A differential operator and weak topology for Lipschitz maps

Abbas Edalat
Department of Computing
Imperial College London, UK
ae@doc.ic.ac.uk

February 25, 2010

Abstract

We show that the Scott topology induces a topology for real-valued Lipschitz maps on Banach spaces which we call the L-topology. It is the weakest topology with respect to which the L-derivative operator, as a second order functional which maps the space of Lipschitz functions into the function space of non-empty weak* compact and convex valued maps equipped with the Scott topology, is continuous. For finite dimensional Euclidean spaces, where the L-derivative and the Clarke gradient coincide, we provide a simple characterization of the basic open subsets of the L-topology. We use this to verify that the L-topology is strictly coarser than the well-known Lipschitz norm topology. A complete metric on Lipschitz maps is constructed that is induced by the Hausdorff distance, providing a topology that is strictly finer than the L-topology but strictly coarser than the Lipschitz norm topology. We then develop a fundamental theorem of calculus of second order in finite dimensions showing that the continuous integral operator from the continuous Scott domain of non-empty convex and compact valued functions to the continuous Scott domain of ties is inverse to the continuous operator induced by the L-derivative. We finally show that in dimension one the L-derivative operator is a computable functional.

Key Words: Domain theory, Clarke gradient, Weakest topology, Second order functionals, Hausdorff metric, Fundamental Theorem of Calculus.

Mathematical subject codes: 03D80, 26A24, 06B35, 54E55.

1 The case for Lipschitz maps in computation

Real-valued Lipschitz maps on Euclidean spaces have a number of fundamental properties that make them into a suitable class of functions in a variety of contexts with wide applications in pure and applied mathematics. For these, they are the appropriate choice of functions in many different areas of computation.

Closed under composition and sitting between the class of continuous functions and those of continuously differentiable functions, Lipschitz maps contain the important class of piecewise polynomial functions, which are widely used in geometric modelling, approximation and interpolation and are supported in Mat-Lab [10]. They are uniformly continuous and have much better invariant properties than differentiable maps as they are closed under the fundamental min and max operations. Lipschitz maps with uniformly bounded Lipschitz constants are also closed under convergence with respect to the sup norm. In the theory and application of ordinary differential equations, Lipschitz maps represent the most fundamental class of maps in view of their basic and essentially unrivalled property that a Lipschitz vector field in \mathbb{R}^n has a unique solution in the initial value problem [9].

In a more theoretical direction, Lipschitz maps are, by Rademacher's theorem, differentiable almost everywhere on finite dimensional Euclidean spaces [8, page 148], and by Kirszbraun's theorem [27, page 202], enjoy the desirable property that they can be extended from any subset of a Hilbert space to the whole space with the same Lipschitz constant. Lipschitz maps are at the very foundation of non-linear functional analysis [2] and have been the subject of a hugely growing research in the theory of manifolds including Riemannian surfaces at the forefront of development of mathematics in relation to theoretical physics [6].

In the past quarter of a century, a new notion of derivative for Lipschitz maps has emerged that extends the classical (Fréchet) derivative for continuously differentiable functions and is moreover always defined and continuous with respect to what is in fact the Scott topology on a domain. The Scott topology [1, 28], which has proved to be an essential tool in the theory of computation, has now found a new area of application in mathematical analysis.

In 1980's, motivated by applications in non-smooth analysis, optimization and control theory, Frank Clarke developed a set-valued derivative for real-valued Lipschitz maps on Euclidean spaces, which is now called the Clarke gradient [7]. On finite dimensional Euclidean spaces, the Clarke gradient has non-empty compact and convex subsets of the Euclidean space as its values. For example, the absolute value function, which is not classically differentiable at zero, is a Lipschitz map that has Clarke gradient [-1, 1] at zero.

It is of great interest to computer science that the Clarke gradient of a Lipschitz map is upper semi-continuous as a function, i.e., it is continuous with respect to the upper topology on the hyperspace of the non-empty compact and convex subsets of the Euclidean space. In finite dimensions, the upper topology coincides with the Scott topology on the hyperspace when it is ordered by reverse inclusion (i.e., its specialization order). Furthermore, on infinite dimensional Banach spaces the Clarke gradient, which takes non-empty weak* compact and convex subsets of the dual of the Banach space as its values, remains Scott continuous (see acknowledgements).

In a series of papers, Borwein and his collaborators have studied various properties of the Clarke gradient and developed new related notions [3, 4, 5]. In particular, given a weak* upper semi-continuous map g that is non-empty, convex and compact set-valued from a Banach space to the space of subsets of its dual, a g-Lipschitz map is defined as one whose Clarke gradient at every point is contained in the set value of g at that point. Various interesting properties of the set of all g-Lipschitz maps, including some residual properties of certain subsets of it, are shown for separable Banach spaces as well as general Banach spaces [5].

Despite the central place Lipschitz maps occupy in many branches of computation as well as in pure and applied mathematics, they have not yet been a subject of study in computable analysis to the extent that no mention of Lipschitz maps can be found in the standard texts in computable analysis [33, 38].

In [18], a domain-theoretic derivative was introduced for real-valued functions of the real line, which was later extended to higher dimensions [19, 15] and shown to be mathematically equivalent to the Clarke gradient in finite dimensional spaces [15]. The L-derivative, as the domain-theoretic derivative is now called, has a number of distinct features compared with the Clarke gradient:

- (i) Whereas the Clarke gradient of a Lipschitz map is defined by using the generalized directional derivative based on taking the limsup of the rate of change of the function along a given direction, the L-derivative is constructed by collecting together some finitary generalized Lipschitz properties of the map that allow a natural way of approximating the L-derivative using domain theory.
- (ii) Any generalized Lipschitz property also gives rise to a corresponding set of primitive maps, which provides a fundamental theorem of calculus for Lipschitz maps, a duality between primitive maps and their L-derivatives, that extends the classical theorem in calculus for continuously differentiable functions to Lipschitz maps. This duality, which is a consequence of generalized Lipschitz properties of maps, is used in Borwein et al [5], for any derivative *g*, to actually define the set of the so-called *g*-Lipschitz maps. In finite dimensions, where the L-derivative is known to be equal to the Clarke

gradient, the set of g-Lipschitz maps coincides with the set of primitives of q.

(iii) The L-derivative gives rise to a continuous Scott domain with an effective structure for real-valued Lipschitz maps on finite dimensional Euclidean spaces.

This work has led to a domain-theoretic framework for solving initial value problems [17, 24, 20, 22] including the use of the "rectangular" L-derivative in the second order Euler method [19], a domain-theoretic framework of the implicit and inverse function theorem for Lipschitz functions [21] and a denotational semantics for hybrid systems [23].

Two fundamental and related questions arise:

- (1) What is the appropriate topology on the space of Lipschitz maps in computation?
- (2) Can we obtain a second order typed Fundamental Theorem of Calculus with a continuous derivative operator and a corresponding continuous integral operator as inverses of each other?

We use two different methods, one classical and one domain-theoretic, to tackle and answer the first question:

- (i) We obtain the weakest (i.e., the initial) topology on the space of Lipschitz functions that makes the L-derivative operator acting on real-valued Lipschitz maps on Banach spaces a continuous functional. This is similar to characterizing the C^1 topology on continuously differentiable real-valued maps as the weakest topology that makes the classical Fréchet derivative operator continuous as a second order functional. It is also in tune with the way some of the fundamental topologies, such as the subspace topology, the weak topology of a normed vector space and the weak* topology on its dual are defined.
- (ii) We obtain the topology on the space of Lipschitz maps that makes the insertion of these maps onto the set of maximal elements of the domain for Lipschitz maps a topological embedding. This is in line with constructing computational models for classical spaces in mathematics [14, 30] by embedding them into the set of maximal elements of suitable domains.

These two approaches lead to an identical result: the Scott topology, both on the hyperspace in (i) and on the domain of Lipschitz maps in (ii) above, induces a topology for maps, called the D-topology, whose intersection with the C^0 norm topology provides a new topology, called the L-topology, for Lipschitz maps. We compare the L-topology with the well-known Lipschitz norm topology for real-valued Lipschitz maps, which we now describe. Given any metric space (X,d), the collection $\operatorname{Lip}(X,d)$ of bounded real-valued Lipschitz functions on X is equipped with its $\operatorname{Lipschitz\ norm\ } \|\cdot\|_{\operatorname{Lip}}$ defined as

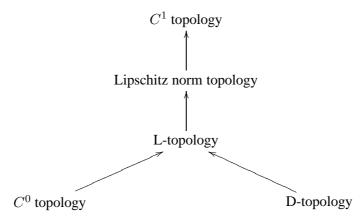
$$||f||_{Lip} = ||f|| + ||f||_d \tag{1}$$

where $||f|| = \sup\{|f(x)| : x \in X\}$ is the sup norm and

$$||f||_d = \sup\{|f(x) - f(y)|/d(x,y) : x, y \in X, x \neq y\}.$$

If (X, d) is complete then so is the Lipschitz norm [35].

The relationship between these topologies is depicted in the diagram below:



In the finite dimensional case, we derive an elementary characterization of the basic open subsets of the L-topology in terms of ties or primitive maps. This is used to prove that the L-topology is strictly coarser than the Lipschitz norm topology. In the one dimensional case, we further prove a density lemma for Lipschitz maps which we use to show that the basic open subsets of the L-topology are regular.

Using the Hausdorff distance between non-empty compact subsets of finite dimensional Euclidean spaces, we also construct a complete metric for Lipschitz maps which induces a topology strictly finer than the L-topology and strictly coarser than the Lipschitz norm topology.

Next, we verify that in finite dimensions the domain-theoretic structure of the space of non-empty compact and convex valued maps is preserved after restricting to integrable maps and also after identifying maps that are almost everywhere the

same. This enables us to derive, using domain theory, a second order typed fundamental theorem of calculus showing that the integral operation and the induced L-derivative operation are continuous inverses of each other.

Finally, in dimension one, we identify the L-derivative operator as an element of an effectively given continuous Scott domain of functionals and use this to show that the L-derivative is a computable functional.

2 Clarke's gradient

Let $U \subset X$ be an open subset of the Banach space X and let $f: U \to \mathbb{R}$ be locally Lipschitz. The *generalized directional derivative* [7, Chapter 2] of f at x in the direction of v is

$$f^{\circ}(x;v) = \limsup_{y \to x} \frac{f(y+tv) - f(y)}{t}.$$
 (2)

The generalized gradient of f at x, denoted by $\partial f(x)$ is the subset of X^* given by

$${A \in X^* : f^{\circ}(x; v) \ge A(v) \text{ for all } v \in X}.$$

It is shown in [7, page 27] that

- $\partial f(x)$ is a non-empty, convex, weak* compact subset of X^* .
- For $v \in X$, we have:

$$f^{\circ}(x;v) = \max\{A(v) : A \in \partial f(x)\}. \tag{3}$$

We will use the following result several times in this paper. Let $U \subset \mathbb{R}^n$ be an open subset.

Theorem 2.1 (Rademacher) [8, page 148] If $f: U \to \mathbb{R}$ is Lipschitz, then it is differentiable almost everywhere.

There is an alternative characterization of the generalized gradient when $X = \mathbb{R}$, whose proof uses Rademacher's Theorem. If Ω_f is the nullset where the Lipschitz map $f: U \to \mathbb{R}$ fails to be differentiable then:

$$\partial f(x) = \begin{bmatrix} \lim_{\substack{x_i \to x \\ x_i \notin \Omega_f}} f'(x_i), \lim_{\substack{x_i \to x \\ x_i \notin \Omega_f}} f'(x_i) \end{bmatrix}, \tag{4}$$

see [7, page 63] and [5, Corollary 5].

We now present the notion of T-Lipschitz functions due to Borwein et al [5]. Let $T:U\to 2^{X^*}$ be non-empty, convex and weak* compact set-valued function on the non-empty open subset U of a Banach space X. Then, T is said to be weak* upper semi-continuous if $\{x\in X:T(x)\subset W\}$ is open in U for any weak* open subset $W\subset X^*$. The set of T-Lipschitz maps is now defined as

```
\Upsilon_T = \{ f : U \to \mathbb{R} : f \text{ is locally Lipschitz and } \partial f(x) \subset T(x) \text{ for all } x \in U \}.
```

A number of closure properties and residual properties of various subsets of χ_T have been shown in [5] in the case of separable and also for general Banach spaces. In particular, it is shown that Υ_T is a convex sub-lattice of the locally Lipschitz functions defined on U and that (Υ_T, ρ) is a complete metric space, where $\rho(f,g) := \min\{1, \|f-g\| : x \in U\}$.

3 Lipschitz derivative

In this section we establish our notation and review the elements of the domaintheoretic differential calculus that we need here. For simplicity, we start with realvalued Lipschitz maps on finite dimensional Euclidean spaces before looking at the infinite dimensional case. Then, we extend a number of key results previously only known in dimension one to higher dimensions that will be required in this paper and finally recall how the domain for Lipschitz maps is constructed.

We consider continuous maps of type $f:U\to\mathbb{R}$ where $U\subset\mathbb{R}^n$ is an open subset. The set of all such functions is denoted by $(U\to\mathbb{R})$. The choice of U as an open subset makes the extension of our results to infinite dimensional Banach spaces smooth and uniform. But for finite dimensional spaces, we can also choose U to be a regular compact subset such as $[0,1]^n$.

By a domain we mean a directed complete partial order (dcpo). We assume the reader is familiar with the elements of domain theory, in particular the way-below relation, continuous Scott domains, as well as the Scott and Lawson topologies [1, 37, 28]. In particular, we recall that in any continuous domain D with a basis $B \subset D$, subsets of the form $\uparrow x = \{y : x \ll y\}$, where $x \in B$ form a collection of basic Scott open sets.

Let $(\mathbf{C}(\mathbb{R}^n), \sqsubseteq)$ denote the domain of all non-empty convex and compact subsets of \mathbb{R}^n , augmented with a least element denoted by \bot , ordered by reverse inclusion. The maximal elements are singleton sets $\{x\}$ for $x \in \mathbb{R}^n$; for convenience we write any maximal element $\{x\}$ simply as x. The dcpo $(\mathbf{C}(\mathbb{R}^n), \sqsubseteq)$ is a continuous Scott domain as it is a continuous retract [1] of the upper space $\mathbf{U}(\mathbb{R}^n)$, the set of non-empty compact subsets of \mathbb{R}^n ordered by reverse inclusion, which is a continuous Scott domain [13]. In fact, the convex hull map $H: \mathbf{U}(\mathbb{R}^n) \to \mathbf{U}(\mathbb{R}^n)$

that takes any non-empty compact subset to its convex hull is a Scott continuous map with $\mathbf{C}(\mathbb{R}^n)$ as its image. When n=1, the dcpo $\mathbf{C}(\mathbb{R})$ is simply the domain $\mathbf{I}\mathbb{R}$ of the non-empty compact intervals of \mathbb{R} ordered by reverse inclusion.

