

Non-Deterministic Turing Machines

A NDTM can choose which of a number of instructions to execute at points in a run..

no program control at run time.

..so a run is not determined in advance - no control via δ -function,
..can have more than 1 entry for (state q_i , symbol read a)

This can give a “free” exhaustive search for a possible solution which is then checked.

We would like to replace this non-deterministic choice with a clever search strategy to select a suitable possible solution, and then check it in p-time.

The choice is done by **multiple entries for $(q,a) \in Q \times \Sigma$** .

Formal definition of NDTM

$N = (Q, \Sigma, I, q_0, \delta, F)$, with

$$\delta: (Q \setminus F) \times \Sigma \rightarrow 2^{Q \times \Sigma \times \{\pm 1, 0\}}$$

- $2^{Q \times \Sigma \times \{\pm 1, 0\}}$: the set of all subsets of $Q \times \Sigma \times \{\pm 1, 0\}$

ie. the function value for (q,a) is a set of the alternatives

If there is no applicable instruction for (q,a) then $\delta(q,a) = \emptyset$
(empty set).

**if $\delta(q,a)$ contains only one (q',a',d) or is empty,
we have an ordinary deterministic TM.**

Input and Output for NDTMs

Input: tape contents before the first \wedge as before

Output: can have many different results on tape for an input w -
for each successful (H & S) run
 \square a set of possible outputs.

\square simplify by considering only yes/no problems

- **acceptance** for NDTMs:

N **accepts** $w \in I^*$ if there exists a successful run with w as input:
-..if at least one run on w Halts and Succeeds.

- **rejection** for NDTMs

- N **rejects** $w \in I^*$ if all runs on input w Halt and Fail.

Speed of NDTMs

For any input $w \in I^*$ the NDTM can

- 1) Halt and Succeed (i.e. accept w)
- 2) Halt and Fail (i.e. reject w)
- (3) Never halt..excluded when N *solves* the problem).

Run-time function for NDTMs:

$\text{time}_N(n) = \text{length of longest run for any } w \in I^* \text{ of length } n.$

$\text{time}_N(n) \leq \quad .$

We say that a NDTM N runs in polynomial time if

\square a polynomial p such that

$$\text{time}_N(n) \leq p(n), \text{ all } n > 0$$

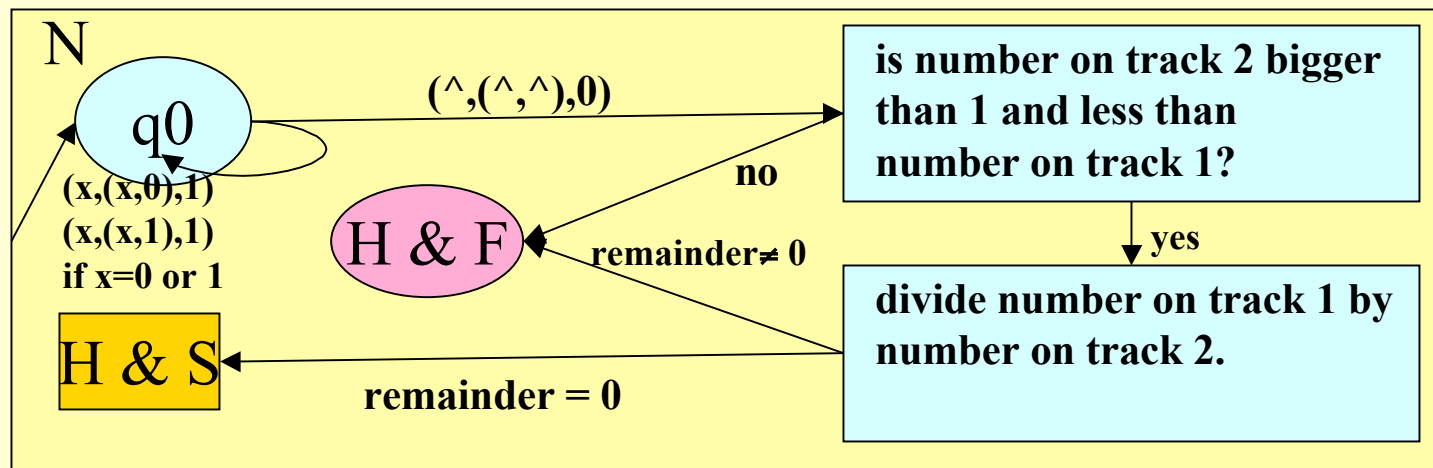
$p(n)$ is an upper bound on time for inputs of length n .

