

Verifying and timing concurrent instruments

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thanks to Sam Aaron for some of these slides & inspiration

A talk about...

- Verification
- Analysis
- Programming
- Music
- Outreach
- Education


```

(ns meta-ex.shader
  (:use [overtone.live])
  (:require [shadertone.tone :as t]))

(t/start-fullscreen "resources/shaders/fireball.glsl")

(t/start-fullscreen "resources/shaders/sine_dance.glsl")
(t/start-fullscreen "resources/shaders/electron.glsl")

(t/start-fullscreen "resources/shaders/spectrograph.glsl"
  ;; this puts the FFT data in iChannel0 and a texture of the
  ;; previous frame in iChannel1
  :textures [:overtone-audio :previous-frame])

(t/start-fullscreen "resources/shaders/menger-san.glsl"
  ;; this puts the FFT data in iChannel0 and a texture of the
  ;; previous frame in iChannel1
  )

(t/start-fullscreen "resources/shaders/zoomwave.glsl"
  :textures [ :overtone-audio :previous-frame ])

(t/start-fullscreen "resources/shaders/wave.glsl" :textures [ :overtone-audio ])

(t/start-fullscreen "resources/shaders/simpletex.glsl"
  :textures [:overtone-audio "resources/textures/granite.png"
    "resources/textures/towel.png"])

(t/stop)

(demo 5 (* (sin-osc:kr 0.3) (saw [200 101])) )

(t/start-fullscreen "resources/shaders/simplecube.glsl" :textures ["resources/textures/buddha_*.jpg"])

(defsynth vvv
  (let [a (+ 300 (* 50 (sin-osc:kr (/ 1 3))))
        b (+ 300 (* 100 (sin-osc:kr (/ 1 5))))
        _ (tap "a" 60 {a2k a})
        _ (tap "b" 60 {a2k b})]
    (out 0 (pan2 (+ (sin-osc a)
                    (sin-osc b))))))

(def v (vvv))

(t/start-fullscreen "resources/shaders/vvv.glsl"
  :user-data { "iA" (atom {:synth v :tap "a"})
              "iB" (atom {:synth v :tap "b"}) })

(kill v)
(stop)

```

```

(ns meta-ex.grumbles
  (:use [overtone.live]
        [meta-ex.kit.mixer]
        [meta-ex.sets.ignite]))

;; Inspired by an example in an early chapter of the SuperCollider book

(defsynth grumble [speed 6 freq-mul 1 out-bus 0 amp 1]
  (let [snd (mix (map f (= (sin-osc (* % freq-mul 100))
                              (max 0 (+ (lf-noiselikr (lag speed 60))
                                           (line:kr 1 -1 30 :action FREE))))
                [1 (/ 2 3) (/ 3 2) 2]))]
    (out out-bus (* amp (pan2 snd (sin-osc:kr 50))) )))

(defsynth grumble [speed 6 freq-mul 1 out-bus 0 amp 1]
  (let [snd (mix (map f (= (square (* % freq-mul 100))
                              (max 0 (+ (lf-noiselikr (lag speed 60))
                                           (line:kr 1 -1 30 :action FREE))))
                [1 (/ 2 3) (/ 3 2) 2]))]
    (out out-bus (* amp (pan2 (lpf snd (mouse-x 200 2000)) (sin-osc:kr 50))
  )))

~ n

(defonce grumble-g (group))

(def ob (nkmx :s1))
(def ob 0)
(volume 0.55)

(grumble :head grumble-g :freq-mul 2 :out-bus ob :amp 2)
(grumble :head grumble-g :freq-mul 1.8 :out-bus ob :amp 2)
(grumble :head grumble-g :freq-mul 1.5 :out-bus ob :amp 2)

~ ~

(do (grumble [:head grumble-g] :freq-mul 1 :out-bus ob :amp 1)
    (grumble [:head grumble-g] :freq-mul 0.5 :out-bus ob :amp 1))

(do (grumble [:head grumble-g] :freq-mul 1 :out-bus ob :amp 3)
    (grumble [:head grumble-g] :freq-mul 0.5 :out-bus ob :amp 2))
(ctl grumble-g :speed 1997)

(defn sin-ctl
  (ctl-id arg-map
    (reduce (lambda [res [k v]]
              (let [idx (synth-arg-index meta-mix k)]
                (merge res (map (lambda ([k v])
                                   [(keyword (str (name k) "-" idx) v)]
                                   v))))
            {}
            arg-map))

(sin-ctl nkmx-sctl :s1
  :amp 1
  :freq-mul 0
  :mul 1
  :add 0.5)

(ctl nkmx-sctl :s1
  :freq-mul-7 0
  :mul-7 1
  :add-7 0.5)

(ctl nkmx-sctl :s1
  :freq-mul-13 1/8
  :mul-13 1
  :add-13 0.5)

::(status)

