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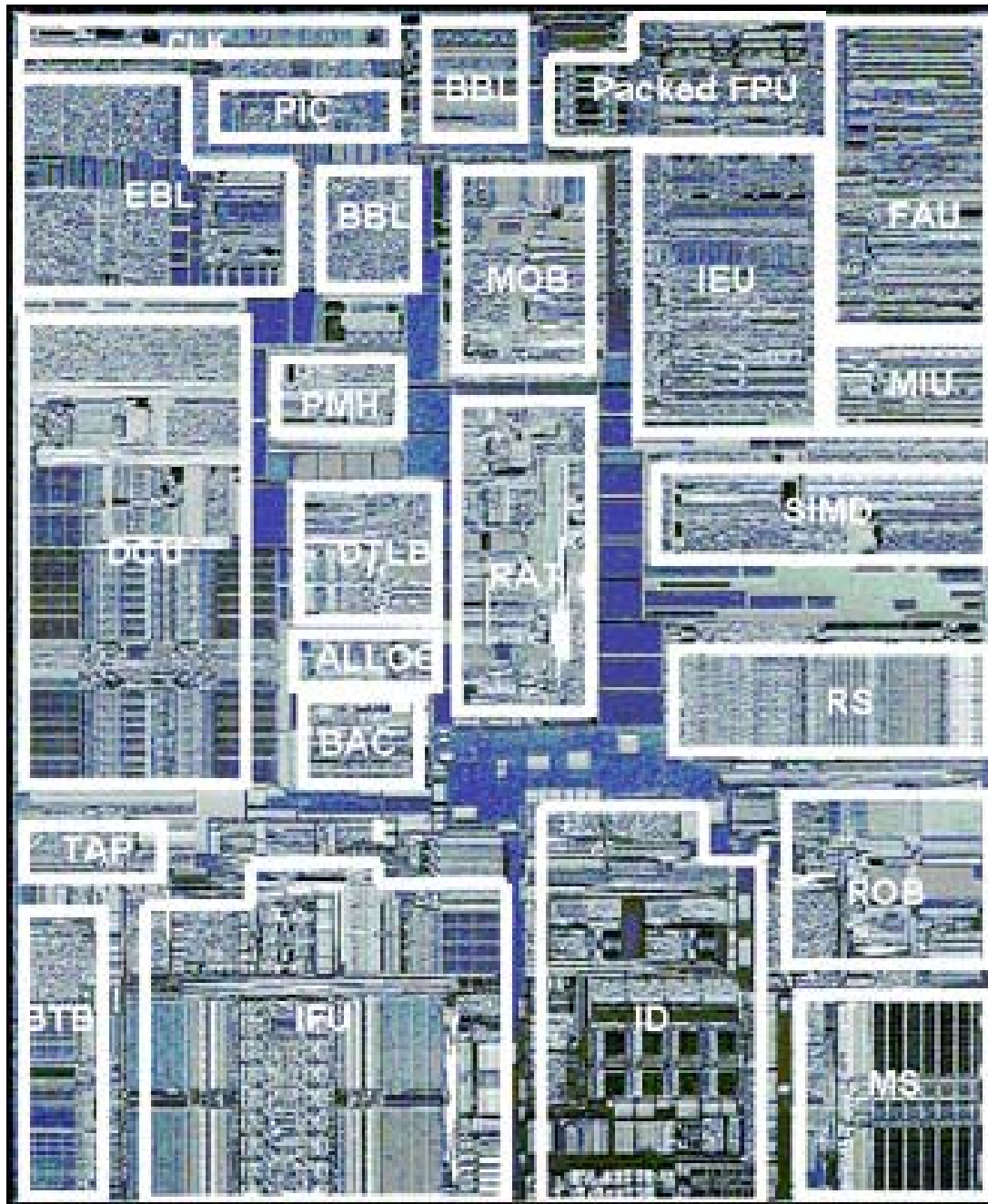
Advanced Computer Architecture Chapter 5

Instruction Level Parallelism - the static scheduling approach

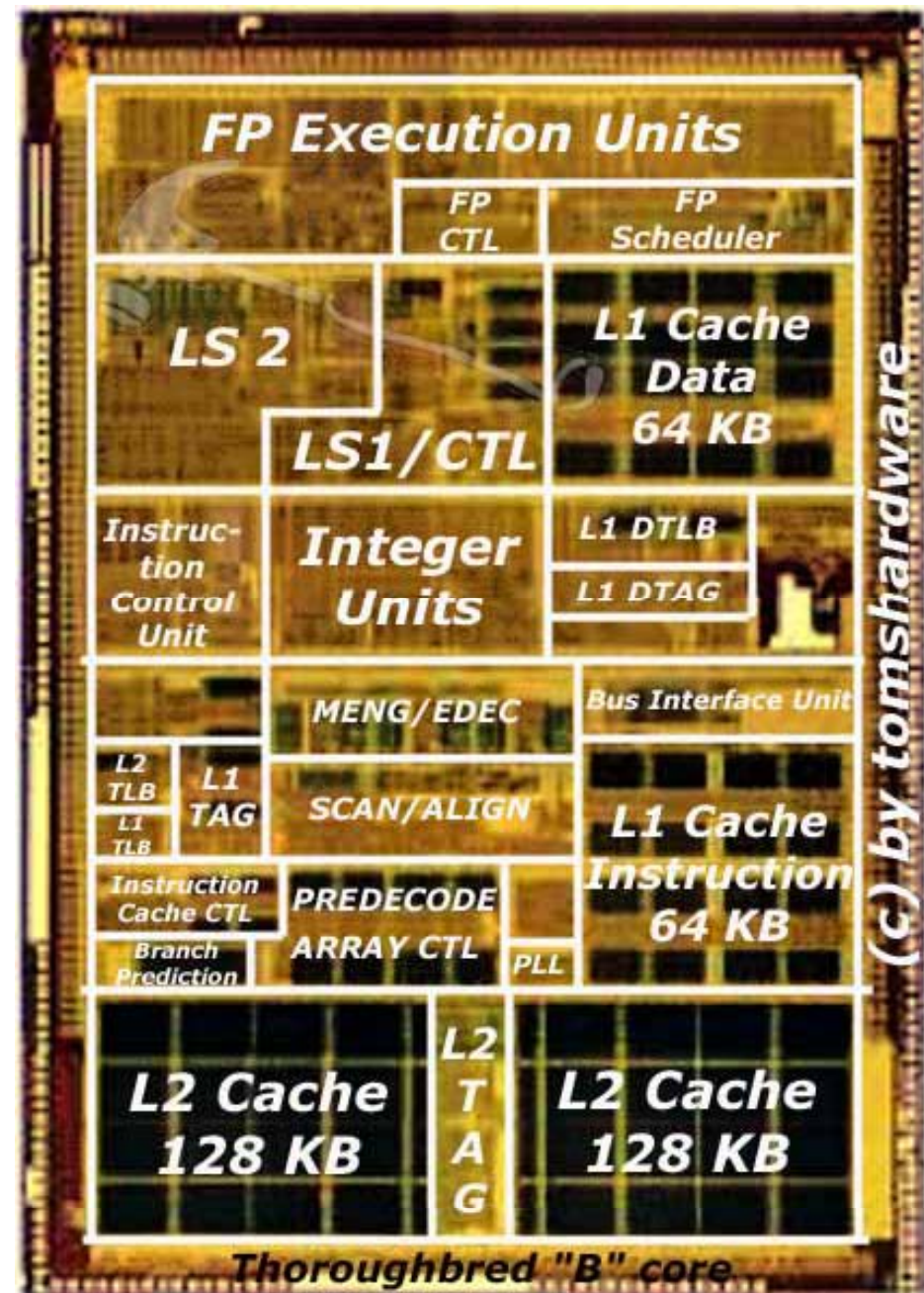
February 2009

Paul H J Kelly

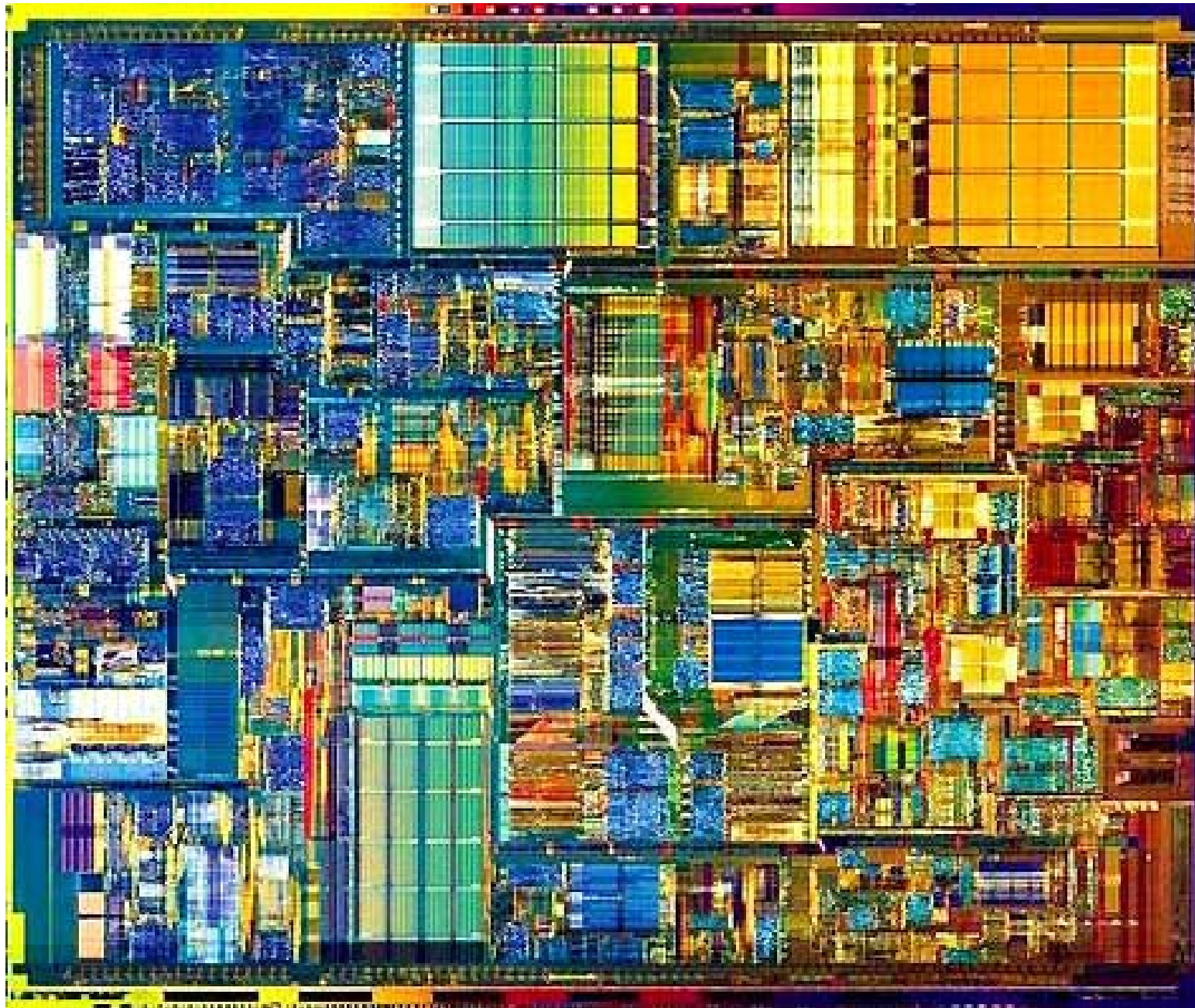
These lecture notes are partly based on the course text, Hennessy and Patterson's *Computer Architecture, a quantitative approach* (3rd and 4th eds), and on the lecture slides of David Patterson and John Kubiatawicz's Berkeley course



