

Link failure and two-phase commit

```

CHAN(From=0, To=1)
=(chan[From][To].send[m:Msg] -> CHAN[m]
 | step1 -> CHAN
 | step2 -> CHAN['null'])
),
CHAN[m:Msg]
=(chan[From][To].recv[m] -> CHAN
 | step1 -> CHAN
 | step2 -> CHAN[m]
 | step2 -> linkfail[From][To]->CHAN['null']
).

|| NETWORK = (forall[i:0..N-1][j:0..N-1]
  if (i!=j) then CHAN(i,j)
  || CLOCK
).

```

Distributed Algorithms

1

Atomic Commitment Properties - liveness

- **Weak Termination**: If there are **no failures**, then all processes eventually decide.

```

assert
WEAKTERM = ([forall[i:ID] (!CRASHED[i] && !LINKFAIL[i])
-> <>forall[i:ID] DECIDED[i])

```

This reads: if its always the case that all processes do not crash **and** **there are no link failures** then eventually all processes reach the decided state.

Distributed Algorithms

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Atomic Commitment Properties - safety

```

fluent
LINKFAIL[i:ID] = <linkfail[i].{{ID}}\{i}}, never>

```

Validity - 2:

If all processes vote yes, and there are **no failures**, then yes is the only possible decision value.

```

assert VALID_2
= ([forall[i:ID]
(VOTE[i]['yes'] && !CRASHED[i] && !LINKFAIL[i])
-> !ABORT[ID])

```

Distributed Algorithms

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Distributed two-phase commit

```

PARTICIPANT(id=0)
= (init->vote[id][v: {yes, no}] -> step1 -> SEND_ALL(id, v) ; ROUND1[v],
ROUND1[v: {yes, no, null}])
= (chan.{{[ID]}\{[id]}}. [id].recv[m:Msg]
-> if (v=='no') then ROUND1['no']
  else if (m=='no') then ROUND1['no']
  else if (m=='yes' && v=='yes') then ROUND1['yes']
  else if (m=='yes' && v=='null') then ROUND1['null']
  else if (m=='null' && (v=='yes' || v=='null')) then
ROUND1['null']
 | step1 -> ROUND2[v]
),
ROUND2[v: {yes, no, null}]
= DECIDE(id, v); ENDED,
ENDED
= ({step1, step2} -> ENDED)
+ {chan[id][id].recv[Msg], chan[id][id].send[Msg]}.

```

Distributed Algorithms

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