## Effective partial solvers for parity games<sup>1</sup>

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#### Abstract

Partial methods play an important role in formal methods and beyond. Recently such methods were developed for parity games, where polynomial-time partial solvers decide the winners of a *subset* of nodes. We investigate here how effective polynomial-time partial solvers can be in principle by studying polynomial-time interactions of partial solvers. Concretely, we propose simple, generic composition patterns for partial solvers that preserve polynomial-time computability. We show that an implementation of this semantic framework manually discovers new partial solvers – including those that merge node sets that have the same but unknown winner – by studying games that composed partial solvers can neither solve nor simplify. We experimentally validate that this data-driven approach to refinement leads to polynomial-time partial solvers that can solve all standard benchmarks of structured games. For one of these polynomial-time partial solvers, we were unable to find even a sole random game that it won't solve completely, although we generated a few billion random games of varying configurations to that end. However, the work presented here does not yet offer any deeper characterisations of which games are completely solved by such partial solvers.

## 1 Introduction

Parity games are two-player games on directed graphs that are determined [18, 3, 21]. Parity games have several applications, including as back-ends in formal methods: Let us mention here the controller synthesis of reactive systems as well as satisfiability checking of the modal mu-calculus and the temporal logic CTL\*, where parity games serve as a technical aid in determinising non-deterministic Büchi automata (see e.g. the discussion in [6]). There is therefore a clear benefit in having effective means of solving parity games.

The exact computational complexity for finite parity games has been on open problem for over 20 years: deciding which player wins a node in a parity game is known to be in UP $\cap$ coUP [16] and the fastest known algorithms run in sub-exponential time in the size of games (see e.g. [15, 19]). Some types of parity games have polynomial-time solutions. We may bound the index of games (i.e. the largest color of a game) by a fixed natural number; then, e.g., Zielonka's algorithm based on the whole-set rule [8] becomes polynomial time. Or we may bound a descriptive complexity measure: parity games with bounded DAG-width [1], tree-width [1, 5] or entanglement [2] can be solved in polynomial time.

Algorithms that solve parity games do so using specific mechanisms, for example strategy improvement [20] or progress measures [14]. But it seems not feasible to let such mechanisms interact in iterative computations, even though this might speed up solving. The difficulty is that such mechanisms operate over very different views of games and their complexity; for example, how might one use a strategy-improvement step (which updates one player's strategy) to increase a progress measure (an element in a specific complete lattice)?

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Partial solvers [10, 11] have been proposed as algorithms that can solve parts of a parity game but not necessarily all of such a game. Such algorithms are designed to run in polynomial time, and this is relatively easy to obtain. The harder part is to understand which parity games are solved completely by a given partial solver. Partial solvers are related to known static analyses such as priority propagation (see e.g. [7]), that may decrease colours of nodes. Extant work has shown the feasibility of using partial solvers [10, 11], yet they don't completely solve some benchmarks of structured games and they don't solve many randomly generated games. Moreover, we don't have a good understanding of whether partial solvers could improve their effectiveness through interaction.

But furthering such an understanding seems feasible as all these methods share a common view of the complexity of a finite game – say the number of nodes plus the number of edges plus the sum of all colours of all nodes. This common view allows us to think of static analyses, let us mention color reductions based on abstract Rabin index computations [9], as partial solvers as well and to then *compose* partial solvers to improve their effectiveness. This discussion leads us to consider the following hypothesis, which we split into three parts:

- H1 There are simple, generic, yet effective composition patterns for partial solvers that preserve polynomial-time computability.
- H2 These patterns can be used to manually discover new partial solvers, by studying games that these compositions patterns can neither solve nor simplify.
- H3 The approach of H1-H2 leads to polynomial-time partial solvers that can solve all standard benchmarks of structured games, and that only very rarely do not completely solve a randomly generated game.

The main contribution of this paper is to present compelling evidence for the hypothesis H1-H3. In particular, our work will show that this approach can discover refined views of a game's complexity by discovering novel ways of simplifying games; for example, by merging a set of nodes that a partial solver determines as having the same winner into a sole node – even though the winner of that node is not known at merge time. We believe that the approach we here advocate can discover more such novel simplification mechanisms for solving parity games, that it can shed more light on what types of parity games can be solved in polynomial time, and that it can foster new perspectives on the descriptive complexity of this open problem.

**Outline of paper:** We review background in Section 2, develop our composition framework for partial solvers in Section 3, and show how its use leads to data-driven refinement of partial solvers in Section 4. In Section 5, we report our experimental and validation work for this framework and for our newly discovered partial solvers. Related work is discussed in Section 6, further insights are discussed in Section 7, and Section 8 concludes the paper. An appendix contains proofs and details on experimental data.

# 2 Background

We define key concepts of parity games, review some partial solvers and static analyses for such games, and fix technical notation used in this paper.

**Parity games.** We write  $\mathbb{N}$  for the set  $\{0, 1, \ldots\}$  of natural numbers. A parity game G is a tuple  $(V, V_0, V_1, E, c)$ , where V is a set of nodes partitioned into possibly empty node sets  $V_0$  and  $V_1$ , with an edge relation  $E \subseteq V \times V$  that contains no dead-ends (i.e. for all v in V there is a w in V with (v, w) in E), and a colouring function  $c: V \to \mathbb{N}$ . Throughout, we write p (or sometimes p') for one of 0 or 1 and 1 - p for the other player. Nodes in  $V_0$  are owned by player 0, nodes in  $V_1$  are owned by player 1. We write owner(v) to denote the p for which v is in  $V_p$ . In figures, c(v) is written within nodes v, nodes in  $V_0$  are depicted as circles and nodes in  $V_1$  as squares. For a relation  $\rho \subseteq A \times B$  and  $X \subseteq A$  we write  $X \bullet \rho$  for set  $\{b \in B \mid \exists a \in X : (a, b) \in \rho\}$ , whereas  $\rho \bullet Y$  denotes set  $\{a \in A \mid \exists b \in Y : (a, b) \in \rho\}$  for  $Y \subseteq B$ ; we will abuse this notation for singleton X and Y as in  $v \bullet E$  or  $E \bullet v$  in a parity game. Below we write C(G) for the set of colours in game G, i.e.  $C(G) = \{c(v) \mid v \in V\}$ . For each p in  $\{0, 1\}$ , the preference ordering  $\leq_p$  on C(G) is given by  $c_1 \leq_p c_2$  iff  $(c_1\%2 = p$  and  $c_2\%2 = 1 - p)$  or  $(c_1$  and  $c_2$  have parity p and  $c_1 \leq c_2$  or  $(c_1$  and  $c_2$  have parity 1 - p and  $c_2 \leq c_1$ ).

A play from some node  $v_0$  results in an infinite play  $\pi = v_0 v_1 \dots$  in (V, E) where the player who owns  $v_i$  chooses the successor  $v_{i+1}$  such that  $(v_i, v_{i+1})$  is in E. Let  $\mathsf{Inf}(\pi)$  be the set of colours that occur in  $\pi$  infinitely often:  $\mathsf{Inf}(\pi) = \{k \in \mathbb{N} \mid \forall j \in \mathbb{N} : \exists i \in \mathbb{N} : i > j \text{ and } k = c(v_i)\}$ . Player 0 wins play  $\pi$  iff min  $\mathsf{Inf}(\pi)$  is even; otherwise player 1 wins play r.

A strategy for player p is a total function  $\sigma_p: V^* \cdot V_p \to V$  where the pair  $(v, \sigma_p(w \cdot v))$  is in Efor all v in  $V_p$  and w in  $V^*$ . A play  $\pi$  conforms with  $\sigma_p$  if for every finite prefix  $v_0 \ldots v_i$  of  $\pi$  with  $v_i$  in  $V_p$  we have  $v_{i+1} = \sigma_p(v_0 \ldots v_i)$ . A strategy  $\sigma_p$  is memoryless if for all w, w' in  $V^*$  and v in  $V_p$ we have  $\sigma_p(w \cdot v) = \sigma_p(w' \cdot v)$  and such a  $\sigma_p$  can be seen to have type  $V_p \to V$ .

It is well known that each parity game is determined [18, 3, 21]: (i) node set V is the disjoint union of two, possibly empty, sets  $Win_0[G]$  and  $Win_1[G]$ , the winning regions of players 0 and 1 (respectively) in G; and (ii) there are memoryless strategies  $\sigma_0$  and  $\sigma_1$  such that all plays beginning in  $Win_0[G]$  and conforming with  $\sigma_0$  are won by player 0, and all plays beginning in  $Win_1[G]$  and conforming with  $\sigma_1$  are won by player 1. Solving a parity game means computing such data  $(Win_0[G], Win_1[G], \sigma_0, \sigma_1)$ . By abuse of language, we view  $\emptyset$  also as a parity game with empty node set.

Throughout this paper, we write G for a parity game  $(V, V_0, V_1, E, c)$ , and let X be a non-empty set of nodes of G. We define the rank of parity game G as  $\mathbf{r}(G) = |V| + |E| + \sum_{v \in V} c(v)$ . We write x%2 for x modulo 2 for an integer x, and  $\mathsf{Attr}_p[G, X]$  to denote the attractor of node set X for player p, which computes the alternating reachability of X for that player in the game graph of G (see e.g. Definition 1 in [10]). It is well known that  $\mathsf{Attr}_p[G, X]$  is contained in the winning region  $\mathsf{Win}_p[G]$  whenever  $X \subseteq \mathsf{Win}_p[G]$ . A node set  $X \subseteq V$  is a p-trap in G, if player 1 - p can play such that all plays beginning in X also stay in X in G. Winning regions  $\mathsf{Win}_p[G]$  are (1-p)-traps. The color of a finite path or cycle P in the directed graph (V, E) is defined to be  $\min\{c(v) \mid v \text{ is on } P\}$ . A subset  $C \subseteq V$  of a directed graph is called a (maximal) strongly connected component, denoted by SCC, if for all v, w in C there is a path in (V, E) from v to w; and if there is no strict superset of C in (V, E) with that property.

**Example 1** For parity game G on the right in Figure 2, we have  $\operatorname{Win}_1[G] = \emptyset$  and  $\operatorname{Win}_0[G] = V$ . The memoryless strategy  $\sigma_0$ , already completely determined by  $\sigma_0(v_4) = v_{19}$ , is a winning strategy for player 0 on  $\operatorname{Win}_0[G]$ .

**Partial solvers and static analyses.** We present partial solvers and static analyses for parity games, some of them already in a form suitable for the composition patterns developed in this paper. All these partial solvers and static analyses preserve the winning regions of the (remaining)

game, and can be computed in polynomial time in the size of their input games [10, 12, 9].

Static color compression *scc* is agnostic to the game graph and makes C(G) convex in  $\mathbb{N}$ , e.g.  $C(G) = \{0, 2, 3, 6, 7\}$  becomes  $\{0, 1, 2, 3\}$  where nodes coloured with 2 now have color 0, nodes coloured 3 now have color 1 and so forth.

Priority propagation pp is informed by the game graph. At node v, let p(v) denote min(max  $c(v \in E)$ , max  $c(E \bullet v)$ ) where  $c(Y) = \{c(y) \mid y \in Y\}$ ; if there is a node v with p(v) < c(v), one such node is selected by pp and the color at v is changed to p(v); otherwise pp has no effect on G.

The monotone attractor for a node set X of color d in C(G) [10] is defined as follows: it is the greatest set of nodes  $Y_X$  in G from which player d%2 can force to reach nodes in X whilst only encountering nodes of color  $\geq d$  en route. A node set X is a *fatal* attractor [10] if it is contained in its monotone attractor  $Y_X$ , and then all nodes in X are won by player d%2 in parity game G [10]. We write fa for the static analysis that returns a fatal attractor (say by exploring colours in descending order) if G has one, and returns nothing otherwise.

Another static analysis ari is based on the abstract Rabin index of parity games [9]: for node v with c(v) > 1, let  $c'_v$  be the maximal color of all cycles that go through node v in G; if there is a node v with  $c'_v < c(v)$ , then ari chooses one such node and changes the color at v to  $c'_v$ ; otherwise ari has no effect on G.

Finally, let gfa be a more general form of partial solver fa, based on the partial solver in [12]. Now, X is a set of nodes of color parity p (not necessarily of the same color), and  $Y_X$  is the greatest set of nodes from which player p can ensure that X is reached such that the minimal color encountered en route has parity p [12]. Partial solver gfa returns a set X that is contained in the corresponding  $Y_X$ , if there is such a pair  $(X, Y_X)$ , and returns nothing otherwise.

### **3** Semantics for composition

We now present a semantic framework in which our partial solvers can be expressed and composed with ease. Fundamental to this is the notion of state, as the semantics of a partial solver will be a state transformer. This notion of state is a result of our data-driven discovery of partial solvers, and so it may also be refined in the future for novel types of partial solvers.

- **Definition 1** 1. A state s is a tuple  $(W_0, W_1, \rho, G', G)$  where G = (V, ...) and G' = (V', ...)are parity games,  $\mathsf{r}(G') \leq \mathsf{r}(G)$ ,  $\rho \subseteq V' \times V$ , and  $\mathsf{Win}_p[G] = W_p \cup \mathsf{Win}_p[G'] \bullet \rho$  for p in  $\{0, 1\}$ .
  - 2. Let  $\Sigma$  be the set of all such states. We write  $s.W_p$ ,  $s.\rho$  and so forth to refer to these respective components of such a state s.
  - 3. The rank  $\mathbf{r}(s)$  of a state is defined as  $\mathbf{r}(s.G')$ .
  - 4. Let  $\leq \subseteq \Sigma \times \Sigma$  be given by  $s' \leq s$  iff  $(s = s' \text{ or } \mathbf{r}(s') < \mathbf{r}(s))$ .

