

(star)

(no star)

Chalice to Boogie

Program Verification for Object-Oriented Programs

Chinmay Kakatkar

```
class Car
{
    int fuel;

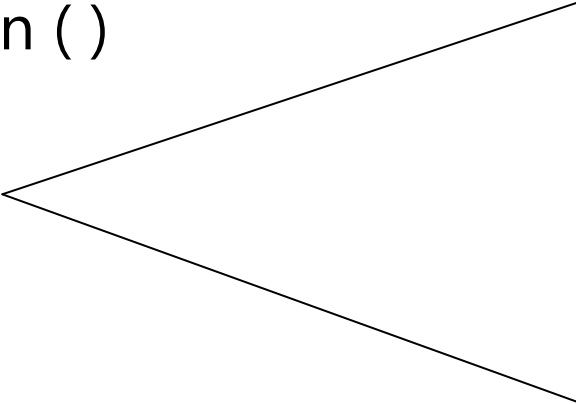
    void refuel ( int amount )
    {
        this.fuel := amount;
    }

    void main ( )
    {
        ...
    }
}
```

```
class Car
{
    int fuel;

    void refuel ( int amount )
    {
        this.fuel := amount;
    }
}
```

```
void main ( )
{
    ...
}
}
```

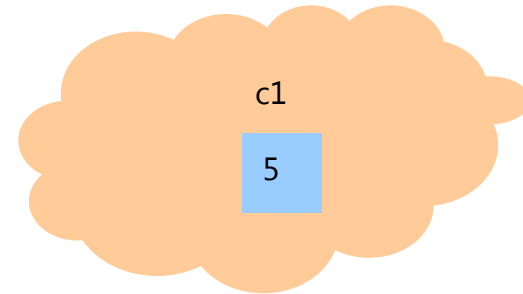
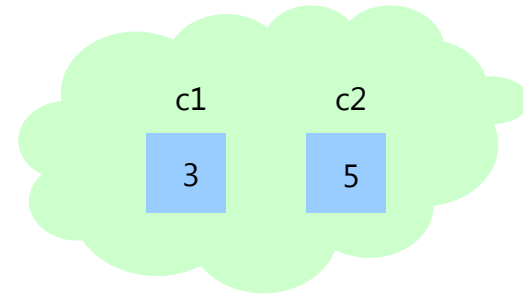


```
Car c1 := new Car ( );
Car c2 := new Car ( );
c1.refuel ( 3 );
c2.refuel ( 5 );
assert ( c1.fuel == 3 );
```

```
class Car
{
  int fuel;

  void refuel ( int amount )
  {
    this.fuel := amount;
  }

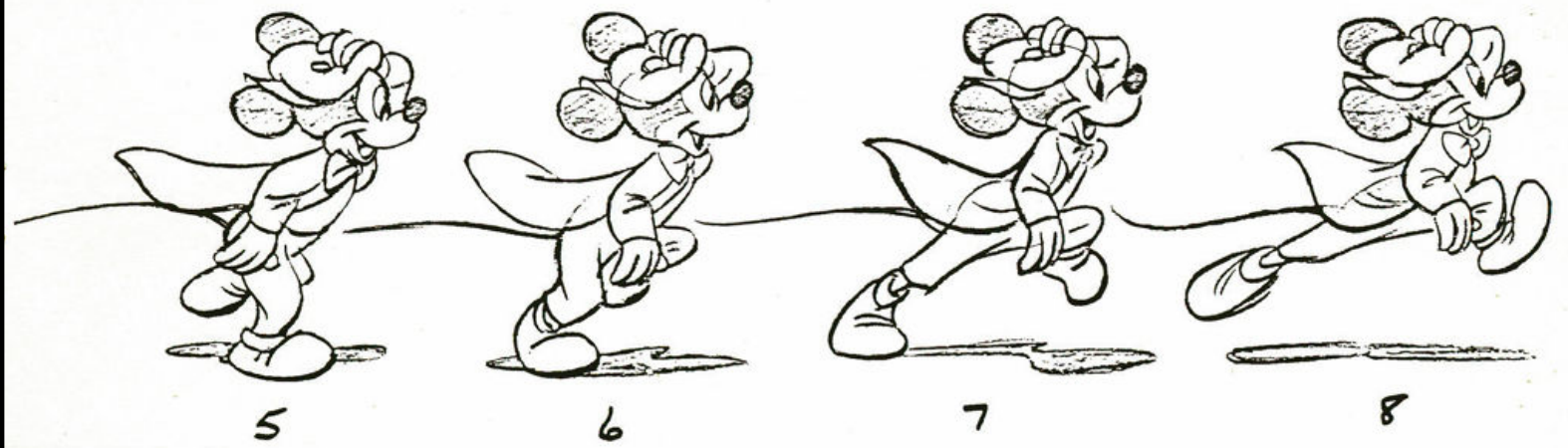
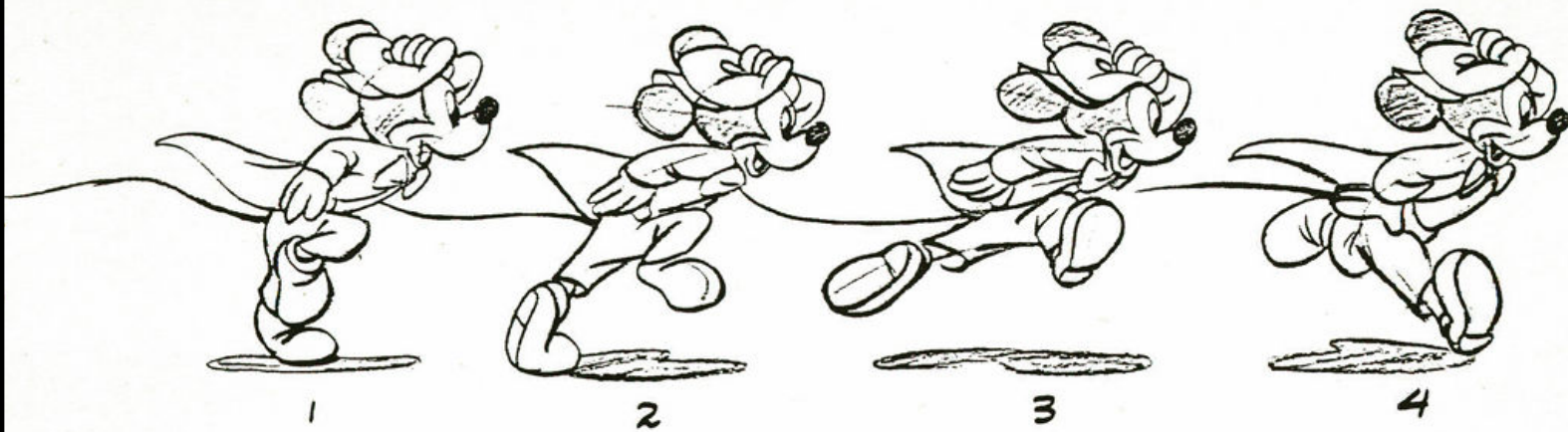
  void main ( )
  {
    ...
  }
}
```



```
Car c1 := new Car ();
Car c2 := new Car ();
c1.refuel ( 3 );
c2.refuel ( 5 );
assert ( c1.fuel == 3 );
```

The Problem is
Framing

MICKEY MOUSE / *run cycle*



(IN THIS ACTION — DRAWING NO 1 WOULD FOLLOW NO 8)



"We wish to ***logically represent how*** the execution of ***a command changes the state without having to explicitly say how the command does not change the state.***"

One Solution is
Implicit Dynamic Frames (IDF)