Example of a Non-Deterministic Turing Machine

Non-primality testing. Given a number n , is n composite?

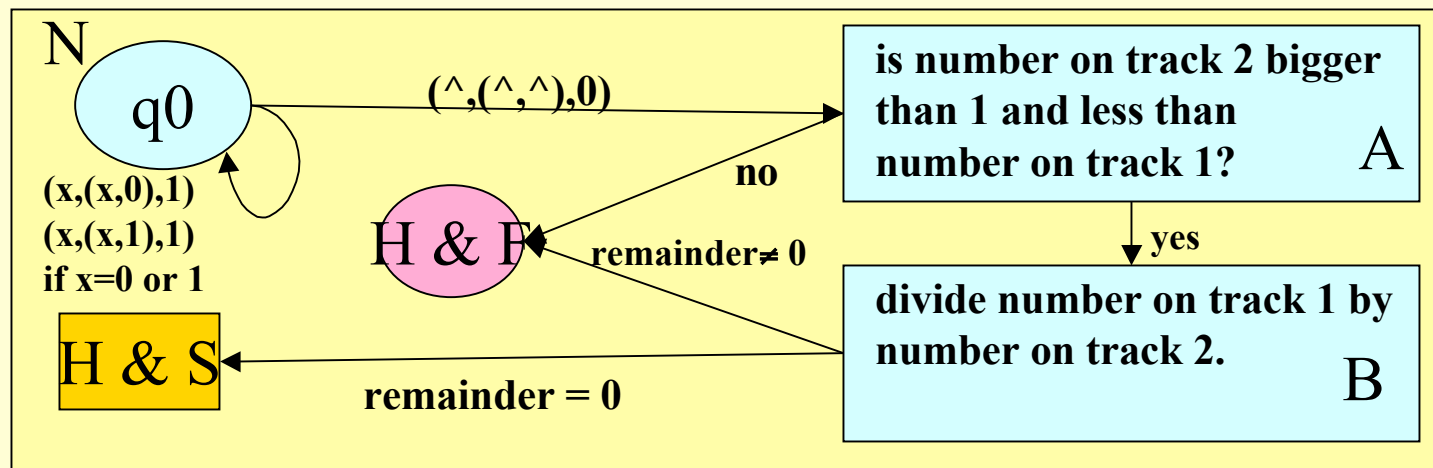
We build a 2-track NDTM which:

1. Guesses a number m , where $1 < m < n$.
2. Divides n by m (deterministically in p -time)
3. If there is no remainder (m divides n) then
 it Halts and Succeeds: “yes”
 otherwise it Halts and Fails: “no”.