Intel Pentium III



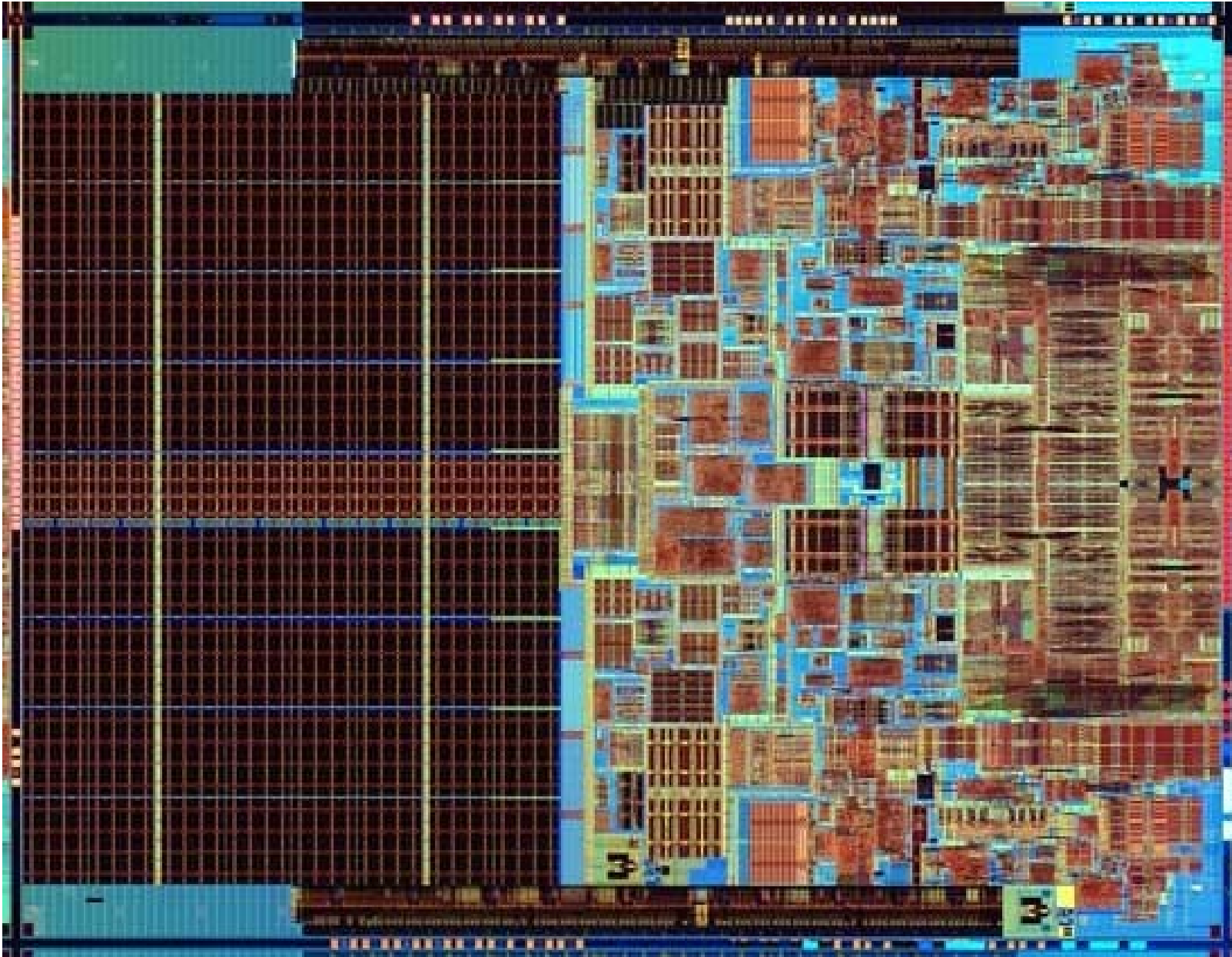
AMD Athlon CPU core



- 42M transistors
- 1.5GHz
- 180nm process
- 8K L1
- 256K L2

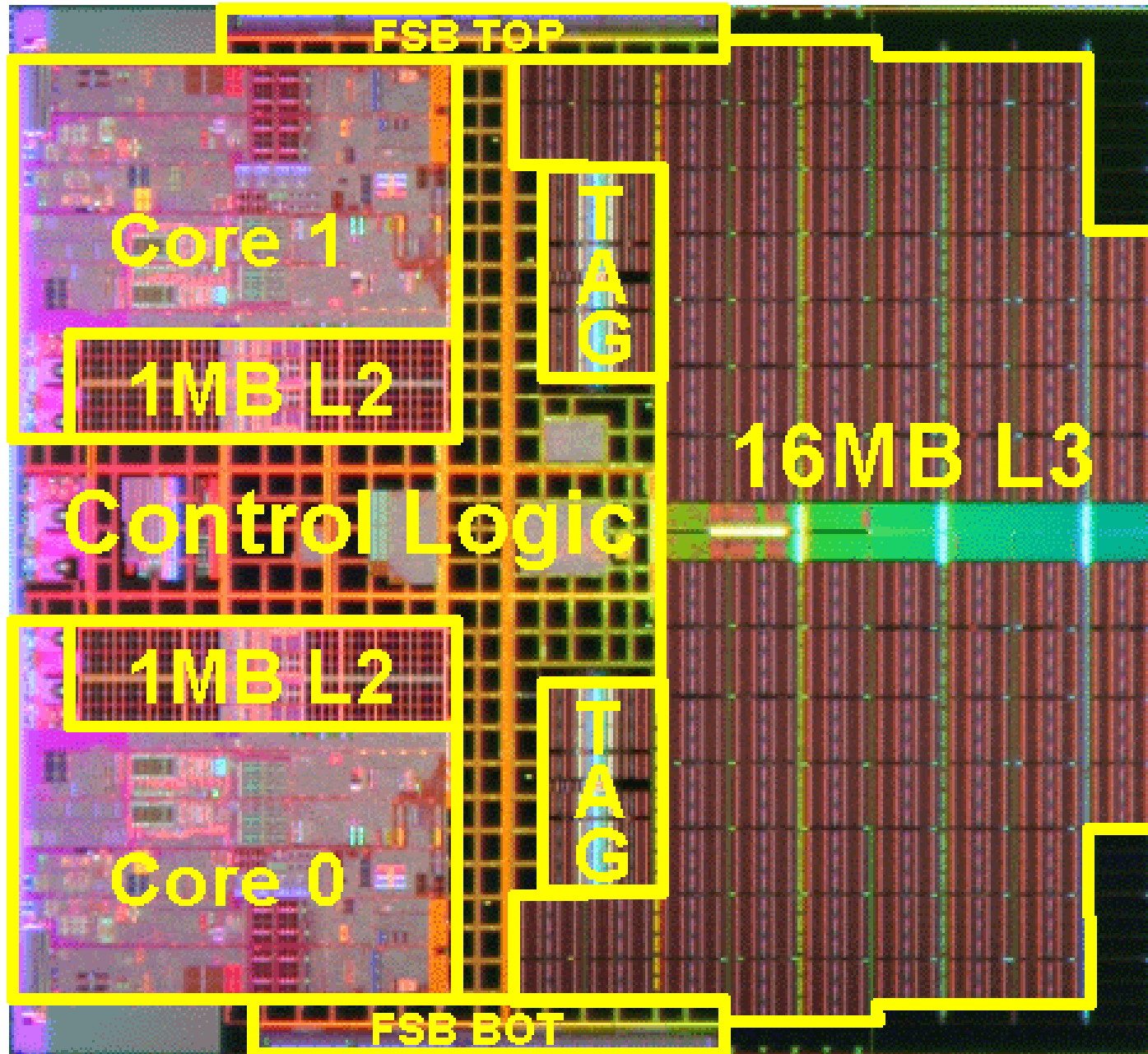
Intel 2000 - Pentium 4 "Netburst"

Intel Core 2 Duo



- Two cores/die
- 291M transistors
- 1.8-3.0 GHz
- 65nm process
- 4MB L2
- 65W

Intel 2006 - Tulsa: dual-core Pentium 4 ("Netburst") with shared L3

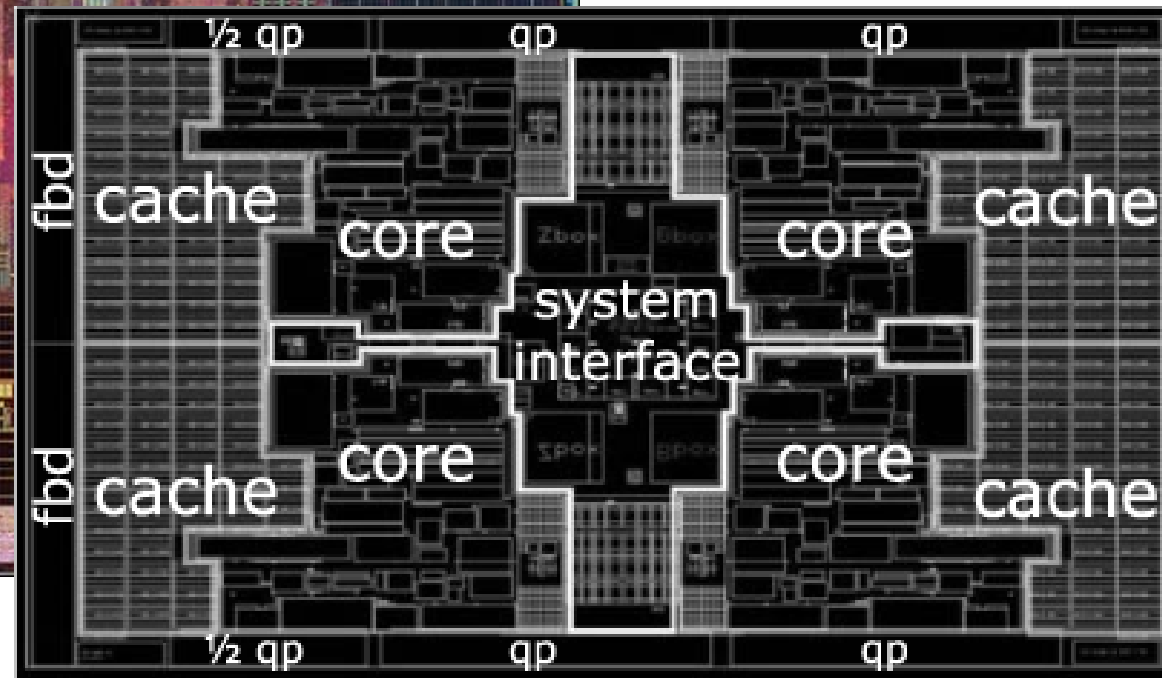


- 1MB L2 cache per core
- 16MB of inclusive shared L3 cache
- 1.3B transistors (121M/core)
- 435mm² in 65nm with 8 layers of copper interconnect
- 3.4GHz with 1.25V, and a 150W TDP and 110W average power.

<http://www.realworldtech.com/page.cfm?ArticleID=RWTO21906030756>

Intel 2008: Tukwila

- Quad-core
- IA-64
- 30MB L2



2B transistors

2GHz

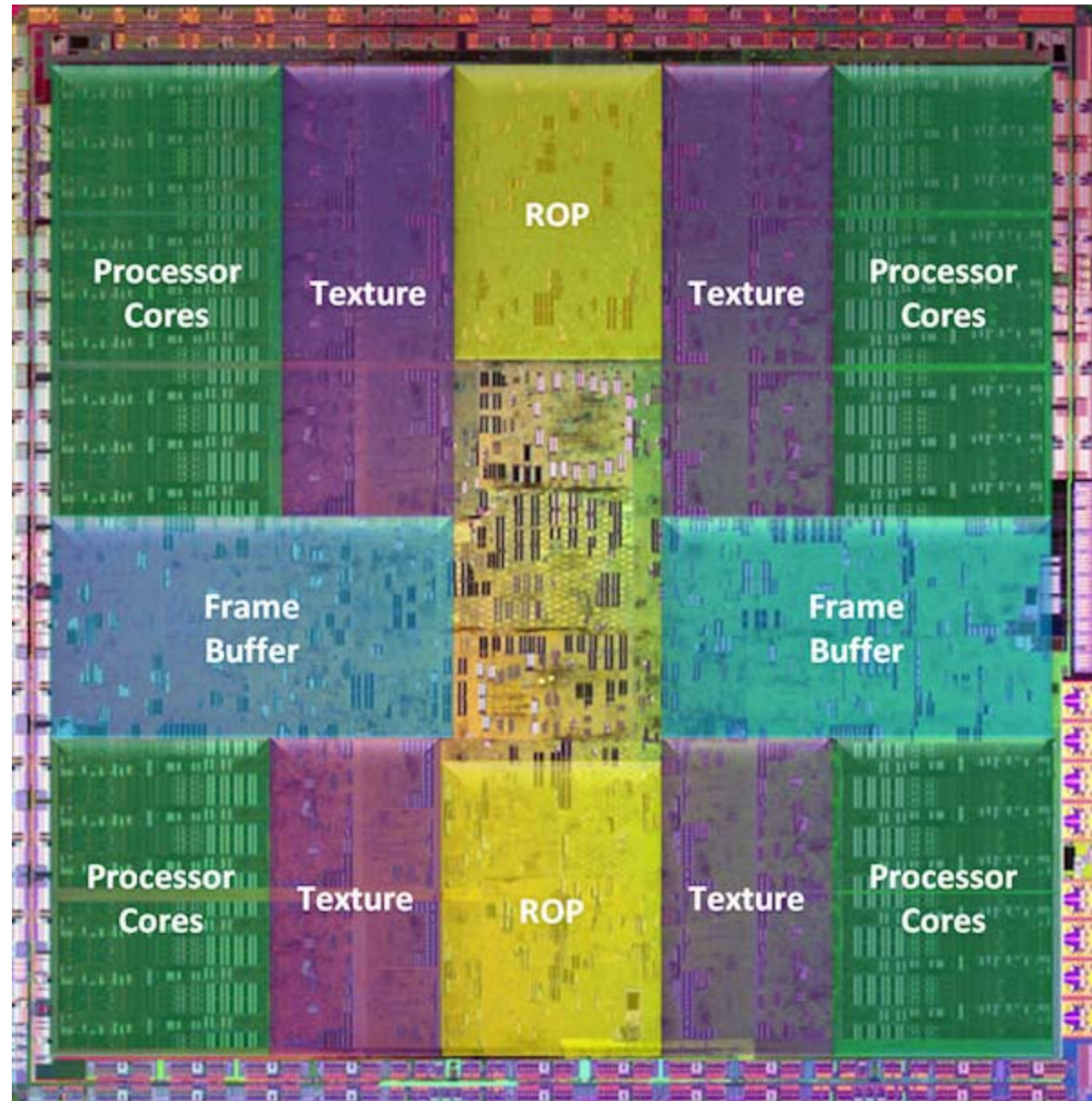
170W

65nm

	FET count	Voltage	Power
Core logic	430M	0.9-1.15V	100W
Sys Int	157M	0.9-1.15V	30W
L3 cache	1,420M	1.10V	20W
IO logic	39M	1.10V	20W
Chip Total	2.046B		170W

nVidia 2008

- nVidia G200
- 1.4B transistors
- 65nm
- 576mm² (apparently)
- max thermal design power (TDP): 236W
- Cards sell for around £320



Intel® Pentium® 4 and Intel® Xeon™ Processor Optimization

➡ <http://www.intel.com/design/pentium4/manuals/24896607.pdf>

Desktop Performance & Optimization for Intel® Pentium® 4 Processor

➡ <ftp://download.intel.com/design/pentium4/papers/24943801.pdf> (much shorter!)

Intel® compilers

➡ <http://www.intel.com/software/products/compilers/>

Intel's VTune performance analysis tool

➡ <http://www.intel.com/software/products/vtune/>

AMD Athlon x86 Code Optimization Guide

➡ http://www.amd.com/us_en/assets/content_type/white_papers_and_tech_docs/22007.pdf

➡ (see page 67 for the nine-step development of a routine to copy an array - 570MB/s to 1630MB/s)

Table 1. Approximate Ranges of Potential Application-Level Performance Gains of Several Code Optimization Techniques.

Item	Category	Coding Technique	Potential Relative Performance Gain
1	Memory	Pay Attention to Store-To-Load Forwarding Restrictions	~1.1 – 1.3X
2	Memory	Avoid Cache Line Splits, MOB Splits	~1.1 – 1.2X
3	Memory	Avoid Aliasing	~1.05 – 1.1X
4	Memory	Use 16 Byte Load/Store	~1.1X
5	Memory	Use Optimal Prefetch Instruction	~1.1 – 1.15X
6	Memory	Avoid Sparse Data Structures	~1.1 – 1.3X
7	Memory	Use Hybrid SOA Data Structure	~1.1X
8	Computation	Improve Branch Predictability	~1.05 – 1.1X
9	Computation	Minimize x87 Modes Changes	~1.1 – 1.3X
10	Computation	Eliminate x87 FP Exceptions	~1.1 – 1.3X
11	Computation	Enable FTZ/DAZ	~1.1 – 1.3X on SSE applications
12	Computation	Replace Long-latency Instructions	~1.1 – 1.2X
13	Graphics/Bus	Avoid Partial Writes/ Software Write-Combining	~1.1 – 1.2X
14	General	Integer work oads	~1.1 – 1.2X
15	General	Floating-point/SIMD workloads	~1.3 – 1.7X

Example: Pentium 4 memory aliasing

“There are several cases where addresses with a given stride will compete for some resource in the memory hierarchy. Note that first-level cache lines are 64 bytes and second-level cache lines are 128 bytes. Thus the least significant 6 or 7 bits are not considered in alias comparisons. The aliasing cases are listed below.

- 2K for data – map to the same first-level cache set (32 sets, 64-byte lines). There are 4 ways in the first-level cache, so if there are more than 4 lines that alias to the same 2K modulus in the working set, there will be an excess of first-level cache misses.
- 16K for data – will look same to the store-forwarding logic. If there has been a store to an address which aliases with the load, the load will stall until the store data is available.
- 16K for code – can only be one of these in the trace cache at a time. If two traces whose starting addresses are 16K apart are in the same working set, the symptom will be a high trace cache miss rate. Solve this by offsetting one of the addresses by 1 or more bytes.
- 32K for code or data – map to the same second-level cache set (256 sets, 128-byte lines). There are 8 ways in the second-level cache, so if there are more than 8 lines that alias to the same 32K modulus in the working set, there will be an excess of second-level cache misses.
- 64K for data – can only be one of these in the first-level cache at a time. If a reference (load or store) occurs that has bits 0-15 of the linear address, which are identical to a reference (load or store) which is underway, then second reference cannot begin until first one is kicked out of cache. Avoiding this kind of aliasing can lead to a factor of three speedup.” (<http://www.intel.com/design/pentium4/manuals/24896607.pdf> page 2-38)

Review: extreme dynamic ILP

■ P6 (Pentium Pro, II, III, AMD Athlon)

- Translate most 80x86 instructions to micro-operations
 - Longer pipeline than RISC instructions
- Dynamically execute micro-operations

■ "Netburst" (Pentium 4, ...)

- Much longer pipeline, higher clock rate in same technology as P6
- Trace Cache to capture micro-operations, avoid hardware translation

■ Intel Next Generation Microarchitecture (Pentium M, Core, Core 2 Duo)

- Shorter pipeline, wider issue, high-bandwidth smart decode instead of trace cache

■ How can we take these ideas further?

- Complexity of issuing multiple instructions per cycle
- And of committing them
 - n-way multi-issue processor with an m-instruction dynamic scheduling window
 - m must increase if n is increased
 - Need n register ports
 - Need to compare each of the n instruction's src and dst regs to determine dependence
- Predicting and speculating across multiple branches
- With many functional units and registers, wires will be long - need pipeline stage just to move the data across the chip

Overview

- The previous Chapter: Dynamic scheduling, out-of-order (o-o-o): binary compatible, exploiting ILP in hardware: BTB, ROB, Reservation Stations, ...
- How much of all this complexity can you shift into the compiler?
- What if you can also change instruction set architecture?
- VLIW (Very Long Instruction Word)
- EPIC (Explicitly Parallel Instruction Computer)
 - Intel's (and HP's) multi-billion dollar gamble for the future of computer architecture: Itanium, IA-64
 - Started ca.1994...not dead yet - but has it turned a profit?

Running Example

▶ This code adds a scalar to a vector:

```
for (i=1000; i>=0; i=i-1)
    x[i] = x[i] + s;
```

▶ Assume following latency all examples

<i>Instruction producing result</i>	<i>Instruction using result</i>	<i>Execution in cycles</i>	<i>Latency in cycles</i>
FP ALU op	Another FP ALU op	4	3
FP ALU op	Store double	3	2
Load double	FP ALU op	1	1
Load double	Store double	1	0
Integer op	Integer op	1	0

FP Loop: Where are the Hazards?