Theory: **Kassios (2006), Smans (2008)**

Implementation: **ETH, Microsoft Research, Leuven**



Car program in Chalice

```
class Car
```

```
{
```

```
  var fuel : int;
```

```
  void refuel (amount : int)
```

```
    requires acc (this.fuel);
```

```
    ensures acc (this.fuel) &*& this.fuel == amount;
```

```
  {
```

```
    this.fuel := amount;
```

```
  }
```

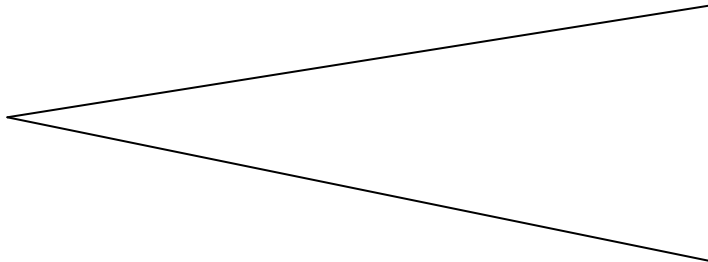
```
  void main ()
```

```
  {
```

```
    ...
```

```
  }
```

```
}
```



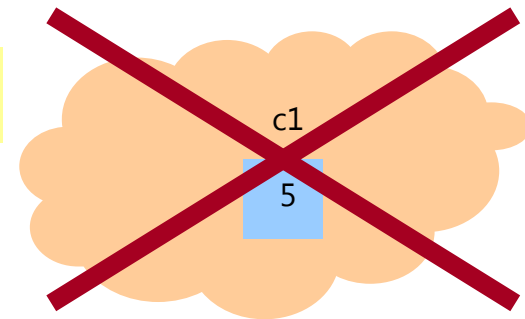
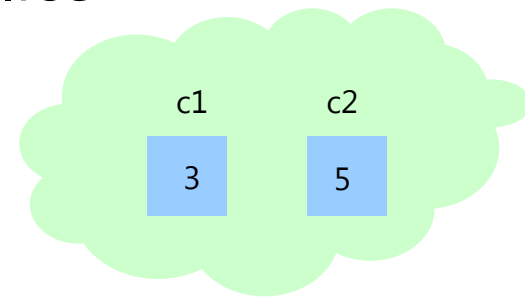
```
var c1 := new Car;  
var c2 := new Car;  
call c1.refuel ( 3 );  
call c2.refuel ( 5 );  
assert c1.fuel == 3;
```

Car program in Chalice

```
class Car
{
  var fuel : int;

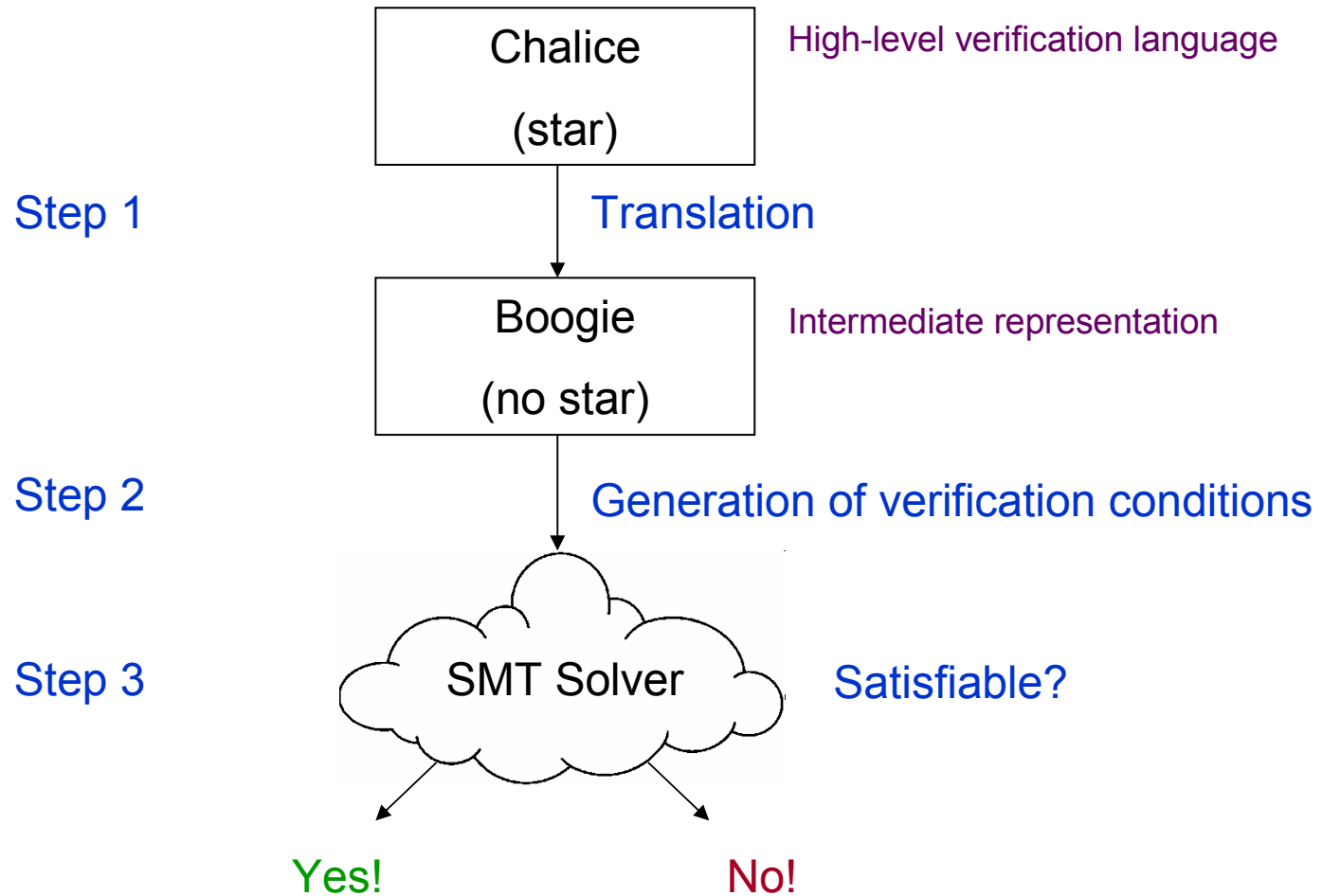
  void refuel (amount : int)
  requires acc (this.fuel);
  ensures acc (this.fuel) &*& this.fuel == amount;
  {
    this.fuel := amount;
  }

  void main ()
  {
    ...
  }
}
```