The left and right end points of any non-empty bounded interval $c \in \mathbb{R}$ are denoted by c^- and c^+ respectively. Thus, a non-empty compact interval $c \in \mathbb{R}$ is written in terms of its ends points as $c = [c^-, c^+]$. For any topological space Y, a Scott continuous function $f: Y \to \mathbb{IR}$ is characterized by a lower and an upper semi-continuous functions, $f^-, f^+: Y \to \mathbb{R}$ respectively, with $f(x) = [f^-(x), f^+(x)]$; we write $f = [f^-, f^+]$. The scalar product of vectors in \mathbb{R}^n , i.e., the map $-\cdot -: \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$ with $x \cdot y = \sum_{i=1}^n x_n y_n$, is extended to a map $-\cdot -: \mathbf{C}(\mathbb{R}^n) \times \mathbb{R}^n \to \mathbb{IR}$ with $b \cdot r = \{z \cdot r | z \in b\}$. The Euclidean norm $\|z\|$ of $z \in \mathbb{R}^n$ is given by $\|z\| = \sqrt{z \cdot z}$. For a subset A of a topological space, Cl(A), A° , A^c denote the closure, interior and complement of A respectively. If A is a subset of a metric space (Y,d) then for any t>0 we denote the t-neighbourhood of A by $A_t = \{x \in Y: \exists y \in A. d(x,y) < t\}$.

For a topological space Y, we denote its lattice of open subsets by $\mathcal{O}(Y)$. Given a dcpo D with bottom \bot , the single-step function $b\chi_a:Y\to D$, where $a\in\mathcal{O}(Y)$ is an open set and $b\in D$, is defined as $b\chi_a(x)=b$ if $x\in a$ and \bot otherwise. The *domain*, $\mathrm{dom}(f)$, of a Scott continuous function $f:Y\to D$ is given by $\mathrm{dom}(f)=\{x\in Y:f(x)\neq\bot\}$. Since U with its Euclidean topology is a locally compact Hausdorff space, its lattice of open subsets is continuous. It follows by [28, Proposition II-4.20(iv)] (equivalently from [26]) that the space $(U\to \mathbf{C}(\mathbb{R}^n))$ of all Scott continuous functions ordered pointwise is a continuous Scott domain and any $g\in(U\to\mathbf{C}(\mathbb{R}^n))$ can be expressed as the supremum of single-step functions way-below it: $g=\sup\{b\chi_a:b\chi_a\ll g\}$. Lubs of finite and consistent sets of such single-step functions form a basis for $(U\to\mathbf{C}(\mathbb{R}^n))$. Note that here we use the standard notation for step functions in terms of characteristic functions as in [28].

Any single step function of type $U \to \mathbf{C}(\mathbb{R}^n)$ defines a family of maps of type $U \to \mathbb{R}$ as follows [15]. We say $f \in (U \to \mathbb{R})$ has an interval Lipschitz constant $b \in \mathbf{C}(\mathbb{R}^n)$ in a convex open subset $a \subset U$ if for all $x, y \in a$ we have: $b \cdot (x-y) \sqsubseteq f(x) - f(y)$, i.e., $f(x) - f(y) \in b \cdot (x-y)$. The single tie of $b\chi_a$, denoted by $\delta(b\chi_a)$, is the collection of all real-valued continuous functions f on U that have an interval Lipschitz constant b in a. Note that in our previous work the notation $\delta(a,b)$ was used instead of $\delta(b\chi_a)$. The new notation emphasizes more explicitly the connection between a single-tie and its associated single-step function, which is more convenient for expressing the results of this paper. If $f \in \delta(b\chi_a)$ then f is Lipschitz in a with Lipschitz constant $\sup\{\|z\|:z\in b\}$ and the same is true for the extension of f by continuity to $\mathrm{Cl}(a)$.

A tie is any intersection of single-ties, including the empty intersection. For any

indexing set I, the family of single-step functions $(b_i\chi_{a_i})_{i\in I}$ is bounded in $(U \to \mathbf{C}(\mathbb{R}^n))$ if $\bigcap_{i\in I} \delta(b_i\chi_{a_i}) \neq \emptyset$ [15, Proposition 3.9]. Moreover, if $\sup_{i\in I} b_i\chi_{a_i} \sqsubseteq \sup_{i\in I} b_i\chi_{a_i}$, then we have [15, Corollary 3.12]:

$$\bigcap_{i\in I} \delta(b_i \chi_{a_i}) \supseteq \bigcap_{i\in J} \delta(b_i \chi_{a_i}).$$

It follows that any non-empty tie $\Delta = \bigcap_{i \in I} \delta(b_i \chi_{a_i})$ is uniquely associated with the Scott continuous function $g = \sup_{i \in I} b_i \chi_{a_i}$ and we write $\Delta = \delta(g)$. Therefore, $\delta(g)$ is a family of Lipschitz functions whose local Lipschitz properties are expressible by single-ties provided by the single-step functions below g. We note that $\delta(g)$ is always non-empty for n=1 but can be the empty set in higher dimensions n>1. In [19, Section 6], an example of a step function g for dimension n=2 is given with $\delta(g)$ the empty set. A function $g \in (U \to \mathbf{C}(\mathbb{R}^n))$ is called integrable if $\delta(g) \neq \emptyset$.

Let $(\mathbf{T}(U),\supseteq)$ be the partial order of ties of continuous functions of type $U\to\mathbb{R}$ ordered by reverse inclusion. The set of L-primitives of a Scott continuous function is precisely the tie associated with it. The *L-primitive map* is defined by

$$\int : (U \to \mathbf{C}(\mathbb{R}^n)) \to \mathbf{T}(U)
f \mapsto \delta(f).$$

The set $\int f$ is the collection of the *L-primitives* of f and the map \int is continuous with respect to the Scott topologies on $(U \to \mathbf{C}(\mathbb{R}^n))$ and $\mathbf{T}(U)$. In this paper, it is convenient to use $\delta(g)$, whenever g is a step function, i.e. the lub of a finite bounded set of single-step functions, and use $\int g$ for a general Scott continuous function.

The interval Lipschitz constants for a map provide us with its local differential properties, which can be collected to define its global derivative. The *Lipschitz derivative* or the *L-derivative* of a continuous function $f:U\to\mathbb{R}$ is accordingly defined as the Scott continuous map

$$\mathcal{L}f: U \to \mathbf{C}(\mathbb{R}^n), \tag{5}$$

given by

$$\mathcal{L}f = \sup\{b\chi_a : f \in \delta(b\chi_a)\}. \tag{6}$$

Example 3.1 The b-cone. Let $v \in a \subset U$, $r \in \mathbb{R}$ and let b be any non-empty convex and compact subset of \mathbb{R}^n . We construct two functions $f^u, f^l : a \to \mathbb{R}$ with $f^u(v) = f^l(v) = r$ and $\mathcal{L}f^u(v) = \mathcal{L}f^l(v) = b$. The graphs of f^u and f^l are respectively the upper and lower parts of a cone in \mathbb{R}^{n+1} , called the b-cone with vertex at (v, r), denoted by $K_b(v, r)$. For n = 1, we have $b = [b^-, b^+]$ and

 $K_b(v,r)$ is simply the cone with vertex $(v,r) \in \mathbb{R}^2$ generated by the two lines with slope b^- and b^+ . For example, when b = [-1,1] and x = r = 0, then the b-cone is given by the two lines with slopes -1 and 1 through the origin corresponding to the two functions $f^u = \lambda x.|x|$ and $f^l = \lambda x. - |x|$. For n > 1, let P^n_u be the hyperplane in \mathbb{R}^{n+1} that is perpendicular to \mathbb{R}^n , passes through (v,r) and is parallel with the unit vector $u \in \mathbb{R}^n$. Then P^n_u intersects $K_b(v,r)$ in the hyper-line that stands at angle $\arctan((b \cdot u)^+)$ with the \mathbb{R}^n hyperplane.

Proposition 3.2 [15, Corollary 8.2] In finite dimensional Euclidean spaces, the L-derivative coincides with the Clarke gradient.

3.1 Infinite dimensional case

The L-derivative can be extended to real-valued functions on any Banach space X [15]; we will briefly sketch the way this is done here. Let $U \subset X$ be any open subset of X. We consider the differential properties of continuous maps $f:U\to\mathbb{R}$ with respect to the norm topology on X. The L-derivative of f at any point in U where the function is locally Lipschitz will be a non-empty, convex and weak* compact subset of the dual space X^* . Let $\mathbf{C}(X^*)$ denote the dcpo of such subsets ordered by reverse inclusion. Then the notion of tie of a function, which we have seen in the finite dimensional case \mathbb{R}^n , can be extended to any Scott continuous function $g:U\to\mathbf{C}(X^*)$ that is expressible as the lub of step functions. These functions form a sub-dcpo $(U\to_s\mathbf{C}(X^*))$ of $(U\to\mathbf{C}(X^*))$ which includes all classical functions that map any point of U to a singleton point, i.e. a maximal point, of $\mathbf{C}(X^*)$. Ties of functions are then used to define the L-derivative of any continuous map $f:U\to\mathbb{R}$ as

$$\mathcal{L}f:U\to\mathbf{C}(X^*)$$

with its values given by $\mathcal{L}f = \sup\{b\chi_a : f \in \delta(b\chi_a)\}$ as in Equation 6. It is shown in [15] that $\mathcal{L}f$ is Scott continuous. It is not known if the L-derivative in the infinite dimensional case coincides with the Clarke gradient.

The Gâteaux derivative of f at x, when it exists, belongs to the L-derivative. Similarly for the Fréchet derivative. [15, Corollary 4.7]

Note that since the L-derivative can be extended to infinite dimensional Banach spaces, it can be applied to functionals of higher order type such as $(U \to \mathbb{R}) \to \mathbb{R}$. In fact, if $U \subset X$ is an open subset of a Banach space X, then the function space $(U \to \mathbb{R})$ of continuous functions of type $U \to \mathbb{R}$, equipped with the operator norm, forms a Banach space and therefore the L-derivative is well-defined and Scott continuous on functionals of type $(U \to \mathbb{R}) \to \mathbb{R}$ or, inductively, of higher types.

3.2 Properties of ties

For real-valued functions on any Banach space, the first order typed Fundamental Theorem of Calculus (FTC) between the L-derivative and primitives gives us the relation [15]:

 $f \in \int g \text{ iff } g \sqsubseteq \mathcal{L}f.$ (7)

It is an extension of the classical version of the FTC. In fact, for a continuous real-valued function g, we have $f \in \int g$ iff f is C^1 with f' = g where f' is the classical (Fréchet) derivative of f.

Note that in our domain-theoretic setting the set Υ_g of g-Lipschitz maps, as in [5], is characterized by: $f \in \Upsilon_g$ iff $g \sqsubseteq \partial f$. For real-valued functions on a general Banach space, we know that $\mathcal{L}f \sqsubseteq \partial f$ ([15, Corollary 4.9]) and thus in general $\int g \subseteq \Upsilon_g$. Since in finite dimensions the Clarke gradient and the L-derivative coincide (Proposition 3.2), we obtain from FTC in Equation 7:

Corollary 3.3 In finite dimensions, the set of primitives of $g \in (U \to \mathbf{C}(\mathbb{R}^n))$ coincides with the set of g-Lipschitz maps, i.e., $\int g = \Upsilon_g$.

The following notions and results generalize those for dimension one in [18]. We define the function

$$r: (U \to \mathbf{C}(\mathbb{R}^n)) \to (U^2 \to \mathbf{I}\mathbb{R})$$
 (8)

with the lower and upper parts of $r(g):U^2\to \mathbf{I}\mathbb{R}$ for $g\in (U\to \mathbf{C}(\mathbb{R}^n))$ given by

$$(r(g))^{\pm}:(x,y)\mapsto\left\{ \begin{array}{ll} \int_{[x,y]}(g\cdot v)^{\pm}d\,\mu_{[x,y]} & [x,y]\subset\mathrm{dom}(g)\\ \bot & \mathrm{otherwise} \end{array} \right.$$

where $v=\frac{y-x}{\|y-x\|}$ for $x\neq y$ and $\mu_{[x,y]}$ is the one dimensional Lebesgue measure on the line segment

$$[x,y] = \{tx + (1-t)y : 0 \le t \le 1\},\tag{9}$$

and for any Lebesgue integrable function $f:[x,y] \to \mathbb{R}$, we have:

$$\int_{[x,y]} f \, d\mu = \int_0^1 f((1-t)x + ty) \, dt = \int_0^1 f(x + t(y-x)) \, dt.$$

Note that, by the monotone convergence theorem, the map r is Scott continuous. Let $B(w, \delta)$ denote the open ball of radius δ centred at $w \in \mathbb{R}^n$.

Lemma 3.4 Let $h: U \to \mathbb{R}$ be Lipschitz $x, y \in U$, with $x \neq y$, and suppose $\delta > 0$ is such that $B(w, \delta) \subset U$ for all $w \in [x, y]$. Then, we have:

$$h(z+y) - h(z+x) = \int_{[z+x,z+y]} h' \cdot v \, d\mu_{[z+x,z+y]},$$

where $v = (y - x)/\|y - x\|$, for almost all $z \in \mathbb{R}^n$ with $|z| < \delta$ with respect to the Lebesgue measure on \mathbb{R}^n .

Proof Since h, being Lipschitz, is differentiable almost everywhere in U with respect to the n-dimensional Lebesgue measure, it follows from Fubini's theorem that for almost all $z \in U$ with $|z| < \delta$ the map h is differentiable almost everywhere on [y+z,x+z] with respect to $\mu_{[y+z,x+z]}$. If $z \in U$ with $|z| < \delta$ is such a value, then the restriction of h on [y+z,x+z] is absolutely continuous and the result follows. \square

Lemma 3.5 Let a be a convex open subset of U and $b \in \mathbf{C}(\mathbb{R}^n)$. If $h: U \to \mathbb{R}$ is Lipschitz and for almost all $x \in a$ we have $h'(x) \in b$, then $\mathcal{L}(h) \supseteq b\chi_a$.

Proof Let $x, y \in a$. Suppose $\delta > 0$ is such that $B(w, \delta) \subset a$ for all $w \in [x, y]$. By Lemma 3.4, for almost all $z \in \mathbb{R}^n$ with $|z| < \delta$, we have:

$$h(x+z) - h(y+z) = \int_0^1 h'(y+z+t(x-y)) \cdot (x-y) \, dt \in b \cdot (x-y).$$

Since h is continuous, by letting $z \to 0$, we obtain:

$$h(x) - h(y) \in b \cdot (x - y)$$
.

Hence, $h \in \delta(b\chi_a)$ and the result follows. \square

Corollary 3.6 Suppose $g \in (U \to \mathbf{C}(\mathbb{R}^n))$ and $h : U \to \mathbb{R}$ is Lipschitz. If for almost all $x \in dom(g)$ we have $h'(x) \in g(x)$, then $\mathcal{L}h \supseteq g$.