State s models an intermediate state of computation within an implicit composition context: the original input game is s.G and parity game s.G' is the continuation game that still needs to be solved; node sets  $s.W_p$  for p in  $\{0,1\}$  model those nodes in s.G for which the winner is already decided as player p; for v in V', node set  $v \bullet \rho$  represents those nodes in V that have the same (not yet known) winner in s.G as v has in s'.G'; and the winning regions  $\text{Win}_p[s.G]$ of s.G are the union of  $s.W_p$  and the image of the winning region  $\text{Win}_p[s.G']$  under relation  $\rho$ . A state models configurations of partial solver computations, where  $(\emptyset, \emptyset, \Delta_{V_G}, G, G)$  is a natural initial configuration with  $\Delta_{V_G} = \{(v, v) \mid v \in V_G\}$ , and the more general configurations model composition contexts. Note that  $(\Sigma, \leq)$  is a partial order with the descending chain condition, where the length of any descending chain starting in s is polynomial in r(s.G'). We can now define partial solvers formally.

**Definition 2** 1. A partial solver is a terminating algorithm A whose semantics f is a state transformer of type  $\Sigma \to \Sigma$  and satisfies, for all s in  $\Sigma$ :

P1 
$$s.G = f(s).G$$
  
P3  $r(f(s)) = r(s)$  implies  $f(s) = s$   
P2  $r(f(s)) \le r(s)$   
P4  $s.W_p \subseteq f(s).W_p$  for all  $p \in \{0,1\}$ 

- 2. We write  $\Sigma_f = \{s \in \Sigma \mid f(s) = s\}$  for the set of fixed points of f.
- 3. We assume that all A run in two stages: first, A evaluates s.G'; second, A updates state s to f(s) where f(s).G' is the result of the first stage.
- 4. Let  $\mathcal{P}$  be the set of partial solvers A that run in polynomial time in  $\mathbf{r}(s.G')$  in the first stage and in  $\mathbf{r}(s.G)$  in the second stage.

By abuse of language, we may sometimes refer to functions f as partial solvers, but it will be clear from context what a corresponding algorithm will be. Condition P1 means that s.G records the input game which thus won't change under f; P2 says that the partial solver cannot increase the rank of the continuation game s.G'; P3 says that failure to decrease the rank means that fwon't change state; and P4 models that decisions of winners of nodes in s.G are inherited by state transformations. Note that P2 and P3 together are equivalent to the simpler  $f(s) \leq s$  but we appeal to P2 and P3 in proofs.

Refinement for state transformers  $f \leq g$  is defined as  $f \leq g$  if, and only if  $\forall s \in \Sigma$ :  $f(s) \leq g(s)$ . We say then that f refines g, and so any partial solver with semantics f refines any partial solver with semantics g. Note that P2 and P3 imply that the strict version f < g of  $f \leq g$  satisfies that the rank of f(s) is less than that of g(s) for at least one state s. The set  $\Sigma_f$  denotes the set of *residual games* of partial solver G, which f cannot simplify.

We now formally present the five analyses from Section 2 in this setting: Static color compression *scc* maps a state  $s = (W_0, W_1, \rho, G', G)$  to s' which is s except that s.G' may change to reflect the compressed, convex color set. Priority propagation pp also may only change s.G' such that the color of at most one node in s.G' is decreased and all other aspects of s.G' remain the same in s'. For fatal attractor detection fa, suppose it detects a fatal attractor X won by player p in G. We set  $Z = \operatorname{Attr}_p[s.G', X]$ . Partial solver fa then transforms state s into (assuming p = 0 without loss of generality):  $s' = (W_0 \cup Z \bullet \rho, W_1, \rho', G' \setminus Z, G)$ . where  $\rho'$  is the restriction of  $\rho$  from domain V'to  $V' \setminus Z$ , and  $G' \setminus Z$  is parity game G' restricted to node set  $V' \setminus Z$  (which eliminates all incoming and outgoing edges of Z as well). Next, consider static analysis ari. If there is no node v in s.G'with  $c'_v < c(v)$ , then ari(s) = s. Otherwise, some such node is chosen and s' equals s except that s'.G' reduces the color at node v to  $c'_v$  in s.G'. The behaviour of gfa is the same as for fa above except that the manner in which such a node set X is computed differs [12], e.g. colours of nodes in X may vary. We summarise:

**Lemma 1** The partial solvers scc, pp, fa, ari, and gfa have state transformer semantics  $\Sigma \to \Sigma$ and are in  $\mathcal{P}$ .

We are interested in sequential iterations of partial solvers that revert control to the first solver in the sequence as soon as state rank decreases: Let  $f_1, \ldots, f_k$  be elements of  $\mathcal{P}$  with  $k \geq 1$ . Let, for each s in  $\Sigma$ , set  $M_s$  be  $\{i \mid 1 \leq i \leq k, \mathsf{r}(f_i(s)) < \mathsf{r}(s)\}$ . Then while  $(f_1, \ldots, f_k)(s)$  is defined as s if  $M_s = \emptyset$  and as while  $(f_1, \ldots, f_k)(f_{j_m}(s))$  otherwise where  $j_m = \min(M_s)$ . It is not hard to show that this defines a family of operators on  $\mathcal{P}$ :

**Lemma 2** For  $k \ge 1$ , operator  $\lambda(f_1, \ldots, f_k)$  while  $(f_1, \ldots, f_k)$  has type  $\mathcal{P}^k \to \mathcal{P}$ .

For a partial solver  $g = \mathsf{while}(f_1, \ldots, f_k)$ , we have  $\Sigma_g = \bigcap_{i=1}^k \Sigma_{f_i}$ . In particular,  $\Sigma_g$  is invariant under permuting the order of the  $f_i$  in g. Operator  $\mathsf{while}(\cdot)$  supports our data-driven approach to refinement as follows: given  $g_0 = \mathsf{while}(f_1, \ldots, f_k)$  we study games s.G' with  $\mathsf{while}(f_1, \ldots, f_k)(s) = s$ to learn a new static analysis  $f_{k+1}$  with  $\mathsf{while}(f_1, \ldots, f_k, f_{k+1})(s) \neq s$ , and then similarly consider  $g_1 = \mathsf{while}(f_1, \ldots, f_k, f_{k+1})$  on the set of states  $\Sigma_{g_0}$  for further refinement. These are refinements since  $\mathsf{while}(f_1, \ldots, f_k) \geq \mathsf{while}(f_1, \ldots, f_k, f_{k+1})$  for all  $k \geq 1$  and all partial solvers  $f_1, \ldots, f_{k+1}$ . The partial solvers in [10, 11, 12] could not completely solve all 1-player games. We show that such completeness is achievable by the interaction of such partial solvers with ari and scc' – a variant of scc that statically compresses the color set of each SCC in a parity game *separately*: if C is such a SCC with set of colours  $\mathcal{C}$ , then scc' makes  $\mathcal{C}$  convex in  $\mathbb{N}$  and recolours the SCC C accordingly. This also illustrates how we may reason about states in  $\Sigma_g$ :

**Theorem 1** Let  $g = \text{while}(f_1, \ldots, f_k)$  be in  $\mathcal{P}$  with  $\{scc', ari, f_a\}$  contained in  $\{f_1, \ldots, f_k\}$ . Then there is no s in  $\Sigma_q$  for which s.G' is a 1-player game.

The next operator transforms a partial solver f into a second-order version that tests consequences of edge removals on residual games of f. For game G with edge relation E, we define two derived games:  $G_{(v,w)} = G$  except where  $v \bullet E$  is now  $\{(v,w)\}$ ; and  $G \setminus (v,w) = G$  except where (v,w) is removed from E. By abuse of notation, we write  $s \setminus (v,w)$  for a state that equals state sexcept that  $(s \setminus (v, w)).G'$  equals  $G' \setminus (v, w)$ . That is to say,  $G_{(v,w)}$  removes from E all edges (v, w')with  $w \neq w'$ , whereas  $G \setminus (v, w)$  removes from G the edge (v, w). The game  $G \setminus (v, w)$  will not introduce deadlocks as it will only be called on nodes v with  $|v \bullet E| > 1$ . We also require notation for initial calling contexts of partial solvers:  $\operatorname{call}(f)(G) = (f(s).W_0, f(s).W_1)$  where s equals  $(\emptyset, \emptyset, \Delta_{V_G}, G, G)$ . Expression  $\operatorname{call}(f)(G)$  extracts the respective set of nodes that f can decide to be won by each player, when run in an initial configuration for G. We can now test whether the commitment to edge (v, w) in  $G_{(v,w)}$  turns a residual state of f into one that it not residual, and this will allow us to simplify G to either  $G_{(v,w)}$  or  $G \setminus (v, w)$ , as shown in Figure 1. Function lifted(.) either leaves a state unchanged or decreases the rank of s.G' by removing at least one edge.

We use  $\mathsf{lifted}(\cdot)$  as an auxiliary function for defining, for all f in  $\mathcal{P}$ , function  $\mathsf{lift}(f) \colon \Sigma \to \Sigma$ through  $\mathsf{lift}(f) = \mathsf{while}(f, \mathsf{lifted}(f))$ . Note that  $\mathsf{lift}(f)$  now has domain  $\Sigma$  as the semantics of  $\mathsf{while}(\cdot)$ enforces that  $\mathsf{lifted}(f)$  is only reached with input from  $\Sigma_f$ . Let algorithm A have semantics f; we write  $\mathsf{lifted}(A)$  for the algorithm obtained from the pseudo-code for  $\mathsf{lifted}(f)$  in Figure 1 when all applications of f are implemented by A. Then  $\mathsf{lift}(A)$  denotes  $\mathsf{while}(A, \mathsf{lifted}(A))$ .

**Lemma 3** For each A in  $\mathcal{P}$  with semantics f, the algorithm lift(A) is in  $\mathcal{P}$  as well and has semantics lift(f).

Of course, we may appeal to Lemma 3 repeatedly to define higher-order versions lift(lift(A)) and so forth for algorithms A in  $\mathcal{P}$  with semantics f, which are all in  $\mathcal{P}$  by virtue of this lemma. Next, we use these operators for data-driven refinement.

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 \begin{array}{l} lifted(f)(s) \ \{ \\ let \ H = (V^*, V_0^*, V_1^*, E^*, c^*) \ be \ s.G'; \\ for \ (v \ in \ V^* \ such \ that \ |v \bullet E^*| > 1) \ \{ \\ p = owner(v); \\ for \ (w \ in \ v \bullet E^*) \ \{ \\ let \ (U_0, U_1) = \mathsf{call}(f)(H_{(v,w)}); \\ if \ (v \ in \ U_p) \ \{ \\ return \ (s.W_0, s.W_1, s.\rho, H_{(v,w)}, s.G); \\ elseif \ (v \ in \ U_{1-p}) \ \{ \\ return \ (s.W_0, s.W_1, s.\rho, H \setminus (v, w), s.G); \\ \} \\ \} \\ return \ s; \\ \end{array} \right\}
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Figure 1: Pseudo-code for function lifted(·) with dependent type  $\prod_{f:\mathcal{P}} (\Sigma_f \to \Sigma)$ : for partial solver A in  $\mathcal{P}$  with semantics f, it renders a partial solver lifted(A) in  $\mathcal{P}$  with semantics lifted(f):  $\Sigma_f \to \Sigma$  by testing effects of edge removals on running A

### 4 Data-driven refinement

We begin our illustration of data-driven refinement with partial solver  $ps_1 = \text{while}(scc, pp, fa, ari, gfa)$ . Based on the semantics of  $\text{while}(f_1, \ldots, f_k)$ , we may assume that the input domain of each  $f_j$  with j > 1 equals  $\bigcap_{i=1}^{j-1} \Sigma_{f_i}$ . In particular, if some partial solver  $f_j$  requires that its input games have no fatal attractors, this is guaranteed by having  $f_l = fa$  for some l < j. We will also exploit that a new analysis  $f_{k+1}$  (which may be more expensive, say) is only ever called in the refinement while $(f_1, \ldots, f_{k+1})$  on states that are residual for while $(f_1, \ldots, f_k)$ .

Some static analyses below will merge a set of nodes X to a sole node owned by player p and of color d. This merge operation can be defined generically:

**Definition 3** Let s be a state,  $X \subseteq s.V'$  with  $|X| \ge 2$  and  $X \bullet E' \setminus X \ne \emptyset$ . Let p be a player, d a color, and  $z \notin s.V'$ . Then tuple merge(s, X, p, d, z) denotes

$$(s.W_0, s.W_1, merge(\rho, X, z), merge(s.G', X, p, d, z), G)$$

$$(1)$$

where the parity game merge(s.G', X, p, d, z) is defined as  $(V^*, V_0^*, V_1^*, E^*, c^*)$  with  $V_{1-p}^* = V_{1-p}' \setminus X$ ,  $V_p^* = (V_p' \setminus X) \cup \{z\}, E^* = (E' \setminus X \times X) \cup ((E'.X \setminus X) \times \{z\}) \cup (\{z\} \times (X \bullet E' \setminus X)), and c^*(v) = c'(v)$  for all  $v \neq z$  whereas  $c^*(z) = d$ . Relation merge( $\rho, X, z$ ) is defined as  $(\rho \setminus X \times s.V') \cup \{(z, w) \mid w \in X \bullet \rho\}$ .

