ \bigcup \{\mathsf{LV}_{\textit{entry}}(\ell') \mid (\ell', \ell) \in \textit{flow}^R(S_{\star})\}, \text{otherwise} \end{cases}$$

$$\mathsf{LV}_{\mathit{entry}}(\ell) = (\mathsf{LV}_{\mathit{exit}}(\ell) \setminus \mathit{kill}_{\mathsf{LV}}([B]^{\ell}) \cup \mathit{gen}_{\mathsf{LV}}([B]^{\ell})$$
  
where  $[B]^{\ell} \in \mathit{blocks}(S_{\star})$ 

# Solutions via Iteration Operator

becomes a function on the lattice  $\mathcal{P}(\mathbf{Var})^{2n}$ 

$$\mathbf{F}: \mathcal{P}(\mathbf{Var})^{2n} \to \mathcal{P}(\mathbf{Var})^{2n}$$

$$\mathbf{F}_{i}^{\bullet}(\mathsf{LV}_{entry}(1), \dots, \mathsf{LV}_{exit}(n)) = \mathsf{LV}_{entry}(i)$$

$$\mathbf{F}_{i}^{\circ}(\mathsf{LV}_{entry}(1), \dots, \mathsf{LV}_{exit}(n)) = \mathsf{LV}_{exit}(i)$$

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# LV Constraints: LV=

The Live Variable Analysis is equivalently given as the solution to the following system of constraints:

$$\mathsf{LV}_{\textit{exit}}(\ell) \ \supseteq \ \left\{ \begin{array}{l} \emptyset, \text{if } \ell \in \textit{final}(\mathcal{S}_{\star}) \\ \bigcup \{\mathsf{LV}_{\textit{entry}}(\ell') \mid (\ell',\ell) \in \textit{flow}^R(\mathcal{S}_{\star})\}, \text{otherwise} \end{array} \right.$$

$$\mathsf{LV}_{\mathit{entry}}(\ell) \supseteq (\mathsf{LV}_{\mathit{exit}}(\ell) \setminus \mathit{kill}_{\mathsf{LV}}([\ensuremath{\mathcal{B}}]^\ell) \cup \mathit{gen}_{\mathsf{LV}}([\ensuremath{\mathcal{B}}]^\ell) \ \ \, \text{where } [\ensuremath{\mathcal{B}}]^\ell \in \mathit{blocks}(\ensuremath{\mathcal{S}_\star})$$

# LV Solutions to LV and LV

Consider collections *live* = (*live*<sub>entry</sub>, *live*<sub>exit</sub>) of functions:

$$\textit{live}_{\mathsf{entry}}: \mathbf{Lab}_{\star} o \mathcal{P}(\mathbf{Var}_{\star}) \ \textit{live}_{\mathsf{exit}}: \mathbf{Lab}_{\star} o \mathcal{P}(\mathbf{Var}_{\star})$$

If *live* solves  $LV^{=}$  for a statement S we write:

$$live \models LV^{=}(S)$$

If *live* solves  $LV^{\subseteq}$  for a statement S we write:

live 
$$\models LV^{\subseteq}(S)$$

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### Theorem 1

Given a label consistent program  $S_{\star}$ .

lf

▶ live 
$$\models LV^{=}(S_{\star})$$

then

▶ live 
$$\models LV^{\subseteq}(S_{\star})$$
.

That is: The least solution of  $LV^{=}(S_{\star})$  coincides with the least solution to  $LV^{\subseteq}(S_{\star})$ .

# Theorem 1 - Proof [Not for Exam]

#### Proof.

If  $live \models LV^{=}(S_{\star})$  also  $live \models LV^{\subseteq}(S_{\star})$  as " $\supseteq$ " includes "=".

To show that  $LV^{=}(S_{\star})$  and  $LV^{\subseteq}(S_{\star})$  have the same least solution consider the iteration operator  $\mathbf{F} = \mathbf{F}_{LV}^{S} = \mathbf{F}_{LV}^{S}$ 

$$live \models LV^{\subseteq}(S_{\star}) \quad iff \quad live \supseteq \mathbf{F}(live)$$
  
 $live \models LV^{=}(S_{\star}) \quad iff \quad live = \mathbf{F}(live)$ 

By Tarski's Fixed Point Theorem we have:

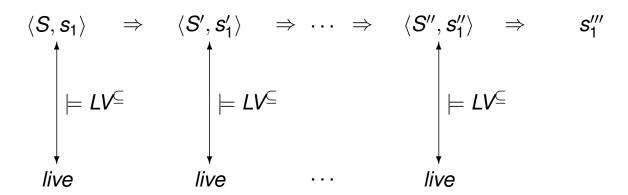
$$\textit{lfp}(\textbf{F}) = \bigcap \{\textit{live} \mid \textit{live} \supseteq \textbf{F}(\textit{live})\} = \bigcap \{\textit{live} \mid \textit{live} = \textbf{F}(\textit{live})\}.$$

Since  $lfp(\mathbf{F}) = \mathbf{F}(lfp(\mathbf{F}))$  and  $lfp(\mathbf{F}) \supseteq \mathbf{F}(lfp(\mathbf{F}))$  we see that we get the same least solutions.