```

```

1  [|||||] 18.1% Tasks: 248 total, 0 running
2  [|||] 1.3% Load average: 1.72 1.61 1.59
3  [|||] 6.5% Uptime: 17:27:12
4  [|||] 1.3%
5  [||||] 8.4%
6  [|||] 1.3%
7  [||||] 9.6%
8  [|||] 0.8%
Mem[|||||||||||||||||]14939/16384MB
Swp[|] 7/1024MB

PID USER PRI NI VIRT RES SHR S CPU% MEM% TIME+ Command
4425 sam 31 0 2407M 1668 0 C 0.0 0.0 0:00.00 http
1 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (launched)
11 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (UserEventAgent)
12 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (kextd)
13 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (taskgated)
14 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (notified)
15 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (securityd)
16 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (diskarbitrationd)
17 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (configd)
18 root 0 0 0 0 0 7 0.0 0.0 0:00.00 (powerd)

F1Help F2Setup F3Search F4Invert F5Free F6SortBy F7Nice F8Nice F9Kill F10Quit

```

```
# meta-ex
```

—> Connection established

www.ck12.org

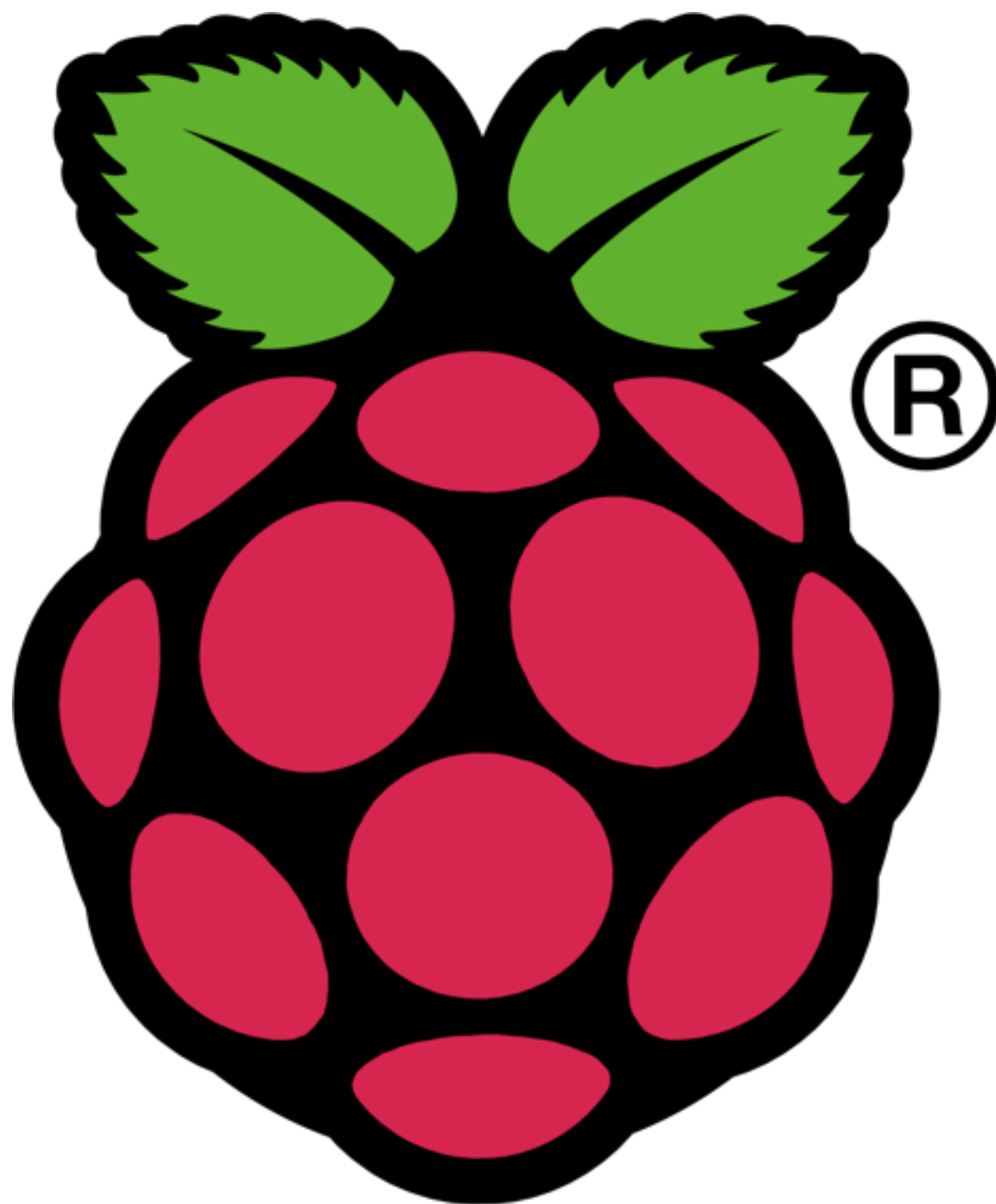
Collaborative Programmable Music. v0.10-dev

