A Case Study in Reasoning about Actions and Continuous Change (extended version)

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November 1995

Imperial College Research Report DoC 95/20

Abstract

This paper shows how the Situation Calculus can be extended to deal both with 'narratives' and with domains containing real-valued parameters, whose actual values may vary continuously between the occurrences of actions. In particular, a domain is represented where action occurrences may be 'triggered' at instants in time when certain parameters reach particular values. Its formalisation requires the integration of several types of default reasoning. Hence Baker's circumscriptive solution to the frame problem is extended to reflect the assumptions that by default a given action does not occur at a given time point, that by default a given set of parameter values does not trigger a given action, and that by default a given action occurrence does not result in a discontinuity for a given parameter. Regarding the minimisation of discontinuities, the example illustrates how circumstances can arise where, at a particular time point, discontinuities in some parameters can be 'traded' for discontinuities in others. It is argued that, in general, in such cases extra domain-specific information will be necessary in order to eliminate anomalous models of the domain.

1 Introduction

This paper is a slightly extended version of [5]. It builds on the work of Miller and Shanahan [6], of Sandewall [9] [10] and of Pinto [7] to develop a Situation Calculus able to represent both 'narrative' information and information about real-valued parameters whose actual values may vary continuously in time. The need to represent continuous change raises several issues in reasoning about actions. In particular, a truly comprehensive solution to the frame problem must be applicable to domains involving both continuous and discrete change.

Narrative information is information about what actions have or have not actually occurred at particular instants of time. In order to represent narratives, the Situation Calculus's usual ontology (of actions, Boolean-valued fluents and situations) is extended here, as in [6], with a time line (in fact, a real-number line). Using the extra predicate *Happens*, action occurrences are embedded at various points along this time line, thus dividing it into non-overlapping intervals. Extra axioms are included which equate all the time points within a single such interval to a single situation, using the function *State* (mapping time points to situations). The axiomatisation thus ensures that between action occurrences (the Boolean values of) all fluents persist. At points in time where actions occur, this principle of persistence is weakened to a default. Which fluents persist at such points is largely determined by the particular solution to the frame problem employed by the conventional Situation Calculus component of the theory. The solution used here is based on that of Baker [1]. As in [6], Baker's circumscription policy is extended, in this case to model other modes of default reasoning relating either to continuous change or to narratives.

To deal with continuous change, the Situation Calculus's ontology is further extended with the familiar mathematical notion of a *parameter*. Whereas fluents take on Boolean values at different moments of time, parameters take on real number values. As mentioned above, fluents are associated with the notion of persistence. The corresponding notion for parameters is that of *continuity* (in the usual mathematical sense). Following Sandewall [9], in this paper the view is taken that during periods of time in which no actions occur, both the principle of persistence of fluent values and the principle of continuity of parameter values are inviolate. At points in time where actions occur, both of these principles are weakened to defaults. A problem analogous to the frame problem arises for parameters – that is, how to succinctly express that most parameters remain continuous at most points where actions occur. To borrow some terminology from Sandewall, attention will be restricted here to narratives which are *piecewise continuous*, i.e. in which there are only a finite number of action occurrences in any given finite interval of time.

The paper is organised as follows. In Section 2, an example domain is introduced, and a conventional mathematical model constructed and examined in some detail. The example is of particular interest first because it involves *negative feedback*, and second because it includes an action occurrence which has been 'triggered' by parameters reaching certain values at the end of a period of continuous change. In Section 3 the domain-independent axioms of the extended Situation Calculus are described, and in Section 4 the formalism is applied to the example described in Section 2. The paper ends with a general discussion in Section 5.

2 The Water Tanks Example

This example involves two open-top water tanks, $TankA$ and $TankB$. The two tanks have identical length and width, but $TankA$ is taller than $TankB$. $TankA$ is suspended above $TankB$, and in the bottom of $TankA$ are two taps, $TapC$ and $TapD$, both of which (when open) discharge water into $TankB$, at a rate proportional to the level of water in $TankA$ (i.e. at a rate proportional to the water pressure at the bottom of $TankA$). Initially, $TankA$ contains more water than will fit into $TankB$, $TankB$ is empty, and both taps are closed. This initial scenario is illustrated in Figure 1. L is the initial level of the water in $TankA$, and H_B is the height of $TankB$.

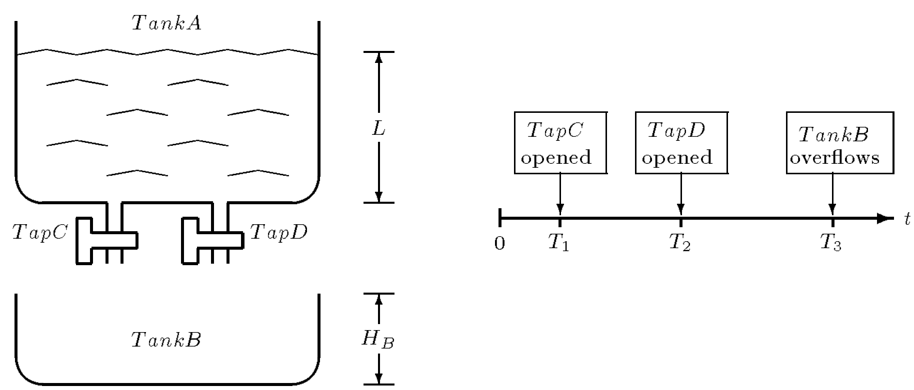

Figure 1

Suppose that at time T_1, $TapC$ is opened causing water to flow from $TankA$ to $TankB$, at time T_2 (sometime later) $TapD$ is also opened, and at time T_3 (sometime later still) $TankB$ overflows. This course of events is also illustrated in Figure 1. Note that the overflowing event (i.e. action occurrence) at T_3 is 'triggered' – T_3 is determined by the times T_1 and T_2 and the functions describing the flow of water through the two taps.