- First translate into MIPS code:

-To simplify, assume 8 is lowest address

```
Loop:  L.D      F0,0(R1)  ;F0=vector element
        ADD.D   F4,F0,F2  ;add scalar from F2
        S.D     0(R1),F4  ;store result
        DSUBUI  R1,R1,8   ;decrement pointer 8B (DW)
        BNEZ    R1,Loop   ;branch R1!=zero
        NOP                ;delayed branch slot
```

Where are the stalls?

FP Loop Showing Stalls

```
1 Loop: L.D      F0,0(R1) ;F0=vector element
2          stall
3          ADD.D  F4,F0,F2 ;add scalar in F2
4          stall
5          stall
6          S.D    0(R1),F4 ;store result
7          DSUBUI R1,R1,8  ;decrement pointer 8B (DW)
8          BNEZ   R1,Loop  ;branch R1!=zero
9          stall          ;delayed branch slot
```

<i>Instruction producing result</i>	<i>Instruction using result</i>	<i>Latency in clock cycles</i>
FP ALU op	Another FP ALU op	3
FP ALU op	Store double	2
Load double	FP ALU op	1

 **9 clocks: Rewrite code to minimize stalls?**

Revised FP Loop Minimizing Stalls

```
1 Loop: L.D    F0,0(R1)
2          stall
3          ADD.D F4,F0,F2
4          DSUBUI R1,R1,8
5          BNEZ  R1,Loop ;delayed branch
6          S.D   8(R1),F4 ;altered when move past DSUBUI
```

Swap BNEZ and S.D by changing address of S.D

<i>Instruction producing result</i>	<i>Instruction using result</i>	<i>Latency in clock cycles</i>
FP ALU op	Another FP ALU op	3
FP ALU op	Store double	2
Load double	FP ALU op	1

6 clocks, but just 3 for execution, 3 for loop overhead; How make faster?

Unroll Loop Four Times (straightforward way)

```
1 Loop:L.D      F0,0(R1)
2      ADD.D     F4,F0,F2
3      S.D       0(R1),F4
4      L.D       F6,-8(R1)
5      ADD.D     F8,F6,F2
6      S.D       -8(R1),F8
7      L.D       F10,-16(R1)
8      ADD.D     F12,F10,F2
9      S.D       -16(R1),F12
10     L.D       F14,-24(R1)
11     ADD.D     F16,F14,F2
12     S.D       -24(R1),F16
13     DSUBUI    R1,R1,#32
14     BNEZ      R1,LOOP
15     NOP
```

1 cycle stall
2 cycles stall
;drop DSUBUI & BNEZ
;drop DSUBUI & BNEZ
;drop DSUBUI & BNEZ
;alter to 4*8

Rewrite loop to
minimize stalls?

$15 + 4 \times (1+2) = 27$ clock cycles, or 6.8 per iteration
Assumes R1 is multiple of 4

Unroll the loop four times

- Four copies of the loop body
- One copy of increment and test
- Adjust register-indirect loads using offsets

```
1 Loop: L.D    F0, 0(R1)
2      ADD.D   F4, F0, F2
3      S.D     0(R1), F4      ;drop DSUBUI & BNEZ
4      L.D     F0, -8(R1)
5      ADD.D   F4, F0, F2
6      S.D     -8(R1), F4     ;drop DSUBUI & BNEZ
7      L.D     F0, -16(R1)
8      ADD.D   F4, F0, F2
9      S.D     -16(R1), F4    ;drop DSUBUI & BNEZ
10     L.D     F0, -24(R1)
11     ADD.D   F4, F0, F2
12     S.D     -24(R1), F4
13     DSUBUI  R1, R1, #32     ;alter to 4*8
14     BNEZ    R1, LOOP
15     NOP
```

- Re-use of registers creates WAR (“anti-dependences”)
 - How can we remove them?

Loop unrolling...

```
1 Loop: L.D    F0, 0(R1)
2      ADD.D   F4, F0, F2
3      S.D     0(R1), F4      ;drop DSUBUI & BNEZ
4      L.D     F6, -8(R1)
5      ADD.D   F8, F6, F2
6      S.D     -8(R1), F8     ;drop DSUBUI & BNEZ
7      L.D     F10, -16(R1)
8      ADD.D   F12, F10, F2
9      S.D     -16(R1), F12   ;drop DSUBUI & BNEZ
10     L.D     F14, -24(R1)
11     ADD.D   F16, F14, F2
12     S.D     -24(R1), F16
13     DSUBUI  R1, R1, #32     ;alter to 4*8
14     BNEZ    R1, LOOP
15     NOP
```

The original “register renaming”

Unrolled Loop That Minimizes Stalls

```
1 Loop: L.D      F0, 0(R1)
2         L.D      F6, -8(R1)
3         L.D      F10, -16(R1)
4         L.D      F14, -24(R1)
5         ADD.D    F4, F0, F2
6         ADD.D    F8, F6, F2
7         ADD.D    F12, F10, F2
8         ADD.D    F16, F14, F2
9         S.D      0(R1), F4
10        S.D      -8(R1), F8
11        S.D      -16(R1), F12
12        DSUBUI   R1, R1, #32
13        BNEZ     R1, LOOP
14        S.D      8(R1), F16 ; 8-32 = -24
```

What assumptions made when moved code?

- ➡ OK to move store past DSUBUI even though changes register
- ➡ OK to move loads before stores: get right data?
- ➡ When is it safe for compiler to do such changes?

14 clock cycles, or 3.5 per iteration

Compiler Perspectives on Code Movement

■ Name Dependencies are Hard to discover for Memory Accesses

- Does $100(R4) = 20(R6)$?
- From different loop iterations, does $20(R6) = 20(R6)$?
- Need to solve the “dependence equation”

■ Our example required compiler to know that if R1 doesn't change then:

$$0(R1) \neq -8(R1) \neq -16(R1) \neq -24(R1)$$

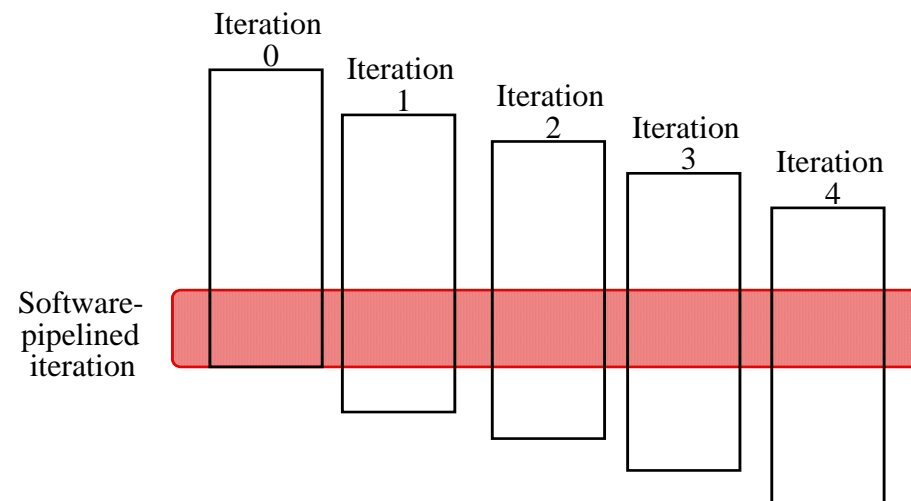
There were no dependencies between some loads and stores so they could be moved by each other

Steps Compiler Performed to Unroll

- ✓ Check OK to move the S.D after DSUBUI and BNEZ, and find amount to adjust S.D offset
- ✓ Determine unrolling the loop would be useful by finding that the loop iterations were independent
- ✓ Rename registers to avoid name dependencies
- ✓ Eliminate extra test and branch instructions and adjust the loop termination and iteration code
- ✓ Determine loads and stores in unrolled loop can be interchanged by observing that the loads and stores from different iterations are independent
 - ✦ requires analyzing memory addresses and finding that they do not refer to the same address.
- ✓ Schedule the code, preserving any dependences needed to yield same result as the original code

Another possibility: Software Pipelining

- Observation: if iterations from loops are independent, then can get more ILP by taking instructions from different iterations
- Software pipelining: reorganizes loops so that each iteration is made from instructions chosen from different iterations of the original loop (~ Tomasulo in SW)



Software Pipelining Example

Before: Unrolled 3 times

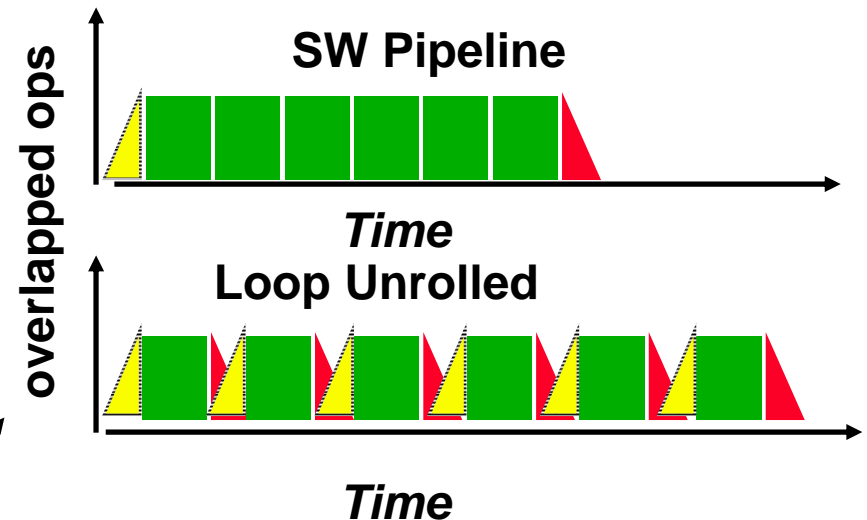
```
1  L.D   F0,0(R1)
2  ADD.D F4,F0,F2
3  S.D   0(R1),F4
4  L.D   F6,-8(R1)
5  ADD.D F8,F6,F2
6  S.D   -8(R1),F8
7  L.D   F10,-16(R1)
8  ADD.D F12,F10,F2
9  S.D   -16(R1),F12
10 DSUBUI R1,R1,#24
11 BNEZ  R1,LOOP
```

After: Software Pipelined

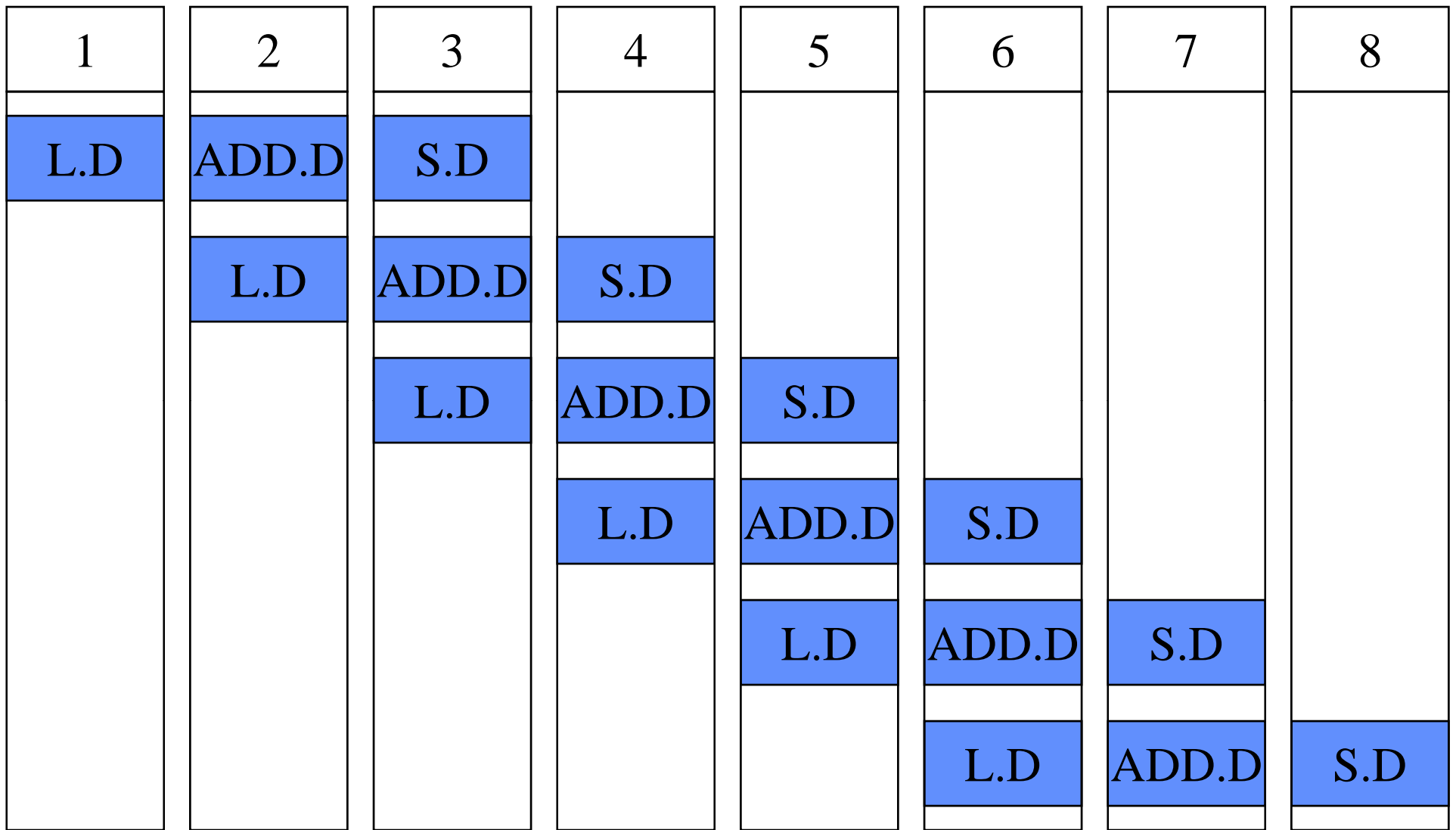
```
1  S.D   0(R1),F4 ; Stores M[i]
2  ADD.D F4,F0,F2 ; Adds to M[i-1]
3  L.D   F0,-16(R1); Loads M[i-2]
4  DSUBUI R1,R1,#8
5  BNEZ  R1,LOOP
```

- **Symbolic Loop Unrolling**

- Maximize result-use distance
- Less code space than unrolling
- Fill & drain pipe only once per loop
vs. once per each unrolled iteration in loop unrolling



5 cycles per iteration



Pipeline fills

Pipeline full

Pipeline drains

Loop-carried dependencies

Example: Where are data dependencies?
(A,B,C distinct & non-overlapping)

```
for (i=0; i<100; i=i+1) {  
    A[i+1] = A[i] + C[i];    /* S1 */  
    B[i+1] = B[i] + A[i+1];  /* S2 */  
}
```

1. S2 uses the value, A[i+1], computed by S1 in the same iteration.
2. S1 uses a value computed by S1 in an earlier iteration, since iteration i computes A[i+1] which is read in iteration i+1. The same is true of S2 for B[i] and B[i+1].

This is a “**loop-carried dependence**”: between iterations

For our prior example, each iteration was distinct

Implies that iterations can't be executed in parallel,
Right????

Does a loop-carried dependence mean there is no parallelism???

Consider:

```
for (i=0; i< 8; i=i+1) {  
    A = A + C[i];      /* S1 */  
}
```

Could compute:

"Cycle 1":
temp0 = C[0] + C[1];
temp1 = C[2] + C[3];
temp2 = C[4] + C[5];
temp3 = C[6] + C[7];
"Cycle 2":
temp4 = temp0 + temp1;
temp5 = temp2 + temp3;
"Cycle 3":
A = temp4 + temp5;

Relies on associative nature of "+".

See "Parallelizing Complex Scans and Reductions" by Allan Fisher and Anwar Ghuloum (<http://doi.acm.org/10.1145/178243.178255>)

Associativity in floating point

• $(a+b)+c = a+(b+c)$?

• Example: Consider 3-digit base-10 floating-point

$$\underbrace{1+1+1+1+1+1+1+1+\dots+1+1+1+1+1+1+1+1+1+1+1+1+1+1}_{1000 \text{ ones}} + 1000$$

$$1000 + \underbrace{1+1+1+1+1+1+1+1+\dots+1+1+1+1+1+1+1+1+1+1+1+1+1+1}_{1000 \text{ ones}}$$

Consequence: many compilers use loop unrolling and reassociation to enhance parallelism in summations
And results are different!