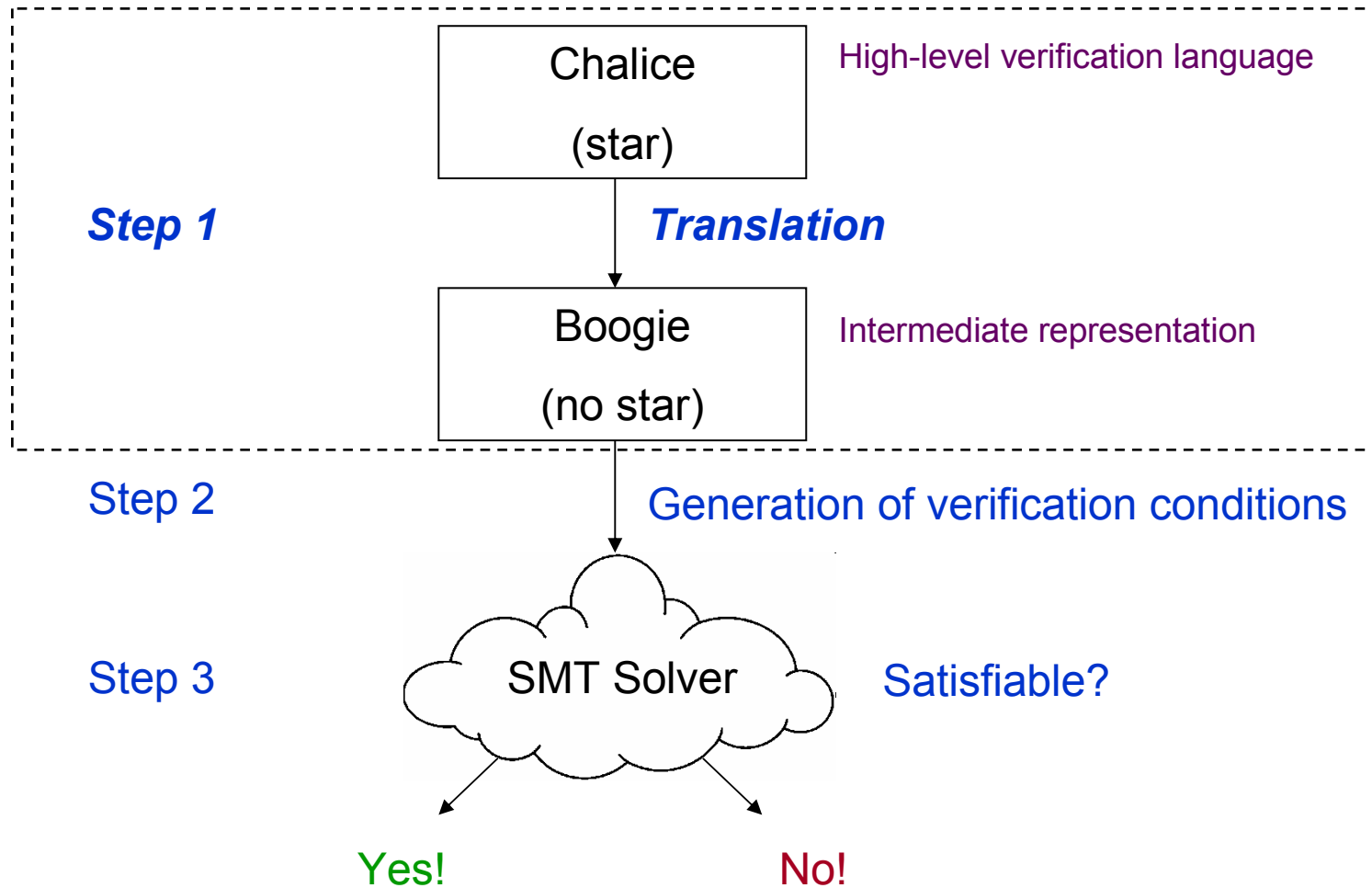


```
var c1 := new Car;
var c2 := new Car;
call c1.refuel ( 3 );
call c2.refuel ( 5 );
assert c1.fuel == 3;
```

Verification Pipeline



Verification Pipeline



Contributions

1. Formalization of a Chalice subset
2. Formalization of a Boogie subset
3. Formalization of a subset translation from Chalice to Boogie
4. Proof of Soundness of Translation

Contributions

1. Formalization of a Chalice subset
2. Formalization of a Boogie subset
3. Formalization of a subset translation from Chalice to Boogie
4. Proof of Soundness of Translation

Chalice

(has star)

Our subset ignores concurrency features

We give:

- ***Operational semantics***
- ***Hoare logic*** { Pre } C { Post }
- ***Soundness proof of Hoare logic w.r.t. operational semantics***

“A Sip of the Chalice” (Drossopoulou & Raad, 2011)

Self-framing

Badly framed Car program in Chalice (1)

```
class Car
{
  var fuel : int;

  void refuel ( amount : int )
  requires true;
  ensures this.fuel == amount;
  {
    this.fuel := amount; //ERROR: update is not framed
  }

  void main ( )
  {
    ...
  }
}
```

Badly framed Car program in Chalice (2)

```
class Car
{
  var fuel : int;

  void refuel ( amount : int )
  requires this.fuel == 0; //ERROR: assertion not self-framing
  ensures acc ( this.fuel ) &*& this.fuel == amount;
  {
    this.fuel := amount;
  }

  void main ( )
  {
    ...
  }
}
```

Our approach to self-framing

An assertion A is ***self-framing***

if and only if

**All heap references in A are
sufficiently framed by the access predicate.**

$$A = \underbrace{\text{acc} (x.f) \&^*\& \dots \&^*\&}_{\text{Rights}} \underbrace{x.f == 100}_{\text{Access}}$$

A is self-framing

if and only if

$$\text{Access} (A) \subseteq \text{Rights} (A)$$

To be or not to be self-framing

A	Access (A)	Rights (A)	
<code>acc(x.f) &* & x.f == 100</code>	{ x.f }	{ x.f }	✓
<code>acc(x.f) &* & y.f == 90</code>	{ y.f }	{ x.f }	✗
<code>acc(x.f) &* & x.g == 101</code>	{ x.g }	{ x.f }	✗
<code>acc(x.f)</code>	{ }	{ x.f }	✓

Our approach to self-framing
is *intuitive*,
provides an *operational* angle,
and *simplifies* proof of soundness.



Challenges

- Scoping & Simplification
- Design choices
- Formalization of method calls

Contributions

1. Formalization of a Chalice subset
2. **Formalization of a Boogie subset**
3. Formalization of a subset translation from Chalice to Boogie
4. Proof of Soundness of Translation

Boogie

(no star)

Our Boogie subset mirrors our Chalice subset

We give an operational semantics for our Boogie subset

Motivated in Rustan Leino's talk at Imperial College London (2012)

$$\frac{\varphi(\text{mask})(r, C.f) = v}{\llbracket \text{CanAccess}(\text{mask}, r, f) \rrbracket_{\varphi} = v}$$

$$\frac{\forall r : \text{ObjectReference}, f : \text{FieldId}. (\varphi(\text{mask})(r, C.f) \in \{0, 1\})}{\llbracket \text{IsGoodMask}(\text{mask}) \rrbracket_{\varphi} = 1}$$

$$\frac{\forall r : \text{ObjectReference}, f : \text{FieldId}. (\text{CanAccess}(\text{mask}, r, f) \Rightarrow \varphi(h_i)(r, C.f) = \varphi(h)(r, C.f))}{\llbracket \text{IsGoodInhaleState}(h_i, h, \text{mask}) \rrbracket_{\varphi} = 1}$$

$$\overline{\llbracket \text{mask}[r, C.f] \rrbracket_{\varphi} = \varphi(\text{mask})(r, C.f)}$$

$$\overline{\llbracket h[r, C.f] \rrbracket_{\varphi} = \varphi(h)(r, C.f)}$$

$$\frac{\varphi \models B}{\text{assume } B, \varphi \rightsquigarrow \varphi}$$

$$\frac{\varphi \models B}{\text{assert } B, \varphi \rightsquigarrow \varphi}$$

$$\overline{\text{havoc}(x), \varphi \rightsquigarrow \varphi[x \mapsto v]}$$

$$\frac{\varphi \not\models B}{\text{assert } B, \varphi \rightsquigarrow \text{ERROR}}$$

$$\frac{\varphi(\text{mask})(r, C.f) = v}{\llbracket \text{CanAccess}(\text{mask}, r, f) \rrbracket_{\varphi} = v}$$

$$\frac{\forall r : \text{ObjectReference}, f : \text{FieldId}. (\varphi(\text{mask})(r, C.f) \in \{0, 1\})}{\llbracket \text{IsGoodMask}(\text{mask}) \rrbracket_{\varphi} = 1}$$

$$\frac{\forall r : \text{ObjectReference}, f : \text{FieldId}. (\text{CanAccess}(\text{mask}, r, f) \Rightarrow \varphi(h_i)(r, C.f) = \varphi(h)(r, C.f))}{\llbracket \text{IsGoodInhaleState}(h_i, h, \text{mask}) \rrbracket_{\varphi} = 1}$$

$$\overline{\llbracket \text{mask}[r, C.f] \rrbracket_{\varphi} = \varphi(\text{mask})(r, C.f)}$$

$$\overline{\llbracket h[r, C.f] \rrbracket_{\varphi} = \varphi(h)(r, C.f)}$$

$$\frac{\varphi \models B}{\text{assume } B, \varphi \rightsquigarrow \varphi}$$

$$\frac{\varphi \models B}{\text{assert } B, \varphi \rightsquigarrow \varphi}$$

$$\overline{\text{havoc}(x), \varphi \rightsquigarrow \varphi[x \mapsto v]}$$

$$\frac{\varphi \not\models B}{\text{assert } B, \varphi \rightsquigarrow \text{ERROR}}$$

Challenges

- Scoping, Simplification, Design
- Formalization of Boogie-specific commands

Without the benefit of existing literature!