A mathematical model of this domain can be formulated in a standard way. Four parameters are needed – all functions from time (represented by the non-negative reals) to the reals. $LevelA(t)$ and $LevelB(t)$ are the functions representing the levels of water in $TankA$ and $TankB$ respectively, and $FlowC(t)$

and $FlowD(t)$ represent the water flow through $TapC$ and $TapD$. Let K be the constant of proportionality between the level of water in $TankA$ and the flow through either of the taps when open. It will be assumed that specific values have been given for T_1 and T_2 such that $0 < T_1 < T_2$. The specific value of T_3 is obviously dependent on L, H_B, K, T_1 and T_2, and it will also be assumed that L, H_B, K, T_1 and T_2 are such that $T_2 < T_3$.

The process of constructing the model may be summarised as follows. (i) Formulate some equations relating the functions $LevelA(t)$, $LevelB(t)$, $FlowC(t)$ and $FlowD(t)$ and/or their derivatives under various different physical circumstances of the system. (ii) Divide the time line into several intervals (such as the interval between T_1 and T_2, where $TapC$ is open but $TapD$ is closed). For each such interval, pick a subset of these equations which are applicable throughout the interval, and solve them simultaneously to derive explicit independent expressions for each parameter in terms of time alone. Generally, because the initial equations are often differential equations, these solutions will contain unknown constants. (iii) Use knowledge of the physics of the system to assign particular values to these unknown constants. As will be seen, these assignments are in fact determined either by 'initial conditions', or by decisions as to which parameters of the system are continuous at the points T_1, T_2 and T_3.

To simplify the discussion, a particular convention concerning the points of transition between one interval and the next is adopted in this section. Whenever the interval of time under consideration has a greatest lower bound T_l (other than 0), it is assumed that T_l is *not* contained in the interval, but whenever the interval has a least upper bound T_u, it is assumed that T_u *is* contained in the interval. Hence, for example, it is assumed that the interval where $TapC$ is open but $TapD$ is closed is the half-open interval $(T_1, T_2]$. Furthermore, at all points in each such interval $(T_l, T_u]$, except possibly at T_u, it is assumed that each parameter is continuous, and that all its derivatives are well defined and are also continuous. At points such as T_u, it is simply stipulated that for each parameter P (which may be a derivative of some other parameter)

$$P(T_u) \stackrel{\text{def}}{=} \lim_{t \to T_u^-} P(t)$$

i.e. the value of each parameter at T_u is defined as its limit from the left at T_u. The successive derivatives of P at t are written as $P'(t)$, $P''(t)$, etc.

The following equations are each applicable in the circumstances indicated

Always:	$LevelA'(t) = -(FlowC(t) + FlowD(t))$	(1)
$TankB$ not full:	$LevelB'(t) = FlowC(t) + FlowD(t)$	(2)
$TankB$ full:	$LevelB'(t) = 0$	(3)
$TapC$ closed:	$FlowC(t) = 0$	(4)
$TapC$ open:	$FlowC(t) = K.LevelA(t)$	(5)
$TapD$ closed:	$FlowD(t) = 0$	(6)

$$TapD \text{ open:} \quad FlowD(t) = K.LevelA(t) \tag{7}$$

In the interval $[0, T_1]$ the relevant equations are (1), (2), (4) and (6). Their simultaneous solution is

$$\begin{aligned} LevelA(t) &= C_1 \\ LevelB(t) &= C_2 \\ FlowC(t) &= 0 \\ FlowD(t) &= 0 \end{aligned}$$

where C_1 and C_2 are arbitrary real valued constants. Since it is also known that $LevelA(0) = L$ and $LevelB(0) = 0$ (because these values have been given as initial conditions),

$$LevelA(t) = L \tag{S1}$$
$$LevelB(t) = 0 \tag{S2}$$
$$FlowC(t) = 0 \tag{S3}$$
$$FlowD(t) = 0 \tag{S4}$$

At time T_1, $TapC$ is opened, so that in the interval $(T_1, T_2]$ the equations to solve are (1), (2), (5) and (6). Their simultaneous solution is

$$\begin{aligned} LevelA(t) &= C_3.e^{-Kt} \\ LevelB(t) &= C_4 - C_3.e^{-Kt} \\ FlowC(t) &= C_3.Ke^{-Kt} \\ FlowD(t) &= 0 \end{aligned}$$

where C_3 and C_4 are arbitrary real valued constants. In fact, it is implicit in the description of the domain that no 'sudden' change in the level of $TankA$ or of $TankB$ occurs at T_1 – i.e. it is known that $LevelA(t)$ and $LevelB(t)$ are both continuous at T_1. Hence, with a little algebra, it is easy to see that $C_3 = Le^{KT_1}$ and $C_4 = L$. Hence the final solution in this interval is

$$LevelA(t) = Le^{-K(t-T_1)} \tag{S5}$$
$$LevelB(t) = L - Le^{-K(t-T_1)} \tag{S6}$$
$$FlowC(t) = LKe^{-K(t-T_1)} \tag{S7}$$
$$FlowD(t) = 0 \tag{S8}$$

Notice that this solution forces a discontinuity in $LevelA'(t)$, $LevelB'(t)$ and $FlowC(t)$ at the point T_1, and also forces discontinuities in all their derivatives. Merely mechanically limiting the number of discontinuous parameters at this point, without considering the physical realities of the system, could have resulted in trading all these discontinuities for a single discontinuity in $LevelA(t)$, by putting $C_3 = C_4 = 0$.