What if We Can Change Instruction Set?

- ▀ Superscalar processors decide on the fly how many instructions to issue
 - ➡ HW complexity of Number of instructions to issue $O(n^2)$
- ▀ Why not allow compiler to schedule instruction level parallelism explicitly?
- ▀ Format the instructions in a potential issue packet so that HW need not check explicitly for dependences

VLIW: Very Large Instruction Word

Each “instruction” has explicit coding for multiple operations

- In IA-64, grouping called a “packet”
- In Transmeta, grouping called a “molecule” (with “atoms” as ops)

Tradeoff instruction space for simple decoding

- The long instruction word has room for many operations
- By definition, all the operations the compiler puts in the long instruction word are independent => execute in parallel
- E.g., 2 integer operations, 2 FP ops, 2 Memory refs, 1 branch
 - 16 to 24 bits per field => 7*16 or 112 bits to 7*24 or 168 bits wide
- Need compiling technique that schedules across several branches

Recall: Unrolled Loop that Minimizes Stalls for Scalar

1	Loop:	L.D	F0,0(R1)		L.D to ADD.D: 1 Cycle
2		L.D	F6,-8(R1)		ADD.D to S.D: 2 Cycles
3		L.D	F10,-16(R1)		
4		L.D	F14,-24(R1)		
5		ADD.D	F4,F0,F2		
6		ADD.D	F8,F6,F2		
7		ADD.D	F12,F10,F2		
8		ADD.D	F16,F14,F2		
9		S.D	0(R1),F4		
10		S.D	-8(R1),F8		
11		S.D	-16(R1),F12		
12		DSUBUI	R1,R1,#32		
13		BNEZ	R1,LOOP		
14		S.D	8(R1),F16	; 8-32 = -24	

14 clock cycles, or 3.5 per iteration

Loop Unrolling in VLIW

<i>Memory reference 1</i>	<i>Memory reference 2</i>	<i>FP operation 1</i>	<i>FP op. 2</i>	<i>Int. op/ branch</i>	<i>Clock</i>
L.D F0,0(R1)	L.D F6,-8(R1)				1
L.D F10,-16(R1)	L.D F14,-24(R1)				2
L.D F18,-32(R1)	L.D F22,-40(R1)	ADD.D F4,F0,F2	ADD.D F8,F6,F2		3
L.D F26,-48(R1)		ADD.D F12,F10,F2	ADD.D F16,F14,F2		4
		ADD.D F20,F18,F2	ADD.D F24,F22,F2		5
S.D 0(R1),F4	S.D -8(R1),F8	ADD.D F28,F26,F2			6
S.D -16(R1),F12	S.D -24(R1),F16				7
S.D -32(R1),F20	S.D -40(R1),F24			DSUBUI R1,R1,#48	8
S.D -0(R1),F28				BNEZ R1,LOOP	9

Unrolled 7 times to avoid delays

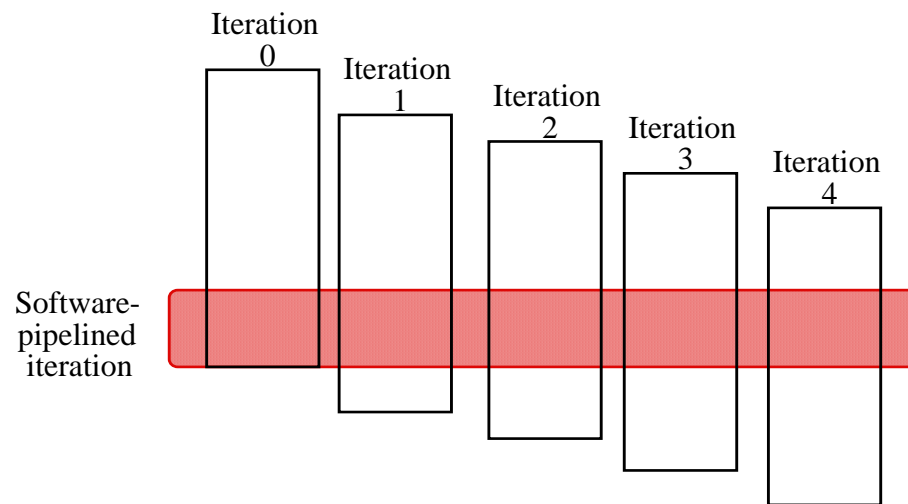
7 results in 9 clocks, or 1.3 clocks per iteration (1.8X)

Average: 2.5 ops per clock, 50% efficiency

Note: Need more registers in VLIW (15 vs. 6 in SS)

Recall: Software Pipelining

- Observation: if iterations from loops are independent, then can get more ILP by taking instructions from different iterations
- Software pipelining: reorganizes loops so that each iteration is made from instructions chosen from different iterations of the original loop (~ Tomasulo in SW)



Recall: Software Pipelining Example

Before: Unrolled 3 times

```

1  L.D    F0,0(R1)
2  ADD.D  F4,F0,F2
3  S.D    0(R1),F4
4  L.D    F6,-8(R1)
5  ADD.D  F8,F6,F2
6  S.D    -8(R1),F8
7  L.D    F10,-16(R1)
8  ADD.D  F12,F10,F2
9  S.D    -16(R1),F12
10 DSUBUI R1,R1,#24
11 BNEZ   R1,LOOP
    
```

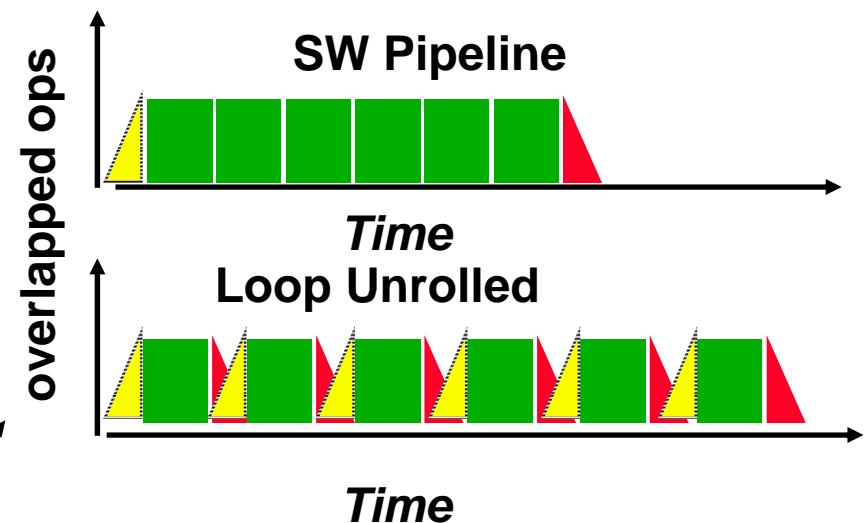
After: Software Pipelined

```

1  S.D    0(R1),F4 ; Stores M[i]
2  ADD.D  F4,F0,F2 ; Adds to M[i-1]
3  L.D    F0,-16(R1); Loads M[i-2]
4  DSUBUI R1,R1,#8
5  BNEZ   R1,LOOP
    
```

• Symbolic Loop Unrolling

- Maximize result-use distance
- Less code space than unrolling
- Fill & drain pipe only once per loop
vs. once per each unrolled iteration in loop unrolling



Software Pipelining with Loop Unrolling in VLIW

<i>Memory reference 1</i>	<i>Memory reference 2</i>	<i>FP operation 1</i>	<i>FP operation 2</i>	<i>Int. op/branch</i>	<i>Clock</i>
L.D F0,-48(R1)	ST 0(R1),F4	ADD.D F4,F0,F2			1
L.D F6,-56(R1)	ST -8(R1),F8	ADD.D F8,F6,F2		DSUBUI R1,R1,#24	2
L.D F10,-40(R1)	ST 8(R1),F12	ADD.D F12,F10,F2		BNEZ R1,LOOP	3

Software pipelined across 9 iterations of original loop

➡ In each iteration of above loop, we:

- Store to m,m-8,m-16 (iterations l-3,l-2,l-1)
- Compute for m-24,m-32,m-40 (iterations l,l+1,l+2)
- Load from m-48,m-56,m-64 (iterations l+3,l+4,l+5)

➡ 9 results in 9 cycles, or 1 clock per iteration

➡ Average: 3.3 ops per clock, 66% efficiency

**Note: Need fewer registers for software pipelining
(only using 7 registers here, was using 15)**

Trace Scheduling

Parallelism across IF branches vs. LOOP branches?

Two steps:

➤ *Trace Selection*

- Find likely sequence of basic blocks (*trace*) of (statically predicted or profile predicted) long sequence of straight-line code

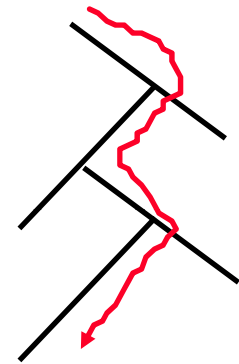
➤ *Trace Compaction*

- Squeeze trace into few VLIW instructions
- Need bookkeeping code in case prediction is wrong

This is a form of compiler-generated speculation

- Compiler must generate “fixup” code to handle cases in which trace is not the taken branch
- Needs extra registers: undoes bad guess by discarding

Subtle compiler bugs mean wrong answer vs. poorer performance; no hardware interlocks



Advantages of HW (Tomasulo) vs. SW (VLIW) Speculation

HW advantages:

- HW better at memory disambiguation since knows actual addresses
- HW better at branch prediction since lower overhead
- HW maintains precise exception model
- HW does not execute bookkeeping instructions
- Same software works across multiple implementations
- Smaller code size (not as many nops filling blank instructions)

SW advantages:

- Window of instructions that is examined for parallelism much higher
- Much less hardware involved in VLIW (unless you are Intel...!)
- More involved types of speculation can be done more easily
- Speculation can be based on large-scale program behavior, not just local information

Superscalar v. VLIW

- Smaller code size
- Binary compatibility across generations of hardware
- Simplified Hardware for decoding, issuing instructions
- No Interlock Hardware (compiler checks?)
- More registers, but simplified Hardware for Register Ports (multiple independent register files?)

Real VLIW

VLIW Minisupercomputers/Superminicomputers:

- ▶ Multiflow TRACE 7/300, 14/300, 28/300 [Josh Fisher]
- ▶ Multiflow TRACE /500 [Bob Colwell]
- ▶ Cydrome Cydra 5 [Bob Rau]
- ▶ IBM Yorktown VLIW Computer (research machine)

Single-Chip VLIW Processors:

- ▶ Intel iWarp

Single-Chip VLIW Media (throughput) Processors:

- ▶ Trimedia, Chromatic, Micro-Unity
- ▶ DSP Processors (TI TMS320C6x)

Hybrids...

- ▶ Intel/HP EPIC IA-64 (Explicitly Parallel Instruction Comp.)
- ▶ Transmeta Crusoe (x86 on VLIW??)

Problems with First Generation VLIW

▀ Increase in code size

- ▀ generating enough operations in a straight-line code fragment requires ambitiously unrolling loops
- ▀ whenever VLIW instructions are not full, unused functional units translate to wasted bits in instruction encoding

▀ Operated in lock-step; no hazard detection HW

- ▀ a stall in any functional unit pipeline caused entire processor to stall, since all functional units must be kept synchronized
- ▀ Compiler might know functional unit latencies, but caches harder to predict

▀ Binary code compatibility

- ▀ Pure VLIW => different numbers of functional units and unit latencies require different versions of the code

Intel/HP IA-64 “Explicitly Parallel Instruction Computer (EPIC)”

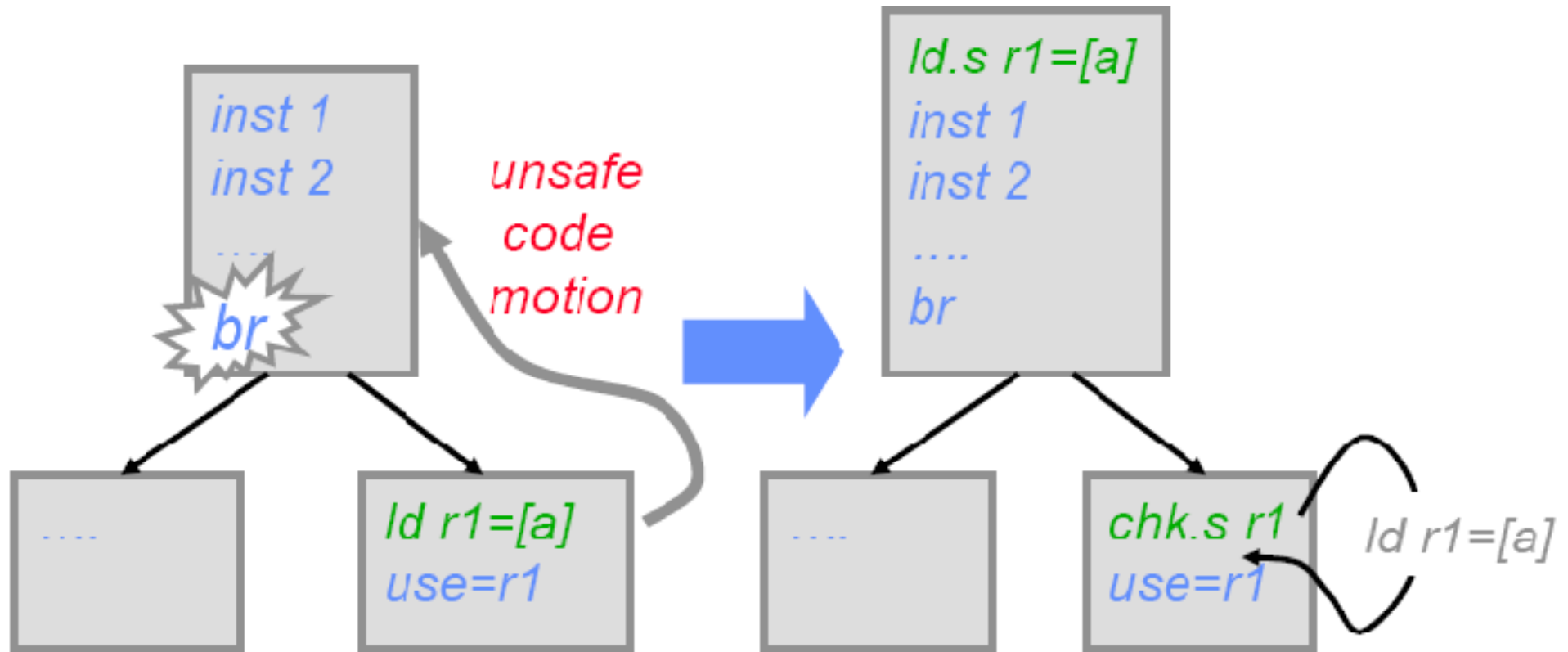
- ✚ IA-64: instruction set architecture; EPIC is type
 - EPIC = 2nd generation VLIW?
- ✚ Itanium™ first implementation
 - Highly parallel and deeply pipelined hardware at 800Mhz
 - 6-wide, 10-stage pipeline
 - Not competitive
- ✚ Itanium 2
 - 6-wide, 8-stage pipeline
 - 16KB L1I, 16KB L1D (one cycle), 256KB L2 (5 cycle), 3MB L3 (12 cycle), all on-die
 - <http://www.intel.com/products/server/processors/server/itanium2/>
 - Competitive for some applications (eg SPEC FP)
- ✚ 128 64-bit integer registers + 128 82-bit floating point registers
 - Not separate register files per functional unit as in old VLIW
- ✚ Hardware checks dependencies (interlocks => binary compatibility over time)
- ✚ Predicated execution (select 1 out of 64 1-bit flags)
=> 40% fewer mispredictions?