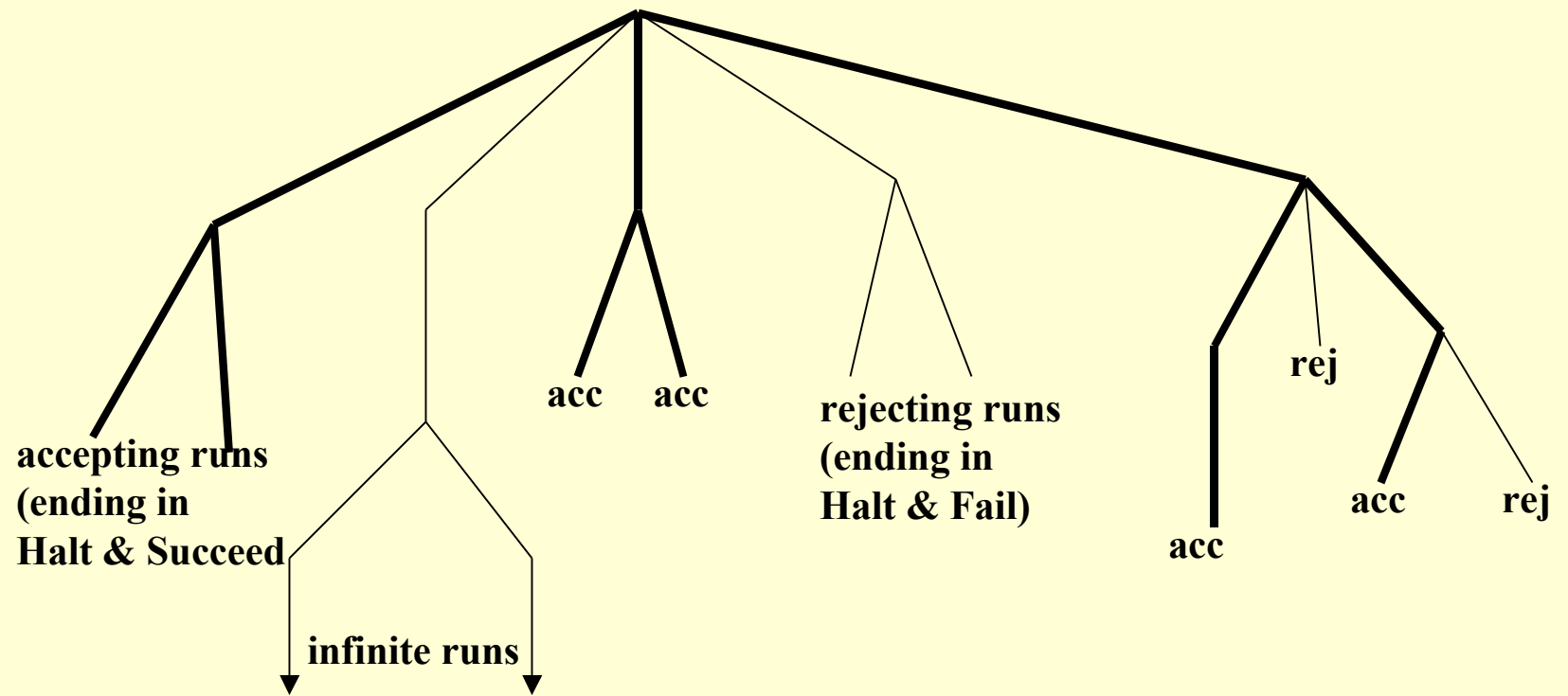


Example of a Non-Deterministic Turing Machine

- the input is a binary number on a single track
- N non-deterministically writes a binary number, m on track 2.
ending at the end of n .
- N checks whether $m = 0$, or $m = 1$ or $m \geq n$: if so N Halts and Fails
if not, N divides n by m and checks whether the remainder > 0
..if not, N Halts and Succeeds
otherwise N Halts and Fails



NDTM N



tree representation of the possible runs of NDTM, N on some input

The Class NP of problems

NP consists of all yes/no problems A such that there is some **NDTM** N that runs in **p-time** and solves A ;

N accepts all the yes-instances of A
rejects all the no-instances of A .

This is the class of (\square) type problems that would be in P if they had a clever search strategy.

$P \subseteq NP$ as p-time deterministic TMs are a special case of p-time non-deterministic TMs.

$P = NP?$.. yes/no problem not yet answered

Simulation of NDTMs by ordinary TMs.

..we demonstrate that a NDTM is no more powerful than an ordinary TM..further evidence for the Church-Turing Thesis.

..we have seen the non-determinism as a way of guessing from the search space of possible solutions..and then checking deterministically whether this *is* a solution..

Equivalence of ordinary TMs and NDTMs:

- 1) given an ordinary TM $M = (Q, \Sigma, I, q_0, \delta, F)$ we can construct an equivalent NDTM $N = (Q, \Sigma, I, q_0, \delta, F)$ such that:
 $\delta(q, a) = \{\delta(q, a)\}$ if $\delta(q, a)$ is defined
 \emptyset otherwise.

N behaves exactly as M - deterministically,
but it is a valid NDTM.

Equivalence

2) any yes/no problem solvable by a NDTM can also be solved by an ordinary deterministic Turing Machine.

