Strong Normalisation in the π -Calculus

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We introduce a typed π -calculus where strong normalisation is ensured by typability. Strong normalisation is a useful property in many computational contexts, including distributed systems. In spite of its simplicity, our type discipline captures a wide class of converging name-passing interactive behaviour. The proof of strong normalisability combines methods from typed λ -calculi and linear logic with process-theoretic reasoning. It is adaptable to systems involving state, polymorphism and other extensions. Strong normalisation is shown to have significant consequences, including finite axiomatisation of weak bisimilarity, a fully abstract embedding of the simply-typed λ -calculus with products and sums and basic liveness in interaction. Strong normalisability has been extensively studied as a fundamental property in functional calculi, term rewriting and logical systems. This work is one of the first steps to extend theories and proof methods for strong normalisability to the context of name-passing processes.

Key Words: concurrency theory, the π -calculus, strong normalisation, type theory

1. INTRODUCTION

Background. The formal study of types in programming languages and computational calculi has led to the understanding that types can ensure a wide range of desirable computational properties, ranging from error-free execution to precise logical specification of program behaviour. One important property in this context, widely found in typed λ -calculi, is *strong normalisation* (SN), which says that computation in programs necessarily terminates regardless of evaluation strategy. This is interesting from a logical viewpoint especially because, by the correspondence between proofs and programs, SN of certain λ -calculi implies consistency of the corresponding logical systems. For this reason, functional calculi and logics have been the main focus in the study of strong normalisability.

The significance of SN is, however, not limited to this traditional setting. SN is also interesting in the context of communicating processes. As an example, consider a distributed client-server interaction: when a client requests some service, s/he may naturally wish the computation on the server's side to terminate and return an answer. SN is thus a basic requirement for, say, interaction between banks and their customers. As another example, the

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resource preservation guaranteed by SN has been one of the main reasons for Gunter and his colleagues to develop their typed programming language for active networks (PLAN) [25,54] on the basis of a simply typed λ -calculus. Such languages would in general require primitives for communication and concurrency. This suggests a systematic effort to extend the accumulated theories of functional SN types to the realm of interactivity is a worthwhile endeavour.

We are thus motivated to reposition and study strong normalisability in the context of process theory. In particular, is there a basic typed process calculus in which strongly normalising functional calculi are faithfully embeddable? By faithful, we mean that typability of the encoding automatically ensures strong normalisability of the source calculus. More ambitiously, can we obtain exact semantic correspondence, including full abstraction and full completeness? Obtaining affirmative answers to these questions would not be of mere theoretical interest: since typed λ -calculi offer a basic theory of procedure calls, a fundamental abstraction in programming, embeddability of SN functional calculi would capture interactive behaviour powerful enough to involve non-trivial procedural calls while maintaining SN. Exploration of strong normalisability in this broader context might also shed new light on typed functional computation itself.

The present work is a trial in this direction, introducing a typed π -calculus in which firstorder strongly normalising λ -calculi are fully abstractly embeddable. The type discipline simply adds causal chains to the system introduced in [11] where we established a fully abstract encoding of PCF. This small addition radically changes the class of typable process behaviour, turning possibly diverging computation into a strongly normalising one. As would be imagined by the embeddability of typed λ -calculi, the proof of SN is non-trivial, defying naive structural induction. We adapt methods developed for strongly normalising λ -calculi [8, 23, 61], combined with process-algebraic reasoning techniques [11, 51, 53, 57, 66]. As far as we know, this is the first time a compositional principle for ensuring SN has been established for name passing processes with non-trivial use of replication. The proof method for SN is applicable to significant extensions of the presented formalism, including state and polymorphism [12, 32, 35, 67, 68]. Further discussions on these extensions are found in Section 7. In the following, we outline key technical ideas and relate our work to the existing literature.

The π -**Calculus.** Following [11], we use an asynchronous variant of the π -calculus [31]. Computation in this calculus is generated by interaction between processes.

$$x(\vec{y}) \cdot P \mid \overline{x} \langle \vec{v} \rangle \longrightarrow P\{\vec{v}/\vec{y}\}$$

Here \vec{y} denotes a potentially empty vector $y_1...y_n$, | denotes parallel composition, $x(\vec{y}).P$ is input, and $\overline{x}\langle \vec{v} \rangle$ is asynchronous output. Operationally this reduction represents the consumption of an asynchronous message by a receptor. The idea extends to a receptor with replication

$$!x(\vec{y}).P | \overline{x} \langle \vec{v} \rangle \longrightarrow !x(\vec{y}).P | P\{\vec{v}/\vec{y}\},$$

where the replicated process remains in the configuration after reduction, which behaves as a shared resources or a remote server. As a simple example of a process, first consider the *forwarder* agent Fw(ab)

$$\mathsf{Fw}\langle ab\rangle \stackrel{\mathrm{def}}{=} !a(x).\overline{b}\langle x\rangle$$

which repeatedly inputs a value at a and outputs it immediately at b. As another example, the following is a client which requests, via a, to have a value returned via a private name c

 $\overline{a}(c) c(y) P$

where $\overline{a}(c)c(y).P$ stands for $(vc)(\overline{a}\langle c \rangle | c(y).P)$ with (vc) being a restriction operator. Using these agents, *R* below is a simple way to represent what may be regarded as a denial of service at *c*.

 $R \stackrel{\text{def}}{=} Fw \langle aa \rangle | \overline{a}(c) c(y) . P$

This process does not directly demonstrate circularity as in the example above. However, since *R* causes an infinite reduction sequence, the receptor c(y).*P* waits forever for an answer at *c*. In an untyped setting, *R* is equal to $\overline{a}(c) c(y)$.*P* up to asynchronous bisimilarity [31], but the two are quite different regarding resource consumption. The next example shows how subtleties arise through new link creation of the π -calculus.

$$a(x)$$
. Fw $\langle bx \rangle | \overline{a}(c)$ Fw $\langle cb \rangle | \overline{b}$

After one step reduction via a, we obtain

$$Fw\langle bc \rangle | Fw\langle cb \rangle | \overline{b}$$

which exhibits divergence.

Type Discipline for SN. The type discipline of this paper is a simple refinement of [11]. Concretely, the system is based on two central ideas:

(1) *Linear types* [22, 42, 44, 66], which ensure that a channel is used exactly once for input/output and, for a replicated channel, an input occurs exactly once and output occurs zero or more times [11, 40, 50, 53, 57].

(2) Action types with causality, where causality is represented by edges in a directed graph whose acyclicity ensures the absence of circular dependencies [42, 44, 66], cf. [22]. Transmission of causality is controlled by a form of *cut elimination* in action types.

Let us illustrate these points by examples. In the standard typing system of the π -calculus [50, 64], Fw $\langle ab \rangle$ is typed as follows:

$$\vdash \mathtt{Fw}\langle ab \rangle \triangleright a : (\mathsf{T}) \otimes b : (\mathsf{T})$$

where $a:(\tau)$ represents that name *a* inputs or outputs value with type τ ; \otimes represents the disjoint union of channel types (often written " $a:(\tau), b:(\tau)$ "). As first refinement, we attach *action modes* to types to ensure the linearity of channels. To simplify discussions, here we use only two modes, "!" and "?", which represent *unique server* and *client requests to server*, respectively. Let us assume $F_{W}\langle ab \rangle \stackrel{\text{def}}{=} !a.\overline{b}$ which does not carry any name for simplifying examples. This process has the following type.

$$\vdash \mathsf{Fw}\langle ab\rangle \triangleright a:()^! \otimes b:()^? \tag{1}$$

This type means that a unique replicated input (server) exists at a and b is a channel that is used for service requests from a unique replicated server at b [10, 11, 27, 57]. When

composing processes, cut elimination occurs between input and output on a shared name with dual types. Here ! and ? are dual to each other, cf. [22], so that cut elimination occurs between ()! and ()?, resulting in ()! since the server can always consume a client request. Thus the composition of Fw(ab) and Fw(bc) is typed as:

$$\vdash \operatorname{Fw}\langle ab\rangle | \operatorname{Fw}\langle bc\rangle \triangleright a: ()^{!} \otimes b: ()^{!} \otimes c: ()^{?}.$$

$$(2)$$

The ideas similar to the refinement above were already presented in [10, 11, 27, 42, 57]. But none of those typing disciplines ensures termination of processes. In fact, the diverging process in (1) is still typable as follows.

$$\vdash \operatorname{Fw}\langle bc \rangle | \operatorname{Fw}\langle cb \rangle \triangleright b: ()^{!} \otimes c: ()^{!}$$
(3)

In the light of such examples, the second refinement introduces the idea to record causality of behaviour in types. For example, Fw(ab) is now typed as follows:

$$\vdash \mathtt{Fw}\langle ab\rangle \triangleright a: ()^{!} \rightarrow b: ()^{?}$$

Here $a: ()^! \to b: ()^?$ indicates that the process repeatedly inputs at *a* and then outputs at *b*. Cut elimination now occurs between dual input and output by keeping the causality between channels. For example, we have:

$$(a:()^{!} \to b:()^{?}) \otimes (b:()^{!} \to c:()^{?}) = (a:()^{!} \to c:()^{?}) \otimes (b:()^{!} \to c:()^{?})$$

hence we can type the process in (2) as:

$$\vdash \mathtt{Fw}\langle ab\rangle | \mathtt{Fw}\langle bc\rangle \triangleright a: ()^{!} \rightarrow c: ()^{?} \otimes b: ()^{!} \rightarrow c: ()^{?}$$

Now we can detect a cyclic dependency such as Fw(bc) | Fw(cb) in (3) by looking at their types $b: ()^? \rightarrow c: ()^?$ and $c: ()^! \rightarrow b: ()^?$ [32, 40, 66] (which, when combined, induces a vicious circle). This simple causality information turns the system with possibly diverging processes [10, 11] into a strongly normalising one. The type discipline based on these ideas is formally presented in Section 2.

Proving SN for the π -**Calculus.** To prove SN for typable processes, the first idea would be, in the light of the previous examples, to show that reduction steps follow a non-circular ordering on free channels, e.g. the reductions of $\overline{a}\langle v \rangle |Fw \langle ab \rangle |Fw \langle bc \rangle$ proceed at *a*, *b* and *c* in this order, but in $\overline{a}\langle v \rangle |Fw \langle ab \rangle |Fw \langle ba \rangle$ are repeated between *a* and *b*. However, due to creation of new links and replication of terms, both being crucial features of π -calculi, such reasoning is infeasible, at least in its naive form. To see this, consider the following process which only adds one name restriction " $\overline{a}(c)$ " to CCS term:

$$|a(x).(\overline{x}|\overline{x})| \overline{a}(c) F_{W}\langle cb \rangle | !b.(\overline{a}\langle y \rangle | \overline{a}\langle y \rangle)$$
(4)

(this process is typable by $a:(()^?)! \otimes b:()! \to y:()^?$ as we shall see later). The process owns reductions first at *a*, then at *b*, then at *a* again. Further, the number of redexes increases exponentially in its course, *but* the computation terminates. Such behaviour occurs when a process requests the same resource more than once in an interaction, e.g. in an encoding of

the λ -term $\lambda xyz.((xz)(yz))$ [49]. The difficulty in analysing (4) can be seen by considering the following subterm of a one step descendant of (4).

 $(\mathbf{v} c)(\overline{c} \,|\, \overline{c} \,|\, \mathbf{Fw} \langle cb \rangle)$

It contains a chain $c \to b$, which is difficult to determine before *c* is passed. But if we naively represent causality incorporating bound names in (4), there is a circular chain $a \to c \to b \to a$, although this cycle never arises in actual interaction. How can we then prove termination? Simple structural inductions would not be usable for the same reason they do not work in typed λ -calculi [8, 20].

The idea we use is suggested by SN proofs for typed λ -calculi, due to, among others, Tait [61]. His method employs a semantic interpretation of each type $[\sigma]$ as a collection of strongly normalising λ -terms, and shows that all typable terms are indeed in these sets. A key step is to prove that $\lambda x : \sigma . M \in [[\sigma \to \tau]]$ for each $M : \tau$ (for which by induction $M \in [[\tau]]$), which means, by definition, $(\lambda x.M)N \in [\tau]$ for each $N \in [\sigma]$. But all semantic types have the property that $M\{N/x\} \in [[\tau]]$ and $(\lambda x.M)N \longrightarrow M\{N/x\}$ imply $(\lambda x.M)N \in [[\tau]]$, hence we have only to show $M\{N/x\} \in [[\tau]]$. To be able to do this we strengthen the induction hypothesis $M \in [\tau]$ to $M \in [\tau]_{\rho}$ for each environment ρ , mapping each variable of type σ to some term in $[\sigma]$. Now the result is immediate [8, 20]. While we cannot use an identical framework due to the different nature of reduction in the π -calculus, a similar technique works "for the induction to go through". A key observation concerns the close correspondence between the substitution $M\{N/x\}$ and the consumption of a message $\overline{x}\langle v \rangle$ by a replicated process !x(y).Q. Thus, at each induction step, we prove that $P|(R_1|...|R_n)$ converges for each possible "environment" $R_1 | ... | R_n$ which complements P. Termination behaviour is calculated via the extended reduction suggested by strong bisimilarity (which does not change termination) together with replication theorems [11, 51, 57]. Finally acyclicity in causality yields strong normalisation.

Summary of Contributions. The following summaries main technical contributions of the present paper. (4) solves an open problem in [49] for the simple type hierarchy.

(1) Introduction of a linear π -calculus in which where strong normalisability is ensured by typability.

(2) Establishment of the proof methodology for strong normalisability of typable processes, combining ideas from traditional SN proofs for typed λ -calculi with process-theoretic reasoning. We also show the result extends to the linear π -calculus with free name passing via encoding.

(3) Establishment of the finite axiomatisation of the weak bisimilarity in linear processes as a consequence of strong normalisability. The axiomatisation yields an effective procedure to compute equality over linear processes via their normal forms.

(4) Embedding, using Milner's encoding [49], of the simply typed λ -calculus with sums and products ($\lambda_{\rightarrow,\times,+}$) into our typed π -calculus. The embedding is fully abstract w.r.t. the observational congruence of $\lambda_{\rightarrow,\times,+}$, justifying all commutative conversions and η -equations [6, 18, 19, 23], automatically leading to SN in the source calculus.

(5) Establishment of a basic interaction-based liveness property in linear processes via their strong normalisability, bridging the traditional notion of SN and one of the basic properties in concurrent, interactive computation.

Related Work. Strong normalisation in typed λ -calculi has been studied extensively in the past; detailed surveys can be found in [8, 20]. The present paper shows that traditional methods for proving SN can be adapted to interacting processes, suggesting their applicability to a new domain.

Abramsky extends the Curry-Howard correspondence to linear logic [22] using proof expressions (which are proof nets in term form), and proves their SN [1], guiding our present usage of acyclicity in names. This programme is taken further with realisability semantics of linear logic in [5] where CCS processes act as realisers, using renaming operators for typed process composition [27]. The operational structure of [5] follows his own π -calculus encoding of proof nets [2], offering a process-algebraic understanding of semantics of linear logic. The appeal of realisability lies in treating semantics and syntax uniformly on a logical basis. In the context of SN types for the π -calculus, sharing of names and dynamic link creation in the π -calculus would make it difficult to directly apply the framework in [1, 5]. In comparison, the present work offers a basic type discipline which does not directly correspond to known logical systems but which is based on algebra of processes and simple operational principles, resulting in a new effective method to ensure SN for name passing processes.

As our initial example of server-client interaction suggests, SN in processes is closely related to liveness. Yoshida [66] presents a typed π -calculus with a local liveness property. Kobayashi and his colleagues [38, 40–42] propose several typing systems which ensure different forms of liveness; for example [41] time quotas are assigned to communications for this purpose. Sangiorgi [56] proposes a typing system to guarantee what he calls receptiveness, which means that an appropriate input prefix is always available. Unlike the present work, these and other preceding typing systems for π -calculi [11, 26, 27, 55, 57] do not guarantee SN and the associated liveness properties for processes involving non-trivial use of replication. As a result, embeddability of, say, λ_{\rightarrow} in these systems does not guarantee the SN of the source calculus.

Since the present work was reported in [68], Sangiorgi has proposed a strong normalising typing system for the π -calculus with summation and first order recursive agents. He explicitly adds a global name ordering in processes [58] (this ordering is close to a property derived in our typing system, cf. Proposition 2.1) to ensure strong normalisation. His proofs are similar to ours, using type-directed predicates for termination. His types do not seem to ensure liveness at linear channels. A fully abstract embedding of existing calculi as presented in the present work and the finite axiomatisation of the weak bisimilarity are not reported in [58]. On the other hand, his system can type processes with first-order state (we note that the corresponding result in our setting was discussed in [68, Section 6], see also Section 7 and below), showing another operational investigation for termination in the π -calculus.

A basic feature of our approach is that we construct an integrated calculus combining restricted calculi with clear behavioural characterisations in a bottom-up fashion, cf. [10, 35]. This leads to, among others, a proof methodology for strong normalisability which smoothly extends to other classes of behaviours such as stateful, polymorphic and concurrent computation. For example, [12] establishes strong normalisability of linear processes with second-order polymorphism using the extension of the present proof method based on reducibility candidates induced by double-negation closure, cf.[22]. [67] extends the proof method in the present paper to obtain strong-normalisation of first order state, combining it with recent proof techniques of termination in Classical Logic [43, 62]. These results

can further be augmented to proving liveness in the presence of non-termination and nondeterminism by mixing type structures [11]. This incremental nature of type structure also leads to significant applications of SN to semantics of processes. For example, [69] reports a new bisimilarity method associated with linear type structure and strong normalisability and presented its applications to secrecy in programming languages [16, 59, 60]. In another paper [35], we adapt these results to a practical direction, proposing and verifying the new typing systems for secure programming languages based on linear/affine typed π -calculi, where strong normalisability and linearity play a fundamental role in the analysis.

One of the basic aspects of the type structure in the present work, *input-output modes* (cf. [4, 37, 50, 53]), has its incarnation in the context of Linear Logic, yielding its variant called *Polarised Linear Logic* (LLP) [47, 48], studied by Olivier Laurent. Proof nets for LLP are faithfully embeddable in the replicated fragment of the present calculus (i.e. the sub-calculus which only use !-? types), preserving dynamics. Acyclicity in name usage in the presented type discipline corresponds to the so-called Lafont-Regnier condition in proof nets. These connections shed light on the constructions in the present paper from a logical viewpoint, enriching its understanding. As key differences, the constructions in LLP bear logical significance, making it an effective medium to relate computation and proofs; whereas the present type discipline captures SN in the framework of basic process-theoretic operators (parallel composition, hiding and prefix). This process-based approach leads to a uniform type discipline integrating SN with other classes of behaviours, including diverging computation, state and concurrency, as explored in [12, 32, 35, 67, 69].

Structure of the Paper. This paper is a full version of [68], presenting detailed proofs, further examples and related results. Strong normalisability of the π -calculus with free output, not presented in [68], is discussed in Section 6. One of the main purposes of this paper is to present the central ideas of, and core proof techniques for, the first-order strong normalisable typed π -calculus, as a basis of their further extensions and applications. The reader interested in further work associated with this paper may refer to [12, 29, 32, 35, 67, 69]. In the rest of this paper, Section 2 introduces the syntax and the type discipline of the first-order linear π -calculus. Section 3 proves the main result, strong normalisability. Section 4 presents a complete axiomatisation of weak bisimilarity in linear processes. Section 5 gives a fully abstract encoding of the simply typed λ -calculus with sums and products ($\lambda_{\rightarrow,\times,+}$) in the calculus. Section 7 discusses related results, among others establishing the liveness property of linear processes.

2. PROCESSES AND TYPING

Following [10, 32, 68, 69], we use the asynchronous version of the π -calculus [14, 31] with bound output [56]. We can use free output with precisely the same results, as we shall show in Section 6. However, the proofs for the main results (strong normalisability, axiomatisation of bisimilarity and fully-abstract embedding) are more lucidly presented with bound outputs, cf. [10, 12, 56, 68]. Let $x, y, \ldots, a, b, \ldots$ range over a countable set of names (also called channels). The set of untyped terms, *processes*, is given by the following grammar.

$$P ::= x(\vec{y}).P \text{ input} | P|Q \text{ parallel} | \mathbf{0} \text{ inaction} \\ | \overline{x}(\vec{y})P \text{ output} | (vx)P \text{ hiding} | !x(\vec{y}).P \text{ replication}$$

(Structural Rules)

(S1)	$P 0\equiv P$	(S2) $P Q \equiv Q P$	(S3) $P (Q R) \equiv (P Q) R$
(S4)	$(\mathbf{v}x)0\equiv0$	(S5) $(vx)(vy)P \equiv (vy)(v)$	x)P
(S6)	$(\mathbf{v}x)(P Q) \equiv ((\mathbf{v}x)P) Q$	$(x \not\in \operatorname{fn}(Q))$ (S7) $\overline{x}(\vec{y})\overline{z}(\vec{w})$	$P \equiv \overline{z}(\vec{w})\overline{x}(\vec{y})P \ (x, z \notin \{\vec{w}\vec{y}\})$
(S8)	$(\mathbf{v}z)\overline{x}(\vec{y})P \equiv \overline{x}(\vec{y})(\mathbf{v}z)P$	$(z \not\in \{x\vec{y}\})$ (S9) $\overline{x}(\vec{y})(P Q)$	$D \equiv (\overline{x}(\vec{y})P) Q \ (\{\vec{y}\} \cap \operatorname{fn}(Q) = \emptyset)$

(Reduction)

(Com) $x(\vec{y}).P \mid \overline{x}(\vec{y})Q \longrightarrow (v \vec{y})(P \mid Q)$	(Res) $P \longrightarrow Q \implies (\mathbf{v}x)P \longrightarrow (\mathbf{v}x)Q$
$(Com_!) !x(\vec{y}).P \overline{x}(\vec{y})Q \longrightarrow !x(\vec{y}).P (v\vec{y})(P Q)$	(Out) $P \longrightarrow Q \implies \overline{x}(\vec{y})P \longrightarrow \overline{x}(\vec{y})Q$
(Par) $P \longrightarrow P' \implies P Q \longrightarrow P' Q$	(Cong) $P \equiv P' \longrightarrow O' \equiv O \implies P \longrightarrow O'$

FIG. 1. Reduction and Structural Rules

The bound/free names are defined as usual. We assume that names in a vector \vec{y} are pairwise distinct. Up to structural equality, the output $\overline{x}(\vec{y})Q$ acts like $(\nu \vec{y})(\overline{x}\langle \vec{y}\rangle|Q)$ in the standard syntax. The reduction relation \rightarrow and the structural congruence \equiv are defined in Figure 1. The multi-step reduction \rightarrow is given as $\rightarrow \rightarrow \stackrel{\text{def}}{\equiv} \equiv \cup \rightarrow^*$.

As a simple example of processes and their reductions, a *copy-cat agent* [37] is given by $[x \to y] \stackrel{\text{def}}{=} !x(c).\overline{y}(c')c'.\overline{c}$, which links two locations *x* and *y*. The *omega agent* is defined as $\Omega_u \stackrel{\text{def}}{=} (vy)([u \to y]|[y \to u])$, which immediately diverges when it is interrogated at *u*.

2.1. Types

Action Modes. The following pairs of *action modes* [11, 32] prescribe how each channel is used in typed processes.

\downarrow	Linear Input	\uparrow	Linear Output
!	Server input	?	Client request to !

" \downarrow " mode is associated with an input (e.g. x in x(y).P) and "!" mode is associated with a replicated input (e.g. x in !x(y).P). " \uparrow " (resp. "?") mode is associated with an output delivered to " \downarrow " (resp. "!"). For example, if $\overline{x}(\overline{y})P$ is composed with x(y).P, then x in $\overline{x}(\overline{y})P$ has a \uparrow -mode, and if it is composed with !x(y).P, then x has a ?-mode. We also use the mode \updownarrow which guarantees uncomposability of linear channel; for example, if x.0 has a \downarrow mode and \overline{x} has a \uparrow -mode, then $x.0 | \overline{x}$ has \updownarrow -mode at x. The \updownarrow -mode at x indicates that the process $x.0 | \overline{x}$ cannot be composed with any process that has x as a free name.

We let p, q, \ldots range over action modes. If $p \neq \uparrow$, we write \overline{p} for the *dual* of p, a self-inverse map on the action modes such that $\overline{\downarrow} = \uparrow$ and $\overline{!} = ?$. The four modes correspond to $!_1, ?_1, !_{\omega}$ and $?_{\omega}$ introduced in [11], except that the present modes indicate true linearity for linear channels (i.e. input and output interact precisely once) rather than affinity (i.e. input and output interact at most once) and lack of divergence for replicated channels.

Channel Types. Next we define *channel types* by the following grammar. Below p_{1} (resp. p_{0}) denotes input (resp. output) modes.

$$\boldsymbol{\tau} ::= \boldsymbol{\tau}_{\mathrm{I}} \mid \boldsymbol{\tau}_{\mathrm{o}} \mid \boldsymbol{\uparrow} \qquad \boldsymbol{\tau}_{\mathrm{I}} ::= (\boldsymbol{\tilde{\tau}}_{\mathrm{o}})^{p_{\mathrm{I}}} \qquad \boldsymbol{\tau}_{\mathrm{o}} ::= (\boldsymbol{\tilde{\tau}}_{\mathrm{I}})^{p_{\mathrm{O}}}$$

The IO-alternation constraint (names used for input carry only output names and vice versa) comes from game semantics [4, 34, 37]. This condition is not essential for SN but simplifies presentation and proofs. For characterising sequential interaction, we may add further constraints as in [10]; we do not do so here since the proof structure of strong normalisability does not change by having this constraint. Let $md(\tau)$ be the outermost mode of τ ; for \uparrow we set $md(\uparrow) = \uparrow$. We define \odot as the least commutative partial operation on channel types such that:

(1)
$$\tau \odot \overline{\tau} = \uparrow (\mathsf{md}(\tau) = \downarrow)$$
 (2) $\tau \odot \tau = \tau \text{ and } \tau \odot \overline{\tau} = \overline{\tau} (\mathsf{md}(\tau) = ?)$

Intuitively, (1) says that once we compose input-output linear channels, the channel becomes uncomposable. (2) says that a server should be unique, but an arbitrary number of clients can request interactions. For example, |x.0| | x.0 is never typable because of $()! \neq ()!$, while $\overline{x} | \overline{x}$ is typable by $x: ()^2$, and $|x.0| \overline{x} | \overline{x}$ by x: ()!. This partial algebra of channel types ensures, among others, determinacy of computation in typable processes by controlling their composability.

Action Types and their Algebra. Channel types are assigned to free names of a process to specify possible usage of names. Action types, on the other hand, carry causality information [66] and witness the real usage of channels. We first define action types. An *action type*, denoted A, B, \ldots , is a finite directed graph with nodes of the form $x:\tau$, such that:

• no name occurs twice; and

• edges are of the form $x: \tau \to y: \tau'$ such that either (1) $md(\tau) = \downarrow$ and $md(\tau') = \uparrow$ or (2) $md(\tau) = !$ and $md(\tau') = ?$.