Contributions

1. Formalization of a Chalice subset
2. Formalization of a Boogie subset
- 3. Formalization of a subset translation from Chalice to Boogie**
4. Proof of Soundness of Translation

Boogie

Has special commands and
predicates

< frame_B >

Chalice to Boogie

Has notion of star operator



Has special commands and predicates

$\langle \text{mask}_C, \text{heap}_C, \text{frame}_C \rangle$



$\langle \text{frame}_B \rangle$

Translation needs to be meaning-preserving

Method Call

Caller

x.y(m)

Callee



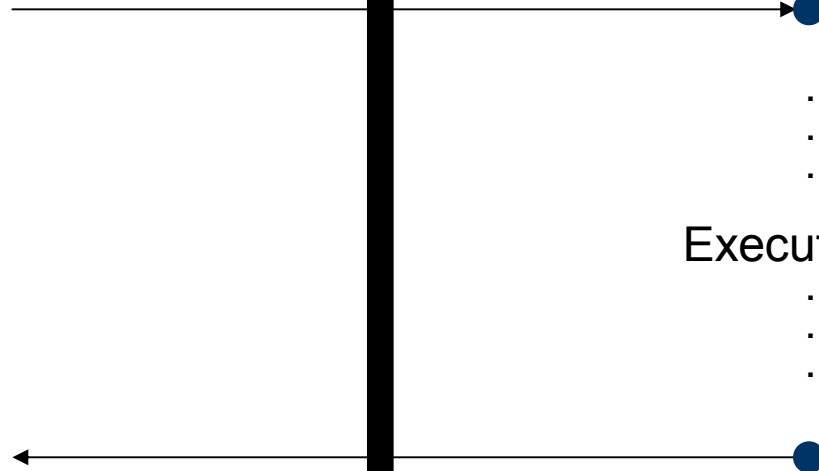
⋮

Execute method body

⋮



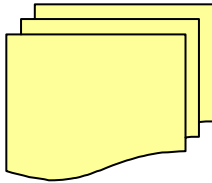
return



Caller

Callee

x.y(m) *Exhale (PRE)*

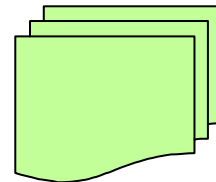


Inhale (PRE)

Execute method body

return *Inhale (POST)*

Exhale (POST)





The image shows a large white rectangular area enclosed by a thick black border. On the left side of this area, there is a horizontal line. From the center of this line, a semi-circle extends downwards. To the right of this semi-circle, the horizontal line continues to the right edge of the white area. At the top of this right edge, there is a semi-circular notch that extends upwards. The text 'x.m(y)' is located in the upper-left quadrant of the white area.

x.m(y)

x.m(y)

method m (t p)

requires Ar;
ensures Ae;

```
{  
  method body...  
}
```



x.m(y)

method m (t p)

requires Ar;
ensures Ae;

{
 method body...
}

```
var mask_e : Mask; var heap_i : Heap;  
var y1 : Expression;  
y1 := y;
```

```
mask_e := mask;  
exhale( Ar [ this / x ] [ y1 / y ], mask_e );  
mask := mask_e;
```

```
havoc heap_i;  
assume IsGoodInhaleState( heap_i , heap , mask );  
inhale( Ae [ this / x ] [ y1 / y ], mask , heap_i );
```

x.m(y)

method m (t p)

requires Ar;
ensures Ae;

```
{  
  method body...  
}
```

```
var mask_e : Mask; var heap_i : Heap;  
var y1 : Expression;  
y1 := y;
```

```
mask_e := mask;  
exhale( Ar [ this / x ] [ y1 / y ], mask_e );  
mask := mask_e;
```

```
havoc heap_i;  
assume IsGoodInhaleState( heap_i , heap , mask );  
inhale( Ae [ this / x ] [ y1 / y ], mask , heap_i );
```

procedure C.m (this : C , p : t)

```
{  
  var mask_e : Mask; var heap_i : Heap;
```

```
havoc heap_i;  
assume IsGoodInhaleState ( heap_i , heap , mask );  
inhale ( Ar , mask , heap_i );
```

```
translate ( method body );
```

```
mask_e := mask;  
exhale ( Ae , mask_e );  
mask := mask_e;  
}
```


exhale(acc(x.f) , mask) = assert 0 < mask[x , C.f];
mask[x , C.f] := mask[x , C.f] - 1;
assume IsGoodMask (mask);

exhale(a1 &* & a2 , mask) = exhale(a1 , mask);
exhale(a2 , mask);

exhale(b , mask) = assert translate (b);

inhale(b , mask , heap_i) = assume translate (b);

inhale(a1 &* & a2 , mask , heap_i) = inhale(a1 , mask , heap_i);
inhale(a2 , mask , heap_i);

inhale(acc(x.f) , mask , heap_i) = heap[x , C.f] := heap_i[x , C.f];
mask[x , C.f] := mask[x , C.f] + 1;
assume IsGoodMask (mask);

Checking self-framedness of assertions in Boogie (1)

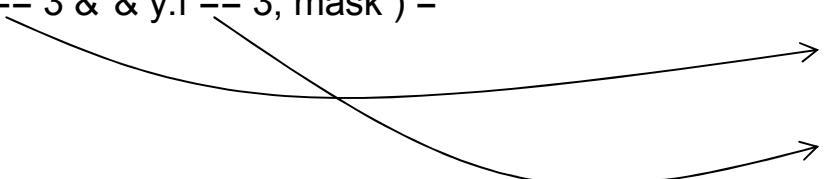
Not self-framing:

```
A = x.f == 3 &* & y.f == 3;
```

```
exhale(x.f == 3 &* & y.f == 3, mask ) =
```

```
assert heap[ x , C.f ] == 3; //ERROR
```

```
assert heap[ y , C.f ] == 3;
```



Checking self-framedness of assertions in Boogie (2)

Self-framing:

$A = \text{acc}(x.f) \ \&^* \ \& \ \text{acc}(y.f) \ \&^* \ \& \ x.f == 3 \ \&^* \ \& \ y.f == 3;$ *where x and y not aliases of each other!*

$\text{exhale}(\text{acc}(x.f) \ \&^* \ \& \ \text{acc}(y.f) \ \&^* \ \& \ x.f == 3 \ \&^* \ \& \ y.f == 3, \text{mask}) =$

$\text{assert } 0 < \text{mask}[x, C.f];$
 $\text{mask}[x, C.f] := \text{mask}[x, C.f] - 1;$
 $\text{assume } \text{IsGoodMask}(\text{mask});$