Given a NDTM N \square construct a deterministic TM to solve the same Problem.

We will simulate N with a 3-tape ordinary TM, M :

M rejects/accepts the same input words

M does breadth-first traversal of the tree of possible runs of N for given input w .

M Halts and Succeeds when it finds a Halting state of N .

why a breadth-first tree traversal?

-we want to find any H & S

- we don't want to go down infinite (non-terminating) branches.

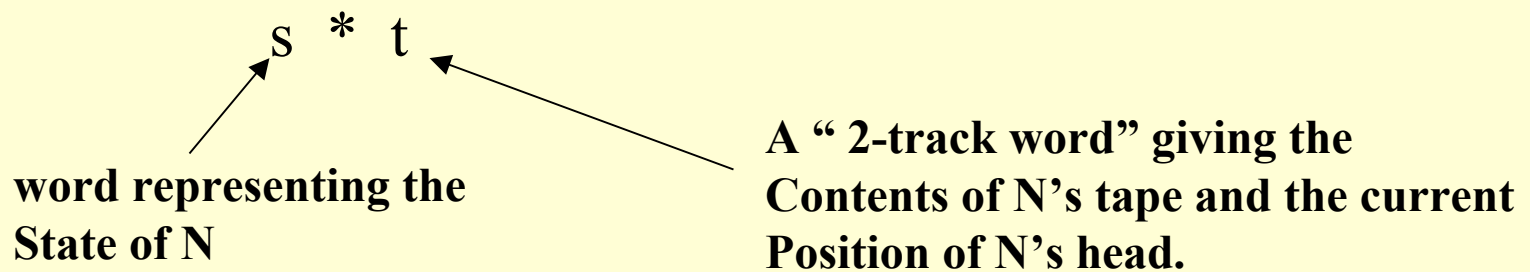
At each node of the search tree, N has a **configuration**:

- current state of N
- current contents of N's tape
- position of read head of N

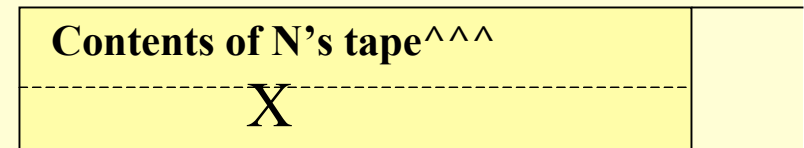
which determines what N does next..

..the possible nodes at the next level of the tree

Representation of the configuration of N:

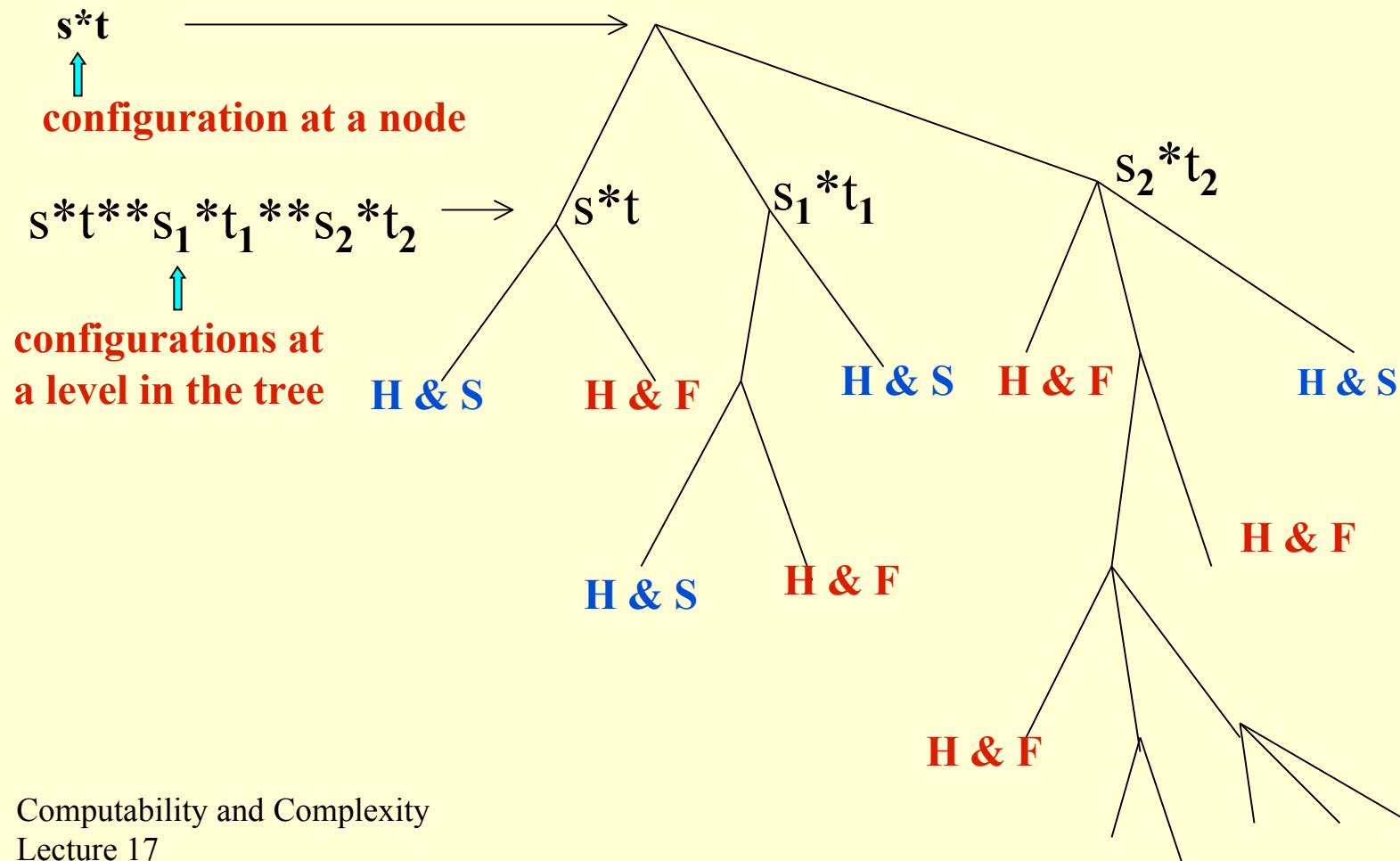


current position of N's head



We can describe a level of the run-tree of N by the set of possible configurations after the corresponding number of steps in N 's run.

N 's run tree has levels:



M simulates N by building up the possible configurations of N, level-by-level: at first N has input word w \square M starts with w on tape 1

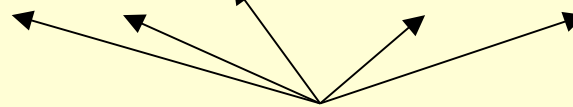
\square replace w by $\text{config}(q_0, w, 0)$

tape 2 is used for scratch work

Breadth-first search for Halt and Succeed:

after n cycles (levels of the run tree):