We write $x \to y$ if $x: \tau \to y: \tau'$ for some τ and τ' . If *x* occurs in *A* and for no *y* we have $y \to x$ then we say *x* is *active in A*. |A| (resp. fn(*A*), active(*A*), md(*A*)) denotes the set of nodes (resp. names, active names, modes) in *A*. We often write $x: \tau \in A$ instead of $x: \tau \in |A|$, and write A(x) for the channel type assigned to *x* in *A*. A/\vec{x} is the result of taking off nodes with names in \vec{x} from *A*. $A \otimes B$ is the graph union of *A* and *B*, with the condition that fn(*A*) \cap fn(*B*) = \emptyset . $x: \tau \to A$ is a result of adding $x: \tau$ to *A* with an edge from $x: \tau$ to all of *A*'s active nodes.

It is sometimes useful to write down action types syntactically, in which case we generate action types from the following grammar:

$$A ::= \emptyset \mid a: \tau \mid A \otimes B \mid a: \tau \to (b: \tau_1 \otimes b: \tau_2 \cdots \otimes b: \tau_n)$$

where we assume, in $a: \tau \to (b: \tau_1 \otimes b: \tau_2 \cdots \otimes b: \tau_n)$, that τ is of mode \downarrow or ! and, accordingly, τ_i is of mode \uparrow or ?. We allow, in $A \otimes B$, two different names with the same ?-type to occur in both *A* and *B*; otherwise we prohibit shared usage of names. We shall often use this notation in examples.

The symmetric partial operator \odot on channel types is already given before. We extend this operator to action types as follows. First, a symmetric relation \asymp on action types is defined as follows. $A \asymp B$ iff:



- whenever $x: \tau \in A$ and $x: \tau' \in B$, $\tau \odot \tau'$ is defined; and
- whenever $x_1 \rightarrow x_2, x_2 \rightarrow x_3, \ldots, \rightarrow x_n$ alternately in *A* and *B* ($n \ge 2$), we have $x_1 \neq x_n$.

Next we extend \odot to action types. $A \odot B$ is defined iff $A \simeq B$ and, if so, is given by the following action type.

• $x: \tau \in |A \odot B|$ iff either (1) $x \in (fn(A) \setminus fn(B)) \cup (fn(B) \setminus fn(A))$ and $x: \tau$ occurs in A or B; or (2) $x: \tau' \in A$ and $x: \tau'' \in B$ and $\tau = \tau' \odot \tau''$.

• $x \to y$ in $A \odot B$ iff $x = z_1 \to z_2, z_2 \to z_3, \dots, z_{n-1} \to z_n = y$ $(n \ge 2)$ alternately in A and B and, moreover, for no w we have $w \to x$ and for no w' we have $y \to w'$ in either A or B.

We can easily check the following property of ⊙. See Appendix A.2 for the proof.

LEMMA 2.1. \odot on action types is a symmetric and associative partial operation with identity $\mathbf{0}$.

We illustrate how this operator works via simple examples.

EXAMPLE 2.1. Figure 2 shows two examples of composition between action types using \odot . In the linear case, ordering from/to node *b* disappears. On the other hand, in the replicated case, we keep the original ordering because $!b(\vec{y}).P$ remains persistent. The same examples can also be written down syntactically, using the grammar of action types introduced before as follows.

$$\begin{array}{ll} (1) & a:(\tau)^{\downarrow} \to (b:(\overline{\tau})^{\uparrow} \otimes c:(\overline{\tau})^{\uparrow}) \odot b:(\tau)^{\downarrow} \to (d:(\overline{\tau})^{\uparrow} \otimes e:(\overline{\tau})^{\uparrow}) \\ &= a:(\tau)^{\downarrow} \to (c:(\overline{\tau})^{\uparrow} \otimes d:(\overline{\tau})^{\uparrow} \otimes e:(\overline{\tau})^{\uparrow}) \otimes b:\uparrow \\ (2) & a:(\tau)^{!} \to (b:(\overline{\tau})^{?} \otimes c:(\overline{\tau})^{?}) \odot b:(\tau)^{!} \to (d:(\overline{\tau})^{?} \otimes e:(\overline{\tau})^{?}) \\ &= a:(\tau)^{!} \to (c:(\overline{\tau})^{?} \otimes d:(\overline{\tau})^{?} \otimes e:(\overline{\tau})^{?}) \otimes b:(\tau)^{!} \to (d:(\overline{\tau})^{?} \otimes e:(\overline{\tau})^{?}) \end{array}$$

Note shared ?-channels are duplicated in the syntactic representation.

(Zero) _	(Par) $\vdash P_i \triangleright A_i (i = 1, 2)$ $A_1 \asymp A_2$	(Res) $\vdash P \triangleright A^{x:\tau}$ $md(\tau) \in \{\uparrow, !\}$	(Weak) $\vdash P \triangleright A^{-x}$ $md(\tau) \in \{ \ddagger, ? \}$
⊢ 0 ⊳ _	$\vdash P_1 P_2 \triangleright A_1 \odot A_2$	$\vdash (\mathbf{v} x : \tau) P \triangleright A / x$	$\vdash P \triangleright A \otimes x : \tau$
(In [↓]) ⊢ <i>P</i> ⊳ ÿ: τ ⊗	$\uparrow A^{-x} \otimes ?B^{-x}$	(In [!]) ⊢ <i>P</i> ⊳ \vec{y} : $\vec{\tau}$ ⊗ ? <i>A</i> ^{-x}	(Out) $\vdash P \triangleright A^{\vec{y}:\vec{\tau}} A \asymp x: (\vec{\tau})^{p_0}$
$\vdash x(\vec{y}:\vec{\tau}).P \triangleright$	$(x:(\vec{\tau})^{\downarrow} \to A) \otimes B$	$\vdash !x(\vec{y}:\vec{\tau}).P \triangleright x: (\vec{\tau})! \rightarrow A$	$\vdash \overline{x}(\vec{y})P \triangleright A/\vec{y} \odot x : (\vec{\tau})^{p_{0}}$
	FIG	4.3. Linear Typing Rules	

2.2. Linear Typing

We are now ready to present the typing rules for strong normalisability. The rules are given in Figure 3, using sequent of the form.¹ In the typing rules we use the following notations:

- $A^{\vec{y}:\vec{\tau}}$ is A in which each $y_i:\tau_i$ in $\vec{y}:\vec{\tau}$ occurs.
- A^{-x} is A such that $x \notin fn(A)$.
- pA means A such that md(A) = p.

We say *P* is typable under *A*, or *P* has action type *A*, if $\vdash P \triangleright A$ is derivable. Brief illustration of each rule in Figure 3 follows.

(Zero) starts from the empty action type.

(Par) uses \asymp and \odot for controlling composition (which in effect ensures both determinacy and strong normalisability). For example, if *P* has type $x:()^{\uparrow}$ and *Q* has type $x:()^{\uparrow}$, then P | Q is not typable because $()^{\uparrow} \neq ()^{\uparrow}$.

(Res) allows hiding of a name only when its action mode is \uparrow or ! (which intuitively says that channels of modes \uparrow , \downarrow or ? should always be compensated by their duals before they are restricted).

(Weak) weakens \uparrow and ? since we allow the possibility of having no action at these channels. Formally the weakening of these nodes is necessary for having subject reduction.

 (\ln^{\downarrow}) records the causality from linear input type $x: (\vec{\tau})^{\downarrow}$ to linear output types. The side condition A^{-x} and B^{-x} ensure linearity (i.e. unique occurrence) of *x*. For IO-alternation, we let all free names under an input be outputs [10, 11, 35, 69].

(In!) records the causality from replicated input type to ?-types. The side condition A^{-x} is required to ensure acyclicity. Of course we cannot allow \uparrow -types in the body, for otherwise linearity would be lost. For example, if z is linear channel, then $|x(\vec{y}).(\overline{z}|Q)$ should be untypable because z is copied at each interaction.

(Out) does not suppress the body by prefix since output is asynchronous. Essentially the rule composes the output prefix and the body in parallel. This rule can be understood by translating $\overline{x}(\vec{y})P$ to $(\nu \vec{y})(\overline{x}\langle \vec{y}\rangle | P)$: suppose *P* has a type *A*. First we check $A \asymp x: (\vec{\tau})^{p_0}$, then if defined, we hide \vec{y} from $A \odot x: (\vec{\tau})^{p_0}$, whence $\overline{x}(\vec{y})P$ has type $A/\vec{y} \odot x: (\vec{\tau})^{p_0}$.

¹We prefer the format $\vdash P \triangleright A$ to $A \vdash P$. This is because A in $\vdash P \triangleright A$ abstracts the behaviour of P rather than its environment. This point would be elucidated when we discuss translation of λ -calculus in Section 5.

EXAMPLE 2.2.

• A *copy-cat* copies all information from one channel to another [4, 37], one instance of which appeared already. We show, step by step, how $[u \to x]^{\tau} \stackrel{\text{def}}{=} !u(a).\overline{x}(b)b.\overline{a}$, the copy-cat from *u* to *x* of type $\tau = (()^{\uparrow})!$, can be typed:

(1) $\vdash \mathbf{0} \triangleright \mathbf{0}$, (2) $\vdash \overline{a} \triangleright a: ()^{\uparrow}$, (3) $\vdash b.\overline{a} \triangleright b: ()^{\downarrow} \rightarrow a: ()^{\uparrow}$, (4) $\vdash \overline{x}(b)b.\overline{a} \triangleright x: \overline{\tau} \otimes a: ()^{\uparrow}$ (by $b: ()^{\downarrow} \rightarrow a: ()^{\uparrow}/b = a: ()^{\uparrow}$) and; (5) $\vdash !u(a).\overline{x}(b)b.\overline{a} \triangleright u: \tau \rightarrow x: \overline{\tau}$ (by $x: \overline{\tau} \otimes a: ()^{\uparrow}/a = x: \overline{\tau}$).

In this derivation, the length of paths in action types does not exceed 1 even when the term gets bigger and bigger in size. In fact, we can show that all paths in action types of derivable sequents have length 0 or 1.

- First we have: $\vdash a.(\overline{b} \mid \overline{c}) \triangleright a: ()^{\downarrow} \rightarrow (b:()^{\uparrow} \otimes c:()^{\uparrow}) \text{ and } \vdash b.\overline{d} \triangleright b:()^{\downarrow} \rightarrow d:()^{\uparrow}.$ Then
- (1) $\vdash a.(\overline{b} \mid \overline{c}) \mid b.\overline{d} \triangleright a: ()^{\downarrow} \rightarrow (c:()^{\uparrow} \otimes d:()^{\uparrow}) \otimes b: \downarrow$ (by (Par)), and
- (2) $\vdash (vb)(a.(\overline{b} | \overline{c}) | b.\overline{d}) \triangleright a: ()^{\downarrow} \rightarrow (c:()^{\uparrow} \otimes d:()^{\uparrow})$ (by (Res)).
- The connection of two links (copy-cats) is typed as:

$$\vdash [x \to y]^{\tau} \mid [y \to z]^{\tau} \triangleright (x: \tau \to z: \overline{\tau}) \otimes (y: \tau \to z: \overline{\tau})$$

with $x: \tau \to y: \overline{\tau} \odot y: \tau \to z: \overline{\tau} = x: \tau \to z: \overline{\tau}$. However, $[x \to x]^{\tau}$ and $[x \to y]^{\tau} | [y \to x]^{\tau}$ which represent cyclic forwarding are untypable by the side condition A^{-x} in (In¹) and by definition of \asymp , respectively.

Remark. In [10, 11, 32, 66] as well as in the early version of this paper [68], we used the two-sided sequent $\Gamma \vdash P \triangleright A$ where Γ is a standard environment which maps channels to pair types (of the form $\langle \tau, \overline{\tau} \rangle$) and *A* records the action modes attached to names and causality between names. For example, the copy cat in Example 2.2 (1) is typed as

$$y: \langle \tau, \overline{\tau} \rangle, x: \langle \tau, \overline{\tau} \rangle \vdash [x \to y]^{\tau} \triangleright ! x \to ? y$$

where $\langle \tau, \overline{\tau} \rangle$ denotes a pair of input and output types. The typing in this format is similar to those proposed in [17, 38] where types are CCS or π -terms. Compared to [17, 38], the syntax of action types of the present type discipline (in this format) is simpler since the maximum path length is at most 1; hence an action type is essentially representable as parallel composition of $(!)a.(\overline{b_1}|...\overline{b_n})$. The merit of two-sided sequent is its clear division of behavioural constraints into channel types and causality. It may also be useful for type inference. The merit of one-sided sequent is its conciseness and its (potential) faithfulness to semantic content of typed processes. Single- and two-sided sequents result in equivalent typability; the present paper uses the single-sided sequent because it gives a more concise representation of semantic types.

2.3. Basic Properties of Typing System

Next we discuss basic properties of the typing system. We begin with name usage in typed processes which form the basis of our later proof of strong normalisability. Below the first property says linear input/output channels and replicated channels occur precisely once in a given process. Acyclicity, the second property, says that the typing rules ensure global partial order between free names via compositional, local type-checking. This property becomes crucial in our SN proof later.

PROPOSITION 2.1. Let $\vdash P \triangleright A$.

(1) (linearity) If $x: \tau \in A$ and $md(\tau) \in \{\downarrow, \uparrow, !\}$, *x* occurs precisely once in *P*.

(2) (acyclicity) G(P) denotes a directed graph such that; (i) nodes are fn(P); and (ii) edges are given by: $x \cap y$ iff $P \equiv (\forall \vec{z})(Q|R)$ such that $Q \equiv x(\vec{w}).Q_0$ or $Q \equiv !x(\vec{w}).Q_0$ where $y \in fn(Q_0), x \notin \{\vec{z}\}$ and $y \notin \{\vec{z}\vec{w}\}$. A cycle in G(P) is a sequence of form $x \cap y_1 \dots \cap y_n \cap x$ ($n \ge 0$) with $y_i \neq x$. Then G(P) has no cycle.

Proof. Both are by induction on the typing rules. (1) is mechanical. For (2), we show that if $\vdash P \triangleright A$ then $x: \tau \to y: \tau'$ in *A* iff $x \curvearrowright \ldots \curvearrowright y$ is a maximal non-cycle in *P*. This is proven simultaneously with: if there are name-disjoint $x_1 \to x_2, x_3 \to x_4, \ldots, x_{2n-1} \to x_{2n}$ then the corresponding maximal non-cycles do not overlap in names, again by induction on the typing rules. The key case is (Par), the only rule which extends the chain. Assume $x_1 \to x_2, x_2 \to x_3, \ldots, x_{n-1} \to x_n$ in $A \uplus B$ and $x_1 \to x_n$ in $A \odot B$. By inductive hypothesis there are the corresponding maximal non-cycles. In them, names used in different cycles in *A* (resp. in *B*) never overlap with each other. Further, since intermediate names in these non-cycles have either mode ! or mode \uparrow , these names do not overlap between *A* and *B* either. Thus the result of connecting all these non-cycles again gives a non-cycle, which clearly corresponds to $x_1 \to x_n$, as required.

Remark. In Proposition 2.1 (2), the notion of chain does not include the case where an intermediate channel is restricted (unlike [1]). While such cases can be included, they are not necessary in the proof of strong normalisability given later, cf. Lemma 3.3. Also note that this property is derived *a posteriori* by defining a composition operator on types, in contrast to [58] which assumes this global condition *a priori*.

Next we list basic properties of the reduction relation in typed processes. In (3) below and henceforth we use the following notations.

- $P \Downarrow Q \Leftrightarrow^{\text{def}} P \longrightarrow^* Q \not\to$.
- $P \Downarrow \stackrel{\text{def}}{\Leftrightarrow} \exists Q.P \Downarrow Q.$ Further, $P \Uparrow \stackrel{\text{def}}{\Leftrightarrow} \forall n \in \mathbb{N}. P \longrightarrow^{n}$.
- $SN(P) \Leftrightarrow \neg P \Uparrow$.
- $\mathsf{CSN}(P) \stackrel{\text{def}}{\Leftrightarrow} \mathsf{SN}(P) \land (P \Downarrow Q_{1,2} \Rightarrow Q_1 \equiv Q_2).$

PROPOSITION 2.2. Let $\vdash P \triangleright A$.

(1) (subject reduction) If $P \longrightarrow^* Q$ then $\vdash Q \triangleright A$.

(2) (strong confluence) If $P \longrightarrow Q_i$ (i = 1, 2), then either $Q_1 \equiv Q_2$ or there exists R s.t. $Q_i \longrightarrow R$ (i = 1, 2).

(3) (determinacy) Let $\vdash P \triangleright A$. (i) $P \rightarrow P'$ and SN(P') imply SN(P). (ii) $P \Downarrow Q_i$ (i = 1,2) imply $Q_1 \equiv Q_2$. And (iii) $P \Downarrow \Leftrightarrow SN(P) \Leftrightarrow CSN(P)$.

Proof. (1) uses Lemma 2.1. See Appendix A.2. For (2), we note that the critical pairs arise only when a replicated input is shared which does not change its shape. See Appendix A.3. (3) is standard, cf. [1, 7, 36, 39], all using Proposition 2.2 (2).

3. STRONG NORMALISATION

This section proves the following result.

THEOREM 3.1. (main theorem, strong normalisation) $\vdash P \triangleright A \Rightarrow CSN(P)$.

A few significant consequences of the theorem will be discussed in Sections 4, 5, 6 and 7. In the proof, we first introduce the *extended reduction relation* \mapsto , which eliminates all *cuts* (mutually dual channels) in a typed process. Next we define *semantic types* [[A]], which are sets of typed terms that converge when composed with all necessary "resources" (i.e. complementary processes). Finally we prove that each typable process is in the corresponding semantic type. This part is divided into two stages. We start with showing all normal forms are in their semantic types. Then we establish that each typable process combined with resources always reaches a normal form, which implies strong normalisability of \rightarrow . In the second stage acyclicity of name ordering (cf. Proposition 2.1) becomes crucial: we first define a reduction strategy based on name ordering, then we show any parallel-composed normal forms always reach to a normal form by this strategy.

3.1. Extended Reductions

DEFINITION 3.1. (extended reductions) We define \mapsto_1 , \mapsto_r and \mapsto_g as the typed compatible relations on typed processes modulo \equiv which are generated by the following rules.

(E1)	$C[\overline{x}(\vec{y})P] x(\vec{y}).Q$	\mapsto_{I}	$C[(\mathbf{v}\vec{\mathbf{y}})(P Q)]$
(E2)	$C[\overline{x}(\vec{y})P] !x(\vec{y}).Q$	\mapsto_{r}	$C[(\nu \vec{y})(P Q)] !x(\vec{y}).Q$
(E3)	$(\mathbf{v} x)! x(\vec{y}). Q$	\mapsto_{g}	0

Here we assume the term on the left-hand side in each rule is well-typed. $\mapsto \stackrel{\text{def}}{=} (\mapsto_1 \cup \mapsto_r \cup \mapsto_g)$ is called the *extended reduction* relation. A process is in *extended normal form* if it does not contain \mapsto -redex.

The idea of \mapsto is to capture known process-algebraic laws as one step reductions: \mapsto_1 , \mapsto_r and \mapsto_g correspond to the β /linear law [26, 27, 42, 66], the replication law [11, 53, 57] and the garbage collection law, respectively. As an example of \mapsto , we have:

$$|b(y).\overline{c}(z)z.\overline{y}| |c(z).\overline{z} \mapsto_{\mathsf{r}} |b(y).(\mathbf{v}z)(z.\overline{y}|\overline{z})| |c(z).\overline{z} \mapsto_{\mathsf{l}} |b(y).\overline{y}| |c(z).\overline{z}|$$

Immediately $\longrightarrow \subseteq \mapsto$. $P \Downarrow_e$, $SN_e(P)$ and $CSN_e(P)$ are given as $P \Downarrow$, SN(P) and CSN(P)in §. 2.3 using \mapsto instead of \longrightarrow . A \mapsto -*redex* is a pair of subterms which form a redex for \mapsto in a given term.

PROPOSITION 3.1. Let all processes be typed below.

(1) If $\Gamma \vdash P \triangleright A$ and $P \mapsto P'$ then $\Gamma \vdash P' \triangleright A$.

(2) (CR) If $P \mapsto^* Q_i$ then $Q_i \mapsto^* R$ (i = 1, 2).

(3) (determinacy) If $P \mapsto P'$ and $SN_e(P')$ then $SN_e(P)$. Thus $P \downarrow_e iff SN_e(P)$ iff $CSN_e(P)$.

(4) (convergence) (i) $P | Q \downarrow_e$ implies $P \downarrow_e$ and $Q \downarrow_e$, (ii) if $P \downarrow_e$, then $(\forall x)P \downarrow_e$, and (iii) $P \downarrow_e$ iff $a(\vec{x}) \cdot P \downarrow_e$, (iv) $P \downarrow_e$ iff $!a(\vec{x}) \cdot P \downarrow_e$, and (v) $P \downarrow_e$ iff $\overline{a}(\vec{x})P \downarrow_e$.

Proof. See Appendix B.1. The proof of Church-Rosser proceeds by 'postponing' applications of \mapsto_{q} ,

Note the Church-Rosser property is no longer one-step.

Let us say a process *P* is *prime with subject x*, or simply *prime*, if either *P* is input with subject *x* or $P \equiv \overline{x}(y_1..y_n) \prod_{i \in I} P_i$ such that each P_i is prime with subject y_i where $\prod_{i \in I} P_i$ denotes the *n*-ary parallel composition of $\{P_i\}_{i \in I}$ (if $I = \emptyset$ then $\prod_{i \in I} P_i = \mathbf{0}$). In the following proofs we use a variant of the typing rule for output prefixes which is given by adding the condition " $P \equiv \prod P_i$ with P_i prime with subject y_i " in the premise of (Out) in Figure 3. We call this system, *alternative typing system*. Note that, in the alternative typing system, we can assume active names under an output prefix are bound by that prefix. With the same proof as in Appendix D of [11], we can easily check:

PROPOSITION 3.2. If $\vdash P \triangleright A$ is derivable in the system in Figure 3, then for some $P_0 \equiv P$ we have $\vdash P_0 \triangleright A$ in the alternative typing system.

Proposition 3.2 says that we can assume, without loss of generality, that all prefixed processes are primes whenever we are discussing properties invariant under \equiv (such as strong normalisability). For this reason the following convention does not lose generality in our technical development.

CONVENTION 3.1. Hereafter in this section we assume all typed processes are derived in this alternative typing system.

When we work in the alternative typing system, we restrict \equiv so that it is generated without (S7) and (S9) in Figure 1 (for having closure of typability under \equiv and \rightarrow).

Among others the alternative typing gives a simple inductive characterisation of extended normal forms which we shall use in the proof. Below and henceforth we write NF_e for the set of extended normal forms: NF_e $\stackrel{\text{def}}{=} \{P \mid \exists A. \vdash P \triangleright A \text{ and } P \not\leftrightarrow \}$.

PROPOSITION 3.3. NF_e coincides with, up to \equiv , the set of the processes inductively generated by the following rules:

- $0 \in \mathsf{NF}_e$,
- If $P \in \mathsf{NF}_e$ then $x(\vec{y}:\vec{\tau}).P$, $!x(\vec{y}:\vec{\tau}).P$, $\overline{x}(\vec{y}:\vec{\tau})P \in \mathsf{NF}_e$.
- If $P_i \in \mathsf{NF}_e$ $(i \in I \neq \emptyset)$, P_i is a prime, and $P_i | P_j \not\mapsto (i \neq j)$ then $\prod_{i \in I} P_i \in \mathsf{NF}_e$.

where we implicitly assume typability in each rule.

That is, a process is in NF_e iff either: (1) it is inaction, (2) it is a prefix of an ENF, or (3) *n*-ary parallel composition of ENFs without complementary input and output. Note this also says that an ENF does not have substantial hiding (i.e. a hiding $(v_x)P$ such that $x \in fn(P)$). For the proof of Proposition 3.3, the set thus generated is immediately a subset of NF_e by definition. For the reverse direction, we use induction on tying rules of the (alternative) typing system, noting if $P \in NF_e$ then its subterms are also in NF_e. For (Res),

assume (vx)P is derived. Since $P \in NF_e$, if x has mode \updownarrow , this x is the result of weakening, hence the hiding (vx) can be taken away by \equiv . Further x cannot have mode ! since if so it would result in a \mapsto -redex (of rule (E3)). For (Par) assume $P_1|P_2$ is derived. Since each $P_i \in NF_e$, by induction it is (up to \equiv) derived from one of the three rules above. If either is derived from the first one we have nothing to prove. If not, then each is derived from the second or the third rule (up to \equiv), and they do not share a complementary channel by $P_1|P_2 \in NF_e$, thus as required.

3.2. Semantic Types

Semantic types are provably strongly normalising typed terms of some kind. We need some preliminaries.

- $\mathsf{cl}(A) \stackrel{\text{def}}{=} \otimes_{x_i:\tau_i \in A, \mathsf{md}(\tau_i) \in \{\uparrow, ?\}} x_i : \overline{\tau_i}.$
- Let $A \simeq B$ and $A \odot B = C \otimes \vec{x}$: \uparrow where $\uparrow \notin md(C)$. Then $A \cdot B \stackrel{\text{def}}{=} C$.

By cl(*A*), called the *complement of A*, we indicate the (type of the) environment which gives complementary linear and replicated inputs for all free output channels in *A*. $A \cdot B$ is a "semantic version" of $A \odot B$, where we forget inessential \uparrow -channels. Hence by definition, $md(A \odot B) = !$. We can now define semantic types.

DEFINITION 3.2. Recall $\vec{y}: \vec{\tau} = y_1: \tau_1 \otimes \cdots \otimes y_n: \tau_n$. The semantic type [[A]] and the prime semantic type $\langle \langle x: \tau \rangle \rangle$ are defined by the following rules:

$$\begin{bmatrix} [A] \end{bmatrix} \stackrel{\text{def}}{=} \{ \vdash P \triangleright A \mid \forall Q \in \langle \langle \mathsf{cl}(A) \rangle \rangle. \ P | Q \Downarrow_e R \in \langle \langle A \cdot \mathsf{cl}(A) \rangle \rangle \}$$

$$\langle \langle x : (\vec{\tau})^{\downarrow} \rangle \rangle \stackrel{\text{def}}{=} \{ x(\vec{y} : \vec{\tau}) . P \mid P \in \llbracket \vec{y} : \vec{\tau} \rrbracket \}$$

$$\langle \langle x : (\vec{\tau})^! \rangle \rangle \stackrel{\text{def}}{=} \{ !x(\vec{y} : \vec{\tau}) . P \mid P \in \llbracket \vec{y} : \vec{\tau} \rrbracket \}$$

$$\langle \langle \otimes_{i \in I} x_i : \tau_i \rangle \rangle \stackrel{\text{def}}{=} \{ \Pi_{i \in I} P_i \mid P_i \in \langle \langle x_i : \tau_i \rangle \rangle \quad i \in I \}$$

We note the one-sided sequent offers a simpler form of semantic types than those originally defined in [68]. We can check:

PROPOSITION 3.4. The rules of [A] and $\langle \langle \otimes_{i \in I} x_i : \tau_i \rangle \rangle$ are well-defined.

Proof. We formulate a notion of size of types, then verify that each semantic type is defined by semantic types of strictly smaller size. The *size* of *A* is given by $\sharp(A) \stackrel{\text{def}}{=} \sum_{x \in \mathsf{fn}(A)} A(x)$, where $\sharp((\vec{\tau})^p) \stackrel{\text{def}}{=} \sum_i \sharp(\tau_i) + 1$ and $\sharp(\updownarrow) = 1$. Write \leq for the ordering w.r.t. the size of types thus defined. By $\sharp(x:(\vec{\tau})^p) \leq \sum_i \sharp(\vec{y}:\vec{\tau})$, we know that $\langle\langle x:(\vec{\tau})^p \rangle\rangle$ is defined from types of strictly smaller size, $[\![y_i:\tau_i]\!]$. The same holds for $\langle\langle \otimes_i x:\tau_i \rangle\rangle$. By definition we have $\sharp(A) \geq \sharp(\mathsf{cl}(A) \cdot A) \geq \sharp(\mathsf{cl}(A))$. Thus $[\![A]\!]$ is defined by prime semantic types of

the same or smaller size, which, in turn, are defined from those of strictly smaller size.