In the interval $(T_2, T_3]$, both $TapC$ and $TapD$ are open, and the equations to solve are (1), (2), (5) and (7). Their simultaneous solution is

$$LevelA(t) = C_5.e^{-2Kt}$$
$$LevelB(t) = C_6 - C_5.e^{-2Kt}$$
$$FlowC(t) = C_5.Ke^{-2Kt}$$
$$FlowD(t) = C_5.Ke^{-2Kt}$$

where again C_5 and C_6 are arbitrary real valued constants. Again, it is known that $LevelA(t)$ and $LevelB(t)$ are both continuous at T_2. Hence $C_5 = Le^{K(T_1+T_2)}$ and $C_6 = L$. Hence the final solution in this interval is

$$LevelA(t) = Le^{K(T_1+T_2-2t)} \tag{S9}$$
$$LevelB(t) = L - Le^{K(T_1+T_2-2t)} \tag{S10}$$
$$FlowC(t) = LKe^{K(T_1+T_2-2t)} \tag{S11}$$
$$FlowD(t) = LKe^{K(T_1+T_2-2t)} \tag{S12}$$

As before, this solution forces discontinuities at the point T_2, this time in $LevelA'(t)$, $LevelB'(t)$ and $FlowD(t)$ and all their derivatives. In this case there are two other sets of assignments to C_5 and C_6 which would have resulted in trade-offs in discontinuities. The assignments $C_5 = 0$ and $C_6 = L - Le^{K(T_1-T_2)}$ would have kept $FlowD(t)$ and its derivatives continuous at T_2 (as well as maintaining the continuity of $LevelB(t)$). Alternatively, to keep $LevelA'(t)$ and $LevelB'(t)$ continuous at T_2 the assignment $C_5 = \frac{L}{2}e^{K(T_1+T_2)}$ and $C_6 = L(1 + \frac{1}{2}e^{K(T_1+T_2)} + e^{K(T_1-T_2)})$ could have been made. However, both of these alternative sets of assignments would have resulted in discontinuities in $LevelA(t)$ – i.e. 'sudden disappearances' of water from $TankA$, as well as discontinuities in $FlowC(t)$ and its derivatives.

The specific value for T_3 can now also be computed, using (S10) and the knowledge that $LevelB(T_3) = H_B$. This gives

$$T_3 = \frac{T_1+T_2}{2} + \frac{1}{2K}ln(\frac{L}{L-H_B})$$

Finally, in the region $(T_3, +\infty)$, $TankB$ is overflowing, and the equations to solve are (1), (3), (5) and (7). Their simultaneous solution is

$$LevelA(t) = C_7.e^{-2Kt}$$
$$LevelB(t) = C_8$$
$$FlowC(t) = C_7.Ke^{-2Kt}$$
$$FlowD(t) = C_7.Ke^{-2Kt}$$

where again C_7 and C_8 are arbitrary real valued constants. Again, it is known that $LevelA(t)$ and $LevelB(t)$ are both continuous at T_2. Hence $C_7 = Le^{K(T_1+T_2)}$ $(= C_5)$ and $C_8 = H_B$. Hence the final solution in this interval is

$$LevelA(t) = Le^{K(T_1+T_2-2t)} \tag{S13}$$
$$LevelB(t) = H_B \tag{S14}$$
$$FlowC(t) = LKe^{K(T_1+T_2-2t)} \tag{S15}$$
$$FlowD(t) = LKe^{K(T_1+T_2-2t)} \tag{S16}$$

At T_3, no trade-offs in discontinuities are possible. The inclusion of equation (3) in the model for this last region guarantees a discontinuity in $LevelB'(t)$ and all its derivatives. Since (S13), (S15) and (S16) are identical to (S9), (S11) and (S12) respectively, all other parameters are continuous at this point.

For the sake of discussion, expressions such as (1) – (7) will be referred to here as *equality constraints*, and expressions such as (S1) – (S16) as *trajectories*. (Trajectories are thus a special case of equality constraint which mention only one parameter, and no derivatives of parameters.)

There are several points to note about mathematical models such as the one above. First, notice that there is often a natural association between individual equality constraints such as (1) – (7) and individual or 'local' properties of the domain. For example, (5) must hold if and only if $TapC$ is open. Second, for other more complex domains, perhaps involving non-linear relationships between parameters and derivatives, it might not be easy to formulate explicit trajectories for each parameter – it may be necessary for example to employ numerical or approximation methods to provide a simultaneous solution to a given set of equality constraints. Third, notice that the equality constraints such as (1), (2), etc. persist through the transition points T_1, T_2 and T_3 to a greater degree than the trajectories (S1), (S2), etc. For example, expression (1) is relevant throughout all four intervals, whereas the expressions (S1), (S3) and (S9) are all different.

For these reasons, a suitably extended Situation Calculus will be used in this paper to describe transitions from one set of equality constraints such as {(1), (2), (4), (6)} to another such as {(1), (2), (5), (6)}, and mathematics will be relied upon to transform a given set of equality constraints such as {(1), (2), (4), (6)} into a set of trajectories such as {(S1), (S2), (S3), (S4)}. As has been seen, the mathematics sometimes generates arbitrary constant symbols in trajectories, such as $C_1, \ldots, C_8$. The extended Situation Calculus must therefore enable the inference of the specific numerical values of these constants. Such inferences will be based in part on the general principle of minimising discontinuities at points of transition, and in part on domain-specific information, such as the 'commonsense' knowledge that opening a tap does not cause a body of water to instantaneously disappear.