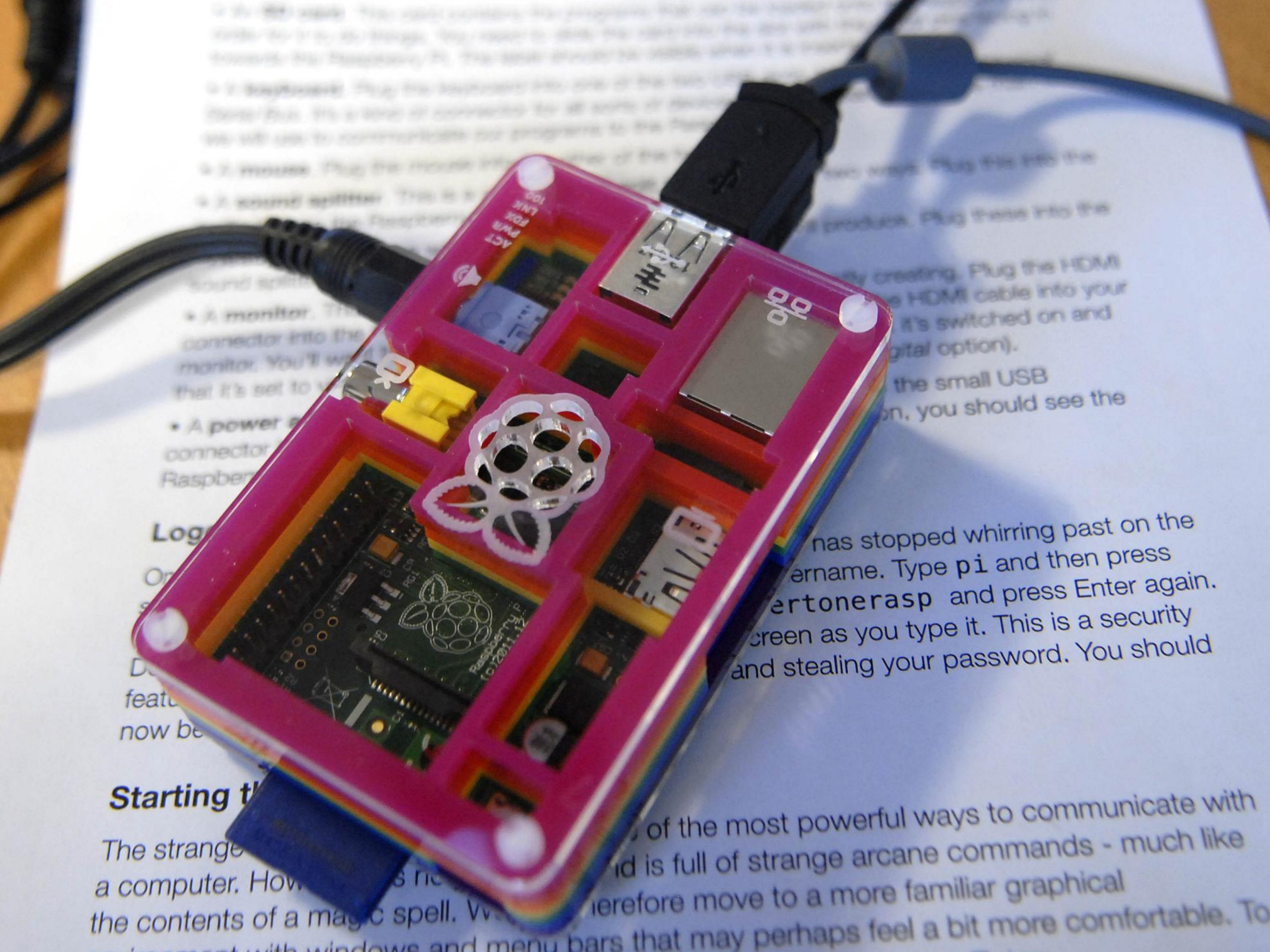
Hello Sam. Do you feel it? I do. Creativity is rushing through your veins today!

```

nil
user=> Loading shader from file: resources/shaders/fireball.glsl
Loading shader from file: resources/shaders/menger-san.glsl
Loading shader from file: resources/shaders/sine_dance.glsl
Loading shader from file: resources/shaders/fireball.glsl
Loading shader from file: resources/shaders/spectrograph.glsl
setting up :previous-frame texture
Loading shader from file: resources/shaders/electron.glsl
(use 'o(use 'overtone.live)2014-09-04 16:26:18.480 java[4344:00b] Unknown modifier
with keycode: 0

```



...the Raspberry Pi. The Raspberry Pi is a small, single-board computer that can be used for a variety of projects. It is a great way to learn about computers and programming. It is also a great way to create something new. The Raspberry Pi is a small, single-board computer that can be used for a variety of projects. It is a great way to learn about computers and programming. It is also a great way to create something new.

- A monitor. The monitor is connected to the Raspberry Pi via an HDMI cable. You'll want to make sure that it's set to the correct input on the monitor.
- A power source. The Raspberry Pi is powered by a 5V USB power source. You can use a USB power bank or a USB power adapter to power the Raspberry Pi.