Some observations:

Lemma 3.1.

(1) If $P \in \llbracket A \rrbracket$ then $\vdash P \triangleright A$ and $SN_e(P)$. (2) $\llbracket A \rrbracket \subseteq \llbracket A \otimes B \rrbracket$ and $\llbracket A \rrbracket \subseteq \llbracket B \rrbracket$ with $A \subseteq B$. Also $\llbracket A \otimes x : \uparrow \rrbracket = \llbracket A \rrbracket$. (3) Let $P \mapsto P'$. Then $P \in \llbracket A \rrbracket$ iff $P' \in \llbracket A \rrbracket$. (4) Let $P_i \in \langle \langle x_i : \tau_i \rangle \rangle$ $(1 \le i \le n)$ such that $x_1, ..., x_n$ are pairwise distinct. Then $\prod_{i \in I} P_i \in [\![\otimes_i x_i : \tau_i]\!]$.

Proof. For (1), the first half is immediate, while the latter half is because of Proposition 3.1 (3). The first half of (2) is direct from the definition. The latter half is because: $\vdash P \triangleright A \otimes x$: ↓ with $x \in \text{fn}(P)$ implies that there always exists a P' s.t. $P \mapsto_1 P'$ with $\vdash P' \triangleright A$. For (3), "then" is trivial from the definition of $[\![A]\!]$, while "if" is by CR of \mapsto . Finally, for (4), we note $\text{md}(\tau_i) \in \{\downarrow, !\}$, which means $\text{cl}(\otimes x_i : \tau_i) = \emptyset$. Hence we can take $Q \equiv \mathbf{0}$ in the definition of $[\![\otimes_i x_i : \tau_i]\!]$.

3.3. Main Proofs

This subsection presents the main arguments for strong normalisability. First we show that all (typable) normal forms are semantically typed. The difficult case here is output $\overline{a}(\vec{x})P$ to replication $|a(\vec{x}).Q$ because after reduction $\overline{a}(\vec{x})P||a(\vec{x}).Q \longrightarrow (v\vec{x})(P|Q)||a(\vec{x}).Q$, P may interact again with $|a(\vec{x}).Q$. Our formulation of semantic types based on \mapsto makes the inductive argument possible.

First we prove that a typable extended normal form is an element of a semantic type.

LEMMA 3.2. If $\vdash P \triangleright A$ and $P \in \mathsf{NF}_e$ then $P \in \llbracket A \rrbracket$.

Proof. By Lemma 3.1 (2), it suffices to consider only minimum action types (i.e. fn(P) = fn(A)). For brevity we write $P_{\langle px \rangle}$ ($p \in \{!, \downarrow\}$) for a process in normal form in a prime semantic type. Also throughout the proof we set $fn(A) = \{a_i\}$ and $fn(B) = \{b_j\}$. The proof proceeds by the rule induction on the generation of $\vdash P \triangleright A$ with respect to the rules given in Proposition 3.3. Below given $A = \bigotimes_i x_i : \tau_i$, we write \overline{A} for $\bigotimes_i x_i : \overline{\tau_i}$.

(**Inaction**). By $cl(\emptyset) = \emptyset$, if $Q \in \langle \langle cl(\emptyset) \rangle \rangle$, then $Q \equiv 0$. Hence $0 | Q \equiv 0 \downarrow_e 0 \in \langle \langle \emptyset \rangle \rangle$ with $cl(\emptyset) \cdot \emptyset = \emptyset$, so that we have $0 \in [\![\emptyset]\!]$.

(Linear Input). Assume $P \in [\![\vec{y}: \vec{\tau} \otimes \uparrow A \otimes ?B]\!]$. We show $x(\vec{y}: \vec{\tau}) \cdot P \in [\![(x: (\vec{\tau})^{\downarrow} \to \uparrow A) \otimes ?B]\!]$. Let $\tau = (\vec{\tau})^{\downarrow}$. First we note $cl((x: \tau \to A) \otimes B) = \overline{A} \otimes \overline{B}$. Let $Q \in \langle\langle \overline{A} \otimes \overline{B} \rangle\rangle$ and $R \in \langle\langle \vec{y}: \vec{\tau} \rangle\rangle$. W.l.o.g. we assume

• $Q \equiv Q_1 | Q_2 \in \mathsf{NF}_e$ such that $Q_1 \equiv \prod_i Q_{1i} \langle \downarrow a_i \rangle \in \langle \langle \overline{A} \rangle \rangle$ and $Q_2 \equiv \prod_j Q_{2j} \langle \flat_j \rangle \in \langle \langle \overline{B} \rangle \rangle$; and • $R \equiv R_1 | R_2 \in \mathsf{NF}_e$ such that $R_1 \stackrel{\text{def}}{=} \prod_k R_{1k} \langle \downarrow z_k \rangle \in \langle \langle \otimes_{z_k = z_k} z_k : \overline{\tau_k} \rangle \rangle$ and $R_2 \stackrel{\text{def}}{=} \prod_l R_{2l} \langle \flat_{w_l} \rangle \in \langle \langle \otimes_{w_l = y_l} w_l : \overline{\tau_l} \rangle \rangle$ with $\{ \vec{y} \} = \{ \vec{z} \vec{w} \}$.

By induction hypothesis,

$$P|(Q|R_1|R_2) \Downarrow_e Q_2|R_2 \in \langle\!\langle \otimes_{w_l=y_l} w_l : \overline{\tau_l} \otimes \overline{B} \rangle\!\rangle \tag{5}$$

Hence by Proposition 3.1 (4-i), we know $P|Q \Downarrow_e P'|Q_2$ where $fn(P') \subseteq \{\vec{y}\}$. By the definition of \mapsto this implies $x(\vec{y}).P|Q \Downarrow_e x(\vec{y}).P'|Q_2$. We now show $P' \in [\![\vec{y}:\vec{\tau}]\!]$, which implies, by definition of $[\![\cdot]\!], x(\vec{y}).P' \in \langle\langle x:\tau \rangle\rangle$. We already know $P|Q|R_1|R_2 \mapsto^* P'|Q_2|R_1|R_2$, while by (5) above, we have $P|Q|R_1|R_2 \mapsto^* P'|Q_2|R_1|R_2 \Downarrow_e Q_2|R_2$. Note that $fn(Q_2)$ and fn(R) are disjoint, hence there is no interaction between Q_2 and $P'|R_1|R_2$. Now by CR of \mapsto we know $P'|R_1|R_2 \Downarrow_e R_2 \in \langle\langle \otimes_{w_l=y_l} w_l:\overline{\tau_l}\rangle\rangle$. This shows $P' \in [\![\vec{y}:\vec{\tau}]\!]$, as required.

(Replicated Input). Similar to the previous case.

(Linear Output). Similar to and simpler than the next case.

(**Replicated Output**). Assume $P \in [[C \otimes x: (\vec{\tau})^2]]$ with $C/\vec{y} = \uparrow A \otimes ?B^{-x}$. Let $\tau = (\vec{\tau})^2$. We have to show $\overline{x}(\vec{y}:\vec{\tau})P \in [[A \otimes B \otimes x:\tau]]$. First we note that $cl(A \otimes B \otimes x:\tau) = cl(C \otimes x:\tau) = (\overline{A} \otimes \overline{B} \otimes x:\overline{\tau})$. Assume $Q \in \langle\langle \overline{A} \otimes \overline{B} \otimes x:\overline{\tau} \rangle\rangle$. W.l.o.g. we can write $Q \equiv !x(\vec{y}).Q'_0 | Q_1 | Q_2$ where $!x(\vec{y}).Q'_0 \in \langle\langle x:\overline{\tau} \rangle\rangle$, $Q_1 \equiv \Pi_i Q_{1i} \langle u_{ai} \rangle$ and $Q_2 \equiv \Pi_j Q_{2j} \langle u_{bj} \rangle$. Then we have:

$$\overline{x}(\vec{y})P \mid Q \longrightarrow (\nu \vec{y})(P \mid Q'_0) \mid !x(\vec{y}) \cdot Q'_0 \mid Q_1 \mid Q_2$$

By induction hypothesis, $P|!x(\vec{y}).Q'_0|Q_1|Q_2 \downarrow_e P'|!x(\vec{y}).Q'_0|Q_2$ such that $P' \in [\![\vec{y}:\vec{\tau}]\!]$ with $\mathsf{md}(\tau_i) \in \{!,\downarrow\}$. Hence we can write $P' \equiv \Pi_k R_{1k\langle \downarrow z_k \rangle} | \Pi_l R_{2l\langle !w_l \rangle}$ with $\{\vec{y}\} = \{\vec{z}\vec{w}\}$. We also note that $Q'_0 \in \langle\!\langle \otimes y_i:\tau_i \rangle\!\rangle$. Hence, by assumption,

$$(\mathbf{v}\vec{y})(P'|Q'_0) \mapsto^*_{\mathsf{I}} (\mathbf{v}\vec{y})(\Pi_l R_{2l\langle !w_l \rangle} | Q''_0) \mapsto^* (\mathbf{v}\vec{y})(\Pi_l R_{2l\langle !w_l \rangle}) \mapsto^*_{\mathsf{q}} \mathbf{0}$$

Now by CR, we have $P \mid Q \Downarrow_e ! x(\vec{y}) . Q'_0 \mid Q_2 \in \langle \langle \overline{B} \otimes x : \overline{\tau} \rangle \rangle$, as desired.

(**Composition of Primes**). Given $\Pi_{i \in I} P_i$, assume by induction $P_i \in [[A_i]]$ $(i \in I)$ and $P_i | P_j \not\rightarrow$ for $i \neq j$. Note that, for each $x \in \operatorname{fn}(A_i) \cap \operatorname{fn}(A_j)$ $(i \neq j)$ we have $x : \tau \in |A_i| \cap |A_j|$ and $\operatorname{md}(\tau) = ?$. Let $C = A_1 \odot \ldots \odot A_n$ and $Q \in \langle \langle \operatorname{cl}(C) \rangle \rangle$. W.l.o.g.,

$$Q \, \equiv \, \Pi_{1 \leq i \leq n} (\Pi_{1 \leq k_i \leq m_i} Q'_{k_i} \langle \downarrow a_{k_i} \rangle) \mid \Pi_j Q''_j \langle ! b_j
angle$$

where $\{a_{k_i}\}_{1 \le k_i \le m_i}$ is the set of linear output channels in P_i and $\{b_j\}$ is the union of all replicated output channels from $A_1, ..., A_n$. By inductive hypothesis (the first part), we have $P_i | Q \Downarrow_e P'_i | \prod_{h \ne i} (\prod_{k_h} Q'_{k_h})$ with $P'_i \in \langle \langle A_i \cdot cl(A_i) \rangle \rangle$ for each *i*. Since only replicated Q''_j is shared among P_i , by $\otimes cl(A_i) \supseteq \overline{B}$ and $\otimes (A_i \cdot cl(A_i)) = C \cdot cl(C)$, we have $\Pi P_i | Q \Downarrow_e \Pi P'_i | \prod_j Q''_j (!b_j) \in \langle \langle C \cdot cl(C) \rangle \rangle$, as required. We have now exhausted all cases.

We use the following corollary of Lemma 3.2.

COROLLARY 3.1.

(1) Suppose fn(P) = \emptyset and $P \mapsto^* P' \in [\![\emptyset]\!]$. Then $P \Downarrow_e 0$. (2) If $\vdash P \triangleright x : \tau \in \mathsf{NF}_e$ with $\mathsf{md}(\tau) \in \{\downarrow, !\}$, then $P \in \langle\!\langle x : \tau \rangle\!\rangle$.

Proof. Both (1) and (2) are straightforward by the above lemma and Lemma 3.1 (3) and (4), respectively. ■

We can now establish the main lemma.

LEMMA 3.3. (main lemma) Suppose $\vdash P \triangleright A$. Then $P[Q \Downarrow_e \text{ for each } Q \in [[cl(A)]]$.

Before giving the proof, we discuss its key ideas informally. The proof argues by induction on the typing rules. Given Lemma 3.2, prefix and restriction become trivial, but parallel composition causes a couple of problems. Even if $|a.\overline{b}$ and $(\overline{a} | !b.\overline{c})$ are in NF_e, their composition (with environment !c.0) allows reductions. How can we prove termination? The key idea is to contract \mapsto -redexes from the end of the order of names $c \curvearrowleft b \curvearrowleft a$ as:

 $\begin{aligned} & |a.\overline{b} | \overline{a} | !b.\overline{c} | !c.\mathbf{0} \ \mapsto_{\mathsf{r}} \ !a.\overline{b} | \overline{a} | !b.\mathbf{0} | !c.\mathbf{0} \\ & \mapsto_{\mathsf{r}} \ !a.\mathbf{0} | \overline{a} | !b.\mathbf{0} | !c.\mathbf{0} \ \mapsto_{\mathsf{r}} \ !a.\mathbf{0} | !b.\mathbf{0} | !c.\mathbf{0} \end{aligned}$

and prove that this reduction strategy terminates due to acyclicity of names. This strategy also works for the more complex π -process which corresponds to the term in §.1 (4).

$$\begin{aligned} & !a(x).(\overline{x} \mid \overline{x}) \mid \overline{a}(c)c.\overline{b} \mid !b.\overline{a}(y') ! y'.\overline{y} \quad \mapsto^{2} \quad !a(x).(\overline{x} \mid \overline{x}) \mid (\mathbf{v}c)(!c.\overline{b} \mid \overline{c} \mid \overline{c}) \mid !b.(\mathbf{v}y')(!y'.\overline{y} \mid \overline{y}' \mid \overline{y}') \\ & \mapsto^{6} \quad !a(x).(\overline{x} \mid \overline{x}) \mid \overline{b} \mid \overline{b} \mid !b.(\overline{y} \mid \overline{y}) \\ & \mapsto^{2} \quad !a(x).(\overline{x} \mid \overline{x}) \mid \overline{y} \mid \overline{y} \mid \overline{y} \mid \overline{y} \mid \overline{y} \mid \overline{y}) \end{aligned}$$

The proof follows. Below we say an output channel $x \in fn(A)$ is *complemented by R* if $\vdash R \triangleright cl(A)$.

Proof. By rule induction on the typing rules.

Case (Zero). Suppose $\vdash \mathbf{0} \triangleright \emptyset$. Then $cl(\emptyset) = \emptyset$. Since for all $Q \in \llbracket \emptyset \rrbracket$, we have $Q \Downarrow_e \mathbf{0}$ by Corollary 3.1 (1), $\mathbf{0} \mid Q \Downarrow_e \mathbf{0}$, as desired.

Case (Res). We do case analysis based on the mode of the hidden channel.

Subcase: $\vdash (vx)P \triangleright A$ *is derived from* $\vdash P \triangleright A \otimes x$: \updownarrow . We show, for each complementing process $Q \in [[cl(A)]]$, we have $(vx)P|Q \Downarrow_e$. By induction hypothesis, for each $R \in [[cl(A \otimes x: \updownarrow)]]$, we have $P|R \Downarrow_e$. Note that $cl(A \otimes x: \updownarrow) = cl(A)$ by definition. Hence, obviously, we have $P|Q \Downarrow_e$ for each $Q \in [[cl(A)]]$. This in turn implies $(vx)P|Q \equiv (vx)(P|Q) \Downarrow_e$ by Proposition 3.1 (4-ii), hence done.

Subcase: $\vdash (vx)P \triangleright A$ *is derived from* $\vdash P \triangleright B$ *such that* md(B(x)) = !. Without loss of generality, we set $B = A_0 \odot x : \tau \rightarrow ?B_0$ and $A_0 \odot ?B_0 = A$. Again, by definition, we know cl(A) = cl(B). The rest is similar to the above case.

Case (Weak). Trivial by inductive hypothesis.

Case (In¹). Assume $\vdash x(\vec{y}).P \triangleright A$ is derived from $\vdash P \triangleright \vec{y}: \vec{\tau} \otimes \uparrow A_0^{-x} \otimes ?B_0^{-x}$ with $A = (x: (\vec{\tau})^{\downarrow} \rightarrow A_0) \otimes B_0$. Let $C = \vec{y}: \vec{\tau} \otimes A_0 \otimes B_0$. By induction hypothesis, for each $Q \in [[cl(C)]]$, we have $P \mid Q \Downarrow_e$, which implies $P \Downarrow_e P' \in \mathsf{NF}_e$ by Proposition 3.1 (4-i). Then by construction of NF_e , we know $a(\vec{y}).P' \in \mathsf{NF}_e$, hence by Lemma 3.2, we know $a(\vec{y}).P' \in [[A]]$. Now by Lemma 3.1 (3), we have $a(\vec{y}).P \in [[A]]$. Then by Lemma 3.1 (1), $a(\vec{y}).P \Downarrow_e$, as desired.

Case ($In^{!}$). Similar to (In^{\downarrow}).

Case (Out). Assume $\vdash \overline{x}(\overline{y})P \triangleright A$ is derived from $\vdash P \triangleright C^{-x}$ such that $\operatorname{active}(C) = \overline{y}$ and $C/\overline{y} = A$. Let $A(x) = \tau$.

Subcase: $\operatorname{md}(\tau) = \uparrow$. By induction hypothesis, for each $Q \in [[\operatorname{cl}(C)]]$, we have $P | Q \Downarrow_e P' | Q'$ with $P' \in [[\vec{y} : \vec{p}]]$ where $\tau = (\vec{p})^{\uparrow}$. Assume $R \in [[\operatorname{cl}(A)]]$. Then by the shape of the action type and by definition, we can set $R \stackrel{\text{def}}{=} (x(\vec{y}).R') | Q$ such that $x(\vec{y}).R' \in [[x : \overline{\tau}]]$ and $Q \in [[\operatorname{cl}(C)]]$. We can now calculate:

 $\overline{x}(\overline{y})P|(x(\overline{y}).R')|Q \mapsto^* \overline{x}(\overline{y})P'|(x(\overline{y}).R')|Q' \mapsto (\nu \overline{y})(P'|R')|Q'.$

By definition $R' \in [\![\vec{y} : \vec{\beta}]\!]$, we have $P'|R' \Downarrow_e$. Also by $Q \in [\![cl(C)]\!]$, we have $Q' \Downarrow_e$. Note that fn(Q') is disjoint from fn(P'|R') so that there is no further \Downarrow_e from $(\nu \vec{y})(P'|R')|Q'$. Hence we have $(\nu \vec{y})(P'|R')|Q' \Downarrow_e$, as required.

Subcase: $md(\rho) = ?$. Similar to the subcase above.

Case (Par). Suppose $\vdash P_i \triangleright A_i$ with i = 1, 2 such that $A_1 \simeq A_2$ and let $A = A_1 \odot A_2$. By induction hypothesis $P_1 \Downarrow_e P'_1$ and $P_2 \Downarrow_e P'_2$. Let $P \stackrel{\text{def}}{=} P'_1 | P'_2$. Then $P \equiv Q_1 | ... | Q_n$ where each Q_i is prime. If n = 0 there is nothing to prove. Assume $n \ge 0$ and let $X \stackrel{\text{def}}{=} \{1, 2, ..., n\}$. We

define the relation \searrow on *X* as follows:

$$i \searrow j \stackrel{\text{def}}{\Leftrightarrow} \exists x \in \text{fn}(Q_i), y \in \text{fn}(Q_j). x \curvearrowright y$$

For example, take the process $P \equiv |a.\overline{b}| |\overline{a}| |b.\overline{c}| |c.0$ discussed just before the proof of this lemma, then we have: $1 \searrow 3$, $2 \searrow 1$, $3 \searrow 4$. As in this example, \searrow^* never collapses two names. In fact, if $i \searrow^+ j \searrow^+ i$ then there is a cycle of the form $x \curvearrowright^+ x$ in the sense of Proposition 2.1 (2). Thus the relation \searrow^* is always a partial order on *X*. We now define a series of sets $X_1, X_2, ...$ as follows, writing $\max(Y, \leq)$ for the set of maximal elements of a partially ordered set *Y*.

$$X_1 \stackrel{\text{def}}{=} \max(X, \searrow^*) \quad X_{i+1} \stackrel{\text{def}}{=} \max(X \setminus \bigcup_{1 < j < i} X_i, \searrow^*)$$

(as a example, $X_1 = 4, X_2 = 3, X_3 = 1, X_4 = 2$ in *P*). As *X* is finite, $X_1, ..., X_m$ partition *X* for some *m*. Now let $S_i \stackrel{\text{def}}{=} \prod_{j \in X_i} Q_j$ for $1 \le i \le m$. Then $P \equiv \prod_{1 \le i \le m} S_i$ and $S_i \in NF_e$ for each *i*. Choose any $R \in \langle \langle c|(A) \rangle \rangle$. Note the series $S_1, ..., S_n$ is constructed so that outputs in S_{i+1} are always complemented by inputs in $S_i | S_{i-1} | ... | S_1 | R$. Now let $\vdash S_i \triangleright C_i$ s.t. $\odot_{1 \le i \le m} C_i = A$ and let $E_i \stackrel{\text{def}}{=} cl(C_1) \odot C_1 \odot ... \odot C_{i-1}$ for $1 \le i \le m$. Then $E_i = cl(C_i)$ for each *i*. Note also $E_1 = cl(A)$ and $E_m = cl(A) \odot A$. We now show, by induction on $1 \le l \le m+1$, that for some $R_l \in \langle \langle E_l \rangle \rangle$

$$P \mid R \mapsto^* \Pi_{l < i < m} S_i \mid R_l.$$

This proves the lemma when l = m + 1. For the base case, take $R_1 \equiv R$. For the inductive step, assume $P|R \mapsto^* \prod_{l \le i \le m} S_i|R_l$ such that $R_l \in \langle\langle E_l \rangle\rangle$. By Lemma 3.2 and by $S_l \in \mathsf{NF}_e$ we know that $S_l \in [[C_l]]$. By $E_l = \mathsf{cl}(C_l) = \mathsf{cl}(C_1) \odot C_1 \odot \ldots \odot C_{l-1}$, this implies $S_l|R_l \Downarrow_e R' \in I(E_l)$.

 $\langle\langle E_{l+1}\rangle\rangle$. We can now set $R' \equiv R_{l+1}$, as desired.

As an immediate corollary, we obtain:

THEOREM 3.2. (strong normalisability in \mapsto) $\vdash P \triangleright A$ implies $CSN_e(P)$.

By $\longrightarrow \subseteq \mapsto$ and Proposition 2.2 (3-iii), we have now established Theorem 3.1.

Remark. Theorem 3.1 (SN w.r.t. \rightarrow) arises as a corollary of Theorem 3.2 (SN w.r.t. \rightarrow). This does not mean, however, Theorem 3.1 is of a secondary interest. For example, the liveness property we establish in Section 7 is a direct consequence of Theorem 3.1 rather than that of Theorem 3.2. Further, when state is incorporated, the notion of extended reduction itself becomes inapplicable as it is while Theorem 3.1 and the associated liveness property still make sense. On the other hand, Theorem 3.2 has equational significance, as we shall explore in the next sections.

4. CHARACTERISATION OF BISIMILARITY

As a significant consequence of strong normalisability of typed processes, this section shows that weak bisimilarity has a finite axiomatisation in linear processes.

4.1. Typed Transitions and Bisimulations

Typed transitions describe the observations a typed observer can make of a typed process. The typed transition relation is a proper subset of the untyped transition relation,

$$(\equiv) \frac{P_{1}^{\prime} \equiv P_{1} \ P_{1}^{A_{1}} \stackrel{l}{\longrightarrow} P_{2}^{A_{2}} \ P_{2} \equiv P_{2}^{\prime}}{P_{1}^{\prime A_{1}} \stackrel{l}{\longrightarrow} P_{2}^{A_{2}} \ A_{2} \equiv P_{2}^{\prime}} \qquad (\operatorname{Res}) \frac{P_{1}^{A_{1}} \stackrel{l}{\longrightarrow} P_{2}^{A_{2}} \ x \notin n(l)}{(vx)P_{1}^{A_{1}/x} \stackrel{l}{\longrightarrow} (vx)P_{2}^{A_{2}/x}}$$
$$(\operatorname{Par}) \frac{P_{1}^{A_{1}} \stackrel{l}{\longrightarrow} P_{2}^{A_{2}} \ A_{1} \odot B \text{ allows } l}{P_{1} |Q_{1}^{A_{1} \odot B} \stackrel{l}{\longrightarrow} P_{2}|Q^{A_{2} \odot B}} \qquad (\operatorname{Com}) \frac{P_{1}^{A_{1}} \stackrel{l}{\longrightarrow} P_{2}^{A_{2}} \ Q_{1}^{B_{1}} \stackrel{\overline{1}}{\longrightarrow} Q_{2}^{B_{2}}}{P_{1} |Q_{1}^{A_{1} \odot B_{1}} \stackrel{\tau}{\longrightarrow} (vbn(l))(P_{2} |Q_{2})^{A_{2} \odot B_{2}}}$$

A allows l means (1) if $fn(l) = \uparrow$, then $l = \tau$ and (2) if md(fn(l)) = !, then l is not output.

FIG. 4. Typed Transition System

while not restricting τ -actions: hence typed transitions restrict observability, not computation. Let the set of *action labels l, l',...* be given by the following grammar.

$$l ::= \tau | x(\vec{y}) | \overline{x}(\vec{y})$$

fn(*l*) and bn(*l*) respectively denote free and bound names in *l*. n(*l*) is the set of names in *l*. Using these labels, the typed transition, written $P^A \xrightarrow{l} Q^B$ where P^A is a shorthand for $\vdash P \triangleright A$, is defined as in Figure 4. Prefix rules are standard, except we do not allow a linear input action and an output action when there is a complementary channel in the process. For example, if a process has $x: \ddagger$ (resp. $x: (\vec{\tau})^!$) in its action type, then both input and output actions (resp. output) at x should be excluded since such actions can never be observed in a typed context (cf. Section 4.2 and Appendix E of [11]). Among the remaining rules, the first rule says that the transition relation is defined on processes modulo \equiv . Among the remaining rules, the first rule says that the transition is defined on processes modulo \equiv . As we shall discuss later we can dispense with this rule by adding two transition rules for output prefix. The induced transition is well-defined in the following sense.

PROPOSITION 4.1. If $\vdash P \triangleright A$ and $P^A \xrightarrow{l} Q^B$ is derivable from Figure 4 then $\vdash Q \triangleright B$.

Proof. Simple inspection of each rule in Figure 4.

In the light of Proposition 4.1, we hereafter safely assume $\vdash P \triangleright A$ and $\vdash Q \triangleright B$ hold whenever we write $P^A \stackrel{l}{\longrightarrow} Q^B$. We also observe:

PROPOSITION 4.2. Let $\vdash P \triangleright A$. Then $P \longrightarrow Q$ iff $P^A \xrightarrow{\tau} Q^A$.

