# **Dynamical Systems**

# Continuous maps of metric spaces

- ► We work with metric spaces, usually a subset of ℝ<sup>n</sup> with the Euclidean norm.
- A map of metric spaces *F* : *X* → *Y* is continuous at *x* ∈ *X* if it preserves the limits of convergent sequences, i.e., for all sequences (*x<sub>n</sub>*)<sub>*n*≥0</sub> in *X*:

$$x_n \rightarrow x \Rightarrow F(x_n) \rightarrow F(x).$$

- F is **continuous** if it is continuous at all  $x \in X$ .
- Examples:
  - All polynomials,  $\sin x$ ,  $\cos x$ ,  $e^x$  are continuous maps.
  - x → 1/x : ℝ → ℝ is not continuous at x = 0 no matter what value we give to 1/0. Similarly for tan x at x = (n + ½)π for any integer n.
  - The step function s : ℝ → ℝ : x → 0 if x ≤ 0 and 1 otherwise, is not continuous at 0.
  - Intuitively, a map ℝ → ℝ is continuous iff its graph can be drawn with a pen without leaving the paper.

### Continuity and Computability

- Continuity of F is necessary for the computability of F.
- Here is a simple argument for  $F : \mathbb{R} \to \mathbb{R}$  to illustrate this.
- An irrational number like π has an infinite decimal expansion and is computable only as the limit of an effective sequence of rationals (x<sub>n</sub>)<sub>n≥0</sub> with say x<sub>0</sub> = 3, x<sub>1</sub> = 3.1, x<sub>2</sub> = 3.14 ···.
- ► Hence to compute  $F(\pi)$  our only hope is to compute  $F(x_n)$  for each rational  $x_n$  and then take the limit. This requires  $F(x_n) \rightarrow F(\pi)$  as  $n \rightarrow \infty$ .

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### Discrete dynamical systems

- A deterministic discrete dynamical system F : X → X is the action of a continuous map F on a metric space (X, d), usually a subset of ℝ<sup>n</sup>.
- X is the set of states of the system; and d measures the distance between states.
- If  $x \in X$  is the state at time *t*, then F(x) is the state at t + 1.
- We assume *F* does not depend on *t*.
- ► Here are some key continuous maps giving rise to interesting dynamical systems in ℝ<sup>n</sup>:
- ▶ Linear maps  $\mathbb{R}^n \to \mathbb{R}^n$ , eg  $x \mapsto ax : \mathbb{R} \to \mathbb{R}$  for any  $a \in \mathbb{R}$ .
- Quadratic family  $F_c : \mathbb{R} \to \mathbb{R} : x \mapsto cx(1-x)$  for  $c \in [1, 4]$ .
- We give two simple applications of linear maps here and will study the quadratic family later on in the course.

### In Finance

Suppose we deposit 1,000 in a bank at 10% interest. If we leave this money untouched for *n* years, how much money will we have in our account at the end of this period?

Example (Money in the Bank)

$$A_0 = 1000,$$
  
 $A_1 = A_0 + 0.1A_0 = 1.1A_0,$   
 $\vdots$   
 $A_n = A_{n-1} + 0.1A_{n-1} = 1.1A_{n-1}.$ 

This linear map is one of the simplest examples of an **iterative process** or discrete dynamical system.  $A_n = 1.1A_{n-1}$  is a 1st order **difference equation**. In this case, the function we iterate is  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = 1.1x.

# In Ecology

Let  $P_n$  denote the population alive at generation n. Can we predict what will happen to  $P_n$  as n gets large? Extinction, population explosion, etc.?

### Example (Exponential growth model)

Assume that the population in the succeeding generation is directly proportional to the population in the current generation:

$$P_{n+1} = rP_n,$$

where *r* is some constant determined by ecological conditions. We determine the behaviour of the system via iteration. In this case, the function we iterate is the function  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = rx.

### Iteration

► Given a function F : X → X and an initial value x<sub>0</sub>, what ultimately happens to the sequence of iterates

 $x_0, F(x_0), F(F(x_0)), F(F(F(x_0))), \ldots$ 

We shall use the notation

$$F^{(2)}(x) = F(F(x)), F^{(3)}(x) = F(F(F(x))), \dots$$

For simplicity, when there is no ambiguity, we drop the brackets in the exponent and write

$$F^n(x) := F^{(n)}(x).$$

Thus our goal is to describe the asymptotic behaviour of the iteration of the function *F*, i.e. the behaviour of *F<sup>n</sup>(x<sub>0</sub>)* as *n* → ∞ for various initial points *x<sub>0</sub>*.

### Orbits

### Definition

Given  $x_0 \in X$ , we define the **orbit of**  $x_0$  **under** *F* to be the sequence of points

$$x_0 = F^0(x_0), x_1 = F(x_0), x_2 = F^2(x_0), \dots, x_n = F^n(x_0), \dots$$

The point  $x_0$  is called the **initial point** of the orbit.

#### Example

If  $F(x) = \sin(x)$ , the orbit of  $x_0 = 123$  is

$$x_0 = 123, x_1 = -0.4599..., x_2 = -0.4439...,$$

 $x_3 = -0.4294..., \dots, x_{1000} = -0.0543..., x_{1001} = -0.0543..., \dots$ 

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## **Finite Orbits**

• A fixed point is a point  $x_0$  that satisfies  $F(x_0) = x_0$ .