Log

...has stopped whirring past on the screen. Type `pi` and then press Enter. Type `raspberry` and press Enter again. You should see the screen as you type it. This is a security feature to prevent password theft and stealing your password. You should

Starting t

The strange world of the most powerful ways to communicate with a computer. How it is full of strange arcane commands - much like the contents of a magic spell. We therefore move to a more familiar graphical user interface with windows and menu bars that may perhaps feel a bit more comfortable. To



Sonic Pi



The following instructions are for searching for:

- 1. How to use the components of a program to together.
- 2. Understand how a computer that will work as computer code.
- 3. How to use a simple computer program.

Objectives:

- 1. How to use the components to get your program to run and working on your code, use the guide.
- 2. Using your knowledge, use your program.
- 3. How to be able to write the code and understand how to use.
- 4. How to use it.
- 5. How the program will work, check on the code using, go to programming, and select.

What you will do:

- 1. If you are: 100% to 100%
- 2. If you are: 100% to 100%

What you will do:

- 1. How the program will work, check on the code using, go to programming, and select.





DON VALLEY BOWL
10th & 11th JUNE 2011
ARCTIC MONKEYS
MILES KANE
THE VACCINES
ANNA CALVI
MABEL LOVE
DEAD SONS

```
end  
sleep 0.1  
play 10, 1000, 0.5  
sleep 0.1  
on thread do  
  play 10  
  sample 1000000  
end  
sleep 0.1  
loop  
end  
with 10000 1000000000  
on thread do  
  play 10, 1000, 0.5  
  sample 1000000  
end  
sleep 0.1  
play 10, 1000, 0.5  
sleep 0.1  
on thread do
```

CODE LIKE A ROCKSTAR



LEARN TO CODE AND MAKE
MUSIC WITH (((Sonic π)))
VISIT [RASPBERRYPI.ORG](https://raspberrypi.org) TO FIND OUT MORE!

BE PART OF THE
UK'S FIRST EVER
LIVE CODING
SUMMER
SCHOOL!

SONIC PI

LIVE & CODING

MUSIC
TECHNOLOGY
ART

AT CAMBRIDGE JUNCTION
MON 28 JUL - FRI 01 AUG
JUNCTION.CO.UK

Sonic Pi v2.0

COMPETITION FOR SCHOOLS



Are you the next Daft Punk?

Make sure there's more than a screwdriver in your sonic toolbox.

Sonic Pi is a way to get creative with music and computing. We're hunting down the UK's best young musical coding talent from outer space: is it you? Create a 2-minute or 200-line piece of music on the theme **Space Wonders** with Sonic Pi v2.0 on a Raspberry Pi, and you could be in with a chance of winning one of hundreds of Raspberry Pi kits for yourself and your school, along with workshops with musical artists Juneau Projects, and with live coder-musician Sam Aaron!

Check out raspberrypi.org/competitions/sonic-pi to find out how to enter.



π)))
Sonic Pi

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coder-musician Sam Aaron,
workshops Juneau Projects, and with live
kits for yourself and your school, along with workshops with
musical artists Juneau Projects, and with live coder-musician Sam Aaron!

