

# Stochastic Process Algebras and Ordinary Differential Equations Salad

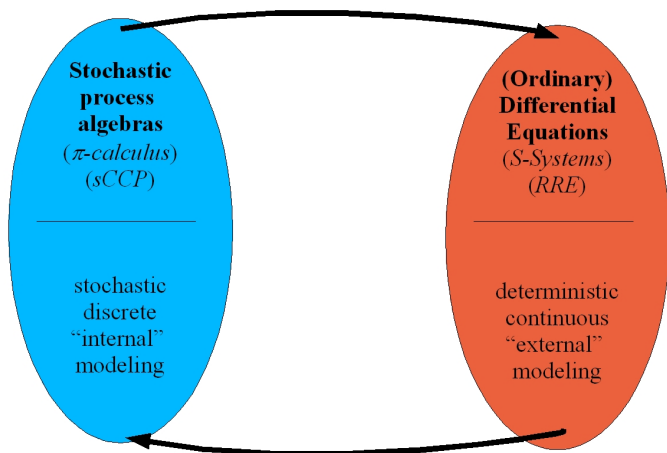
Luca Bortolussi<sup>1</sup>    Alberto Policriti<sup>1,2</sup>

<sup>1</sup>Department of Mathematics and Computer Science  
University of Udine, Italy.

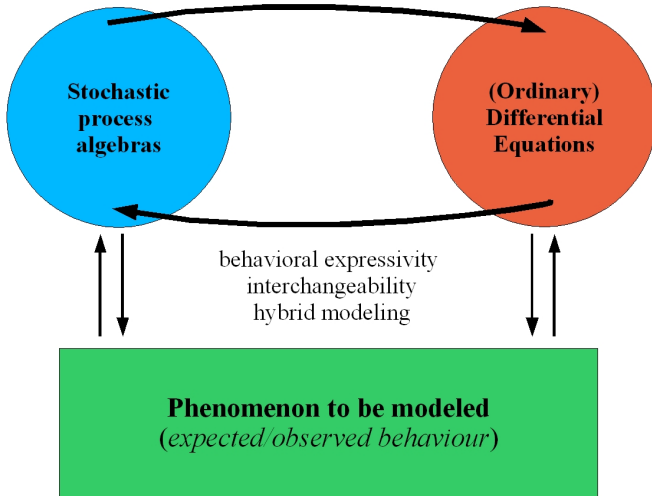
<sup>2</sup>Center for Biomolecular Medicine  
Trieste, Italy.

PASTA, London, 29<sup>th</sup> June 2006

# The picture



# A more detailed picture



# Outline

- 1 Preliminaries
  - ODEs
  - SPAs
- 2 From ODEs to SPAs
  - Translation into sCCP
- 3 From SPAs to ODEs
  - Hillston's method

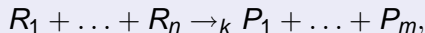
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# Mass Action Equations

## Chemical Equations

Chemical reactions can be represented by a set of **chemical equations** of the form:



where

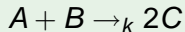
- $R_i$ 's are the reactants;
- $P_j$ 's are the products;
- $k$  is the basic rate (speed).

## Mass Action Equations

Chemical equations can be converted into a set of differential equations with the format

$$\dot{X}_i = \sum_{j=1}^{n_j} k_j X_{j_1} \cdots X_{j_{h_j}} - \sum_{l=1}^{m_i} k_l X_{l_1} \cdots X_{l_{h_l}}.$$

## Example



$$[\dot{A}] = [\dot{B}] = -k[A][B]$$

$$[\dot{C}] = 2k[A][B]$$

# S-Systems

**S-systems** describe the dynamical behavior of a biological system by a set of differential equations over reactants

- non-linear, time-invariant, DAE systems;
- biologically plausible and expressive;
- analytical approximation power.

## Definition

An **S-system's** equation has the form:

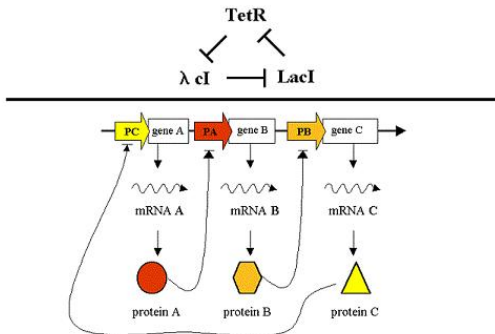
$$\dot{X}_i = \alpha_i \prod_{j=1}^{n+m} X_j^{g_{ij}} - \beta_i \prod_{j=1}^{n+m} X_j^{h_{ij}}$$

with  $\alpha_i, \beta_i \geq 0$  called *rate constants* and  $g_{ij}, h_{ij}$  called *kinetic orders*.

