

Decision Forests for Tissue-specific Segmentation of High-grade Gliomas in Multi-channel MR

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Goal: Automatic segmentation of tumorous tissue types

Active Cells (AC), Necrotic Core (NC), and Edema (E)

Challenge:

High variability in structure, location, shape and appearance

Motivation:

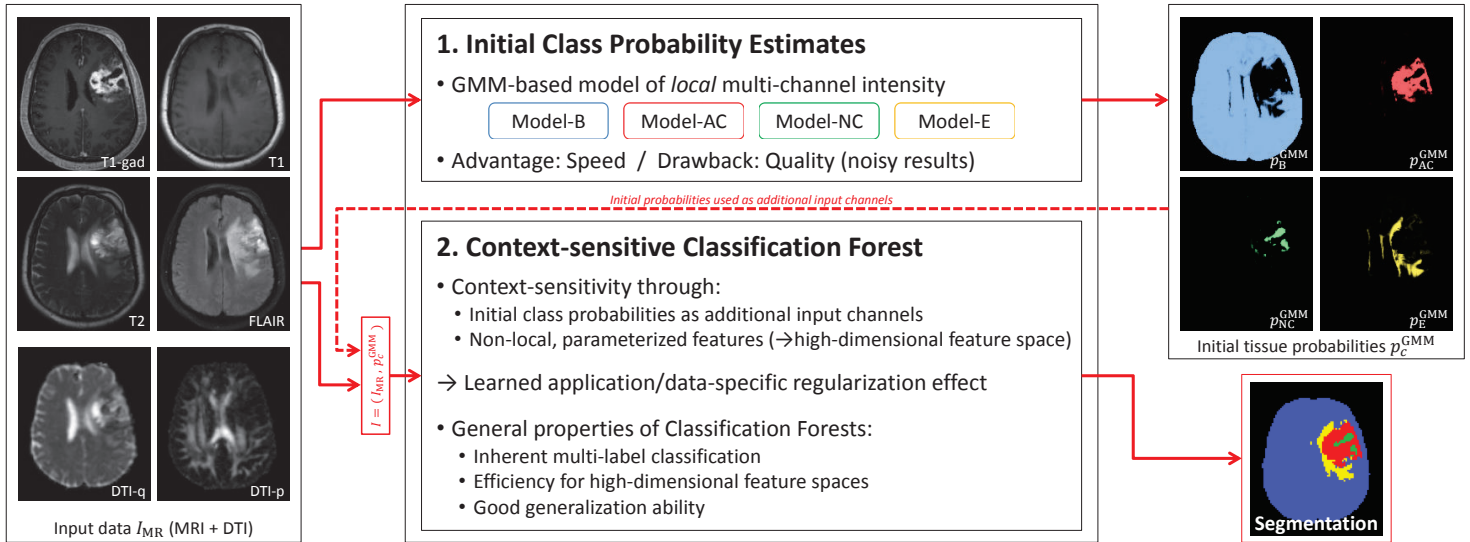
Clinical practice: Time savings

Initialize interactive segmentation for treatment

Research: Volumetric measurements for individual tissues

Quantification of progress/treatment in follow-up and research studies

Our Approach: Context-sensitive Classification Forest



Initial Probabilities: GMM-based posteriors

- Train likelihood model of local, multi-channel MR intensity for each class c (GMM-based)

$$p(I_{MR}|c)$$

- Probability of class c given intensity at point x (posterior probability)

$$p_c^{GMM}(x) = p^{GMM}(c|I_{MR}(x)) = \frac{p(I_{MR}(x)|c) p_c}{\sum_{c_j} p(I_{MR}(x)|c_j) p_{c_j}}$$

with empirical class probability p_c

Forest Feature Types: non-local, parametric, intensity-based

- Type 1: Intensity Difference**

$$f_{j_1, j_2, v}^1(x, I) = I_{j_1}(x) - I_{j_2}(x + v)$$

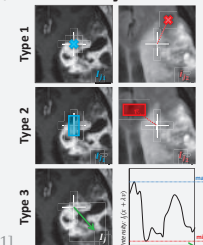
- Type 2: Intensity Difference of Region Means**

$$f_{j_1, j_2, s_1, s_2, v}^2(x, I) = \mu(N_{j_1}^{s_1}(x)) - \mu(N_{j_2}^{s_2}(x + v))$$