Proof. Standard. In detail: By induction on generation rules of \rightarrow , it is easy to check $P \rightarrow Q$ implies $P^A \xrightarrow{\tau} Q^A$. For the other direction, we first show, by rule induction on transition rules, that, if x has mode \downarrow (resp. !), $P^A \xrightarrow{x(\vec{y})} Q^A$ implies $P \equiv C[x(\vec{y}).P_1]$ and $Q \equiv C[P_1]$ (resp. $P \equiv C[!x(\vec{y}).P_1]$ and $Q \equiv C[!x(\vec{y}).P_1|P_1]$) where C[] is a reduction context. Similarly for $P^A \xrightarrow{\overline{x(\vec{y})}} Q^A$. Using them we show, again by rule induction on transition rules, that $P^A \xrightarrow{\tau} Q^A$ implies $P \equiv C[C_1[(!)x(\vec{y}).P_1][C_2[\overline{x}(\vec{y})P_2]]$ where C, C_1 and C_2 are reduction contexts. From this it is immediate $P^A \xrightarrow{\tau} Q^A$ implies $P \rightarrow Q$.

Finally we present the two rules for asynchronous output which allow us to dispense with (\equiv) from Figure 4, which becomes useful in our proof later.

$$\frac{P_1^{A_1} \xrightarrow{l} P_2^{A_2} \quad \mathsf{n}(l) \cap \{\vec{y}\} = \emptyset}{\overline{x}(\vec{y}) P_1^{A_1/\vec{y} \odot x: (\vec{\tau})^p} \xrightarrow{l} \overline{x}(\vec{y}) P_2^{A_2/\vec{y} \odot x: (\vec{\tau})^p}} \qquad \frac{P_1^{A_1} \xrightarrow{x(\vec{z})} P_2^{A_2}}{\overline{x}(\vec{y}) P_1^{A_1/\vec{y} \odot x: (\vec{\tau})^p} \xrightarrow{\tau} (\mathsf{v}\vec{y}) P_2\{\vec{y}/\vec{z}\}^{A_2/\vec{z}}} \tag{6}$$

These rules materialise asynchronous nature of the output in transition (the second rule needs renaming to avoid clash of bound names). The transition system which adds the rules in (6) to the rules in Figure 4 replacing \equiv in (\equiv) by \equiv_{α} , is called *syntactic transition system*. The transition system which simply replaces \equiv in (\equiv) by \equiv_{α} from the rules in Figure 4, is called *prime syntactic transition system*. We observe:

PROPOSITION 4.3.

(1) If $P^A \xrightarrow{l} Q^B$ in the syntactic transition system, so is in the original system.

(2) If $P^A \xrightarrow{l} Q^B$ in the original transition system, then $P^A \xrightarrow{l} Q_0^B$ such that $Q_0 \equiv Q$ in the syntactic transition system.

(3) Let P^A be derived under Convention 3.1. Then $P^A \stackrel{l}{\longrightarrow} Q^B$ in the original transition system iff $P^A \stackrel{l}{\longrightarrow} Q_0^B$ such that $Q_0 \equiv Q$ in the prime syntactic transition system.

Proof. For (1), we show that the added rules are derivable from the rules in Figure 4, which is immediate. For (2) we first show, in the syntactic transition, if $P_0^A \xrightarrow{l} Q_0^B$ and $P \equiv P_0$ then $P^A \xrightarrow{l} Q^B$ such that $Q \equiv Q_0$. The proof is standard, using rule induction on the syntactic transition system together with inspection of the structure of processes. From this it is easy to check that the given statement holds, this time by rule induction on the original transition system. Finally for (3) "if" is by (1) while "only if" is by (2), noting, under Convention 3.1, the transition system is identical.

Note (3) indicates that the prime syntactic transition is precisely the transition which corresponds to Convention 3.1.

Based on typed transition, we define a bisimulation. Let us say a relation over typed processes is *typed* if it only relates processes with identical action type. A typed relation is a *typed congruence* when it is a typed equivalence which contains \equiv and which is closed under each typing rule (allowing, as a result, weakening of bases, cf. [11,53]). Below $\stackrel{\hat{l}}{\Longrightarrow}$ denotes the standard abstracted transition.

DEFINITION 4.1. (typed bisimulation) A typed relation **R** is a *weak bisimulation*, or a *bisimulation*, if $P_1^{A_1} \mathbf{R} Q_1^{A_1}$ implies: whenever $P_1^{A_1} \xrightarrow{l} P_2^{A_2}$ then there is a typed transition

sequence $Q_1^{A_1} \stackrel{\hat{l}}{\Longrightarrow} Q_2^{A_2}$ such that $P_2^{A_2} \mathbf{R} Q_2^{A_2}$, as well as the symmetric case. By replacing $\stackrel{\hat{l}}{\Longrightarrow}$ with $\stackrel{l}{\longrightarrow}$, we obtain a *strong bisimulation*. If $P^A \mathbf{R} Q^A$ for some weak (resp. strong) bisimulation \mathbf{R} , we write $P^A \approx Q^A$ (resp. $P^A \sim Q^A$).

We often omit A from P^A , writing $P \approx Q$, if A is clear from the context. By definition, \approx (resp. \sim) is the union of all weak bisimulations (resp. strong bisimulations), which is in fact the largest weak (resp. strong) bisimulation, and is called *weak* (resp. *strong*) *bisimilarity*. The following technical development focusses on weak bisimilarity, which we hereafter simply call *bisimilarity*. \approx is clearly an equivalence relation. Since \equiv is easily a bisimulation, by Proposition 4.3, it is enough to use the syntactic transition to derive $P \approx Q$ (and the prime one if we are under Convention 3.1).

4.2. Axioms

Let \Im ($\Im',...$) denote a formal (equational) theory over typed processes, which is a set of axioms and rules with formulae of the form $P^A = Q^A$. In $P^A = Q^A$, P^A and Q^A should be well-typed: we shall however not mention types unless they are necessary, writing P = Q. If P = Q is provable in \Im , we write $\Im \vdash P = Q$. $\Im + \Im'$ is the result of adding the axioms and rules from two theories. We extend this to an arbitrary family of theories.

Axioms I: (Pre)Congruence Rules. We consider the standard equivalence rules and closure under well-typed contexts, identifying two α -equivalent terms. This theory is denoted \Im_c . We also define its subtheory \Im_p by removing (C2) from \Im_c .

(C1) $P \equiv_{\alpha} Q \Rightarrow P = Q$	(C2) $P = Q \Rightarrow Q = P$
(C3) $P = Q, Q = R \Rightarrow P = R$	
(C4) $P = Q \Rightarrow P R = Q R$	(C5) $P = Q \Rightarrow R P = R Q$
(C6) $P = Q \Rightarrow (vx)P = (vx)Q$	(C7) $P = Q \Rightarrow x(\vec{y}) \cdot P = x(\vec{y}) \cdot Q$
(C8) $P = Q \Rightarrow \overline{x}(\overline{y})P = \overline{x}(\overline{y})Q$	(C9) $P = Q \Rightarrow !x(\vec{y}).P = !x(\vec{y}).Q$

Axioms II: Structural Rules. Let \Im_s denote the set of rules derived from the axioms (S1–9) in Figure 1. Hence $P \equiv Q$ stands for $\Im_c + \Im_s \vdash P = Q$.

Axioms III: Conversion Rules. Convertibility is induced by the extended reduction relation, taking (E1–3) from Definition 3.1 as rules. \mathfrak{Z}_e denotes the theory. Note $P \mapsto Q$ iff $\mathfrak{Z}_p + \mathfrak{Z}_s + \mathfrak{Z}_e \vdash P = Q$.

DEFINITION 4.2. The typed congruence \leftrightarrow is defined by the following logical equivalence: $P \leftrightarrow Q$ iff $\mathfrak{I}_c + \mathfrak{I}_s + \mathfrak{I}_e \vdash P = Q$.

In other words, \leftrightarrow is the symmetric and transitive closure of $\mapsto \cup \equiv$.

4.3. Characterisation and its Proof

We now show that \leftrightarrow completely characterises bisimilarity.

THEOREM 4.1. (characterisation of \approx) $\leftrightarrow = \approx$.

We prove Theorem 4.1 by showing two inclusions, $(1) \leftrightarrow \subset \approx$ and $(2) \leftrightarrow \supset \approx$. We call the first inclusion *soundness* and the second one *completeness*. For soundness, we first show \approx is a typed congruence.

PROPOSITION 4.4. \approx is a typed congruence.

Proof. Using the characterisation in Proposition 4.3 (1)(2), it is enough to show \approx derived using the syntactic transition is a typed congruence. Input prefixes, parallel composition and restriction are entirely standard, cf. [46]. For output prefix we define $\mathbf{R} \stackrel{\text{def}}{=} \mathbf{R}_1 \cup \mathbf{R}_2 \cup \mathbf{R}_3$ where:

- (1) $\mathbf{R}_1 \stackrel{\text{def}}{=} \approx;$
- (2) $\mathbf{R}_2 \stackrel{\text{def}}{=} \{ \langle \overline{x}(\overline{y}) P_1, \overline{x}(\overline{y}) P_2 \rangle \mid P_1 \approx P_2 \}; \text{ and}$
- (3) $\mathbf{R}_3 \stackrel{\text{def}}{=} \{ \langle (\mathbf{v} \vec{y}) P_1 \{ \vec{y} / \vec{z} \}, (\mathbf{v} \vec{y}) P_2 \{ \vec{y} / \vec{z} \} \rangle \mid P_1 \approx P_2 \}.$

In (3) we assume the mentioned substitution is well-typed. It is easy to check whenever $P\mathbf{R}_1 \cup \mathbf{R}_2 Q$ its derivatives are related by \mathbf{R} . For \mathbf{R}_3 we show this relation coincides with \approx . Clearly $\mathbf{R}_3 \supset \approx$ (let \vec{y} be the empty string). For the reverse inclusion, under $P_1 \approx P_2$ we have: $(\nu \vec{y})P_1\{\vec{y}/\vec{z}\} \approx (\nu \vec{y})(P_1|\Pi[z_i \rightarrow y_i]) \approx (\nu \vec{y})(P_2|\Pi[z_i \rightarrow y_i]) \approx$ $(\nu \vec{y})P_2\{\vec{y}/\vec{z}\}$, where the first and the last equations are by the copy-cat law (see Section 6 for the definition of copycat together with the copy-cat law), while the second equation is by closure of \approx under parallel composition and hiding. Thus $P\mathbf{R}_3Q$ im-

plies $P \approx Q$, that is $\mathbf{R}_3 \subset \approx$. This shows **R** is indeed a bisimulation, hence as required.

Next we show:

PROPOSITION 4.5. If $\mathfrak{S}_e \vdash P = Q$ then $P \approx Q$.

Proof. See Appendix C.1. ■

Since \leftrightarrow is the congruent closure of \mathfrak{I}_e , by Propositions 4.4 and 4.5 we conclude:

Corollary 4.1. $\leftrightarrow \subset \approx$.

For the reverse inclusion, we reduce the equality by \leftrightarrow to those over normal forms.

DEFINITION 4.3. Let us write $P \equiv Q$ for $\mathfrak{I}_c + \{(S2,S3,S5-9)\} \vdash P = Q$ and $P \triangleright Q$ for $\mathfrak{I}_p + \mathfrak{I}_s \vdash P = Q$ (note \triangleright is a *precongruence*). We say *P* is in \triangleright -normal form if: (1) $P \in \mathsf{NF}_e$ and (2) $P \triangleright Q$ implies $P \equiv Q$.

Note $P \equiv' Q$ means that *P* and *Q* are essentially identical without changing the size of terms. For \triangleright -normal forms we observe:

Lemma 4.1.

(1) A process in NF_e is a \triangleright -normal form iff it is without name hiding and it does not contain **0** as its proper subterm.

(2) If $\vdash P \triangleright A$ then there is a \triangleright -normal form Q such that $P \mapsto^* Q$.

(3) The set of \triangleright -normal forms coincide with those processes generated by the rules in *Proposition 3.3.*

(4) If $\vdash P \triangleright A$ and P is a \triangleright -normal form then $P \equiv P_{\downarrow} |P_{\uparrow}| P_{\uparrow} |P_{\uparrow}| P_{\uparrow}$ where:

$$P_{\downarrow} = \Pi_{i \in I_{\downarrow}} y_i(\vec{z}_i) . P_i \qquad P_{\uparrow} = \Pi_{i \in I_{\uparrow}} \overline{y}_i(\vec{z}_i) P_i P_! = \Pi_{i \in I_!} ! y_i(\vec{z}_i) . P_i \qquad P_? = \Pi_{i \in I_{\uparrow}} \overline{y}_i(\vec{z}_i) P_i$$

Here $I_{\downarrow}, I_{\uparrow}, I_{!}, I_{?}$ *partition the finite set I such that* (i) *for all* $i, j \in I \setminus I_{?}$: $i \neq j$ *implies* $x_{i} \neq x_{j}$, (ii) *for all* $i \in I_{!} \cup I_{?}$ *and all* $j \in I_{\downarrow} \cup I_{\uparrow}$: $x_{i} \neq x_{j}$ *and* (iii) P_{i} *is in* \triangleright *-normal form for all* $i \in I$. *Furthermore,* $P_{\downarrow}, P_{\uparrow}, P_{!}$ *and* $P_{?}$ *are unique up to* \equiv' .

(5) If $\vdash P \triangleright A$ is a \triangleright -normal form and $P \xrightarrow{l} Q$ is a transition, then $l \neq \tau$.

Proof. See Appendix C.2. ■

Let *P* be a \triangleright -normal form. Then $P \equiv P_{\downarrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P_{\uparrow}|P$

LEMMA 4.2. Let $P_1^i | P_1^i | P_1^i | P_2^i$ be a normal form decomposition P^i (i = 1, 2).

(1) Assume that $P_{\downarrow}^{1} = \prod_{j=1}^{m} y_{i}(\vec{z}_{i}) \cdot P_{j}^{1}$ and $P_{\downarrow}^{2} = \prod_{j=1}^{n} a_{i}(\vec{b}_{i}) \cdot P_{j}^{2}$. Then $P_{\downarrow}^{1} \approx P_{\downarrow}^{2}$ iff m = n and there is a permutation σ of $\{1, \ldots, n\}$ such that $y_{i}(\vec{z}_{i}) \cdot P_{i}^{1} \approx a_{\sigma(i)}(\vec{b}_{\sigma(i)}) \cdot P_{\sigma(i)}^{2}$ for all *i*. Similarly for $P_{\uparrow}^{1,2}$, $P_{\uparrow}^{1,2}$ and $P_{\uparrow}^{1,2}$. (2) $P^{1} \approx P^{2}$ iff $P_{\downarrow}^{1} \approx P_{\downarrow}^{2}$, $P_{\uparrow}^{1} \approx P_{\uparrow}^{2}$, $P_{\uparrow}^{1} \approx P_{\uparrow}^{2}$ and $P_{\uparrow}^{2} \approx P_{\uparrow}^{2}$.

Proof. For (1), the cases for $P_{\downarrow}^{1,2}$, $P_{\uparrow}^{1,2}$ and $P_{!}^{1,2}$ are immediate by considering traces. For $P_{?}^{1,2}$, we proceed by contradiction. Assume w.l.o.g. $P_{?}^{1} \equiv \overline{x}(\overline{y})P_{1}|\overline{x}(\overline{z})P_{2}|P'$ while $P_{?}^{2} \equiv \overline{x}(\overline{d})Q|Q'$ such that neither P' nor Q' contain x as an active name. By Lemma 3.2, all active names in P_{1}, P_{2} and Q are in $\{\overline{y}\}, \{\overline{z}\}$, and $\{\overline{d}\}$, respectively. Typing then ensures that all these active names are inputs. By Lemma 4.1 (5), no process in \triangleright -normal form can have a τ -transition. Hence $P_{?}^{1}$ and $P_{?}^{2}$ cannot have the same set of traces. (2) follows from (1).

We now prove the key lemma for completeness. For (2). we can indeed show \triangleright -normal forms are a class of processes where \approx , \sim , \equiv' and \equiv all coincide.

LEMMA 4.3. Let P and Q be \triangleright -normal forms. Then $P \approx Q$ iff $P \equiv Q$.

Proof. The *size* of *P*, size(*P*), is the number of constructors in *P*. size(*P*) is invariant under \equiv '. By induction on size(*P*) + size(*Q*) we show $\approx \subset \equiv$ '. The base case, size(*P*) + size(*Q*) = 2, is immediate. The inductive step uses Lemma 4.2 (1,2) to reduce the argument to each prime component for which, after stripping off the common prefix, we can always use induction. Since \equiv ' is easily a bisimulation we also have \equiv ' $\subset \approx$, hence done.

We can now conclude the proof of Theorem 4.1 by establishing the completeness, $\leftrightarrow \supset \approx$, and combining it with Proposition 4.1. Assume $P \approx Q$. By Lemma 4.1 (2) we can find \triangleright -normal forms P_{nf} and Q_{nf} of P and Q, respectively, such that $P \mapsto^* P_{nf}$ and $Q \mapsto^* Q_{nf}$. By Corollary 4.1, we know $P_{nf} \approx Q_{nf}$. But Lemma 4.3 implies that \approx restricted to \triangleright -normal forms is contained in \leftrightarrow , hence $P \mapsto^* P_{nf} \leftrightarrow Q_{nf}$ and $Q \mapsto^* Q_{nf}$ which means $P \leftrightarrow Q$, as required.

5. FULLY ABSTRACT EMBEDDING OF $\lambda_{\rightarrow,\times,+}$ 5.1. The Functional Calculus

We use the simply typed λ -calculus with products and sums (written $\lambda_{\rightarrow,\times,+}$ from now on) as a testbed for the expressiveness of the presented calculus, establishing its fully abstract embeddability in the π -calculus. We have chosen $\lambda_{\rightarrow,\times,+}$ because of its rich type structures and non-trivial equational theory. For simplicity we omit base types other than unit. We review the syntax of types and terms below, with *i* ranging over $\{1,2\}$.

$$\begin{array}{l} T \;::=\; \text{unit} \; \mid T_1 \to T_2 \; \mid T_1 \times T_2 \; \mid T_1 + T_2 \\ M \;::=\; x \mid () \; \mid \lambda x : T.M \mid \langle M, N \rangle \mid \pi_i(M) \mid \text{in}_i(M) \mid \text{case} \; L \; \text{of} \; \{ \text{in}_i(x_i : T_i).M_i \}_{i \in \{1,2\}} \end{array}$$



We write $M \equiv_{\alpha} N$ for α -equality on terms. A term is *closed* if no variables occur free. The typing rules are standard, which we list in Figure 5 (cf. [24, 52]). We write $E \vdash M : T$ when a term *M* is typable with type *T* under a base *E*. We write $C[]_T:T'$ for a (typed) context of type *T'* with one hole of type *T*. We often omit type annotations from terms and contexts.

The reduction relation, written ~>, is the least compatible relation which includes:

$$\begin{array}{ll} (\beta) & (\lambda x.M)N \rightsquigarrow M\{N/x\} \\ (\text{proj}_i) & \pi_i \langle M_1, M_2 \rangle \rightsquigarrow M_i \\ (\text{case}_i) & \text{case in}_i(L) \text{ of } \{ \text{in}_i(x_i).N_i \} \rightsquigarrow N_i\{L/x_i\} \end{array}$$

Other possible notions of reduction include commuting conversions and η -rules [22]. We take the minimum meaningful reduction for simplicity, but the main technical results in this section hold for all reasonable variations (this is essentially because normal forms of boolean observables are invariant under these rules). We write $M \Downarrow N$ when $M \rightsquigarrow^* N$ and $N \not\rightsquigarrow$. A *normal form* is a term which has no further reductions. By easy induction on the structure of terms, a closed normal form of type $T \rightarrow T'$ (resp. $T \times T', T + T'$) has shape $\lambda x.M$ (resp. $\langle M, N \rangle$, $in_i(M)$).

Equality in $\lambda_{\to,\times,+}$ is not as simple as it may look, due to the existence of sums [22]. To have a semantically meaningful equality, we use observation of "values", cf. [52]. Let true $\stackrel{\text{def}}{=} \operatorname{in}_1(())$ and false $\stackrel{\text{def}}{=} \operatorname{in}_2(())$, both of type $\mathbb{B}_{\lambda} \stackrel{\text{def}}{=} \operatorname{unit} + \operatorname{unit}$. Then $E \vdash M \cong_{\lambda} N : T$ when, for each context $C[]_T : \mathbb{B}_{\lambda}$ such that C[M] and C[N] are closed, we have $(C[M] \Downarrow$ true $\Leftrightarrow C[N] \Downarrow$ true). The same equality is obtained by taking observability at each sum type, justifying all commuting conversions and η -rules.

5.2. Extension with Branching and Selection

Before encoding $\lambda_{\rightarrow,\times,+}$, we extend the typed π -calculus to its full syntax [11] by incorporating branching and selection. Branching is necessary to represent sums in $\lambda_{\rightarrow,\times,+}$ and is also used for defining a reduction-based typed congruence [33].

$$P ::= \cdots |x[\&_i(\vec{y}_i).P_i]| !x[\&_i(\vec{y}_i).P_i]| \overline{x} \mathbf{i} \mathbf{n}_i(\vec{y})P$$

$$\tau_{\mathtt{I}} ::= \cdots |[\&_i \vec{\tau}_i]^{\downarrow}| [\&_i \vec{\tau}_i]! \qquad \tau_{\mathtt{O}} ::= \cdots |[\oplus_i \vec{\tau}_i]^{\uparrow}| [\oplus_i \vec{\tau}_i]?$$

We often omit the indexing set *I* (which should be either countable or finite) of $x[\&_{i \in I}(\vec{y}_i).P_i]$. $x[\&_{i \in I}(\vec{y}_i).P_i]$ is called *branching*, while $\overline{x}in_i(\vec{y}:\vec{\tau})P$ is called *selection*. Similarly for

(Typing Rules)

(Bra [!])	(Sel)
$\vdash P_i \triangleright y_i: t_i \otimes A$	$\vdash P \triangleright A^{j,i} = A \approx x : [\bigoplus_i \tau_i]^{P \cup i}$
$\vdash !x[\&(\vec{y}_i).P_i] \triangleright x : [\&_i \vec{\tau}_i]! \rightarrow A$	$\vdash \overline{x} \mathrm{in}_j(\vec{y}) P \triangleright A/\vec{y} \odot x \colon [\oplus_i \vec{\tau}_i]^{p_{\circ}}$

(Labelled Transition Rules)

$$\begin{split} & x[\&_i \vec{y}_i.P_i]^A \xrightarrow{x \mathbf{i} \mathbf{n}_i(\vec{y}_i)} P_i^{\vec{y}_i:\vec{\tau}_i \otimes A/x} & (x : [\&\vec{\tau}_i]^\downarrow \in A) \\ & !x[\&_i \vec{y}_i.P_i]^A \xrightarrow{x \mathbf{i} \mathbf{n}_i(\vec{y}_i)} !x[\&_i \vec{y}_i.P_i] | P_i^{\vec{y}_i:\vec{\tau}_i \otimes A} & (x : [\&\vec{\tau}_i]^! \in A) \\ & \overline{x} \mathbf{i} \mathbf{n}_i(\vec{y}) P^A \xrightarrow{\overline{x} \mathbf{i} \mathbf{n}_i(\vec{y})} P^{\vec{y}:\vec{\tau}_i \otimes A/x} & (x : [\oplus_i \vec{\tau}_i]^\uparrow \in A) \\ & \overline{x} \mathbf{i} \mathbf{n}_i(\vec{y}) P^A \xrightarrow{\overline{x} \mathbf{i} \mathbf{n}_i(\vec{y})} P^{\vec{y}:\vec{\tau}_i \otimes A} & (x : [\oplus_i \vec{\tau}_i]^? \in A) \end{split}$$

 $[\&_i \vec{\tau}_i]^p$ and $[\bigoplus_i \vec{\tau}_i]^p$. \equiv is defined as in Figure 1. The reduction for branching involves selection of one branch, discarding the remaining ones, as well as name passing.

$$\begin{aligned} x[\&_i(\vec{y}_i).P_i] &| \overline{x} in_j(\vec{y}_j) \cdot Q \longrightarrow (v \vec{y}_j)(P_j \mid Q) \\ &! x[\&_i(\vec{y}_i).P_i] &| \overline{x} in_j(\vec{y}_j)Q \longrightarrow ! x[\&_i(\vec{y}_i).P_i] |(v \vec{y}_j)(P_j \mid Q) \end{aligned}$$

As an example, a *natural number agent*, $[[n]]_u \stackrel{\text{def}}{=} !u(c)\overline{c} in_n$, acts as a server which necessarily returns a fixed answer, *n*; see [11, 35, 69] for further examples of reductions.

The typing rules for branching/selection are given in Figure 6. \mapsto is extended as in Definition 3.1. Below in (E4) we assume *n* holes exhaust all occurrences of (linear) *x*; we extend (E1) in a similar way, reducing *n*-holes simultaneously.

- (E4) $C[\overline{x}in_{j_1}(\vec{y}_{j_1})P]..[\overline{x}in_{j_n}(\vec{y}_{j_n})P]|x[\&_i(\vec{y}_i).Q_i] \mapsto_{\mathsf{I}} C[(v\vec{y}_{j_1})(P|Q_{j_1})]..[(v\vec{y}_{j_n})(P|Q_{j_n})]$
- (E5) $C[\overline{x}in_j(\vec{y}_j)P]|!x[\&_i(\vec{y}_i).Q_i] \mapsto_{\mathsf{r}} C[(\mathsf{v}\,\vec{y}_j)(P|Q_j)]|!x[\&_i(\vec{y}_i).Q_i]$
- (E6) $(\mathbf{v}x)!x[(\vec{y})_i \cdot Q_i] \mapsto_{\mathbf{g}} \mathbf{0}$

The typed transition is defined by extending the set of labels with $xin_i(\vec{y})$ and $\overline{x}in_i(\vec{y})$ and by adding the rules in Figure 6. The weak bisimilarity \approx is then defined by the same clause as in Definition 4.1 in Section 4 using the extended transition relation.

The technical development for the full calculus is identical with that for the unary calculus in the preceding sections, except for the following minor changes:

• In Proposition 2.1: In (1), "precisely once" for a \uparrow -channel becomes, under a branching input, "precisely once in each branch". In (2), we extend the relation \frown for branching inputs and outputs.

• In Proposition 3.3 we add the following clauses to the generation rules of NF_e: if $P_i \in NF_e$ then $x[(\vec{y}_i).P_i]$ and $!x[(\vec{y})_i.P]$ are in NF_e; if $P \in NF_e$ then $\overline{xin}_i(\vec{y})P \in NF_e$.

• In the definition of semantic types (Definition 3.2), we add:

daf

$$\langle \langle x : [\&_i \vec{\tau}_i]^{\downarrow} \rangle \rangle \stackrel{\text{def}}{=} \{ x [\&_i (\vec{y} : \vec{\tau}_i) . P_i] \mid P_i \in [[\vec{y} : \vec{\tau}_i]] \}$$
$$\langle \langle x : [\&_i \vec{\tau}_i]^! \rangle \rangle \stackrel{\text{def}}{=} \{ ! x [\&_i (\vec{y} : \vec{\tau}_i) . P_i] \mid P_i \in [[\vec{y} : \vec{\tau}_i]] \}$$

With these changes, all arguments and results for the unary calculus carry over to the full syntax. We summarise the main syntactic properties below.

Proposition 5.1.

(1) (reduction) $If \vdash P \triangleright A$, then (i) $P \longrightarrow Q$ implies $\vdash Q \triangleright A$ and (ii) $P \longrightarrow Q_{1,2}$ implies either $Q_1 \equiv Q_2$ or $Q_{1,2} \longrightarrow R$ for some R, and (iii) $\mathsf{CSN}(P)$.