Proposition 3.7 (i) $h \in \int g iff$

$$\forall x, y \in U. (r(g))^{-}(x, y) \le h(y) - h(x) \le (r(g))^{+}(x, y)$$

- (ii) If g is an integrable map, then the two functions $\lambda y.(r(g))^-(x,y)$ and $\lambda y.(r(g))^+(x,y)$ are Lipschitz and are respectively the least and greatest functions $h \in \int g$ with h(x) = 0.
- (iii) The following two conditions are equivalent:

- (a) $g_1 \sqsubseteq g_2$ a.e., i.e., $g_1(x) \sqsubseteq g_2(x)$ for almost all $x \in U$ with respect to the n-dimensional Lebesgue measure on U.
- (b) $r(g_1) \sqsubseteq r(g_2)$.
- (iv) The equivalent conditions (a) and (b) in (iii) imply:
 - (c) $\int g_1 \supseteq \int g_2$.
- (v) If g_2 is integrable then (c) in (iv) above implies (a) and (b) in (iii).

Proof (i) Suppose $h \in \int g$ and $x,y \in U$ with $x \neq y$. Then $\mathcal{L}h \supseteq g$ and $h'(x) \in (\mathcal{L}h)(x) \subset g(x)$ for all $x \in \text{dom}(g)$ by [15, Corollary 4.7]. Let $\delta > 0$ be such that $B(w,\delta) \subset U$ for all $w \in [x,y]$. By Lemma 3.4, for almost all z with $|z| < \delta$, we get:

$$\int_{[x+z,y+z]} (g \cdot v)^{-} d\mu_{[x+z,y+z]} \le h(y+z) - h(x+z) \le \int_{[x+z,y+z]} (g \cdot v)^{+} d\mu_{[x+z,y+z]},$$

where $v = (y - x)/(\|y - x\|)$. Thus, we have

$$\int_0^1 (g \cdot v)^- ((y-x)t + x + z) \, dt \le h(y+z) - h(x+z) \le \int_0^1 (g \cdot v)^+ ((y-x)t + x + z) \, dt,$$
(10)

for almost all z with $|z| < \delta$. Let $\epsilon > 0$ be given. Since h, being Lipschitz, is continuous at x and y, there exists $\delta_0 > 0$ such that for $|z| < \delta_0$ we have:

$$|(h(y+z) - h(x+z)) - (h(y) - h(x))| < \epsilon/2.$$
(11)

On the other hand, since the two maps $t \mapsto (g \cdot v)^- : [0,1] \to \mathbb{R}$ and $t \mapsto (g \cdot v)^+ : [0,1] \to \mathbb{R}$ are respectively lower and upper semi-continuous on the compact set [0,1], it follows that there exists $\delta_1 > 0$ such that for all $|z| < \delta_1$ and all $t \in [0,1]$, we have the following inequalities:

$$\int_0^1 (v \cdot g)^- ((y - x)t + x) dt - \frac{\epsilon}{2} < \int_0^1 (v \cdot g)^- ((y - x)t + x + z) dt, \quad (12)$$

$$\int_0^1 (v \cdot g)^+ ((y - x)t + x + z) \, dt < \int_0^1 (v \cdot g)^+ ((y - x)t + x) \, dt + \frac{\epsilon}{2}. \tag{13}$$

Thus, combining the inequalities in 10, 11, 12 and 13, we have:

$$\int_0^1 (g \cdot v)^- ((y - x)t + x) dt - \epsilon < h(y) - h(x) < \int_0^1 (g \cdot v)^+ ((y - x)t + x) dt + \epsilon$$

and, since $\epsilon > 0$ is arbitrary, we obtain

$$\int_0^1 (g \cdot v)^-((y-x)t + x) \, dt \le h(y) - h(x) \le \int_0^1 (g \cdot v)^+((y-x)t + x) \, dt$$

as required.

On the other hand, suppose the above two inequalities hold. For $x \neq y$, let y = x + tv with $v = (y - x)/(\|y - x\|)$ and $t = \|y - x\|$. Then

$$\frac{\int_{[x,y]} (g \cdot v)^{-} d\mu}{t} \le \frac{h(x+tv) - h(x)}{t} \le \frac{\int_{[x,y]} (g \cdot v)^{+} d\mu}{t}.$$

By Rademacher's theorem again, h has Fréchet derivative almost everywhere. Therefore, taking the limit $t \to 0$ we obtain for almost all $x \in U$:

$$(g \cdot v)^-(x) \le v \cdot h'(x) \le (g \cdot v)^+(x).$$

Since v is an arbitrary unit vector, it follows that for almost all $x \in U$ we have: $h'(x) \in g(x)$. By corollary 3.6, we get $\mathcal{L}h \supseteq g$ as required.

(ii) The maps $g^- \cdot v$ and $g^+ \cdot v$ are lower and upper semi-continuous functions respectively and therefore attain their minimum and maximum values, respectively, on the compact set [x,y]. Thus, the two maps $\lambda y.(r(g))^-(x,y)$ and $\lambda y.(r(g))^+(x,y)$ are Lipschitz. From (i), it follows that they are the least and greatest functions $h \in \int g$ with h(x) = 0.

(iii) (a) \Rightarrow (b). This follows from monotonicity of r.

(b) \Rightarrow (a). Suppose $[x,y] \subset \text{dom}(g)$ and $[x',y'] \subset [x,y]$. From $r(g_1)(x',y') \sqsubseteq r(g_2)(x',y')$ we obtain:

$$\int_{[x',y']} (g_1 \cdot v)^- d\mu \le \int_{[x',y']} (g_2 \cdot v)^- d\mu$$
$$\int_{[x',y']} (g_1 \cdot v)^+ d\mu \ge \int_{[x',y']} (g_2 \cdot v)^+ d\mu.$$

Since the above inequalities hold for all $[x',y'] \subset [x,y]$, it follows that for almost all $z \in [x,y]$ with respect to the one-dimensional Lebesgue measure on the line segment [x,y] we have the two inequalities: $(g_1 \cdot v)^-(z) \leq (g_2 \cdot v)^-(z)$ and $(g_1 \cdot v)^+(z) \geq (g_2 \cdot v)^+(z)$. Fix the unit vector v. Then by Frobenius theorem $(g_1 \cdot v)^-(z) \leq (g_2 \cdot v)^-(z)$ and $(g_1 \cdot v)^+(z) \geq (g_2 \cdot v)^+(z)$ for almost all $z \in U$ with respect to the n-dimensional Lebesgue measure. Finally, by using Frobenius theorem with spherical integration we obtain $g_1(z) \sqsubseteq g_2(z)$ for almost all $z \in U$. (iv) (a) \Rightarrow (c). From $g_1 \sqsubseteq g_2$ a.e. we obtain $r(g_1) \sqsubseteq r(g_2)$. Thus by (i) we obtain $h \in \int g_1$ if $h \in \int g_2$.

(v) From (ii), we obtain (iii)(b). \Box

3.3 Lipschitz Domain and computability

In [14], a domain-theoretic computational model for a classical space X is defined to be a domain D with a topological embedding (i.e., a continuous and open injection) of X into a subset of maximal elements of D equipped with its relative Scott topology. For a countably based locally compact Hausdorff space, the upper space (the collection of the non-empty compact subsets of the space ordered by reverse inclusion) was proposed as a proto-type model. In this case, as in the case of the domain of formal balls [16] for a complete separable metric space (Polish space), the computational model is an ω -continuous domain. In these two instances, the embedding is actually onto the set of maximal elements of the continuous domain under consideration. However, there are important classes of function spaces with an embedding into a proper subset of the maximal elements of a continuous domain. A basic example is the embedding of the space $([0,1] \to \mathbb{R})$ of C^0 functions into the set of maximal elements of $([0,1] \to \mathbb{R})$. For example, the map $f:[0,1] \to \mathbb{R}$ with

$$x \mapsto \begin{cases} 0 & x < 0 \\ 1 & x > 0 \\ [0,1] & x = 0 \end{cases},$$

is a maximal element of $([0,1] \to \mathbf{I}\mathbb{R})$, which is not in the image of the embedding $E:([0,1] \to \mathbb{R}) \to ([0,1] \to \mathbf{I}\mathbb{R})$ given by $g \mapsto \lambda x. \{g(x)\}$. For the case when the embedding is onto the set of maximal elements, Lawson later showed that an ω -continuous domain is a computational model for a Polish space iff the relative Scott topology and the relative Lawson topology coincide on its the set of maximal elements. [30, 31].

The Scott continuous domain $D^n(U)$ for real-valued Lipschitz maps on an open subset $U \subset \mathbb{R}^n$ is the set of pairs $(f,g) \in (U \to \mathbf{I}\mathbb{R}) \times (U \to \mathbf{C}(\mathbb{R}^n))$ that are *consistent*, i.e., for which there exists a Lipschitz map $h:U \to \mathbb{R}$ with $f \sqsubseteq h$ and $g \sqsubseteq \mathcal{L}h$; see [15]. For n=1, it was shown in [18] that consistency on the basis consisting of step functions given by rational numbers is decidable, implying that $D^n(U)$ can be given an effective structure. A similar result was given in [19] for n>1 in the case of the "rectangular" L-derivative of a function $h:U \to \mathbb{R}$, whose values, for a fixed coordinate system, at each point $x_0 \in U$ is the smallest hyper-rectangle in \mathbb{R}^n that contains the non-empty compact and convex set $(\mathcal{L}h)(x_0)$. The proofs for the special case of "rectangular" L-derivative in [19] can be extended to show that consistency is decidable for n>1, giving an effective structure for $D^n(U)$ in the finite dimensional case. Equipped with an effective structure, the domain $D^n(U)$ provides an enumeration of the computable pairs $(f,\mathcal{L}f) \in D^n(U)$. Thus, the notions of a computable map and a computable L-derivative are inseparable in this context and are built within the domain of Lip-

schitz maps.

Similarly, the domain D(U) for real-valued Lipschitz maps on an open subset $U\subset X$ of a Banach space is constructed by taking the consistent pairs of the product domain

$$(U \to_s \mathbf{I}\mathbb{R}) \times (U \to_s \mathbf{C}(X^*)),$$

where $(U \to_s \mathbf{I}\mathbb{R})$ is the sub-dcpo of $(U \to \mathbf{I}\mathbb{R})$ consisting of Scott continuous functions that are the supremum of step functions; see [15] for details.

4 Weak Topology for Lipschitz maps

In this section we derive a new topology for Lipschitz maps as the weakest topology that makes the L-derivative operator continuous.

We note that the C^1 topology on the space of continuously differentiable functions can be characterized as the weakest topology that makes the classical Fréchet derivative operation continuous. In fact, let $C^0(U)$ and $C^1(U)$ be, respectively, the Banach spaces of continuous functions and continuously differentiable functions on an open subset $U \subset \mathbb{R}^n$. Consider the pairing map

$$(\operatorname{Id}, \frac{d}{dx}): C^1(U) \to C^0(U) \times (U \to \mathbb{R}^n)$$

where Id is the identity function and $\frac{d}{dx}$ is the Fréchet derivative operation, i.e. $(\mathrm{Id}, \frac{d}{dx})(f) = (f, f')$. The C^1 norm topology on $C^1(U)$ is precisely the weakest topology such that the above pairing function is continuous.

The above observations lead us naturally to a concrete scheme how to define the weak topology for Lipschitz maps. Instead of the classical Fréchet derivative, we will use the L-derivative. We therefore define the *L-topology* on the collection $(U \to \mathbb{R})$, of real-valued continuous functions on U, to be the weakest topology on $(U \to \mathbb{R})$ such that the pairing map

$$(\mathrm{Id},\mathcal{L}):(U\to\mathbb{R})\to(U\to\mathbb{R})\times(U\to\mathbf{C}(X^*))$$

with $f\mapsto (f,\mathcal{L}f)$ is continuous, where the function space $(U\to\mathbb{R})$ in the range of the pairing function above is equipped with its C^0 norm topology and $(U\to\mathbf{C}(X^*))$ is equipped with its Scott topology.

Let the *D-topology* on $(U \to \mathbb{R})$ be the weakest topology such that

$$\mathcal{L}: (U \to \mathbb{R}) \to (U \to \mathbf{C}(X^*))$$

is continuous. Note that the D-topology, like the $\|\cdot\|_d$ norm topology in the definition of the Lipschitz norm topology $\|\cdot\|_L$ in Equation 1, is not T_0 as any two

functions differing by a constant always belong to the same D-open sets. The L-topology, however, is the intersection (i.e. join) of the C^0 topology and the D-topology on $(U \to \mathbb{R})$ and is thus Hausdorff.

Since the L-derivative of a C^1 function coincides with its Fréchet derivative, it follows that the C^1 topology on $C^1(U)$ is precisely the relative L-topology for the subspace $C^1(U)$.

The L-topology has also a domain-theoretic characterization as follows. Consider the domain D(U) for real-valued Lipschitz maps on U, where $U \subset X$ is an open subset and X is \mathbb{R}^n or an infinite dimensional Banach space.

Proposition 4.1 The L-topology on $(U \to \mathbb{R})$ is precisely the topology that makes the insertion map

$$f \mapsto (f, \mathcal{L}f) : (U \to \mathbb{R}) \to D(U)$$

a topological embedding with respect to the Scott topology on D(U), i.e., the L-topology is the topology that makes D(U) a computational model.

Proof We first note that for each $f \in (U \to \mathbb{R})$, the pair $(f, \mathcal{L}f) \in D(U)$ is maximal [15, Proposition 5.8] and that the insertion map is one to one. Next we note that the function space $(U \to \mathbb{R})$, equipped with its sup norm, is homeomorphic with the subset of maximal elements of $(U \to \mathbf{I}\mathbb{R})$, equipped with its relative Scott topology, under the correspondence $f \mapsto \lambda x.\{f(x)\}$; see [18, Theorem 2.2]. The statement that the L-topology is the weakest topology that makes the operator $(\mathrm{Id},\mathcal{L}): f \mapsto (f,\mathcal{L}f): (U \to \mathbb{R}) \to (U \to_s \mathbf{I}\mathbb{R}) \times (U \to_s \mathbf{C}(X^*))$ continuous is equivalent to the assertion that the insertion map is continuous and that it is an open map. \square

5 L-topology in finite dimensions

When $X = \mathbb{R}^n$, the pairing map reduces to:

$$(\mathrm{Id},\mathcal{L}):(U\to\mathbb{R})\to D^n(U)$$

where $D^n(U) \subset (U \to \mathbf{I}\mathbb{R}) \times (U \to \mathbf{C}(\mathbb{R}^n))$ is a continuous Scott domain. Since the space of Lipschitz maps equipped with the L-topology is precisely the set of maximal elements of $D^n(U)$, it follows that this space is a Polish space, i.e., a separable completely metrizable topological space [28, chapter V-6].