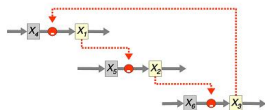
- E. O. Voit. Computational Analysis of Biochemical Systems A Practical Guide for Biochemists and Molecular Biologists. Cambridge University Press, 2000.

# A paradigmatic example — the Repressilator

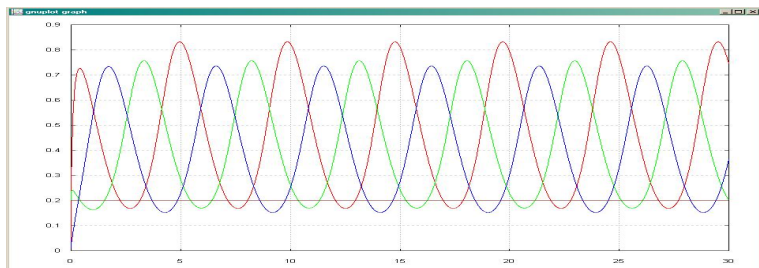
**The Repressilator:**  
a cyclic, three-repressor, transcriptional network



# S-Systems — the Repressilator equations



$$\begin{aligned}\dot{X}_1 &= \alpha_1 X_3^{-1} - X_1^{0.5}, & \alpha_1 &= 0.2, \\ \dot{X}_2 &= \alpha_2 X_1^{-1} - X_2^{0.578151}, & \alpha_2 &= 0.2, \\ \dot{X}_3 &= \alpha_3 X_2^{-1} - X_3^{0.5}, & \alpha_3 &= 0.2.\end{aligned}$$



# Biology and $\pi$ -calculus

## A (restricted) syntax of $\pi$ -calculus

$P, Q ::=$	$\Sigma$	Summation	$\Sigma ::=$	$\mathbf{0}$	Null
	$  P Q$	Parallel		$  \pi.P + \Sigma$	Action
	$  !\pi.P$	Repication	$\pi ::=$	$x\langle n \rangle$	Output
				$  x(m)$	Input, $x \neq m$

Quantitative aspect: **interaction “rates” assigned to channels.**

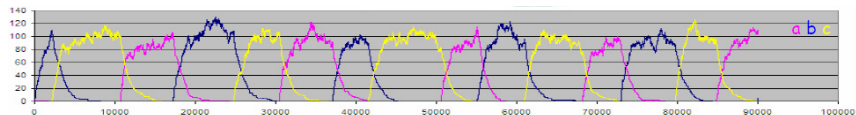
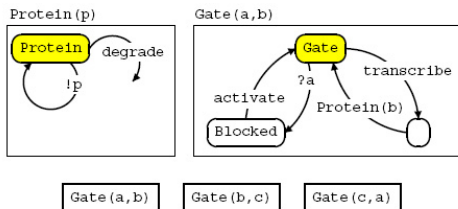
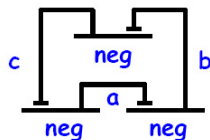
C.Priami. *The stochastic pi-calculus*. The Computer Journal 38: 578-589, 1995.

## Can we use $\pi$ -calculus for (biological) simulation?

Molecule	Process
Interaction capability	Channel
Interaction	Communication
Modification (of cellular components)	State change (state transition systems)

A. Regev and E. Shapiro *Cellular Abstractions: Cells as Computation*. **Nature**, vol. 429 (2002)

# Repressilator in $\pi$



# Concurrent Constraint Programming

## Constraint Store

- In this process algebra, the main objects are **constraints**, which are *formulae over an interpreted first order language* (i.e.  $X = 10$ ,  $Y > X - 3$ ).
- Constraints can be added to a "container", the **constraint store**, but can never be removed.