(2) (extended reduction) $If \vdash P \triangleright A$, then (i) $P \mapsto Q$ implies $\vdash Q \triangleright A$ and (ii) $P \mapsto Q_{1,2}$ implies $Q_{1,2} \mapsto^* R$ for some R, and (iii) $CSN_e(P)$.

(3) (finite axiomatisation) Let $\leftrightarrow = (\mapsto \cup \equiv)^*$. Then $\leftrightarrow = \approx$.

Branching allows us to define contextual equality in the strongly normalising processes, using observables at non-trivial branching types. Formally the *contextual congruence* \cong is the maximum typed congruence over (extended) processes satisfying the following condition. Let $\mathbb{B} = [\bigoplus_{i=1,2}]^{\uparrow}$ below.

If
$$P_1 \Downarrow_x^i$$
 and $P^{x:\mathbb{B}} \cong Q^{x:\mathbb{B}}$, then $Q \Downarrow_x^i$ $(i = 1, 2)$

where $P \Downarrow_x^i$ means $P \longrightarrow^* \overline{x} \operatorname{in}_i(\overline{y}) P'$ and $P^{x:\mathbb{B}} \cong Q^{x:\mathbb{B}}$ relate P and Q typed under $x:\mathbb{B}$. As in bisimilarity, we sometimes simply write $P \cong Q$ for $P^A \cong Q^A$. We observe:

PROPOSITION 5.2.

(1) (maximal consistency) \cong is maximally consistent in the sense that the only typed congruence which strictly includes \cong is the universal relation.

(2) (context lemma) Let $\vdash P_{1,2} \triangleright A$. Then $P_1 \cong P_2$ if and only if, for each $\vdash R \triangleright \overline{A} \otimes x : \mathbb{B}$, $(\nu \operatorname{fn}(A))(P_1|R) \Downarrow_x^i$ iff $(\nu \operatorname{fn}(A))(P_2|R) \Downarrow_x^i$.

(3) (innocuous actions) If $\vdash P \triangleright A$ and md(A) = ? then $P^A \cong \mathbf{0}^A$.

Proof. For (1), let **R** be the result of adding an equation to \cong . By the definition of \cong there are $P^{x:\mathbb{B}} \mathbf{R} Q^{x:\mathbb{B}}$ such that $P \Downarrow_x^1$ and $Q \Downarrow_x^2$. Take any $\vdash R_{1,2} \triangleright \uparrow ?A$ (with $x \notin \operatorname{fn}(A)$). Then $S \stackrel{\text{def}}{=} x[.R_1 \&. R_2]$ is typable. By the congruence of **R** we have $S|P_1\mathbf{R}S|P_2$. Since $\longrightarrow \in \cong$ (cf. Proposition 5.1) this implies $R_1\mathbf{R}R_2$. From such $R_{1,2}$ we can build any prime/non-prime terms, by which we conclude the universality of **R**. (2) is standard: for reference Appendix D.1 lists the proof. For (3), suppose $P \stackrel{\text{def}}{=} \overline{x}(\overline{y})P'$ has type ?A and take the context $C[\]$ from A to $u: \mathbb{B}$. By (2) above we can set $C[\]$ has form $(\vee w)(S|R|[\])$ where R is the composition of replicated processes compensating A. Since u cannot occur in R it occurs in S, whose behaviour at u does not depend on P in C[P], i.e. $C[P] \Downarrow_u^i$ iff $C[\mathbf{0}] \Downarrow_u^i$, hence $P \cong \mathbf{0}$. (An alternative concise proof of (3) using a refined bisimulation is given in [69].) ■ \cong and \approx are related in the following way.

Proposition 5.3. $\approx \subsetneq \cong$.

Proof. By Proposition 4.4, \approx is a typed congruence and it respects convergence at \mathbb{B} by definition. Since \cong is the maximum such this shows $\approx \subset \cong$. For strictness, take $\vdash \overline{x} \triangleright x$: ()[?].

By Proposition 5.2 (3) this process is \cong -equal to 0 but clearly $\overline{x} \not\approx 0$.

Finally we list processes of specific form used in the encoding later, called *copycat*. A copy-cat dynamically links two locations, which has an origin in *forwarder* in actors as well as in game semantics.

$$\begin{aligned} & [x \to x']^{(\vec{\tau})^{\downarrow}} \stackrel{\text{def}}{=} x(\vec{y}) \cdot \overline{x'}(\vec{y'}) \Pi_i [y'_i \to y_i]^{\overline{\tau_i}} \\ & [x \to x']^{(\vec{\tau})^{\downarrow}} \stackrel{\text{def}}{=} !x(\vec{y}) \cdot \overline{x'}(\vec{y'}) \Pi_i [y'_i \to y_i]^{\overline{\tau_i}} \\ & [x \to x']^{[\&_i \vec{\tau}_i]^{\downarrow}} \stackrel{\text{def}}{=} x [\&_i (\vec{y}_i) \cdot \overline{x'} \operatorname{in}_i (\vec{y'}_i) \Pi_{ij} [y'_{ij} \to y_{ij}]^{\overline{\tau_{ij}}}] \\ & [x \to x']^{[\&_i \vec{\tau}_i]^{\downarrow}} \stackrel{\text{def}}{=} !x [\&_i (\vec{y}_i) \cdot \overline{x'} \operatorname{in}_i (\vec{y'}_i) \Pi_{ij} [y'_{ij} \to y_{ij}]^{\overline{\tau_{ij}}}] \end{aligned}$$

The following property of copy-cats is used later.

PROPOSITION 5.4.

 $(1) \vdash [x \to y]^{\tau} \triangleright x: \tau \to (y: \overline{\tau} \otimes ?A) \text{ for each input type } \tau \text{ and } ?A \text{ with } x, y \notin fn(A).$ (2) $(\vee y) (P|[y \to x]^{\tau}) \mapsto^* P\{x/y\}$ assuming typability.

Proof. See Appendix D.2. ■

5.3. Sequentiality

One of the basic notions we shall use for the proof of the full abstraction, is *sequentiality*. "Sequential" in this context means that processes have at most one active thread: The combination with the sequential type discipline in [10] can realise this behaviour in linear processes. While the full abstraction result is established in the linear π -calculus without the sequentiality constraint, sequentiality plays a crucial role in several arguments. Below we restrict the linear π -calculus to its sequential subsystem following [11] and study its basic properties used in the subsequent proofs.

The first constraint on the linear typing is on channel types.

DEFINITION 5.1. The set of *sequential channel types* is generated by:

• $(\tau_1 ... \tau_n)^{\downarrow}$ is sequential if, for each $1 \le i \le n$, τ_i is sequential and $md(\tau_i) = ?$; and

• $(\tau_1 .. \tau_n)^!$ is sequential if, for each $1 \le i \le n$, τ_i is sequential and, for each $1 \le i \le n-1$, $\mathsf{md}(\tau_i) = ?$ while $\mathsf{md}(\tau_n) = \uparrow$.

Dually for output types and similarly for branching/selection types (imposing the same constraint for each summand).

The sequent for sequential typing has the form $\vdash_{\phi} P \triangleright A$ where $\phi \in \{I, \circ\}$ is an *IO-mode*, which ensures *P* contains at most one active thread. ϕ obeys the partial algebra $I \odot I = I$ and $I \odot \circ = \circ \odot I = \circ$. When $\phi_1 \odot \phi_2$ is defined (that is, if they are not simultaneously output), then we write $\phi_1 \approx \phi_2$.

The typing rules are given in Figure 7 (the sequential version of (Bra) and (Sel) follow (In) and (Out)). The use of IO-modes in in (Par) ensures single threading since $\circ \odot \circ i$ is undefined. An output (resp. input) can only prefix a body in input (resp. output) mode, resulting in output (resp. input) mode. **0** starts from I. Other rules, (Res,Weak), do not change IO-modes. For this system we observe:

(Zero) _	(Par) $\vdash_{\phi_i} P_i \triangleright A_i (i = 1, 2)$ $A_1 \asymp A_2 \phi_1 \asymp \phi_2$	2)	(Res) $\vdash_{\phi} P \triangleright A^{x:\tau}$ $md(\tau) \in \{\uparrow, !\}$	_	(Weak) $\vdash_{\phi} P \triangleright A^{-x}$ $md(\tau) \in \{\updownarrow, ?\}$
⊢₋ 0⊳₋	$\vdash_{\phi_1 \odot \phi_2} P_1 P_2 \triangleright A_1 \odot$	A_2	$\vdash_{\phi} (\mathbf{v} x : \tau) P \triangleright A / x$		$\vdash_{\phi} P \triangleright A \otimes x : \tau$
(In [↓]) ⊢ ₀ <i>P</i> ⊳ ÿ: t̃⊗	$\uparrow A^{-x} \otimes ?B^{-x}$	(In [!]) ⊢₀ <i>P</i> ⊳	$ec{\mathbf{v}}:ec{\mathbf{t}}\otimes ?A^{-x}$	(Ou ⊦⊥	$ P \triangleright A^{\vec{y}:\vec{\tau}} A \asymp x: (\vec{\tau})^{p_0} $
$\vdash_{I} x(\vec{y}:\vec{\tau}).P \triangleright$	$(x:(\vec{\tau})^{\downarrow} \to A) \otimes B$	$\vdash_{I} ! x(\bar{y})$	$T: \vec{\tau}).P \triangleright x: (\vec{\tau})! \rightarrow A$	⊦₀;	$\overline{x}(\vec{y})P \triangleright A/\vec{y} \odot x : (\vec{\tau})^{p_{\circ}}$
	FIG. 7. Linear Sequential Typing				

PROPOSITION 5.5.

(1) If $\vdash_{\phi} P \triangleright A$ and $P \longrightarrow Q$ then $\vdash_{\phi} Q \triangleright A$. Similarly if $\vdash_{\phi} P \triangleright A$ and $P \mapsto Q$ then $\vdash_{\phi} Q \triangleright A$. (2) If $\vdash_{\phi} P \triangleright A$ and $P \longrightarrow Q_{1,2}$ then $Q_1 \equiv Q_2$. (3) If $\vdash_{\phi} P \triangleright A$ then CSN(P) and $CSN_e(P)$.

Proof. (1) follows the proof of Proposition 2.2 (presented in Appendix A.2 using A.4), incorporating IO-modes in addition. (2) is because there is at most one active output in a sequential process. (3) is immediate since $\vdash_{\phi} P \triangleright A$ implies $\vdash P \triangleright A$ by definition.

Remark. Proposition 5.5 (2) indicates the sequential nature of dynamics in sequential linear processes: in spite of this, \mapsto gives a way of computing normal forms of sequential processes by parallel reduction.

A significant property is that linear processes typed under sequential channel types are already sequential from a semantic viewpoint.

DEFINITION 5.2. An action type *A* is *sequential* if all channel types used in *A* are sequential and, moreover, it does not contain two linear output channels.

Having at most one linear output in an action type (cf. [11, Appendix F]) makes it possible to have inductive definition of sequentialisation, given next.

PROPOSITION 5.6. (sequentialisation) Given $\vdash P \triangleright A$ such that A is sequential, $P \in \mathsf{NF}_e$ and P does not contain hiding, define P^{\sharp} by the following induction, implicitly assuming typability under sequential A in each case.

- $\mathbf{0}^{\sharp} \stackrel{\text{def}}{=} \mathbf{0} \text{ and } (P|Q)^{\sharp} \stackrel{\text{def}}{=} P^{\sharp}|Q^{\sharp}.$
- $(x(\vec{y}).P)^{\sharp} \stackrel{\text{def}}{=} x(\vec{y}).P^{\sharp}$ and $(!x(\vec{y}).P)^{\sharp} \stackrel{\text{def}}{=} !x(\vec{y}).P^{\sharp}$, similarly for branching.
- • $(\overline{x}(\overline{y})P)^{\sharp} \stackrel{\text{def}}{=} \overline{x}(\overline{y})P^{\sharp}$ if $\uparrow \in \mathsf{md}(A)$, $(\overline{x}(\overline{y})P)^{\sharp} \stackrel{\text{def}}{=} \mathbf{0}$ if $\uparrow \not\in \mathsf{md}(A)$, similarly for selection.

Then we have $\vdash_{\phi} P^{\sharp} \triangleright A$ for some ϕ and, moreover, $P \cong P^{\sharp}$.

Proof. We first show, by rule induction, $\vdash_{\phi} P^{\sharp} \triangleright A$ for some ϕ whenever $\vdash P \triangleright A$ for $P \in \mathsf{NF}_e$ and sequential A. W.l.o.g. we work under Convention 3.1. If $P = \mathbf{0}$ then $\vdash \mathbf{0} \triangleright$? A hence

 $\vdash_{I} \mathbf{0} \triangleright A$, as required. For $P = P_1 | P_2$, let $\vdash_{\phi_i} P_i \triangleright A_i$ (i = 1, 2) such that $A = A_1 \odot A_2$. Suppose $\phi_1 = \phi_2 = \circ$. Since $P \in \mathsf{NF}_e$, P_1^{\sharp} and P_2^{\sharp} respectively contains prime outputs S_1^{\sharp} and S_2^{\sharp} as factors of parallel composition. By A being sequential, one of S_1^{\sharp} and S_2^{\sharp} has only ?-mode channels (note a prime output does not contain input subjects), which is impossible by construction. Thus one of ϕ_1 and ϕ_2 is I, from which sequential typability is immediate. The remaining cases are direct from the induction hypothesis. For $P \cong P^{\sharp}$, the only non-trivial case is $(\overline{x}(\overline{y})P)^{\sharp} \stackrel{\text{def}}{=} \mathbf{0}$ when $\uparrow \not\in \mathsf{md}(A)$, for which we use Proposition 5.2 (3). The rest is direct from induction hypothesis.

Using sequentialisation we establish a refined context lemma. We only present the result for processes of the form needed for our later result.

LEMMA 5.1. (sequential context lemma) Let $\vdash P_{1,2} \triangleright x: \tau \to ?A$ (with $\mathsf{md}(\tau) = !$) such that τ and A are sequential. Then $P_1 \cong P_2$ iff for each $\vdash_0 T \triangleright x: \overline{\tau} \otimes u: \mathbb{B}$ and for each $\vdash_1 R \triangleright \overline{A}$ we have $(\vee \vec{w})(P_1|R|S_1) \Downarrow_u^i \Leftrightarrow (\vee \vec{w})(P_2|R|S_2) \Downarrow_u^i$ where $\mathsf{fn}(A) = \{\vec{w}\}$.

Proof. By Proposition 5.2 (2) and by absorbing/garbage collecting processes using extended reduction, we know $P_1 \cong P_2$ iff for each $\vdash T \triangleright x : \overline{\tau} \otimes u : \mathbb{B}$ and for each $\vdash R \triangleright \overline{A}$. By $\approx \subset \cong$ we know $P \mapsto P'$ implies $P \cong P'$, so that we can take R and T to be in NF_e. Using Proposition 5.6 we can further reduce R and T to be sequential processes.

5.4. Encoding and Soundness

The encoding of $\lambda_{\rightarrow,\times,+}$ is given in Figure 8. The encoding of a $\lambda_{\rightarrow,\times,+}$ -type *T*, written T° , maps *T* to a replicated type. The encoding of a $\lambda_{\rightarrow,\times,+}$ -term $E \vdash M : T$, written $[\![E \vdash M : T]\!]$ or $[\![M : T]\!]$ for brevity, adapts Milner's call-by-name encoding [49] to our type structure by adding an indirection at each λ -abstraction. The encoding of terms follows the encoding of types, and uses type information on variables in a λ -term. The encoding of a base *E*, written E° , maps each x:T in *E* to $x:\overline{T^{\circ}}$, dualising the mode. This can be understood as follows: if we have a $\lambda_{\rightarrow,\times,+}$ -term $x:T \vdash M:T'$. The corresponding process interacts with a datum of type T° in the environment, and produces a datum of type T'° . Thus at *x*, the process itself should have the type which complements T° , that is $\overline{T^{\circ}}$.

PROPOSITION 5.7. For each T, T° is a sequential unary channel type of mode !.

Proof. By rule induction of the map ()°. The base case is ()° = (()[†])!, which is immediate. For induction, $(T_1 \Rightarrow T_2)^\circ = (\overline{T_1^\circ}(T_2^\circ)^\dagger)!$ is sequential iff $T_{1,2}^\circ$ are sequential and have mode !, which is the induction hypothesis. Similarly for $(T_1 \times T_2)^\circ$ and $(T_1 + T_2)^\circ$.

PROPOSITION 5.8. (syntactic soundness) If $E \vdash M : T$ then $\vdash [[M:T]]_u \triangleright u : T^\circ \to E^\circ$.

Proof. See Appendix D.3.

Note also $[[M : T]]_u$ has always the shape $!u(\vec{z}).P$. Further $[[M : T]]_u$ is sequentially typable, though we do not use this property in our subsequent proof. This concludes the verification of static properties of the encoding.

For dynamics, we obtain:

PROPOSITION 5.9. If $E \vdash M : T$ and $M \rightsquigarrow M'$ then $[\![M]\!]_u \mapsto^+ [\![M']\!]_u$.

Remark. Note there is an exact operational correspondence between \rightsquigarrow and \mapsto : \rightsquigarrow is simulated by \mapsto directly, not up to some semantic equality.

 $\begin{array}{lll} \textbf{(Type)} & \text{unit}^{\circ} \stackrel{\text{def}}{=} (()^{\uparrow})! & (T_1 \Rightarrow T_2)^{\circ} \stackrel{\text{def}}{=} (\overline{T_1^{\circ}}(T_2^{\circ})^{\uparrow})! \\ & (T_1 \times T_2)^{\circ} \stackrel{\text{def}}{=} ((T_1^{\circ} T_2^{\circ})^{\uparrow})! & (T_1 + T_2)^{\circ} \stackrel{\text{def}}{=} ([T_1^{\circ} \oplus T_2^{\circ}]^{\uparrow})! \\ \textbf{(Base)} & \emptyset^{\circ} \stackrel{\text{def}}{=} \emptyset & (E \cdot x; T)^{\circ} \stackrel{\text{def}}{=} E^{\circ} \cdot x; \overline{T^{\circ}} \end{array}$

(Terms)

$$\begin{split} & [[x:T]]_{u} \stackrel{\text{def}}{=} [u \to x]^{T^{\circ}} \\ & [[():\text{unt}]]_{u} \stackrel{\text{def}}{=} !u(x).\overline{x} \\ & [[\lambda x:T'.M:T' \Rightarrow T]]_{u} \stackrel{\text{def}}{=} !u(xz).\overline{z}(m) [[M:T]]_{m} \\ & [[MN:T]]_{u} \stackrel{\text{def}}{=} !u(\overline{z}).(\nu m n) ([[M:T' \Rightarrow T]]_{m} | \operatorname{Arg}\langle m, N, \overline{z} \rangle^{T' \Rightarrow T}) \quad (*) \\ & [[\langle M_{1}, M_{2} \rangle : T \times T']]_{u} \stackrel{\text{def}}{=} !u(c).\overline{c}(m_{1}m_{2}) ([[M_{1}:T]]_{m_{1}} | [[M_{2}:T']]_{m_{2}}) \\ & [[\pi_{1}(M):T]]_{u} \stackrel{\text{def}}{=} !u(\overline{z}).(\nu m) ([[M:T \times T']]_{m} | \operatorname{Proj}_{1}\langle m, \overline{z} \rangle^{T}) \quad (*) \\ & [[\operatorname{inl}(M):T+T']]_{u} \stackrel{\text{def}}{=} !u(c).\overline{c}\operatorname{inl}(m) [[M:T]]_{m} \\ & [[\operatorname{case} L \text{ of } \{\operatorname{in}_{i}(x_{i}:T_{i}).M_{i}\}_{i \in \{1,2\}} : T]]_{u} \stackrel{\text{def}}{=} !u(\overline{z}).(\nu l) ([[L:T_{1}+T_{2}]]_{l} | \operatorname{Sum}\langle l, \overline{z}, \{(x_{i})M_{i}\}\rangle^{T}) \quad (*) \\ & \operatorname{Arg}\langle m, N, \overline{z} \rangle^{T_{i} \Rightarrow T_{2}} \stackrel{\text{def}}{=} \overline{m}(nc) ([[N:T_{1}]]_{n} | c(w).\operatorname{Msg}\langle w\overline{z}\rangle^{T_{\circ}}) \\ & \operatorname{Proj}_{i}\langle m, \overline{z}\rangle^{T} \stackrel{\text{def}}{=} \overline{m}(nc) ([[N:T_{1}]]_{n} | c(w).\operatorname{Msg}\langle w\overline{z}\rangle^{T_{\circ}}) \\ & \operatorname{Proj}_{i}\langle m, \overline{z}\rangle^{T} \stackrel{\text{def}}{=} \overline{m}(e) e(\nu_{1}\nu_{2}).\operatorname{Msg}\langle \nu_{i}\overline{z}\rangle^{T} \\ & \operatorname{Sum}\langle l, \overline{z}, \{(x_{i})M_{i}\}\rangle^{T} \stackrel{\text{def}}{=} \overline{l}(c) c[\&_{i \in \{1, 2\}}(x_{i}).(\nu m) ([[M_{i}:T]]_{m} | \operatorname{Msg}\langle m\overline{z}\rangle^{T^{\circ}})] \\ & \operatorname{Msg}\langle x\overline{y}\rangle^{(\dagger)'} \stackrel{\text{def}}{=} \overline{x}(\overline{y}') \prod [y'_{i} \to y_{i}]^{\overline{v}_{i}} \\ & (*) \ \overline{z} = z_{1}z_{2} \ \text{if } T = T_{1} \Rightarrow T_{2}, \text{else } \ \overline{z} = z. \\ & \text{We omit }\operatorname{inr}(M) \ \text{and} \pi_{2}(M). \end{array}$$

FIG. 8. Encoding of $\lambda_{\rightarrow,\times,+}$

Proof. See Appendix D.4. ■

COROLLARY 5.1. $\lambda_{\rightarrow,\times,+}$ is strongly normalising.

Proof. Immediate from Theorem 3.2 and Proposition 5.9.

Proposition 5.9 and its corollary offer a faithful computational embedding of $\lambda_{\rightarrow,\times,+}$ in the π -calculus: we now show that this also extends to semantics, starting from soundness. To this end we first analyse the inhabitation property of the linear π -calculus at $\mathbb{B}^{\circ}_{\lambda}$.

PROPOSITION 5.10. If $\vdash P \triangleright u : \mathbb{B}^{\circ}_{\lambda}$ and $P \in \mathsf{NF}_{e}$ then either $P \equiv [[\mathsf{true} : \mathbb{B}_{\lambda}]]_{u}$ or $P \equiv [[\mathsf{false} : \mathbb{B}_{\lambda}]]_{u}$.

Proof. We use Proposition 3.3, noting $\mathbb{B}^{\circ}_{\lambda} \stackrel{\text{def}}{=} ([\bigoplus_{i=1,2}(()^{\uparrow})!]^{\uparrow})!$. Let *P* be a >-normal form such that $\vdash P \triangleright u: \mathbb{B}^{\circ}_{\lambda}$. By Proposition 3.3, $P = !u(z).P'_1$ such that $\vdash P'_1 \triangleright z: [\bigoplus_{i=1,2}(()^{\uparrow})!]^{\uparrow}$. Again by Proposition 3.3 $P'_1 = \overline{z} i n_i(w)P'_2$ with $\vdash P'_2 \triangleright w: (()^{\uparrow})!$. This way we reach $P \equiv !u(z).\overline{z}inj_i(w)!w(v).\overline{v}$.

LEMMA 5.2. (computational adequacy) Let $M : \mathbb{B}_{\lambda}$ be closed. Then $M \Downarrow \text{true iff}$ $\llbracket M \rrbracket_{u} \Downarrow_{e} \llbracket \text{true} \rrbracket_{u}$.

Proof. Proposition 5.9 gives the "only if" direction, noting $[[true]]_u \in NF_e$. For the "if" direction, we first observe the following property.

Claim. If $\vdash M : \mathbb{B}_{\lambda}$ and $M \Downarrow N$ then either $N \equiv_{\alpha}$ true or $N \equiv_{\alpha}$ false.

This is because, as mentioned in Section 5.1, closed $\lambda_{\to,\times,+}$ -normal forms of type unit, $T_1 \Rightarrow T_2$, $T_1 \times T_2$ and $T_1 + T_2$ have the shape, respectively, (), $\lambda x.M$, $\langle M_1, M_2 \rangle$ and $\operatorname{in}_i M$ [because: there is nothing to prove when the term is either (), $\lambda x.M$, $\langle M, N \rangle$ or $\operatorname{in}_i(M)$; if the closed normal form is MN, by induction M should be abstraction hence induces a redex, a contradiction; if $\pi(M)$ is a closed normal form M is again so, thus by induction we know M is a pairing which is impossible; similarly for case L of $\{\operatorname{in}_i(x_i).M_i\}$ with respect to L]. Hence N as above should have form $\operatorname{in}_i(N')$ where N' is of type unit and is again a closed normal form, that is $N' \stackrel{\text{def}}{=}$ (), as required. Suppose $[\![M]\!] \Downarrow [\![true]\!]_u$ and $M \Downarrow N$. If N =true we are done. If not, N = false. By Proposition 5.9, we know $[\![M]\!]_u \Downarrow [\![false]\!]_u$, which contra-

dicts the CR of \mapsto , hence done.

By the standard argument we obtain:

COROLLARY 5.2. (soundness) $\llbracket E \vdash M : T \rrbracket_u \cong \llbracket E \vdash N : T \rrbracket_u$ implies $E \vdash M \cong_{\lambda} N : T$.

5.5. Completeness

We now tackle a harder direction, the equational completeness of the encoding. While preceding studies of types for the π -calculus have established the soundness of some λ calculus embeddings, they are rarely complete due to the fine-grained nature of namepassing [66]. The technical development in this subsection shows, following [10], that the duality-based type discipline gives a precise representation of functional strong normalising computation as name-passing processes, leading to full abstraction. The proof uses *finite canonical forms* (FCFs) [4, 37], which are semantically innocuous extension of $\lambda_{\rightarrow,\times,+}$ -terms that can cleanly represent linear sequential processes under the encoded $\lambda_{\rightarrow,\times,+}$ -typing. Via FCFs, we know all linear sequential processes of $\lambda_{\rightarrow,\times,+}$ -types can be decoded back into $\lambda_{\rightarrow,\times,+}$ -terms. By sequential context lemma, this is enough to represent all pertinent process contexts as $\lambda_{\rightarrow,\times,+}$ -terms, reaching the completeness. In comparison with [10], we entirely argue via syntactic structure without going through innocent functions (even though the definability argument is closely related to the one based on innocent functions in [10]). The grammar of finite canonical forms [4, 37] (FCFs) follow.

$$F ::= () | x | \lambda x.F | \langle F_1, F_2 \rangle | \operatorname{in}_i(F) | \operatorname{case} x \operatorname{of} \{ \operatorname{in}_i(x_i).F_i \}$$
$$| \operatorname{let} () = z \operatorname{in} F | \operatorname{let} x = zF \operatorname{in} F' | \operatorname{let} \langle x, y \rangle = z \operatorname{in} F$$

FCFs use three additional constructs, let () = N in M (let-unit), let $x = N_1N_2 : S$ in M (let-app) and let $\langle x, y \rangle = N$ in M (let-prod). We omit their typing rules [4, 37]. Hereafter we only consider well-typed FCFs.