$\text{assert } 0 < \text{mask}[y, C.f];$
 $\text{mask}[y, C.f] := \text{mask}[y, C.f] - 1;$
 $\text{assume } \text{IsGoodMask}(\text{mask});$

$\text{assert } \text{heap}[x, C.f] == 3;$

$\text{assert } \text{heap}[y, C.f] == 3;$

Car program still running ...

```
class Car
{
  var fuel : int;

  void refuel ( amount : int )
  requires acc ( this.fuel );
  ensures acc ( this.fuel ) &*& this.fuel == amount;
  {
    this.fuel := amount;
  }

  void main ( )
  {
    var c1 := new Car;
    var c2 := new Car;

    call c1.refuel ( 3 );

    call c2.refuel ( 5 );
    assert ( c1.fuel == 3 );
  }
}
```

```
call c1.refuel ( 3 );
```

```
//set up variables  
var mask_e : Mask; var heap_i : Heap;  
var y : Expression;  
y := 3;
```

```
mask_e := mask;
```

```
//exhale precondition  
assert 0 < mask_e [ this , Car.fuel ];  
mask_e [ this , Car.fuel ] := mask_e [ this , Car.fuel ] - 1;  
assume IsGoodMask ( mask_e );
```

```
mask := mask_e;
```

```
havoc heap_i;
```

```
assume IsGoodInhaleState ( heap_i , heap , mask );
```

```
//inhale postcondition  
heap [ this , Car.fuel ] := heap_i [ this , Car.fuel ];  
mask [ this , Car.fuel ] := mask [ this , Car.fuel ] + 1;  
assume IsGoodMask ( mask );  
assume heap [ this , Car.fuel ] == y;
```

```
void refuel ( amount : int )  
requires acc ( this.fuel );  
ensures acc ( this.fuel ) &*& this.fuel == amount;  
{  
    this.fuel := amount;  
}
```

```
procedure Car.refuel ( this : Car , amount : int )  
{  
    var mask_e : Mask; var heap_i : Heap;
```

```
havoc heap_i;  
assume IsGoodInhaleState ( heap_i , heap , mask );
```

```
//inhale precondition  
heap [ this , Car.fuel ] := heap_i [ this , Car.fuel ];  
mask [ this , Car.fuel ] := mask [ this , Car.fuel ] + 1;  
assume IsGoodMask ( mask );
```

```
//translate method body  
CanAccess ( mask , this , Car.fuel );  
heap [ this , Car.fuel ] := amount;
```

```
mask_e := mask;
```

```
//exhale postcondition  
assert 0 < mask_e [ this , Car.fuel ];  
mask_e [ this , Car.fuel ] := mask_e [ this , Car.fuel ] - 1;  
assume IsGoodMask ( mask_e );  
assert heap [ this , Car.fuel ] == amount;  
mask := mask_e;  
}
```

Contributions

1. Formalization of a Chalice subset
2. Formalization of a Boogie subset
3. Formalization of a subset translation from Chalice to Boogie
4. **Proof of Soundness of Translation**