Corollary 5.1 *In finite dimensions, the L-topology admits a complete metric.*

Furthermore, the L-topology has an elementary characterization in terms of ties of functions: the D-topology has a basis consisting of subsets of the form $\check{\delta}(g) := \mathcal{L}^{-1}(\uparrow g)$ for any step function $g \in (U \to \mathbf{C}(\mathbb{R}^n))$ with $\uparrow g \neq \emptyset$.

We note that if $g = \sup_{i \in I} b_i \chi_{a_i}$, for a finite indexing set I, then $\uparrow g = \bigcap_{i \in I} \uparrow (b_i \chi a_i)$. Since, by FTC (Equation 7), $\delta(b\chi_a) = \mathcal{L}^{-1}(\uparrow (b\chi_a))$, it follows that $\check{\delta}(b\chi_a) \subset \delta(b\chi_a)$ and more generally for any step function $g \in (U \to \mathbf{C}(\mathbb{R}^n))$:

$$\check{\delta}(g) \subset \delta(g).$$
(14)

The countable collection of step functions of the form $\bigcup_{1 \leq i \leq m} (b_i \chi_{a_i})$ where, for $1 \leq i \leq m$, the subset a_i is the interior of a convex rational polyhedron whereas the subset b_i is the closed hull of a rational convex polyhedron, provides a countable basis of the Scott topology on $(U \to \mathbf{C}(\mathbb{R}^n))$. Since the C^0 norm topology is second countable, it follows that the D-topology and thus its intersection with the C^0 norm topology are both second countable.

In this section and in Section 8, closure and interior of subsets are meant to be with respect to the L-topology.

Proposition 5.2 Any tie is closed in the L-topology.

Proof Since a tie is an intersection of single-ties, it is sufficient to show the statement for a single-tie $\delta(b\chi_a)$. Since the L-topology is second countable, it suffices to prove the closure property for sequences. Let $(f_i)_{i\geq 0}$ be a sequence in $\delta(b\chi_a)$ which converges to a function $f:U\to\mathbb{R}$ in the L-topology and thus in particular in the C^0 norm topology. Then, for each $i\geq 0$, we have: $b\cdot(x-y)\sqsubseteq f_i(x)-f_i(y)$. From the compactness of $b\cdot(x-y)$, we conclude by taking the limit that for all $x,y\in a$ we have: $b\cdot(x-y)\sqsubseteq f(x)-f(y)$ as required. \square

From Equation 14, we conclude:

Corollary 5.3 *If* g *is a step function, then:* $Cl(\check{g}) \subset \delta(g)$.

Corollary 5.4 The L-topology is the weakest topology on $(U \to \mathbb{R})$ such that the pairing map

$$(Id, \mathcal{L}): (U \to \mathbb{R}) \to (U \to \mathbb{R}) \times (U \to \mathbf{C}(\mathbb{R}^n))$$

is continuous, where the function space $(U \to \mathbb{R})$ in the range of the pairing function above is equipped with its C^0 norm topology and $(U \to \mathbf{C}(\mathbb{R}^n))$ is equipped with its Lawson topology.

Proof The Scott topology on $(U \to \mathbf{C}(\mathbb{R}^n))$ is refined by the Lawson topology by taking $\uparrow g$ as sub-basic closed subsets for all step functions g. But $\mathcal{L}^{-1}(\uparrow b\chi_a) = \delta(b\chi_a)$ is closed in the L-topology by Proposition 5.2. \square

We say that the way-below relation in a continuous domain D is meet-stable if $x \ll y$ and $x \ll z$ imply $x \ll y \sqcap z$ for all x, y and z in the domain. For example, the continuous Scott domain $\mathbf{C}(\mathbb{R}^n)$ is meet-stable, a property which follows easily from the characterization of the way-below relation given by $A \ll B$ iff $B^{\circ} \subset A$. Similarly, the lattice $\mathcal{O}(U)$ of open subsets of any open set $U \subset \mathbb{R}^n$ is meet-stable.

Proposition 5.5 [1, Theorem 4.2.18.] The lattice of Scott open sets of any Scott continuous domain (more generally of any F-S domain) is meet-stable.

It is easy to check that D is meet-stable if the meet-stability relation holds for the elements of a basis closed under binary meet. In fact, suppose the meet-stability relation holds for such a basis and let $x \ll y$ and $x \ll z$. By the interpolation property of the way-below relation in a continuous domain we can find basis elements b_i for $1 \le i \le 4$ such that $x \ll b_1 \ll b_2 \ll y$ and $x \ll b_3 \ll b_4 \ll z$. Then we have $x \sqsubseteq b_1 \sqcap b_3$ with $b_1 \sqcap b_3 \ll b_2$ and $b_1 \sqcap b_3 \ll b_4$. By assumption, it follows that $b_1 \sqcap b_3 \ll b_2 \sqcap b_4$ from which we obtain: $x \ll y \sqcap z$.

Definition 5.6 We say an element x of a continuous Scott domain D is *regular* if $x = \inf\{y : x \ll y\}$.

For example, in $\mathbf{C}(\mathbb{R}^n)$ the regular elements are precisely those subsets that are regular as compact subsets of \mathbb{R}^n . It follows that $\mathbf{C}(\mathbb{R}^n)$ has a countable basis of regular elements (consisting for example of all n-dimensional rational convex polyhedra regarded as compact subsets). Similarly, any step function of type $U \to \mathbf{C}(\mathbb{R}^n)$ whose values are regular elements of $\mathbf{C}(\mathbb{R}^n)$ is a regular element of the function space $(U \to \mathbf{C}(\mathbb{R}^n))$ and this function space has a basis of regular step functions. The next result furnishes a connection between the way-below relations on a continuous Scott domain and its lattice of open subsets.

Proposition 5.7 *Let a and b be two elements in any continuous Scott domain D.*

- (i) We have: $\uparrow a \ll \uparrow b$ if $b \ll a$.
- (ii) Suppose D is meet-stable and a is regular. Then $b \ll a$ if $\uparrow a \ll \uparrow b$.

Proof (i) Suppose $b \ll a$ and assume $\uparrow b \subseteq \bigcup_{i \in I} O_i$ where $(O_i)_{i \in I}$ is a directed set of open subsets. It follows that there is $i \in I$ with $a \in O_i$ and thus $\uparrow a \subseteq O_i$ as required.

(ii) Suppose $\uparrow a \ll \uparrow b$. We have $\uparrow b = \bigcup \{ \uparrow c : b \ll c \}$ where the collection of open subsets $\{ \uparrow c : b \ll c \}$ is directed since D is meet-stable. Thus for some $c \in R$ we have $\uparrow a \subset \uparrow c$. By the regularity of a, we obtain $b \ll c \sqsubseteq \inf\{x : c \ll x\} \sqsubseteq \inf\{x : a \ll x\} = a$, as required. \square

If D is a continuous Scott domain and Y is a topological space with a continuous lattice of open sets, then, as we have already pointed out, the function space $(Y \to D)$ is a continuous Scott domain [28, Proposition II-4.20(iv)]. Furthermore, we have:

Proposition 5.8 Suppose D is a continuous Scott domain and Y is a topological space with a meet-stable continuous lattice of open sets. Let $U \subset Y$ be open, $s \in D$ and $f \in (Y \to D)$. Then $s\chi_O \ll f$ iff $O \ll f^{-1}(\uparrow s)$.

Proof [26, Proposition 5]. \square

Proposition 5.9 If D is a continuous Scott domain and Y is a topological space with a meet-stable continuous lattice of open sets, then the function space $Y \to D$ is meet-stable.

Proof By the remark after Proposition 5.5, it is sufficient to check the meet-stability condition for step functions, which form a basis of the function space. Let $O \subset Y$ be open, $s \in D$ and $f, g \in (Y \to D)$ with $s\chi_O \ll f$ and $s\chi_O \ll g$. Then, by Proposition 5.8, we have $O \ll f^{-1}(\uparrow s)$ and $O \ll g^{-1}(\uparrow s)$. Thus, by meet-stability of $\mathcal{O}(Y)$, we have $O \ll f^{-1}(\uparrow s) \cap g^{-1}(\uparrow s) = (f \cap g)^{-1}(\uparrow s)$. It follows, by Proposition 5.8 again, that $s\chi_O \ll f \cap g$, from which the result follows since any step function is a finite supremum of single-step functions. \square

Corollary 5.10 For any open subset $U \subset \mathbb{R}^n$, the function space $(U \to \mathbf{C}(\mathbb{R}^n))$ is meet-stable.

Corollary 5.10 will be used to prove the computability of the L-derivative operator in Section 10 (Proposition 10.6). We now proceed to obtain a simple characterization of the basic open subsets of the L-topology.

Lemma 5.11 Let D be a continuous Scott domain with a meet-stable way-below relation and Y a topological space such that $\mathcal{O}(Y)$ is a meet-stable continuous lattice. Then for any open set $a \subset Y$ and $s \in D$ we have

$$\uparrow(s\chi_a) = \bigcup \{\uparrow(t\chi_b) : a \ll b \& s \ll t\} = \bigcup \{\uparrow(t\chi_b) : a \ll b \& s \ll t\}.$$

Proof We show the first equality from which the second follows easily. Since $\mathcal{O}(Y)$ is a meet-stable continuous lattice and D is a continuous Scott domain, we have, from Proposition 5.8, the following relation:

$$s\gamma_a \ll f \iff a \ll f^{-1}(\uparrow s)$$
 (15)

Thus, $a \ll b \& s \ll t$ implies $\uparrow(t\chi_b) \subset \uparrow(s\chi_a)$. It remains to show the reverse inclusion. Let $(s\chi_a) \ll f$. Then, since D is a continuous domain, there exists a step function $\sup_{i \in I} s_i \chi_{a_i}$, where I is a finite indexing set, with

$$s\chi_a \ll \sup_{i \in I} s_i \chi_{a_i} \ll f.$$

From $s\chi_a\ll \sup\{s_i\chi_{a_i}:1\leq i\leq m\}$, by Equation 15, we get

$$a \ll \bigcup_{J \subset I} \{ \bigcap_{j \in J} a_j : s \ll \sup_{j \in J} s_j \}.$$

Since the way-below relation in D is meet-stable, we have

$$s \ll \inf_{J \subset I} \{ \sup_{j \in J} s_j : s \ll \sup_{j \in J} s_j \}.$$

Let $s' \in D$ be such that $s \ll s' \ll \inf_{J \subset I} \{ \sup_{j \in J} s_j : s \ll \sup_{j \in J} s_j \}$. Also let a' be an open subset of Y with

$$a \ll a' \ll \bigcup_{J \subset I} \{ \bigcap_{j \in J} a_j : s \ll \sup_{j \in J} s_j \}.$$

Then we have $s\chi_a \ll s'\chi_{a'} \ll f$, which completes the proof. \square

Since finite intersection distributes over arbitrary union, we can conclude with the same assumptions on Y and D:

Corollary 5.12 *For any step function* $g \in (Y \to D)$ *we have:*

$$\uparrow g = \bigcup \{ \uparrow h : g \ll h \text{ step function } \}$$

$$=\bigcup\{{\uparrow}h:g\ll h \text{ step function }\}.$$

These results now translate to basic L-open subsets, providing a simple characterization of these subsets.

Corollary 5.13 We have for any step function $g: U \to \mathbb{C}\mathbb{R}^n$, we have:

- (i) $\check{\delta}(g) = \bigcup \{\delta(h) : g \ll h \text{ step function } \}.$
- (ii) $\check{\delta}(g) = \bigcup \{ \check{\delta}(h) : g \ll h \text{ step function } \}.$

Proof Since $\mathcal{O}(U)$ and $\mathbf{C}(\mathbb{R}^n)$ are, by the remark preceding Proposition 5.5, respectively a meet-stable continuous lattice and a meet-stable continuous Scott domain, the two equalities in Corollary5.12 hold, to which we apply the inverse map \mathcal{L}^{-1} to obtain the required results. \square

6 L-topology and Lipschitz norm

Recall the definition of the Lipschitz norm in Section 1. In finite dimensions we can show the following:

Theorem 6.1 *The L-topology is coarser than the Lipschitz norm topology in finite dimensions.*

Proof Let $f \in \check{\delta}(b\chi_a)$ for some single-step function $b\chi_a \in (U \to \mathbf{C}(\mathbb{R}^n))$. We will find a neighbourhood of f in the Lipschitz norm topology that is contained in $\check{\delta}(b\chi_a)$. We have $f \in \delta(d\chi_c)$ for some $a \ll c$ and $b \ll d$. Thus,

$$f(x) - f(y) \in d \cdot (x - y), \tag{16}$$

for all $x,y\in \mathrm{Cl}(c)$. Let e be such that $b\ll e\ll d$. Then there exists t>0 such that $d_t\subset e$. (Recall that A_t is the t-neighbourhood of a set A.) It follows that for all $x,y\in c$ with $x\neq y$ we have

$$(d \cdot (x-y))_{t||x-y||} \subset e \cdot (x-y). \tag{17}$$

Consider any Lipschitz map h with $||f - h||_L < t$. Then, we have:

$$|(h(x) - h(y)) - (f(x) - f(y))| = |(h(x) - f(x)) - (h(y) - f(y))| \le t|x - y|,$$

for all $x,y\in \mathrm{Cl}(c)$. It follows, by Equations 16 and 17, that $h(x)-h(y)\in e\cdot (x-y)$ and thus $h\in \delta(e\chi_c)\subset \check{\delta}(b\chi_a)$. \square

Next, we show that the L-topology is strictly coarser than the Lipschitz norm topology in finite dimensions. We recall the following notion from classical measure theory.

Definition 6.2 A measurable subset $A \subset [0,1]$ is *splitting* if for any interval $I \subset [0,1]$ of length $\ell(I) > 0$ we have: $0 < \mu(A_k \cap I) < \ell(I)$, where μ is the Lebesgue measure.

It is well-known that splitting sets exist; see [29]. If A is splitting and $f = \lambda x$. $\int_0^x \chi_A d\mu$, then the Clarke gradient (equivalently the L-derivative) is easily seen to have constant value [0,1], i.e., $\partial f(x) = [0,1]$ for all $x \in [0,1]$. [32, Proposition 1.9]).

Proposition 6.3 The L-topology is strictly coarser than the Lipschitz norm topology in finite dimensions.