M has $s^*t^{**}s_1^*t_1^{**}s_2^*t_2^{**}s_3^*t_3^{**}\dots s_r^*t_r$ on tape 1

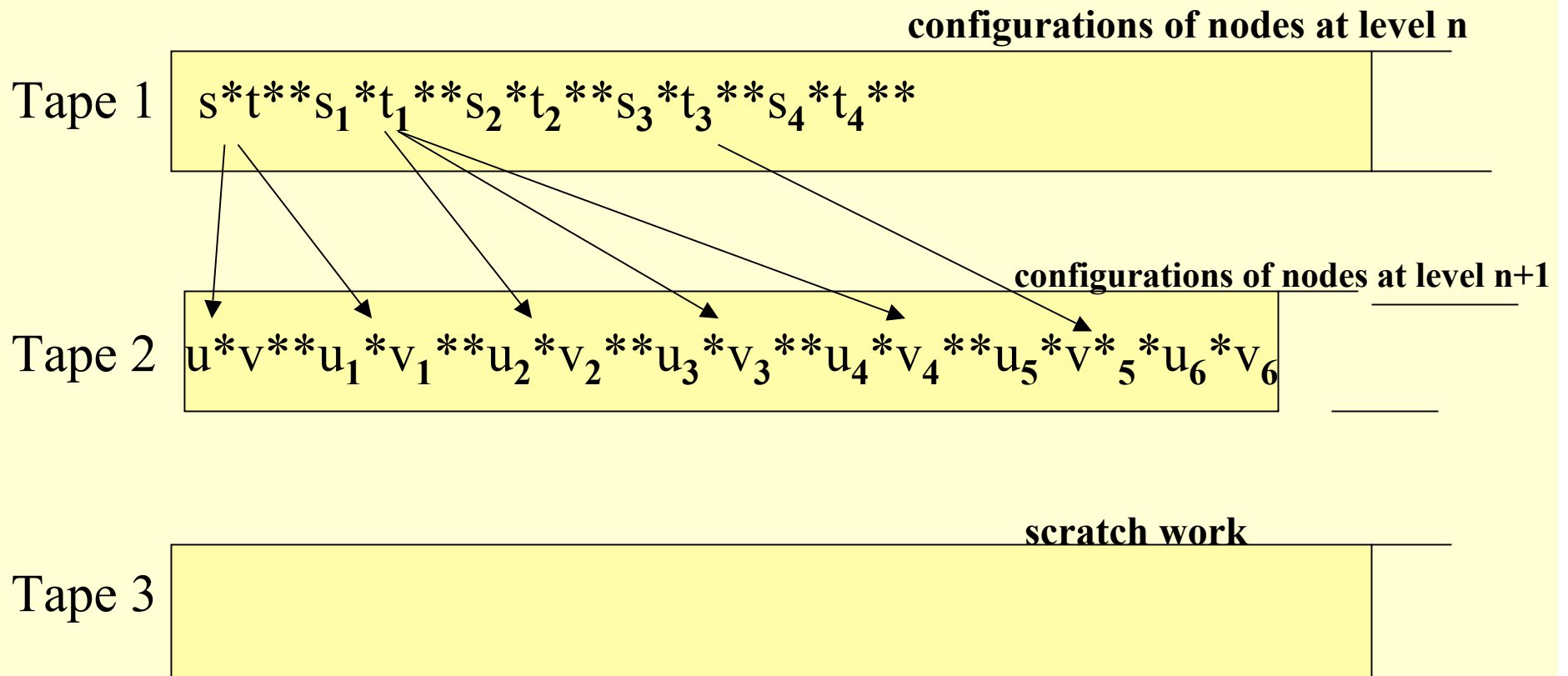


configurations for nodes at level n

M follows N:

- look for a Halting State of N among the configurations at level n
it there is one \square M Halts and Succeeds
- check each $s_i^*t_i$..each node at level n , calculate possible nodes at level $n+1$..(ignore if this involves move left from $s_q 0$)
..add the new configuration to the end of tape 2 of M
if no child nodes, no change to tape 2.

M now has:



When all level $n+1$ configurations are on tape 2,
 copy Tape 2 to Tape 1 and repeat for level $n+1$ on tape 1, building
 Level $n+2$ on Tape 2.

The cycle is repeated for level $n+1$.
if Tape 2 is empty at the end of a cycle



Success/ Failure:

N accepts w \square \square some successful run of N on w
 \square somewhere in the tree \square config(q, w, m), $q \in F$.
M will find this, and Halt & Succeed.

N rejects w \square every run of N on w \square Halt and Fail
 \square tree has finite depth, say n
level $n+1$ is empty \square Halt and Fail.

N and M solve the same yes/no problem.



Summary

We have defined **Nondeterministic Turing Machines**

..and shown that they are equivalent to ordinary deterministic TMs,
by showing that

1) An ordinary TM is a special case of a NDTM
($\delta(q, a)$ has one entry or is the empty set)

2) We can build an ordinary TM, M which searches the run-tree of
a NDTM N and: **Halts and Succeeds** when it finds the first (w.r.t
distance in levels from the start of the run) possible
halting state(there is an accepting run of N on w)
or: **Halts & Fails** if it has explored the whole tree
without finding a halting state.

The complexity class NP:

those yes/no problems which can be solved in p-time by a NDTM.