# If you've scheduled loops, you've gone too far

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Imperial College London

# Write data parallel code

as any fule kno

# Write data/task parallel code

as any fule kno

#### Lemma

You can't trust computational scientists to write good code.

### Corollary

Make it "impossible" to not write good code.

### DSLs for finite elements

Find  $(u, p, T) \in V \times W \times Q$  s.t.

$$\int \nabla u \cdot \nabla v + (u \cdot \nabla u) \cdot v$$
$$-p \nabla \cdot v + \frac{\text{Ra}}{\text{Pr}} Tg\hat{z} \cdot v \, dx = 0$$
$$\int \nabla \cdot uq \, dx = 0$$
$$\int (u \cdot \nabla T)S + \text{Pr}^{-1} \nabla T \cdot \nabla S \, dx = 0$$
$$\forall (v, q, T) \in V \times W \times Q$$

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 $\forall (v, q, T) \in V \times W \times Q$ 

from firedrake import \* mesh = Mesh(...) V = VectorFunctionSpace(mesh, "CG", 2) W = FunctionSpace(mesh, "CG", 1) Q = FunctionSpace(mesh, "CG", 1) Z = V \* W \* 0Ra = Constant(200)Pr = Constant(6.18)upT = Function(Z)u, p, T = split(upT) v. a. S = TestFunctions(Z) bcs = [...] # no-flow + temp gradient nullspace = MixedVectorSpaceBasis( Z. [Z.sub(0). VectorSpaceBasis(constant=True).  $Z_{sub}(2)$ F = (inner(grad(u), grad(v)))+ inner(dot(grad(u), u), v) - inner(p, div(v)) + (Ra/Pr)\*inner(T\*g, v) + inner(div(u). a) + inner(dot(grad(T), u), S) + (1/Pr) \* inner(grad(T), grad(S)))\*dx

solve(F == 0, upT, bcs=bcs, nullspace=nullspace)

#### + a DSL for solver configuration

```
-snes type newtonls
-snes rtol 1e-8
-snes linesearch type basic

    ksp type fgmres

    ksp gmres modifiedgramschmidt

-mat type matfree
-pc type fieldsplit
-pc fieldsplit type multiplicative
-pc fieldsplit 0 fields 0.1
-pc fieldsplit 1 fields 2
-prefix push fieldsplit 1
  -ksp type gmres
  -ksp rtol 1e-4,
  -pc type python
  -pc python type firedrake.AssembledPC
  -assembled mat type aij
  -assembled pc type telescope
  -assembled pc telescope reduction factor 6
  -assembled telescope pc type hypre
  -assembled telescope pc hypre boomeramg P max 4
  -assembled telescope pc hypre boomeramg agg nl 1
  -assembled_telescope_pc_hypre_boomeramg_agg_num_paths 2
  -assembled telescope pc hypre boomeramg coarsen type HMIS
  -assembled telescope pc hypre boomeramg interp type ext+i
  -assembled telescope pc hypre boomeramg no CF True
-prefix pop
-prefix_push fieldsplit 0
  -ksp type gmres
  -ksp gmres modifiedgramschmidt
  -ksp rtol 1e-2
  -pc type fieldsplit
  -pc fieldsplit type schur
  -pc fieldsplit schur fact type lower
```

-prefix push fieldsplit 0 -ksp type preonly -pc type python -pc python type firedrake.AssembledPC -assembled mat type aij -assembled pc type hypre -assembled pc hypre boomeramg P max 4 -assembled pc hypre boomeramg agg nl 1 -assembled pc hypre boomeramg agg num paths 2 -assembled pc hypre boomeramg coarsen type HMIS -assembled pc hypre boomeramg interp type ext+i -assembled pc hypre boomerame no CF -prefix pop -prefix push fieldsplit 1 -ksp type preonly -pc type python -pc python type firedrake.PCDPC -pcd Fp mat type matfree -pcd Kp ksp type preonly -pcd Kp mat type aij -pcd Kp pc type telescope -pcd Kp pc telescope reduction factor 6 -pcd Kp telescope pc type ksp -pcd Kp telescope ksp ksp max it 3 -pcd Kp telescope ksp ksp type richardson -pcd Kp telescope ksp pc type hypre -pcd Kp telescope ksp pc hypre boomeramg P max 4 -pcd Kp telescope ksp pc hypre boomeramg agg nl 1 -pcd Kp telescope ksp pc hypre boomeramg agg num paths 2 -pcd Kp telescope ksp pc hypre boomeramg coarsen type HMIS -pcd Kp telescope ksp pc hypre boomeramg interp type ext+i -pcd Kp telescope ksp pc hypre boomeramg no CF -pcd Mp mat type aii -pcd Mp ksp type richardson -pcd Mp pc type sor -pcd Mp ksp max it 2 -prefix pop -prefix pop

### Firedrake www.firedrakeproject.org

[...] an automated system for the solution of partial differential equations using the finite element method.