Whenever we invoke the above merge method, we need to ensure that the resulting tuple is an actual state. The parity game merge(s.G', X, p, d, z) has no dead-ends: this is so since z has at least one outgoing edge, which is guaranteed by the fact that (x, v) is in s.E' for some x in X and some v in  $s.V' \setminus X$ .

Next, we present two static analyses that use the above merging method.

Sole successor node merging:  $m_{ss}$ . An inspection of residual games for  $ps_1$  identifies a method  $m_{ss}$  for merging two nodes which leads to a refined partial solver  $ps_2 = \text{while}(scc, pp, fa, ari, gfa, m_{ss})$ .



Figure 2: Left: Residual game s.G' for  $ps_1$ . Right: game  $m_{ss}(s).G'$  obtained from the call  $merge(s, \{v_{14}, v_3\}, owner(v_3), c(v_3), v_{26})$ 

To see how  $m_{ss}$  works, let s be a state in  $\Sigma$ . Suppose that there are two nodes v and w in s.G' such that  $v \bullet E' = \{w\}, w \bullet E' \not\subseteq \{v, w\}$ , and the color of v in s.G' is not smaller than that of w. Choose some z not in the node set of s.G'. Then

$$m_{ss}(s) = merge(s, \{v, w\}, owner(w), c(w), z)$$

$$\tag{2}$$

We note that (2) is well defined as  $w \bullet E'$  contains a node not in the merge set  $\{v, w\}$ . If there are no such nodes v and w, then we set  $m_{ss}(s) = s$ . Figure 2 shows a residual game for  $ps_1$  and the effect of  $m_{ss}$  on it: node  $v_{14}$  is v, node  $v_3$  is w, the owner of w is player 1, the color of w is 2, and z is  $v_{26}$ .

#### **Theorem 2** The static analysis $m_{ss}$ is in $\mathcal{P}$ .

Merging SCCs:  $m_{scc}$ . The study of residual games for  $ps_2$  introduces more complex methods for merging nodes. We will only describe one of these next, static analysis  $m_{scc}$  which operates on states residual for fa and attempts to merge an SCC in a sub-game of the residual game. For state s, this analysis checks whether there is some color d such that the following can be realised: Let  $H = (V'[Z], E' \cap Z \times Z)$  be the game graph that restricts the game graph of s.G' to  $Z = \{w \in V'_{1-p} \mid c(w) \ge d\}$ , the set of all nodes w owned by player 1 - p and of color  $\ge d$  in s.G'where p = d%2. Suppose there is an SCC C in H and a subset  $X \subseteq C$  with |X| > 1 such that all elements in X have color d and where  $X \bullet E' \cap (V' \setminus X)$  is non-empty in G'. The latter implies that

$$m_{scc}(s) = merge(s, X, 1 - p, d, z)$$
(3)

is well defined: from  $X \bullet E' \cap (V' \setminus X) \neq \emptyset$  we infer that the parity game  $m_{scc}(s).G'$  contains no dead-ends. If there is no such color d with corresponding H and X, then we set  $m_{scc}(s)$  equal to s. This defines a refined partial solver  $ps_3 = \mathsf{while}(scc, pp, fa, ari, gfa, m_{ss}, m_{scc})$ . Figure 3 shows a residual game for  $ps_2$  and the effect of  $m_{scc}$  on it: d is 2, p is 0, node set X is  $\{v_5, v_{33}\}$ , and z is  $v_{34}$ .

The soundness proof for this analysis is pretty straightforward: first we show that the same player indeed wins all nodes in X, and then we show that the merged version of the continuation game has the same winning region modulo  $\rho$ .

**Theorem 3** The static analysis  $m_{scc}$  is in  $\mathcal{P}$  with domain  $\Sigma_{fa}$ .



Figure 3: Left: Residual game s.G' for  $ps_2$ . Right: game  $m_{scc}(s).G'$  obtained from the call  $merge(s, \{v_5, v_{33}\}, 1-0, 2, v_{34})$ 



Figure 4: Left: Residual game s.G' for  $ps_3$ . Right: game  $er_{fa}(s).G'$  which removes edge  $(v_{25}, v_{16})$  since  $s.G'_{(v_{25},v_{16})}$  contains  $\{v_{25}, v_{16}\}$  as a fatal attractor for color 0

Edge removal based on conditional fatal attractors:  $er_{fa}$ . The residual games of  $ps_3$  led us to studying edge removal methods for states in  $\Sigma_{fa}$ . We discovered static analysis  $er_{fa}$  which works as follows for any s in  $\Sigma_{fa}$ : If there is an edge (v, w) in s.G' such that  $s.G'_{(v,w)}$  has a fatal attractor, then  $er_{fa}$  choses one such edge and sets  $er_{fa}(s) = s \setminus (v, w)$ , i.e. removes edge (v, w) from s.G'. The intuition is that we may remove the edge anyway if v is won by player 1 - owner(v), and we may remove it if v is won by player owner(v) as then (v, w) cannot be part of any winning strategy for that player since s is in  $\Sigma_{fa}$ . Otherwise, if no such edge exists,  $er_{fa}(s)$  equals s. For refined partial solver  $ps_4$  being while  $(scc, pp, fa, ari, gfa, m_{ss}, m_{scc}, er_{fa})$ , Figure 4 shows s.G' for some s in  $\Sigma_{ps_3}$  and the effect of  $er_{fa}$  on it: d is 2, p is 0, set X is  $\{v_5, v_{33}\}$ , and z is  $v_{34}$ .

**Theorem 4** The static analysis  $e_{f_a}$  is in  $\mathcal{P}$  with domain  $\Sigma_{f_a}$ .

Edge removal based on shared descendant:  $er_{sd}$ . Residual games for partial solver  $ps_4$  suggested to us the following static analysis  $er_{sd}$ , which removes an edge based on a shared descendant. This checks, for s in  $\Sigma$ , whether there are three different nodes v, w, z in s.G', an edge (v, w) in s.G', p in  $\{0,1\}$ , and two colours  $c_v$  and  $c_w$  in C(s.G') (not necessarily at v or w) with  $c_v \leq_p c_w$  such that:

- there is a path  $P_{vz}$  of color  $c_v$  from node v to z in s.G' such that all nodes on  $P_{vz}$  are in  $V_p$  or have only one outgoing edge in s.G', and
- there is a path  $P_{wz}$  of color  $c_w$  from node w to z in s.G' such that all nodes on  $P_{wz}$  are in  $V_{1-p}$  or have only one outgoing edge in s.G'.



Figure 5: Left: Residual game s.G' for  $ps_4$ . Right: game  $er_{sd}(s).G'$  which removes edge  $(v_0, v_{20})$  since it has two control paths that meet the criteria for  $er_{sd}$ 

If there are such data,  $er_{sd}$  chooses one such edge (v, w) and sets  $er_{sd}(s) = s \setminus (v, w)$ , i.e. edge (v, w) is removed from s.G'. The intuition is that this only requires an argument when player p wins v in s.G' with a winning strategy that moves from v to w: then we can employ a *dominance* argument based on  $\leq_p$  as indicated below and detailed in Section A of the appendix. Otherwise, if no such edge exists,  $er_{sd}(s)$  equals s. Figure 5 shows the effect of  $er_{sd}$  on a residual game for  $ps_4$ : v is  $v_0$ , w is  $v_{20}$ , p is 1, z is  $v_8$ , the path  $P_{vz}$  (blue, via  $v_{16}$  and  $v_{21}$ ) has color  $c_v = 0$ , and the path  $P_{wz}$  (green, via  $v_{19}$ ) has color  $c_w = 0$ . This yields a refined partial solver  $ps_5 = while(scc, pp, fa, ari, gfa, m_{ss}, m_{scc}, er_{fa}, er_{sd})$ .

The proof of the correctness of  $er_{sd}$  exploits that removing an edge (v, w) where v is in  $V_p$  cannot increase the winning region of player p. Therefore, it will suffice to show that this does not decrease the winning region of player p. Only the case when v is won by player p with a strategy that moves from v to w is of real interest. We then use this strategy  $\tau$  and the path  $P_{vz}$  to define a new strategy  $\gamma$  with finite memory for that player on the new game  $G'' = s.G' \setminus (v, w)$ . We then show that this new strategy  $\gamma$  is winning in game G'' on the old winning region of s.G', by showing that each infinite play in game G'' conformant with the new strategy  $\gamma$  determines an infinite play in game G'' is better or equal with respect to  $\preceq_p$  to the outcome of the infinite play in game s.G'. This ensures that player p wins the infinite play in the new game G'', as he does win the infinite play in game s.G'.

**Theorem 5** The static analysis  $er_{sd}$  is in  $\mathcal{P}$ .

### 5 Experimental results

https://www.dropbox.com/s/g10y1plcc4io9tk/code\_partial\_solvers.zip?dl=0 has all the relevant source code of our tool for realising experiments reported below. Our framework and its implementation in Python do not compute winning strategies since soundness proofs for some partial solvers require finite memory (shown in the appendix); related to that, in [12] it was noted that the partial solver psolC, to which while(gfa) is similar, may require finite memory. We use PGSolver [6, 7] as a test oracle to validate that our implementations of partial solvers are sound, i.e. that they never misclassify the winner of a node of an input game.

**Experiments on structured benchmarks.** We ran  $ps_1$  on Keiren's comprehensive benchmark suite [17] on a HP EliteDesk 800 G1 TWR with RAM 16GB and an Intel Core i7-4770 3.40GHz. For efficiency reasons, we ran  $ps_1$  over all games in that suite whose textual representation was less than 200KB. This suite contains the PGSolver benchmarks as well; however, for some of the latter types Keiren's suite only contains games whose textual representation is larger than 200KB; for these types we thus used PGSolver itself to generate such test games, the full list of these games in contained in Section B in the appendix. In this manner, we tested 481 games – some of which with more than 10,000 nodes. Both  $ps_1$  and our implementation of Zielonka's algorithm solved 464 of these games completely and agreed on those solutions. For the remaining 17 games, an exception was raised (stack overflow or a timeout of 60 seconds) for at least one of  $ps_1$  or our implementation of Zielonka's algorithm. Our version of Zielonka's algorithm was also extensively tested against the PGSolver command pgsolver - global recursive, justifying its use in validation testing. That use allowed us to unit test more efficiently, as our pipe from Python to PGSolver input was rather slow.

**Random games used.** We used a standard type of random game [7] with configuration xx-yy-aa-bb, which has xx nodes whose ownership is determined uniformly at random, yy colours where colours of nodes are independently and uniformly drawn from set  $\{0, 1, \ldots, yy\}$ , and where for each node v the set  $v \bullet E$  has at least aa and at most bb elements; the cardinality of  $v \bullet E$  is determined for each node independently and uniformly at random.

Unit testing for our implementation of solvers. For each of the four new analyses of Section 4, we generated a stream of random games and applied the analysis to each game as often as it would result in state changes. For each state change, we tested whether the winning regions (modulo potential node merging via  $\rho$ ) won't change. Specifically, we generated 100,000 such tests for each analysis. For  $er_{fa}$ , we used configuration 60-30-2-3 and 100,395 games in  $\Sigma_{fa}$  to generate that many tests. For  $er_{sd}$ , we used configuration 60-30-2-3 with 24,081 games, for  $m_{ss}$  we took configuration 60-30-1-3 and 100,140 games in  $\Sigma_{fa}$ , and for  $m_{scc}$  we had configuration 60-30-1-3 with 1,885,423 games. Note that such tests may generate fewer games than test cases, if the analysis can be applied repeatedly on continuation games. But we may have to generate more games than tests, which was the case for analyses that require states from  $\Sigma_{fa}$ .

In addition, we did unit testing of partial solvers  $ps_1$  through to  $ps_5$ : we generated 10 million games of type 50-25-2-4 as a test harness; these partial solvers never misclassified a node for all of these games, based on the regression test with PGSolver as described above. Here we also unit tested that these are refinements:  $ps_1 \ge ps_2 \ge ps_3 \ge ps_4 \ge ps_5$ . This gave us high confidence that these implementations are correct. So we turned unit tests off in further experiments that explored billions of random games in search for residual games.

Finally, we unit tested lifted( $\cdot$ ); first, we looked at 974 residual games that we found for  $ps_5$  and ran lifted( $ps_5$ ) on those. For each of these 974 games, this call removed at least one edge (i.e. it reached the **if** or **elseif** branch) and we successfully tested that this did not change the winning regions. We did the same unit tests on 24,132 residual games for  $ps_4$  that we generated. For each of these games, the **if** or **elseif** branch was reached and the resulting game did not

change winning regions.