## Agents

Agents can perform two basic operations on this store (**asynchronously**):

- Add a constraint (**tell** **ask**)
- Ask if a certain relation is entailed by the current configuration (**ask** instruction)

## Syntax of CCP

$$\text{Program} = \text{Decl}.A$$

$$D = \varepsilon \mid \text{Decl}.D \mid p(x) : -A$$

$$A = \mathbf{0} \mid \text{tell}(c).A \mid \text{ask}(c_1).A_1 + \text{ask}(c_2).A_2 \mid A_1 \parallel A_2 \mid \exists_x A \mid p(x)$$

# Stochastic CCP

## Syntax of Stochastic CCP

$$\text{Program} = D.A$$
$$D = \varepsilon \mid D.D \mid \rho(\mathbf{x}) : -A$$
$$\pi = \text{tell}_\lambda(c) \mid \text{ask}_\lambda(c)$$
$$M = \pi.A \mid M + M'$$
$$A = \mathbf{0} \mid [\rho(\mathbf{x})]_\lambda \mid M \mid \exists_x A \mid (A_1 \parallel A_2)$$

L.Bortolussi. *Stochastic CCP*. QAPL, 2006.

## Stochastic information

Each basic instruction (tell, ask, procedure call) has a **rate** attached to it.

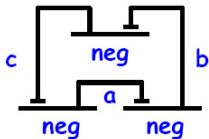
*Rates are functions from the constraint store  $\mathcal{C}$  to positive reals:*

$$\lambda : \mathcal{C} \longrightarrow \mathbb{R}^+.$$

## Why another Process Algebra?

- Constraints are powerful and easy to program.
- Variables allow to store numerical information..
- We can use “clever” stochastic rates.

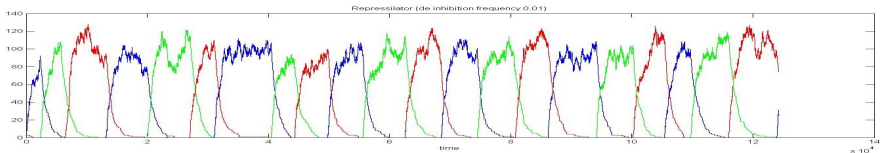
# Repressilator in sCCP



```
degradator(X) :- tell[λD·X](X = X - 1).degradator(X)
```

```
neg(X, Y) :- ( tell[λP](X = X + 1)
  + ask[λI·Y](Y > 0).ask[λU](true)).neg(X, Y)
).neg(X, Y)
```

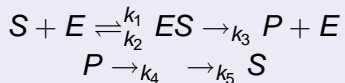
```
neg_gate(X, Y) :- neg(X, Y) || degradator(X)
```



# Using different kinetic laws: enzymatic reaction

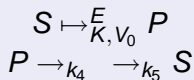
Non-constant rates allow to describe more complicated kinetic dynamics than Mass Action's one.

## Mass Action dynamics

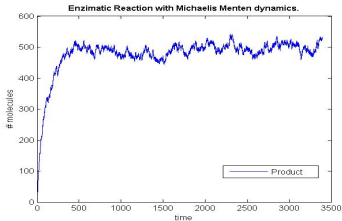
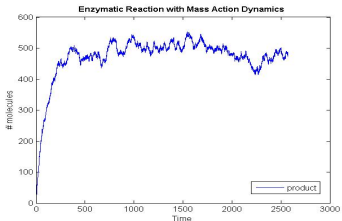


The rate of  $S + E \xrightarrow{k_1} ES$  is  $k_1[S][E]$ .

## Michaelis-Menten dynamics



The rate of  $S \xrightarrow{E, V_0} P$  is  $\frac{V_0[S]}{[S]+K}$



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# Simulating ODEs with SPAs



## Motivations

- Study **expressivity** in terms of **representable behaviors** of SPA
- From “external” to “internal” descriptions: identify **logical patterns of interactions**.

# Using S-Systems to determine rate functions

A generic form for S-System equations is

$$\dot{X}_i = \underbrace{V^+(X_1, \dots, X_{m+n})}_{\text{production speed}} - \underbrace{V^-(X_1, \dots, X_{m+n})}_{\text{degradation speed}}.$$

A generic S-System equation has *non-linear dependencies* on variables.

$$\dot{X}_i = \alpha_i \prod_{j=1}^{n+m} X_j^{g_{ij}} - \beta_i \prod_{j=1}^{n+m} X_j^{h_{ij}}$$

We can use these expression as rates.