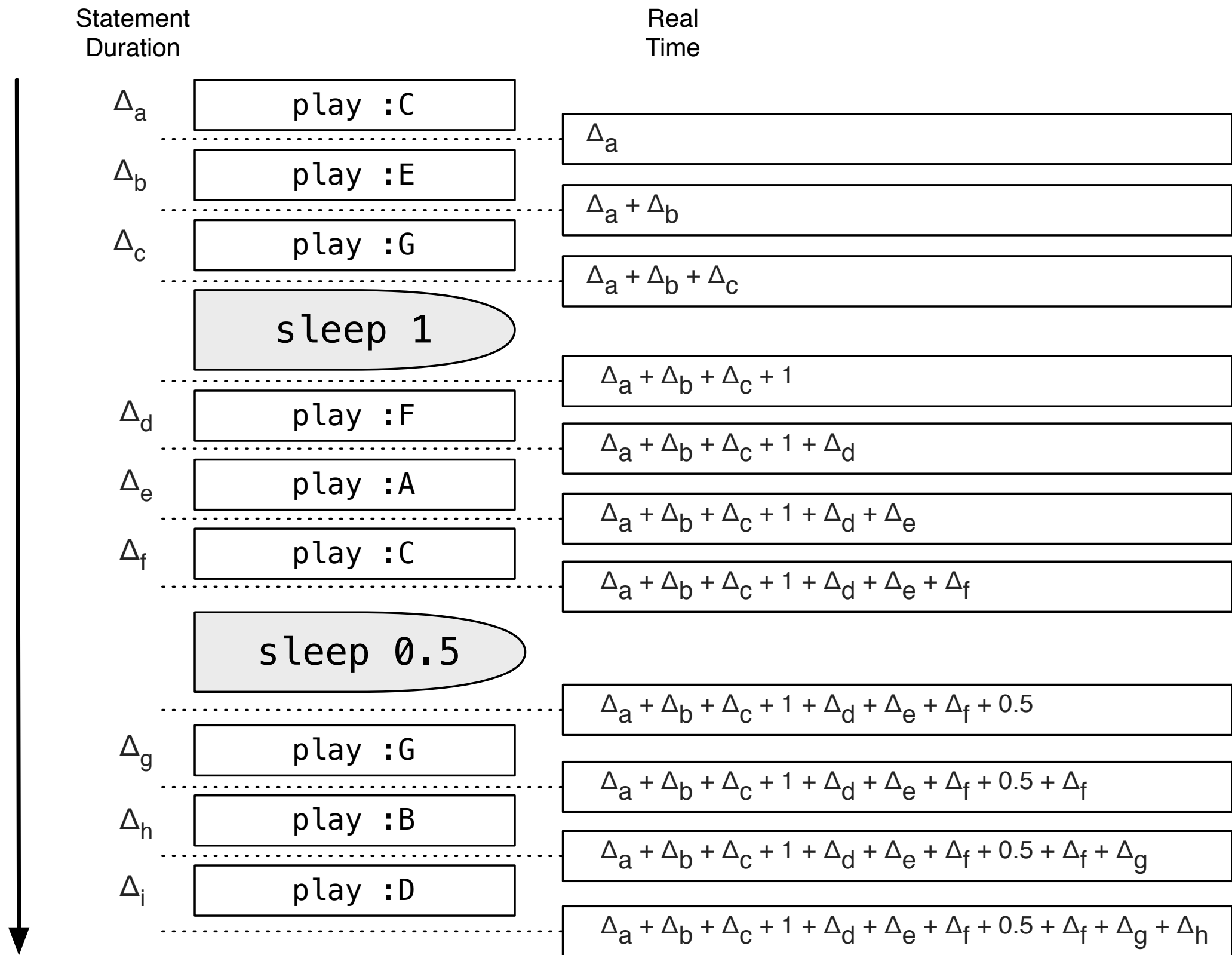


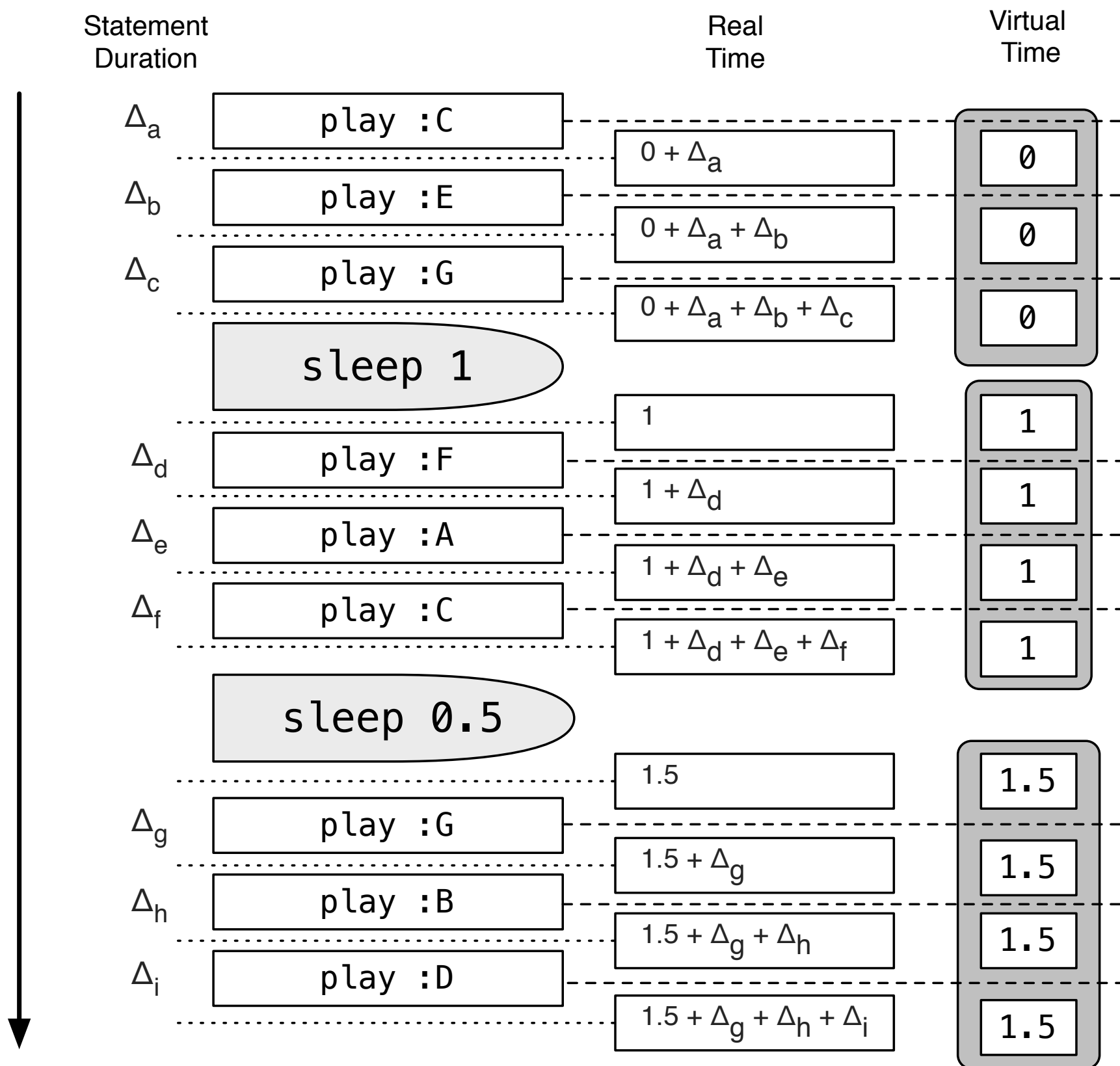
sonic pi
π)))



