

## Extended logic programs: Disjunction

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**Disjunction (1) — ‘shifting’**

We have seen that the disjunction ‘ $A$  or  $B$ ’ ( $A$  and  $B$  literals) can be approximated by means of a construct sometimes called ‘shifting’.

Example

$$\left. \begin{array}{l} a \leftarrow \text{not } b \\ b \leftarrow \text{not } a \end{array} \right\} \quad \text{has answer sets } \{a\}, \{b\}$$

Why ‘approximation’?

$$\left. \begin{array}{l} a \leftarrow \text{not } b \\ b \leftarrow \text{not } a \\ a \leftarrow b \end{array} \right\} \quad \text{has one answer set } \{a\}$$

Fine. But consider:

$$\left. \begin{array}{l} a \leftarrow \text{not } b \\ b \leftarrow \text{not } a \\ a \leftarrow b \\ b \leftarrow a \end{array} \right\} \quad \text{has no answer sets!! (Check for yourself.)}$$

‘Shifting’ is a good encoding of disjunction in certain circumstances — for instance, when the disjuncts are mutually exclusive.

**Disjunction (2) — ‘Choice rules’**

As we have seen (in the notes on ASP solvers) the disjunction ‘ $A$  or  $B$ ’ ( $A$  and  $B$  literals) can also be expressed by means of a ‘choice rule’ (choose any subset) together with an integrity constraint (but not the empty subset), or using a cardinality constraint:

$$1 \{A, B\} \leftarrow$$

And as we have seen, the choice rule can be expressed as an extended logic program, as follows.

Example:

$$\left. \begin{array}{ll} a \leftarrow \text{not } a' & a' \leftarrow \text{not } a \\ b \leftarrow \text{not } b' & b' \leftarrow \text{not } b \\ f \leftarrow \text{not } a, \text{ not } b, \text{ not } f & \end{array} \right\} \quad \text{has answer sets } \{a, b'\}, \{a', b\}, \{a, b\}$$

$$\left. \begin{array}{ll} a \leftarrow \text{not } a' & a' \leftarrow \text{not } a \\ b \leftarrow \text{not } b' & b' \leftarrow \text{not } b \\ f \leftarrow \text{not } a, \text{ not } b, \text{ not } f \\ a \leftarrow b & \end{array} \right\} \quad \text{has answer sets } \{a, b'\}, \{a, b\}$$

$$\left. \begin{array}{ll} a \leftarrow \text{not } a' & a' \leftarrow \text{not } a \\ b \leftarrow \text{not } b' & b' \leftarrow \text{not } b \\ f \leftarrow \text{not } a, \text{ not } b, \text{ not } f \\ a \leftarrow b \\ b \leftarrow a & \end{array} \right\} \quad \text{has answer sets } \{a, b\}$$

## Disjunctive logic programs

This part is for *BACKGROUND INTEREST* only. Details are not examinable. I have included it because you will see references to disjunctive logic programs, e.g. in the guide to *clingo*.

Clauses are as in extended logic programs or of the form

$$A ; B \leftarrow L_1, \dots, L_m$$

$A$  and  $B$  are literals: i.e., either of the form  $p$  or  $\neg p$  where  $p$  is an atom.  $L_i$  are literals or nbf-literals as usual, i.e., of the form  $p$ ,  $\neg p$ , not  $p$  or not  $\neg p$  where  $p$  is an atom.

$A ; B$  is sometimes written  $A \mid B$ . You can read it as the disjunction ‘ $A$  or  $B$ ’ — except that disjunction in disjunctive logic programs has a particular *special meaning* that comes out because of its minimality semantics.

*Answer sets* are defined as usual, in terms of *reducts*. Given a disjunctive logic program  $P$  and a set of literals  $X$ , the reduct  $P^X$  is defined in the usual way: delete from  $P$  any clause which has a literal not  $B$  in its body where  $B \in X$ ; delete all other literals not  $C$  in the remaining clauses (i.e., those conditions not  $C$  which are satisfied in  $X$ , i.e., where  $C \notin X$ ).

The reduct  $P^X$  contains no occurrences of negation-by-failure. We have the usual ‘stability requirement’:  $X$  is an answer set of  $P$  iff  $X$  is an answer set of  $P^X$ . The difference is that now there is the possibility of disjunction in clauses, the answer set of  $P^X$  might not be unique (unlike for extended logic programs, where the reduct is a set of definite clauses, and the answer set — the least Herbrand model — is unique.)

So what is the answer set of disjunctive logic program without negation-by-failure, i.e., of a set of definite clauses or clauses of the form

$$A ; B \leftarrow L_1, \dots, L_m \tag{1}$$

where  $A, B, L_1, \dots, L_m$  are all literals (no negation-by-failure).

Let  $X$  be a set of literals.  $X$  *satisfies* a clause of the form (1) if whenever  $\{L_1, \dots, L_m\} \subseteq X$  then either  $A \in X$  or  $B \in X$  (or both). Just as you would expect.

Now, by definition,  $X$  is an answer set of a disjunctive logic program  $P$  without negation-by-failure if  $X$  is a *minimal* set of literals that satisfies all the clauses of  $P$ . (Or as we also say, when  $X$  is a minimal Herbrand model of  $P$ .)

All this seems very natural. But look at some simple examples. (Negation-by-failure works the same way—via reducts—as in extended logic programs.)

Simplest example:

$$a ; b \leftarrow \left. \begin{array}{l} \end{array} \right\} \quad \begin{array}{l} \text{models: } \{a\}, \{b\}, \{a,b\} \\ \text{answer sets (minimal): } \{a\}, \{b\} \end{array}$$

$$a ; b \leftarrow \left. \begin{array}{l} a \leftarrow b \end{array} \right\} \quad \begin{array}{l} \text{models: } \{a\}, \{a,b\} \\ \text{answer sets (minimal): } \{a\} \end{array}$$

$$a ; b \leftarrow \left. \begin{array}{l} a \leftarrow b \\ b \leftarrow a \end{array} \right\} \quad \begin{array}{l} \text{models: } \{a,b\} \\ \text{answer sets (minimal): } \{a,b\} \end{array}$$

*clingo*, and many other ASP solvers, do not support disjunctive logic programs. (The computational complexity is much higher, because of the built-in minimality feature.)

And it is not clear how useful this reading of disjunction is for knowledge representation anyway. (It is useful for some algorithmic tasks.)