Comparing effectiveness of new analyses. We wanted to understand how often these four analyses can simplify games. For this, we considered states in  $\Sigma_{fa}$  to create an input common to all these analyses. We generated 100,000 states s in  $\Sigma_{fa}$  where s.G' is the result of eliminating all fatal attractors from a random game of configuration type 60-30-2-3. The analyses simplified 99,596 such games for  $er_{fa}$ , 84,126 games for  $er_{sd}$ , 80,327 for  $m_{ss}$ , and 7,946 for  $m_{scc}$ . Then we did a similar experiment for 25,360 residual games of a partial solver similar to  $ps_3$ , whose residual games are all in  $\Sigma_{fa} \cap \Sigma_{er_{fa}} \cap \Sigma_{m_{ss}}$ : as expected, we confirmed that neither  $er_{fa}$  nor  $m_{ss}$  simplified any of these games - whereas  $er_{sd}$  simplified 25,355 of these and  $m_{scc}$  simplified 20,119 of these.

**Experiments for data-driven refinement.** We conducted experiments to determine which random game configurations xx-yy-aa-bb are more prone to generating residual games for our partial solvers above: when bb equals aa + 2 and xx and yy are fixed, we noticed that bb = 2 was most effective at generating residual games whereas  $aa \ge 5$  was very ineffective. Fixing aa and bb and letting yy be xx or xx/2, we noted that residual games occur more frequently as xx increases from 30 to about 90 but then occur less frequently again. Fixing only yy, we noted that an increase beyond 15 did not have much effect.

These insights informed a large experiment in which we generated 10, 422, 420 random games of type 50-25-2-3 in total – more than 10 million games – and recorded how many residual games each of the five partial solvers had for these: 32,716 for  $ps_1$ , 30, 631 for  $ps_2$ , 19, 230 for  $ps_3$ , 958 for  $ps_4$ , and only 136 for  $ps_5$ . This illustrates that each of the newly discovered partial solvers leads to more effective refinements of existing ones. Moreover, the partial solver lift( $ps_5$ ) completely solves the 136 residual games this experiment discovered for  $ps_5$ .

**Experiments for** lift(·). We ran lift( $ps_5$ ) on a range of random game configurations to see whether we could find any non-empty residual games. We tested this on games of varying configurations with node sizes ranging from 40 to 1000. All of these games, totalling to 9,353,516,890 (over nine billion games), were solved completely by lift( $ps_5$ ); specifically, we first ran  $ps_5$  on these games and invoked lift( $ps_5$ ) on all the non-empty residual games, which were only in the order of thousands. This staging is justified as  $ps_5$  is part of the interaction within lift( $ps_5$ ). More details are shown in Section C in the appendix.

## 6 Related work

In [6], a pattern is proposed, implemented, and evaluated for how to solve parity games. This generic solver can be seen as a composition context of partial solvers (in our setting and terminology) in which all but one partial solver run in polynomial time, and where the latter is a complete solver that is only called when the partial solvers cannot progress on any terminal SCC of the parity game. The aim of this is to gain efficiency, and this was successfully demonstrated in [6]. But our aim here is to gain *effectiveness* so that a composition context of partial solvers would never or very rarely have to call a complete solver.

In [8], it is shown that a variant of Zielonka's algorithm solves some classes of parity games in polynomial time, and an improved lower (exponential) bound is derived for solving all parity games with such recursive algorithms. In [13], a function related to lift(f) is studied; using our terminology, it operates as follows: for  $w \neq w'$  in  $v \bullet E$ , if there is some node z in G such that f detects a different winner for node z in the two games  $G_{(v,w)}$  and  $G_{(v,w')}$ , then node v is won by player owner(v) in parity game G. It would be of interest to integrate this method into our framework for experimental evaluation.

In [11], another function similar to lift(f) is investigated: apart from presentational differences (our work here uses states), the function in [11] essentially omits the *if* part of code in Figure 1 and its soundness proof had severe restrictions on the types of partial solvers that it may use as arguments.

In [12], experiments compared the effectiveness of partial solver psolB of [10] (which is similar to while(fa)) and psolC (which is similar to while(gfa): on random games, psolC was more effective than psolB on games with higher edge density, but not at all more effective on games with lower edge density.

In [4], the concept of a snare is defined for mean-payoff games, a generalisation of parity games (see e.g. [2]). A snare is a subset of nodes for which player Max has a partial strategy that is winning on the sub-game restricted to that node set. Sole opponent Min may have escape nodes out of the snare; if there is only one such escape node, then edges that are not escape edges may be removed without changing the winning regions of the mean-payoff game.

## 7 Discussion

We also ran detailed experiments on residual games of some of the partial solvers  $ps_1$  to  $ps_5$ . Specifically, we studied structural features of their terminal SCCs. It appears that such SCCs have statistically significant structure. For example, we were unable to find a terminal SCC of a residual game that has two winners; however, we could then manually combine two such games to construct a residual terminal SCC in which both players win nodes.

We implemented the partial solver  $er_{sd}$  in a weaker version than that presented above: control paths only have nodes *owned* by the controlling player. It may be possible to generalise the  $er_{sd}$  specified in the paper such that node z is reached in the alternating sense by the controlling player (on a tree rather than on a path), and always reached with the specified color.

Our approach to data-driven refinement of partial solvers worked well since residual games were found within a reasonable amount of time. But this method led to powerful partial solvers for which we now genuinely struggle to find any residual games by relying on standard random and non-random benchmarks. This may make it harder to evaluate and improve such a partial solver. Theorem 1, however, suggests one form of evaluation: to prove mathematical properties of residual games that may also imply that well known types of games are never residual for a given partial solver. We can, e.g., show that  $ps_1$  completely solves all Büchi games, as **psolB** in [10] does that.

Our paper focussed on *effectiveness*: the ability of a partial solver to completely solve a game in polynomial time. Our framework can also facilitate the study of the *efficiency* of composed partial solvers, e.g. by choosing the order of arguments in  $while(\cdot)$  to increase empirically observed running times.

## 8 Conclusions

There are many heuristics for solving or preprocessing parity games, potentially decreasing the complexity of a parity game by reducing some of its colours, by removing some of its edges, or by removing some of its nodes (whose winners would then be known). Such methods are sound as

they do not alter the winning regions of the resulting parity game. We developed here a semantic composition framework that allows such methods to interact and to share information so that their power of inference could be amplified. Concretely, we developed the notion of state that captures computational state within a composition context and defined partial solvers as certain state transformers. Two composition operators for partial solvers were developed and shown to preserve polynomial-time computability: a sequential iteration of a list of partial solvers that tracks progress, and a lift operator testing soundness of edge removals by exploring consequences of edge commitments for a partial solver.

We instantiated these composition operators with partial solvers from the literature and applied them experimentally to study games that such composed partial solvers cannot simplify. These games, seen as data, led to the incremental design of new partial solvers, even to a new method that merges nodes known to have the same but unknown winner. We proved the soundness of these new solvers. Our focus was on computing winning regions, not winning strategies. It would be of interest to understand whether we could also compute memoryless winning strategies within this framework, in which winning strategies with finite memory are computable in principle.

We unit tested the implementation of our framework to validate experimental results. The latter demonstrated the effectiveness of such a sequence of refined partial solvers: after only a few refinement steps we arrived at a partial solver that not only solved all structured games from the state-of-the-art benchmark suite for parity games, but whose lifted version also solved all random games generated within a month of calendar time. We think this is compelling evidence that there are very effective polynomial-time partial solvers for parity games.

The strength of this work is that is yields effective partial solvers that are guaranteed to run in polynomial time. But this is also its weakness in that we do not, at present, have a good understanding of what types of parity games are solved completely for certain partial solvers. More powerful versions of Theorem 1, which extend to classes of 2-playergames, would be a first step in addressing that weakness.

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# A Proofs

This section contains proofs of lemmas and theorems in this paper.

**Proof of Lemma 1:** All five state transformations can be computed in polynomial time; this is clear for *scc* and *pp*. It follows for *fa* from [10], for *ari* from [9], and for *gfa* from [12]. It is clear that all these analyses satisfy properties P1-P4. The analyses *scc*, *pp*, and *ari* either return the same state *s* or decrease the color of exactly one node in *s.G'*. Therefore, it suffices to show that these decreases do not change the winning region of *s.G'*. For *scc* and *pp* this is well known, and for *ari* this is shown in [9]. The analyses *fa* and *gfa* both change state in the same manner and so the argument for *s'* being a state is the same: the rank of *s'.G'* is less than that of *s.G'*, which is less than or equal to the rank of *s.G*; thus,  $r(s'.G') \leq r(s'.G)$  follows as *s'.G* equals *s.G*. Relation  $\rho'$  has the right type (as all pairs (u, v) from  $\rho$  with u in Z have been moved to  $W_0$ , without loss of generality). Since  $W_1$  won't change in *s'*, and since Z is won by player 0 in *s.G'*, we infer that also  $\mathsf{Win}_1[G' \setminus Z]$  equals  $\psi_1[G']$ . Therefore, the union of  $W_1$  and  $\mathsf{Win}_1[G'] \bullet \rho = \mathsf{Win}_0[G]$ , where we may decompose the former to  $W_0 \cup ((Z \bullet \rho) \cup (\mathsf{Win}_0[G'] \setminus Z) \bullet \rho) = (W_0 \cup Z \bullet \rho) \cup (\mathsf{Win}_0[G' \setminus Z]) \bullet \rho = s'.W_0 \cup \mathsf{Win}_0[s'.G']$ . **QED.** 

**Proof of Lemma 2:** Let  $f_1, \ldots, f_k$  be all in  $\mathcal{P}$ . Let  $g = \mathsf{while}(f_1, \ldots, f_k)$ . We need to show that g is in  $\mathcal{P}$ . Let s be in  $\Sigma$ . Let  $A_i$  be a polynomial-time algorithm for computing  $f_i$ . Then an algorithm A for the execution of g at s will apply  $A_1$  to s and return  $A_1(s)$  if its rank is smaller than that of s. Otherwise, it will apply  $A_2$  and so forth. Either one of these  $A_i$  decreases the rank and then  $A_1$  starts again, or A terminates. Either way, the number of times that each  $A_i$  is called is bounded by  $\mathsf{r}(s.G')$ , and each  $A_i$  is polynomial-time in the size of the respective games in s. Therefore, A itself is polynomial-time as well.

It remains to show that g is a partial solver. Since each  $f_i$  maps states to states, it follows from the definition of g that it also maps states to states. So it remains to prove that g satisfies properties P1-P4. Since all  $f_i$  satisfy P1-P3, it immediately follows that g also satisfies P1-P3. But no  $f_i$  removes nodes from the sets that classify winners by P4. By definition of g, this implies that g satisfies P4 as well. **QED**.

**Proof of Theorem 1:** Let s be in  $\Sigma_g$ . Since scc', ari, and fa are contained in  $\{f_1, \ldots, f_k\}$ and g equals while $(f_1, \ldots, f_k)$ , we have that  $\Sigma_g$  is contained in  $\Sigma_{scc'} \cap \Sigma_{ari} \cap \Sigma_{fa}$ . **Proof by**  contradiction: Assume that s.G' is a 1-player game. Without loss of generality, all nodes in s.G' are owned by player p. In particular, any cycle in s.G' whose color has parity p would give rise to a fatal attractor for player p in s.G', but s.G' is residual for g and so residual for fa as well. But then the parity of the color of all cycles in the game s.G' must equal 1 - p. Consider a node z of a terminal SCC C in s.G'. Then  $c'_z$ , the maximal color of all cycles in s.G' through z, must have parity 1 - p as we showed that this is the case for all cycles in s.G'. Since  $c(z) \ge c'_z$  and since s.G' is in  $\Sigma_{ari}$ , this implies that  $c(z) = c'_z$  and so c(z) has parity 1 - p. Since s is in  $\Sigma_{scc'}$ , this implies that all nodes in the SCC C have the same color, and of parity 1 - p. But then player p cannot escape from reaching such nodes, and so player 1 - p would have a fatal attractor in s.G', a contradiction to s being in  $\Sigma_{fa}$ . Therefore, s.G' cannot be a 1-player game. **QED**.

**Proof of Lemma 3:** Let A be in  $\mathcal{P}$  with semantics f. We first consider lifted(f) and show that it is of type  $\Sigma_f \to \Sigma$  and can be computed by lifted(A) in polynomial time. Let s be in  $\Sigma_f$ . We first want to show that lifted(f)(s) is in  $\Sigma$ . Either lifted(f)(s) returns s, which is contained in  $\Sigma$  or it returns something that equals s except that s.G' is simplified by removing one or more outgoing edges of v in s.G', without introducing deadlocks. Since this decreases the rank of s.G' and leaves sets  $s.W_p$  unchanged, it suffices to show that s.G' and the simpler game have the same winning regions. We have two cases.

**Case 1:** Let the simpler game lifted (f)(s).G' be  $H_{(v,w)}$ . Then v has at least one more outgoing edge in s.G' other than (v, w), is owned by player p, and the partial solver f when run on the initial configuration for game  $H_{(v,w)}$  decides that player p wins node v in  $H_{(v,w)}$ . But then we know that  $H_{(v,w)}$  and s.G' have the same winning strategies:  $\operatorname{Win}_{1-p}[s.G']$  is contained in  $\operatorname{Win}_{1-p}[H_{(v,w)}]$ since the latter game removes some edge for player p only. Since parity games are determined, it suffices to show that  $\operatorname{Win}_p[s.G']$  is contained in  $\operatorname{Win}_p[H_{(v,w)}]$ . Let  $\tau$  be a memoryless strategy for player p that is winning in node set  $\operatorname{Win}_p[s.G']$  in s.G'. We define a strategy  $\gamma: V^* \cdot V_p \to V$  for player p in  $H_{(v,w)}$  as follows: as long as node v has not been reached in a play,  $\gamma$  plays like  $\tau$ ; if and when node v is reached,  $\gamma$  plays a strategy that witnesses that node v is won by player p in  $H_{(v,w)}$ . Then  $\gamma$  is a winning strategy for player p in  $\operatorname{Win}_p[s.G']$  in  $H_{(v,w)}$ .

