

## Lecture 14

Let's put together a Manual Processor

# The processor

Inside every computer there is at least one processor which can take an instruction, some operands and produce a result.

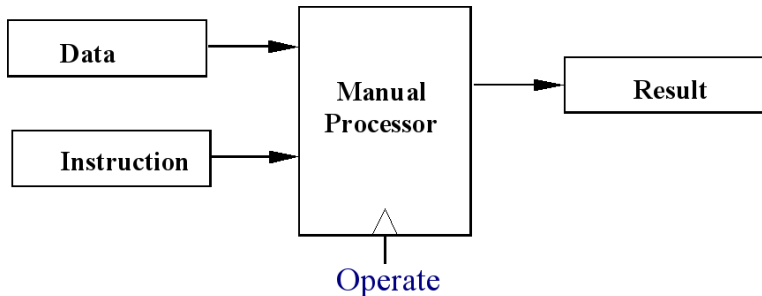
Processors can be operated in different ways for example as:

- A central processor unit (CPU)
- A peripheral of another computer
  - Array Processor
  - Graphics Processor (GPU)
- A manually programmed processor
  - Stand alone calculator

We will now design a manual (or externally programmed) processor.

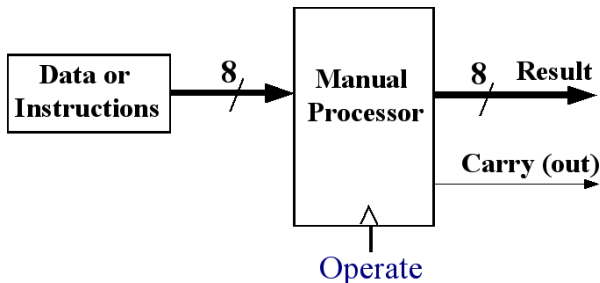
## The Block Diagram of a Processor

Both the data and the instructions will be binary numbers. The processing will be a sequence of one or more steps controlled by a clock. The result will be a binary number.



## An 8 bit processor architecture

We will base our design on the von Neumann architecture (1945) which subdivided the components of a processor into arithmetic units and registers, and had a common input stream for data and instructions. We will carry out processing on 8 bit bytes (similar to the processors of the 1970's).



# The Actions of a Simple Processor

As an example we will find the average of two numbers.

$$\text{Result} = (A+B)/2$$

Because of our choice of architecture all numbers must be represented in 8 bits.

Thus the sum  $A+B$  must be less than 256.

We will see later on how to extend the processing to cope with larger numbers.

# The Actions of a Simple Processor

The following steps are carried out:

1. The first number is set up on the input lines and stored in a register (A)
2. The second number is set up on the input lines and stored in a register (B)
3. The arithmetic circuits are set up to add register A to register B.
4. The resulting sum of A and B is transferred back into register A.
5. The shifting circuits are set up to shift the contents of register A one bit to the right.
6. The result is loaded onto an output register (Res).

The processor is a **sequential digital circuit**

# Designing a Processor

From the example we see that we need a number of different components to make our processor:

Registers:

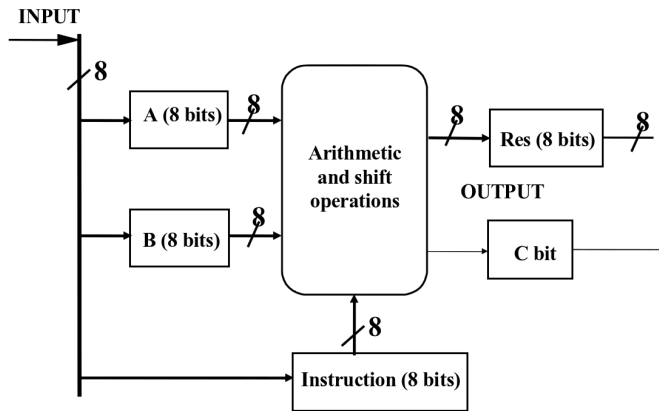
- Registers to store the input data (A) & (B)
- A register to store the result (Res)
- A one bit register to store the carry (C)(if any)
- A register to store the instruction (IR)

Arithmetic Circuits:

- An 8 bit adder
- An 8 bit shifter

## The data path diagram

The example also suggests that the registers and arithmetic units must be connected in a specific way. A simple data path diagram might be:





## The data path diagram

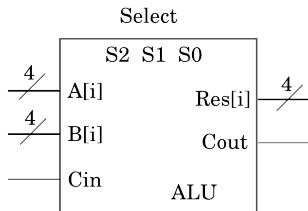
Note the following about the data path diagram:

- There is no information about when the data transfers occur. The diagram shows only the possible paths where data can be transferred.
- The arithmetic and shift operations are done by combinational circuits without more registers.
- The function of the arithmetic circuits are controlled by the bits in the instruction register.
- The processor is unable to execute further operations on the results register.