- Written in Python.
- Finite element problems specified with *embedded* domain specific language, UFL (Alnæs, Logg, Ølgaard, Rognes, and Wells 2014) from the FEniCS project.
- *Runtime* compilation to low-level (C) code.
- Explicitly data parallel API.

F. Rathgeber, D.A. Ham, LM, M. Lange, F. Luporini, A.T.T. McRae, G.-T. Bercea, G.R. Markall,

P.H.J. Kelly. TOMS, 2016. arXiv: 1501.01809 [cs.MS]

### Code transformation

- Represent fields as expansion in some basis  $\{\phi_i\}$  for the discrete space.
- Integrals are computed by numerical quadrature on mesh elements.

$$\int_{\Omega} F(\phi_i)\phi_j \,\mathrm{d} x \to \sum_{e \in \mathcal{T}} \sum_{q} w_q F(\phi_i(q))\phi_j(q)$$

• Need to evaluate  $\phi_j$  and  $F(\phi_i)$ , defined by basis coefficients  $\{f_i\}_{i=1}^N$ , at quadrature points  $\{q_j\}_{j=1}^Q$ .

$$\mathcal{F}_q = \left[\Phi f\right]_q = \sum_i \phi_{i,q} f_i$$

•  $\Phi$  is a  $Q \times N$  matrix of basis functions evaluated at quadrature points.

• For degree p elements in d dimensions.  $N, Q = \mathcal{O}(p^d)$ .

- For degree p elements in d dimensions.  $N, Q = \mathcal{O}(p^d)$ .
- So I need  $\mathcal{O}(p^{2d})$  operations. Right?

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- So I need  $\mathcal{O}(p^{2d})$  operations. Right?
- Well not always....

### **Exploiting structure**

Often,  $\phi$  might have a tensor decomposition.

.)

$$\phi_{i,q}(x,y,\ldots) := \varphi_{j,p}(x)\varphi_{k,r}(y)\ldots$$

and so

$$F_{(p,r)} = \sum_{j,k} \phi_{(j,k),(p,r)} f_{j,k}$$
$$= \sum_{j,k} \varphi_{j,p} \varphi_{k,r} f_{j,k}$$
$$= \sum_{j} \varphi_{j,p} \sum_{k} \varphi_{k,r} f_{j,k}$$

at the cost of some temporary storage, this requires only  $\mathcal{O}(dp^{d+1})$  operations.

### Tensions

- You want the granularity of the data parallel operation to be small
- That way the programmer has less chance to get it wrong
- But, can you then get the "good" algorithm?

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Will your blas library notice if

• But, can you then get the "good" algorithm?

Will your compiler hoist into array temporaries?

```
for (p = 0; p < L; p++)
for (r = 0; r < L; r++)
for (j = 0; j < M; j++)
for (k = 0; k < M; k++)
F[L*p+r][j*M+k] += f(p,j)*g(r,k)</pre>
PHI has Kronecker-product
structure?
double PHI[L][M] = {{ ... }};
dgemv(PHI, Fi, Fq)
```

### Scheduling

- Front-end DSL matches finite elements
- Compiler frontend removes finite element specific constructs  $\rightarrow$  DAG representation of tensor-algebra.
- These operations can have structure (e.g. tensor-product decomposition)
- Transformations on the DAG to minimise op-count, perhaps promote vectorisation.
- $\cdot$  Scheduling  $\leftrightarrow$  topological sort of DAG
- Opportunity to introduce hardware- and problem-guided heuristics, and optimisation passes

Homolya, LM, Luporini, Ham. arXiv: 1705.03667 [cs.MS]

Homolya, Kirby, Ham. In preparation

- $\checkmark$  A DSL should elegantly capture mathematical structure
- ✓ things expressible in the mathematics can be compiled to efficient code and algorithms!
- ✗ All else cannot be compiled, need graceful degradation.
- ✗/✓ Greatest advantages come when you incorporate them at the top level.

# Thanks!

- Alnæs, M. S., A. Logg, K. B. Ølgaard, M. E. Rognes, and G. N. Wells (2014). "Unified Form Language: A Domain-specific Language for Weak Formulations of Partial Differential Equations". ACM Trans. Math. Softw. 40. doi:10.1145/2566630. arXiv: 1211.4047 [cs.MS].
- Homolya, M., L. Mitchell, F. Luporini, and D. A. Ham (2017). *TSFC: a structure-preserving form compiler*. arXiv: 1705.03667 [cs.MS].
- Rathgeber, F., D. A. Ham, L. Mitchell, M. Lange, F. Luporini, A. T. T. McRae, G.-T. Bercea, G. R. Markall, and P. H. J. Kelly (2016). "Firedrake: automating the finite element method by composing abstractions". ACM Transactions on Mathematical Software 43. doi:10.1145/2998441. arXiv: 1501.01809 [cs.MS].