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#### Preservation of Solution

During the (actual) execution of any program  $S_*$  a solution to the Live Variable analysis  $LV^{\subseteq}(S_*)$  remains a solution.



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Given a label consistent program  $S_1$ .

lf

- ▶  $live \models LV^{\subseteq}(S_1)$  and
- ►  $flow(S_1) \supseteq flow(S_2)$  and
- ▶  $blocks(S_1) \supseteq blocks(S_2)$

then

▶ live  $\models LV^{\subseteq}(S_2)$ 

with  $S_2$  being label consistent.

#### Proof [Not for Exam].

If  $S_1$  is label consistent and  $blocks(S_1) \supseteq blocks(S_2)$  then  $S_2$  is also label consistent.

If  $live \models LV^{\subseteq}(S_1)$  then live also satisfy each constraint in  $LV^{\subseteq}(S_2)$  and hence  $live \models LV^{\subseteq}(S_2)$ .

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### Lemma 3

Given a label consistent program S.

lf

- ► live  $\models LV^{\subseteq}(S)$  and
- $\blacktriangleright \langle S, s \rangle \Rightarrow \langle S', s' \rangle$

then

▶ live  $\models LV^{\subseteq}(S')$ .

#### Proof [Not for Exam].

Follows directly from Lemma 1 and Lemma 2.

Given a label consistent program S.

lf

▶ live  $\models LV^{\subseteq}(S)$ 

then for all  $(\ell, \ell') \in \mathit{flow}(S)$  we have:

ightharpoonup live<sub>exit</sub>( $\ell$ )  $\supseteq$  live<sub>entry</sub>( $\ell'$ )

### Proof [Not for Exam].

Follows immediately from the construction of  $LV^{\subseteq}(S)$ .

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#### Correctness Relation

Assume that *V* is a set of *live variables*.

Define the correctness relation via

$$s_1 \sim_V s_2 \text{ iff } \forall x \in V : s_1(x) = s_2(x).$$

In other word:

Two states are equivalent iff for all live variables – i.e. all "practical purposes" – the states  $s_1$  and  $s_2$  agree on the variables in V.

## Example

Consider 
$$[x := y + z]^{\ell}$$
 and  $V_1 = \{y, z\}$  and  $V_2 = \{x\}$ .  $s_1 \sim_{V_1} s_2$  means  $s_1(y) = s_2(y) \land s_1(z) = s_2(z)$ .  $s_1 \sim_{V_2} s_2$  means  $s_1(x) = s_2(x)$ .

Assume 
$$\langle [x:=y+z]^\ell, s_1 \rangle \Rightarrow s_1', \, \langle [x:=y+z]^\ell, s_2 \rangle \Rightarrow s_2'$$
 then  $s_1 \sim_{V_1} s_2$  ensures  $s_1' \sim_{V_2} s_2'$ .

If  $V_2 = \mathsf{LV}_{exit}(\ell)$  thus is the set of live variables after  $[x := y + z]^\ell$  then  $V_1 = \mathsf{LV}_{entry}(\ell)$  is the set of live variables before  $[x := y + z]^\ell$ .

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## Correctness of LV Analysis

Short-hand notation:  $N(\ell) = live_{entry}(\ell)$  and  $X(\ell) = live_{exit}(\ell)$ .

Given a label consistent program S.

lf

▶ live 
$$\models LV^{\subseteq}(S)$$

then

 $lacksquare s_1 \sim_{\mathit{live}_{\mathsf{exit}}(\ell)} s_2 ext{ implies } s_1 \sim_{\mathit{live}_{\mathsf{entry}}(\ell')} s_2 ext{ for all } \ (\ell,\ell') \in \mathit{flow}(S).$ 

#### Proof [Not for Exam].

Follows directly from Lemma 4 and the definition of  $\sim_V$ .