In the context of the functional calculus, we may consider FCFs in terms of their translation into $\lambda_{\rightarrow,\times,+}$ -terms, which folds "let" constructs using substitutions. The map, denoted fold (\cdot) , is given as follows.

$$\begin{array}{rl} \operatorname{fold}(()) & \stackrel{\mathrm{def}}{=} & () \\ & \operatorname{fold}(x) & \stackrel{\mathrm{def}}{=} & x \\ & \operatorname{fold}(\lambda x.F) & \stackrel{\mathrm{def}}{=} & \lambda x.\operatorname{fold}(F) \\ & \operatorname{fold}(\lambda x.F) & \stackrel{\mathrm{def}}{=} & \langle \operatorname{fold}(F_1), \, \operatorname{fold}(F_2) \rangle \\ & \operatorname{fold}(\operatorname{in}_i(F)) & \stackrel{\mathrm{def}}{=} & \operatorname{in}_i(\operatorname{fold}(F)) \\ & \operatorname{fold}(\operatorname{case} x \text{ of } \{\operatorname{in}_i(x_i).F\}) & \stackrel{\mathrm{def}}{=} & \operatorname{case} x \text{ of } \{\operatorname{in}_i(x_i).\operatorname{fold}(F)\} \\ & \operatorname{fold}(\operatorname{let}() = z \operatorname{in} F) & \stackrel{\mathrm{def}}{=} & \operatorname{fold}(F) \\ & \operatorname{fold}(\operatorname{let} x = zF \operatorname{in} F') & \stackrel{\mathrm{def}}{=} & \operatorname{fold}(F) \{z \operatorname{fold}(F)/x\} \\ & \operatorname{fold}(\operatorname{let}\langle x,y\rangle = z \operatorname{in} F) & \stackrel{\mathrm{def}}{=} & \operatorname{fold}(F) \{\pi_1(z), \pi_2(z)/x, y\} \end{array}$$

By structural induction, we can check fold(F) is a \rightsquigarrow -normal form for each F. By combining this folding with $[\![]\!]_u$, we can now encode FCFs into the π -calculus.

Another way to map FCFs into the π -calculus is to directly encode FCFs to ENFs. Below we set, w.l.o.g.: for lets, $[\![F]\!]_u \stackrel{\text{def}}{=} ! u(\vec{w}) . P$; and, for case, $[\![F_i]\!]_u \stackrel{\text{def}}{=} ! u(\vec{w}) . P_i$.

$$\begin{array}{l} \langle \langle () \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(c).\overline{c} \\ \langle \langle x \rangle \rangle_{u} \stackrel{\text{def}}{=} [u \to x] \\ \langle \langle \lambda x.F \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(xc).\overline{c}(f) \langle \langle F \rangle \rangle_{f} \\ \langle \langle \langle F_{1}, F_{2} \rangle \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(c).\overline{c}(f_{1}f_{2}) (\langle \langle F \rangle \rangle_{f_{1}} | \langle \langle F \rangle \rangle_{f_{2}}) \\ \langle \langle \operatorname{in}_{i}(F) \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(c).\overline{c}\operatorname{in}_{i}(f) \langle \langle F \rangle \rangle_{f} \\ \langle \langle \operatorname{case} z \text{ of } \{ \operatorname{in}_{i}(x_{i}).F_{i} \} \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(\vec{w}).\overline{z}(c)c[\&_{i}(x_{i}).P_{i}] \\ \langle \langle \operatorname{let} () = z : \operatorname{unit} \operatorname{in} F \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(\vec{w}).\overline{z}(f'c) (\langle \langle F' \rangle \rangle_{f'} | c(x).P) \\ \langle \langle \operatorname{let} \langle x, y \rangle = z \operatorname{in} F : T \rangle \rangle_{u} \stackrel{\text{def}}{=} !u(\vec{w}).\overline{z}(c)c(xy).P \end{array}$$

 $\langle\langle F \rangle\rangle_u$ and $[[fold(F)]]_u$ semantically coincide:

LEMMA 5.3. For each $E \vdash F : T$, we have $\llbracket \text{fold}(F) : T \rrbracket_u \cong \langle \langle F : T \rangle \rangle_u$.

Proof. See Appendix D.5. ■

A fundamental property of FCFs is that we can decode back processes of $\lambda_{\rightarrow,\times,+}$ -types onto corresponding FCFs. The decoding is done by first choosing sequential processes (which does not lose generality by Proposition 5.6), then transforming them using certain permutation.

PROPOSITION 5.11.

(1) For each T and E, $u:T^{\circ} \to E^{\circ}$ is sequential in the sense of Definition 5.2. (2) For each $E \vdash F:T$, we have $\vdash_{I} \langle \langle F:T \rangle \rangle_{u} \triangleright u:T^{\circ} \to E^{\circ}$.

Proof. (1) is from Proposition 5.8 (1). (2) is easy induction.

LEMMA 5.4. Assume below processes are in NF_e , are sequentially typed with sequential action types, and obey Convention 3.1 and the standard bound name convention. (1) (permutation) $\overline{x}(\vec{r}c)(R \mid c[\&_i(\vec{w}_i).\overline{z}(e)!e(\vec{y}).P_i]) \cong \overline{z}(e)!e(\vec{y}).\overline{x}(\vec{r}c)(R \mid c[\&_i(\vec{w}_i).P_i])$ if x has ?-mode and z has \uparrow -mode.

(2) (η -expansion, 1) $|u(\vec{x}z).P \cong |u(\vec{x}z).\overline{z}(\vec{m})P'$ for some \vec{m} and P' if z is typed as $(\vec{\tau})^{\uparrow}$.

(3) $(\eta$ -expansion, 2) We say a sequential P is η -expanded if, for each subterm of P of the form $!u(\vec{x}z) \cdot P'$ with z typed with a unary linear type, P' has the shape $\overline{z}(\vec{y})Q$. Then for each sequential P, there is an η -expanded P^{η} such that $P \cong P^{\eta}$.

Proof. (2) and (3) use (1). See Appendix D.6 for detail.

We can now define the reverse map. Let $\vdash P \triangleright u: T^{\circ} \to E^{\circ}$ such that $P \in NF_{e}$ without hiding or redundant **0**. By Propositions 5.11 (1) and 5.6, we safely assume *P* is sequentially typed. Further by Lemma 5.4 (3) let *P* be η -expanded.² Noting these conditions are satisfied by each subterm of *P*, the map ((*P*)) is defined by the following induction. In the last four lines we assume $z \notin \{\vec{y}\}$.

$$\begin{array}{rcl} & ((!u(c).\overline{c})) & \stackrel{\text{def}}{=} & () \\ & ((!u(xc).\overline{c}(f)P)) & \stackrel{\text{def}}{=} & \lambda x. ((P)) \\ & ((!u(c).\overline{c}(f_1f_2)(!f_1(\vec{y_1}).P_1|!f_2(\vec{y_2}).P_1))) & \stackrel{\text{def}}{=} & (((!f_1(\vec{y_1}).P_1)), ((!f_2(\vec{y_2}).P_2))) \\ & ((!u(c).\overline{c}\text{in}_i(f)P)) & \stackrel{\text{def}}{=} & \text{in}_i(((P))) \\ & ((!u(\vec{y}).\overline{c}(c)c.P)) & \stackrel{\text{def}}{=} & \text{let} & () = z \text{ in} & ((!u(\vec{y}).P)) \\ & ((!u(\vec{y}).\overline{c}(c)c(R-P'))) & \stackrel{\text{def}}{=} & \text{let} & x = z((P)) \text{ in} & ((!u(\vec{y}).P')) \\ & ((!u(\vec{y}).\overline{c}(c)c(x_1x_2).P)) & \stackrel{\text{def}}{=} & \text{let} & \langle x_1, x_2 \rangle = y \text{ in} & ((!u(\vec{y}).P)) \\ & ((!u(\vec{y}).\overline{c}(c)c[\&_i(x_i).P_i])) & \stackrel{\text{def}}{=} & \text{case } z \text{ of} & \{\text{in}_i(x_i).((!u(\vec{y}).P_i))\} \end{array}$$

By inspecting each rule, we immediately observe:

PROPOSITION 5.12. Let $\vdash_{I} P \triangleright E^{\circ} \cdot u : T^{\circ}$. $P \in \mathsf{NF}_{e}$ and P is η -expanded. Then (1) $E \vdash (\!(P)\!) : T$ and (2) $P \equiv \langle \langle (\!(P)\!) : T \rangle \rangle_{u}$.

A key property for the completeness follows.

COROLLARY 5.3. (definability) $Let \vdash P \triangleright E^{\circ} \cdot u : T^{\circ}$. Then $P \cong \llbracket M : T \rrbracket_u$ for some $E \vdash M : T$.

Proof. By Propositions 5.11 (1) and 5.6, take the sequential version of P, P^{\ddagger} . By Lemma 5.4 (3), further take its η -expansion, $P^{\ddagger\eta}$. Let $M \stackrel{\text{def}}{=} \operatorname{fold}(((P^{\ddagger\eta})))$. Then we have:

$$P \cong P^{\sharp\eta} \equiv \langle \langle ((P^{\sharp\eta})) : T \rangle \rangle_u \cong [[\mathsf{fold}(((P^{\sharp\eta}))) : T)]_u \stackrel{\text{def}}{=} [[M : T]]_u$$

as required (the first equation is by Propositions 5.6 and 5.11 (1); the next \equiv is by Lemma 5.4 (3); and the third equation is by Lemma 5.3).

We can now establish the full abstraction. We use the following isomorphism between \mathbb{B} and $\mathbb{B}^{\circ}_{\lambda}$ (actually we only need one direction of the isomorphism).

²In fact, we only need η -expansion for function types, i.e. when a subterm has the form !u(xz).P. Alternatively, we can dispense with η -expansion by adding an additional syntax to FCFs.

PROPOSITION 5.13. (isomorphism) Write $C[\cdot]_A^B$ for a context whose hole has type A and whose result has type B. Define:

$$C_{\mathbf{f}}\left[\begin{array}{c} \cdot \end{array}_{x:\mathbb{B}}^{y:\mathbb{B}_{\lambda}^{\circ}} \stackrel{\text{def}}{=} y(c).(\mathbf{v}x)(x[\&_{i=1,2}.\overline{c}\mathtt{i}\mathtt{n}_{i}(f)!f(g).\overline{g}] \mid [\cdot]) \\ C_{\mathbf{b}}\left[\begin{array}{c} \cdot \end{array}_{y:\mathbb{B}_{\lambda}^{\circ}} \stackrel{\text{def}}{=} (\mathbf{v}y)(\overline{y}(c)c[\&_{i=1,2}.\overline{x}\mathtt{i}\mathtt{n}_{i}] \mid [\cdot]) \end{array}\right]$$

Then we have:

(1) $C_{\mathsf{f},\mathsf{b}}$ are well-typed. (2) $P^{x:\mathbb{B}} \bigcup_{x}^{1} iff C_{\mathsf{f}}[P]^{y}_{x} \bigcup_{e} [[\mathsf{true}]]_{y}, dually P^{y:\mathbb{B}^{y}_{\lambda}} \bigcup_{e} [[\mathsf{true}]]_{y} iff C_{\mathsf{b}}[P]^{x}_{y} \bigcup_{x}^{1}.$ (3) $C_{\mathsf{b}}[C_{\mathsf{f}}[P]^{y}_{x}]^{y}_{y} \mapsto^{+} P \text{ for each } \vdash P \triangleright x: \mathbb{B} \text{ and, dually, } C_{\mathsf{f}}[C_{\mathsf{b}}[Q]^{x}_{y}]^{y}_{x} \mapsto^{+} Q.$

Proof. (1) is immediate. For (2) let $\vdash P \triangleright x$: \mathbb{B} . Without loss generality let $P \in \mathsf{NF}_e$, so that $P \equiv \overline{x} in_i$.

$$C_{f}[P]_{x}^{y} \stackrel{\text{def}}{=} !y(c).(\forall x)(x[\&_{i=1,2}.\overline{c} \operatorname{in}_{i}(f)!f(g).\overline{g}] | \overline{x} \operatorname{in}_{i}) \\ \mapsto^{1} !y(c).\overline{c} \operatorname{in}_{i}(f)!f(g).\overline{g}$$

Similarly $C_{b}[!y(c).\overline{cin}_{i}(f)!f(g).\overline{g}]_{y}^{x} \mapsto^{*} \overline{xin}_{i}$, hence done. (3) follows (2).

1.6

THEOREM 5.1. (full abstraction)
$$E \vdash M_1 \cong_{\lambda} M_2 : T$$
 iff $[[M_1 : T]]_u \cong [[M_2 : T]]_u$.

Proof. Let $E \vdash M_{1,2}$: *T* with $E = y_1 : T_2, ..., y_n : T_n$. By Corollary 5.2, we only have to show the "then" direction. We prove the contrapositive, $[\![M_1:T]\!]_u \cong [\![M_2:T]\!]_u$ implies $M_1 \cong_{\lambda} M_2$. Below we often omit type annotation for brevity.

$$\begin{split} \llbracket M_{1}:T \rrbracket_{u} & \not\cong \llbracket M_{2}:T \rrbracket_{u} \\ \Leftrightarrow \quad \exists \vdash_{I} R \triangleright \overline{E^{\circ}}, \ \vdash_{\circ} S \triangleright u: \overline{T^{\circ}} \otimes v: \mathbb{B}, \\ (vx\vec{y})(\llbracket M_{1} \rrbracket_{u} | R | S) \downarrow_{v}^{1}, (vx\vec{y})(\llbracket M_{2} \rrbracket_{u} | R | S) \downarrow_{v}^{2} \\ (Lem. 5.1) \\ \Leftrightarrow \quad \exists \vdash_{I} R \triangleright \overline{E^{\circ}}, \ \vdash_{\circ} S \triangleright u: \overline{T^{\circ}} \otimes v: \mathbb{B}, \\ C_{f}[(vx\vec{y})(\llbracket M_{1} \rrbracket_{u} | R | S)]_{v}^{w} \downarrow_{e} \llbracket \text{true} \rrbracket_{w}, \ C_{f}[(vx\vec{y})(\llbracket M_{2} \rrbracket_{u} | R | S)]_{v}^{w} \downarrow_{e} \llbracket \text{false} \rrbracket_{w}. \\ (Prop. 5.13(2)) \\ \Leftrightarrow \quad \exists \vdash_{I} R \triangleright \overline{E^{\circ}}, \ \vdash_{\circ} S \triangleright u: \overline{T^{\circ}} \otimes v: \mathbb{B}, \\ (vx\vec{y})(\llbracket M_{1} \rrbracket_{u} | R | C_{f}[S]_{v}^{w}) \downarrow_{e} \llbracket \text{true} \rrbracket_{w}, \ (vx\vec{y})(\llbracket M_{2} \rrbracket_{u} | R | C_{f}[S]_{v}^{w}) \downarrow_{e} \llbracket \text{false} \rrbracket_{w}. \\ (Lem. D.1) \\ \Rightarrow \quad \exists \vdash N_{i}: T_{i}, \ u: T \vdash L: \mathbb{B}, \\ (vx\vec{y})(\llbracket M_{1} \rrbracket_{u} | \Pi \llbracket N_{i} \rrbracket_{y_{i}} \llbracket L \rrbracket_{w}) \downarrow_{e} \llbracket \text{true} \rrbracket_{w}, \ (vx\vec{y})(\llbracket M_{2} \rrbracket_{u} | \Pi \llbracket N_{i} \rrbracket_{y_{i}} \llbracket L \rrbracket_{w}) \downarrow_{e} \llbracket \text{false} \rrbracket_{w}. \\ (Cor.5.3) \\ \Leftrightarrow \quad (\lambda u.L)((\lambda y_{1}...y_{n}.M_{1})\vec{N}) \Downarrow \text{true}, \ (\lambda u.L)((\lambda y_{1}...y_{n}.M_{2})\vec{N}) \Downarrow \text{false}. \\ (Lem. 5.2) \\ \overset{\text{def}}{\Leftrightarrow} M_{1} \not\cong_{\lambda} M_{2}, \end{aligned}$$

as required.

Remark. By Corollary 5.3, the embedding is in addition fully complete (in the sense of [3]) up to \cong .

6. LINEAR π -CALCULUS WITH FREE NAME PASSING

In the previous sections, we have investigated the properties of the linear π -calculus whose outputs are restricted to those which pass only bound names. Using bound names has significance in making the representation of computational behaviour as tight as possible: given some behaviour which we wish to model, the way of representing it in the typed calculus becomes strongly constrained and thus, for example, we own a fairly tractable notion of inhabitants in each type (Theorem 5.1). However, a natural question remains: can we impose behavioural constraints of the similar kind on terms with free name passing, i.e. using the standard syntax for the asynchronous π -calculus? And if we can, does it add any expressive power? This is not only intellectual curiosity. Apart from the simplicity of the presentation (by moving to free name passing we can get rid of a couple of added structural rules), free name passing makes the computation more tractable: it also has technical advantages in the second-order setting [12].

This section studies these questions, extending the syntax to free outputs while using precisely the same type structures. The typing rules do not change except for free outputs. The embedding of terms of the system with bound outputs into the system with free outputs is essentially subset inclusion. After presenting the translation, we show these two maps not only preserve types but also the semantics: they do not change the behaviour of processes up to the canonical equalities. This result also shows that the universe of linear terms with free outputs is semantically equivalent to its strict subset which use only bound outputs, thus answering the question posed above. The extended reduction is used as a tractable tool to prove their correspondence.

6.1. Linear Typing with Free Name Passing

The syntax of processes with free name passing is the standard asynchronous polyadic π calculus with branchings and selections. We take off the bound output and selection from the syntax in Section 5 and replace them with the following two.

$$P ::= \dots | \overline{x} \langle \vec{y} \rangle | \overline{x} \operatorname{in}_i \langle \vec{y} \rangle$$

The bound output $\overline{x}(\vec{y})P$ can be recovered as $(\vee \vec{y})(\overline{x}\langle \vec{y}\rangle|P)$, so that the second syntax in fact subsumes the first one. For the reduction relation \longrightarrow , we replace the axioms with:

$$\begin{array}{ccc} x(\vec{y}).P \mid \overline{x}\langle \vec{v} \rangle & \longrightarrow & P\{\vec{v}/\vec{y}\}\\ x[\&_i(\vec{y}_i).P_i] \mid \overline{x} \mathrm{in}_i \langle \vec{v} \rangle & \longrightarrow & P\{\vec{v}/\vec{y}_i\} \end{array}$$

Similarly for replication. The typing rules for these processes are exactly the same except that the sequent is now written $\vdash_f P \triangleright A$ and that we use the following rules for outputs.

(Out)	(Sel)
$\vdash_{\mathrm{f}} \overline{x} \langle \vec{y} \rangle \triangleright x : (\vec{\tau})^{p_{\mathrm{O}}} \odot \vec{y} : \overline{\vec{\tau}}$	$\vdash_{\mathrm{f}} \overline{\mathrm{xin}_j} \langle \vec{\mathrm{y}}_j \rangle \triangleright x : [\oplus_i \vec{\mathrm{t}}_i]^{p_0} \odot \vec{\mathrm{y}}_j : \overline{\vec{\mathrm{t}}_j}$

In (Out), we assume $\tau_i = \tau_j$ if $y_i = y_j$. Similarly for (Sel). Note the types for object names in the above two rules are dualised. The resulting system is denoted FNP and the original system is denoted BNP. For clarity we hereafter write $\vdash_b P \triangleright A$ for the typability in BNP.

The rules for outputs given above, are best understood in terms of the following representation of free outputs in the realm of bound outputs.

$$\overline{x}\langle \vec{y}^{\vec{\tau}}\rangle^{\circ} \stackrel{\text{def}}{=} \overline{x}(\vec{w})\Pi_i [w_i \to y_i]^{\tau_i}$$

(The same expression already appeared as $Msg\langle x\vec{w}\rangle$ in Figure 8). The annotation of free objects do not lose generality since, when processes are typed, we can always restore the original type information. The above representation says that a free name output is a bound name output in which all exported names are "equated" with the mentioned free names. In this representation, w_i is used as τ_i and, as a result, y_i is used as $\overline{\tau}_i$, illustrating the typing rules given above.

Let $\vdash P \triangleright A$ and define P° by extending the above map compositionally, i.e. $\mathbf{0}^{\circ} \stackrel{\text{def}}{=} \mathbf{0}$, $(P|Q)^{\circ} \stackrel{\text{def}}{=} P^{\circ}|Q^{\circ}, ((\mathbf{v}x)P)^{\circ} \stackrel{\text{def}}{=} (\mathbf{v}x)(P^{\circ}), (x(\vec{y}).P)^{\circ} \stackrel{\text{def}}{=} x(\vec{y}).(P^{\circ}), (!x(\vec{y}).P)^{\circ} \stackrel{\text{def}}{=} !x(\vec{y}).(P^{\circ})$ and $\overline{x}\langle \vec{y}^{\vec{\tau}} \rangle^{\circ} \stackrel{\text{def}}{=} \overline{x}(\vec{w}) \prod_{i} [w_{i} \rightarrow y_{i}]^{\tau_{i}}$, similarly for branching. We shall be using this encoding for relating the two systems. We can easily check:

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PROPOSITION 6.1. \vdash_{\mathrm{f}} P \triangleright A \text{ iff } \vdash_{\mathrm{b}} P^{\circ} \triangleright A.
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While we can directly verify various syntactic properties of FNP, a simple way to do so is by reducing them to those of BNP. We first define the extended reduction for the free output calculus as follows.

where $(E1_f, E2_f, E3_f)$ correspond to (E1, E2, E3) respectively (In $(E1_f)$ we incorporate occurrences of linear output names in branches, cf. Section 5.1). (E1, E2, E3) are changed accordingly. We now show, via the mapping $(\cdot)^\circ$, the dynamics of BNP can completely mimic that of FNP.

PROPOSITION 6.2. (simulation) Let $\vdash_f P \triangleright A$ below.

(1) If
$$P \equiv Q$$
 then $P^{\circ} \equiv Q^{\circ}$. Also $P^{\circ} \{\vec{v}/\vec{y}\} \stackrel{\text{def}}{=} (P\{\vec{v}/\vec{y}\})^{\circ}$.
(2) If $P \longrightarrow Q$ then $P^{\circ} \longrightarrow \stackrel{*}{\longrightarrow} Q^{\circ}$.
(3) If $P \mapsto Q$ then $P^{\circ} \mapsto \stackrel{+}{\longrightarrow} Q^{\circ}$.

Proof. Two statements in (1) are mechanical. For (2) we argue by rule induction. For the base case, we use Proposition 5.4 (2) as well as the latter half of (1) above to obtain:

$$\begin{array}{rcl} x(\vec{y}).P|\overline{x}\langle \vec{v}\rangle & \stackrel{\text{def}}{=} & x(\vec{y}).P^{\circ}|\overline{x}(\vec{y})\Pi[y_{i} \rightarrow v_{i}] \\ & \longrightarrow & (\nu \vec{y})(P^{\circ}|[v_{i} \rightarrow y_{i}]) \\ & \mapsto^{*} & P^{\circ}\{\vec{v}/\vec{y}\} \stackrel{\text{def}}{=} (P\{\vec{v}/\vec{y}\})^{\circ} \end{array}$$

hence as required. Similarly for the replicated reduction. The inductive cases are immediate from the corresponding induction hypotheses, using the first part of (1) for the closure

under \equiv . (3) is similar.

Below CSN(P) and $CSN_e(P)$ in FNP are understood as those ideas in BNP.

COROLLARY 6.1.

(1) (reduction) If $\vdash_f P \triangleright A$, then (i) $P \longrightarrow Q$ implies $\vdash_f Q \triangleright A$; (ii) $P \longrightarrow Q_{1,2}$ implies either $Q_1 \equiv Q_2$ or $Q_{1,2} \longrightarrow R$ for some R; and (iii) $\mathsf{CSN}(P)$.

(2) (extended reduction) If $\vdash_f P \triangleright A$, then (i) $P \mapsto Q$ implies $\vdash_f Q \triangleright A$; (ii) $P \mapsto Q_{1,2}$ implies $Q_{1,2} \mapsto^* R$ for some R; and (iii) $\text{CSN}_e(P)$.

Proof. Direct from the corresponding results in BNP. As an example, let $\vdash_f P \triangleright A$ and $P \longrightarrow Q$. Then $\vdash_b P^\circ \triangleright A$ by Proposition 6.1. Further let $P \longrightarrow Q$. By Proposition 6.2 we have $P^\circ \mapsto^* Q^\circ$, hence by subject reduction in BNP we have $\vdash_b Q^\circ \triangleright A$. Again by Proposition 6.1 this means $\vdash_b Q \triangleright A$, as required.

Remark. (on bisimilarities) Define \approx in FNP using the standard free name passing transition, combined with the type-directed constraints given in Figure 4. We can easily show \approx coincides with the congruent closure of \mapsto in FNP, using precisely the same reasoning. This result cannot be obtained via the embedding, because \approx is not abstract enough in comparison wit the one induced by the encoding: the equivalence obtained via the embedding (based on \approx in BNP) is strictly more general. We can regain the latter by using a refined typed transition discussed in [12] (also see [13]); though we use neither of these bisimilarities in the following discussions.

6.2. Mutual Fully Abstract Embeddings

For mutual embeddings between BNP and FNP, we use the contextual congruences of the previous section (defined by the same clause for BNP and FNP). We write this maximum congruence for BNP and FNP, \cong_b and \cong_f , respectively. If we wish to designate them without specifying which, we write \cong . Since the symmetric closure of \mapsto is a typed congruence which respects convergence at \mathbb{B} , we know $\mapsto \subset \cong$. We use the following observations [33, 56].

LEMMA 6.1. For each $\vdash_{\mathbf{b}} P \triangleright A$ with $\mathsf{md}(A(x)) \in \{\uparrow, ?\}$ and a fresh name y, we have $(\mathsf{v}x)(P|[x \to y]) \cong_{\mathbf{b}} P\{y/x\}$. Similarly, for each $\vdash_{\mathbf{f}} P \triangleright A$ with $\mathsf{md}(A(x)) \in \{\uparrow, ?\}$, we have $(\mathsf{v}x)(P|[x \to y]) \cong_{\mathbf{f}} P\{y/x\}$.

Proof. By Proposition 5.4 (2) $(vx)(P|[x \to y]) \mapsto^* P\{y/x\}$ in BNP. By Proposition 6.2 the same is true for FNP. Since \mapsto stays within \cong , we are done.

Let $\vdash_{b} P \triangleright A$. Then we write P^{\star} for the result of translating P into a process with free name passing by the following map for bound output, $(\overline{x}(\overline{y})P)^{\star} \stackrel{\text{def}}{=} (v\overline{y})(\overline{x}\langle \overline{y}\rangle|P^{\star})$, as well as $\mathbf{0}^{\star} \stackrel{\text{def}}{=} \mathbf{0}, (P|Q)^{\star} \stackrel{\text{def}}{=} P^{\star}|Q^{\star}, ((vx)P)^{\star} \stackrel{\text{def}}{=} (vx)(P^{\star}), (x(\overline{y}).P)^{\star} \stackrel{\text{def}}{=} x(\overline{y}).(P^{\star})$ and $(!x(\overline{y}).P)^{\star} \stackrel{\text{def}}{=} !x(\overline{y}).(P^{\star})$, similarly for branching. We can verify:

PROPOSITION 6.3. $\vdash_{b} P \triangleright A$ iff $\vdash_{f} P^{\star} \triangleright A$.