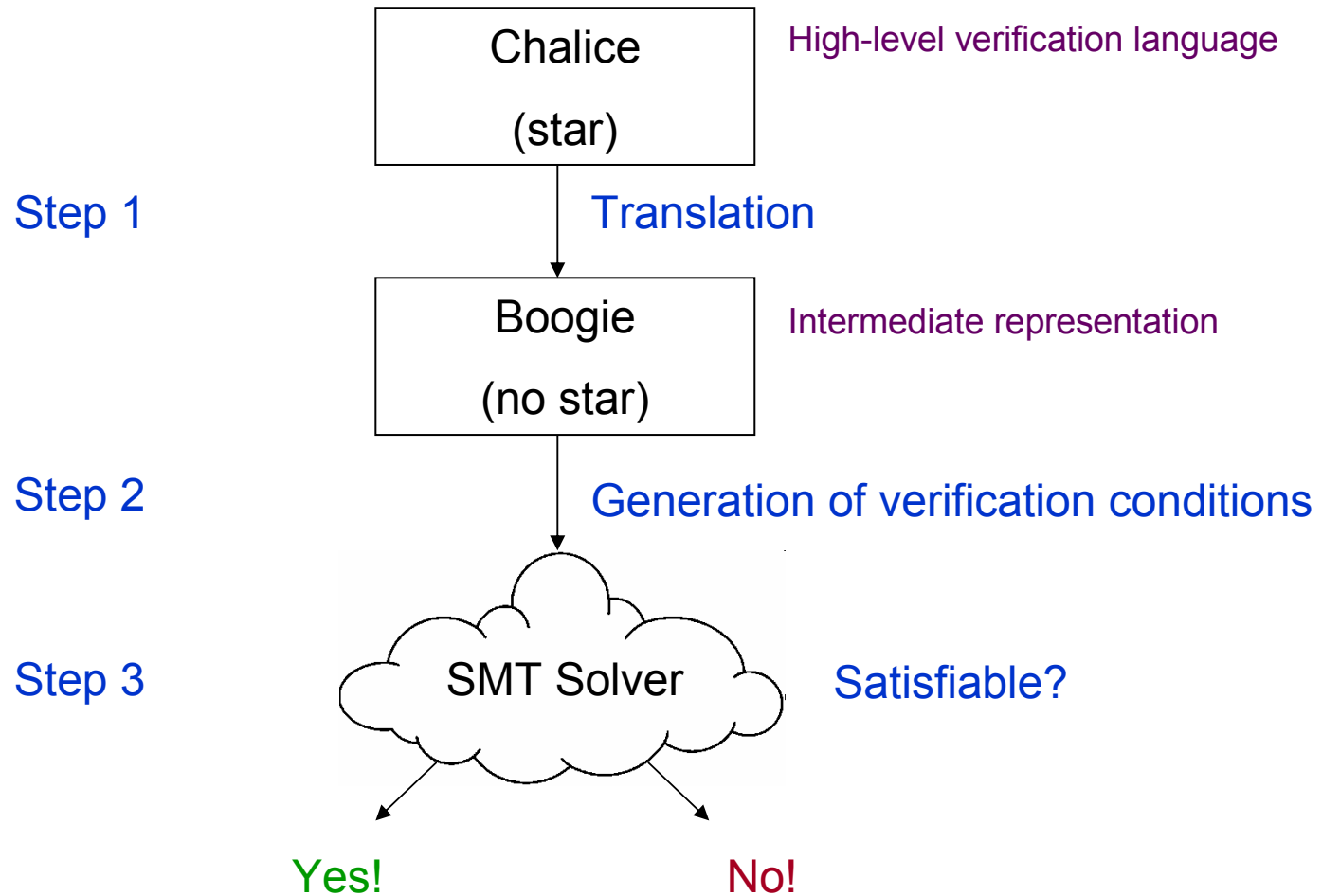
Soundness Argument

The **translation** of a Chalice program ***P*** is sound

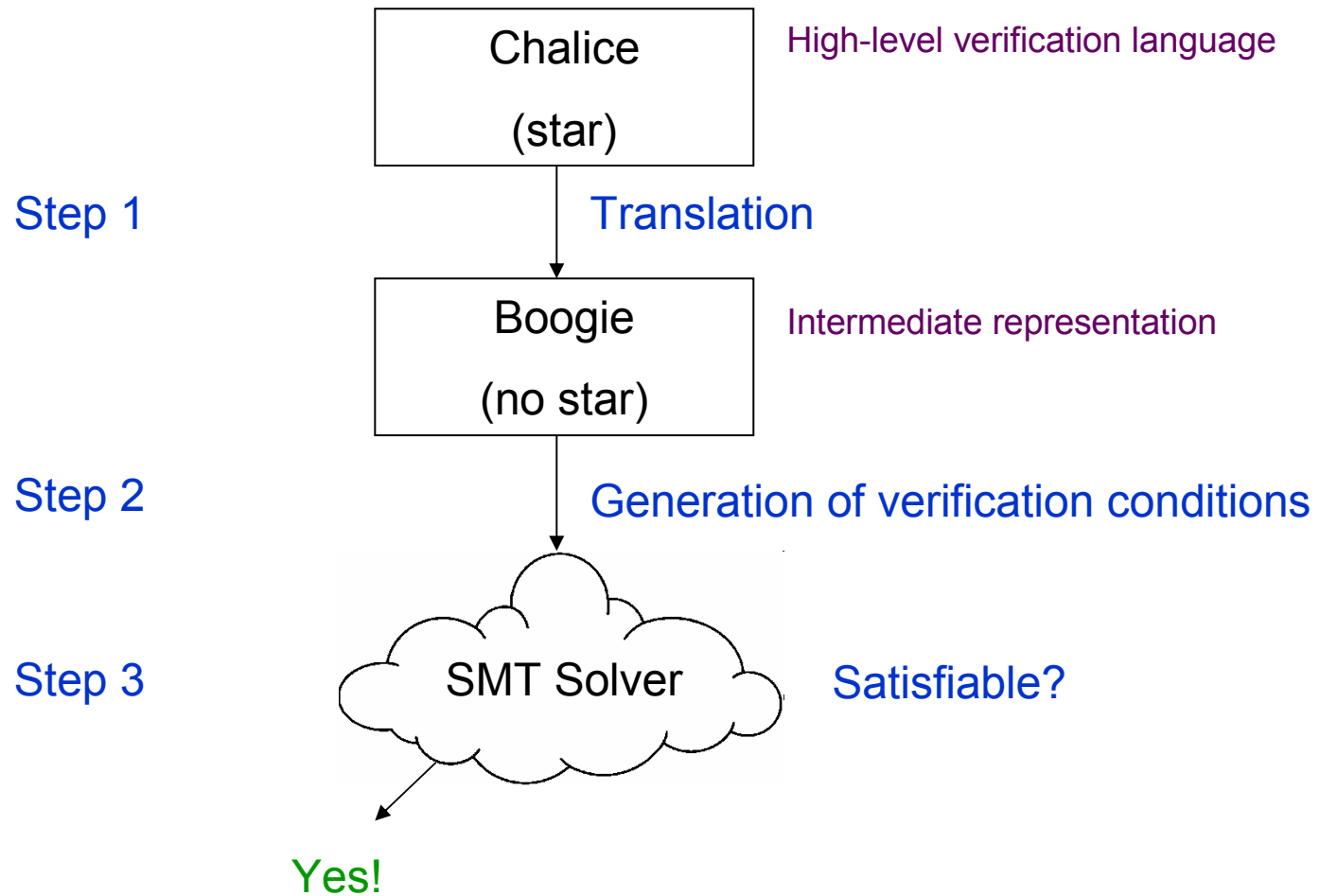
if and only if

given that ***P*** verifies in the Boogie environment, it **also** verifies in the Chalice environment.

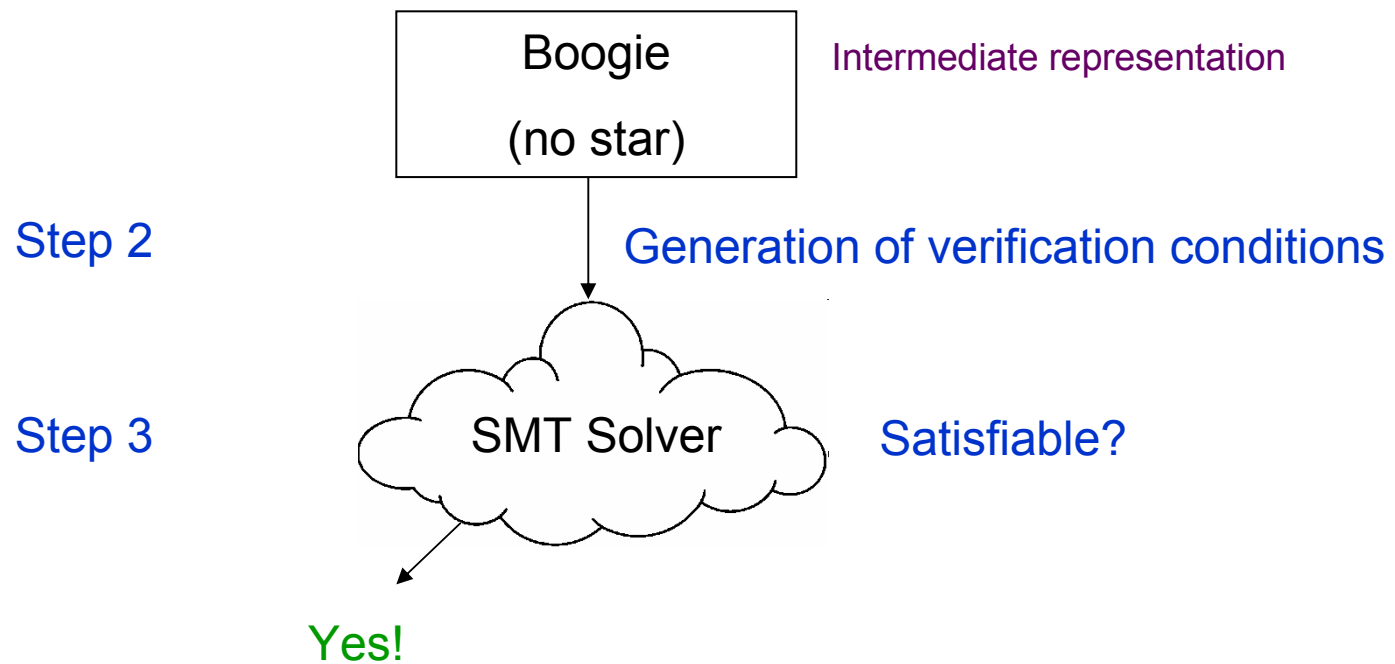
Verification Pipeline Revisited



If program verifies in Chalice environment ...



If program verifies in Boogie environment ...



Lemma 6.4.4. $\forall C : \text{ClassId}, m : \text{MethId} :$

If:

1. $\text{Prog}_C(C, m) = \text{requires } A; \text{ensures } A'; \{C_C\} \wedge$
2. $(\text{inhale}(A, \text{mask}, h_i); \text{translate}(C_C); \text{exhale}(A, \text{mask}_e)), \varphi_\varepsilon \not\rightarrow \text{ABORT} \wedge$
3. $\Pi, \varphi_C, h_C \models A \wedge$
4. $C_C, \Pi, \varphi_C, h_C \rightsquigarrow \Pi', \varphi'_C, h'_C$

Then $\Pi', \varphi'_C, h'_C \models A'$

Other Machinery

Auxiliary Definitions, Lemmas ...