## The Arithmetic-Logic Unit (ALU)

We now design one important component of the central processor unit - the ALU - which carries out arithmetic or logic operations on its two inputs A and B.

We will design a 4-bit unit that can be used as a building block to construct ALUs of any precision.



The select lines (S2, S1, S0) determine the function of A and B that appears on the output.

## The ALU functions

The selection bits determine which out of 8 possible functions is used.

Selection	Function
000	0
001	B-A
010	A-B
011	A plus B
100	A XOR B
101	A OR B
110	A AND B
111	-1

When  $C_{in} = 1$  three operations change:

011: Res = A plus B plus 1

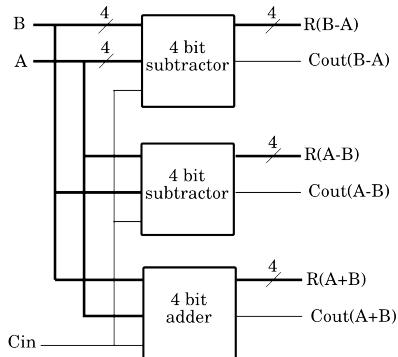
010: Res = A - B - 1

001: Res = B - A - 1

# Designing the ALU

An arithmetic logic unit is a simple combinational circuit that can be built from components that we have already designed.

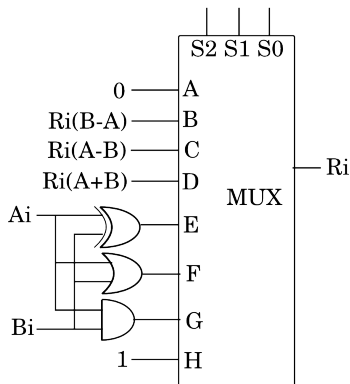
To provide the arithmetic functions we use adders and subtractors.



# Designing the ALU

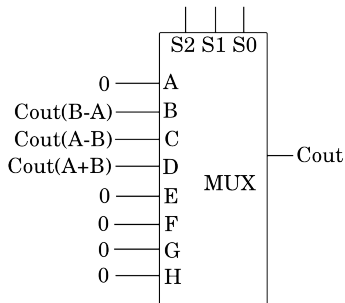
The logic functions are provided by simple gates.

We need a multiplexer for each bit of the ALU to make the function selection.



## Designing the ALU

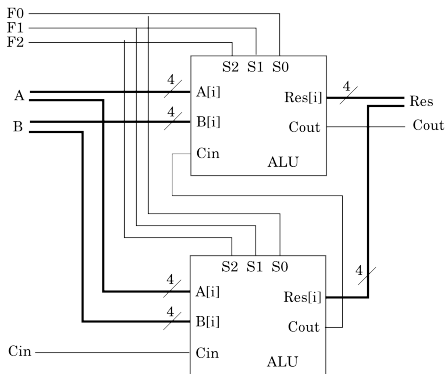
To finish the job we need one more multiplexer to provide the carry out.



## Extending the ALU to 8 bits

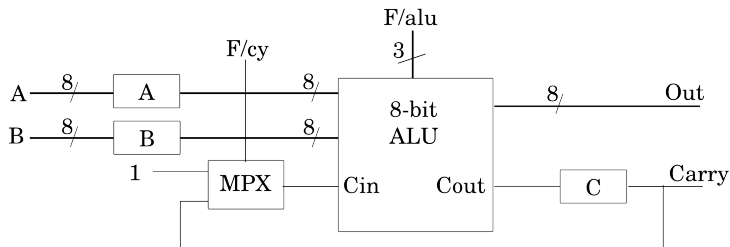
We can now follow the functional approach and extend our ALU to 8 bits

Similarly we can scale it up to 32 bits or larger as the need arises.



## Organising the Carry

We can use a 2-to-1 multiplexer to allow two different carry input bits. The Carry in may be set to 1 or to the previous Carry out.

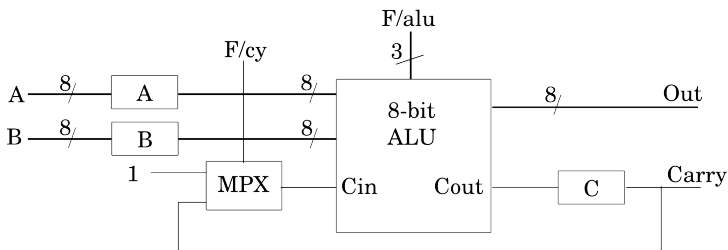


The carry may be set to zero by setting the register C to zero. Thus the full range of arithmetic operations can be used.



## Problem

Why set the carry this way? Wouldn't it be simpler to connect the multiplexer inputs to 1 & 0 rather than using register C?

