Program Analysis (470)

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Spring 2015

Program analysis is an automated technique for finding out properties of programs without having to execute them.

- Compiler Optimisation
- Program Verification
- Security Analysis

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- Control Flow Analysis
- Types and Effects Systems
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Consider the following fragment in *some* procedural language.

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1: m \leftarrow 2;

2: while n > 1 do

3: m \leftarrow m \times n;

4: n \leftarrow n - 1

5: end while

6: stop [m \leftarrow 2]^{1};
while [n > 1]^{2} do
[m \leftarrow m \times n]^{3}
[n \leftarrow n - 1]^{4}
end while
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We annotate a program such that it becomes clear about what program point we are talking about.

4/2

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        [stop]<sup>5</sup>
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4/28

A Parity Analysis

Claim: This program fragment always returns an **even** m, idependently of the initial values of m and n.

We can statically determine that in any circumstances the value of m at the last statement will be **even** for any input n.

A program analysis, so-called parity analysis, can determine this by propagating the even/odd or *parity* information *forwards* form the start of the program.

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We will assign to each variable one of three properties:

- even the value is known to be even
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Executing the program with *abstract* values, parity, for m and n.

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1: m \leftarrow 2;
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2: while n > 1 do

3: $m \leftarrow m \times n$;

4: $n \leftarrow n-1$

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    m ← 2;
    while n > 1 do
    m ← m × n;
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    end while
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The first program computes 2 times the factorial for any positive value of n. Replacing '2' by '1' in the first statement gives:

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    m ← 1;
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i.e. the factorial – but then the program analysis is unable to tell us anything about the parity of m at the end of the execution.

The analysis of the new program does not give a satisfying result because:

- m could be **even** if the input n > 1, or
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Such a loss of precession is a common feature of program analysis: many properties that we are interested in are essentially undecidable and therefore we cannot hope to detect (all of) them accurately.

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- specification,
- implementation,
- correctness,
- applications.

Data Flow Analysis

The starting point for data flow analysis is a representation of the control flow graph of the program: the nodes of such a graph may represent individual statements – as in a flowchart – or sequences of statements; arcs specify how control may be passed during program execution.

The data flow analysis is usually specified as a set of equations which associate analysis information with program points which correspond to the nodes in the control flow graph. This information may be propagated *forwards* through the program (e.g. parity analysis) or *backwards*.

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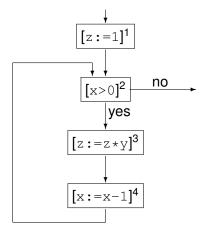
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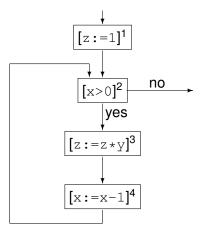
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Control Flow Information



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Reaching Definition (RD) analysis determines which set of definitions (i.e. assignments) are current when control reaches a certain program point p.

The analysis can be specified by equations of the form:

$$\mathsf{RD}_{entry}(p) = \left\{ egin{array}{ll} \mathsf{RD}_{init} & \text{if p is initial} \\ \bigcup\limits_{p' \in pred(p)} \mathsf{RD}_{exit}(p') & \text{otherwise} \end{array}
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At each program point some definitions get "killed" (those which define the same variable as at the program point) while others are "generated".

A suitable representation for properties are sets of pairs, where each pair contains a variable x and a program point p: the meaning of the pair (x, p) is that the assignment to x at point p is the current one. The initial value in this case is:

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Equations & Solutions

For our initial program fragment

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while [n > 1]^2 do

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2	$\{(m,1),(m,3),(n,?),(n,4)\}$	$\{(m,1),(m,3),(n,?),(n,4)\}$
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How can we construct solution to the data flow equations? Answer: Iteratively, by improving approximations/guesses.

INPUT: Control Flow Graph i.e. initial(p), pred(p).

OUTPUT: Reaching Definitions RD.

METHOD: Step 1: Initialisation

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- Available Expressions Avoid Re-computations
- Very Busy Expressions Hoisting
- Live Variables Dead Code Elimination
- Information Flow Computer Security
- Shape Analyis Pointer Analysis etc.