Proof It is sufficient to prove the proposition in dimension one, i.e., we assume $U=[0,1]\subset\mathbb{R}$. Let $A\subset[0,1]$ be a splitting set and let $f=\lambda x$. $\int_0^x\chi_A\,d\mu$, which is Lipschitz with $\mathcal{L}f=\lambda x$. [0,1]. We claim that there is no open subset of the L-topology which contains f and is contained in the open ball with centre f and radius 1/2 with respect to the Lipschitz norm. Let $g\in(([0,1]\to\mathbb{IR}))$ be any step function with $\mathcal{L}f\in \uparrow g$. Let $c\in \mathrm{dom}(g)$ and $\epsilon>0$ be small enough so that $[c,c+\epsilon]\subset \mathrm{dom}(g)$. Put $D=A\setminus (c,d)$ and $f_\epsilon=\lambda x$. $\int_0^x\chi_A\,d\mu$. Then, we have $\mathcal{L}f_\epsilon(x)=[0,1]\chi_D$, $\mathcal{L}f_\epsilon\in \uparrow g$ and $f_\epsilon\to f$ in the sup norm as $\epsilon\to 0^+$. But for any $\epsilon>0$, we have

$$\sup_{c < x < d} \frac{|f(x) - f_{\epsilon}(x) - (f(c) - f_{\epsilon}(c))|}{x - c} = \sup_{c < x < d} \frac{|f(x) - f(c)|}{x - c} = 1,$$

and thus $\|f - f_{\epsilon}\|_{Lip} \ge 1$, which proves the claim.

7 Hausdorff induced metric for Lipschitz maps

In this section, we derive a complete metric on Lipschitz maps in $(U \to \mathbb{R})$ induced from the Hausdorff metric and show that it is strictly finer than the L-topology and strictly coarser than the Lipschitz norm topology. Recall that, given any Hausdorff space X, the Vietoris topology on the Vietoris space $\mathbf{V}(X)$, i.e., the space of non-empty compact subsets of X, has basic open subsets of the form $\Box O_0 \cap \bigcap_{1 \leq i \leq m} \Diamond O_i$ where $O_i \subset \mathbb{R}^n$ $(i=0,\cdots,m)$ are open and $C \in \Box(O)$ if $C \subset O$ whereas $C \in \Diamond O$ if $C \cap O \neq \emptyset$. If X is locally compact then so is $\mathbf{V}(X)$, and the way-below relation on the basic open subsets in $\mathcal{O}(\mathbf{V}(X))$ satisfy: $\Box O_0 \cap (\bigcap_{1 \leq i \leq m} \Diamond O_i) \ll \Box O'_0 \cap (\bigcap_{1 \leq i \leq m} \Diamond O'_i)$ iff $O_i \ll O'_i$ for $i=0,\cdots,m$. In this case, the partial order $(\mathbf{V}(X),\supset)$ is a continuous Scott domain with the proviso that it has no bottom element. The Lawson topology here coincides with the Vietoris topology. For $X = \mathbb{R}^n$ we will always use a basis of convex and relatively compact open subsets for \mathbb{R}^n . Let $\mathbf{C}^+(\mathbb{R}^n)$ denote the domain $\mathbf{C}(\mathbb{R}^n)$ without its bottom element.

The Vietoris topology on the Vietoris space of any metric space is equivalent to the topology induced by the Hausdorff metric which we denote by d_H , i.e.,

 $d_H(C_1,C_2)$ is the Hausdorff distance between two non-empty, compact subsets on X [36, Theorem 7.4.3]. This gives a metric topology on the function space $(U \to \mathbf{C}^+(\mathbb{R}^n))$, by putting $d_H^*(f,g) = \sup_{x \in U} d_H(f(x),g(x))$. Since the metric d_H is complete, it follows that the function space metric d_H^* is also complete [12, Theorem 2.6].

Lemma 7.1 Suppose $K \subset \mathbf{C}^+(\mathbb{R}^n)$ is compact with respect to the Lawson topology. Then, the union $\bigcup_{C \in K} C \subset \mathbb{R}^n$ is compact with respect to the Euclidean topology.

Proof We will show that any sequence $(x_m)_{m\geq 0}$ in $\bigcup_{C\in K} C\subset \mathbb{R}^n$ has a convergent subsequence. Let $C_m\in K$ be such that $x_m\in C_m$ for $m\geq 0$. Then the sequence C_m in the compact set K has a convergent subsequence $C_{m_i}\to D\in K$ with $d_H(C_{m_i},D)\to 0$ as as $i\to\infty$. Thus, for each i, there exists $y_i\in D$ with $d(x_{m_i},y_i)\leq d_H(C_{m_i},D)$. Since $D\subset \mathbb{R}^n$ is compact, there is a subsequence $y_{i_t}\to y\in D$ as $t\to\infty$ and it follows that $x_{m_{i_t}}\to y$ and the proof is complete. \square

Proposition 7.2 The function space metric d_H^* is strictly finer than the Lawson topology on $(U \to \mathbf{C}^+(\mathbb{R}^n))$.

Proof Suppose that $f \in (U \to \mathbf{C}^+(\mathbb{R}^n))$ and $f \in \uparrow s \cap (\bigcap_{i \in J} (\uparrow g_i)^c)$, which is a basic open subset of the Lawson topology for step functions s and g_j with $j \in J$, where J is a finite indexing set. Assume $s = \sup_{i \in I} s_i$ for a finite set of single-step functions $s_i = b_i \chi_{O_i}$. Then, $s_i \ll f$ and, by Proposition 5.8, we have $O_i \ll f^{-1}(\uparrow b_i)$ for each $i \in I$. Thus, the closure $\overline{O_i}$ is compact and, by the continuity of f, the set $f[O_i] \subset \uparrow b_i \subset \mathbf{C}^+(\mathbb{R}^n)$ is compact with respect to the Lawson topology. By Lemma 7.1, the set $C_i = \bigcup \{C : C \in f[\overline{O_i}]\} \subset (b_i)^{\circ} \subset \mathbb{R}^n$ is compact and thus there exists $\epsilon_i > 0$ such that $(C_i)_{\epsilon_i} \subset (b_i)^{\circ}$. It follows that for $\epsilon = \min\{\epsilon_i : i \in I\}$ we have $h \in \uparrow s$ if $d_H^*(f,h) < \epsilon$. On the other hand, for $j \in J$, there exists $x_j \in U$ such that $f(x_j) \notin \uparrow g_j(x_j)$, i.e., $f(x_j) \setminus g_j(x_j) \neq \emptyset$. Let $\delta_j = \inf\{\delta: f(x_j) \subset (g_j(x_j))_{\delta}\}.$ Then $d^*(f,h) < \delta$ implies $h(x_j) \setminus g_j(x_j) \neq \emptyset$ and hence $h \in (\uparrow g_j)^c$. Put $\delta = \min\{\epsilon, \delta_j : j \in J\}$. Then $d^*(f,h) < \delta$ implies $h \in \uparrow s \cap (\bigcap_{j \in J} (\uparrow g_j)^c)$, which shows that the d_H^* metric topology is finer than the Lawson topology. Next we show that the d_H^* metric topology is strictly finer than the Lawson topology. Consider the constant function $h = \lambda x$. [0, 1]. We claim that there is no Lawson open subset which contains the constant function h and is contained in the d_H^* ball of centre h and radius 1/2 with respect to the d_H^* metric. Let h be in the basic Lawson open set $\uparrow g_0 \cap \bigcap_{1 \leq i \leq m} (\uparrow g_i)^c$, with step functions $g_i \in (U \to \mathbf{I}\mathbb{R})$ for $0 \le i \le m$. Then there are points $x_i \in U$ with $[0,1] \not\sqsubseteq g_i(x_i)$ for $1 \le i \le m$. Let $[c,d] \subset U \setminus \{x_i : 1 \le i \le m\}$ and put $f = [0,1]\chi_D$, where $D = U \setminus (c,d)$. Then, $f \in {\uparrow} g_0 \cap \bigcap_{1 \le i \le m} ({\uparrow} g_i)^c$ but $d_H^*(f,h) = 1$. \square

We note also that for any compact subset $V \subset U$ the d^* -metric topology on $(V \to \mathbf{C}(\mathbb{R}^n))$ will be equivalent to the compact-open topology of the function space as an instance of a general result on metrics for function spaces [12, pages 269-270].

For Lipschitz maps $f, g: U \to \mathbb{R}$, we now define a metric.

Definition 7.3 The *induced Hausdorff metric* on Lipschitz functions is given by by d_L :

$$d_L(f,g) = \max(\|f - g\|, d_H^*(\mathcal{L}f, \mathcal{L}g)).$$

Theorem 7.4 The induced Hausdorff metric is complete on the space of Lipschitz maps.

Proof Let $(f_i)_{i\geq 0}$ be a Cauchy sequence of Lipschitz maps with respect to the L-metric. Thus, $(f_i)_{i\geq 0}$ and $(\mathcal{L}f_i)_{i\geq 0}$ are Cauchy sequences with respect to the C^0 norm topology and d_H^* respectively. Let $\lim_{i\to\infty} f_i = f$ in the C^0 norm topology and $\lim_{i\to\infty} \mathcal{L}f_i = g$ in the d_H^* metric. Since the convergence is uniform, f is continuous. We will now show that $g = \mathcal{L}f$ by using Proposition 7.2 which tells us that the d_H^* metric topology is finer than the Lawson topology on $(U \to \mathbb{C}\mathbb{R}^n)$. Suppose $b\chi_a \ll g$. Then, as $b\chi_a$ is Lawson open, there exists K such that for all K is K we have K is an implies K in the K in the sum of K in the sum of K is an implied K in the sum of K in the sum of K in the sum of K is an implied K in the sum of K in the sum of

$$\{f(x)-f(y):x,y\in \mathrm{Cl}(a)\}\subset$$

$$d\cdot\{x-y:x,y\in \mathrm{Cl}(a)\}\subset b^\circ\cdot\{x-y:x,y\in \mathrm{Cl}(a)\}.$$

Since $b^{\circ} \cdot \{x-y: x,y \in \operatorname{Cl}(a)\}$ is an open interval and we have the convergence $f_i \to f$ in the C^0 norm topology and thus uniformly, there exists an integer $N \geq 0$ such that for all $i \geq N$ and for all $x,y \in \operatorname{Cl}(a)$ we have $f_i(x) - f_i(y) \in b^{\circ} \cdot (x-y)$. In particular for all $i \geq N$ we have $f_i \in \delta(b\chi_a)$, i.e., $b\chi_a \sqsubseteq \mathcal{L}f_i$. Since $\uparrow(b\chi_a)$ is closed in the Vietoris (Lawson) topology and $\mathcal{L}f_i \to g$ in the finer d_H^* metric topology, we obtain $b\chi_a \sqsubseteq g$. We conclude that $\mathcal{L}f \sqsubseteq g$ which completes the proof. \square

We now compare the d_L -metric topology with the L-topology.

Proposition 7.5 The d_L metric topology on Lipschitz functions $U \to \mathbb{R}$ is strictly finer than the L-topology.

Proof That the d_L metric topology is finer the L-topology follows immediately from Proposition 7.2. To show that it is strictly finer, let $A \subset [0,1]$ be a splitting set (Definition 6.2), and let $f = \lambda x$. $\int_0^x \chi_A d\mu$, which is Lipschitz with $\mathcal{L}f = \lambda x$. [0,1]. We claim that there is no open subset of the L-topology which contains f and is contained in the open ball with centre f and radius 1/2 with respect to the d_L metric. Let $g \in (U \to \mathbf{C}(\mathbb{R}^n))$ be any step function with $\mathcal{L}f \in \mathfrak{g}$. Let $c \in \text{dom}(g)$ and $\epsilon > 0$ be small enough so that $[c, c + \epsilon] \subset \text{dom}(g)$. Put $D = A \setminus (c, d)$ and $f_{\epsilon} = \lambda x$. $\int_0^x \chi_A d\mu$. Then, we have $\mathcal{L}f_{\epsilon}(x) = [0, 1]\chi_D$, $\mathcal{L}f_{\epsilon} \in \mathfrak{f}g$ and $f_{\epsilon} \to f$ in the sup norm as $\epsilon \to 0^+$. But for any $\epsilon > 0$, we have $d_H^*(f, f_{\epsilon}) = 1$ which proves the claim. \square

Next we compare the induced Hausdorff metric d_L with the Lipschitz norm. Recall that any convex subset $A \subset \mathbb{R}^n$ is the intersection of the half-spaces that contain it, i.e., $\bigcap \{S : A \subset S, \text{ for a half-space } S\}$. It is also easy to show:

Lemma 7.6 For any convex subset $A \subset \mathbb{R}^n$, we have: $A_{\epsilon} = \bigcap \{S_{\epsilon} : A \subset S, S \text{ a half-space}\}.$

Proposition 7.7 *The Lipschitz norm topology is finer than the induced Hausdorff metric topology.*

Proof Let $f:U\to\mathbb{R}$ be Lipschitz and let $\epsilon>0$ be given. We will show that the open ball around f of radius $\epsilon/2$ with respect to the Lipschitz norm is contained in the open ball around f of radius ϵ with respect to the d_L metric. In fact, suppose $\|f-g\|_{Lip}<\epsilon/2$. The, $\|f-g\|<\epsilon/2$ and $\|f-g\|_d<\epsilon/2$, i.e.,

$$\sup_{x \neq y} \frac{|(f(x) - g(x)) - (f(y) - g(y))|}{|x - y|} < \epsilon/2.$$
(18)

Let $v \in \mathbb{R}^n$ be any unit vector. By Equations 2.3, for any Lipschitz map $h: U \to \mathbb{R}$ we have:

$$v \cdot \mathcal{L}h(x) = \limsup_{y \to x} \frac{h(y + tv) - h(y)}{t}.$$

On the other hand, using Equation 18, we obtain:

$$\begin{split} & \limsup_{y \to x} \frac{g(y+tv) - g(y)}{t} \\ &= \limsup_{y \to x} \sup_{t \downarrow 0} \frac{(g(y+tv) - f(y+tv)) - (g(y) - f(y))}{t} + \frac{f(y+tv) - f(y)}{t} \\ &\leq \sup_{x \neq y} \frac{|(f(x) - g(x)) - (f(y) - g(y))|}{|x-y|} + \limsup_{y \to x} \sup_{t \downarrow 0} \frac{f(y+tv) - f(y)}{t} \\ &< \frac{\epsilon}{2} + \limsup_{y \to x} \inf_{t \downarrow 0} \frac{f(y+tv) - f(y)}{t} \end{split}$$

Thus, $v \cdot \mathcal{L}g(x) < \epsilon + v \cdot \mathcal{L}f(x)$ and similarly, $v \cdot \mathcal{L}f(x) < \epsilon + v \cdot \mathcal{L}g(x)$ for any unit vector $v \in \mathbb{R}^n$. By Lemma 7.6, it follows that $d_H^*(\mathcal{L}g, \mathcal{L}f) < \epsilon$ as required. \square

Finally, we will show that the induced Hausdorff metric d_L is strictly coarser than the Lipschitz norm topology. This requires some preliminary work.