3 A Situation Calculus for Piecewise Continuous Domains

3.1 The Language

Following the usual practice, the Situation Calculus presented here will be written in a sorted predicate calculus, with sorts $\mathcal{A}$, $\mathcal{S}$ and $\mathcal{F}$, for actions, situations and fluents respectively, as well as a sort $\mathcal{X}$ for 'domain objects' (blocks, water-tanks, or whatever). It will also include a sort $\mathcal{T}$ of time-points, a sort

$\mathcal{P}$ of parameters, and a sort $\mathcal{R}$ of values which parameters can take at specific time-points. In fact, models will be considered only in which terms of sort $\mathcal{R}$ are interpreted as real numbers, and terms of sort $\mathcal{T}$ are interpreted as non-negative reals. The sorting of the logic is summarised in Figure 2 below.

NAME OF SORT	SYMBOL	VARIABLES
Actions	$\mathcal{A}$	$a, a_1, a_2, \ldots$
Situations	$\mathcal{S}$	$s, s_1, s_2, \ldots$
Fluents	$\mathcal{F}$	$f, f_1, f_2, \ldots$
Times	$\mathcal{T}$	$t, t_1, t_2, \ldots$
Parameters	$\mathcal{P}$	$p, p_1, p_2, \ldots$
Reals	$\mathcal{R}$	$r, r_1, r_2, \ldots$
Domain objects	$\mathcal{X}$	$x, x_1, x_2, \ldots$
F-preds (predicate sort)	$\mathcal{H} = 2^{\mathcal{F}}$	$h, h_1, h_2, \ldots$
Valuations (function sort)	$\mathcal{V} : \mathcal{P} \mapsto \mathcal{R}$	$v, v_1, v_2, \ldots$

Figure 2

Figure 2 also includes the second order sorts $\mathcal{H}$ (f-preds) and $\mathcal{V}$ (valuations). F-preds, which are predicates ranging over fluents, are included so that the second-order version of Baker's solution to the frame problem [1] can be incorporated in the framework. They help in establishing a large enough space of situations in each model, so that the solution to the frame problem cannot be compromised by failing to take into account a particular hypothetical combination of fluents (see [1] for further explanation).

Valuations, which are functions from $\mathcal{P}$ to $\mathcal{R}$, are included here for an analogous reason. As stated in the introduction, and following the approach in [6], in the axiomatization given below a function *State* will be used to associate particular (half-open) intervals along the time line with a single situation. But in domains involving continuous change, the effects of a particular action may not depend only on which fluents hold throughout such intervals of time. They may also depend on the instantaneous values of the (continuously varying) parameters at the particular *instants* of time at which the action occurs. Therefore, to fully describe action preconditions it is sometimes necessary to be able to refer to specific parameters' values. Here (as in [1]) situations may be thought of as sets of fluents. Similarly, valuations are in effect sets of parameter values. Since action preconditions may be expressed partly in terms of parameter values, the *Result* function is extended here so as to range over valuations as well as over actions and situations. For example, the fact that turning a car ignition key starts the engine if the battery is connected and has sufficient voltage might be axiomatized using the fluents *Connected* and *EngineOn*, the parameter *Voltage* and the action *Turn*, as

$$\begin{aligned} & Holds(EngineOn, Result(Turn, v, s)) \leftarrow \\ & \quad [Holds(Connected, s) \ \wedge \ v(Voltage) > 12] \end{aligned}$$

The use of universally quantified variables of sort $\mathcal{V}$ effectively establishes a large enough space of sets of parameter values, irrespective of whether the values in a particular such set ever simultaneously occur at any point in time. This becomes especially important when attempting to describe all the hypothetical instantaneous circumstances under which an action (such as the overflow action in the example of the previous section) could be triggered. The formalisation below will incorporate a default assumption that a given hypothetical circumstance does not trigger a given action. To avoid problems analogous to the Yale Shooting Problem, it is therefore important not to index triggering information with a temporal argument.

The domain-independent predicate,function and constant symbols of the formalism are listed in Figure 3.

FUNCTION	SORT
Sit	$2^{\mathcal{F}} \mapsto \mathcal{S}$
$Result$	$\mathcal{A} \times \mathcal{V} \times \mathcal{S} \mapsto \mathcal{S}$
$State$	$\mathcal{T} \mapsto \mathcal{S}$
$Function$	$\mathcal{P} \times \mathcal{T} \mapsto \mathcal{R}$
$Values$	$\mathcal{T} \mapsto \mathcal{V}$
δ	$\mathcal{P} \mapsto \mathcal{P}$

PREDICATE	SORT
$Holds$	$\mathcal{F} \times \mathcal{S}$
Ab	$\mathcal{A} \times \mathcal{F} \times \mathcal{V} \times \mathcal{S}$
$Absit$	$2^{\mathcal{F}}$
$Happens$	$\mathcal{A} \times \mathcal{T}$
$Performed$	$\mathcal{A} \times \mathcal{T}$
$Triggers$	$\mathcal{V} \times \mathcal{S} \times \mathcal{A}$
$Continuous$	$\mathcal{P} \times \mathcal{T}$
$Differentiable$	$\mathcal{P} \times \mathcal{T}$
$Breaks$	$\mathcal{A} \times \mathcal{P} \times \mathcal{V} \times \mathcal{S}$
$InstantEffect$	$\mathcal{A} \times \mathcal{P} \times \mathcal{V} \times \mathcal{S} \times \mathcal{R}$
$<$	$\mathcal{R} \times \mathcal{R}$
$<$	$\mathcal{T} \times \mathcal{T}$

CONSTANT	SORT
$S0$	$\mathcal{S}$
all real numbers	$\mathcal{R}$
0 and all +ve real numbers	$\mathcal{T}$

Figure 3

3.2 Domain-independent Axioms

The following six domain-independent axioms, which do not directly concern continuous change, are included in every theory. All variables are assumed to be universally quantified with maximum scope unless otherwise stated. Axiom (F1) is a frame axiom. Note that, for the reasons described above, both the function *Result* and the predicate *Ab* range over valuations as well as situations. As usual, *Ab* is minimised to provide a non-monotonic solution to the frame problem. Axiom (ES1) is Baker's second order 'existence of situations' axiom (the second conjunct of which simply expresses the uniqueness-of-names property for *Sit* terms). *Absit* is minimised at a higher priority than *Ab* so as to establish a large enough space of situations in each minimal model (see [1] for further explanation).