Demo #1

play, sleep, loops, iteration





A formal semantics for sleep

- Abstract interpretation “time system”
- Denotational semantics (via monads)
- Prove “time safety” = prove semantics sound wrt. time system

“Temporal semantics for a live coding language”

Aaron, Orchard, Blackwell, FARM 2014

Simplified Sonic Pi v2.0 syntax

$$P ::= P; S \mid \emptyset$$

$$S ::= E \mid v = E$$

$$E ::= \text{sleep } \mathbb{R}_{\geq 0} \mid A^i \mid v$$

Time system

$[—]_v$: virtual time

$$[\emptyset]_v = 0$$

$$[P; v = E]_v = [P]_v + [E]_v$$

$$[\text{sleep } t]_v = t$$

$$[A^i]_v = 0$$

$[—]_t$: actual time

$$[\emptyset]_t \approx 0$$

$$[P; \text{sleep } t]_t \approx ([P]_v + t) \max [P]_t$$

$$[P; v = A^i]_t \approx [P]_t + [A^i]_t$$

e.g. $P; \text{sleep } 2$ where $[P]_t = 1, [P]_v = 0$

$$\therefore [P; \text{sleep } 2]_t = (0 + 2) \max 1 = 2$$

$$[P; \text{sleep } 2]_v = 2$$

Time system

$[—]_v$: virtual time

$$[\emptyset]_v = 0$$

$$[P; v = E]_v = [P]_v + [E]_v$$

$$[\text{sleep } t]_v = t$$

$$[A^i]_v = 0$$

$[—]_t$: actual time

$$[\emptyset]_t \approx 0$$

$$[P; \text{sleep } t]_t \approx ([P]_v + t) \max [P]_t$$

$$[P; v = A^i]_t \approx [P]_t + [A^i]_t$$

e.g. $P; \text{sleep } 1$ where $[P]_t = 2, [P]_v = 0$

$$\therefore [P; \text{sleep } 1]_t = (0 + 1) \max 2 = 2$$

$$[P; \text{sleep } 1]_v = 1$$

Time system

$[—]_v$: virtual time

$$[\emptyset]_v = 0$$

$$[P; v = E]_v = [P]_v + [E]_v$$

$$[\text{sleep } t]_v = t$$

$$[A^i]_v = 0$$

$[—]_t$: actual time

$$[\emptyset]_t \approx 0$$

$$[P; \text{sleep } t]_t \approx ([P]_v + t) \max [P]_t$$

$$[P; v = A^i]_t \approx [P]_t + [A^i]_t$$

Lemma 1. *For any program P then $[P]_t \geq [P]_v$.*

Denotational semantics

- State for *virtual time*
- Read only *actual time* (updated from OS)

`Temporal a = (start time, current time) →`
`(old vtime → (a, new vtime))`

$\llbracket P \rrbracket_{\text{top}} : \text{Temporal } ()$

- Paper describes core monadic semantics with Haskell

`Temporal a = (Time, Time) →`
`(VTime → IO (a, VTime))`

Time safety

soundness of the denotational semantics

- wrt. virtual time

Lemma 2. $[runTime \llbracket P \rrbracket]_v = \llbracket P \rrbracket_v$

- wrt. actual time (modulo constant sequential overhead)

Lemma 3. $[runTime \llbracket P \rrbracket]_t \approx \llbracket P \rrbracket_t$

Demo #2

“live loops”, synchronisation

Two problems

- Thrashing (zero time sleep)
- Deadlock

Preventing thrashing

- Perform virtual time analysis
- Ensure that:

$$[P]_v \neq 0$$

- Current system needs extending to concurrent & higher-order setting

Extended time system

$$[\text{seq}] \frac{[P]_v = p \quad [E]_v = e}{[P; v = E]_v = p + e} \quad [\text{null}] \frac{}{[\emptyset]_v = 0} \quad [\text{var}] \frac{}{[v]_v = 0}$$

$$[\text{sleep}] \frac{}{[\text{sleep } t]_v = t} \quad [\text{act}] \frac{}{[A^i]_v = 0}$$

$$[\text{cond}] \frac{[e_1]_v = s \quad [e_2]_v = t}{[\text{if } g_1 \text{ then } e_1 \text{ else } e_2]_v = s \max t}$$

$$[\text{spawn}] \frac{[P]_v = t}{[\text{spawn :name } P]_v = 0} \quad [\text{loop}] \frac{[P]_v = t}{[\text{loop } P]_v = \infty}$$

$$\text{iterate} \frac{[P]_v = t}{[n.\text{times } P]_v = nt} \quad n \text{ is constant}$$