**Case 2:** Otherwise, the simpler game lifted(f)(s). G' must be  $H \setminus (v, w)$ . Then we know that player 1 - p wins node v in s. G'. Then removing the edge (v, w) from that game won't change any winning regions as v is owned by player p who loses that node in  $H_{(v,w)}$ , and that resulting game is  $H \setminus (v, w)$ .

As for computational complexity, we note that state changes in the computation of lifted(A)only ever change the component s.G' and leave all other components the same. Since lifted(f)does not increase rank, it follows that there are at most r(s) many calls to A in lifted(A) which computes lifted(f)(s). This computation therefore takes time polynomial in the respective sizes of games in s, as this is the case for A as well.

Finally, let s be in  $\Sigma$ . Then the algorithm  $\mathsf{while}(A, \mathsf{lifted}(A))$  has semantics  $\mathsf{while}(f, \mathsf{lifted}(f))$ and, by virtue of Lemma 2, is running in polynomial time in the sizes of the games in s since this is true for A and  $\mathsf{lifted}(A)$ . Since f has type  $\Sigma \to \Sigma$  and  $\mathsf{lifted}(f)$  has type  $\Sigma_f \to \Sigma$ , the semantics of  $\mathsf{while}(f, \mathsf{lifted}(f))$  ensures that it has then type  $\Sigma \to \Sigma$  and so  $\mathsf{while}(A, \mathsf{lifted}(A))$  is a partial solver. **QED**.

**Proof of Theorem 2:** Clearly,  $m_{ss}$  is computing in polynomial time in the size of states. Properties P1-P4 are obviously satisfied for  $m_{ss}(s)$ , so it remains to show that  $m_{ss}(s)$  as in (2) defines a state. By definition of  $merge(\rho, X, z)$  and since s is a state, we know that  $m_{ss}(s).W_p$  unioned with the image of the winning region for player p in  $m_{ss}(s).G'$  under relation  $merge(\rho, X, z)$  will

equal Win<sub>p</sub>[s.G]. Therefore, it suffices to that end to show that v and w have the same winner in s.G': For p with  $v \in V_p$  we use that s.G' is determined. Let player p win node w in s.G'. Then player p also wins node v since w is in Win<sub>p</sub>[s.G'] and the latter is closed under p-attractors in s.G'. Otherwise, player 1 - p wins node w and so v is in the (1 - p)-attractor of Win<sub>1-p</sub>[s.G'] (which equals Win<sub>1-p</sub>[s.G']) since w is in Win<sub>p</sub>[s.G'] and w is the only successor of v in s.G'. **QED**.

**Proof of Theorem 3:** Let us first understand that  $m_{scc}$  can be computed in time polynomial in the sizes of games in s. We need to find such H and X for at most  $|\mathsf{C}(s.G')|$  many colours, which is bounded by  $\mathsf{r}(s.G')$ . For each such color d, the game graph H can be computed in time linear in |s.G'|. The SCC decomposition of H uses Tarjan's algorithm, which is polynomial time in H. Then we need to inspect at worst all SCCs C of H, whose number is bounded by |s.V'|, to see whether C contains such a desired X. Let Z be the set of all nodes in such an SCC C of color d:

- Let Z contain less than 2 elements. Then we ignore this SCC.
- Let Z contain at least two elements. **Proof by Contradiction:** Suppose there is no edge from Z in s.G' to a node not in Z. Then Z is a fatal attractor for player p in s.G' for color d: even though all nodes in Z are owned by player 1-p, that player cannot escape this set with opposing color. But by assumption, s.G' has no fatal attractors, a contradiction. Therefore, there is some edge (v, w) in s.E' with v in Z and  $w \notin Z$ . Thus, we may set X to be that Z.

In other words, the analysis  $m_{scc}$  only does not change the state s if for all colours d, all SCCs of H (which depends on d) have at most one element of color d. And the analysis  $m_{scc}(s)$  can be computed in polynomial time in the sizes of games in s. It is routine to show that  $m_{scc}(s)$  satisfies properties P1-P4, assuming that  $m_{scc}(s)$  is a state. Therefore, we focus on showing the latter. Clearly, the rank of  $m_{scc}(s)$  is less than or equal to r(s), either the state does not change or the new state has at least one less node and no more edges or total color sum than before.

For d, p, and X meeting the assumptions of  $m_{scc}(s)$  we argue that all nodes in X are won by the same player in parity game s.G': Let us assume that player 1 - p wins some node x in X in game s.G'. Player 1 - p can reach all nodes in X from x in s.G', since X is an SCC in the game graph H whose nodes are all owned by player 1 - p, and since H is a sub-graph of s.G'. Therefore, player 1 - p can attract all of X to x and so win all of X in s.G'. Therefore, either player 1 - pwins all nodes of X in s.G', or player 1 - p wins none of the nodes of X in s.G'. But this means, by determinacy, that X is won by the same player in parity game s.G'.

Next, let G'' be the parity game  $m_{scc}(s).G'$ . Since s is a state, we know that  $s.W_p \cup \operatorname{Win}_p[s.G'] \bullet \rho$ equals  $\operatorname{Win}_p[s.G]$ . By the definition of  $merge(\rho, X, z)$  applied to  $m_{scc}$ , we learn from that that  $m_{scc}(s).W_p$  unioned with the image of the winning region of player p in  $m_{scc}(s).G'$  under relation  $merge(\rho, X, z)$  equals  $\operatorname{Win}_p[s.G]$  as well. Therefore, it remains to show two things: all nodes  $v \neq z$ in G'' have the same winner in G'' and in s.G'; and node z in G'' has the same winner in G'' as node set X has in s.G'.

Let  $v \neq z$  be a node in G''. We do a case analysis over who wins that node in G'':

- Let v be won by player p in G''. Then player p has a memoryless winning strategy  $\tau$  in G'' for his winning region in G''. Note that z and all nodes in X are owned by player 1 p. Therefore,  $\tau$  is also a strategy of player p in game s.G'. We claim that  $\tau$  is winning for player p for node v in s.G' as well. Let  $\pi$  be any infinite play conformant with  $\tau$  and starting at v in s.G'.
  - Let an infinite suffix of  $\pi$  be in node set X. Then the set  $lnf(\pi)$  equals  $\{d\}$  as d is the only color infinitely occurring in  $\pi$ . Since d has parity p, player p wins  $\pi$  in s.G'.

- Otherwise, there is at least one node w not in X that occurs in  $\pi$  infinitely often. But then  $\pi$  eventually leaves X each time it enters X, and so  $\pi$  corresponds to an infinite play  $\pi'$  in G'' that is conformant with  $\tau$  and such that all maximal finite sub-plays in  $\pi$ that are in node set X are replaced with the play consisting of the sole move z. Since z and all nodes in X have color d, the outcome of the plays  $\pi$  and  $\pi'$  is the same. But  $\pi'$  is won by player p in G'' as it is conformant with  $\tau$ . So  $\pi$  is won by player p in s.G'.
- Let v be won by player 1 p in G'' and let  $\gamma$  be a memoryless winning strategy for player 1-p on his winning region in G''. We construct a strategy for player 1-p in s.G' that contains finite memory as follows: By definition of G'', we know that  $\tau(z)$  is neither z nor in X. By the definition of the edge relation in G'', there must exist some  $x^*$  in X such that  $(x^*, \tau(z))$  is in s.E'. Strategy  $\gamma$  behaves the same as  $\tau$  as long as, and until, a play reaches a node x in X. If x equals  $x^*$ , then  $\gamma$  moves to  $\tau(z)$  – noting that  $(x^*, \tau(z))$  is an edge in s.G'. Otherwise,  $\gamma$  moves on a finite path from x to  $x^*$  (in some deterministic manner, without leaving X). So let  $\pi'$  be the resulting infinite play in s.G' that is conformant with  $\gamma$ , begins in v, and where player p makes the same moves as in  $\pi$  (if we abstract any maximal sub-play of nodes from X in  $\pi'$  to z in  $\pi$ ). Since player 1 - p wins  $\pi$ , there is some node u on  $\pi$  that occurs infinitely often and whose color decides that play. In particular,  $u \neq z$  and the parity of c(u) is 1-p. But then the path  $\pi'$  contains u infinitely often as well: only z is replaced by a finite path in X (of color d) and the predecessors and successors of z on  $\pi$  (which are not in X by construction) are also predecessors, respectively, successors of nodes from X in  $\pi$ . Since  $\pi'$  does not change the set of colours occurring on  $\pi$  (infinitely or not), this means that c(u) also decides the winner of play  $\pi'$ , and that is player 1 - p.

The above case analysis also applies to plays that begin in node z; in this case, there is just one occurrence of z on  $\pi$  that does not have a predecessor but this is immaterial to the above argument. **QED**.

**Proof of Theorem 4:** Let s be in  $\Sigma_{fa}$ . Properties P1-P4 are clearly satisfied of  $er_{fa}(s)$ . The algorithm A that computes  $er_{fa}(s)$  makes at most |s.E'| many calls to partial solver fa on states whose rank is smaller than  $\mathbf{r}(s)$ . Since fa is in  $\mathcal{P}$ , algorithm A computes  $er_{fa}(s)$  in polynomial time in the sizes of games in s.

Thus it suffices to show that  $s \setminus (v, w)$  is a state. Since no nodes are removed and  $\rho$  remains the same, it suffices to show that removing the edge (v, w) won't change the winning regions in s.G'. Let p be such that  $v \in V_p$ .

**Case 1:** If v is in  $Win_{1-p}[s.G']$ , then removing that edge won't change winning regions as  $Win_{1-p}[s.G']$  is a p-trap in s.G'.

**Case 2:** Otherwise, v must be in  $\operatorname{Win}_p[s.G']$ . There are no fatal attractors in s.G' but there is a fatal attractor X in  $s.G'_{(v,w)}$  for some color d. Then the winning strategy for player p' = d%2for this fatal attractor, which reaches from all nodes in X again nodes in X such that only nodes of color  $\geq d$  are encountered en route, would also be winning in s.G' if p' where to be p, as then player p could choose move (v, w) at node v to conclude that X is a fatal attractor in s.G'. This contradiction shows that p' = 1 - p. But then the move (v, w) cannot be a part of any memoryless strategy that is winning on  $\operatorname{Win}_p[s.G']$  in game s.G' for player p: otherwise, the winning strategy for the fatal attractor X in  $s.G'_{(v,w)}$  would also realise X as a fatal attractor in s.G' – contradicting the soundness of the partial solvers.

To summarise, it is safe to remove that edge without changing the winning regions of s.G' and  $er_{fa}(s).G'$ . QED.

**Proof of Theorem 5:** First, we show that  $er_{sd}$  can be computed in polynomial time. For each edge (v, w) in s/G' with  $v \neq w$ , we explore any z in s.V' different from v and w, and do suitable SCC decompositions to determine whether there are desired paths from v to z and from w to z. For p = c(v)%2, we may determine paths  $P_{vz}$  by restricting nodes of s.G' to those owned by player p or being deterministic. Then we can do an SCC decomposition of the resulting game graph. Using that decomposition, we can decide whether such a path exists and, if so, determine the most preferred color  $c_v$  of such paths for player p, with respect to  $\preceq_p$ . Similarly, we may restrict the game graph of s.G' to nodes owned by player 1-p or being deterministic and do an SCC decomposition on the resulting game graph. If a path  $P_{wz}$  exists, we may use that SCC decomposition to find a path with the least preferred color  $c_w$  of such a path for player p, with respect to  $\preceq_p$ . If  $c_v \preceq_p cc_w$ , then we have found an instance of  $er_{sd}$  where we may remove edge (v, w) from s.G'. Otherwise, we explore the next element z. If all candidates z have been explored unsuccessfully, we move to the next edge of s.G'. The first phase of this algorithm is clearly polynomial time in r(s.G'); the state update (as second phase) is clearly polynomial time in r(s.G).

Second, let  $p, v, w, z, c_v, c_w$  be as above. Let  $H = (V', V'_0, V'_1, E' \setminus \{(v, w)\}, c')$  be the game  $s.G'_{(v,w)}$ . We claim that  $\operatorname{Win}_{p'}[H] = \operatorname{Win}_{p'}[s.G']$  for all p' in  $\{0,1\}$ . Note that H is obtained by removing an edge from a node in s.G' that is owned by player p. Therefore, we have that  $\operatorname{Win}_{1-p}[s.G']$  is contained in  $\operatorname{Win}_{1-p}[H]$ . Since parity games are determined, it therefore suffices to show that  $\operatorname{Win}_p[s.G']$  is contained in  $\operatorname{Win}_p[H]$ . Let  $\tau$  be a strategy that is winning on  $\operatorname{Win}_p[s.G']$  in game s.G' for player p. We will use  $\tau$  and finite memory to construct a strategy  $\gamma$  that is winning for player p on  $\operatorname{Win}_p[s.G']$  in the parity game H – which has the same node set as s.G'.