Challenges

- **Design** of translation function
- **Formulating** & **justifying** soundness argument
- **Lemmas** and **proofs**

Highlights

1. Formalization of a Chalice subset
 - Approach to self-framing
2. Formalization of a Boogie subset
 - Operational semantics
3. Formalization of a sound translation from Chalice to Boogie
 - Translation function, soundness argument & proofs

Applications

1. Boogie-based verification
2. Pedagogic uses

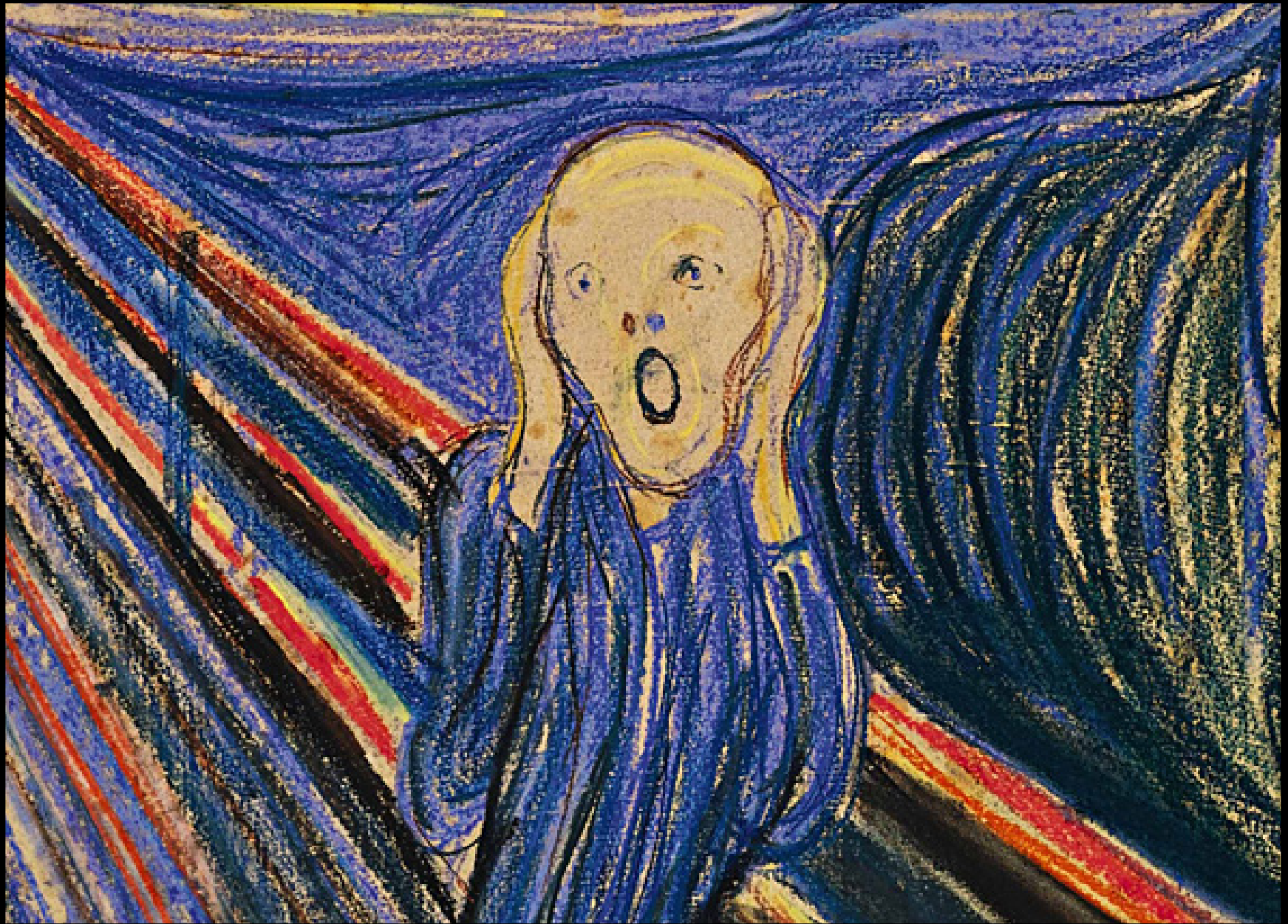
Applications

1. Boogie-based verification
2. Pedagogic uses

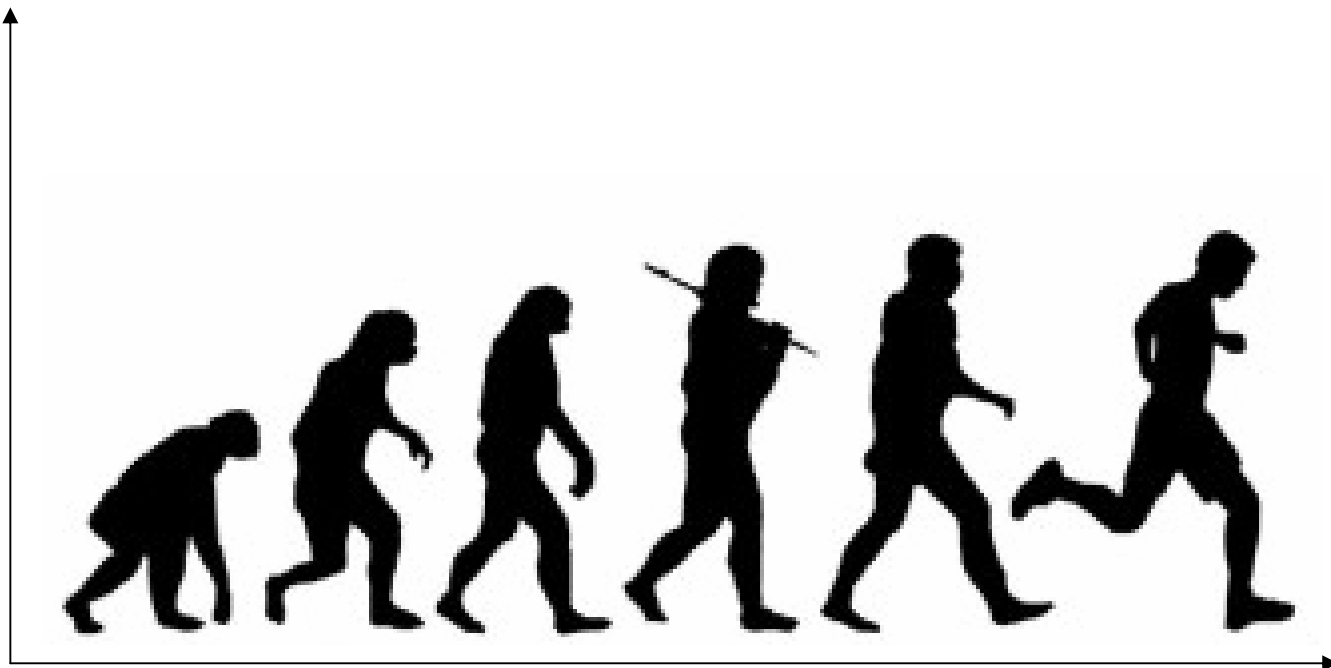
<http://rise4fun.com/>

A Challenging Project

- ❖ Lots of **background reading**
- ❖ An **open-ended** project
- ❖ Balancing **breadth** and **depth** of investigation
- ❖ Experimenting with **tools**
- ❖ Formalizing **approaches** and **arguments**
- ❖ Making **original** contributions
- ❖ I am not JMC or MEng (but **I am passionate about research!**)



Knowledge



Time

Future Work

1. **Formalize** translation of **while loop**, and proof of **method call**
2. **Extend** **language subsets** to include **concurrency**
3. **Consider** **translation** from **VeriFast** to **Chalice**



Q&A

Extra Slides

Usual approach to self-framing

An assertion A is ***self-framing***

if and only if

The validity of A is preserved in all heaps which agree in the locations mentioned in the permissions. *(Parkinson & Summers, 2011)*

While loop

```
while ( condition )  
{  
  
    // check invariant holds upon loop entry (assert ...)  
  
    loop body ...  
  
    // check invariant holds after arbitrary loop iteration (havoc...)  
  
}
```

Method call

If:

- $x.m(y)$
- translation of $x.m(y)$ gives a Boogie encoding C_B
- C_B verifies in Boogie
- Chalice and Boogie starting configurations are congruent
- and given preconditions of operational semantics for $x.m(y)$...

Then:

(esp. using Lemmas for Inhale / Exhale ...)