$$\neg Ab(a, f, v, s) \rightarrow [Holds(f, Result(a, v, s)) \leftrightarrow Holds(f, s)] \tag{F1}$$

$$\begin{aligned} &[\neg Absit(h) \rightarrow [Holds(f, Sit(h)) \leftrightarrow h(f)]] \wedge \\ &\qquad [Sit(h_1) = Sit(h_2) \rightarrow (h_1(f) \leftrightarrow h_2(f))] \end{aligned} \tag{ES1}$$

$$State(t) = S0 \leftarrow \neg\exists a_1, t_1[Happens(a_1, t_1) \ \wedge \ t_1 < t] \tag{N1}$$

$$\begin{aligned} &State(t) = Result(a_1, Values(t_1), State(t_1)) \leftarrow \\ &\qquad [Happens(a_1, t_1) \ \wedge \ t_1 < t \wedge \\ &\qquad \neg\exists a_2, t_2[Happens(a_2, t_2) \wedge t_1 < t_2 \wedge t_2 < t]] \end{aligned} \tag{N2}$$

$$[Happens(a_1, t) \wedge Happens(a_2, t)] \rightarrow a_1 = a_2 \tag{N3}$$

$$Happens(a, t) \leftrightarrow \ [Performed(a, t) \vee Triggers(Values(t), State(t), a)] \tag{N4}$$

Axioms (N1)–(N4) concern the narrative aspect of each theory. Axioms (N1) and (N2) associate half-open intervals along the time line to situations in a straightforward way. (N2) is shorter than its counterpart in [6], because the simplifying assumption is made here that two or more actions do not occur simultaneously – this assumption is expressed in Axiom (N3). The issue of concurrency is orthogonal to the main concerns of this paper. To deal with concurrency and the combined effects of simultaneous actions, the axioms can be extended in the manner described in [6].

Axiom (N4) provides a definition of *Happens* in terms of the predicates *Performed* and *Triggers*. It expresses that an action A happens at a particular time T either if it is performed at T (implicitly by an external agent), or if it is triggered by the instantaneous set of circumstances at T. This set of circumstances is captured partly by the situation term $State(T)$, which enables indirect reference to the set of fluents which hold at T, and partly by the valuation term $Values(T)$, which represents the instantaneous values of all parameters at T.

Both the predicates *Performed* and *Triggers* are minimised (this is discussed in more detail below).

To deal with continuous change, two extra function symbols, *Function* and δ, have been included in the language (see Figure 3). Mathematically, parameters can be regarded as functions of time. To reflect this, *Function* takes a parameter and a time point and returns a real number. Axiomatizations of the usual mathematical definitions of continuity and differentiability, in terms of the predicates *Continuous* and *Differentiable*, are assumed, as well as an appropriate definition of the operator $\frac{\partial}{\partial t}$ (see appendix). Given a parameter P, the term $\delta(P)$ names the 'derivative of P'. Hence the following two axioms are included in every theory.

$$Values(t)(p) = Function(p, t) \tag{C1}$$

$$Differentiable(p, t) \rightarrow Function(\delta(p), t) = \frac{\partial}{\partial t} Function(p, t) \tag{C2}$$

To respect the convention regarding parameter values at end points of half-open intervals of time, described at the beginning of Section 2, it is sufficient to axiomatize the mathematical constraint that, at every time-point, the function associated with each parameter is left-hand continuous:

$$\begin{aligned}\forall p,t,r \exists t_1 \forall t_2 [[t_2 < t \wedge (t - t_2) < t_1 \wedge 0 < r] \rightarrow \\ |Function(p, t) - Function(p, t_2)| < r]\end{aligned} \tag{C3}$$

To describe instantaneous changes in the values of parameters at times when actions occur, and discontinuities in their corresponding functions of time, the predicates *InstantEffect* and *Breaks* are introduced. Both predicates are minimised. $InstantEffect(A, P, V, S, R)$ should be read as 'in the circumstance represented by the valuation V and situation S, the action A causes the parameter P to instantaneously take on the value R'. More precisely, Axiom (C6) below states that if A also happens at time T, and V and S describe the circumstances at T, then R is the value of the right-hand limit of P at T. (In fact, *InstantEffect* is not used in the domain specific axioms of the next section, describing the water tanks example. But it is useful for domains such as Sandewall's 'bouncing ball' scenario [9], where it is necessary to express that a 'bounce' action instantaneously reverses the horizontal velocity of a moving ball.)

$Breaks(A, P, V, S)$ can be read as 'in the circumstance represented by the valuation V and situation S, the action A can potentially cause a discontinuity in parameter P'. This predicate is somewhat analogous to the predicate Ab, but with its second argument of sort $\mathcal{P}$ rather than $\mathcal{F}$. The following four domain-independent axioms make direct use of *InstantEffect* and *Breaks*. Axiom (C4) can be regarded as a kind of 'frame axiom' for parameters.

$$\neg[Happens(a,t) \wedge Breaks(a,p,Values(t),State(t))] \rightarrow [Continuous(p,t) \wedge Differentiable(p,t)] \tag{C4}$$

$$Breaks(a,p,v,s) \rightarrow Breaks(a,\delta(p),v,s) \tag{C5}$$

$$[InstantEffect(a,p,Values(t),State(t),r) \wedge Happens(a,t)] \rightarrow \forall r_1 \exists t_1 \forall t_2 [[t < t_2 \wedge (t_2 - t) < t_1 \wedge 0 < r_1] \rightarrow |Function(p,t_2) - r| < r_1] \tag{C6}$$

$$[InstantEffect(a,p,v,s,r) \wedge v(p) \neq r] \rightarrow Breaks(a,p,v,s) \tag{C7}$$

Finally, an axiom is needed expressing the condition of piecewise continuity:

$$\exists r \forall a_1, t_1, a_2, t_2 [[Happens(a_1,t_1) \wedge Happens(a_2,t_2) \wedge t_1 < t_2] \rightarrow 0 < r \leq (t_2 - t_1)] \tag{C8}$$

Circumscription will be used here to model the various modes of default reasoning associated with narrative domains involving continuous change. The predicates *Absit*, *Ab*, *Performed*, *Triggers*, *InstantEffect* and *Breaks* all need to be minimised. The exact circumscription policy and its effects will be discussed in the next section, following an axiomatization of the water tanks example.

