Lecture 14

Let’s put together a Manual Processor
The processor

Inside every computer there is at least one processor which can take an instruction, some operands and produce a result.

Processors can be operated in different ways for example as:

- A central processor unit (CPU)
- A peripheral of another computer
  - Array Processor
  - Graphics Processor (GPU)
- A manually programmed processor
  - Stand alone calculator

We will now design a manual (or externally programmed) processor.
The Block Diagram of a Processor

Both the data and the instructions will be binary numbers. The processing will be a sequence of one or more steps controlled by a clock. The result will be a binary number.

![Block Diagram of a Processor](image-url)
An 8 bit processor architecture

We will base our design on the von Neumann architecture (1945) which subdivided the components of a processor into arithmetic units and registers, and had a common input stream for data and instructions. We will carry out processing on 8 bit bytes (similar to the processors of the 1970’s).
The Actions of a Simple Processor

As an example we will find the average of two numbers.

Result = \( \frac{A+B}{2} \)

Because of our choice of architecture all numbers must be represented in 8 bits.

Thus the sum \( A+B \) must be less than 256.

We will see later on how to extend the processing to cope with larger numbers.
The Actions of a Simple Processor

The following steps are carried out:

1. The first number is set up on the input lines and stored in a register (A)
2. The second number is set up on the input lines and stored in a register (B)
3. The arithmetic circuits are set up to add register A to register B.
4. The resulting sum of A and B is transferred back into register A.
5. The shifting circuits are set up to shift the contents of register A one bit to the right.
6. The result is loaded onto an output register (Res).

The processor is a **sequential digital circuit**
Designing a Processor

From the example we see that we need a number of different components to make our processor:

Registers:
- Registers to store the input data (A) & (B)
- A register to store the result (Res)
- A one bit register to store the carry (C)(if any)
- A register to store the instruction (IR)

Arithmetic Circuits:
- An 8 bit adder
- An 8 bit shifter
The data path diagram

The example also suggests that the registers and arithmetic units must be connected in a specific way. A simple data path diagram might be:
The data path diagram

Note the following about the data path diagram:

- There is no information about when the data transfers occur. The diagram shows only the possible paths where data can be transferred.
- The arithmetic and shift operations are done by combinational circuits without more registers.
- The function of the arithmetic circuits are controlled by the bits in the instruction register.
- The processor is unable to execute further operations on the results register.
The Arithmetic-Logic Unit (ALU)

We now design one important component of the central processor unit - the ALU - which carries out arithmetic or logic operations on its two inputs A and B.

We will design a 4-bit unit that can be used as a building block to construct ALUs of any precision.

The select lines (S2, S1, S0) determine the function of A and B that appears on the output.
The ALU functions

The selection bits determine which out of 8 possible functions is used.

<table>
<thead>
<tr>
<th>Selection</th>
<th>Function</th>
<th>When Cin = 1 three operations change:</th>
</tr>
</thead>
<tbody>
<tr>
<td>000</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>001</td>
<td>B-A</td>
<td></td>
</tr>
<tr>
<td>010</td>
<td>A-B</td>
<td></td>
</tr>
<tr>
<td>011</td>
<td>A plus B</td>
<td>011: Res = A plus B plus 1</td>
</tr>
<tr>
<td>100</td>
<td>A XOR B</td>
<td></td>
</tr>
<tr>
<td>101</td>
<td>A OR B</td>
<td>010: Res = A - B - 1</td>
</tr>
<tr>
<td>110</td>
<td>A AND B</td>
<td>001: Res = B - A - 1</td>
</tr>
<tr>
<td>111</td>
<td>-1</td>
<td></td>
</tr>
</tbody>
</table>
Designing the ALU

An arithmetic logic unit is a simple combinatorial circuit that can be built from components that we have already designed.

To provide the arithmetic functions we use adders and subtractors.
Designing the ALU

The logic functions are provided by simple gates.

We need a multiplexer for each bit of the ALU to make the function selection.
Designing the ALU

To finish the job we need one more multiplexer to provide the carry out.
Extending the ALU to 8 bits

We can now follow the functional approach and extend our ALU to 8 bits.

Similarly, we can scale it up to 32 bits or larger as the need arises.
Organising the Carry

We can use a 2-to-1 multiplexer to allow two different carry input bits. The Carry in may be set to 1 or to the previous Carry out.

The carry may be set to zero by setting the register C to zero. Thus the full range of arithmetic operations can be used.
Problem

Why set the carry this way? Wouldn’t it be simpler to connect the multiplexer inputs to 1 & 0 rather than using register C?
The Shifter

- Earlier in the course we discussed a specialised register, called the shift register, which could shift its contents left or right depending on a multiplexer selection.
- We could incorporate such a shift register in our design, but instead we will make use of a simpler shifter which does not store the result.
- We can achieve all the functionality we need by using multiplexers, and avoid the need for complex clocking arrangements.
A four function Shifter

Our first shifter design will have four functions determined by two selection bits and will have a data length of eight bits.
The Shifter Functions

The basic shifter will perform four operations depending on its two control inputs. These are:

- 00 Hold
- 01 Arithmetic shift left (with carry in)
- 10 Arithmetic shift right
- 11 Rotate right

It is implemented simply using one multiplexer per bit.
Arithmetic Shifts

Arithmetic Left Shift

Arithmetic Right Shift

Rotate Right
The four function shifter circuit

<table>
<thead>
<tr>
<th>Code</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>Hold</td>
</tr>
<tr>
<td>01</td>
<td>Arithmetic Shift Left</td>
</tr>
<tr>
<td>10</td>
<td>Arithmetic Shift Right</td>
</tr>
<tr>
<td>11</td>
<td>Rotate Right</td>
</tr>
</tbody>
</table>
Adding more functions to the Shifter

There are many other different possible shifts that programmers may want to use. One example is:

Logical Shift Right:

This could be done by using first an ALU operation (Data AND 11111110) followed by a rotate right, but that would involve more processing steps and therefore be slow.
The eight function shifter

A variety of useful shifts are defined in this table.

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>unchanged</td>
<td></td>
<td>unchanged</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>left</td>
<td></td>
<td>rotate left</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>left</td>
<td>0</td>
<td>arithmetic left shift</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
<td>left</td>
<td>Cin</td>
<td>left shift with carry</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
<td>right</td>
<td></td>
<td>rotate right</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>right</td>
<td>0</td>
<td>logical right shift</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>right</td>
<td>Input[7]</td>
<td>arithmetic right shift</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td>right</td>
<td>Cin</td>
<td>shift right with carry</td>
</tr>
</tbody>
</table>
The circuit of the eight function shifter

It is a trivial matter to design a similar shifter of any precision.
The Data Path Diagram Again

We now can put more detail onto the data path diagram:

Note that we have not used the Cin input to the shifter in this processor. It will be connected to logic-0.