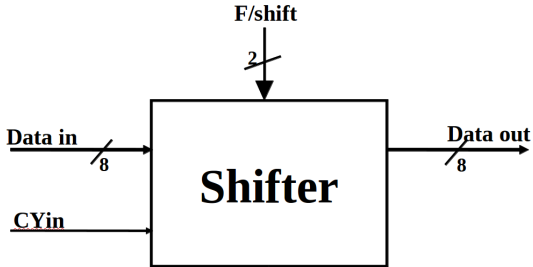


# The Shifter

- Earlier in the course we discussed a specialised register, called the shift register, which could shift its contents left or right depending on a multiplexer selection.
- We could incorporate such a shift register in our design, but instead we will make use of a simpler shifter which does not store the result.
- We can achieve all the functionality we need by using multiplexers, and avoid the need for complex clocking arrangements.

# A four function Shifter

Our first shifter design will have four functions determined by two selection bits and will have a data length of eight bits.



# The Shifter Functions

The basic shifter will perform four operations depending on its two control inputs. These are:

- 00 Hold
- 01 Shift left with carry
- 10 Arithmetic shift right
- 11 Rotate right

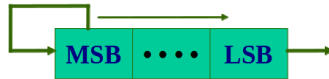
It is implemented simply using one multiplexer per bit.

# Arithmetic Shifts

Left Shift with Carry



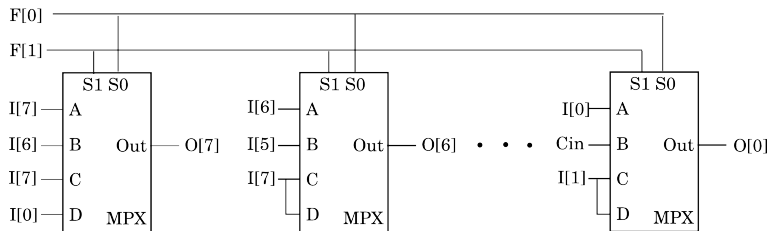
Arithmetic Right Shift



Rotate Right



# The four function shifter circuit



00 (A)	01 (B)	10 (C)	11 (D)
Hold	Shift Left with Carry	Arithmetic Shift Right	Rotate Right

## Adding more functions to the Shifter

There are many other different possible shifts that programmers may want to use. One example is:



Logical Shift Right:

This could be done by using first an ALU operation (Data AND 11111110) followed by a rotate right, but that would involve more processing steps and therefore be slow.

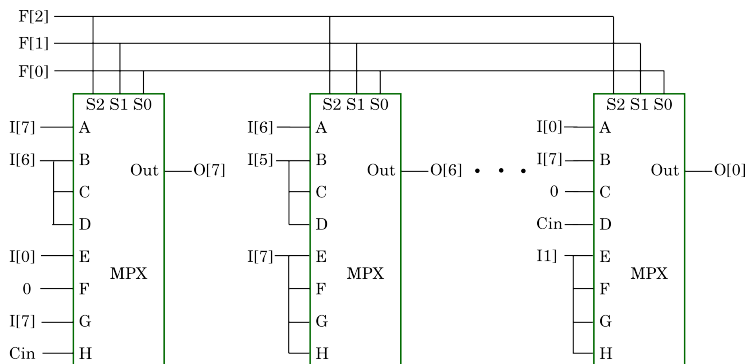
## The eight function shifter

A variety of useful shifts are defined in this table.

<b>F[2]</b>	<b>F[1]</b>	<b>F[0]</b>	<b>Shift</b>	<b>Carry</b>	<b>Function</b>
0	0	0			unchanged
0	0	1	left		rotate left
0	1	0	left	0	arithmetic left shift
0	1	1	left	Cin	left shift with carry
1	0	0	right		rotate right
1	0	1	right	0	logical right shift
1	1	0	right	Input[7]	arithmetic right shift
1	1	1	right	Cin	shift right with carry



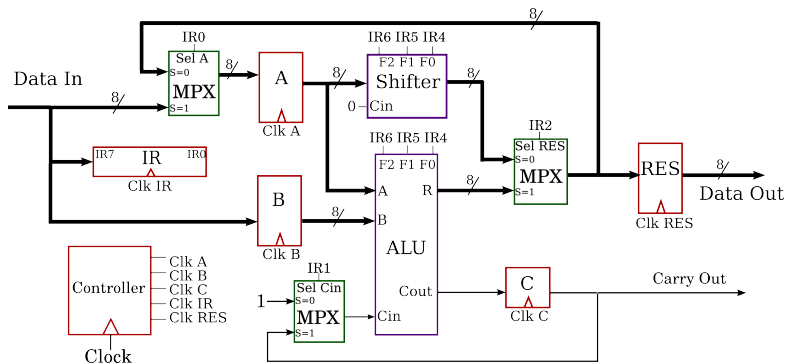
## The circuit of the eight function shifter



It is a trivial matter to design a similar shifter of any precision.

## The Data Path Diagram Again

We now can put more detail onto the data path diagram:



Note that we have not used the **Cin** input to the shifter in this processor. It will be connected to logic-0.