Extended time system

$$[\text{seq}] \frac{[P]_v = p \quad [E]_v = e}{[P; v = E]_v = p + e} \quad [\text{null}] \frac{}{[\emptyset]_v = 0} \quad [\text{var}] \frac{}{[v]_v = 0}$$

$$[\text{sleep}] \frac{}{[\text{sleep } t]_v = t} \quad [\text{act}] \frac{}{[A^i]_v = 0}$$

$$[\text{cond}] \frac{[e_1]_v = s \quad [e_2]_v = t}{[\text{if } g_1 \text{ then } e_1 \text{ else } e_2]_v = s \max t}$$

$$[\text{spawn}] \frac{[P]_v = t}{[\text{spawn :name } P]_v = 0} \quad [\text{loop}] \frac{[P]_v = t \quad t > 0}{[\text{loop } P]_v = \infty}$$

$$\text{iterate} \frac{[P]_v = t}{[n.\text{times } P]_v = nt} \quad n \text{ is constant}$$

Higher-order time system

- Need to associate (virtual) times to functions

$$\begin{array}{c}
 \text{[abs]} \frac{[\Gamma, v : \sigma \vdash e : \tau]_v = n}{[\Gamma \vdash \lambda v. e : \sigma \xrightarrow{n} \tau]_v = 0} \quad \text{[app]} \frac{[\Gamma \vdash e_1 : \sigma \xrightarrow{n_1} \tau]_v = n_1 \quad [\Gamma \vdash e_2 : \sigma]_v = n_2}{[\Gamma \vdash e_1 e_2 : \tau]_v = n + n_1 + n_2}
 \end{array}$$

- Has the shape of traditional *effect system*

$$\begin{array}{c}
 \text{abs} \frac{\Gamma, x : \sigma \vdash e : \tau, \mathbf{F}}{\Gamma \vdash \lambda x. e : \sigma \xrightarrow{\mathbf{F}} \tau, \mathbf{\emptyset}} \quad \text{app} \frac{\Gamma \vdash e_1 : \sigma \xrightarrow{\mathbf{F}} \tau, \mathbf{G} \quad \Gamma \vdash e_2 : \sigma, \mathbf{H}}{\Gamma \vdash e_1 e_2 : \tau, \mathbf{F} \sqcup \mathbf{G} \sqcup \mathbf{H}}
 \end{array}$$

Higher-order & dependent

- Time may depend on parameters:

```
define :foo do |t|  
  sleep t  
  ...  
end
```

$$[\text{app}] \frac{[e_1 : (x : \sigma) \xrightarrow{f(x)} \tau]_v = n_1 \quad [e_2 : \sigma]_v = n_2}{[e_1 \ e_2 : \tau]_v = f(e_2) + n_1 + n_2}$$

- If implicit, dependent-type style formulation not necessary

Other benefits...

- IDE feedback on analysis to aid programming, e.g.,

play :C4	
sleep 0.5	0.5
play :es4	
sleep 0.25	0.75
play :g4	
sleep 0.15	0.90
play :as4	
sleep 0.5	1.40
play :ds4	
sleep 0.125	1.525
play :c5	

How
long is
this so
far?

Preventing deadlocks

- Session-type style analysis
 - `cue` ~ send
 - `sync` ~ receive

`cue :n : n!`

`sync :n : n?`

- Duality \Rightarrow compatibility \Rightarrow no deadlock

Cue/sync session types

```
live_loop :foo do
  sync :B
  cue :A
  play :C3
  sleep 1.0
end
```

: B?.A!.0

```
live_loop :bar do
  sync :A
  cue :B
  play :E4
  sleep 0.5
end
```

: A?.B!.0

$B?.A!.0 \neq \text{dual}(A?.B!.0)$

- Here, incompatibility => deadlock

Cue/sync session types

```
live_loop :foo do
  cue :A
  sync :B
  play :C3
  sleep 1.0
end
```

: $A!.B?.0$

```
live_loop :bar do
  cue :B
  sync :A
  play :E4
  sleep 0.5
end
```

: $B!.A?.0$

$A!.B?.0 \neq dual(B!.A?.0)$

- But this time there is no deadlock

Cue/sync session types

$$A!.B?.0 \neq \text{dual}(B!.A?.0)$$

- cue is asynchronous
- use sub-typing on sessions

$$A!.P <: P.A!$$

$$\therefore A!.B?.0 <: B?.A!.0$$

$$B?.A!.0 = \text{dual}(B!.A?.0)$$

Putting it together

- Virtual time and sessions as effects

$$\Gamma \vdash e : \tau \mid \textcolor{red}{vtime}, \textcolor{blue}{session}$$