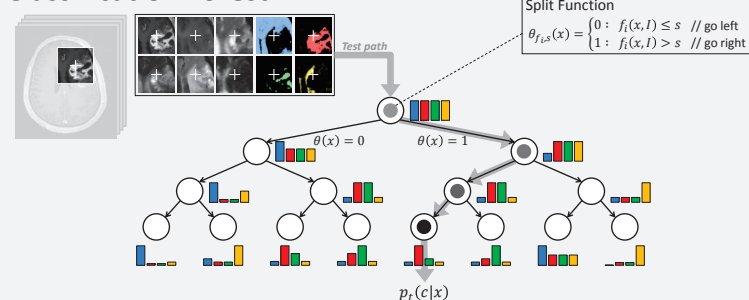
- Type 3: Intensity Range along Ray**

$$f_{j, v}^3(x, I) = \max_{\lambda} I_j(x + \lambda v) - \min_{\lambda} I_j(x + \lambda v)$$

$v = (v_x, v_y, v_z)$: offset vector; N^s : cuboid with side lengths $s = (s_x, s_y, s_z)$; $\lambda \in [0, 1]$



Classification Forest



- Context-sensitive Features (data representation)**
 - Feature vector $f(x, I)_p$ represents a data point at x (spatial point in scan) by non-local, parameterized, and intensity-based features
 - Feature space: $\mathcal{F} = \{ f^t(x, I)_{p_t} : t \in \text{Type}, p \in P \subset \mathbb{Z}^{|p_t|} \}$
 - \rightarrow very high dimension of \mathcal{F} : number of unique parameter settings p_t for all feature types t
 - N.B.:* Automatically learned feature parameters, instead of manual feature design

- Training (learning from training data with manual label annotations)**

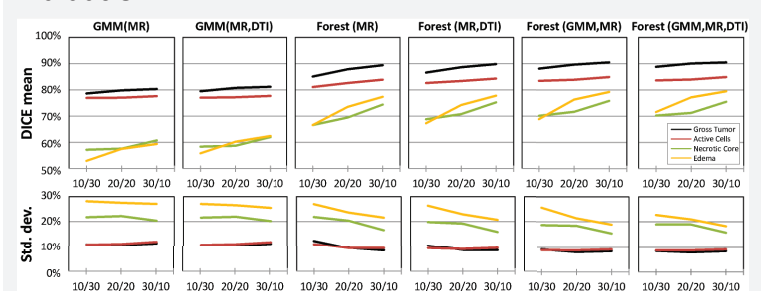
- Determine split functions $\theta_{f_i, s}$ at nodes (\rightarrow tree structure, statistics at leaves): Estimate splitting dimension f_i (from randomly chosen feature subspace \mathcal{F}') and split threshold s for f_i , so as to optimize Information Gain ('clustering of classes')

- Testing (determining the label for unseen data point)**

- For each tree t , apply split tests to reach a leaf, and use the resulting $p_t(c|x)$ in overall prediction

$$p(c|x) = \frac{1}{n} \sum_{t=1}^n p_t(c|x)$$

Evaluation



Dataset of High-grade Glioma Patients

- 40 multi-channel MR scans (pre-treatment): T1-gad, T1, T2, FLAIR, DTI-p, DTI-q
- Pre-processing: skull-stripping, affine intra-patient registration, resampling to 2mm, intensity mean alignment per channel (global multiplicative factor)
- Manual segmentations of AC, NC, E in 3D; gross tumor: GT = AC U NC

Experiment Setup

- Leave-N-out with $N=10, 20, 30 \rightarrow$ Training/Testing ratios of 10/30, 20/20, 30/10
- Repeated 10x with random test set draws \rightarrow 600 test segmentations per approach
- Evaluated approaches (each with and without DTI channels):
 - Baseline: Initial probabilities (GMM-based, local intensity only)
 - Forest without initial probabilities
 - Proposed approach: Forest with initial probabilities
- Settings: number of trees $n=40$, depth $d=20$, per-node-feature-subspace size $|\mathcal{F}'|=200$
- Timings: training per tree: 10-25 min, testing per image 2-3 min