4 An Axiomatization of the Water Tanks Example

The following constant symbols will be used to axiomatize the water tanks example of Section 2. $TurnOnC$, $TurnOnD$ and $StartSpillB$ of sort $\mathcal{A}$, $OpenC$, $OpenD$ and $OverflowingB$ of sort $\mathcal{F}$, and $LevelA$, $LevelB$, $FlowC$ and $FlowD$ of sort $\mathcal{P}$. Uniqueness-of-names axioms are assumed which state that the constants of each sort are distinct, and that each ground term of sort $\mathcal{P}$ constructed with the function δ is distinct from any other. As in Section 2, the meta-variables T_1 and T_2 of sort $\mathcal{T}$ and L, H_B and K of sort $\mathcal{R}$ are also used in the axiomatization below – these should simply be thought of as real number constants.

Given the domain-independent axioms of the previous section, the example can now be described with 27 extra domain-dependent axioms. For readability they are grouped below into 'action rules', 'instantaneous effect rules', 'initial situation facts', 'occurrence facts', 'triggering rules', 'initial value facts' and 'equality constraint rules'. In axioms (T17)–(T27) below, abbreviations have been used for terms of sort $\mathcal{R}$ constructed with the function symbols *Function* and δ. For example, the terms $Function(FlowC,0)$ and $Function(\delta(LevelA),t)$ have been abbreviated to '$FlowC(0)$' and '$LevelA'(t)$' respectively.

Action rules:

$$Holds(OpenC, Result(TurnOnC, v, s)) \tag{T1}$$
$$Holds(OpenD, Result(TurnOnD, v, s)) \tag{T2}$$
$$Holds(OverflowingB, Result(StartSpillB, v, s)) \tag{T3}$$

Instantaneous effect rules:

$$Breaks(TurnOnC, FlowC, v, s) \tag{T4}$$
$$Breaks(TurnOnC, \delta(LevelA), v, s) \tag{T5}$$
$$Breaks(TurnOnC, \delta(LevelB), v, s) \leftarrow \neg Holds(OverflowingB, s) \tag{T6}$$
$$Breaks(TurnOnD, FlowD, v, s) \tag{T7}$$
$$Breaks(TurnOnD, \delta(LevelA), v, s) \tag{T8}$$
$$Breaks(TurnOnD, \delta(LevelB), v, s) \leftarrow \neg Holds(OverflowingB, s) \tag{T9}$$
$$Breaks(StartSpillB, \delta(LevelB), v, s) \tag{T10}$$

Initial situation facts:

$$\neg Holds(OpenC, S0) \tag{T11}$$
$$\neg Holds(OpenD, S0) \tag{T12}$$
$$\neg Holds(OverflowingB, S0) \tag{T13}$$

Occurrence facts:

$$Performed(TurnOnC, T_1) \tag{T14}$$
$$Performed(TurnOnD, T_2) \tag{T15}$$

Triggering rules:

$$\begin{aligned}&[v(LevelB) = H_B \wedge v(\delta(LevelB)) > 0] \\ &\qquad \rightarrow Triggers(v, s, StartSpillB)\end{aligned} \tag{T16}$$

Initial value facts:

$$LevelA(0) = L \tag{T17}$$
$$LevelB(0) = 0 \tag{T18}$$
$$FlowC(0) = 0 \tag{T19}$$
$$FlowD(0) = 0 \tag{T20}$$

Equality constraint rules:

$$LevelA'(t) = -(FlowC(t) + FlowD(t)) \tag{T21}$$
$$Holds(OverflowingB, State(t)) \rightarrow LevelB'(t) = 0 \tag{T22}$$

$$\neg Holds(OverflowingB, State(t)) \rightarrow LevelB'(t) = FlowC(t) + FlowD(t) \tag{T23}$$

$$Holds(OpenC, State(t)) \rightarrow FlowC(t) = K.LevelA'(t) \tag{T24}$$

$$\neg Holds(OpenC, State(t)) \rightarrow FlowC(t) = 0 \tag{T25}$$

$$Holds(OpenD, State(t)) \rightarrow FlowD(t) = K.LevelA'(t) \tag{T26}$$

$$\neg Holds(OpenD, State(t)) \rightarrow FlowD(t) = 0 \tag{T27}$$

The aim in considering this example is to construct a representation, in a principled way, from which the trajectories (S1)–(S16) can be inferred (in the relevant time intervals). Let Π_{wt} be the theory consisting of the domain independent axioms (F1), (ES1), (N1)–(N4) and (C1)–(C8), together with the domain dependent axioms (T1)–(T27) and uniqueness-of-names axioms for actions, fluents and parameters. By itself, Π_{wt} does not entail these trajectories. As discussed above, various modes of default reasoning also need to be represented – namely the assumptions that by default a given action does not affect a given fluent, that by default a given action does not occur at a given time point, that by default a given set of parameter values does not trigger a given action, and that by default a given action occurrence does not result in a discontinuity for a given parameter. Prioritized and parallel circumscription will be used here to model these assumptions (see [4] for a full explanation of the notation used below). The complete representation of the domain is

$$CIRC[\Pi_{wt} \ ; \ Absit > Ab, Performed, Triggers, InstantEffect, Breaks \ ; \\ Holds, Sit, Result, S0, Happens, State, Values, Function, \delta]$$

This expression will be referred to as $CIRC_{cc}[\Pi_{wt}]$. Much further investigation needs to be done to ascertain the extent to which $CIRC_{cc}$ is an appropriate policy in general for domains involving continuous change. It could be, for example, that for other domains extra priorities have to be introduced. However, it is not hard to show that it yields the correct results in the case of the water tanks example. The full proof of this is somewhat tedious, but the following is an outline of its main steps.