Using sCCP, we can associate to each dependent variable an agent subs( $X_i$ ):

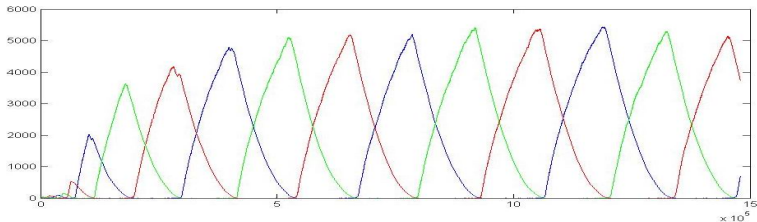
$$\left( \text{tell}(X_i = X_i + \sigma) \left[ \alpha_i \prod_{j=1}^{n+m} X_j^{g_{ij}} \right] + \text{tell}(X_i = X_i - \sigma) \left[ \beta_i \prod_{j=1}^{n+m} X_j^{h_{ij}} \right] \right) .\text{subs}(X_i).$$

# Encoding S-System's Repressilator

$$\begin{aligned}\dot{X}_1 &= \alpha_1 X_3^{-1} - \beta_1 X_1^{0.5}, \\ \dot{X}_2 &= \alpha_2 X_1^{-1} - \beta_2 X_2^{0.5}, \\ \dot{X}_3 &= \alpha_3 X_2^{-1} - \beta_3 X_3^{0.5}, \\ \alpha_i &= 0.2, \quad \beta_i = 1.\end{aligned}$$

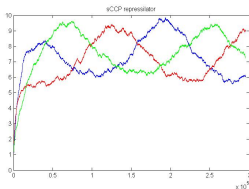
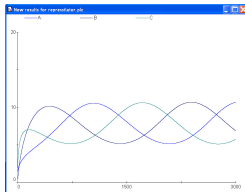
```
subs(X1) ::= (tell(X1 = X1 + σ)[α1X3-1]
             +tell(X1 = X1 - σ)[β1X10.5]).subs(X1)
subs(X2) ::= (tell(X2 = X2 + σ)[α2X1-1]
             +tell(X2 = X2 - σ)[β2X20.5]).subs(X2)
subs(X3) ::= (tell(X3 = X3 + σ)[α3X2-1]
             +tell(X3 = X3 - σ)[β3X30.5]).subs(X3)
```

$\sigma = 1$

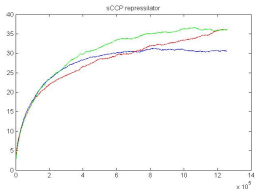
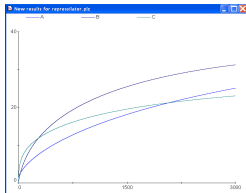


# Repressilator gone wild

S-System's model of repressilator suffers from an **high sensitivity from parameters**, differently from the usual PA models. sCCP model with variable rates has the same "wild" behaviour!

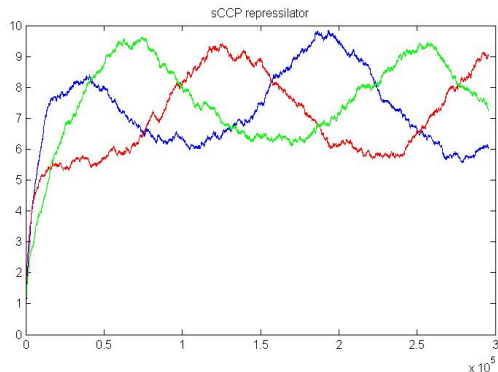


$$\beta_i = 0.01$$



$$\beta_i = 0.001$$

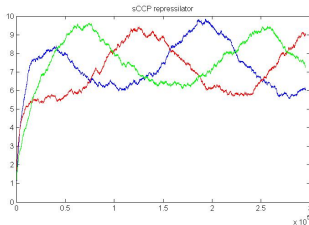
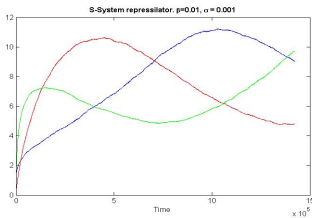
# There's a trick...