We can now state the main result of this section.

THEOREM 6.1. (both-way retracts) For each $\vdash P \triangleright A$, we have $P^{*\circ} \cong_b P$. Similarly, for each $\vdash_f P \triangleright A$, we have $P^{\circ*} \cong_f P$.

Proof. For the first half, we use induction. The only non-trivial case is bound output. Let $\vdash \overline{x}(\vec{y})P \triangleright A$. Then

$$\begin{aligned} (\overline{x}(\overline{y})P)^{\star^{\circ}} &\stackrel{\text{def}}{=} (\nu \, \overline{y}) ((\overline{x}(\overline{w})\Pi_i[w_i \to y_i])|P^{\star^{\circ}}) \\ &\equiv \overline{x}(\overline{w})(\nu \, \overline{y})(\Pi_i[w_i \to y_i]|P^{\star^{\circ}}) \\ &\cong_{\mathsf{h}} \overline{x}(\overline{y})(P^{\star^{\circ}}) \cong_{\mathsf{h}} \overline{x}(\overline{y})P \end{aligned}$$

The last two equations are by Lemma 6.1 and by induction hypothesis, respectively. The second half is also by induction, which boils down to showing $\overline{x}\langle \vec{y} \rangle^{\circ \star} \cong_{f} \overline{x}\langle \vec{y} \rangle$. In fact, using Lemma 6.1, we have:

$$\overline{x}\langle \vec{y} \rangle^{\circ^{\star}} \stackrel{\text{def}}{=} (\mathbf{v} \, \vec{w}) (\overline{x} \langle \vec{w} \rangle | \Pi_i [w_i \to y_i]) \cong_{\mathrm{f}} \overline{x} \langle \vec{y} \rangle$$

as required.

Theorem 6.1 shows that all additional terms in FNP which do not exist in BNP are in fact equivalent to their image in BNP, so that FNP does not add anything to BNP semantically. Further it says that this map is semantically the identity map on BNP. We now conclude the section with a full abstraction result.

COROLLARY 6.2. (full abstraction) $\vdash_{\mathbf{b}} P \cong_{\mathbf{b}} Q \triangleright A$ iff $\vdash_{\mathbf{f}} P^* \cong_{\mathbf{f}} Q^* \triangleright A$. Similarly $\vdash_{\mathbf{f}} P \cong_{\mathbf{f}} Q \triangleright A$ iff $\vdash_{\mathbf{b}} P^\circ \cong_{\mathbf{b}} Q^\circ \triangleright A$.

For the proof we use the characterisation in Proposition 5.2 (2). Suppose $P \cong_b Q$ and $C[P^*] \Downarrow_x^i$. By Theorem 6.1, $R^\circ \cong_f R$, so that $(C[P^*])^\circ \Downarrow_x^i$, that is $C^\circ[P^{*\circ}] \Downarrow_x^i$. Again by Theorem 6.1 we have $C^\circ[P] \Downarrow_x^i$. By assumption we have $C^\circ[Q] \Downarrow_x^i$, that is $(C^\circ[Q])^* \Downarrow_x^i$, from which we know, again by Theorem 6.1, $C[Q^*] \Downarrow_x^i$, as required. The converse is trivial since ()* is syntactic identity. The proof of the second half is precisely symmetric.

7. DISCUSSION AND FURTHER WORK

Summary. The present study is part of our quest to articulate significant classes of computational behaviour using typed π -calculi. Previous work [11] introduced *affine, sequential* types for the π -calculus and established full abstraction for an encoding of PCF, which is the representative sequential functional calculus allowing divergent computation. Using causality between names, the present text refines affine, sequential types into *linear* types to ensure strong normalisability and full abstraction for $\lambda_{\rightarrow,\times,+}$. Figure 9 shows the relationship between these results.

• The addition of branching types is indicated by &, \rightarrow adds causality to action types, and Seq stands for the inclusion of the sequentiality constraints used in [11].

• Determinacy, SN and sequentiality are properties guaranteed by each typing system.

• FC denotes *full completeness* of the embedding of the corresponding λ -calculus into the π -calculus in the sense of [3] (up to \equiv and η -expansion, cf. Proposition 5.3), while FA stands for *full abstraction* up to semantic equality.

For example, the linear typing system in § 2 corresponds to Aff $+ \rightarrow$, its branching extension in §5 to Aff $+ \& + \rightarrow$ and the sequential system in [11] to Aff + & + Seq. Note that the development in § 5 shows that our encoding is already 'almost' fully complete intensionally



FIG. 9. A Family of Affine/Linear Systems

and indeed becomes fully complete by quotienting with the observational congruence. It is also notable that we could have used the call-by-value encoding in [49] to obtain exactly the same result, indicating the flexibility of the proposed calculus to encode functional SN behaviour. Extensions based on this family are summarised in the introduction, but also in [35, Figure 1] and [67, Figure 1]. See also the discussion below.

Liveness in Interaction. A consequence of strong normalisability is liveness in interaction: if a typed agent calls another replicated typed agent and waits for its answer at a linear channel x, then an answer is guaranteed to eventually arrive at x, however complex intermediate interaction sequences would be.

PROPOSITION 7.1. (linear honesty) Let $x: (\tau)^{!} \in A$ such that $\mathsf{md}(\tau) = \uparrow$. Suppose $\vdash P \triangleright A$ with A closed. Then $P \xrightarrow{x(y)} P'$ implies $P' \longrightarrow^* \stackrel{l}{\longrightarrow}$ where l is an output at y.

For the proof we use the following lemma.

LEMMA 7.1. (linear actions) Let $\Gamma \vdash P \triangleright A \otimes \uparrow x$ with A closed. Then for each $P \longrightarrow^* P_0$ there exists P' such that $P_0 \longrightarrow^* P'$ where (1) P' contains no active linear input channels, and (2) P' $\stackrel{l}{\longrightarrow}$ such that l is an output at x.

Proof. Without loss of generality assume $P \equiv \prod_{1.n} P_i^{y_i}$ where each P_i is prime (we can ignore other shapes of P because if there is a restriction at x then the corresponding action type is again closed). By A being closed, all free outputs in P are compensated by free input channels which should be active by well-typedness. This means each P_i is input-prefixed or, if not, it is output-prefixed with x. Suppose there is a linear input prefix with subject, say, $y'_1 \in \{y\}$. Since A is closed, there is a compensating output. Since $P \in NF_e$, this output should be under some input prefix whose subject cannot be y'_1 by acyclicity. This means, say, $y'_2 \sim y'_1$. Again this should be compensated by some output, which should be prefixed by an input with subject z, but z cannot be among $\{y'_1, y'_2\}$ by acyclicity again. So set $z = y'_3$. In this way we have a chain of form $y'_n \sim y'_{n-1} \sim ... \sim y'_1$ which exhaust $\{y\}$. But this means y'_n has no compensating output, contradicting A's being closed. Hence there is

no active linear input in P, establishing (1). Since if x is not active it should be under the prefix of a linear input, this also proves (2), as required.

By CR of \rightarrow and by Theorem 3.1, this establishes Lemma 7.1.

Now Proposition 7.1 is immediate by noting that, after the mentioned input, the term has the action type mentioned in the Lemma after it performs the appropriate input.

We can strengthen Proposition 7.1 by incorporating the possibility that the client itself interacts with the server towards the eventual answer [30]. The central point of the present liveness property is that, in spite of such nested, complex webs of procedure calls, each client is still guaranteed to receive an answer, improving on preceding related type disciplines, cf. [40, 41, 66]. We can further guarantee this liveness property with non-terminated and stateful (i.e. non-deterministic) computation [67]; this property plays as the key rôle to establish further applications for information flow analysis of programming languages [35, 69].

State and Non-functional Control. It is an important subject of study to extend our typing system to allow incorporation of state, control and other non-functional elements. The resulting calculi would be useful as a theoretical basis for the application of SN in a wider realm. Such a formalism might also be useful as a meta-language for logical systems with e.g. non-deterministic cut elimination procedures.

For stateful computation, [67] has verified that our proof method is also applicable in SN for first-order stateful processes combining the proof method established in Classical Logics framework [43, 62]. The basic idea is first replacing replication with recursion [32], then applying the term rewriting technique directly using the extended reduction. This allows to carry over the SN type discipline and related results in imperative computation involving non-trivial procedure calls in [35].

For the incorporation of control into the present type discipline, all we need is to eliminate \downarrow - \uparrow types from the present system. In other words, the system presented in Section 2 already contains the calculus for (linear) control as its subcalculus. This means, among others, the calculus satisfies all syntactic properties we have explored in Sections 2 and 3, including strong normalisability. We have verified that a sequential version of this calculus can fully abstractly embed Parigo's $\lambda\mu$ -calculus. Further discussions on this calculus and its extensions will be discussed elsewhere.

Second-order and Other Extensions in Type Structure. Can the presented results be augmented to cover more expressive notions of types studied in functional calculi? Adding recursive types [50, 64] easily leads to a system that is not strongly normalising: for example, the encoding, following Figure 8, of $(\lambda x.xx)(\lambda x.xx)$ becomes typable. Regarding second-order types, our recent work [12] demonstrates that such extensions coexist harmoniously with SN, as they do in the corresponding functional calculi. In particular, the causality constraints formalised in the present paper are sufficient to encode System F fully abstractly in the second-order extension of the present system. Other, more refined type structures would also be worth studying in the present context: the π -calculus offers a natural habitat to SN typing systems for stateful, control [29], interactive and mobile computation.

Complex Causality. The present work adds minimum causality to the system in [11] to ensure SN of replicated processes. However, our SN proof seems to be able to cope,

without significant change, with more complex causality relations: for example, we could relax the channel type constraints and extend action types to finite graph structures between arbitrary linear nodes as in [66]. An even wider class of SN interactions would be typable if we further allowed edges of the more general form $px \rightarrow qy$, where $p \in \{\downarrow, \uparrow, ?\}$ and $q \in \{!, \downarrow, \uparrow\}$ (i.e. replicated and linear nodes can be mixed). Diverse structures would be embeddable in such an extension, including full proof nets [9]. The status of strong reduction would become subtle in this setting, cf. [22].

Game Semantics. In game semantics, "winning strategies" represent strong normalisation [3]. This representation ensures, essentially by definition, that composition of two winning strategies will never go into infinite τ -actions (which would make the strategy partial). This extensional representation of SN does not directly suggest concrete type disciplines to ensure SN for mobile processes, even though the liveness property discussed in Proposition 7.1 closely corresponds to the games-based characterisation of SN. In this context, we observe that the sequential version of the linear π -calculus discussed in Section 5.3 is the linear refinement of the affine sequential calculus in [10, 11]. This immediately shows that the typed sequential transition for the linear sequential π -calculus is *innocent* in the sense of [4, 10, 37]. The linear liveness in Proposition 7.1 further indicates that it is *total*, in the sense that it is always defined for each legal input; and, moreover, we can show it is *finite* in that the cardinality of the induced innocent function for each process is finite. It would be interesting to use the framework introduced in the present paper, among others typed processes and their behavioural characterisation, for formulating and studying various notions of SN and related ideas in game semantics (for example we may consider explicit incorporation of acyclicity conditions).

Term Rewriting and Reduction Strategies. The proof method presented in this paper uses the extended reduction \mapsto to prove not only SN but also other results including a fully abstract embedding of $\lambda_{\rightarrow,\times,+}$. One of the merits in using \mapsto lies in the potential applicability of various Term Rewriting Lemmas in the context of interacting processes. In fact, technically speaking, this may be regarded as one of the main differences from other studies addressing termination and other related properties of processes [41, 58]. Our recent work [67] partly addresses this point. In Section 3, we define a reduction strategy of \mapsto to prove SN. Like the left-most reduction strategy of the λ -calculus, this strategy could be defined in the untyped setting in general, then could be used to prove the normalisation theorem (i.e. it always derives a normal form if it exists). This opens possibility to study various reduction strategies in the name-passing scenario, which had not been investigated so far due to, among others, existence of structure rules. We may hope that, through such studies, that the accumulated ideas from functional computation such as optimality [45] may be transferable into non-deterministic and non-terminating interactive computation.

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APPENDIX A

A.1. PROOFS FOR SECTION 2

A.2. PROOF OF SUBJECT REDUCTION THEOREM

We prove Proposition 2.2 (1). The key point is to prove basic properties of algebra on action types. We use the same routine as in [11, 32, 66]. We first show:

LEMMA A.1. Assume A, A_1 and A_2 are action types.

- (1) A/\vec{y} is an action type.
- (2) If $A_1 \simeq A_2$, then $A_1 \odot A_2$ is an action type.

Proof. As the proof in Lemma 3.4 in [32]. (1) is trivial. The case $fn(A_1) \cap fn(A_2) = \emptyset$ in (2) is obvious. The other case is proved by induction on the size of A_1 and A_2 using the BNF

representation of action types.

LEMMA A.2. Let A_1 , A_2 , A_3 be action types. Then we have:

(1) (commutativity) Assume $A_1 \simeq A_2$. Then we have $A_2 \simeq A_1$ and $A_1 \odot A_2 = A_2 \odot A_1$.

(2) (associativity) Assume $A_1 \simeq A_2$ and $(A_1 \odot A_2) \simeq A_3$. Then we have: (1) $A_1 \simeq A_3$ and $A_2 \simeq A_3$, (2) $A_1 \simeq (A_2 \odot A_3)$ and (3) $(A_1 \odot A_2) \odot A_3 = A_1 \odot (A_2 \odot A_3)$.

Proof. (1) is obvious by definition. (2) is proved by induction on the size of A_i using the BNF representation of action types. This is proved as (a special case of) Lemma 3.5 in [32].

Lemma A.3.

(1) If $x: \tau \in |A|$ and $\mathsf{md}(\tau) \in \{!, \downarrow\}$ then there is no $y: \tau' \in |A|$ such that $y: \tau' \to x: \tau$. (2) $?B \asymp ?B$ and $B \odot B = B$.

(3) If $A \simeq B$ with $A/\vec{x} = A_0$, $x_i : \tau_i \in |A|$, $\mathsf{md}(\tau_i) \in \{!, \downarrow, \downarrow\}$, and $\mathsf{fn}(B) \cap \{\vec{x}\} = \emptyset$, then $A_0 \simeq B$ and $(A \odot B)/\vec{x} = A_0 \odot B$.

(4) If $A \simeq B$ with $A/\vec{x} = A_0$, $x_i: \tau_i \in |A|$, $\mathsf{md}(\tau_i) \in \{!, \downarrow, \uparrow\}$, and $B/\vec{x} = B_0$, then $A_0 \simeq B$, $A \simeq B_0$, $A_0 \simeq B_0$, and $(A \odot B)/\vec{x} = A_0 \odot B_0$.

(5) Suppose $A/\vec{x} = A_0$, $B/\vec{x} = B_0$ and $A_0 \simeq B_0$. Assume $x_i : \tau_i \in |A|$ with $\mathsf{md}(\tau_i) \in \{\uparrow, \downarrow, \downarrow\}$, and if $x_i : \tau'_i \in |B|$, then $\tau_i \simeq \tau'_i$. Then $A \simeq B$ and $(A \odot B)/\vec{x} = A_0 \odot B_0$.

Proof. (1) is by the definition of permissibility of \rightarrow , i.e. there is no edge to inputs and \uparrow . (2) is obvious by $\tau \odot \tau = \tau$ with md(τ) = ?. For (3), by (1), we can write $A = \bigotimes_i (x_i : \tau_i \rightarrow A'_i) \otimes A'$ since md(τ_i) $\in \{!, \downarrow, \uparrow\}$ (note A_i may be \emptyset). Then by $A \asymp B$, obviously $A_0 = (A_i \otimes A') \asymp B$. Hence we have $(A \odot B)/\vec{x} = (A/\vec{x} \odot B/\vec{x}) = A_0 \odot B$. The proof of (4) is similar. (5) uses (2) and (4).

Remark. If we delete the side condition $md(\tau_i) \in \{!, \downarrow, \uparrow\}$ in (5), the property does not hold. For counterexample, let $A = x_1 : \tau_1 \to x_2 : \overline{\tau_2}$ and $B = x_2 : \tau_2 \to x_1 : \overline{\tau_1}$. Then $A/x_1x_2 \simeq B/x_1x_2$, but $A \odot B$ is undefined.

LEMMA A.4.

(1) $\vdash P \triangleright A \text{ and } P \equiv Q \text{ then } \vdash Q \triangleright A.$

 $\begin{array}{l} (2) \vdash x(\vec{y};\vec{\tau}).P \mid \overline{x}(\vec{y};\vec{\tau}')Q \triangleright A \ implies \vdash (\vee \vec{y};\vec{\tau}'')(P \mid Q) \triangleright A \ with \ \tau'_i = \overline{\tau_i} \ and \ \tau''_i = \tau_i \odot \tau'_i. \\ (3) \quad \vdash !x(\vec{y};\vec{\tau}).P \mid \overline{x}(\vec{y};\vec{\tau}')Q \triangleright A \ implies \ \vdash !x(\vec{y};\vec{\tau}).P \mid (\vee \vec{y};\vec{\tau}'')(P \mid Q) \triangleright A \ \tau'_i = \overline{\tau_i} \ and \ \tau''_i = \overline{\tau_i} \ and \ \tau''_i = \tau_i \odot \tau'_i. \end{array}$

Proof. The proof is essentially the same as in [11, 32]. Assume $\vdash P \triangleright A$. Then, as in [11, Proposition 1 (ii)], there exists a minimum action type A_0 such that $A_0 \subseteq A_1$ and $\vdash P \triangleright A_0$ (since we only have to use (Weak) before restriction and input rules). Hence in the following we only consider the minimum action types.

(1) By rule induction on \equiv . The case of $P | \mathbf{0} \equiv P$ is easy because \emptyset is a unit of \odot . Similarly the cases of $P | Q \equiv Q | P$, and $(P | Q) | R \equiv P | (Q | R)$ are proved by Lemma A.2 (1) and (2), respectively. Next take the structural rule

$$(\overline{x}(\overline{y})P) \mid Q \equiv \overline{x}(\overline{y})(P \mid Q) \text{ with } x \notin fn(Q)$$

Assume $\vdash \langle \overline{x}(\overline{y})P \rangle | Q \triangleright A$ such that $x \notin \operatorname{fn}(Q)$. By typing rules we can assume $\vdash \overline{x}(\overline{y})P \triangleright A_1$ and $\vdash Q \triangleright A_2$ with $A_1 \simeq A_2$ and $A_1 \odot A_2 = A$. By strengthening of bases we can set $\{\overline{y}\} \cap \operatorname{fn}(A_2) = \emptyset$. From $\vdash \overline{x}(\overline{y})P \triangleright A_1$ we deduce $\vdash P \triangleright A'_1 \otimes \overline{y}: \overline{\tau}$ with $A_1 = A'_1 \odot x: (\overline{\tau})^{p_0}$. By Lemma A.3 (5) and associativity, we have $A'_1 \otimes \overline{y}: \overline{\tau} \simeq A_2$ and $((A'_1 \otimes \overline{y}: \overline{\tau}) \odot A_2)/\overline{y} \odot x: (\overline{\tau})^{p_0} = A$, so that $\vdash \overline{x}(\overline{y})(P|Q) \triangleright A$. The inverse and other cases are similarly dealt with.

(2) It is proved by the same reasoning as (3) below (the proof is simpler than (3)).

(3) We prove the monadic case. The polyadic case is just the same. Suppose

$$\vdash !x(y:\tau).P \mid \overline{x}(y:\tau')Q \triangleright A$$

Then, we have the derivations such that

$$\vdash !x(y:\tau).P \triangleright A_1$$
 and $\vdash \overline{x}(y:\tau')Q \triangleright A_2$

with $A_1 \stackrel{\text{def}}{=} (x: (\tau)! \to ?A_1')$ and $A_1 \odot A_2 = A$. Then the above input and output processes are derived by (ln!) and (Out) from

$$\vdash P \triangleright y: \tau \otimes A'_1 \text{ and } \vdash Q \triangleright (y: \tau' \to A'_2) \otimes A''_2 \text{ with } (A'_2 \otimes A''_2) \odot x: (\tau')^? = A_2$$

First, by $A_1 \simeq A_2$, we have $\tau = \overline{\tau'}$. Also by (iv), we have $A'_1 \simeq (A'_2 \otimes A''_2)$ and $A'_1 \odot (A'_2 \otimes A''_2) = A_1/x \odot A_2/x$.

Suppose $md(\tau) = \downarrow$. Then we have

$$\vdash P \mid Q \triangleright y : \downarrow \otimes (A_1/x \odot A_2/x)$$

Hence by (Res), we have:

$$\vdash (\vee y:\uparrow)(P \mid Q) \triangleright (A_1/x \odot A_2/x)$$

Next we apply (Weak) to A_2/x in order to obtain A_2 . Then we have:

$$\vdash (\mathbf{v} y: \uparrow) (P \mid Q) \triangleright A_1 / x \odot A_2$$

By (4) in Lemma A.3, $A_1 \odot A_1/x = A_1$, together with associativity, we finally have

$$\vdash !x(y:\tau).P \mid (\forall y:\uparrow)(P \mid Q) \triangleright A$$

The case $md(\tau) = ?$ is just the same by replacing \uparrow by $\overline{\tau}$ above.

By the above lemma, we conclude with Proposition 2.2(1).

A.3. PROOF OF STRONGLY CONFLUENCE

We prove Proposition 2.2 (ii). The only case for a critical pair is $\langle !a(\vec{x}).P, \overline{a}(\vec{x})Q_1 \rangle$ and $\langle !a(\vec{x}).P, \overline{a}(\vec{x})Q_2 \rangle$. If *R* contains this critical pair, then we can write down

 $R \equiv (\mathbf{v}\vec{c})(!a(\vec{x}).P \,|\, \overline{a}(\vec{x})Q_1 \,|\, \overline{a}(\vec{x})Q_2 \,|\, Q')$

Suppose

$$R \longrightarrow (\mathbf{v}\vec{c}) (!a(\vec{x}).P | (\mathbf{v}\vec{x})(P | Q_1) | \overline{a}(\vec{x})Q_2 | Q') \stackrel{\text{def}}{=} R_1 \quad \text{and} \\ R \longrightarrow (\mathbf{v}\vec{c}) (!a(\vec{x}).P | \overline{a}(\vec{x})Q_1 | (\mathbf{v}\vec{x})(P | Q_2) | Q') \stackrel{\text{def}}{=} R_2.$$

Then by contracting $|a(\vec{x}).P$ and $\overline{a}(\vec{x})Q_2$ in R_1 , we have

$$R_1 \longrightarrow (\mathbf{v}\vec{c})(!a(\vec{x}).P \mid (\mathbf{v}\vec{x})(P \mid Q_1) \mid (\mathbf{v}\vec{x})(P \mid Q_2) \mid Q') \stackrel{\text{def}}{=} P'$$

Now by contracting $|a(\vec{x}).P$ and $\overline{a}(\vec{x})Q_1$ in R_2 , we have $R_2 \longrightarrow P'$.

APPENDIX B

PROOFS FOR SECTION 3

B.1. PROOF OF PROPOSITION 3.1

(1) is essentially identical with the proof of \rightarrow , using Lemma A.4. For (2), first we start from the following lemma about garbage collection and linear reduction. The proof is mechanical. We assume all terms are typable.

Lemma B.1.

(1) (postponement of \mapsto_{g}) If $P \mapsto_{g} Q \mapsto_{l} R$, then for some $S, P \mapsto_{l} S \mapsto_{g} R$. Similarly if $P \mapsto_{g} Q \mapsto_{r} R$, then for some $S, P \mapsto_{r} S \mapsto_{g}^{+} R$.

(2) (strong confluence of \mapsto_g) If $P \mapsto_g Q_i$ (i = 1, 2), then $Q_1 \equiv Q_2$ or there exists R such that $Q_i \mapsto_g R$.

(3) (strong normalisation of \mapsto_g) For all P, there exists Q such that $P \mapsto_g^* Q$ and $Q \not\to_g$.

(4) (strong confluence of \mapsto_1) If $P \mapsto_1 Q_i$ (i = 1, 2), then $Q_1 \equiv Q_2$ or there exists R such that $Q_i \mapsto_1 R$.

(5) (strong normalisation of \mapsto_1) For all P, there exists Q such that $P \mapsto_1^* Q$ and $Q \not\mapsto_1$.

Let us define $\mapsto_0 \stackrel{\text{def}}{=} (\mapsto_r \cup \mapsto_l)$. By postponement of \mapsto_g , if $P \mapsto^* R$, then there exists *S* such that $P \mapsto_0^* S \mapsto_g^* R$. Since \mapsto_g always canonically terminates, we only have to show the CR of \mapsto_0 (cf. [39]). For this, it is sufficient to show the following *strip* lemma.

LEMMA B.2. (strip) If $P \mapsto_0 P_1$ and $P \mapsto_0^* P_2$, then there exists P_3 such that $P_1 \mapsto_0^* P_3$ and $P_2 \mapsto_0^* P_3$.

Proof. The only interesting case is that an uncontructed message appears under a replicated input. The proof we use here is similar to the one used in Chapter 11 Section 1 of [7] based on the labelled reduction [45]. Our case is simpler since we only contract one message at each step and there is no overlap of occurrences of two messages which are duplicated from the same replication (cf. [45] and Section 11.2 in [7]). Let P_1 be the result of replacing the redex $\overline{a}(\vec{y})Q_1$ in P by its reduct $(v\vec{y})(R_1 | Q_1)$. If we keep track of what happens with $\overline{a}(\vec{y})Q_1$ during the reduction $P \mapsto_0^* P_2$, then we can find P_3 . To be able to trace $\overline{a}(\vec{y})Q_1$, we define a new set of terms where uncontructed messages can appear underlined [45]. Consequently, if we underline a in $\overline{a}(\vec{y})Q_1$, we only need to reduce all occurrences of the underlined a in P_2 to obtain P_3 . The rest is the just same as in [7].

By Lemma B.2, we obtained CR-property of \mapsto (Proposition 3.1 (2)). To prove that the first statement in Proposition 3.1 (3), we note that $P \mapsto_g P'$ and $SN_e(P')$ does not normally imply $SN_e(P)$ in untyped setting (e.g. $Q \uparrow_e$ but $(vx)!x(\vec{y}).Q \mapsto_g 0$). Hence we shall prove this statement using postponement of \mapsto_g , Lemma B.1 (1).

Lemma B.3.

- (1) If $P \mapsto_0 P'$ and $SN_e(P')$, then $SN_e(P)$.
- (2) Suppose $P \not\to_0$. Then $P \mapsto_{\mathsf{g}} P'$ and $\mathsf{SN}_e(P')$ implies $\mathsf{SN}_e(P)$.
- (3) If $P \mapsto P'$ and $SN_e(P')$, then $SN_e(P)$.

Proof. For (1), we can easily check $P \mapsto_0 P_i$ (i = 1, 2) with $P_1 \equiv P_2$ implies that there exists *R* such that $P_i \mapsto_0^+ R$. Then the rest is standard with Lemma B.2, cf. [1, 7, 36, 39]. (2) is by strong normalisation and church-rosser of \mapsto_g . For (3), by (1) in this lemma, we only have to prove $P \mapsto_g P'$ and $SN_e(P')$ implies $SN_e(P)$. Then by Lemma B.1 (1) there exists at least one pass such that $P' \mapsto_0^* P_1 \mapsto_g^* R \nleftrightarrow$ with $P_1 \not\mapsto_0$. Since $SN_e(R)$, we have $SN_e(P_1)$ by (2). Now by applying Lemma B.1 (1) again, we have some P'_1 such that $P \mapsto_0^* P'_1 \mapsto_g^* R \not\mapsto$ with $P'_1 \not\mapsto_0$. We again have $SN_e(P'_1)$ by (2), from which we can obtain $SN_e(P)$ by (1), as required. ■

The rest of Proposition 3.1 (3) is straightforward by this and CR property of \mapsto .