We construct below a one-parameter family of Lipschitz maps $f_k:[0,1]\to\mathbb{R}$ for $k\in[0,2]$ such that $\mathcal{L}f_k(x)=[0,1]$ for all $x\in[0,1]$ with the property that, as $k\nearrow 1$, we have $f_k\to f_1$ in the d_L metric topology but not in the Lipschitz norm topology.

For $k \in [0, 2]$, we let $f_k = \lambda x$. $\int_0^x \chi_{A_k} d\mu$ where μ is the Lebesgue measure and the measurable set A_k is splitting with $\mu(A_k) = k/2$.

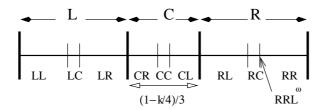
The set A_k can be constructed as the countable union of a double family of Cantor sets that are obtained in a sequence of stages. When k > 0, these Cantor sets will have positive Lebesgue measure.

We first adopt the following uniform scheme, similar to the construction of the standard Cantor set, to construct a Cantor set of Lebesgue measure $s \geq 0$ in a compact interval of length r > 0 with $r \geq s$. In the first stage the symmetrically placed middle open interval of length (r-s)/3 is removed, then in the remaining left and right closed intervals, the two middle open intervals each of length (r-s)/9, and so on. The total Lebesgue measure of the countable set of removed intervals is thus $\frac{r-s}{3}(1+\frac{2}{3}+\frac{4}{9}+\cdots)=r-s$. Thus the Cantor set has Lebesgue measure r-(r-s)=s.

Now we use our uniform scheme to construct A_k . In the first stage, a Cantor set of measure k/4 is constructed on [0,1]. Therefore, the first middle interval, denoted by C, to be removed has length $(1-\frac{k}{4})/3$, the next two middle intervals to be removed, denoted by LC and RC, are in the remaining two intervals L and R on the left and right respectively and have each length $(1-\frac{k}{4})/9$, and so on.

Then in each previously removed interval a new Cantor set is constructed so that the total measure of the countable union of the new Cantor sets is k/8. This is done by constructing a Cantor set of measure k/16 in C, then constructing two Cantor sets each of measure $k/(4\times16)$ (i.e. with total measure k/32) in the left and the right middle intervals, namely LC and RC, then constructing four Cantor sets each of measure $k/(4\times64)$ (i.e., with total measure k/64) in the middle intervals LLC, LRC, RLC, RRC of LL, LR, RL, RR respectively, and so on.

The procedure is then repeated ad infinitum so that a Cantor set is constructed in any previously removed interval. The set A_k will be the countable union of the countable unions of Cantor sets constructed at each stage. These Cantor sets are dense in [0,1]: any non-trivial subinterval of [0,1] contains one of these Cantor sets. We also have $\mu(A_k) = \frac{k}{4} + \frac{k}{8} + \frac{k}{16} \cdots = \frac{k}{2}$, so that $0 < \mu(A_k) < 1$ for $k \in (0,2)$.



Our labelling scheme for the intervals in the above construction is an instance of a general method in symbolic dynamics [11]. For a given $k \in [0,2]$, we represent each point of [0,1] by an infinite sequence of L,C,R, denoting the position of the the point on the Left, Center or Right interval at each stage of construction process, i.e., putting $\Sigma = \{L,C,R\}$, we have a surjection $P_k: \Sigma^\omega \to [0,1]$ that takes any sequence to a point in [0,1]. As each new interval is a contracting affine image of a previous interval, it follows that for $s \in \Sigma^\omega$, we have $P_k(s) = A(s) + B(s)k$ where $A,B: \Sigma^\omega \to [0,1]$.

Furthermore, by construction, $f_k(x)=\int_0^x \chi_{A_k}\,d\mu$ is the sum of the Lebesgue measure of the Cantor sets constructed in [0,x). Since the Lebesgue measure of each such Cantor set is a multiple of k, we have: $f_k(P_k(s))=D(s)k$ where $D:\Sigma^\omega\to[0,1]$. Note that for all $x\in[0,1]$, we have: $f_0(x)=0$ (each Cantor set constructed in this case has Lebesgue measure zero) whereas $f_2(x)=x$ (the sum of the Lebesgue measures of all constructed Cantor sets in [0,1] is 1).

Lemma 7.8 For all $k \in (0,2)$ and $x \in [0,1]$, we have: $\mathcal{L}(f_k)(x) = [0,1]$.

Proof This is an instance of [32, Proposition 1.9]. \square

It follows that for each $k \in [0.2]$, the map f_k is Lipschitz with Lipschitz constant 1.

Lemma 7.9 We have $f_k \to f_{k_0}$ in the induced Hausdorff metric d_L as $k \nearrow k_0$, for any $k_0 \in (0,2]$.

Proof Since $\mathcal{L}f_k = [0,1]$ for any $k \in (0,2)$, it follows trivially that $\mathcal{L}f_k \to \mathcal{L}f_{k_0}$ in the d^* metric as $k \nearrow k_0$. Thus it remains to show that $f_k \to f_{k_0}$ in the sup norm as $k \nearrow k_0$. We will show that for any fixed $x \in [0,1]$, the function $k \mapsto f_k(x)$ is strictly increasing with k and that $f_k(x) \to f_{k_0}(x)$ pointwise as $k \nearrow k_0$. Since f_k is continuous for all $k \in [0,2]$, the result will then follow a well known result in analysis [34, see 7.13]. Since f_k , being Lipschitz, is continuous for each $k \in [0,2]$, it suffices to show the above two properties for a dense subset of [0,1]. To show that $f_{k_1}(x) < f_{k_2}(x)$ for $k_1 < k_2$, we consider the dense subset $\{x_t : t \in \Sigma^*\}$,

where $x_t := P_{k_1}(tRL^{\omega})$. Since for each fixed $k \in [0,1]$, the map f_k is increasing and for $k_1 < k_2$ by construction we have $P_{k_2}(tRL^{\omega}) < P_{k_1}(tRL^{\omega})$, we obtain:

$$f_{k_1}(x_t) = f_{k_1}(P_{k_1}(tRL^{\omega})) = D(tRL^{\omega})k_1 < D(tRL^{\omega})k_2$$
$$= f_{k_2}(P_{k_2}(tRL^{\omega})) < f_{k_2}(P_{k_1}(tRL^{\omega})) = f_{k_2}(x_t),$$

which proves the first assertion. For the second assertion, we consider the dense subset $\{y_t: t \in \Sigma^*\}$, where $y_t:=P_{k_0}(tLR^\omega)$. Since for $k \leq k_0$ we have $P_k(tLR^\omega) \leq P_{k_0}(tLR^\omega)$, we obtain:

$$D(tLR^{\omega})k \le f_k(y_t) \le f_{k_0}(y_t) = D(tLR^{\omega})k_0,$$

and it follows that $f_k(y_t) \to f_{k_0}(y_t)$ as $k \nearrow k_0$, which proves the second assertion, completing the proof. \square

Finally, we can show that $f_k \not\to f_1$ in the Lipschitz norm topology as $k \to 1^-$.

Proposition 7.10 There exists no open set of the d_L metric topology around the map f_1 , as constructed above, that is contained in the open ball $\{f : |||f-f_1||_{Lip} < 1\}$ of unit radius with respect to the Lipschitz norm around f_1 , i.e., the d_L metric topology is strictly coarser than the Lipschitz norm topology.

Proof Consider the family f_k constructed above for $k \in [0,1]$. For any nonnegative k < 1, the map $g_k = f_1 - f_k$, being the difference of two Lipschitz maps, is Lipschitz and is differentiable almost everywhere with $g_k' = f' - f_k'$ almost everywhere. Since f_1' and f_k' are, almost everywhere, equal to χ_{A_1} and χ_{A_k} respectively, they take values 0 and 1 almost everywhere. Thus g_k' has values -1, 0 or 1 almost everywhere. But g_k' cannot take value 0 almost everywhere, since this would imply that g_k would be constant with constant value $g_k(0) = f_1(0) - f_k(0) = 0$, giving $f_1 = f_k$ which contradicts $f_1(1) = 1/2 \neq k/2 = f_k(1)$. Thus, since $g_k(0) = 0$ for all $k \in [0, 2]$, we have:

$$\sup_{x \neq y} \frac{|g_k(x) - g_k(y)|}{|x - y|} \ge \sup_{x \neq 0} \frac{|g_k(x)|}{x} \ge 1,$$

and thus $||g_k||_{Lip} \ge 1$ for all $k \in [0,1)$. Therefore $g_k \ne 0$ as $k \to k_0$, which completes the proof \square

8 L-topology in dimension one

In dimension one (n=1), we assume, for convenience, that the domain $U \subset \mathbb{R}$ of our continuous functions in $(U \to \mathbb{R})$, is a compact interval. We are able to show here that a basic L-open subset $\check{\delta}(g)$ is the interior (with respect to the L-topology) of the associated tie $\delta(g)$. Recall that in dimension one, any Scott continuous function $g \in (U \to \mathbb{IR})$ is integrable, i.e., there exists $h \in \int g$ with $g \sqsubseteq \mathcal{L}h$. In fact, it is shown in [18, section 6] that given any lower semi-continuous function $u:U \to \mathbb{R}$ there exists a least function $s(u,g):\mathrm{dom}(g) \to \mathbb{R}$ such that $u \le s(u,g)$ and $g \sqsubseteq \mathcal{L}s(u,g)$. Furthermore, if $g:U \to \mathbb{IR}$ is a step function and u is the lower part of a step function of type $U \to \mathbb{IR}$, then s(u,g) is a piecewise linear map in each connected component of g; see [17, Section 3]. In the following we deduce that when u is fixed, the least function s(u,g) will depend continuously on g with respect to the metric induced on step functions by the Hausdorff metric.

Recall that our basis elements for the L-topology are given in terms of step functions g with $\uparrow g \neq \emptyset$. This means that if two adjacent intervals in $\mathrm{dom}(g)$, each with a constant value for g, have a common boundary point then the intersection of their corresponding values will have non-empty interior. Thus, the connected components of the closure $\mathrm{Cl}(\mathrm{dom}(g))$ have disjoint closures. Dealing with these connected components separately, let $(U \to^u \mathbf{I}\mathbb{R})$ be the collection of step functions $g \in (U \to \mathbf{I}\mathbb{R})$ with $\uparrow g \neq \emptyset$ such that $\mathrm{Cl}(\mathrm{dom}(g))$ has a single connected component and $\mathrm{dom}(g) \cap \mathrm{dom}(u) \neq \emptyset$. For $g = [g^-, g^+] \in (U \to^u \mathbf{I}\mathbb{R})$, let

$$S(u,g): U \times U \to \mathbb{R}$$
$$(x,y) \mapsto \begin{cases} u(y) + \int_y^x g^-(t) dt & x \ge y \\ u(y) - \int_x^y g^+(t) dt & x < y \end{cases}$$

Let P_g be the partition of the interval $dom(g) \cup dom(u)$ obtained as the common refinement of the partition induced by the step function g and that by the piecewise constant map u such that in each interval in P the values of g and u are constant (note that for g these values are non-empty compact intervals and for u they are real numbers). Then, as in [17], we have:

$$s(u,g) = \lambda x.$$

$$\max\{u(x)\} \cup \{\limsup_{y \to z} S(u,g)(x,y) : z \in P_g \cap \mathrm{dom}(u)\}.$$

Consider $(U \to^u \mathbf{I}\mathbb{R})$ with the partial distance function induced from the Hausdorff metric on $\mathbf{I}\mathbb{R}$, namely: $d(g_1,g_2) = \sup\{d_H(g_1(x),g_2(x)) : x \in \text{dom}(g_1) \cap \text{dom}(g_2)\}$ and consider the partial maps in $U^2 \to \mathbb{R}$ with their partial sup norm: $\|f_1 - f_2\| = \sup\{|f_1(x) - f_2(x)| : x \in \text{dom}(f_1) \cap \text{dom}(f_2)\}$. We then have:

Lemma 8.1 The functions

(i)
$$g \mapsto S_{(u,g)} : (U \to^u \mathbf{I}\mathbb{R}) \to (U^2 \to \mathbb{R})$$

(ii)
$$g \mapsto s_{(u,q)} : (U \to^u \mathbf{I}\mathbb{R}) \to (U \to \mathbb{R})$$

are continuous with respect to partial distance on $(U \to^u \mathbf{I}\mathbb{R})$ and the partial sup norm on $(U^2 \to \mathbb{R})$.

Proof Note that is g^- is lower semi-continuous and the Lebesgue integrals in the definition of S(u,g) depend continuously on g^- . Also, the finite set P_g changes continuously with respect to the Hausdorff metric as g changes continuously with respect to the partial distance on $(U \to^u \mathbf{I}\mathbb{R})$. The result follows as s(u,g) is the minimum of a finite number of functions that vary continuously with g. \square

In order to obtain the regularity results of this section, we need the following density lemma.

Lemma 8.2 (**Density Lemma**) Let $f \in \delta(g)$, with step function $g \in (U \to \mathbf{I}\mathbb{R})$ and let $\epsilon > 0$ be given. Then there exists a step function h and a function k with $g \ll h$ and $k \in \delta(h)$ such that $||f - k|| < \epsilon$.