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### Theorem 2

Given a label consistent program S.

lf

▶ live 
$$\models LV^{\subseteq}(S)$$

then

- (i) If  $\langle S, s_1 \rangle \Rightarrow \langle S', s'_1 \rangle$  and  $s_1 \sim_{\textit{live}_{entry}(\textit{init}(S))} s_2$  then there exists  $s'_2$  such that  $\langle S, s_2 \rangle \Rightarrow \langle S', s'_2 \rangle$  and  $s'_1 \sim_{\textit{live}_{entry}(\textit{init}(S'))} s'_2$ .
- (ii) If  $\langle S, s_1 \rangle \Rightarrow s_1'$  and  $s_1 \sim_{\textit{live}_{entry}(\textit{init}(S))} s_2$  then there exists  $s_2'$  such that  $\langle S, s_2 \rangle \Rightarrow s_2'$  and  $s_1' \sim_{\textit{live}_{exit}(\textit{init}(S))} s_2'$ .

# Theorem 2 - Proof [Not for Exam]

#### Proof.

The proof is by induction on the shape of the inference tree.

```
(ass): ...

(skip): ...

(seq<sup>1</sup>): ...

(seq<sup>T</sup>): ...

(if<sup>T</sup>): ...

(if<sup>F</sup>): ...

(wh<sup>T</sup>): ...

(wh<sup>F</sup>): ...
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# Theorem 2 - Proof (ass) [Not for Exam]

Proof (cont).

The proof is by induction on the shape of the inference tree.

(ass): We have  $\langle [x := a]^{\ell}, s_1 \rangle \Rightarrow s_1[x \mapsto [a]s_1]$  and from the specification of the constraints:

$$live_{entrv}(\ell) = (live_{exit}(\ell) \setminus \{x\}) \cup FV(a)$$

and therefore

$$s_1 \sim_{ extit{live}_{ ext{entry}}(\ell)} s_2 ext{ implies } \llbracket a 
rbracket (s_1) = \llbracket a 
rbracket (s_2)$$

because the value of *a* depends only on variables in it.

Thus with 
$$s_2' = s_2[x \mapsto [a]_A s_2]$$
 we have  $s_1'(x) = s_2'(x)$  and thus  $s_1' \sim_{\textit{live}_{exit}(\ell)} s_2'$ .

# Theorem 2 - Proof (skip) [Not for Exam]

Proof (cont).

(skip): We have  $\langle [skip]^{\ell}, s_1 \rangle \Rightarrow s_1$  and from the specification of the constraints we get:

$$\mathit{live}_{\mathsf{entry}}(\ell) = (\mathit{live}_{\mathsf{exit}}(\ell) \backslash \emptyset) \cup \emptyset = \mathit{live}_{\mathsf{exit}}(\ell)$$

Thus taking  $s_2'$  to be  $s_2$  we get  $s_1' \sim_{\textit{live}_{exit}(\ell)} s_2'$  as required.

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# Theorem 2 - Proof (seq1) [Not for Exam]

Proof (cont).

(seq<sup>1</sup>): We have 
$$\langle S_1; S_2, s_1 \rangle \Rightarrow \langle S'_1; S_2, s'_1 \rangle$$
 because of  $\langle S_1, s_1 \rangle \Rightarrow \langle S'_1, s'_1 \rangle$ .

By construction we have  $flow(S_1; S_2) \supseteq flow(S_1)$  and also  $blocks(S_1; S_2) \supseteq blocks(S_1)$ , thus by Lemma 2  $live \models LV^{\subseteq}(S_1)$  and by the induction hypothesis there exists a  $s_2'$  such that

$$\langle S_1, s_2 
angle \Rightarrow \langle S_1', s_2' 
angle$$
 and  $s_1' \sim_{\mathit{live}_{\mathsf{entry}}(\mathit{init}(S_1'))} s_2'$ 

and the result follows.

# Theorem 2 - Proof (seq<sup>T</sup>) [Not for Exam]

Proof (cont).

(seq<sup>T</sup>): We have  $\langle S_1; S_2, s_1 \rangle \Rightarrow \langle S_2, s_1' \rangle$  because of  $\langle S_1, s_1 \rangle \Rightarrow s_1'$ . Again by Lemma 2, *live* is a solution to  $LV^\subseteq(S_1)$  and thus by induction hypothesis there exists a  $s_2'$  such that

$$\langle \mathcal{S}_1, \mathcal{s}_2 
angle \Rightarrow \mathcal{s}_2' ext{ and } \mathcal{s}_1' \sim_{\mathit{live}_{\mathsf{exit}}(\mathit{init}(\mathcal{S}_1))} \mathcal{s}_2'$$

Now we have:

$$\{(\ell, init(S_2)) \mid \ell \in final(S_1)\} \subseteq flow(S_1; S_2)$$