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$$RD \vdash [x := a]^{\ell} \triangleright [x := a[y \mapsto n]]^{\ell}$$

$$if \begin{cases} y \in FV(a) \land (y,?) \notin RD_{entry}(\ell) \land \\ \forall (y',\ell') \in RD_{entry}(\ell) : \\ y' = y \Rightarrow [\dots]^{\ell'} = [y := n]^{\ell'} \end{cases}$$

$$RD \vdash [x := a]^{\ell} \rhd [x := n]^{\ell}$$
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$$\begin{array}{c|c} RD \vdash S_1 \; \rhd \; S_1' \\ \hline RD \vdash S_1; S_2 \; \rhd \; S_1'; S_2 \\ \hline RD \vdash S_1; S_2 \; \rhd \; S_1'; S_2' \\ \hline RD \vdash S_1; S_2 \; \rhd \; S_1; S_2' \\ \hline RD \vdash S_1 \; \rhd \; S_1' \\ \hline RD \vdash \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2 \; \rhd \; \text{if } [b]^\ell \text{ then } S_1' \text{ else } S_2 \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2 \; \rhd \; \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2' \\ \hline RD \vdash S_1 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash S_1 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash S_1 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash S_1 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \rhd \; S_2' \\ \hline RD \vdash S_1 \; \rhd \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; S_2' \\ \hline RD \vdash S_2 \; \varsigma \; S_2' \\ \hline RD \vdash S_2 \; S_2' \\ \hline RD$$

$$\begin{array}{c|c} RD \vdash S_1 & \triangleright S_1' \\ \hline RD \vdash S_1; S_2 & \triangleright S_1'; S_2 \\ \hline RD \vdash S_2 & \triangleright S_2' \\ \hline RD \vdash S_1; S_2 & \triangleright S_1; S_2' \\ \hline RD \vdash S_1; S_2 & \triangleright S_1; S_2' \\ \hline RD \vdash S_1 & \triangleright S_1' \\ \hline RD \vdash \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2 & \triangleright \text{ if } [b]^\ell \text{ then } S_1' \text{ else } S_2 \\ \hline RD \vdash S_2 & \triangleright S_2' \\ \hline RD \vdash \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2 & \triangleright \text{ if } [b]^\ell \text{ then } S_1 \text{ else } S_2' \\ \hline RD \vdash S & \triangleright S' \\ \hline RD \vdash \text{ while } [b]^\ell \text{ do } S & \triangleright \text{ while } [b]^\ell \text{ do } S' \\ \hline \end{array}$$

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An Example

To illustrate the use of the transformation consider:

$$[x := 10]^1; [y := x + 10]^2; [z := y + 10]^3$$

The (least) solution to the Reaching Definition analysis is:

$$RD_{entry}(1) = \{(x,?), (y,?), (z,?)\}$$

$$RD_{exit}(1) = \{(x,1), (y,?), (z,?)\}$$

$$RD_{entry}(2) = \{(x,1), (y,?), (z,?)\}$$

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$$RD \vdash [y := x + 10]^2 \triangleright [y := 10 + 10]^2$$

and therfore the rules for sequential composition allow us to do the following transformation:

RD ⊢
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; $[y := x + 10]^2$; $[z := y + 10]^3$ ▷ $[x := 10]^1$; $[y := 10 + 10]^2$; $[z := y + 10]^3$

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We can continue this kind of transformation and obtain:

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 \triangleright $[x := 10]^1; [y := 20]^2; [z := y + 10]^3$
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Additional Issues

The above example shows that optimisation is in general the result of a number of successive transformations.

$$RD \vdash S_1 \triangleright S_2 \triangleright \ldots \triangleright S_n$$
.

This could be costly because one S_1 has been transformed into S_2 we might have to *re-compute* the Reaching Definition analysis before the next transformation step can be done.

It could also be the case that different sequences of transformations either lead to different end results or are of very different length.

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Lecture: Milestones

Coursework I: Mid February - Test

Coursework II: Early March – Test

Examination: Sometime in Week 11

Lecture: Milestones

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