Proof Consider the open region formed by the graphs of $f + \epsilon$ and $f - \epsilon$. We regard f as an element of the function space $U \to \mathbb{IR}$ of all Scott continuous functions from U to $I\mathbb{R}$ ordered by pointwise reverse inclusion. Since this function space is a continuous Scott domain, f will be the lub of an increasing sequence of step functions: $f = \sup_{i \geq 0} u_i$. We have $\lim_{i \to \infty} u_i^+ - u_i^- = 0$, and thus there exists $i \geq 0$ 0 such that $u_i^+ - u_i^- < \epsilon/3$. For simplicity we let $u := u_i^-$. Consider the decreasing sequence of step functions $(g_{[1/m]})_{m>N}$ for a positive N such that every value of g has length greater than 2/N. For the sake of a more convenient notation, we put $\overline{g}_m := g_{[1/m]}$ for all $m \geq N$. Now by Lemma 8.1, $s(u, \overline{g}_m) \rightarrow s(u, g)$ with respect to the sup norm on the space of continuous functions $dom(g) \to \mathbb{R}$. Let M>0 be such that $m\geq M$ implies $\|s(u,\overline{g}_m)-s(u,g)\|<\epsilon/3$. Thus, for all $m \geq M$, we have $g \ll \overline{g}_m \sqsubseteq \mathcal{L}s(u, \overline{g}_m)$ and $f - \epsilon/3 < u \leq s(u, \overline{g}_m)$. Furthermore, $s(u, \overline{g}_m) < s(u, g) + \epsilon/3 \le f + \epsilon/3$, i.e. for all $m \ge M$ and all $x \in \text{dom}(g)$ we have: $f(x) - \epsilon/3 < s(u, \overline{g}_m)(x) < f(x) + \epsilon/3$. It remains to show that there exists $m \geq M$ such that we have $|s(u,\overline{g}_m)(x) - f(x)| < \epsilon$ for $x \in \text{dom}(\overline{g}_m) \setminus \text{dom}(g)$. If Cl(dom(g)) = U then we put $k := s(u, \overline{g}_M)$ and $h:=\overline{g}_M$. Then, since $s(u,\overline{g}_M)\in\delta(\overline{g}_M)$, the proof is complete. Otherwise, at least one of $[(dom(\overline{g}_m))^-, (dom(g))^-]$ or $[((dom(g))^+, (dom(\overline{g}_m))^+]$ will be nonempty. Let M_1 , be such that for $m \geq M_1$ both these intervals are non-empty if such M_1 exists or one of the two otherwise. Since f is continuous and defined on

the compact set $C_m:=[(\operatorname{dom}(\overline{g}_m))^-,(\operatorname{dom}(g))^-]\cup[((\operatorname{dom}(g))^+,(\operatorname{dom}(\overline{g}_m))^+],$ there exists a t>0 such that $|f(x)-f(y)|<\epsilon/3$ if |x-y|< t for $x,y\in C_m$. Then, there exists $M_2\geq M_1$ such that $m\geq M_2$ implies $\operatorname{dom}(g))_t\subset\operatorname{dom}(\overline{g}_m)$. Fix $m\geq M_2$. Note that $s(u,\overline{g}_m)$ is made up of line segments with slope bounded by the upper and lower values of g. If A>0 is an upper bound for the maximum of the absolute value of these, then $|s(u,\overline{g}_m)(x)-s(u,\overline{g}_m)(y)|\leq A|x-y|$ for $x,y\in C_m$. Thus, $|s(u,\overline{g}_m)(x)-s(u,\overline{g}_m)(y)|<\epsilon/3$ if $|x-y|<\epsilon/(3A)$. Now let $\overline{g}_m^*=\overline{g}_m\upharpoonright(\operatorname{dom}(g))_{\epsilon/(3A)}$. Then, $s(u,\overline{g}_m^*)\in\delta(\overline{g}_m^*)$. Put $k:=s(u,\overline{g}_m^*)$ and $h:=\overline{g}_m^*$. have for $x\in C_m$:

$$|f(x) - k(x)| \le |f(x) - f(x_0)| + |f(x_0) - k(x_0)| + |k(x_0) - k(x)| < \frac{\epsilon}{3} + \frac{\epsilon}{3} + \frac{\epsilon}{3} = \epsilon,$$

where we have two cases: we use $x_0 = (\operatorname{dom}(g))^-$ if $x \in [(\operatorname{dom}(\overline{g}_m^*))^-, (\operatorname{dom}(g))^-]$ and we use $x_0 = (\operatorname{dom}(g))^+$ if $x \in [(\operatorname{dom}(g))^+, (\operatorname{dom}(\overline{g}_m^*))^+]$. \square

Proposition 8.3 For any step function $g \in (U \to \mathbf{I}\mathbb{R})$ we have: $\delta(g) \subset Cl(\check{\delta}(g))$.

Proof Suppose $f \in \delta(g)$. We show that any basic L-open set containing f will intersect $\check{\delta}(g)$. Let $f \in \check{\delta}(g_0)$ for some step function g_0 and consider any open ball $O_{\epsilon}(f)$ of radius $\epsilon > 0$, around f in the sup norm in $(U \to \mathbb{R})$. Then, $f \in \delta(g_1)$ for some g_1 with $g_0 \ll g_1$. Thus, $\mathcal{L}f \supseteq g$ and $\mathcal{L}f \supseteq g_1$. Put $g_2 := g \sqcup g_1$. Then $f \in \delta(g_2)$. By Lemma 8.2, there exists a step function h with $g_2 \ll h$ and $h \in (U \to \mathbb{R})$ with $\|f - h\| < \epsilon$ and $h \in \delta(h)$. Thus, $h \in \delta(g_2)$ and $h \in \delta(g_2)$ and $h \in \delta(g_2)$ are required. $h \in \delta(g_2)$ as required. $h \in \delta(g_2)$

Recalling Corollary 5.3, we have now all together proved.

Corollary 8.4 For any step function $g \in (U \to \mathbf{I}\mathbb{R})$ we have: $\delta(g) = Cl(\check{\delta}(g))$.

Proposition 8.5 For any step function $g \in (U \to \mathbb{IR})$ we have: $\delta^{\circ}(g) = \check{\delta}(g)$.

Proof Since $\delta(g) = \operatorname{Cl}(\check{\delta}(g))$, we already know that $\delta^{\circ}(g) \supset \check{\delta}(g)$. To show the converse, let $f \in \delta^{\circ}(g)$, i.e., there exists a step function h such that $f \in \check{\delta}(h) \subset \delta(g)$. The latter relation implies, by Corollary 5.13(i), that for any k with $h \ll k$ we have $\delta(k) \subset \delta(g)$. It follows that $h \sqsubseteq g$. On the other hand $f \in \check{\delta}(h)$ implies there exists a step function k with $h \ll k$ and $f \in \delta(k)$. Thus, $f \in \delta(k) \subset \check{\delta}(h) \subset \check{\delta}(g)$, where the latter relation follows from Corollary 5.13(ii). \square

Corollary 8.6 The basic open and closed subsets $\check{\delta}(g)$ and $\delta(g)$ are regular open and closed sets respectively.

The results of this section can be extended, with some effort, to any finite dimension n > 1, by using properties of the L-derivative which extend those in [19] for the "rectangular" derivative.

9 Fundamental Theorem of Calculus

Recall the Fundamental Theorem of Calculus of the first order in Equation 7. In this section we develop the FTC of second order in finite dimensional Euclidean spaces by constructing continuous second order typed integration and differential operators that are inverses of each other.

Throughout this section, we consider $(U \to \mathbf{C}(\mathbb{R}^n))$ with its Scott topology. Since we will be dealing with the primitive maps of functions in $(U \to \mathbf{C}(\mathbb{R}^n))$, we will identify maps that are almost everywhere equal in this function space. We say $f,g \in (U \to \mathbf{C}(\mathbb{R}^n))$ are equivalent and write $f \equiv g$ if f = g a.e., i.e. if f(x) = g(x) for almost all $x \in U$ with respect to the n-dimensional Lebesgue measure on U. We denote the equivalence class of f by E(f). The set of equivalence classes is partially ordered by defining $E(f) \sqsubseteq E(g)$ if $f \sqsubseteq g$ a.e. It is easy to check that this partial order of equivalence classes, which we denote by $(U \to_c \mathbf{C}(\mathbb{R}^n))$, is directed complete and the map $E: (U \to \mathbf{C}(\mathbb{R}^n)) \to (U \to_c \mathbf{C}(\mathbb{R}^n))$, which takes a map to its equivalence class is Scott continuous.

Proposition 9.1 Any equivalence class of maps has a lub in $(U \to \mathbf{C}(\mathbb{R}^n))$ which is in the same class.

Proof Consider an equivalence class E(f). We claim that it has a lub. Since $(U \to \mathbf{C}(\mathbb{R}^n))$ is a continuous Scott domain, it is sufficient to show that E(f) is a bounded set; this follows if we prove that any finite set of maps in E(f) has a lub. In fact, we show that any two members of E(f) have a lub in E(f), from which the claim follows. Let $g \equiv f$ and for the sake of a contradiction, suppose $f(x) \cap g(x) = \emptyset$ for some $x \in U$. Then, by the Scott continuity of f and g, there would exist an open neighbourhood of f that is mapped by f and f to two disjoint open subsets containing f(f) and f and f respectively. But this contradicts the assumption that f = f a.e. It remains to show that f be the sum of Equation 8, we have f and f be the scott continuity of the map f of Equation 8, we have f be the sum of f be the sum of Equation 8, we have f be the sum of Equation 8. The sum of Equation 8 is a sum of Equation 8.

Let $F:(U \to_c \mathbf{C}(\mathbb{R}^n)) \to (U \to \mathbf{C}(\mathbb{R}^n))$ be the map which takes any equivalence class E(f) to its lub, i.e. $F(E(f)) = \sup E(f)$. We have the following.

Proposition 9.2 The pair (F, E) is a continuous section-retraction pair, with $F \circ E \supseteq Id$, i.e., it is a continuous insertion-closure operation.

Corollary 9.3 The dcpo $(U \to_c \mathbf{C}(\mathbb{R}^n))$ is a continuous Scott domain and E preserves the way-below relation.

Proof By [1, Theorem 3.14 and Proposition 3.1.14]. \square

Thus, $(U \to_c \mathbf{C}(\mathbb{R}^n))$ is, by identifying it with its image under the map F, in effect a continuous Scott sub-domain of $(U \to \mathbf{C}(\mathbb{R}^n))$. We know that f = g a.e. implies that $\int f = \int g$, therefore elements of the same class have the same primitive maps. We conclude that taking quotients under the equivalence relation of equality almost everywhere preserves the domain-theoretic structure. Therefore, we adapt the same convention as in classical measure theory where maps that are almost everywhere equal are identified. This means that from now on we implicitly consider $g \in (U \to \mathbf{C}(\mathbb{R}^n))$ as an equivalence class of maps and all relations between maps are assumed to be between their equivalence classes. Therefore f = g means that f and g are in the same equivalence class. i.e., f = g a.e.

To deal with the primitive maps of $(U \to \mathbf{C}(\mathbb{R}^n))$, we still need to restrict to a smaller subdomain, namely that of the integrable maps, i.e. $f \in (U \to \mathbf{C}(\mathbb{R}^n))$ with $\int f \neq \emptyset$. The integrable maps of $(U \to \mathbf{C}(\mathbb{R}^n))$ form a Scott closed subset, and thus a continuous Scott subdomain of $(U \to \mathbf{C}(\mathbb{R}^n))$ [19]. By taking retraction under the restrictions of E and F, we obtain the Scott continuous domain of equivalence classes of integrable maps which we denote by $(U \to_i \mathbf{C}(\mathbb{R}^n))$.

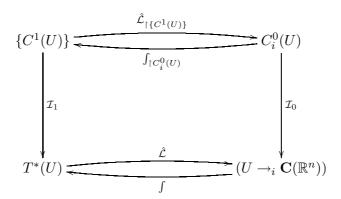
Let $T^*(U)$ be the dcpo of non-empty ties. Define

$$\hat{\mathcal{L}}: T^*(U) \to (U \to_i \mathbf{C}(\mathbb{R}^n))$$

by $\hat{\mathcal{L}}(\Delta) = \inf \{ \mathcal{L}h : h \in \Delta \}.$

Proposition 9.4 The integral map $\int : (U \to_i \mathbf{C}(\mathbb{R}^n)) \to T^*(U)$ and $\hat{\mathcal{L}}$ are inverses of each other.

Let $C_i^0(U)$ denote the set of integrable C^0 real-valued vector fields of type $U \to \mathbb{R}^n$ on the open subset $U \subset \mathbb{R}^n$ equipped with the subspace C^0 topology. Let $\{C^1(U)\}$ be the equivalence classes of real-valued C^1 maps on U under the equivalence relation $f \subseteq g$ if f-g is a constant real number. Then, $\{C^1(U)\}$ inherits the C^1 norm topology. Let \mathcal{I}_1 and \mathcal{I}_0 be respectively the insertion of $\{C^1(U)\}$ and $C_i^0(U)$ into the maximal elements of the continuous Scott domains $T^*(U)$ and $U \to_i \mathbf{C}(\mathbb{R}^n)$. These insertions are topological embeddings with respect to the Scott topology on the two continuous Scott domains.



Corollary 9.5 Second order typed FTC The Scott continuous maps $\hat{\mathcal{L}}$ and \int furnish an isomorphism between the Scott continuous domains for ties and L-derivatives, extending the Fundamental Theorem of Calculus of second order via the topological embeddings \mathcal{I}_1 and \mathcal{I}_0 to Lipschitz maps.

10 L-derivative operator in dimension one

Let $([0,1] \to_D \mathbb{R})$ be the set of Lipschitz maps equipped with the D-topology. In this section, we show that in dimension one the function space $(([0,1] \to_D \mathbb{R}) \to ([0,1] \to I\mathbb{R}))$ of Scott continuous functionals from the function space $([0,1] \to_D \mathbb{R})$, equipped with its D-topology, to the function space $([0,1] \to I\mathbb{R}))$, equipped with its Scott topology, is a continuous Scott domain when it is partially ordered by pointwise ordering of functionals. We will then show that this domain can be given an effective structure and that, with respect to such an effective structure, the L-derivative is a computable functional.

We recall the following definition from [5]. Let I be an open interval in $\mathbb R$ and let $f:I\to\mathbb R$. Then, f is said to be *robustly lower (upper) semi-continuous* if

$$f(x) = \liminf_{\substack{y \to x \\ y \notin N}} f(y) \qquad \left(f(x) = \limsup_{\substack{y \to x \\ y \notin N}} f(y) \right),$$

for each Lebesgue null set N of I. The following result has been proved in [5, Corollary 5] using various results on the residual properties of subsets of T-Lipschitz maps. Here, we give a short and direct proof using splitting sets.

Proposition 10.1 Let $g = [g^-, g^+] \in ([0, 1] \to \mathbf{I}\mathbb{R})$), where $g^-, g^+ : [0, 1] \to \mathbb{R}$ are, respectively, robustly lower and upper semi-continuous. Then, there exists a locally Lipschitz map h on [0, 1] such that $\mathcal{L}h = [g^-, g^+]$.

Proof Let $S \subset [0,1]$ be a splitting subset, and put $h=g^-\chi_S+g^+(1-\chi_S)$. Then h is measurable and we define $f:[0,1]\to\mathbb{R}$ for each $x\in[0,1]$ by the Lebesgue integral $f(x)=\int_0^x h(t)\,dt$. Since f is Lipschitz, by Rademacher's Theorem 2.1, f is differentiable almost everywhere with respect to the Lebesgue measure and for almost all $x\in[0,1]$ we have:

$$f'(x) = h(x) = \begin{cases} g^{-}(x) & x \in S \\ g^{+}(x) & x \in [0, 1] \setminus S. \end{cases}$$

Since in finite dimensions, the L-derivative and the Clarke gradient coincide, it follows by Equation 4 that $\mathcal{L}f=g$ as required. \square

Corollary 10.2 For any step function $g \in ([0,1] \to \mathbf{I}\mathbb{R})$, there exists a locally Lipschitz map $h : [0,1] \to \mathbb{R}$ with $\mathcal{L}h = g$.

Proof We have $g = \sup_{1 \le n \le m} s_n$ where each $s_n = [s_n^-, s_n^+] \chi_{O_n}$ is a single-step function with an open interval O_n and real numbers $s_n^- \le s_n^+$. If $g = [g^-, g^+]$ then $g^- = \max\{s_n^- \chi_{O_n} : 1 \le n \le m\}$ and $g^+ = \min\{s_n^+ \chi_{O_n} : 1 \le n \le m\}$ are, respectively, robustly lower-semi-continuous and upper-semi-continuous. \square

Corollary 10.3 The lattice map $\mathcal{L}^{-1}: \mathcal{O}([0,1] \to \mathbf{I}\mathbb{R}) \to \mathcal{O}([0,1] \to_D \mathbb{R})$ is an isomorphism.