- ▶ **Example:**  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = 4x(1 x) has two fixed points at x = 0 and x = 3/4.
- ► The point x<sub>0</sub> is **periodic** if F<sup>n</sup>(x<sub>0</sub>) = x<sub>0</sub> for some n > 0. The least such n is called the **period** of the orbit. Such an orbit is a repeating sequence of numbers.
- ▶ **Example:**  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = -x has periodic points of period n = 2 for all  $x \neq 0$ .
- A point x<sub>0</sub> is called eventually fixed or eventually periodic if x<sub>0</sub> itself is not fixed or periodic, but some point on the orbit of x<sub>0</sub> is fixed or periodic.
- For the map  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = 4x(1 x), the point x = 1 is eventually fixed since F(1) = 0, F(0) = 0.

# Attracting and Repelling Fixed or Periodic Points

- A fixed point x<sub>0</sub> is **attracting** if the orbit of any nearby point converges to x<sub>0</sub>.
- The basin of attraction of x<sub>0</sub> is the set of all points whose orbits converge to x<sub>0</sub>. The basin can contain points very far from x<sub>0</sub> as well as nearby points.
- ▶ **Example:** Take  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = x/2. Then 0 is an attracting fixed point with basin of attraction  $\mathbb{R}$ .
- A fixed point x<sub>0</sub> is **repelling** if the orbit of any nearby point runs away from x<sub>0</sub>.
- ▶ **Example:** Take  $F : \mathbb{R} \to \mathbb{R}$  with F(x) = 2x. Then 0 is a repelling fixed point.



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# Attracting/Repelling hyperbolic Fixed/Periodic Points

- If f : ℝ → ℝ has continuous derivative f', then a fixed point x<sub>0</sub> is attracting if |f'(x<sub>0</sub>)| < 1. If |f'(x<sub>0</sub>)| > 1, then x<sub>0</sub> is repelling. In both cases we say x<sub>0</sub> is hyperbolic.
- If x₀ is a fixed point of f and |f'(x₀)| = 1 then further analysis is required (eg Taylor series expansion near x₀) to determine the type of x₀, which can also be attracting in one direction and repelling in the other.



- If x₀ is a periodic point of period n, then x₀ is attracting and hyperbolic, if |(f<sup>n</sup>)'(x₀)| < 1.</p>
- Similarly,  $x_0$  is **repelling** and **hyperbolic**, if  $|(f^n)'(x_0)| > 1$ .

# **Graphical Analysis**

Given the graph of a function F we plot the orbit of a point  $x_0$ .

- First, superimpose the diagonal line y = x on the graph. (The points of intersection are the fixed points of F.)
- ▶ Begin at (x<sub>0</sub>, x<sub>0</sub>) on the diagonal. Draw a vertical line to the graph of *F*, meeting it at (x<sub>0</sub>, *F*(x<sub>0</sub>)).
- From this point draw a horizontal line to the diagonal finishing at  $(F(x_0), F(x_0))$ . This gives us  $F(x_0)$ , the next point on the orbit of  $x_0$ .
- Draw another vertical line to graph of *F*, intersecting it at F<sup>2</sup>(x<sub>0</sub>)).
- ► From this point draw a horizontal line to the diagonal meeting it at (F<sup>2</sup>(x<sub>0</sub>), F<sup>2</sup>(x<sub>0</sub>)).
- This gives us  $F^2(x_0)$ , the next point on the orbit of  $x_0$ .
- Continue this procedure, known as graphical analysis. The resulting "staircase" visualises the orbit of x<sub>0</sub>.

### Graphical analysis of linear maps



Figure : Graphical analysis of  $x \mapsto ax$  for various ranges of  $a \in \mathbb{R}$ .

# A Non-linear Example: $F(x) = \cos x$

- ► *F* has a single fixed point, which is attracting, as depicted.
- What is the basin of attraction of this attracting fixed point?



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## Phase portrait

- When graphical analysis describes the behaviour of all orbits of a dynamical system, we have performed a complete orbit analysis providing the phase portrait of the system.
- **Example:** Orbit analysis/phase portrait of  $x \mapsto x^3$ .



What are the fixed points and the basin of the attracting fixed point?

### Phase portraits of linear maps





Figure : Graphical analysis of  $x \mapsto ax$ 

# Bifurcation

- Consider the one-parameter family of quadratic maps x → x<sup>2</sup> + d where d ∈ ℝ.
- For d > 1/4, no fixed points and all orbits tend to  $\infty$ .
- For d = 1/4, a fixed point at x = 1/2, the double root of  $x^2 + 1/4 = x$ .
- ► This fixed point is locally attracting on the left x < 1/2 and repelling on the right x > 1/2.
- For *d* just less than 1/4, two fixed points x<sub>1</sub> < x<sub>2</sub>, with x<sub>1</sub> attracting and x<sub>2</sub> repelling.
- The family  $x \mapsto x^2 + d$  undergoes **bifurcation** at d = 1/4.