and by Lemma 1,  $final(S_1) = \{init(S_1)\}$ . Thus by Lemma 5

$$s_1' \sim_{\textit{live}_{entry}(\textit{init}(S_2))} s_2'$$

and the result follows.

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# Theorem 2 - Proof (if<sup>T</sup>) & (if<sup>F</sup>) [Not for Exam]

Proof (cont).

(if<sup>T</sup>): We have  $\langle \text{if } [b]^{\ell} \text{ then } S_1 \text{ else } S_2, s_1 \rangle \Rightarrow \langle S_1, s_1 \rangle$  with  $\llbracket b \rrbracket (s_1) = \textbf{true}$ . Since  $s_1 \sim_{\textit{live}_{\text{entry}}(\ell)} s_2$  and  $\textit{live}_{\text{entry}}(\ell) \supseteq FV(b)$  we also have  $\llbracket b \rrbracket (s_2) = \textbf{true}$  (the value of b is only dependent on the variables occurring in it) and thus

$$\langle exttt{if} \ [b]^\ell \ exttt{then} \ S_1 \ exttt{else} \ S_2, s_2 
angle \Rightarrow \langle S_1, s_2 
angle$$

From the constraints we get  $live_{entry}(\ell) \supseteq live_{exit}(\ell)$  and hence  $s_1 \sim_{live_{exit}(\ell)} s_2$ . Since  $(\ell, init(S_1)) \in flow(S)$  Lemma 5 gives  $s_1 \sim_{live_{entry}(init(S_1))} s_2$  as required.

 $(if^F)$ : similar to case  $(if^T)$ .

# Theorem 2 - Proof (wh<sup>T</sup>) [Not for Exam]

Proof (cont).

Since  $s_1 \sim_{\mathit{live}_{\mathsf{entry}}(\ell)} s_2$  and  $\mathit{live}_{\mathsf{entry}}(\ell) \supseteq \mathit{FV}(b)$  we also have  $\llbracket b \rrbracket(s_2) = \mathsf{true}$  and thus

$$\langle \mathtt{while}\ [b]^\ell \ \mathtt{do}\ S, s_2 
angle \Rightarrow \langle S; \ \mathtt{while}\ [b]^\ell \ \mathtt{do}\ S, s_2 
angle$$

Again since  $\mathit{live}_{\mathsf{entry}}(\ell) \supseteq \mathit{live}_{\mathsf{exit}}(\ell)$  we have  $s_1 \sim_{\mathit{live}_{\mathsf{exit}}(\ell)} s_2$  and then

$$s_1 \sim_{\mathit{live}_{\mathsf{entry}}(\mathit{init}(s))} s_2$$

from Lemma 5 as  $(\ell, init(S)) \in flow(while [b]^{\ell} do S).$ 

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# Theorem 2 - Proof (wh<sup>F</sup>) [Not for Exam]

Proof (cont).

(wh<sup>F</sup>): We have  $\langle \text{while } [b]^{\ell} \text{ do } S, s_1 \rangle \Rightarrow s_1 \text{ with } [b](s_1) = \text{false}.$ 

Since  $s_1 \sim_{\mathit{live}_{\mathsf{entry}}(\ell)} s_2$  and  $\mathit{live}_{\mathsf{entry}}(\ell) \supseteq \mathit{FV}(b)$  and we also have  $[\![b]\!](s_2) = \mathsf{false}$  and thus:

$$\langle \mathtt{while} \ [b]^\ell \ \mathtt{do} \ S, s_2 
angle \Rightarrow s_2.$$

From the specification of  $LV^{\subseteq}$  we have  $live_{entry}(\ell) \supseteq live_{exit}(\ell)$  and thus  $s_1 \sim_{live_{exit}(\ell)} s_2$ .

# Corollary 1

Given a label consistent program S.

lf

▶ live 
$$\models LV^{\subseteq}(S)$$

then

- (i) If  $\langle S, s_1 \rangle \Rightarrow^* \langle S', s'_1 \rangle$  and  $s_1 \sim_{\textit{live}_{entry}(\textit{init}(S))} s_2$  then there exists  $s'_2$  such that  $\langle S, s_2 \rangle \Rightarrow^* \langle S', s'_2 \rangle$  and  $s'_1 \sim_{\textit{live}_{entry}(\textit{init}(S'))} s'_2$ .
- (ii) If  $\langle S, s_1 \rangle \Rightarrow^* s_1'$  and  $s_1 \sim_{\textit{live}_{entry}}(\textit{init}(s))$   $s_2$  then there exists  $s_2'$  such that  $\langle S, s_2 \rangle \Rightarrow^* s_2'$  and  $s_1' \sim_{\textit{live}_{exit}(\ell)} s_2'$  for some  $\ell \in \textit{final}(S)$ .

### Proof [Not for Exam].

The proof is by induction on the length of the derivation sequences and uses Theorem 2.

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