Show that there exists a terminal Boogie configuration φ_B s. t.

- C_B execution in Boogie leads to φ_B
- Terminal configurations in Chalice and Boogie match

Lemma 6.4.1. *Given $C : Command_C, \forall \Pi : Mask_C, \varphi_C : Store_C, h_C : Heap_C, \varphi_B : Store_B,$*

If:

1. $translate(C), \varphi_B \not\rightarrow ABORT$
2. $\Pi, \varphi_C, h_C \cong \varphi_B$
3. $C, \Pi, \varphi_C, h_C \rightsquigarrow \Pi', \varphi'_C, h'_C$

Then there exists a $\varphi'_B : Store_B$ such that:

4. $translate(C), \varphi_B \rightsquigarrow \varphi'_B$
5. $\Pi', \varphi'_C, h'_C \cong \varphi'_B$

Lemma 6.4.2. *Given $A : \text{Assertion}_C, \text{mask} : \text{Mask}_B, h_B : \text{Heap}$ (where A is self-framing, mask is the current mask, and h_B is the current heap),*

If:

1. $\text{inhale}(A, \text{mask}, h_B) = C_i$ where $C_i : \text{Command}_B$
2. $C_i, \varphi_B \rightsquigarrow \varphi'_B$ where $\varphi'_B : \text{Store}_B$ such that $\varphi'_B \neq \text{ABORT}$
3. $\Pi', \varphi'_c, h'_c \cong \varphi'_B$, where $\Pi' : \text{Mask}_C, \varphi'_c : \text{Store}_C, h'_c : \text{Heap}_C$

Then:

4. $\Pi', \varphi'_c, h'_c \models A$
5. *There exists a $\text{mask}' : \text{Mask}_B$ such that $\varphi'_B \equiv \varphi_B[\text{mask} \mapsto \text{mask}']$, and $\text{mask} \leq_{\Pi} \text{mask}'$.*

Lemma 6.4.3. *Given $A : \text{Assertion}_C, \text{mask} : \text{Mask}_B$, (where A is self-framing, and mask is the current mask)*

If:

1. $\text{exhale}(A, \text{mask}) = C_e$ where $C_e : \text{Command}_B$
2. $C_e, \varphi_B \rightsquigarrow \varphi'_B$ where $\varphi'_B : \text{Store}_B$ such that $\varphi'_B \neq \text{ABORT}$
3. $\Pi, \varphi_C, h_c \cong \varphi_B$

Then:

4. $\Pi, \varphi_C, h_c \models A$, where $\Pi : \text{Mask}_C, \varphi_C : \text{Store}_C, h_c : \text{Heap}_C$
5. *There exists a $\text{mask}' : \text{Mask}_B$ such that $\varphi'_B \equiv \varphi_B[\text{mask} \mapsto \text{mask}']$, and $\text{mask}' \leq_{\Pi} \text{mask}$.*

Definition 6.3.1. *combine* : $Mask_C \times Store_C \times Heap_C \rightarrow Store_B$ such that, for $\Pi : Mask_C, \varphi_C : Store_C, h_C : Heap_C$ we:

1. Create a fresh Boogie variable $mask_B : Mask_B$ and populate it with the access permissions found in Π , such that $\forall v : \{0, 1\}, r : ObjectReference, f : FieldId. (\Pi[r, f] = v \Rightarrow mask[(r, C.f) \mapsto v])$ where f is a field of class C .
2. Create a fresh Boogie variable $h_B : Heap_B$ and populate it with the values found in h_C , such that $\forall r : ObjectReference, f : FieldId. (h_B[(r, C.f) \mapsto \llbracket r.f \rrbracket_{\varphi, h_C}])$ where f is a field of class C .
3. Now take an empty store $\varphi_\varepsilon : Store_B$, such that $\varphi_\varepsilon = \{mask \mapsto \emptyset, heap \mapsto \emptyset\}$.
4. Construct a $\varphi_B : Store_B$, such that $\varphi_B = \varphi_\varepsilon[mask \mapsto mask_B, h \mapsto h_B] \cup \varphi_C$

Definition 6.3.2. $\cong : Mask_C \times Store_C \times Heap_C \times Store_B$ such that, for $\Pi : Mask_C, \varphi_C : Store_C, h_C : Heap_C, \varphi_B : Store_B$, we have

$$\Pi, \varphi_C, h_C \cong \varphi_B \iff combine(\Pi, \varphi_C, h_C) = \varphi_B$$

$Program : ClassId \rightarrow FieldId \times (MethId \times MethDef)$

$B \in Boolean ::= true \mid false \mid \neg B \mid E == E$

$E \in Expression ::= n \mid x \mid x.f \mid E + E \mid x.m_{pure}(E)$

$C \in Command ::= x := y.f \mid x.f := y \mid \text{if } B \text{ then } C \text{ else } C \mid$
 $\quad \text{while } B \text{ do } C \mid C;C \mid \text{skip} \mid x := y.m(E) \mid$
 $\quad x := \text{new } C \mid \text{assert } A$

$A \in Assertion ::= B \mid \text{acc}(x.f) \mid A * A$

$ClassID, FieldID ::= (a - zA - Z)^+$

$Term ::= Boolean \mid Expression \mid Command \mid Assertion$

Figure 3.1: Our Subset of the full Chalice Syntax

$\llbracket \cdot \rrbracket : (Assertion \cup Expression) \times Mask \times Store \times Heap \rightarrow \mathbb{Z}$
 $\rightsquigarrow : Command \times Mask \times Store \times Heap \rightarrow Mask \times Store \times Heap$
 $\Pi \in Mask : ObjectReference \times (ClassId \times (FieldId \rightarrow \{0, 1\}))$
 $\varphi \in Store : Variable \rightarrow \mathbb{Z}$
 $h \in Heap : ObjectReference \rightarrow (ClassId \times (FieldId \rightarrow \mathbb{Z}))$
 $ObjectReference ::= \mathbb{Z}^+$
 $Variable, ClassID, FieldID ::= (a - zA - Z)_+$

Figure 3.2: Runtime Configuration for Our Chalice Subset

$B \in \text{Boolean} ::= \text{true} \mid \text{false} \mid \neg B \mid E == E \mid$
 $\text{CanAccess}(\text{mask}, r, f) \mid$
 $\text{IsGoodInhaleState}(h, h, \text{mask}) \mid$
 $\text{IsGoodMask}(\text{mask})$

$E \in \text{Expression} ::= n \mid x \mid h[r, C.f] \mid \text{mask}[r, C.f] \mid E + E$

$C \in \text{Command} ::= \text{var } x : t \mid x := E \mid h[r, C.f] := E \mid \text{mask}[r, C.f] := E \mid$
 $\text{havoc}(x) \mid \text{if } B \text{ then } C \text{ else } C \mid C; C \mid$
 $\text{assume } B \mid \text{assert } B$

$\text{Term} ::= \text{Boolean} \mid \text{Expression} \mid \text{Command}$

Figure 4.1: Our Subset of the full Boogie Syntax

$\llbracket \cdot \rrbracket : (Boolean \cup Expression) \times Store \rightarrow \mathbb{Z}$

$\rightsquigarrow : Command \times Store \rightarrow Store$

$\varphi \in Store : Variable \rightarrow Value$

$mask \in Mask : ObjectReference \times (ClassId \times (FieldId \rightarrow \{0, 1\}))$

$h \in Heap : ObjectReference \times (ClassId \times (FieldId \rightarrow Value))$

$Variable, ClassId, FieldId ::= (a - zA - Z)^+$

$ObjectReference ::= \mathbb{Z}^+$

$Value ::= \mathbb{Z} | Heap | Mask$

Figure 4.2: **Runtime Configuration for Our Boogie Subset**