Given any model M of Π_{wt}, a corresponding model M' can be constructed with the same universe of discourse, which contains the same interpretations for all ground action, fluent and parameter terms, and which is also a model for Axioms (circ1)–(circ6) below. (M' is constructed using the trajectories (S1)–(S16) to define the interpretations of $Function$ and $Values$, and equating $S0$ and all situation terms constructed with the $Result$ function to an appropriate Sit term. $State(T)$ is equated with $S0$ for $T \leq T_1$, with $Result(TurnOnC, Values(T_1), S0)$ for $T_1 < T \leq T_2$, etc.) In (circ6), n is a variable whose sort is the natural numbers and $NthDerivative(P_1, P_2, N)$ means 'P_1 is the Nth derivative of P_2'. (This of course assumes an appropriate axiomatization of the naturals, and an appropriate definition of $NthDerivative$[1] in terms of the function symbol δ.

[1]E.g. $NthDerivative(p_1, p_2, n) \leftrightarrow$
$([n = 0 \wedge p_1 = p_2] \vee [n = n_1 + 1 \wedge p_1 = \delta(p_3) \wedge NthDerivative(p_3, p_2, n_1)])$

NthDerivative should be regarded as a temporary definitional extension of the language.)

$$\neg Absit(h) \tag{circ1}$$

$$\neg InstantEffect(a,p,v,s,r) \tag{circ2}$$

$$\begin{aligned} & Ab(a,f,v,s) \leftrightarrow \\ & \quad [[a = TurnOnC \wedge \neg Holds(OpenC,s)] \vee \\ & \quad\; [a = TurnOnD \wedge \neg Holds(OpenD,s)] \vee \\ & \quad\; [a = StartspillB \wedge \neg Holds(OverflowingB,s)]] \end{aligned} \tag{circ3}$$

$$\begin{aligned} & Performed(a,t) \leftrightarrow \\ & \quad [[a = TurnOnC \wedge t = T_1] \vee \\ & \quad\; [a = TurnOnD \wedge t = T_2]] \end{aligned} \tag{circ4}$$

$$\begin{aligned} & Triggers(v,s,a) \leftrightarrow \\ & \quad [a = StartSpillB \wedge v(LevelB) = H_B \wedge v(\delta(LevelB)) > 0] \end{aligned} \tag{circ5}$$

$$\begin{aligned} & Breaks(a,p,v,s) \leftrightarrow \\ & \quad [[a = TurnOnC \wedge \exists n.NthDerivative(p, FlowC, n)] \vee \\ & \quad\; [a = TurnOnC \wedge \exists n.NthDerivative(p, \delta(LevelA), n)] \vee \\ & \quad\; [a = TurnOnC \wedge \exists n.NthDerivative(p, \delta(LevelB), n) \\ & \qquad\qquad\qquad \wedge \neg Holds(OverflowingB,s)] \vee \\ & \quad\; [a = TurnOnD \wedge \exists n.NthDerivative(p, FlowD, n)] \vee \\ & \quad\; [a = TurnOnD \wedge \exists n.NthDerivative(p, \delta(LevelA), n)] \vee \\ & \quad\; [a = TurnOnD \wedge \exists n.NthDerivative(p, \delta(LevelB), n) \\ & \qquad\qquad\qquad \wedge \neg Holds(OverflowingB,s)] \vee \\ & \quad\; [a = StartspillB \wedge \exists n.NthDerivative(p, \delta(LevelB), n)]] \end{aligned} \tag{circ6}$$

It is clear that, since the 'if' halves of (circ3)–(circ6) follow from Π_{wt}, the interpretations in M' of all the predicates to be minimised must each be contained in their corresponding interpretations in M. In other words, since M is an arbitrary model of Π_{wt}, (circ1)–(circ6) are entailed by $CIRC_{cc}[\Pi_{wt}]$. It is therefore sufficient to show that the trajectories (S1)–(S16) follow from $\Pi^+_{wt} = \Pi_{wt} \cup \{(\text{circ1}), \ldots, (\text{circ6})\}$.

Axiom (C8), expressing the property of piecewise continuity, plays a crucial role in the derivation of (S1)–(S16) from Π^+_{wt}. For example, to derive (S1)–(S4) in the region $[0, T_1]$, axioms (N4), (T18), (circ4) and (circ5) are first used to establish that no action occurs at time 0. Axiom (C8) ensures that there can only be a finite number of time points in $[0, T_1]$ at which actions occur, and hence that (by (circ4)) there exists a least such time point. Finally, using (N1), (N4), (T11)–(T13), (T21), (T23), (T25), (T27) and (circ5), it is possible to show that if this least time point were before T_1 this would contradict either the continuity condition of axiom (C4), or the left-hand continuity condition of axiom (C6).