The magnitude  
of fluctuations  
is small.  
We used  
 $\sigma = 0.01$

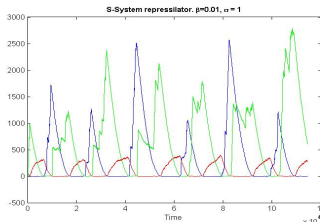
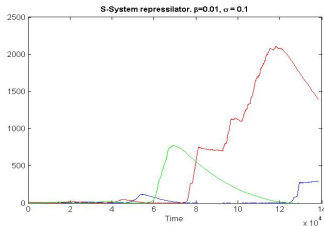
In this way we can reduce the perturbation effect of stochastic fluctuations.

# Dependency on the step size $\sigma$



$\sigma = 0.001$

$\sigma = 0.01$



$\sigma = 0.1$

$\sigma = 1$

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## Hillston's method

Jane has developed a method to associate a set of ODEs to a SPA (precisely PEPA) program.

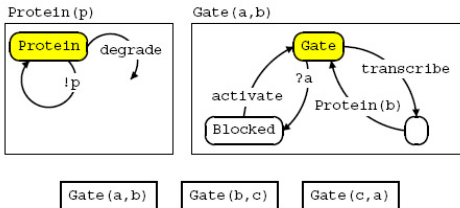
The method can be easily adapted to the (restricted version of) stochastic  $\pi$ -calculus

The translation produces always a set of **Mass Action Equations**, due to the definition of the SOS.

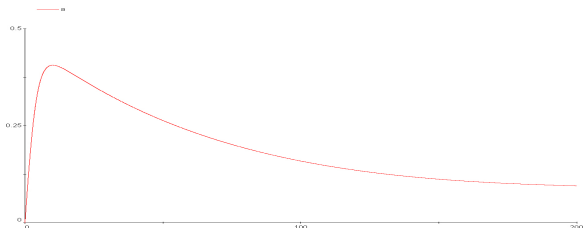
### Question

What does these ODEs tell us? Something about the average behavior?

# ODEs for the repressilator in $\pi$ -calculus



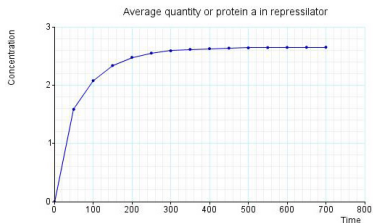
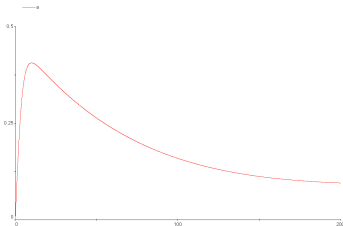
$$\begin{aligned} \dot{X}_1 &= \lambda_P Y_1 - \lambda_D X_1 \\ \dot{X}_2 &= \lambda_P Y_2 - \lambda_D X_2 \\ \dot{X}_3 &= \lambda_P Y_3 - \lambda_D X_3 \\ \dot{Y}_1 &= \lambda_U Z_1 - \lambda_I Y_1 X_3 \\ \dot{Y}_2 &= \lambda_U Z_2 - \lambda_I Y_2 X_1 \\ \dot{Y}_3 &= \lambda_U Z_3 - \lambda_I Y_3 X_2 \\ \dot{Z}_1 &= \lambda_I Y_1 X_3 - \lambda_U Z_1 \\ \dot{Z}_2 &= \lambda_I Y_2 X_1 - \lambda_U Z_2 \\ \dot{Z}_3 &= \lambda_I Y_3 X_2 - \lambda_U Z_3 \end{aligned}$$



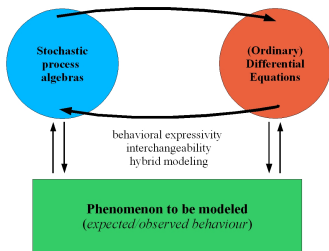
# What's the average?

What's the relationship between the solution of the ODEs and the average value of proteins in the  $\pi$ -repressilator?

*Neither the ODEs nor the average oscillates, but they stabilize at values different two orders of magnitude.*



# Conclusions



- “non-constant rates” are a powerful addition to SPAs (simulating ODEs, complex kinetic laws, etc.)
- stochastic fluctuations sometimes dominate, and they cannot be safely neglected in a translation process.
- Can we find translation techniques invariant w.r.t. the observed behaviour of the “real” system?