Hardware Support for Exposing More Parallelism at Compile-Time

To help trace scheduling and software pipelining, the Itanium instruction set includes several interesting mechanisms:

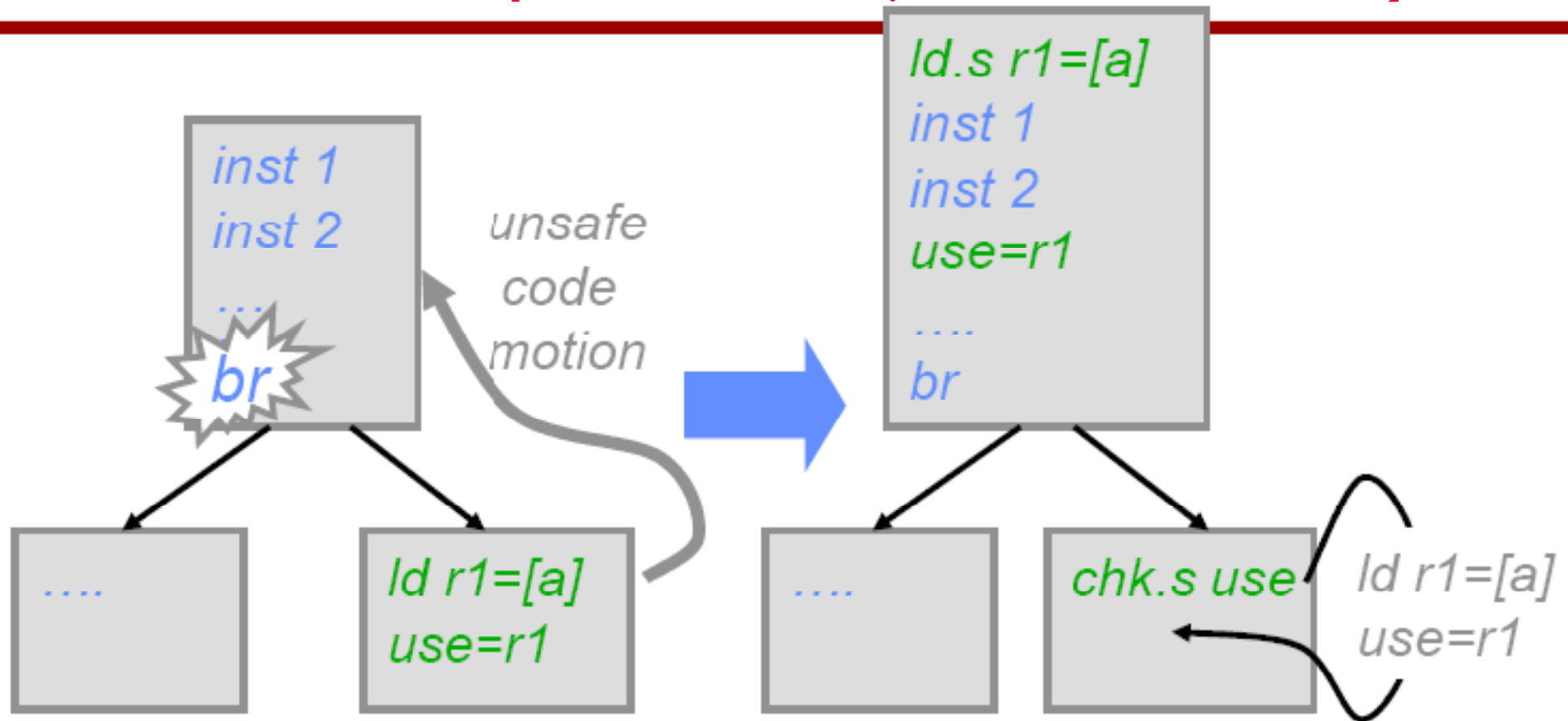
- ▮ Predicated execution
 - ▮ Speculative, non-faulting Load instruction
 - ▮ Software-assisted branch prediction
 - ▮ Register stack
 - ▮ Rotating register frame
 - ▮ Software-assisted memory hierarchy
- ▮ Job creation scheme for compiler engineers

IA64: Speculative, Non-Faulting Load



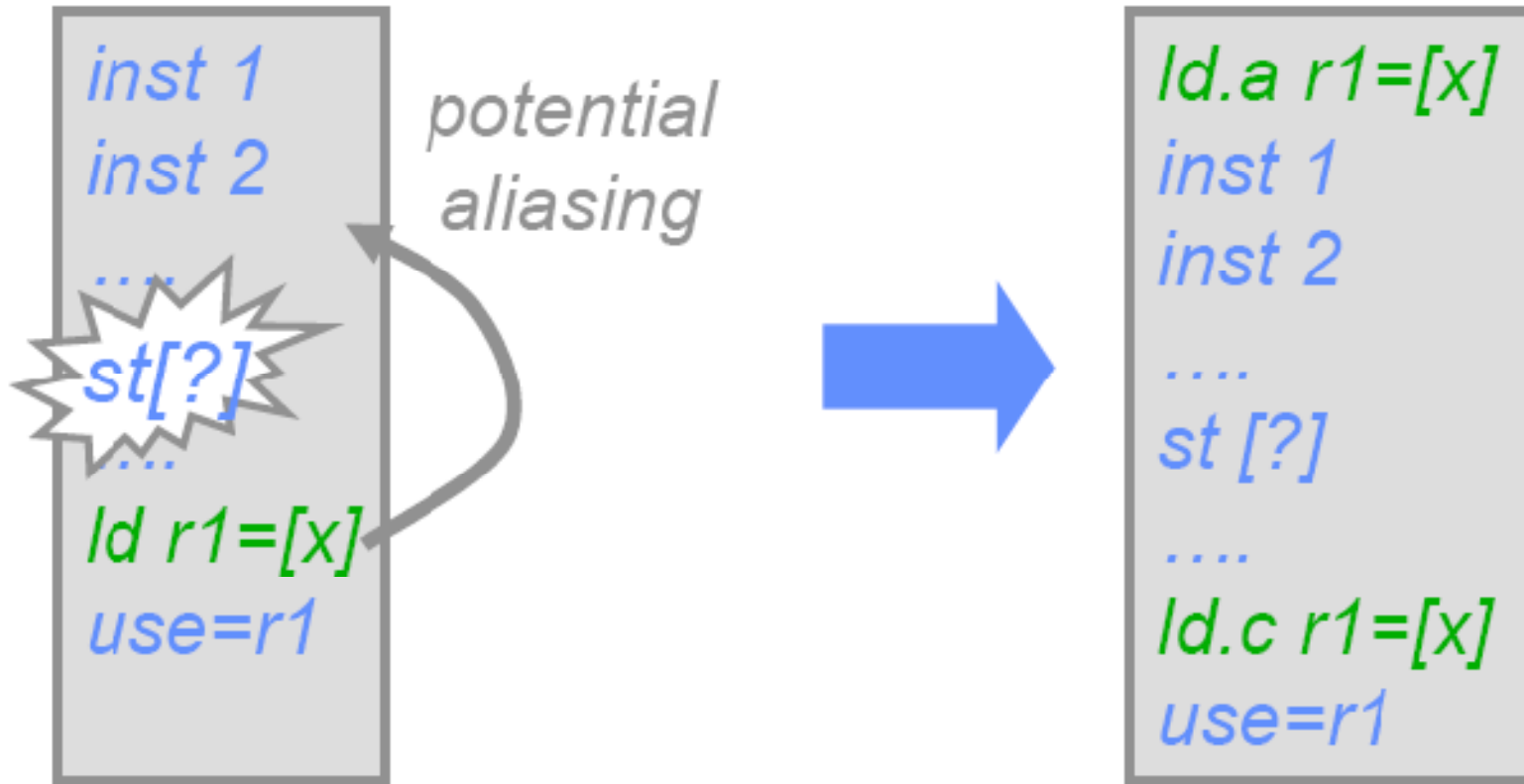
- `ld.s` fetches speculatively from memory
 - i.e. any exception due to `ld.s` is suppressed
- If `ld.s r` did not cause an exception then `chk.s r` is an NOP, else a branch is taken to some compensation code

IA64: Speculative, Non-Faulting Load



- Speculatively-loaded data can be consumed prior to check
- "speculation" status is propagated with speculated data
- Any instruction that uses a speculative result also becomes
 - ➔ (i.e. suppressed exceptions)
- chk.s** checks the entire dataflow sequence for exceptions

IA64: Speculative "Advanced" Load



- **ld.a** starts the monitoring of any store to the same address as the advanced load
- If no aliasing has occurred since **ld.a**, **ld.c** is a NOP
- If aliasing has occurred, **ld.c** re-loads from memory

IA64: Branch prediction

• Static branch hints can be encoded with every branch

- taken vs. not-taken
- whether to allocate an entry in the dynamic BP hardware

• SW and HW has joint control of BP hardware

- "brp" (branch prediction) instruction can be issued ahead of the actual branch to preset the contents of BHT and TBT

Itanium-1 used a 512-entry 2-level BHT and 64-entry BTB

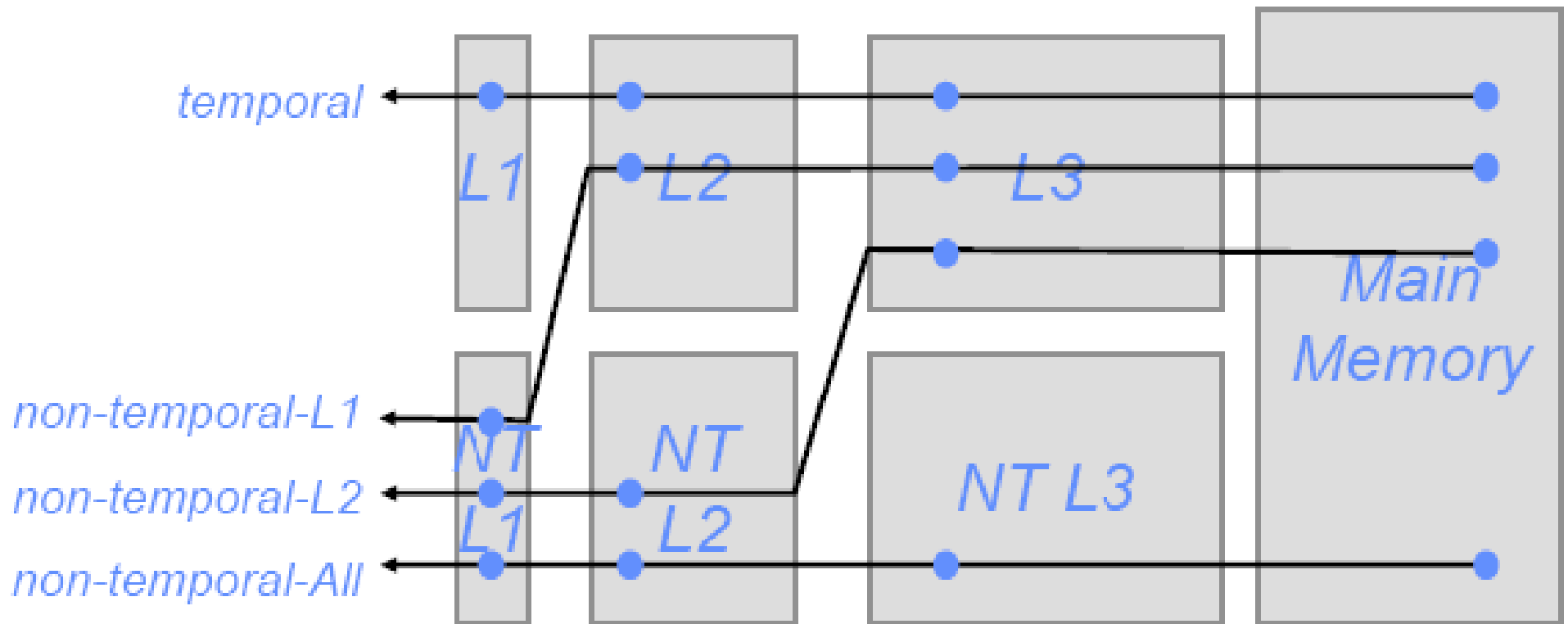
• TAR (Target Address Register)

- a small, fully-associative BTAC-like structure
- contents are controlled entirely by a "prepare-to-branch" inst.
- a hit in TAR overrides all other predictions

• RSB (Return Address Stack)

- Procedure return addr is pushed (or popped) when a procedure is called (or when it returns)
- Predicts nPC when executing register-indirect branches

IA64: Software-Assisted Memory Hierarchies



- ISA provides for separate storages for "temporal" vs "non-temporal" data, each with its own multiple level of hierarchies
- Load and Store instructions can give hints about where cached copies should be held after a cache miss

IA-64 Registers

- The integer registers are configured to help accelerate procedure calls using a register stack
 - mechanism similar to that developed in the Berkeley RISC-I processor and used in the SPARC architecture.
 - Registers 0-31 are always accessible and addressed as 0-31
 - Registers 32-128 are used as a register stack and each procedure is allocated a set of registers (from 0 to 96)
 - The new register stack frame is created for a called procedure by renaming the registers in hardware;
 - a special register called the current frame pointer (CFP) points to the set of registers to be used by a given procedure
- 8 64-bit Branch registers used to hold branch destination addresses for indirect branches
- 64 1-bit predicate registers

Intel/HP IA-64 “Explicitly Parallel Instruction Computer (EPIC)”

- **Instruction group**: a sequence of consecutive instructions with no register data dependences
 - All the instructions in a group could be executed in parallel, if sufficient hardware resources existed and if any dependences through memory were preserved
 - An instruction group can be arbitrarily long, but the compiler must explicitly indicate the boundary between one instruction group and another by placing a **stop** between 2 instructions that belong to different groups
- IA-64 instructions are encoded in **bundles**, which are 128 bits wide.
 - Each bundle consists of a 5-bit template field and 3 instructions, each 41 bits in length
- 3 Instructions in 128 bit “groups”; field determines if instructions dependent or independent
 - Smaller code size than old VLIW, larger than x86/RISC
 - Groups can be linked to show independence > 3 instr

5 Types of Execution in Bundle

<i>Execution Unit Slot</i>	<i>Instruction type</i>	<i>Instruction Description</i>	<i>Example Instructions</i>
I-unit	A	Integer ALU	add, subtract, and, or, cmp
	I	Non-ALU Int	shifts, bit tests, moves
M-unit	A	Integer ALU	add, subtract, and, or, cmp
	M	Memory access	Loads, stores for int/FP regs
F-unit	F	Floating point	Floating point instructions
B-unit	B	Branches	Conditional branches, calls
L+X	L+X	Extended	Extended immediates, stops

- 5-bit template field within each bundle describes both the presence of any stops associated with the bundle *and* the execution unit type required by each instruction within the bundle (see Fig 4.12 page 271)

IA-64 Registers

- Both the integer and floating point registers support register rotation for registers 32-128.
- Register rotation is designed to ease the task of register allocation in software pipelined loops
- When combined with predication, possible to avoid the need for unrolling and for separate prologue and epilogue code for a software pipelined loop
 - ✦ makes the SW-pipelining usable for loops with smaller numbers of iterations, where the overheads would traditionally negate many of the advantages

How Register Rotation Helps Software Pipelining

The concept of a software pipelining branch:

```
L1:    ld4      r35 = [r4], 4    // post-increment by 4
        st4     [r5] = r37, 4    // post-increment by 4
        br.ctop L1 ;;
```

The `br.ctop` instruction in the example rotates the general registers (actually `br.ctop` does more as we shall see)

Therefore the value stored into `r35` is read in `r37` two iterations (and two rotations) later.

The register rotation eliminated a dependence between the load and the store instructions, and allowed the loop to execute in one cycle.

- Register rotation is useful for procedure calls
- It's also useful for software-pipelined loops
- The logical-to-physical register mapping is shifted by 1 each time the branch ("`br.ctop`") is executed

Software Pipelining Example in the IA-64

```
mov pr.rot      = 0      // Clear all rotating predicate registers
cmp.eq p16,p0 = r0,r0    // Set p16=1
mov ar.lc       = 4      // Set loop counter to n-1
mov ar.ec       = 3      // Set epilog counter to 3
```

...