5 Discussion

The formalism developed in this paper is in some respects similar to the extended Situation Calculus of Pinto [7], in that in both approaches it is possible to describe mathematical constraints between parameters, as well as their explicit trajectories. The main advantage of the approach described here over Pinto's is that it deals with what Pinto describes as 'inter-state constraints', by introducing axioms and default reasoning mechanisms involving the predicates $InstantEffect$ and $Breaks$. It also avoids the need to 'name' many different types of mathematical function, and encode various properties of these names, and avoids the need to identify a special class of 'natural' actions as the only type of action that can be triggered.

There is an important advantage of both the axiomatization presented here and Pinto's over approaches which depend on encapsulating the behaviour of at least one parameter inside an explicit $Trajectory$ predicate (or similar), e.g. [11], [13], [12]. This is that information about a parameter's behaviour, in the form of various mathematical constraints, may be distributed in a natural way throughout the domain-dependent part of the theory. For example, in the water tanks scenario the mathematical knowledge of the domain is expressed in axioms (T17)–(T27); it was not necessary to solve the relevant sets of simultaneous differential equations before axiomatizing the domain. Hence these formalisms may be used together with various mathematical techniques or modes of mathematical reasoning as and where necessary (Pinto assumes the availability of an 'oracle' to deal with mathematical aspects of his theories). For example, once the Situation Calculus has been used to establish that a collection of mathematical constraints holds during a particular interval, numerical methods may be used to solve these constraints simultaneously.

In this paper, attention has been restricted to domains in which the set of time points at which actions occur is sparse, i.e. where every finite interval of time contains only a finite number of such points. Further work needs to be done in investigating the consequences of lifting this restriction. Davis [2] provides an interesting general discussion of this and related issues.

As regards default reasoning about discontinuities, the water tanks example shows that, on its own, Sandewall's default mechanism [9] for inferring continuity of parameters across breakpoints (which builds on the idea of *chronological minimisation*) is not always sufficient. In the example, a choice has to be made at particular time points between discontinuities in some parameters or discontinuities in others. The introduction and minimisation here of the predicate $Breaks$ allows such choices to be made based partly on domain-specific information.

As Sandewall points out [9], 'qualitative reasoning' is as much a part of mathematics as 'quantitative reasoning'. Ordinary mathematical language together with standard logic is rich enough to express incomplete knowledge about the functions associated with particular parameters, perhaps using mathematical inequalities or existentially quantified numerical variables. For example, some forms of qualitative reasoning could be achieved within the framework described in this paper using 'constraint rules' such as

$$Holds(OpenC, State(t)) \rightarrow LevelA'(t) > 0$$

$$Holds(OpenC, State(t)) \rightarrow \exists r[FlowC(t) = r.LevelA'(t)]$$

As mentioned in Section 4, further work needs to be done in examining the general properties of the circumscription policy $CIRC_{cc}$. However, its effect as regards the water tanks example is quite straightforward. The fact that axioms (circ1)–(circ6) are entailed by the circumscribed theory shows that, in this case, the various default assumptions are 'mutually independent'. Although this will clearly not always be the case, it could be that for a class of domains at least, some kind of 'separation property' could be proved (analogous to Theorem 3.1 in [6]), perhaps showing the equivalence of sentences such as $CIRC_{cc}[\Pi_{wt}]$ to conjunctions of more manageable expressions. It also seems likely that for domains such as Π_{wt}, circumscription could be replaced by some more specialised procedure for generating expressions such as (circ1)–(circ6), which are, in effect, simply a form of closure axiom for each minimised predicate. (circ3), for example, is analogous to a conjunction of Reiter's *successor state axioms* [8].

In [3], Gelfond, Lifschitz and Rabinov briefly discuss a somewhat different approach to representing continuous change in the Situation Calculus. Periods of continuous change are represented as actions with a non-zero duration. However, it is unclear how phenomena such as triggered action occurrences would be represented using this type of approach.

Acknowledgements

Many thanks to Eugenia Ternovskaia for helpful comments on an earlier draft of this paper, and to Murray Shanahan for useful discussions on this topic. This research was funded by the U.K. Engineering and Physical Sciences Research Council (EPSRC).

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Appendix: Some Mathematical Details

The following axioms provide appropriate definitions of continuity and differentiability. To define derivatives a new function sort is needed, $\mathcal{M} : \mathcal{P} \times \mathcal{T} \mapsto \mathcal{R}$. Notice that *Function* is of sort $\mathcal{M}$. The function $\frac{\partial}{\partial t}$ is of sort $\mathcal{M} \mapsto \mathcal{M}$. The term $\frac{\partial}{\partial t} Function(p,t)$ which appears in Axiom (C2) should more properly be written as $\frac{\partial}{\partial t}(Function)(p,t)$.

$$\begin{aligned} &Continuous(p,t) \leftrightarrow \\ &\qquad \forall r \exists t_1 \forall t_2 [[|t - t_2| < t_1 \wedge 0 < r] \\ &\qquad\qquad \rightarrow |Function(p,t) - Function(p,t_2)| < r] \end{aligned} \tag{A1}$$

$$\begin{aligned} &Differentiable(p,t) \leftrightarrow \\ &\qquad \exists r \forall r_1 \exists t_1 \forall t_2 [[0 < |t - t_2| < t_1 \wedge 0 < r_1] \\ &\qquad\qquad \rightarrow |(\tfrac{Function(p,t) - Function(p,t_2)}{t - t_2}) - r| < r_1] \end{aligned} \tag{A2}$$

$$\begin{aligned} &[Differentiable(p,t) \wedge \tfrac{\partial}{\partial t}(Function)(p,t) = r] \rightarrow \\ &\qquad \forall r_1 \exists t_1 \forall t_2 [[0 < |t - t_2| < t_1 \wedge 0 < r_1] \\ &\qquad\qquad \rightarrow |(\tfrac{Function(p,t) - Function(p,t_2)}{t - t_2}) - r| < r_1] \end{aligned} \tag{A3}$$