**Case 1:** Assume that  $\tau(v) \neq w$ . Then we set  $\gamma = \tau$ . Consider any play that begins in  $\operatorname{Win}_p[s.G']$  and is conformant with  $\tau$ . By our assumption, this play is also one in s.G' and is conformant with  $\tau$ . Since  $\tau$  is winning on  $\operatorname{Win}_p[s.G']$  in s.G', we infer that this play is won by player p in H as well. Therefore, strategy  $\gamma$  is winning for player p on  $\operatorname{Win}_p[s.G']$  in H.

**Case 2:** Assume that  $\tau(v) = w$ . We define  $\gamma$  with finite memory as follows: Consider any finite play  $\delta = v_0 v_1 \dots v_n$  in H with  $v_n \in V_p$  such that v is not in  $\delta$ . Then  $\gamma(\delta) = \tau(v_n)$ . In other words, if v has not been encountered yet in a play,  $\gamma$  plays as  $\tau$  does. Otherwise, let  $\delta$  be such that  $v_n$  equals v and  $v \neq v_j$  for all  $0 \leq j < n$ . Then  $\gamma(\delta)$  will be the next node on the control path  $P_{vz}$ . In fact,  $\gamma$  will keep playing path  $P_{vz}$  as the next moves, extending  $\delta$  to  $\delta' = \delta v_{c_1} \dots v_{c_n}$  where  $P_{vz}$  equals  $v_{c_0}, \dots, v_{c_n}$  with  $c_{c_n} = z$ . Note that player 1 - p cannot avoid this extension from  $\delta$  to  $\delta'$ , since all nodes that she may own on that path are deterministic. Next, the behaviour of  $\gamma$  on  $\delta'$ , expression  $\gamma(\delta')$ , is defined as described above: it will play like  $\tau$  until and if it reaches v again, where it will play the control path  $P_{vz}$  again.

Let x be an arbitrary element in  $\operatorname{Win}_p[s.G']$  and let  $\pi$  be now any *infinite* play in H beginning in x and conformant with  $\gamma$ . We need to show that  $\pi$  is won by player p. Without loss of generality, we may assume that  $\pi$  is also conformant with a strategy  $\sigma$  for player 1 - p in H. Note that  $\pi$  does not necessarily define such a  $\sigma$  uniquely;  $\pi$  determines the output of  $\sigma$  for all finite prefixes of  $\pi$  that require moves of player 1 - p, and we can extend  $\sigma$  for other input in any which way. Since node v is not owned by player 1 - p, it is clear that the set of such strategies  $\sigma$  is the same for player 1 - p in s.G' and in H. Also note that  $\sigma$  may require finite memory, as the play  $\pi$  is any play conformant with  $\gamma$ . It remains to show that play  $\pi$  is won by player p.

We now define a strategy  $\sigma': (V')^* \cdot V'_{1-p} \to V'$  for player 1-p in game s.G' out of  $\sigma$  as follows: for all y in  $V_{1-p}$  with  $y \neq w$  and all  $\alpha$  in  $(V')^*$ , we set  $\sigma'(\alpha y) = \sigma(\alpha y)$ . For y = w, we distinguish two cases, for  $\alpha$  in  $(V')^*$ : If  $\alpha$  is of form  $\alpha' v$ , then we set  $\sigma'(\alpha' vw) = w_{c_1}$ , where  $w_{c_1}$  is the first next node on the control path  $P_{wz}$ ; and then  $\sigma'$  will follow that control path  $P_{wz}$  until it has reached z. Otherwise (when  $\alpha$  does not end in v, including the case in which  $\alpha$  is empty), we set  $\sigma'(\alpha w) = \sigma(w)$ . Let  $\pi'$  be the play that starts in the above x and is conformant with  $\tau$  and with  $\sigma'$  (this play is uniquely determined).

To summarize, we have an infinite play  $\pi$  in H conformant with  $\gamma$  and  $\sigma$ , and an infinite play  $\pi'$  in s.G' conformant with  $\tau$  and  $\sigma'$ , where both plays start at an element x in  $\operatorname{Win}_p[s.G']$ . Since  $\tau$  is winning for player p on  $\operatorname{Win}_p[s.G']$  in s.G', this means that

$$c_{\pi'} = \min(\ln f(\pi')) \text{ has parity } p \tag{4}$$

Let us now define

$$c_{\pi} = \min(\inf(\pi)) \tag{5}$$

If we can show that  $c_{\pi} \leq_p c_{\pi'}$ , then (4) and the definition of  $\leq_p$  imply that  $c_{\pi}$  has parity p. This will conclude the proof that  $\gamma$  is winning on  $\operatorname{Win}_p[s.G']$  in H, since  $\pi$  was an arbitrary play in that game starting at an arbitrary element of  $\operatorname{Win}_p[s.G']$  and conformant with  $\gamma$ .

We note that whenever the plays  $\pi$  and  $\pi'$  reach the node v, then both continue with the respective path  $P_{vz}$  (without its first element that has been already reached) and  $P_{wz}$ , respectively. For example, in Figure 5 path  $P_{vz}$  equals  $v_0, v_{16}, v_{21}, v_8$  and path  $P_{wz}$  equals  $v_{20}, v_{19}, v_8$ .

**Case 2.1:** Let v occur in  $\pi'$  infinitely often. Then v must occur also in  $\pi$  infinitely often. Since  $\tau(v) = w$ , this means that all nodes on  $P_{wz}$  occur in  $\pi'$  infinitely often as well. By the definition of  $\gamma$ , all nodes on  $P_{vz}$  occur in  $\pi$  infinitely often as node v occurs there infinitely often.

The smallest color of  $P_{vz}$  is  $c_v$ , whereas the smallest color of  $P_{wz}$  is  $c_w$ . Now, we know that  $c_v \leq_p c_w$ . Let  $c^*$  be the minimal color of the path  $v, P_{wz}$ . Note that  $c^*$  equals  $\min(c'(v), c_w)$  as the path is  $v, P_{wz}$  and  $c_w$  is the color of path  $P_{wz}$ . We claim that  $c_v \leq_p c^*$ :

- Let  $c_w \leq c'(v)$ . Then  $c^*$  equals  $c_w$  and so  $c_v \leq_p c^*$  follows from  $c_v \leq_p c_w$ .
- Otherwise, let  $c_w > c'(v)$ . Then  $c^*$  equals c'(v) and so it remains to show that  $c_v \leq_p c'(v)$ . Since v is on path  $P_{vz}$ , we infer that  $c'(v) \geq c_v$ . By transitivity, we get  $c_w > c_v$  from  $c_w > c'(v) \geq c_v$ . But then  $c_v \leq_p c_w$  implies that  $c_v$  has parity p by definition of  $\leq_p$ . To show  $c_v \leq_p c'(v)$  (=  $c^*$ ), we note that
  - if c'(v) has parity p, then  $c_v \leq_p c'(v)$  follows since  $c'(v) \geq c_v$  and  $c_v$  has parity p, and
  - if c'(v) has parity 1-p, then  $c_v \leq_p c'(v)$  follows since  $c_v$  has parity p.

It remains to consider nodes that occur infinitely often in either  $\pi$  or  $\pi'$  but neither on  $P_{vz}$  nor on  $P_{wz}$ . By the definition of  $\pi$  and  $\pi'$ , it is clear that such a node occur on  $\pi$  infinitely often if and only if it occur in  $\pi'$  infinitely often. To summarise, we have shown that for each c' in  $\mathsf{Inf}(\pi')$ there is some c in  $\mathsf{Inf}(\pi)$  such that  $c \leq_p c'$ . And this implies  $c_{\pi} \leq_p c_{\pi'}$  as desired.

**Case 2.2:** Let v not occur in  $\pi$  infinitely often. Then the plays  $\pi$  and  $\pi'$  are indistinguishable in s.G' and H and so  $c_{\pi} \leq_p c_{\pi'}$  is clearly the case. **QED.** 

## **B** Keiren's benchmarks

Keiren [17] proposed a comprehensive benchmark suite of parity games that come from four categories of problems. We downloaded the archive for these benchmarks containing the games under the bz2 format. We kept only those files under 200KB. We decompressed them and kept only the txt files under 200KB. This gave us a total of 481 games – respectively 93, 146, 169, 73 games in each category equivchecking, mlsolver, modelchecking, and pgsolver.

### B.1 List of solved games

Here are log entries of the games that were solved completely (all of them correctly as well) by  $ps_1$ :

#### B.1.1 equivchecking

ABP ABP(BW) (datasize=2 capacity=1 windowsize=1)eq=branching-bisim.gm ABP ABP(BW) (datasize=2 capacity=1 windowsize=1)eq=branching-sim.gm ABP ABP(BW) (datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_ABP(BW)\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm ABP\_ABP(BW)\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-bisim.gm ABP\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-sim.gm ABP\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm ABP ABP (datasize=4 capacity=1 windowsize=1)eq=strong-bisim.gm ABP(BW) ABP(BW) (datasize=2 capacity=1 windowsize=1)eq=strong-bisim.gm ABP(BW) ABP(BW) (datasize=4 capacity=1 windowsize=1)eq=strong-bisim.gm ABP(BW)\_CABP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW)\_CABP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW)\_Onebit\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW)\_Onebit\_(datasize=3\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW) Par (datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW)\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm ABP(BW) Par\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW)\_SWP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP(BW)\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_CABP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_CABP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_Onebit\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP Onebit (datasize=3 capacity=1 windowsize=1)eq=strong-bisim.gm ABP\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-bisim.gm ABP\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-sim.gm ABP\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm ABP\_Par\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_SWP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm ABP\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_ABP(BW) (datasize=2\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer\_ABP(BW) (datasize=2\_capacity=1\_windowsize=1)eq=branching-sim.gm Buffer\_ABP(BW)\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_ABP(BW)\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer\_ABP(BW)\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer\_ABP(BW) (datasize=4 capacity=1 windowsize=1)eq=branching-sim.gm Buffer\_ABP(BW)\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer ABP(BW) (datasize=4 capacity=1 windowsize=1)eq=weak-bisim.gm Buffer\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-sim.gm Buffer\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm

Buffer\_ABP\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer\_ABP\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer\_ABP\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-sim.gm Buffer\_ABP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_ABP\_(datasize=4\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer CABP (datasize=2 capacity=1 windowsize=1)eq=branching-bisim.gm Buffer CABP (datasize=2 capacity=1 windowsize=1)eq=branching-sim.gm Buffer\_CABP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer CABP (datasize=2 capacity=1 windowsize=1)eq=weak-bisim.gm Buffer\_CABP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_Onebit\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_Onebit\_(datasize=2\_capacity=2\_windowsize=1)eq=strong-bisim.gm Buffer\_Onebit\_(datasize=3\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_Onebit\_(datasize=3\_capacity=2\_windowsize=1)eq=strong-bisim.gm Buffer Par (datasize=2 capacity=1 windowsize=1)eq=branching-bisim.gm Buffer Par (datasize=2 capacity=1 windowsize=1)eq=branching-sim.gm Buffer Par (datasize=2 capacity=1 windowsize=1)eq=strong-bisim.gm Buffer\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer\_Par\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer\_Par\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-sim.gm Buffer Par (datasize=4 capacity=1 windowsize=1)eq=strong-bisim.gm Buffer\_Par\_(datasize=4\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer\_SWP\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer SWP (datasize=2 capacity=1 windowsize=1)eq=branching-sim.gm Buffer\_SWP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_SWP\_(datasize=2\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer\_SWP\_(datasize=2\_capacity=2\_windowsize=1)eq=branching-bisim.gm Buffer SWP (datasize=2\_capacity=2\_windowsize=1)eq=branching-sim.gm Buffer\_SWP\_(datasize=2\_capacity=2\_windowsize=1)eq=strong-bisim.gm Buffer\_SWP\_(datasize=2\_capacity=2\_windowsize=1)eq=weak-bisim.gm Buffer\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-bisim.gm Buffer\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=branching-sim.gm Buffer\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Buffer\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=weak-bisim.gm Buffer\_SWP\_(datasize=4\_capacity=2\_windowsize=1)eq=strong-bisim.gm CABP\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm CABP\_Par\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Hesselink\_(Implementation)\_Hesselink\_(Specification)\_(datasize=2)eq=strong-bisim.gm Hesselink\_(Implementation)\_Hesselink\_(Specification)\_(datasize=3)eq=strong-bisim.gm Hesselink\_(Specification)\_Hesselink\_(Implementation)\_(datasize=2)eq=strong-bisim.gm Hesselink\_(Specification)\_Hesselink\_(Implementation)\_(datasize=3)eq=strong-bisim.gm Par\_Onebit\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm Par\_Onebit\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm Par\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-bisim.gm Par\_Par\_(datasize=2\_capacity=1\_windowsize=1)eq=branching-sim.gm Par Par (datasize=2 capacity=1 windowsize=1)eq=strong-bisim.gm Par Par (datasize=2 capacity=1 windowsize=1)eg=weak-bisim.gm Par Par (datasize=4 capacity=1 windowsize=1)eq=strong-bisim.gm Par\_SWP\_(datasize=2\_capacity=1\_windowsize=1)eq=strong-bisim.gm Par\_SWP\_(datasize=4\_capacity=1\_windowsize=1)eq=strong-bisim.gm