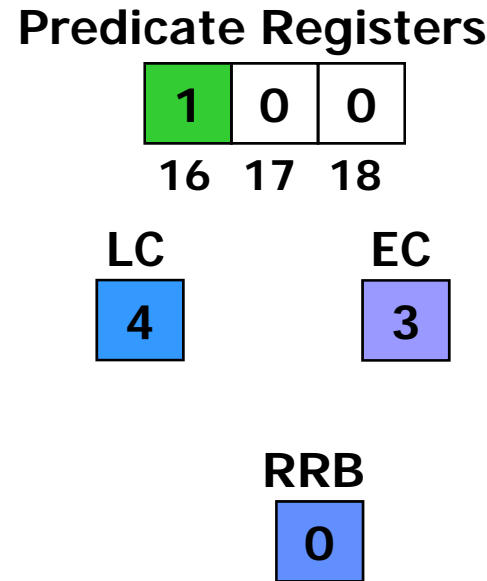
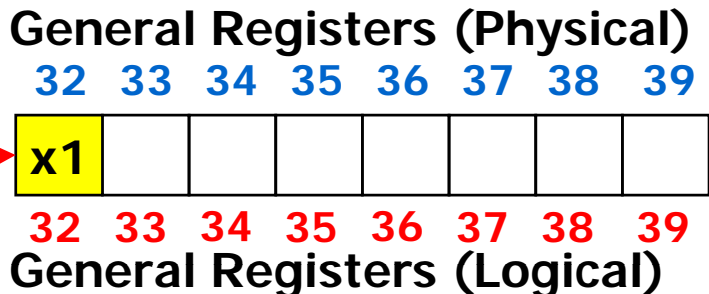
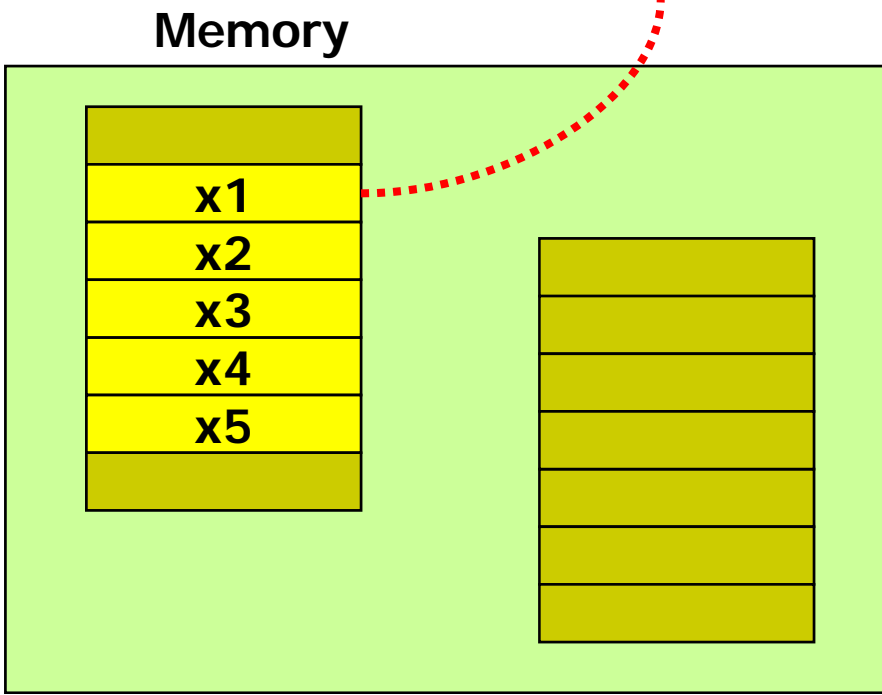
loop:

```
(p16)  ldl r32  = [r12], 1      // Stage 1: load x
(p17)  add r34  = 1, r33        // Stage 2: y=x+1
(p18)  stl [r13] = r35,1        // Stage 3: store y
      br.ctop loop            // Branch back
```

- ▀ “Stage” predicate mechanism allows successive stages of the software pipeline to be filled on start-up and drained when the loop terminates
- ▀ The software pipeline branch “br.ctop” rotates the predicate registers, and injects a 1 into p16
- ▀ Thus enabling one stage at a time, for execution of prologue
- ▀ When loop trip count is reached, “br.ctop” injects 0 into p16, disabling one stage at a time, then finally falls-through

Software Pipelining Example in the IA-64

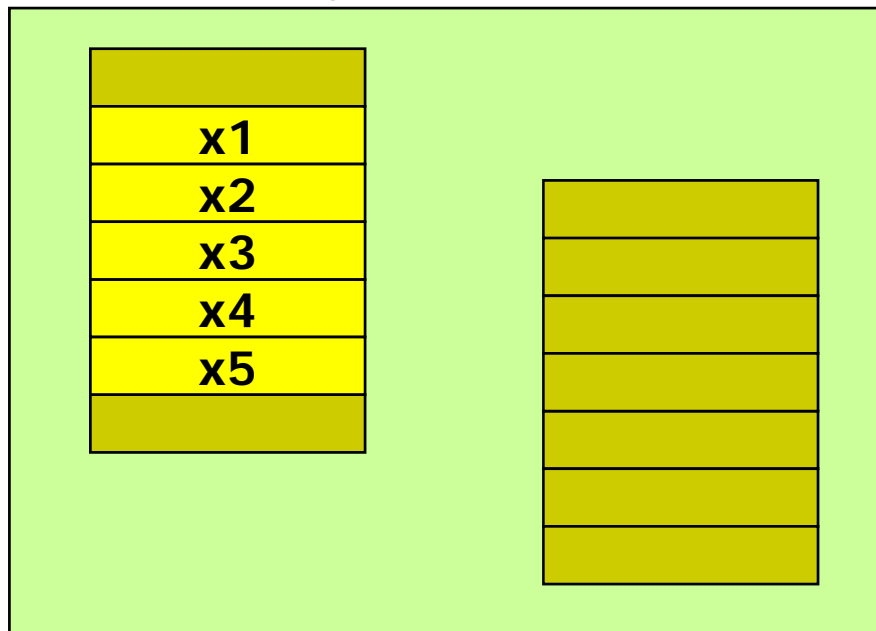
```
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
```



Software Pipelining Example in the IA-64

```
loop:
(p16) ldl r32 = [r12], 1
(p17) add r34 = 1, r33
(p18) stl [r13] = r35, 1
      br.ctop loop
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
x1							

General Registers (Logical)

Predicate Registers

1	0	0
16	17	18

LC

4

EC

3

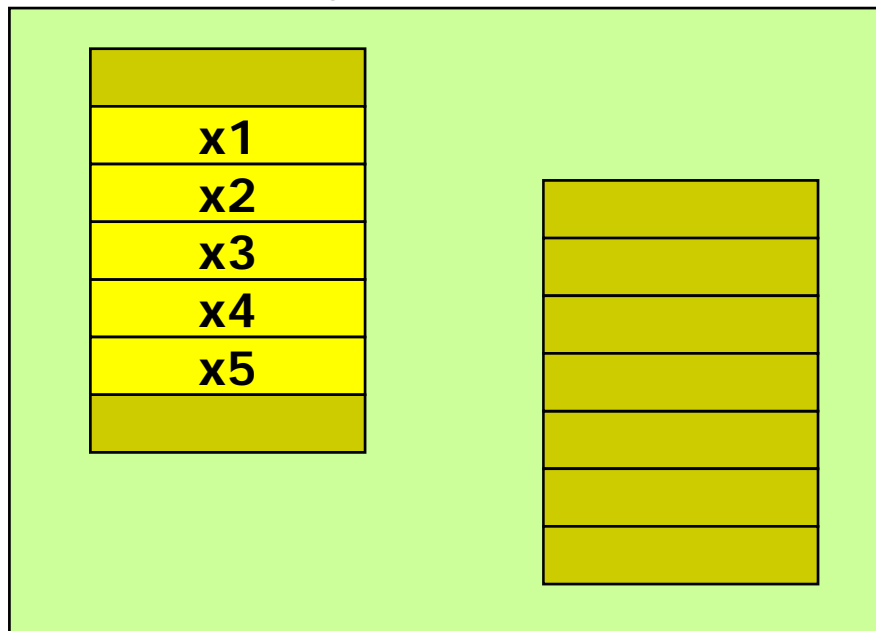
RRB

0

Software Pipelining Example in the IA-64

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loop:
(p16) ldl r32 = [r12], 1
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      br.ctop loop
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
x1							

General Registers (Logical)

Predicate Registers

1	0	0
16	17	18

LC

4

EC

3

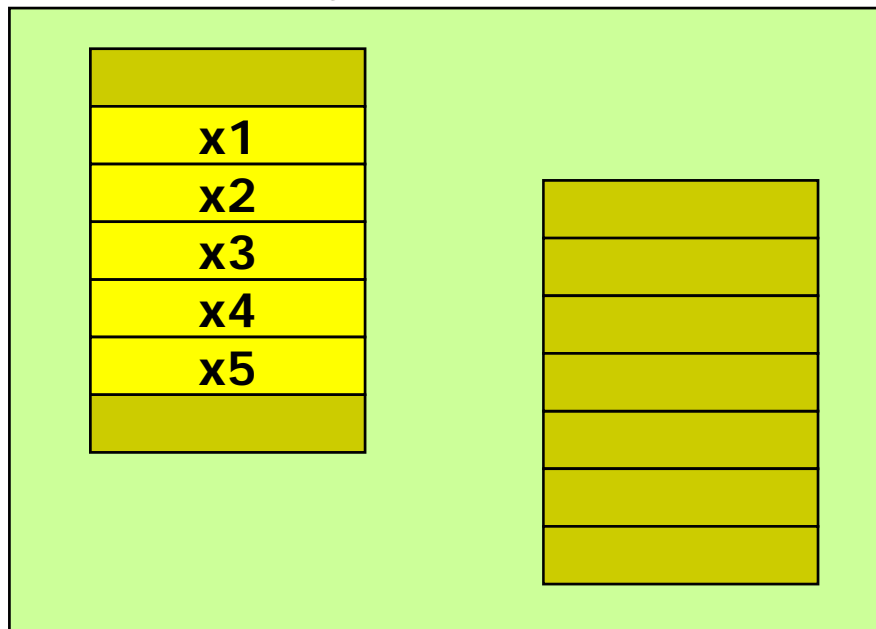
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loop:
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(p18)  stl [r13] = r35,1
      br.ctop loop
```

Memory



General Registers (Physical)

32 33 34 35 36 37 38 39

x1							
----	--	--	--	--	--	--	--

General Registers (Logical)

Predicate Registers



1	0	0
16	17	18

LC

4

EC

3

RRB

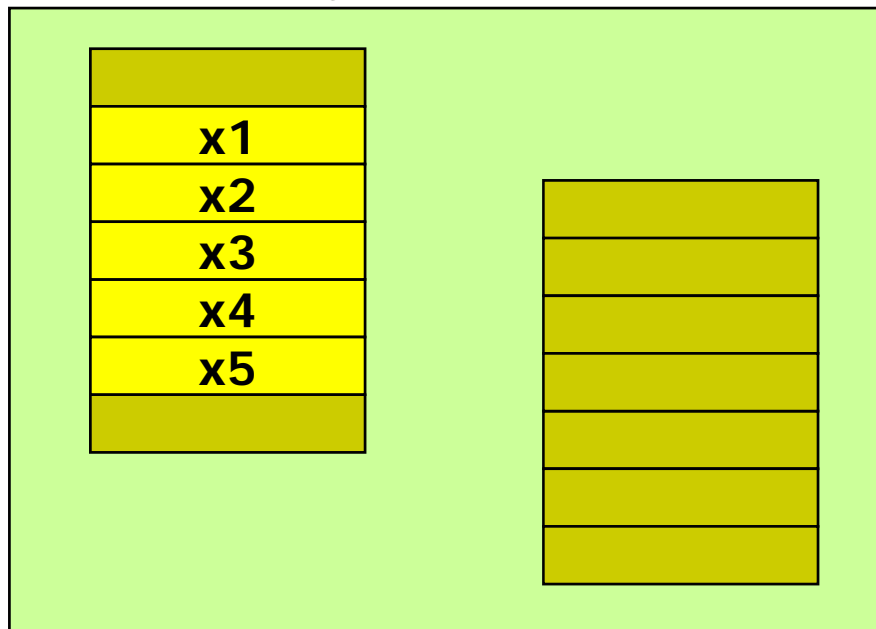
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Software Pipelining Example in the IA-64

```

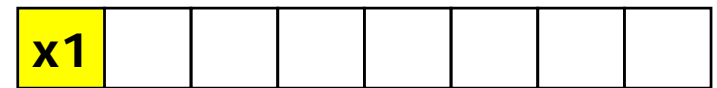
loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory



General Registers (Physical)

32 33 34 35 36 37 38 39



General Registers (Logical)

33 34 35 36 37 38 39 32

Predicate Registers



16 17 18

LC



EC



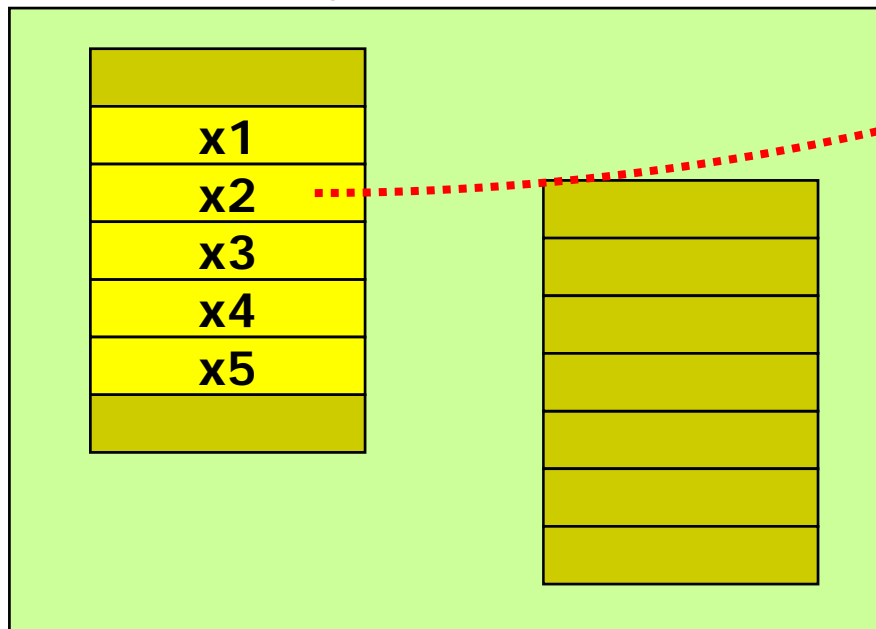
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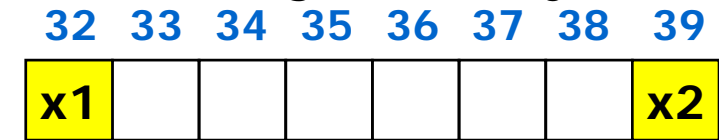
Software Pipelining Example in the IA-64

loop:
(p16) **ldl r32 = [r12], 1**
(p17) add r34 = 1, r33
(p18) stl [r13] = r35, 1
br.ctop loop

Memory

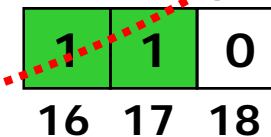


General Registers (Physical)



General Registers (Logical)

Predicate Registers



LC



EC



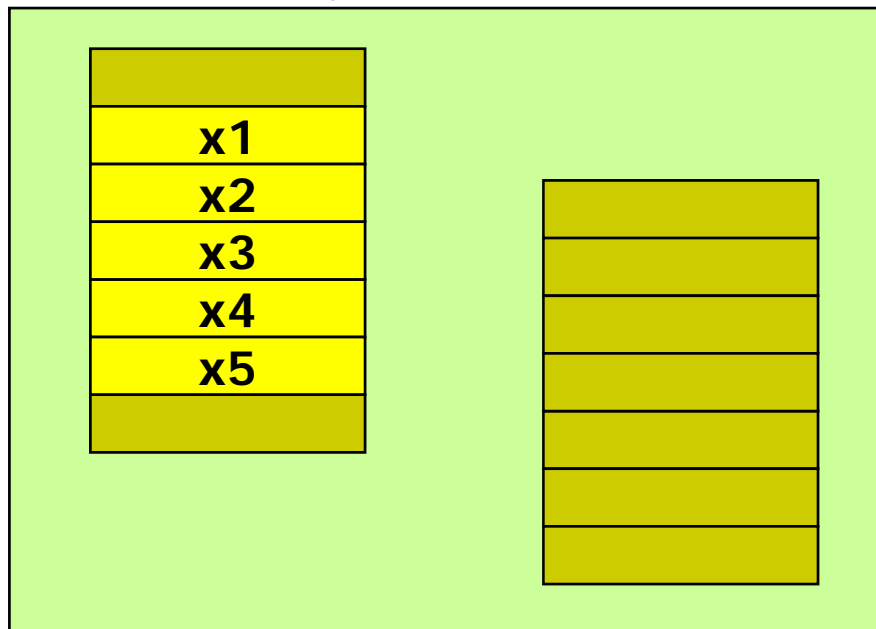
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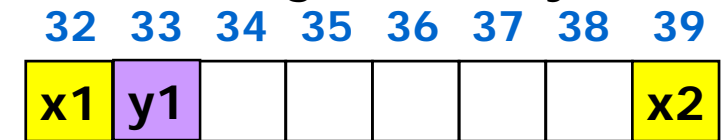
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      br.ctop loop
```