APPENDIX C

PROOFS FOR SECTION 4

C.1. PROOF OF PROPOSITION 4.5

Let $\mathbf{R} \stackrel{\text{def}}{=} \{ \langle P, Q \rangle \mid \mathfrak{I}_e \vdash P = Q \}$. The statement says $\mathbf{R} \subset \approx$. It is enough to show this inclusion under Convention 3.1 since \approx is already closed under \equiv . By Proposition 4.3 (3), it suffices to show $\mathbf{R} \cup \equiv_{\alpha}$ is a bisimulation with respect to prime syntactic transition. We first consider the pair from (E1), $C[\overline{x}(\overline{y})P]|x(\overline{y}).Q$ and $C[(v\overline{y})(P|Q)]$. Let $R = C[\overline{x}(\overline{y})P]|x(\overline{y}).Q$

and set $\vdash R \triangleright A$. If $\vdash R \xrightarrow{l} R'$, we have the following cases.

(1) $C[\overline{x}(\vec{y})P] x(\vec{y}).Q \xrightarrow{l} C'[\overline{x}(\vec{y})P] x(\vec{y}).Q$	(2) $C[\overline{x}(\vec{y})P] x(\vec{y}).Q \xrightarrow{\tau} (\nu \vec{y})(C[P] Q)$
(3) $C[\overline{x}(\vec{y})P] x(\vec{y}).Q \xrightarrow{l} C[\overline{x}(\vec{y})P'] x(\vec{y}).Q$	(4) $C[\overline{x}(\vec{y})P] x(\vec{y}).Q \xrightarrow{\tau} C'[P] x(\vec{y}).Q$
(5) $C[\overline{x}(\vec{y})P] x(\vec{y}).Q \xrightarrow{x(\vec{y})} C[\overline{x}(\vec{y})P] Q$	(6) $C[\overline{x}(\vec{y})P] x(\vec{y}).Q \xrightarrow{\overline{x}(\vec{y})} C[P] x(\vec{y}).Q.$

We shall now show that only the processes in (1), (2) and (3) are typable. To this end we show by induction on the derivation of $\vdash R \triangleright A$ that $\uparrow x \in A$. This implies that C[] cannot contain an input at *x*. Hence (4) is not typable. Similarly, no typable observer could contain an output or an input at *x*, making in (5) and (6) untypable.

The transition (1) is matched by a transition $C[(v\vec{y})(P|Q)] \xrightarrow{l} C'[(v\vec{y})(P|Q)]$ while the empty transition sequence $C[(v\vec{y})(P|Q)]$ matches (2) because $C[(v\vec{y})(P|Q)] \equiv (v\vec{y})(C[P]|Q)$, as can be shown by induction on the derivation of (2). It is easy to see that $C[(v\vec{y})(P|Q)] \xrightarrow{l} C[(v\vec{y})(P'|Q)]$ is an admissible match for (4).

Now assume that $R = C[(v\vec{y})(P|Q)] \xrightarrow{l} R', \vdash R \triangleright A$ and $\vdash R \xrightarrow{l} R'$. We have the following causes of the transition.

(1)
$$C[(v\vec{y})(P|Q)] \xrightarrow{l} C'[(v\vec{y})(P|Q)]$$
 (2) $C[(v\vec{y})(P|Q)] \xrightarrow{\tau} C'[(v\vec{y})(v\vec{z})(P'|Q')]$
(3) $C[(v\vec{y})(P|Q)] \xrightarrow{l} C'[(v\vec{y})(P'|Q)]$ (4) $C[(v\vec{y})(P|Q)] \xrightarrow{l} C'[(v\vec{y})(P|Q')]$

(1) is matched by $C[\overline{x}(\vec{y})P]|x(\vec{y}).Q \xrightarrow{l} C'[\overline{x}(\vec{y})P]|x(\vec{y}).Q$. For (2), we first show, by induction on the transition, that C[] must be a reduction context. If the context C[] in the definition of extended reduction (Definition 3.1) is restricted to a reduction context, then the resulting relation coincides with \longrightarrow , hence also with $\xrightarrow{\tau}$ by Proposition 4.2. Thus we obtain $C[\overline{x}(\vec{y})P]|x(\vec{y}).Q \xrightarrow{\tau} C[(v\vec{y})(P|Q)] \xrightarrow{l} C'[(v\vec{y})(v\vec{z})(P'|Q')]$ as matching transition sequence. The remaining cases (3) and (4) are dealt with in the same way.

Similarly for the pair from (E2), $C[\overline{x}(\overline{y})P]|!x(\overline{y}).Q$ and $C[(v\overline{y})(P|Q)]|!x(\overline{y}).Q$. Finally we can immediately reason about the pair from (E3), $(vx)!x(\overline{y}).P$ and **0**, since no transition is possible in either process.

C.2. PROOF OF LEMMA 4.1

For (1), if a \triangleright -normal form contains hiding and/or redundant $\mathbf{0}$, \equiv' cannot equate it with the result of stripping them off; while if it doesn't, since \triangleright only strips off (rather than increases) them, applying \triangleright is the same thing as applying \equiv' . (2) is immediate by reaching an ENF by Theorem 3.2 and then by stripping redundant hiding and $\mathbf{0}$ by \triangleright (which is inside \equiv). For (3), by definition the processes generated by the rules in Proposition 3.3 do not contain hiding and redundant $\mathbf{0}$. For the converse we argue by structural induction combined with these two conditions to show \triangleright -normal forms can be generated by the three rules in Proposition 3.3. (4) is immediate from (3). For (5), we show this for $P \in NF_e$ which is enough. Suppose $P \in NF_e$ and $P \stackrel{\tau}{\longrightarrow} P'$. We can easily check $P \stackrel{\tau}{\longrightarrow} P'$ implies $P \longrightarrow P'$, that is $P \mapsto P'$, which contradicts $P' \in NF_e$.

APPENDIX D

PROOFS FOR SECTION 5

D.1. PROOF OF PROPOSITION 5.2 (2)

The "only if" direction is immediate from the definition. For the "if" direction, let $C[\cdot]$ be a context with its hole typed A and the result typed $x : \mathbb{B}$ with x fresh (if $x \in \operatorname{fn}(A)$ we can always use a copy-cat to mediate x to a fresh name). Assume the latter condition and $C[P_1] \Downarrow_x^i$. If the hole of $C[\cdot]$ is not under an input prefix, then we already have $C[\cdot] \stackrel{\text{def}}{=} (\operatorname{vfn}(A))(R|[\cdot])$. Suppose the hole is under an input prefix. If $C[P_1] \Downarrow_x^i$ by $C[P_1] \to \overline{x} \operatorname{in}_i | C'[P_1 \sigma]$ keeping P_1 under the input prefix along the way (possibly with some substitution σ) then we have $C[P_2] \to \overline{x} \operatorname{in}_i | C'[P_2]$, i.e. $C[P_2] \Downarrow_x^i$. If not, then suppose $C[P_1] \to C'[P_1\sigma]$ where $C'[P_1\sigma]$ is the first configuration in which the input prefix is taken off. Using copycats, we can represent σ by parallel composition and hiding, so that the former condition gives us $C[P_2] \Downarrow_x^i$, as required.

D.2. PROOF OF PROPOSITION 5.4

Both are mechanical by induction on τ . Below we show the proof for (2), taking the unary replicated case. Let $\tau = (\vec{\rho})!$ so that $[y \to x]^{\tau} \stackrel{\text{def}}{=} ! y(\vec{z}).\overline{x}(\vec{w})\Pi[w_i \to z_i]^{\overline{p_i}}$. Let $P \equiv C[\overline{y}(\vec{z})R_1]..[\overline{y}(\vec{z})R_n]$ where $\overline{y}(\vec{z})R_j$ exhausts all prime outputs in P (these contexts can be nested). Then we have:

$$\begin{aligned} (\mathbf{v}y)(P|[y \to x]^{\mathsf{\tau}}) & \mapsto^{n+1} & C[(\mathbf{v}\vec{z})(R_1|\overline{x}(\vec{w})\Pi[w_i \to z_i]^{\overline{p_i}})]..[(\mathbf{v}\vec{z})(R_n|\overline{x}(\vec{w})\Pi[w_i \to z_i]^{\overline{p_i}})] \\ & \equiv & C[\overline{x}(\vec{w})(\mathbf{v}\vec{z})(R_1|\Pi[w_i \to z_i]^{\overline{p_i}})]..[\overline{x}(\vec{w})(\mathbf{v}\vec{z})(R_n|\Pi[w_i \to z_i]^{\overline{p_i}})] \\ & \mapsto^* & C[\overline{x}(\vec{w})R_1\{\vec{z}/\vec{w}\}]...[\overline{x}(\vec{w})R_n\{\vec{z}/\vec{w}\}] \\ & \equiv_{\alpha} & C[\overline{x}(\vec{z})R_1]...[\overline{x}(\vec{z})R_n] \end{aligned}$$

where: (1) the first extended reduction involves *n* replications and 1 garbage collection; and (2) the second extended reduction in by induction hypothesis. This also gives the base case, where, with $\tau = ()^{!}$, we can dispense with the second steps forward. The final \equiv_{α} is possible because \vec{z} are fresh w.r.t. R_i . Other cases are the same.

D.3. PROOF OF PROPOSITION 5.8

Let $T^{\circ} = (\vec{\tau})^{!}$ and $T_{1,2}$ arbitrary below. We first show:

(1) $\vdash \mathsf{Msg}\langle m, \vec{z} \rangle^T \triangleright m: \overline{T^{\circ}} \otimes \vec{z}: \vec{\tau}.$

(2)
$$\vdash \operatorname{Arg}(m, N, \vec{z})^{T' \Rightarrow T} \triangleright m: \overline{(T' \Rightarrow T)^{\circ}} \otimes \vec{z}: \vec{\tau} \otimes E^{\circ} \text{ if } \vdash [[N:T']]_{u} \triangleright u: T'^{\circ} \to E^{\circ}.$$

(3)
$$\vdash \operatorname{Proj}_i \langle m, \vec{z} \rangle^{T_i} \triangleright m : \overline{(T_1 \times T_2)^\circ} \otimes \vec{z} : \vec{\tau}$$

(4) $\vdash \operatorname{Sum} \langle m, \vec{z}, \{(x_i)M_i\} \rangle^T \triangleright m: \overline{(T_1 + T_2)^\circ} \otimes E^\circ \text{ if } \vdash \llbracket M_i: T'_i \rrbracket_u \triangleright u: T'_i \circ \to E^\circ \ (i = 1, 2)$ for some $T'_{1,2}$.

For proofs, (1) is immediate from Proposition 5.4 (1). The remaining statements are direct from the definition. For example, let $\vdash [[N : T']]_u \triangleright u : T'^\circ \otimes E^\circ$. For simplicity, assume $T^\circ = (\tau)^!$ and, accordingly, $\vec{z} = z$. By (1) we have, noting that $\mathsf{md}(\tau) = \uparrow$ in this case, $\vdash c(w).\mathsf{Msg}\langle w, z \rangle^{T^\circ} \triangleright c : (\overline{T^\circ})^{\downarrow} \to z : \tau$. Together with the given assumption, we obtain:

$$\vdash \overline{m}(nc)(\llbracket N:T' \rrbracket_n \mid c(w).\mathsf{Msg}\langle w, z \rangle^{T^\circ}) \triangleright m: (T'^\circ(\overline{T^\circ})^{\downarrow})^? \otimes z: \mathfrak{r} \otimes E^\circ$$

as required.

Remark. In the above, *m* in Arg $\langle m, N, \vec{z} \rangle^{T' \Rightarrow T}$, $\operatorname{Proj}_i \langle m, \vec{z} \rangle^T$ and $\operatorname{Sum} \langle m, \vec{z}, \{(x_i)M_i\} \rangle^T$ is typed by the dual of the encoded function, product and sum type, respectively, indicating the role of these expressions as the desctructors of the corresponding constructors.

Now we prove Proposition 5.8 by rule induction of the map $\llbracket M : T \rrbracket_{u}$.

Case $[x:T]]_u$. Direct from Proposition 5.4 (1).

Case $[() : unit]_u$. Immediate from the definition.

Case $[\lambda x: T' M: T' \Rightarrow T]_u$. Immediate from the induction hypothesis.

Case $[[MN:T]]_{u}$. By induction hypothesis on [[N:T']] we can apply (2) above to $\operatorname{Arg}\langle m, N, \vec{z} \rangle^{T' \Rightarrow T}$). By induction hypothesis on $[[E \vdash M:T' \Rightarrow T]]_m$ we have $\vdash [[M:T' \Rightarrow T]]_m \triangleright m: (T' \Rightarrow T)^\circ \rightarrow E^\circ$. Thus, with $[[T]] = (\vec{\tau})!$:

$$\vdash (\mathsf{v} mn)(\llbracket M:T' \Rightarrow T \rrbracket_m | \operatorname{Arg} \langle m, N, \vec{z} \rangle^{T' \Rightarrow T}) \triangleright \vec{z}: \vec{\tau} \otimes E^\circ$$

from which we obtain $\vdash !u(\vec{z}).(\vee mn)(\llbracket M:T'\Rightarrow T \rrbracket)_m |\operatorname{Arg}\langle m, N, \vec{z}\rangle^{T'\Rightarrow T}) \triangleright u:T^{\circ} \to E^{\circ}.$

Case $[\![\langle M_1, M_2 \rangle : T_1 \times T_2]\!]_u$. Direct from the induction hypothesis.

Case $[[\pi_i(M) : T]]_{u}$. By (3) above and induction hypothesis, arguing as in the case of $[[MN : T]]_u$ in the last step.

Case $\llbracket \operatorname{inl}(M) : T + T' \rrbracket_u$. Direct from the induction hypothesis.

Case $[[case L of {in_i(x_i : T_i).M_i}_{i \in \{1,2\}} : T]]_u$. By Lemma (2) above and by induction hypotheses, arguing as in the case of $[[MN : T]]_u$ in the last step.

D.4. PROOF OF PROPOSITION 5.9

The proof uses the following variation of the replication theorems [49, 53].

LEMMA D.1.
$$(\mathbf{v}x)(C[\llbracket x:T]\rrbracket_u] | \llbracket N:T\rrbracket_x) \mapsto^* (\mathbf{v}x)(C[\llbracket N]\rrbracket_u] | \llbracket N\rrbracket_x)$$
 assuming typability.
Proof. Let $T^\circ = (\vec{\tau})!$ and $\llbracket N:T\rrbracket_x \stackrel{\text{def}}{=} ! x(\vec{w}) . P$. We have:

$$\begin{aligned} (\mathbf{v}x) \left(C[\llbracket x:T \rrbracket_{u}] | \llbracket N:T \rrbracket_{x} \right) & \stackrel{\text{def}}{=} & (\mathbf{v}x) \left(C[!u(\vec{z}).\vec{x}(\vec{w})\Pi[w_{i} \rightarrow z_{i}]^{\tau_{i}}] | !x(\vec{w}).P \right) \\ & \mapsto & (\mathbf{v}x) \left(C[!u(\vec{z}).(\mathbf{v}\vec{w})(P|\Pi[w_{i} \rightarrow z_{i}]^{\tau_{i}})] | !x(\vec{w}).P \right) \\ & \mapsto^{*} & (\mathbf{v}x) \left(C[!u(\vec{w}).P] | \llbracket N:T \rrbracket_{x} \right) \end{aligned}$$

The last step is by Proposition 5.4 (2). \blacksquare

We can now prove Proposition 5.9. For (β), assuming $[M]_u \stackrel{\text{def}}{=} !u(\vec{z}).P$, we calculate:

$$\begin{split} \llbracket (\lambda x.M)N \rrbracket_{u} &\stackrel{\text{def}}{=} !u(\vec{z}).(\vee m)(!m(xy).\overline{y}(m')\llbracket M \rrbracket_{m'} |\overline{m}(xy)(\llbracket N \rrbracket_{x} | y(m').\operatorname{\mathsf{Msg}}\langle m' \vec{z} \rangle)) \\ & \mapsto^{2} !u(\vec{z}).(\vee xm')(\llbracket M \rrbracket_{m'} |\llbracket N \rrbracket_{x} |\operatorname{\mathsf{Msg}}\langle m' \vec{z} \rangle) \\ & \mapsto^{*} !u(\vec{z}).(\vee x)(P |\llbracket N \rrbracket_{x}) \qquad (\operatorname{Prop.} 5.4 (2)) \\ & \mapsto^{*} !u(\vec{z}).P\{\llbracket N \rrbracket_{v_{1}}..\llbracket N \rrbracket_{v_{1}}..\llbracket x \rrbracket_{v_{n}}\} \qquad (\operatorname{Lemma D.1}) \\ & \stackrel{\text{def}}{=} \llbracket M\{N/x\} \rrbracket_{u}, \end{split}$$

as required. For (proj₁), let $[[M_1 : T_1]]_u \stackrel{\text{def}}{=} !u(\vec{z}).P$ below.

$$\begin{split} \llbracket \pi_1 \langle M_1, M_2 \rangle &: T_1 \rrbracket_u \\ \stackrel{\text{def}}{=} & ! u(\vec{z}) . (\vee m) (!m(c) . \overline{c}(m_1 m_2) \Pi \llbracket M : T_i \rrbracket]_{m_i} | \overline{m}(c) c(m_1 m_2) . \mathsf{Msg} \langle m_1, \vec{z} \rangle) \\ \mapsto^3 & ! u(\vec{z}) . (\vee m_1 m_2) (\Pi \llbracket M : T_i \rrbracket]_{m_i} | \mathsf{Msg} \langle m_1, \vec{z} \rangle) \\ \mapsto^* & ! u(\vec{z}) . P \quad (\stackrel{\text{def}}{=} \llbracket M_1 : T_1 \rrbracket_u). \end{split}$$
(Prop. 5.4 (2))

For (case_i), we again let $\llbracket M_1 : T_1 \rrbracket_u \stackrel{\text{def}}{=} ! u(\vec{z}) . P$.

$$\begin{split} & [[\operatorname{case} \operatorname{in}_{1}(N) \text{ of } \{ \operatorname{in}_{i}(x_{i}:T_{i}).M_{i} \}:T]]_{u} \\ & \stackrel{\mathrm{def}}{=} \ !u(\vec{z}).(\vee l)(!l(c).\overline{c}\operatorname{in}_{1}(x_{1})[\![N:T_{1}]\!]_{x_{1}}|\overline{m}(c)c[\&_{i}(x_{i}).(\vee m)([\![M_{i}:T]]\!]_{m}|\mathsf{Msg}\langle m,\vec{z}\rangle)]) \\ & \mapsto^{3} \ !u(\vec{z}).(\vee x_{1})((\vee m)([\![M_{i}:T]]\!]_{m}|\mathsf{Msg}\langle m,\vec{z}\rangle)|[\![N:T_{1}]\!]_{x_{1}}) \\ & \mapsto^{*} \ !u(\vec{z}).(\vee x_{1})(P|[\![N:T_{1}]\!]_{x_{1}}) \\ & \mapsto^{*} \ [M_{1}\{N/x_{1}\}:T]]_{u}, \end{split}$$
(Prop. 5.4 (2))

hence done.

D.5. PROOF OF LEMMA 5.3

We use two observation which are often useful.

LEMMA D.1. Let R be a replicated process with subject x and assume $\vdash C[P]|R|S \triangleright A$ for some A such that x does not occur in $C[\cdot]$. Then, under the standard bound name convention, $(vx)(C[P]|R|S) \cong C[(vx)(P|R)]|S$.

Proof. Immediate by performing extended reduction at occurrences of *x* in *P* on both sides, and noting $\mapsto \subset \approx \subset \cong$.

LEMMA D.2. Let $\vdash Q_{1,2} \triangleright A$ and let $\{\vec{y}\} \subset \operatorname{fn}(A)$ such that $\operatorname{md}(A(y_i)) = ?$ for each $y_i \in \{\vec{y}\}$. Suppose for each $\vdash R \triangleright \vec{y}: \overline{\vec{\tau}}$ we have $(\mathbf{v}\vec{y})(Q_{1,2}|R) \Downarrow_e Q'$ for some Q'. Then $Q_1 \cong Q_2$.

In the statement above, observe we first choose an arbitrary ?-part of the given action type.

Proof. Below $Q_{1,2}$ and A are as given above, and we let $B \stackrel{\text{def}}{=} \vec{y} : \vec{\tau}$ and $C \stackrel{\text{def}}{=} A/\vec{y}$.

The first equivalence is by Proposition 5.2 (2). The second equivalence is by taking each compensating replicated term to be a prime whose only free name is its subject (this does not lose generality since, by extended reduction with other replicated processes, all ?-moded free names can be compensated and eliminated). For the third equivalence, the "only if" direction is by contradiction, while the "if" direction is by noting, at type $x: \mathbb{B}$, the correspondence in convergence and \cong coincide. The last two (reverses) implications are, respectively, by $\approx \subset \cong$ (cf. Proposition 5.3) and by $\leftrightarrow \subset \approx$ (cf. Theorem 4.1).

reductions and Lemma D.1,

$$\begin{aligned} (\texttt{let } x = zF \texttt{ in } F')_u^{\star} \\ \stackrel{\text{def}}{=} & [\![F'^\circ \{ zF^\circ / x \}]\!]_u \\ \approx & (\forall x) (F'_u^{\star} | (zF)_x^{\star}) \\ \cong & (\forall x) (!u(\vec{v}).P \mid [\![zF]\!]_x) \\ \cong & (\forall xf) (!u(\vec{v}).P \mid !x(\vec{w}).\operatorname{Arg}\langle zf\vec{w} \rangle \mid [\![F]\!]_f) \end{aligned}$$

Let the resulting term be S_1 . We compare S_1 with the direct translation $S_2 \stackrel{\text{def}}{=} !u(\vec{v}).\overline{z}(fc)([[F']]_f|c(x).P)$. For this purpose we compose S_i with $Q \stackrel{\text{def}}{=} !z(fc)\overline{c}(x)!x(\vec{w})Q'$. Note that we can assume any compensating process at *z* has this form without loss of generality (by η -expansion). Immediately $S_1|Q \mapsto^+ (vxf)(!u(\vec{v}).P|!x(\vec{w}).Q'|[[F]]_f)|Q$, while, for the right-hand side, we have:

$$S_2|Q \mapsto^+ !u(\vec{v}).(vfx)(\llbracket F' \rrbracket_f | !x(\vec{w})Q'|P) | Q$$

$$\cong (vfx)(!u(\vec{v}).P | !x(\vec{w}).Q' | \llbracket F' \rrbracket_f).$$

We can now use Lemma D.2.

D.6. PROOF OF LEMMA 5.4

For (1), write Q_1 (resp. Q_2) for the process on the l.h.s. (resp. r.h.s.) of the equation for brevity. By the conditions on typability and by ENFs, we should have $\vdash_0 Q_{1,2} \triangleright_z : \tau^{\uparrow} \otimes x : \rho^! \otimes ?A$ for some *A*. We prove the following claim, which easily entails (cf. Lemma D.2 in Appendix D.5) the required equality.

Claim. Assume, for each $\vdash_{I} U \triangleright \overline{A} \otimes x : \overline{\rho}$, we have $(\nu \operatorname{fn}(A)x)(Q_i|U) \Downarrow_e Q'$ (i = 1, 2) for some Q'. Then $Q_1 \cong Q_2$.

To prove the claim, let $A = \emptyset$ for simplicity, which does not lose generality since processes compensating A are simply absorbed into $Q_{1,2}$ by extended reduction, resulting processes in the same shape. For the same reason we safely assume the occurrence of x in each term is unique. Thus we compose $\vdash_{I} !x(\vec{r}c).S \triangleright x:\overline{\rho}$ to both sides and demonstrate the claim. By Proposition 3.3 and by noting fn $(R|S) \subset \{\vec{r}c\}$, we have $(\nu \vec{r})(R|S) \Downarrow_{e} \overline{c} in_{i}(\vec{w}_{i})T$ for some T. Assume further $(\nu \vec{w}_{i})(T|P_{i}) \Downarrow_{e} P'_{i}$. For Q_{1} we obtain:

$$\begin{aligned} (\mathbf{v}x)(Q_1 \mid !x(\vec{r}c).S) &\stackrel{\text{def}}{=} & (\mathbf{v}x)(\overline{x}(\vec{r}c)(R \mid c[\&_i(\vec{w}_i).\overline{z}(e)!e(\vec{y}).P_i]) \mid !x(\vec{r}c).S) \\ &\mapsto^+ & (\mathbf{v}\vec{r}c)(R \mid S \mid c[\&_i(\vec{w}_i).\overline{z}(e)!e(\vec{y}).P_i]) \\ &\mapsto^* & (\mathbf{v}c)(\overline{c}\mathrm{in}_i(\vec{w}_i)T \mid c[\&_i(\vec{w}_i).\overline{z}(e)!e(\vec{y}).P_i]) \\ &\mapsto & (\mathbf{v}\vec{w}_i)(T \mid \overline{z}(e)!e(\vec{y}).P_i) \\ &\mapsto^* & \overline{z}(e)!e(\vec{y}).P_i' \end{aligned}$$

For Q_2 we have:

$$\begin{aligned} (\mathbf{v}x)(Q_2 \mid !x(\vec{r}c).S) &\stackrel{\text{def}}{=} & (\mathbf{v}x)(\overline{z}(e)!e(\vec{y}).\overline{x}(\vec{r}c)(R \mid c[\&_i(\vec{w}_i).P_i]) \mid !x(\vec{r}c).S) \\ & \mapsto^+ & \overline{z}(e)!e(\vec{y}).(\mathbf{v}\vec{r}c)(R \mid S \mid c[\&_i(\vec{w}_i).P_i]) \\ & \mapsto^* & \overline{z}(e)!e(\vec{y}).(\mathbf{v}\vec{w}_i)(T \mid P_i) \\ & \mapsto^* & \overline{z}(e)!e(\vec{y}).P'_i \end{aligned}$$

hence as required.

For (2), since a linear output cannot occur freely under a replicated input, given a sequential $|u(\vec{x}z).P$ with z of type $(\tau)^{\uparrow}$, we can write P as $C[\overline{z}(c)P_1]..[\overline{z}(c)P_n]$ where either $P \equiv \overline{z}(c)P'$ or each hole is under a linear unary/branching prefix. Treating w.l.o.g. unary prefix as a special case of branching prefix, we prove (2) by induction on the depth of z in P, where the *depth of z in P* is the maximum number of prefixes from the subject of P to an occurrence of z in P. If the depth is zero, there is nothing to prove. Let the depth be n + 1 and let $P \equiv C[\overline{x}(\vec{r}e)(R|e[\&_i.\overline{z}(c)!c(\vec{y}).P_i])]$ where the mentioned occurrence of x is the deepest one (by which they can only occur immediately after e). By (1) above, $P \cong C[\overline{z}(c)!c(\vec{y}).\overline{x}(\vec{r}e)(R|e[\&_i.P_i])]$. By induction hypothesis we are done.

(3) is because the transformation in the proof of (2) can be carried out incrementally. \blacksquare