#### B.1.2 mlsolver

CTLStarBinaryCountern=1\_compact.gm CTLStarBinaryCountern=1.gm CTLStarBinaryCountern=2\_compact.gm CTLStarBinaryCountern=2.gm CTLStarBinaryCountern=3\_compact.gm CTLStarBinaryCountern=3.gm CTLStarBinaryCountern=4\_compact.gm CTLStarBinaryCountern=4.gm CTLStarBinaryCountern=5\_compact.gm CTLStarBinaryCountern=5.gm CTLStarBinaryCountern=6\_compact.gm CTLStarBinaryCountern=7\_compact.gm CTLStarBinaryCountern=8\_compact.gm DemriKillerFormulan=1\_compact.gm DemriKillerFormulan=1.gm DemriKillerFormulan=2\_compact.gm FairSchedulern=1\_compact.gm FairSchedulern=1.gm FLCTLLimitClosuren=1\_compact.gm FLCTLLimitClosuren=1.gm FLCTLLimitClosuren=2\_compact.gm FLCTLLimitClosuren=2.gm FLCTLLimitClosuren=3\_compact.gm FLCTLLimitClosuren=3.gm FLCTLLimitClosuren=4\_compact.gm FLCTLLimitClosuren=5\_compact.gm Includen=1\_compact.gm Includen=1.gm Includen=2\_compact.gm Includen=2.gm Includen=3\_compact.gm Includen=3.gm Includen=4\_compact.gm Includen=4.gm Includen=5\_compact.gm Includen=5.gm Includen=6\_compact.gm Includen=6.gm Includen=7\_compact.gm Includen=7.gm Includen=8\_compact.gm Includen=8.gm LTMucalcBinaryCountern=1\_compact.gm LTMucalcBinaryCountern=1.gm LTMucalcBinaryCountern=2 compact.gm LTMucalcBinaryCountern=2.gm LTMucalcBinaryCountern=3\_compact.gm LTMucalcBinaryCountern=3.gm

```
LTMucalcBinaryCountern=4_compact.gm
LTMucalcBinaryCountern=4.gm
LTMucalcBinaryCountern=5_compact.gm
LTMucalcBinaryCountern=5.gm
LTMucalcBinaryCountern=6_compact.gm
LTMucalcBinaryCountern=6.gm
LTMucalcBinaryCountern=7_compact.gm
LTMucalcBinaryCountern=8_compact.gm
MuCalcLimitClosurephi=p n=0 compact.gm
MuCalcLimitClosurephi=p_n=0.gm
Nestern=1_compact.gm
Nestern=1.gm
Nestern=2_compact.gm
Nestern=2.gm
ParityAndBuechin=1_compact.gm
ParityAndBuechin=1.gm
ParityAndBuechin=2_compact.gm
ParityAndBuechin=2.gm
PDLBinaryCountern=1_compact.gm
PDLBinaryCountern=1.gm
PDLBinaryCountern=2 compact.gm
PDLBinaryCountern=2.gm
PDLBinaryCountern=3_compact.gm
PDLBinaryCountern=3.gm
PDLBinaryCountern=4_compact.gm
PDLBinaryCountern=4.gm
PDLBinaryCountern=5_compact.gm
PDLBinaryCountern=6_compact.gm
Petrin=1_compact.gm
Petrin=1.gm
Petrin=2_compact.gm
Petrin=2.gm
Petrin=3_compact.gm
Petrin=3.gm
Petrin=4_compact.gm
Petrin=4.gm
Petrin=5_compact.gm
Petrin=5.gm
Petrin=6_compact.gm
Petrin=6.gm
Petrin=7_compact.gm
Petrin=7.gm
Petrin=8_compact.gm
Petrin=8.gm
StarNesterk=1_n=1_compact.gm
StarNesterk=1_n=1.gm
StarNesterk=1_n=2_compact.gm
StarNesterk=1_n=2.gm
StarNesterk=1_n=3_compact.gm
StarNesterk=1_n=3.gm
```

StarNesterk=1\_n=4\_compact.gm StarNesterk=1\_n=4.gm StarNesterk=1\_n=5\_compact.gm StarNesterk=1\_n=5.gm StarNesterk=1\_n=6\_compact.gm StarNesterk=1 n=6.gm StarNesterk=1\_n=7\_compact.gm StarNesterk=1\_n=7.gm StarNesterk=1\_n=8\_compact.gm StarNesterk=1\_n=8.gm StarNesterk=2\_n=1\_compact.gm StarNesterk=2\_n=1.gm  $StarNesterk=2_n=2_compact.gm$ StarNesterk=2\_n=2.gm StarNesterk=2\_n=3\_compact.gm StarNesterk=2\_n=3.gm StarNesterk=2\_n=4\_compact.gm StarNesterk=2\_n=4.gm StarNesterk=2\_n=5\_compact.gm StarNesterk=2\_n=5.gm StarNesterk=2\_n=6\_compact.gm StarNesterk=2\_n=6.gm StarNesterk=2\_n=7\_compact.gm  $StarNesterk=2_n=7.gm$ StarNesterk=2\_n=8\_compact.gm StarNesterk=2\_n=8.gm StarNesterk=3\_n=1\_compact.gm StarNesterk=3\_n=1.gm StarNesterk=3\_n=2\_compact.gm StarNesterk=3\_n=2.gm StarNesterk=3\_n=3\_compact.gm StarNesterk=3\_n=3.gm StarNesterk=3\_n=4\_compact.gm StarNesterk=3\_n=4.gm StarNesterk=3\_n=5\_compact.gm StarNesterk=3\_n=5.gm StarNesterk=3\_n=6\_compact.gm StarNesterk=3\_n=6.gm StarNesterk=3\_n=7\_compact.gm StarNesterk=3\_n=7.gm StarNesterk=3\_n=8\_compact.gm StarNesterk=3\_n=8.gm

#### B.1.3 modelchecking

```
ABP(BW)datasize=2_infinitely_often_enabled_then_infinitely_often_taken.gm
ABP(BW)datasize=2_infinitely_often_read_write.gm
ABP(BW)datasize=2_infinitely_often_receive_d1.gm
ABP(BW)datasize=2_infinitely_often_receive_for_all_d.gm
ABP(BW)datasize=2_invariantly_infinitely_many_reachable_taus.gm
```

ABP(BW)datasize=2\_nodeadlock.gm ABP(BW)datasize=2\_no\_duplication\_of\_messages.gm ABP(BW)datasize=2\_no\_generation\_of\_messages.gm ABP(BW)datasize=2\_read\_then\_eventually\_send.gm ABP(BW)datasize=4\_infinitely\_often\_enabled\_then\_infinitely\_often\_taken.gm ABP(BW)datasize=4 infinitely often read write.gm ABP(BW)datasize=4\_infinitely\_often\_receive\_d1.gm ABP(BW)datasize=4\_infinitely\_often\_receive\_for\_all\_d.gm ABP(BW)datasize=4\_invariantly\_infinitely\_many\_reachable\_taus.gm ABP(BW)datasize=4\_nodeadlock.gm ABP(BW)datasize=4\_no\_duplication\_of\_messages.gm ABP(BW)datasize=4\_no\_generation\_of\_messages.gm ABP(BW)datasize=4\_read\_then\_eventually\_send.gm ABP(BW)datasize=8\_infinitely\_often\_read\_write.gm ABP(BW)datasize=8\_infinitely\_often\_receive\_d1.gm ABP(BW)datasize=8\_infinitely\_often\_receive\_for\_all\_d.gm ABP(BW)datasize=8 invariantly infinitely many reachable taus.gm ABP(BW)datasize=8\_nodeadlock.gm ABP(BW)datasize=8\_no\_duplication\_of\_messages.gm ABP(BW)datasize=8\_no\_generation\_of\_messages.gm ABP(BW)datasize=8 read then eventually send.gm ABPdatasize=2\_infinitely\_often\_enabled\_then\_infinitely\_often\_taken.gm ABPdatasize=2\_infinitely\_often\_lost.gm ABPdatasize=2\_infinitely\_often\_read\_write.gm ABPdatasize=2\_infinitely\_often\_receive\_d1.gm ABPdatasize=2\_infinitely\_often\_receive\_for\_all\_d.gm ABPdatasize=2\_invariantly\_infinitely\_many\_reachable\_taus.gm ABPdatasize=2\_nodeadlock.gm ABPdatasize=2\_no\_duplication\_of\_messages.gm ABPdatasize=2\_no\_generation\_of\_messages.gm ABPdatasize=2\_read\_then\_eventually\_send.gm ABPdatasize=2\_read\_then\_eventually\_send\_if\_fair.gm ABPdatasize=4\_infinitely\_often\_enabled\_then\_infinitely\_often\_taken.gm ABPdatasize=4\_infinitely\_often\_lost.gm ABPdatasize=4\_infinitely\_often\_read\_write.gm ABPdatasize=4\_infinitely\_often\_receive\_d1.gm ABPdatasize=4\_infinitely\_often\_receive\_for\_all\_d.gm ABPdatasize=4\_invariantly\_infinitely\_many\_reachable\_taus.gm ABPdatasize=4 nodeadlock.gm ABPdatasize=4\_no\_duplication\_of\_messages.gm ABPdatasize=4\_no\_generation\_of\_messages.gm ABPdatasize=4\_read\_then\_eventually\_send.gm ABPdatasize=4\_read\_then\_eventually\_send\_if\_fair.gm ABPdatasize=8\_infinitely\_often\_enabled\_then\_infinitely\_often\_taken.gm ABPdatasize=8\_infinitely\_often\_lost.gm ABPdatasize=8\_infinitely\_often\_read\_write.gm ABPdatasize=8\_infinitely\_often\_receive\_d1.gm ABPdatasize=8\_infinitely\_often\_receive\_for\_all\_d.gm ABPdatasize=8\_invariantly\_infinitely\_many\_reachable\_taus.gm ABPdatasize=8\_nodeadlock.gm

```
ABPdatasize=8_no_duplication_of_messages.gm
ABPdatasize=8_no_generation_of_messages.gm
ABPdatasize=8_read_then_eventually_send.gm
ABPdatasize=8_read_then_eventually_send_if_fair.gm
BRPdatasize=2_nodeadlock.gm
CABPdatasize=2 infinitely often enabled then infinitely often taken.gm
CABPdatasize=2_infinitely_often_read_write.gm
CABPdatasize=2_infinitely_often_receive_d1.gm
CABPdatasize=2 infinitely often receive for all d.gm
CABPdatasize=2_invariantly_infinitely_many_reachable_taus.gm
CABPdatasize=2 nodeadlock.gm
CABPdatasize=2_no_duplication_of_messages.gm
CABPdatasize=2_no_generation_of_messages.gm
CABPdatasize=2_read_then_eventually_send.gm
CABPdatasize=4_infinitely_often_receive_d1.gm
CABPdatasize=4_infinitely_often_receive_for_all_d.gm
CABPdatasize=4_invariantly_infinitely_many_reachable_taus.gm
CABPdatasize=4_nodeadlock.gm
CABPdatasize=4_no_duplication_of_messages.gm
CABPdatasize=4_no_generation_of_messages.gm
CABPdatasize=4 read then eventually send.gm
CABPdatasize=8_infinitely_often_receive_d1.gm
CABPdatasize=8_nodeadlock.gm
CCP 3.2. max copies per region.gm
Debug_spec_nodeadlock.gm
Domineeringwidth=4_height=4_player1_has_winning_strategy.gm
Domineeringwidth=4_height=4_player2_has_winning_strategy.gm
Elevatorpolicy=FIFO storeys=2 always if max floor requested eventually at max floor.gm
Elevatorpolicy=FIFO storeys=3 always if max floor requested eventually at max floor.gm
Elevatorpolicy=FIFO storeys=4 always if max floor requested eventually at max floor.gm
Elevatorpolicy=FIFO storeys=5 always if max floor requested eventually at max floor.gm
Elevatorpolicy=FIFO storeys=6 always if max floor requested eventually at max floor.gm
Elevatorpolicy=FIFO storeys=7 always if max floor requested eventually at max floor.gm
Elevatorpolicy=FIFO storeys=8 always if max floor requested eventually at max floor.gm
Elevatorpolicy=LIF0_storeys=2_always_if_max_floor_requested_eventually_at_max_floor.gm
Elevatorpolicy=LIF0_storeys=3_always_if_max_floor_requested_eventually_at_max_floor.gm
Elevatorpolicy=LIF0_storeys=4_always_if_max_floor_requested_eventually_at_max_floor.gm
Elevatorpolicy=LIF0_storeys=5_always_if_max_floor_requested_eventually_at_max_floor.gm
Hanoindisks=8 eventually done.gm
Leadernparticipants=3_eventually-stable.gm
Lift_(Correct)nlifts=2_liveness_1_1.gm
Lift_(Correct)nlifts=2_liveness_1_2.gm
Lift_(Correct)nlifts=2_liveness_2_1.gm
Lift_(Correct)nlifts=2_liveness_2_2.gm
Lift_(Correct)nlifts=2_nodeadlock.gm
Lift_(Correct)nlifts=2_safety_1.gm
Lift_(Correct)nlifts=2_safety_2_1.gm
Lift_(Correct)nlifts=2_safety_2_2.gm
Lift_(Correct)nlifts=3_liveness_2_1.gm
Lift_(Correct)nlifts=3_liveness_2_2.gm
```

```
Lift_(Correct)nlifts=3_nodeadlock.gm
Lift_(Correct)nlifts=3_safety_1.gm
Lift_(Correct)nlifts=3_safety_2_1.gm
Lift_(Correct)nlifts=3_safety_2_2.gm
Lift_(Incorrect)nlifts=2_liveness_1_1.gm
Lift (Incorrect)nlifts=2 liveness 1 2.gm
Lift_(Incorrect)nlifts=2_liveness_2_1.gm
Lift_(Incorrect)nlifts=2_liveness_2_2.gm
Lift (Incorrect)nlifts=2 nodeadlock.gm
Lift_(Incorrect)nlifts=2_safety_1.gm
Lift_(Incorrect)nlifts=2_safety_2_1.gm
Lift_(Incorrect)nlifts=2_safety_2_2.gm
Pardatasize=2 infinitely often enabled then infinitely often taken.gm
Pardatasize=2_infinitely_often_read_write.gm
Pardatasize=2_infinitely_often_receive_d1.gm
Pardatasize=2_infinitely_often_receive_for_all_d.gm
Pardatasize=2_invariantly_infinitely_many_reachable_taus.gm
Pardatasize=2_nodeadlock.gm
Pardatasize=2_no_duplication_of_messages.gm
Pardatasize=2_no_generation_of_messages.gm
Pardatasize=2 read then eventually send.gm
Pardatasize=4_infinitely_often_enabled_then_infinitely_often_taken.gm
Pardatasize=4_infinitely_often_read_write.gm
Pardatasize=4_infinitely_often_receive_d1.gm
Pardatasize=4_infinitely_often_receive_for_all_d.gm
Pardatasize=4_invariantly_infinitely_many_reachable_taus.gm
Pardatasize=4_nodeadlock.gm
Pardatasize=4_no_duplication_of_messages.gm
Pardatasize=4_no_generation_of_messages.gm
Pardatasize=4_read_then_eventually_send.gm
Pardatasize=8_infinitely_often_read_write.gm
Pardatasize=8_infinitely_often_receive_d1.gm
Pardatasize=8_infinitely_often_receive_for_all_d.gm
Pardatasize=8_invariantly_infinitely_many_reachable_taus.gm
Pardatasize=8_nodeadlock.gm
Pardatasize=8_no_duplication_of_messages.gm
Pardatasize=8_no_generation_of_messages.gm
Pardatasize=8_read_then_eventually_send.gm
Snakewidth=4_height=4_black_has_winning_strategy.gm
Snakewidth=4_height=4_white_has_winning_strategy.gm
SWPdatasize=2_windowsize=1_infinitely_often_enabled_then_infinitely_often_taken.gm
SWPdatasize=2_windowsize=1_infinitely_often_lost.gm
SWPdatasize=2_windowsize=1_infinitely_often_read_write.gm
SWPdatasize=2_windowsize=1_infinitely_often_receive_d1.gm
SWPdatasize=2 windowsize=1 infinitely often receive for all d.gm
SWPdatasize=2 windowsize=1 invariantly infinitely many reachable taus.gm
SWPdatasize=2_windowsize=1_nodeadlock.gm
SWPdatasize=2_windowsize=1_no_duplication_of_messages.gm
SWPdatasize=2_windowsize=1_no_generation_of_messages.gm
SWPdatasize=2_windowsize=1_read_then_eventually_send.gm
```

```
SWPdatasize=2_windowsize=1_read_then_eventually_send_if_fair.gm
SWPdatasize=2_windowsize=2_no_generation_of_messages.gm
SWPdatasize=4_windowsize=1_infinitely_often_lost.gm
SWPdatasize=4_windowsize=1_infinitely_often_receive_d1.gm
SWPdatasize=4_windowsize=1_infinitely_often_receive_for_all_d.gm
SWPdatasize=4_windowsize=1_invariantly_infinitely_many_reachable_taus.gm
SWPdatasize=4_windowsize=1_nodeadlock.gm
SWPdatasize=4_windowsize=1_no_generation_of_messages.gm
SWPdatasize=8_windowsize=1_read_then_eventually_send_if_fair.gm
SWPdatasize=8_windowsize=1_nodeadlock.gm
```