Proof Let $O_1, O_2 \in \mathcal{O}([0,1] \to \mathbb{IR})$ be Scott open subsets with $\mathcal{L}^{-1}(O_1) = \mathcal{L}^{-1}(O_2)$. If $g \in O_1$ is a step function, then, by Corollary 10.2, there exists a locally Lipschitz function $h : [0,1] \to \mathbb{R}$ with $\mathcal{L}h = g$. Thus, $h \in \mathcal{L}^{-1}(O_2)$ and it follows that $g = \mathcal{L}h \in O_2$. Therefore, O_1 and O_2 contain the same step functions and thus $O_1 = O_2$ as $([0,1] \to \mathbb{IR})$ is a continuous Scott domain. Since, the D-topology is the weakest topology that makes \mathcal{L}^{-1} continuous, it follows that \mathcal{L}^{-1} is also one to one. \square

Next we show that the D-topology on the function space $(U \to_D \mathbb{R})$ has a meet-stable continuous lattice of open sets. This follows from a general result as follows.

Corollary 10.4 The function space $([0,1] \to_D \mathbb{R})$ equipped with the D-topology has a meet-stable continuous lattice of open sets.

Proof By Corollary 10.3, the lattice map $\mathcal{L}^{-1}: \mathcal{O}([0,1] \to \mathbf{I}\mathbb{R}) \to \mathcal{O}([0,1] \to_D \mathbb{R})$ is an isomorphism. Since the function space $([0,1] \to \mathbf{I}\mathbb{R})$ is a continuous Scott domain, it has a meet-stable continuous lattice of open subsets. Thus, the lattice of open subsets of the D-topology is continuous and meet-stable. \square

Corollary 10.5 The function space $(([0,1] \to_D \mathbb{R}) \to ([0,1] \to \mathbb{IR}))$ of Scott continuous functionals from the function space $([0,1] \to_D \mathbb{R})$, equipped with its D-topology, to the function space $([0,1] \to \mathbb{IR})$, equipped with its Scott topology, is a continuous Scott domain when it is partially ordered by pointwise ordering of functionals.

Proof This follows from [28, Proposition II-4.20(iv)], since the lattice of open subsets of the D-topology on $([0,1] \to_D \mathbb{R})$ is continuous and since $([0,1] \to \mathbf{I}\mathbb{R})$ is a continuous Scott domain. \square

We now construct an effective structure on the function space $(([0,1] \to \mathbb{R}) \to \mathbb{R})$ $([0,1] \to \mathbf{I}\mathbb{R}))$ which is induced from the following effective structure on $([0,1] \to$ IR). We start with an effective countable basis \mathcal{B}_0 of IR consisting of the regular (i.e., non-trivial) compact rational intervals on \mathbb{R} . This leads to an effective countable basis \mathcal{B}_1 for $([0,1] \to \mathbb{IR})$ as follows: An element of \mathcal{B}_1 is a step function $s = \sup_{i \in I} b_i \chi_{O_i}$, where I is a finite indexing set, such that $O_i \subset \mathbb{R}$ is a rational open interval, b_i is an element of \mathcal{B}_0 for each $i \in I$ and the values of s are regular compact subsets, i.e., $\bigcap_{i \in J} b_i$ is a regular compact interval whenever $\bigcap_{i \in J} O_i \neq \emptyset$. Hence, elements of \mathcal{B}_1 are regular as in Definition 5.6. From \mathcal{B}_1 , we immediately obtain an effective countable basis \mathcal{B}_2 , of the *D*-topology on ([0,1] $\to \mathbb{R}$), with $\mathcal{B}_2 = \{\mathcal{L}^{-1}(s) : s \in \mathcal{B}_1\}$. Finally, we obtain an effective countable basis \mathcal{B}_3 of $(([0,1] \to \mathbb{R}) \to ([0,1] \to \mathbf{I}\mathbb{R}))$ consisting of step functions made from singlestep functions of the form $s\chi_O$ where $O \in \mathcal{B}_2$ and $s \in \mathcal{B}_1$. It is easy to see that the restrictions to the basis \mathcal{B}_3 of the partial order \sqsubseteq and the way-below relation \ll of $(([0,1] \to \mathbb{R}) \to ([0,1] \to \mathbb{I}\mathbb{R}))$ are both decidable. By taking effective enumerations of \mathcal{B}_0 , \mathcal{B}_1 and \mathcal{B}_2 , we obtain an effective enumeration of \mathcal{B}_3 . Thus, we equip $(([0,1] \to \mathbb{R}) \to ([0,1] \to \mathbb{I}\mathbb{R}))$ with an effective structure.

We will now show that the \mathcal{L} operator as an element of the effectively given continuous Scott domain $(([0,1] \to \mathbb{R}) \to ([0,1] \to \mathbb{I}\mathbb{R}))$ is computable. For this, we need to prove that with respect to an effective enumeration $(f_i)_{i\geq 0}$ of the basis \mathcal{B}_3 the set $\{i: f_i \ll \mathcal{L}\}$ is recursively enumerable [25, Definition 2]. We will actually prove more and show that the above set is recursive, i.e., the relation $f_i \ll \mathcal{L}$ is decidable.

Proposition 10.6 For any element f of the basis \mathcal{B}_3 , the relation $f \ll \mathcal{L}$ is decidable.

Proof We have $f = \sup_{i \in I} g_i$ where each g_i is a single-step function and I is a finite indexing set. Then, $f \ll \mathcal{L}$ iff $\forall i \in I$. $g_i \ll \mathcal{L}$ and it is sufficient to prove that the latter relation is decidable. Now each single-step function g_i is of the form

 $t\chi_O$ where $t \in \mathcal{B}_1$ and $O \in \mathcal{B}_2$ with, say, $O = \mathcal{L}^{-1}(\uparrow s)$ for some $s \in \mathcal{B}_1$. We have:

$$\begin{array}{cccc} t\chi_{\mathcal{L}^{-1}(\mathring{\uparrow}s)} \ll \mathcal{L} & \iff & \mathcal{L}^{-1}(\mathring{\uparrow}s) \ll \mathcal{L}^{-1}(\mathring{\uparrow}t) & \text{By Proposition 5.8} \\ & \iff & \mathring{\uparrow}s \ll \mathring{\uparrow}t & \text{By Corollary 10.3} \\ & \iff & t \ll s & \text{By Corollary. 5.10, regularity of }s \\ & & & & & & & & & \\ \end{array}$$

Assume $s=\sup_{j\in J}b_j\chi_{O_j}$ and $t=\sup_{k\in K}b_k\chi_{O_k}$. Then, we have $t\ll s$ iff $\forall k\in K.b_k\chi_{O_k}\ll\sup_{j\in J}b_j\chi_{O_j}$ iff (by Proposition 5.8 again) $\forall k\in K.O_k\ll\bigcup_{j\in J}\{O_j:b_k\ll b_j\}$. Since the relation $O_k\ll\bigcup_{j\in J}\{O_j:b_k\ll b_j\}$ is decidable, it follows that the relation $t\chi_{\mathcal{L}^{-1}(\uparrow s)}\ll \mathcal{L}$ is decidable and hence $f\ll \mathcal{L}$ is decidable. \square

Corollary 10.7 *The L-derivative operator is a computable functional of type:*
$$([0,1] \rightarrow \mathbb{R}) \rightarrow ([0,1] \rightarrow \mathbb{IR}).\square$$

Note that to prove the above main result of this section, we used the fact that the step functions in $([0,1] \to \mathbb{IR})$ are in the image of \mathcal{L} , a property that has only been proved here for n=1. All other properties we used were valid for any finite dimension $n \geq 1$.

11 Further work and open problems

We list here three open questions: (i) Is the set of the step functions in $([0,1]^n \to \mathbb{C}\mathbb{R}^n)$ in the image of \mathcal{L} for finite dimensions n > 1? If so, all the results in Section 10 would extend to higher finite dimensions, i.e., the L-derivative would be a computable functional. (ii) Can any of the results for finite dimensions be extended to infinite dimensions? (iii) Can one construct a simple complete metric for the L-topology by using the Hausdorff metric to compare L-derivatives?

Acknowledgements

I am grateful to the anonymous referee who introduced me to the work of Borwein and his collaborators and for providing a proof for the Scott continuity of the Clarke gradient in the case of general Banach spaces.

References

- [1] S. Abramsky and A. Jung. Domain theory. In S. Abramsky, D. M. Gabbay, and T. S. E. Maibaum, editors, *Handbook of Logic in Computer Science*, volume 3. Clarendon Press, 1994.
- [2] Y. Benyamini and J. Lindenstrauss. *Geometric Nonlinear Functional Analysis*. American Mathematical Society, 2000.
- [3] J. M. Borwein and W. B. Moors. Essentially smooth lipschitz functions. *Journal of Functional Analysis*, 149(2), 1997.
- [4] J. M. Borwein, W. B. Moors, and Y. Shao. Subgradient representation of multifunctions. *Journal of the Australian Mathematical Society-Series B*, 40:301–313, 1998.
- [5] J. M. Borwein, W. B. Moors, and X. Wang. Generalized subdifferentials: A Baire categorical approach. *Transactions of the American Mathematical Society*, 353(10), 2001.
- [6] D Burago. A Course in Metric Geometry. American Mathematical Society, 2001.
- [7] F. H. Clarke. Optimization and Nonsmooth Analysis. Wiley, 1983.
- [8] F. H. Clarke, Yu. S. Ledyaev, R. J. Stern, and P. R. Wolenski. *Nonsmooth Analysis and Control Theory*. Springer, 1998.
- [9] E. A. Coddington and N. Levinson. *Theory of Ordinary Differential Equations*. McGraw-Hill, 1955.
- [10] T. A. Davis and K. Sigmon. MATLAB Primer. CRC Press, seventh edition, 2005.
- [11] R. Devaney. *An Introduction to Chaotic Dynamical Systems*. Addison Wesley, second edition, 1989.
- [12] J. Dugundji. Topology. Allyn and Bacon, 1966.
- [13] A. Edalat. Domain theory and integration. *Theoretical Computer Science*, 151:163–193, 1995.
- [14] A. Edalat. Dynamical systems, measures and fractals via domain theory. *Information and Computation*, 120(1):32–48, 1995.
- [15] A. Edalat. A continuous derivative for real-valued functions. In S. B. Cooper, B. Löwe, and A. Sorbi, editors, *New Computational Paradigms, Changing Conceptions of What is Computable*, pages 493–519. Springer, 2008.
- [16] A. Edalat and R. Heckmann. A computational model for metric spaces. *Theoretical Computer Science*, 193(1-2):53–73, 1998.
- [17] A. Edalat, M. Krznarić, and A. Lieutier. Domain-theoretic solution of differential equations (scalar fields). In *Proceedings of MFPS XIX*, volume 83 of *Electronic Notes in Theoretical Computer Science*, 2003. Full paper in www.doc.ic.ac.uk/~ae/papers/scalar.ps.

- [18] A. Edalat and A. Lieutier. Domain theory and differential calculus (Functions of one variable). *Mathematical Structures in Computer Science*, 14(6):771–802, December 2004.
- [19] A. Edalat, A. Lieutier, and D. Pattinson. A computational model for multivariable differential calculus. In V. Sassone, editor, *Proc. FoSSaCS 2005*, volume 3441 of *Lecture Notes in Computer Science*, pages 505–519, 2005. Full paper in "www.doc.ic.ac.uk/~ae/papers/multi.ps".
- [20] A. Edalat and D. Pattinson. Domain theoretic solutions of initial value problems for unbounded vector fields. In M. Escardó, editor, *Proc. MFPS XXI*, volume 155, pages 565–581, 2005.
- [21] A. Edalat and D. Pattinson. Inverse and implicit functions in domain theory. In P. Panangaden, editor, *Proc. 20th IEEE Symposium on Logic in Computer Science (LICS 2005)*, pages 417–426, 2005.
- [22] A. Edalat and D. Pattinson. A domain theoretic account of Euler's method for solving initial value problems. In J. Dongarra, K. Madsen, and J. Wasniewski, editors, *Proc. PARA 2004*, volume 3732 of *Lecture Notes in Comp. Sci.*, pages 112–121, 2006.
- [23] A. Edalat and D. Pattinson. Denotational semantics of hybrid automata. *Journal of Logic and Algebraic Programming*, 73:3–21, 2007.
- [24] A. Edalat and D. Pattinson. A domain-theoretic account of Picard's theorem. *LMS Journal of Computation and Mathematics*, 10:83–118, 2007.
- [25] A. Edalat and P. Sünderhauf. A domain theoretic approach to computability on the real line. *Theoretical Computer Science*, 210:73–98, 1998.
- [26] T. Erker, M. Escardó, and K. Keimel. The way-below relation of function spaces over semantic domains. *Topology and Its Applications*, 89(1–2):61–74, November 1998.
- [27] H. Federer. Geometric Measure Theory. Springer, 1969.
- [28] G. Gierz, K. H. Hofmann, K. Keimel, J. D. Lawson, M. Mislove, and D. S. Scott. *Continuous Lattices and Domains*. Cambridge University Press, UK, 2003.
- [29] R. B. Kirk. Sets which split families of measurable sets. *American Mathematical Monthly*, 79:884–886, 1972.
- [30] J. D. Lawson. Spaces of maximal points. *Mathematical Structures in Computer Science*, 7(5):543–555, 1997.
- [31] J. D. Lawson. Computation on metric spaces via domain theory. *Topology and its applications*, 85:247–263, May 1998.
- [32] G. Lebourg. Generic differentiability of lipschitzian functions. *Transaction of AMS*, 256:125–144, 1979.
- [33] M. B. Pour-El and J. I. Richards. *Computability in Analysis and Physics*. Springer-Verlag, 1988.

- [34] W. Rudin. Principles of Mathematical Analysis. McGraw-Hill, 1964.
- [35] D. R. Sherbert. Banach algebras of lipschitz functions. *Pacific Journal of Mathematics*, 13(4):1387–1399, 1963.
- [36] M. B. Smyth. Topology. In S. Abramsky, D. Gabbay, and T. S. E. Maibaum, editors, *Handbook of Logic in Computer Science*, chapter 5. Oxford University Press, 1992.
- [37] V. Stoltenberg-Hansen, I. Lindström, and E. R. Griffor. *Mathematical Theory of Domains*, volume 22 of *Cambridge Tracts in Theoretical Computer Science*. Cambridge University Press, 1994.
- [38] K. Weihrauch. Computable Analysis (An Introduction). Springer, 2000.