Memory

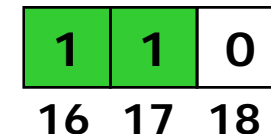


General Registers (Physical)



General Registers (Logical)

Predicate Registers



LC



EC



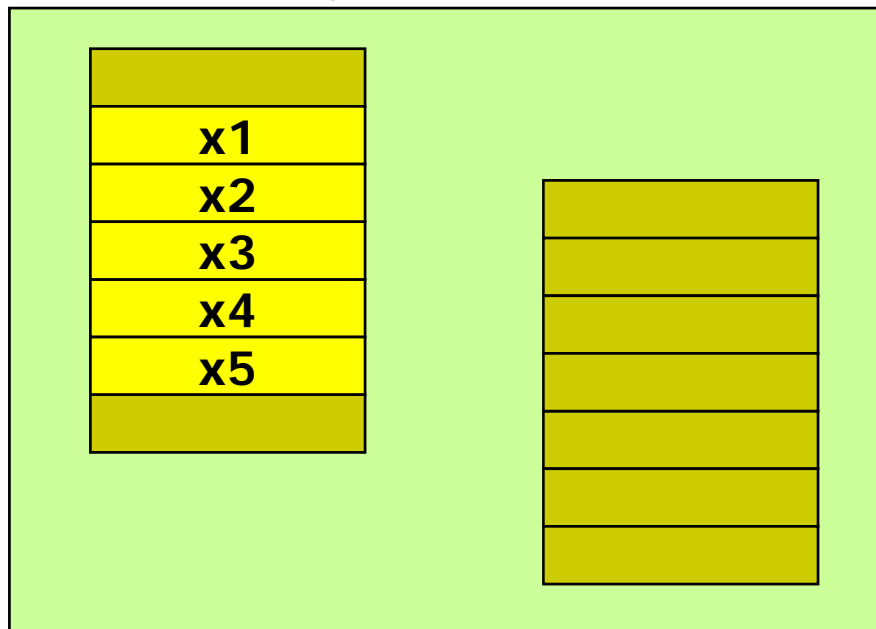
RRB



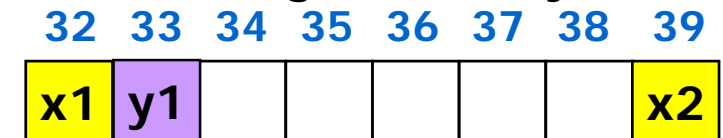
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```

Memory

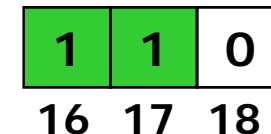


General Registers (Physical)



General Registers (Logical)

Predicate Registers



LC



EC



RRB

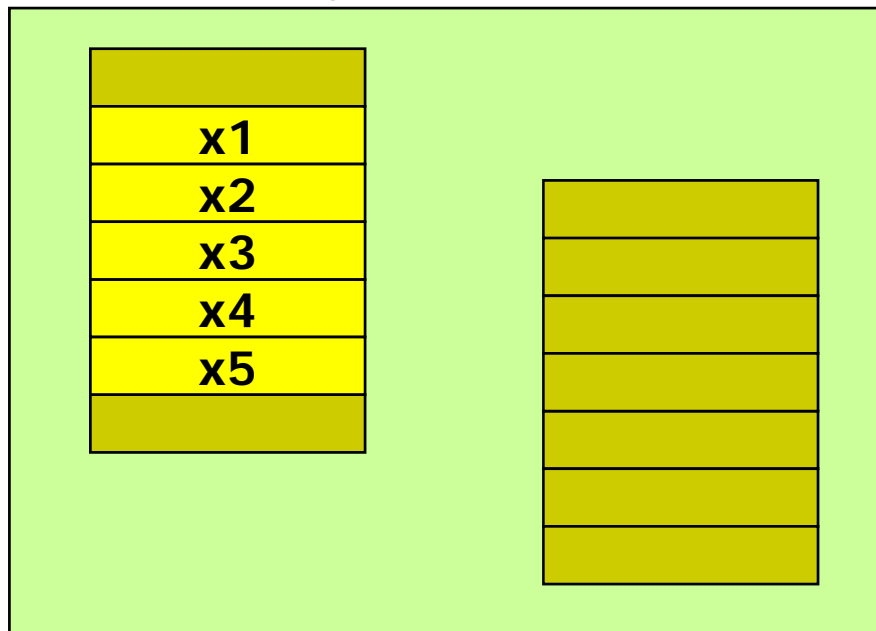


Software Pipelining Example in the IA-64

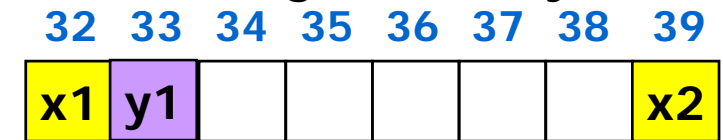
```

loop:
(p16)  ldl r32    = [r12], 1
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      br.ctop loop
    
```

Memory

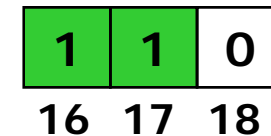


General Registers (Physical)



General Registers (Logical)

Predicate Registers



LC



EC



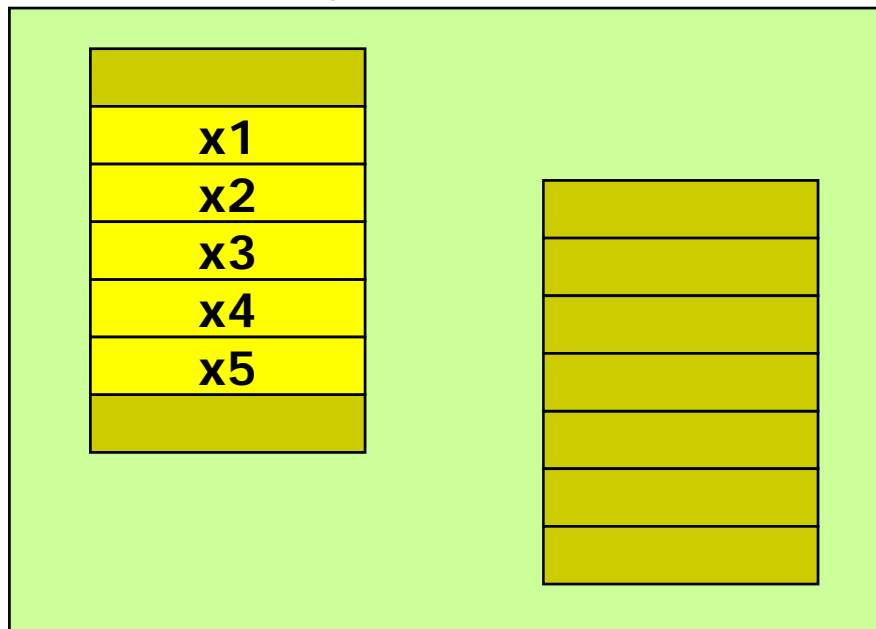
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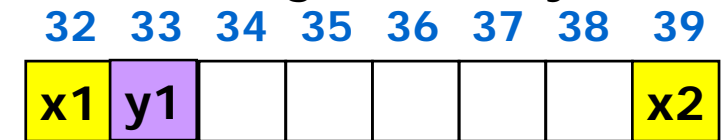
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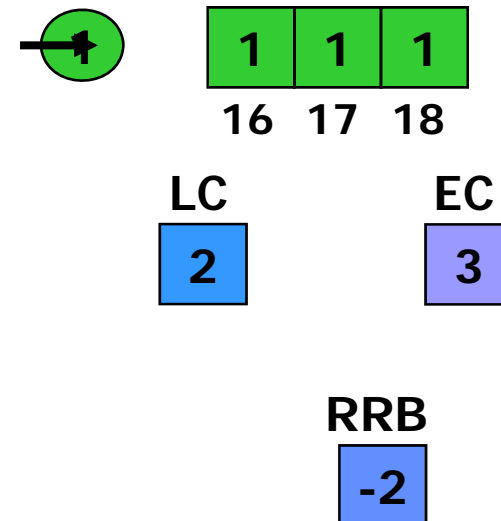


General Registers (Physical)



General Registers (Logical)

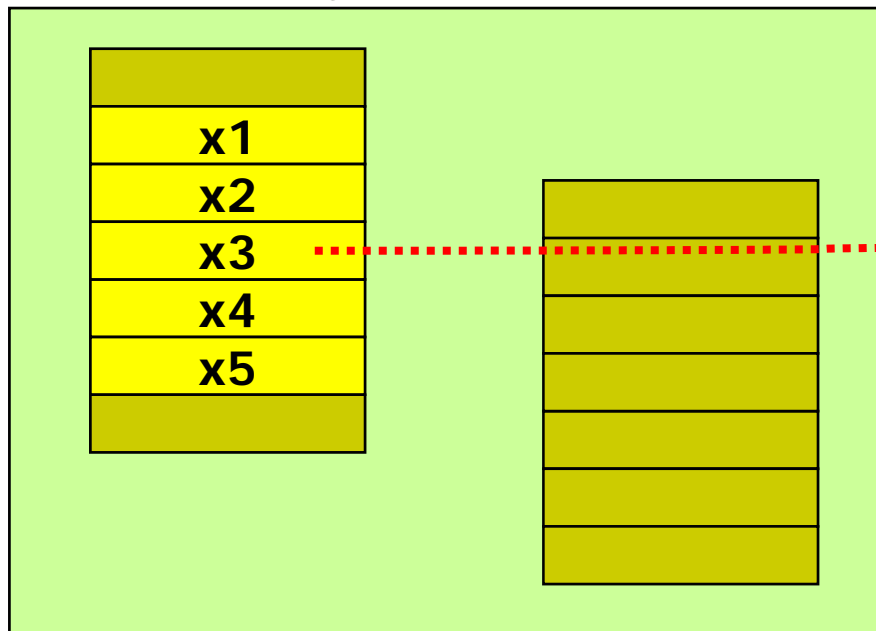
Predicate Registers



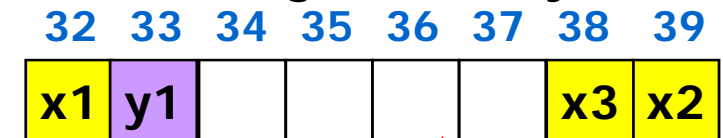
Software Pipelining Example in the IA-64

loop:
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(p17) add r34 = 1, r33
(p18) stl [r13] = r35, 1
br.ctop loop

Memory



General Registers (Physical)



General Registers (Logical)

Predicate Registers



16 17 18

LC



EC



RRB



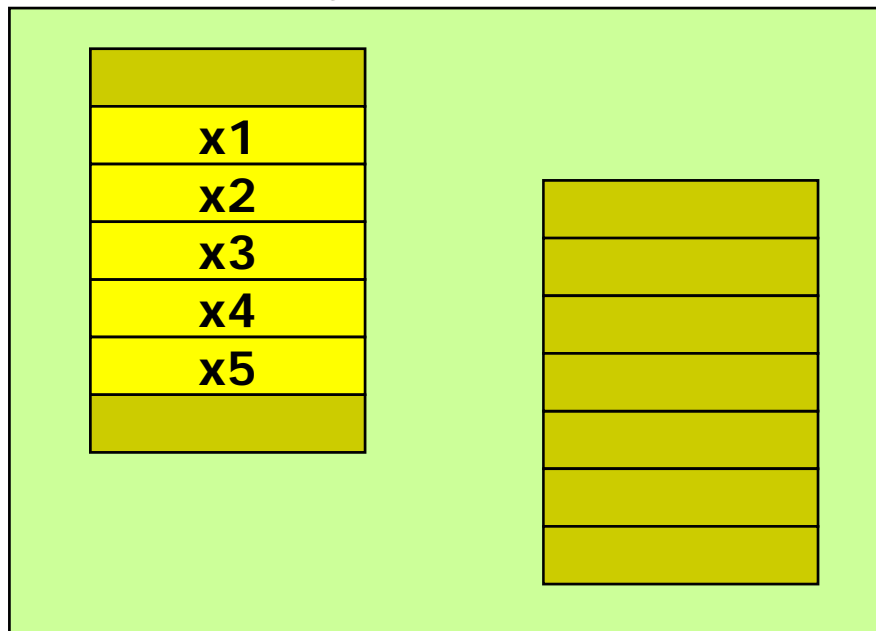
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(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```



Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1					x3	x2

General Registers (Logical)

Predicate Registers

1	1	1
---	---	---

16 17 18

LC

2

EC

3

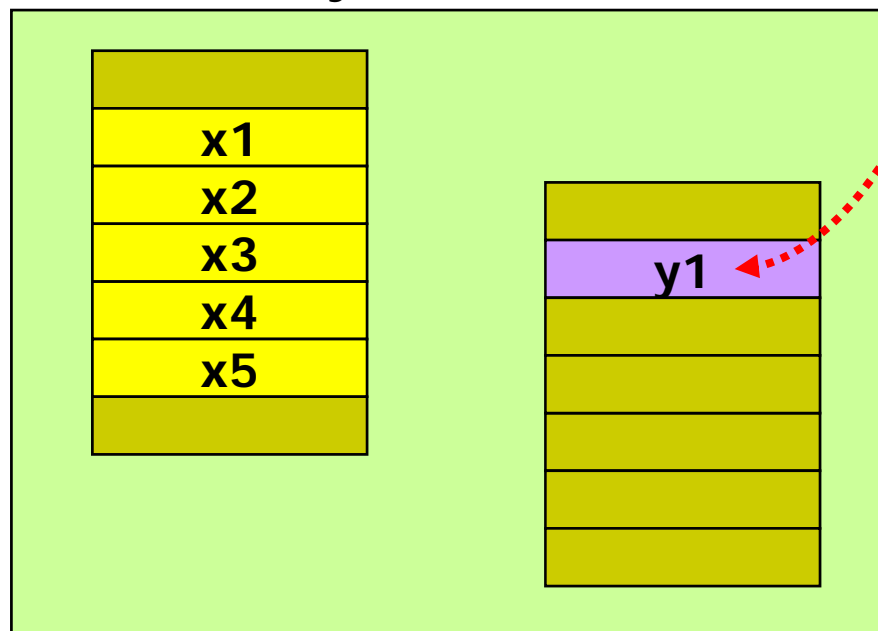
RRB

-2

Software Pipelining Example in the IA-64

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      br.ctop loop
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1					x3	x2

General Registers (Logical)

Predicate Registers

1	1	1
---	---	---

16 17 18

LC

2

EC

3

RRB

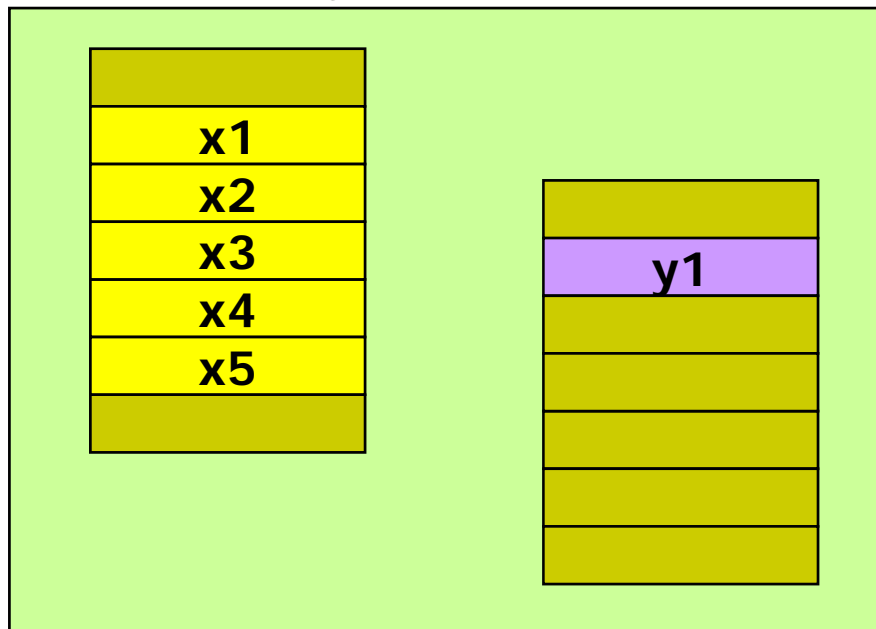
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Software Pipelining Example in the IA-64