#### B.1.4 pgsolver

```
cliquegame(100).gm
cliquegame(200).gm
elevatorverification(3).gm
elevatorverification(4).gm
elevatorverification(-u,_3).gm
elevatorverification(-u,_4).gm
laddergame(1000).gm
laddergame(100).gm
laddergame(2000).gm
laddergame(200).gm
laddergame(500).gm
modelcheckerladder(100).gm
modelcheckerladder(200).gm
randomgame(1000,_10,_1,_20)id=0.gm
randomgame(1000,_10,_1,_20)id=10.gm
randomgame(1000,_10,_1,_20)id=11.gm
randomgame(1000,_10,_1,_20)id=12.gm
randomgame(1000,_10,_1,_20)id=13.gm
randomgame(1000, 10, 1, 20)id=14.gm
randomgame(1000,_10,_1,_20)id=15.gm
randomgame(1000, 10, 1, 20)id=16.gm
randomgame(1000, 10, 1, 20)id=17.gm
randomgame(1000,_10,_1,_20)id=18.gm
randomgame(1000,_10,_1,_20)id=19.gm
randomgame(1000, 10, 1, 20) id=1.gm
randomgame(1000, 10, 1, 20) id=20.gm
randomgame(1000, 10, 1, 20) id=21.gm
randomgame(1000, 10, 1, 20) id=22.gm
randomgame(1000, 10, 1, 20)id=23.gm
randomgame(1000, 10, 1, 20)id=24.gm
randomgame(1000,_10,_1,_20)id=2.gm
randomgame(1000, 10, 1, 20) id=3.gm
randomgame(1000,_10,_1,_20)id=4.gm
randomgame(1000, 10, 1, 20)id=5.gm
randomgame(1000,_10,_1,_20)id=6.gm
randomgame(1000, 10, 1, 20)id=7.gm
```

```
randomgame(1000, 10, 1, 20)id=8.gm
randomgame(1000, 10, 1, 20)id=9.gm
steadygame(1000,_1,_20,_1,_20)id=0.gm
steadygame(1000,_1,_20,_1,_20)id=10.gm
steadygame(1000, 1, 20, 1, 20) id=11.gm
steadygame(1000,_1,_20,_1,_20)id=12.gm
steadygame(1000,_1,_20,_1,_20)id=13.gm
steadygame(1000,_1,_20,_1,_20)id=14.gm
steadygame(1000,_1,_20,_1,_20)id=15.gm
steadygame(1000, 1, 20, 1, 20) id=16.gm
steadygame(1000,_1,_20,_1,_20)id=17.gm
steadygame(1000,_1,_20,_1,_20)id=18.gm
steadygame(1000,_1,_20,_1,_20)id=19.gm
steadygame(1000,_1,_20,_1,_20)id=1.gm
steadygame(1000, 1, 20, 1, 20)id=20.gm
steadygame(1000,_1,_20,_1,_20)id=21.gm
steadygame(1000, 1, 20, 1, 20)id=22.gm
steadygame(1000,_1,_20,_1,_20)id=23.gm
steadygame(1000,_1,_20,_1,_20)id=24.gm
steadygame(1000,_1,_20,_1,_20)id=2.gm
steadygame(1000,_1,_20,_1,_20)id=3.gm
steadygame(1000,_1,_20,_1,_20)id=4.gm
steadygame(1000,_1,_20,_1,_20)id=5.gm
steadygame(1000,_1,_20,_1,_20)id=6.gm
steadygame(1000, 1, 20, 1, 20) id=7.gm
steadygame(1000,_1,_20,_1,_20)id=8.gm
steadygame(1000,_1,_20,_1,_20)id=9.gm
towersofhanoi(5).gm
towersofhanoi(6).gm
```

There were PGSolver games within Keiren's benchmark suite where the latter only contained instances whose textual description was over 200KB. Therefore, we generated smaller such games with PGSolver directly. Here is the list of such games that  $ps_1$  could solve completely within 60 seconds:

```
clustered1000_200_2_5_3_4_6_11_22.gm
clustered100_200_2_5_3_4_6_11_22.gm
clustered200_200_2_5_3_4_6_11_22.gm
clustered300_200_2_5_3_4_6_11_22.gm
clustered400_200_2_5_3_4_6_11_22.gm
jurd10_40.gm
jurd10_50.gm
jurd10_50.gm
recursiveladder100.gm
recursiveladder110.gm
recursiveladder120.gm
recursiveladder90.gm
```

### B.2 Games that raised an exception

For sake of completeness, we also report the games for which either  $ps_1$  or our implementation of Zielonka's algorithm raised an exception (stack overflow or 60 second timeout). The names of games are followed by expressions that indicate whether  $ps_1$  raised a timeout (pt), Zielonka's algorithm raised a timeout (zt),  $ps_1$  had a stack overflow of recursive calls (pr) or whether Zielonka's algorithm had a stack overflow of recursive calls (zr):

#### B.2.1 mlsolver

```
FLCTLStarSimpleLimitClosuren=1_compact.gm pt
FLCTLStarSimpleLimitClosuren=2_compact.gm pt
Nestern=3_compact.gm pt
Nestern=4_compact.gm pt
ParityAndBuechin=3_compact.gm pt
```

#### B.2.2 modelchecking

ABPdatasize=4\_infinitely\_often\_read\_write.gm pt CABPdatasize=8\_infinitely\_often\_read\_write.gm pt SWPdatasize=4\_windowsize=1\_infinitely\_often\_read\_write.gm pt

#### B.2.3 pgsolver

```
jurdzinskigame(50,_50).gm zt pr
modelcheckerladder(1000).gm pr
modelcheckerladder(2000).gm pr
modelcheckerladder(500).gm pr
recursiveladder(1000).gm zr pr
recursiveladder(100).gm zt
recursiveladder(200).gm zt
recursiveladder(500).gm zr pr
```

# **C** Experimental data for $lift(ps_5)$

The results for our experiments with  $lift(ps_5)$  are shown in Figure 6. The left of each row in that figure shows the configuration type, Time shows how long the tests were running in seconds<sup>2</sup>, Total lists how many games were run, Res shows the number of residual games for  $ps_5$ , and Lift shows the number of residual games for lift( $ps_5$ ) This shows several billion random games of varying configurations with node sizes ranging from 40 to 1000. All of these games were solved completely by lift( $ps_5$ ); specifically, we first ran  $ps_5$  on these games and invoked lift( $ps_5$ ) only on the non-empty residual games of  $ps_5$ , of which there were only thousands of games. This staging is justified as  $ps_5$  is part of the interaction within lift( $ps_5$ ) = while( $ps_5$ , lifted( $ps_5$ )).

 $<sup>^{2}</sup>$ This measure is only indicative as the experiment was run in Python processes distributed across standard machines running Ubuntu in our student laboratories.

1000-300-2-4 :	Time = 2608895	Total = 3529605	Res = 0	Lift = 0
200-50-1-2 :	Time = 943643	Total = 1811520	Res = 119	Lift = 0
200-50-1-3 :	Time = 943706	Total = 2203378	Res = 199	Lift = 0
200-50-2-2 :	Time = 1044005	Total = 360691	Res = 655	Lift = 0
200-50-2-3 :	Time = 943746	Total = 1498422	Res = 349	Lift = 0
200-50-2-4 :	Time = 943788	Total = 22164662	Res = 202	Lift = 0
200-50-3-4 :	Time = 426389	Total = 36560774	Res = 15	Lift = 0
200-50-3-5 :	Time = 426336	Total = 43919554	Res = 0	Lift = 0
200-50-4-5 :	Time = 426280	Total = 45220307	Res = 0	Lift = 0
200-50-4-6 :	Time = 426254	Total = 49159218	Res = 0	Lift = 0
30-15-2-4 :	Time = 2846321	Total = 3641298950	Res = 2757	Lift = 0
40-20-2-2 :	Time = 1043808	Total = 447285259	Res = 3469	Lift = 0
40-20-2-4 :	Time = 2846303	Total = 1970608294	Res = 4056	Lift = 0
500-50-2-3 :	Time = 425916	Total = 90187	Res = 23	Lift = 0
500-50-2-4 :	Time = 425984	Total = 5369797	Res = 11	Lift = 0
500-50-3-5 :	Time = 426016	Total = 10364935	Res = 0	Lift = 0
500-50-4-6 :	Time = 426051	Total = 10806672	Res = 0	Lift = 0
50-25-2-2 :	Time = 1043864	Total = 219359597	Res = 4509	Lift = 0
50-25-2-4 :	Time = 2846288	Total = 1157521639	Res = 4486	Lift = 0
55-27-2-4 :	Time = 2846233	Total = 886941637	Res = 4157	Lift = 0
60-25-2-2 :	Time = 788790	Total = 90189308	Res = 3760	Lift = 0
60-30-2-4 :	Time = 2846261	Total = 707252484	Res = 4062	Lift = 0

Figure 6: Experimental results from the search for non-empty residual games for partial solvers  $ps_5$  and  $lift(ps_5)$