$$\tau \xrightarrow{\textcolor{red}{t}, \textcolor{blue}{S}} \tau$$

Putting it together

$$[\text{seq}] \frac{\Gamma \vdash P \mid \textcolor{red}{s}, \textcolor{blue}{S} \quad \Gamma \vdash e : \tau \mid \textcolor{red}{t}, \textcolor{blue}{T}}{\Gamma \vdash P; v = e \mid \textcolor{red}{s} + \textcolor{red}{t}, \textcolor{blue}{S}. \textcolor{blue}{T}} \quad [\text{null}] \frac{}{\Gamma \vdash \emptyset \mid \textcolor{red}{0}, \textcolor{blue}{0}} \quad [\text{var}] \frac{v : \tau \in \Gamma}{\Gamma \vdash v : \tau \mid \textcolor{red}{0}, \textcolor{blue}{0}}$$

$$[\text{sleep}] \frac{}{\Gamma \vdash \text{sleep } t \mid \textcolor{red}{t}, \textcolor{blue}{0}}$$

$$[\text{act}] \frac{}{\Gamma \vdash A^i \mid \textcolor{red}{0}, \textcolor{blue}{0}}$$

$$[\text{sync}] \frac{}{\Gamma \vdash \text{sync } n \mid \textcolor{red}{0}, \textcolor{blue}{n!}}$$

$$[\text{cue}] \frac{}{\Gamma \vdash \text{cue } n \mid \textcolor{red}{0}, \textcolor{blue}{n?}}$$

$$[\text{spawn}] \frac{\Gamma \vdash P \mid \textcolor{red}{t}, \textcolor{blue}{S}}{\text{spawn} : \text{name } P \mid \textcolor{red}{0}, \textcolor{blue}{S}}$$

$$[\text{loop}] \frac{\Gamma \vdash P \mid \textcolor{red}{t}, \textcolor{blue}{S} \quad \textcolor{red}{t} > 0}{\Gamma \vdash \text{loop } P \mid \textcolor{red}{\infty}, \textcolor{blue}{\mu p. (S.p)}}$$

$$\text{iterate} \frac{\Gamma \vdash P \mid \textcolor{red}{t}, \textcolor{blue}{S}}{n.\text{times } P \mid n\textcolor{red}{t}, \textcolor{blue}{\mu p. (S.p)}} \quad n \text{ is constant}$$

$$[\text{cond}] \frac{\Gamma \vdash e_1 : \tau \mid \textcolor{red}{s}, \textcolor{blue}{S} \quad \Gamma \vdash e_2 : \tau \mid \textcolor{red}{t}, \textcolor{blue}{T}}{\text{if } g_1 \text{ then } e_1 \text{ else } e_2 : \tau \mid \textcolor{red}{s} \text{ max } \textcolor{red}{t}, \textcolor{blue}{S} + \textcolor{blue}{T}}$$

Putting it together (2)

$$[\text{abs}] \frac{\Gamma, x : \sigma \vdash e : \tau \mid \textcolor{red}{n}(x), \textcolor{blue}{S}(x)}{\Gamma \vdash \lambda x. e : (x : \sigma) \xrightarrow{\textcolor{red}{n}(x), \textcolor{blue}{S}(x)} \tau \mid \textcolor{red}{0}, \textcolor{blue}{0}}$$

$$[\text{app}] \frac{\Gamma \vdash e_1 : (x : \sigma) \xrightarrow{\textcolor{red}{n}(x), \textcolor{blue}{S}(x)} \tau \mid \textcolor{red}{n}_1, \textcolor{blue}{S}_1 \quad \Gamma \vdash e_2 : \sigma \mid \textcolor{red}{n}_2, \textcolor{blue}{S}_2}{\Gamma \vdash e_1 e_2 : \tau \mid \textcolor{red}{n}(e_2) + \textcolor{red}{n}_1 + \textcolor{red}{n}_2, \textcolor{blue}{S}_1. \textcolor{blue}{S}_2. \textcolor{blue}{S}(e_2)}$$

Time safety - extending

$[\text{—}]_t$: actual time

$$[\emptyset]_t \approx 0$$

$$[P; \text{sleep } t]_t \approx ([P]_v + t) \max [P]_t$$

$$[P; v = A^i]_t \approx [P]_t + [A^i]_t$$

Time safety - extending

$$[P \mid Q]_t \quad \text{where} \quad \begin{array}{l} P = \text{cue} : A; P' \\ Q = \text{sync} : A; Q' \end{array}$$

$$\begin{array}{l} [Q]_t \approx \text{if } [P']_t \leq [Q']_t \\ \quad \text{then } [P']_t \times \lceil [Q']_t / [P']_t \rceil \\ \quad \text{else } [P']_t \end{array}$$

- Complicated multiple (non-leading) cues/syncs
- In practice, one sync/cue per looped thread is fine
 - Auto cue on `live_loop`
 - Optional sync at head

Challenges - “liveness”

- Responsive analysis
- Update AST with changed code, rather than complete re-analyse
- Online analysis? (during typing)

Conclusions

- Programming with music is really fun
- Great for education
- Interesting verification challenges for music
- Need fast analysis for live-programming



<http://sonic-pi.net/>
@fib_crisis