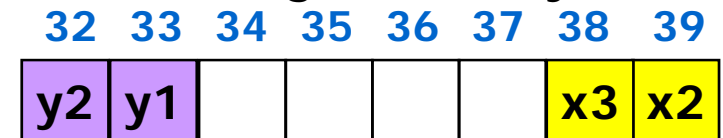
```

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Memory

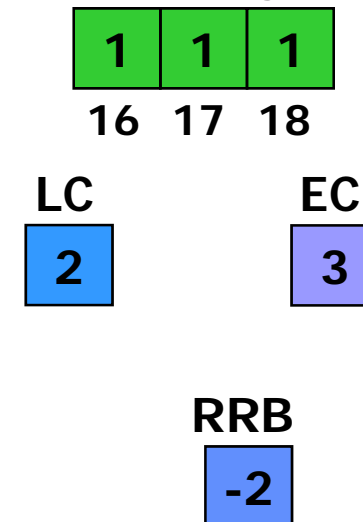


General Registers (Physical)



General Registers (Logical)

Predicate Registers

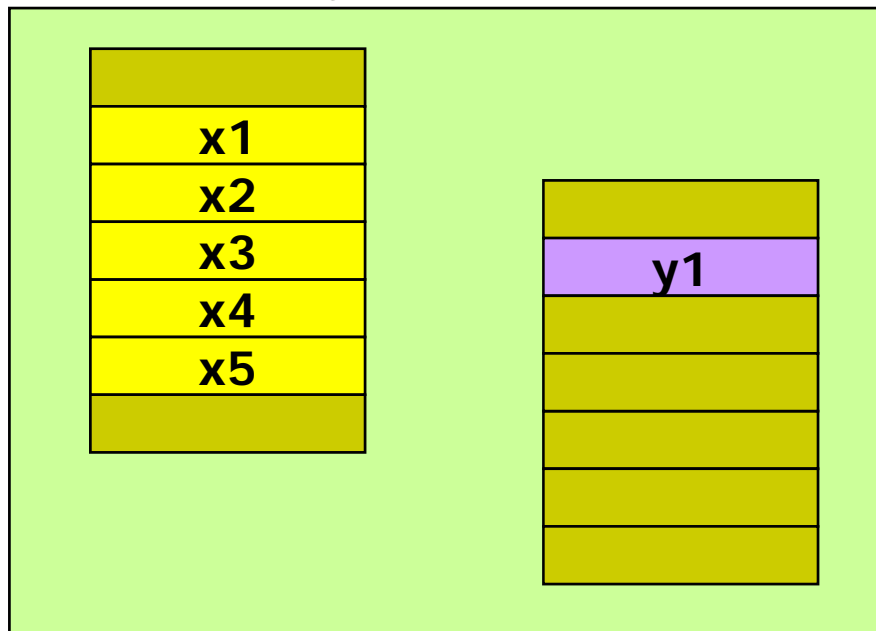


Software Pipelining Example in the IA-64

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Memory

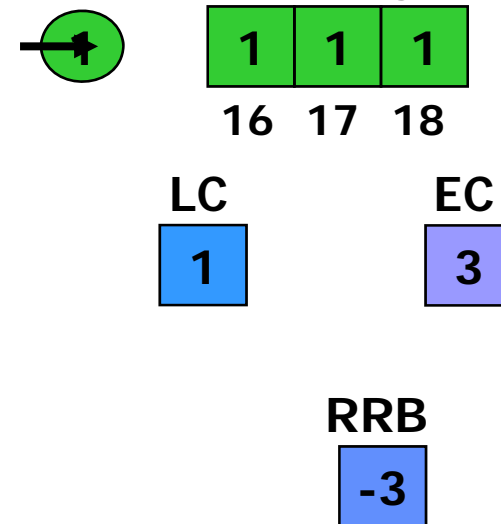


General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1					x3	x2

General Registers (Logical)

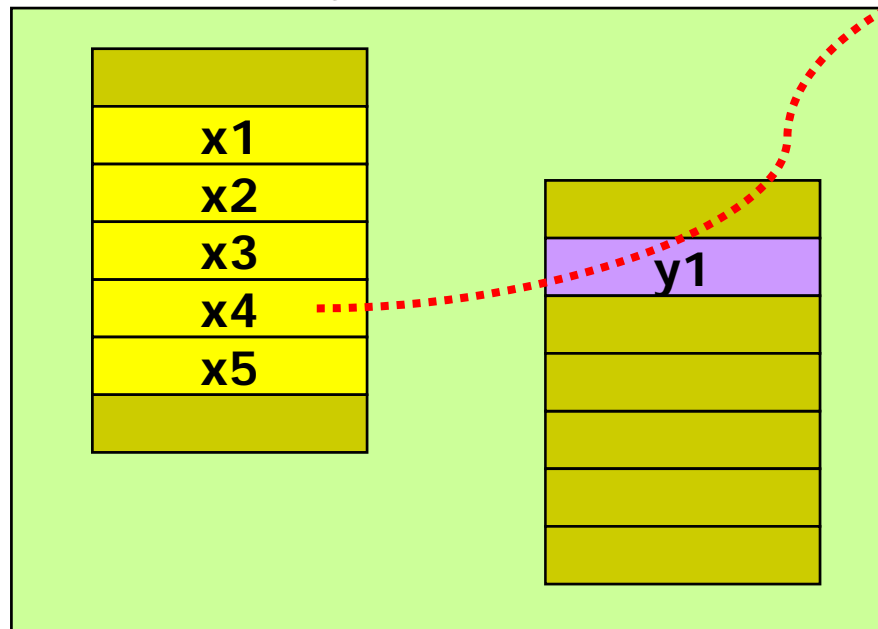
Predicate Registers



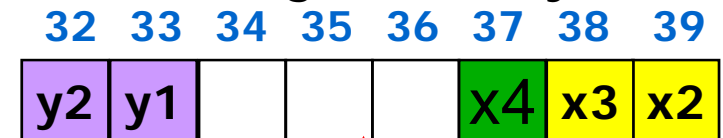
Software Pipelining Example in the IA-64

loop:
(p16) **ldl r32 = [r12], 1**
(p17) add r34 = 1, r33
(p18) stl [r13] = r35, 1
br.ctop loop

Memory

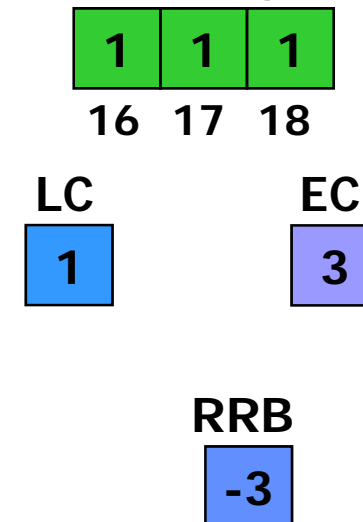


General Registers (Physical)



General Registers (Logical)

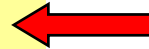
Predicate Registers



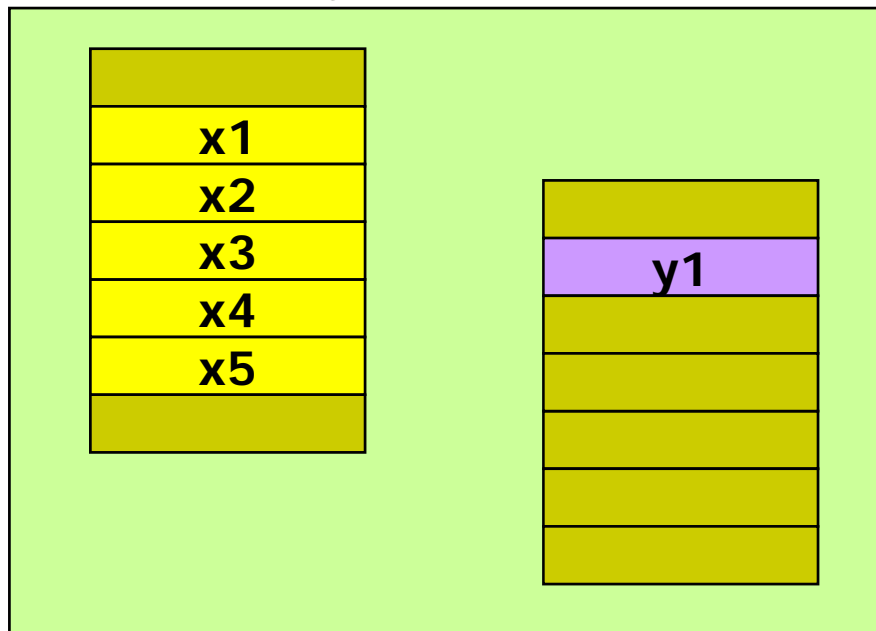
Software Pipelining Example in the IA-64

```

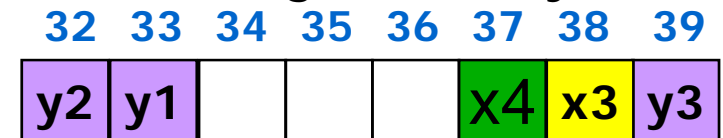
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
    
```



Memory

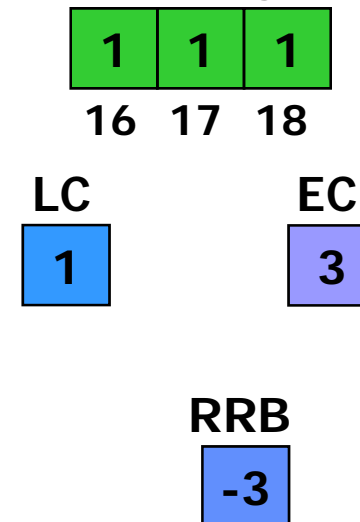


General Registers (Physical)



General Registers (Logical)

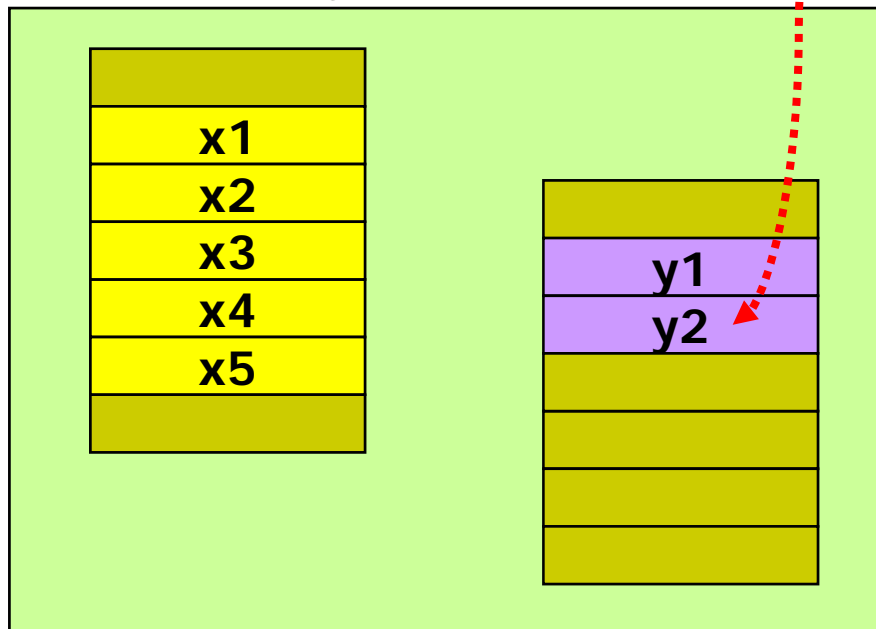
Predicate Registers



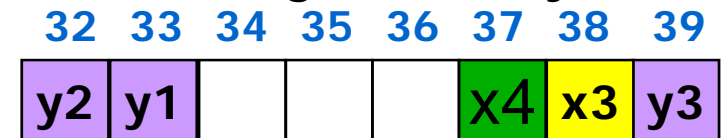
Software Pipelining Example in the IA-64

```
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
```

Memory

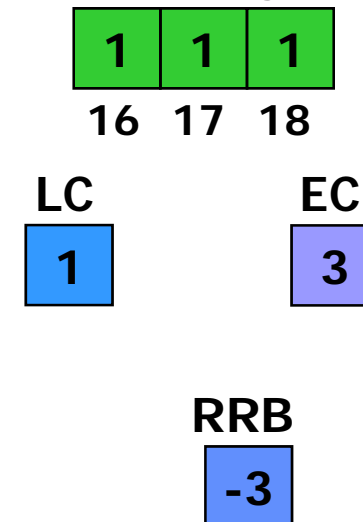


General Registers (Physical)



General Registers (Logical)

Predicate Registers

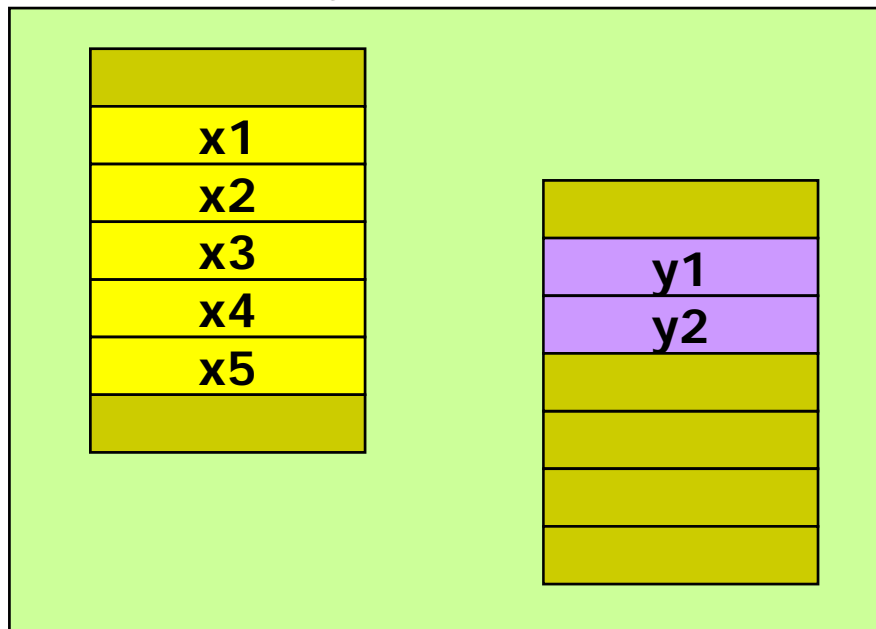


Software Pipelining Example in the IA-64

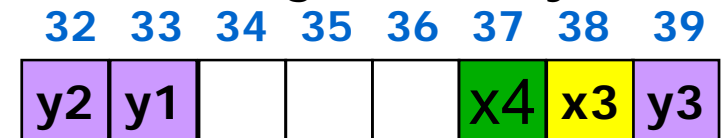
```

loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory

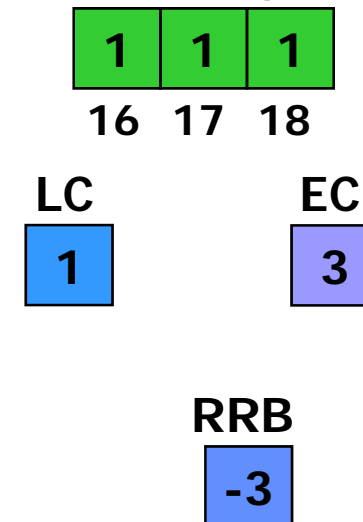


General Registers (Physical)



General Registers (Logical)

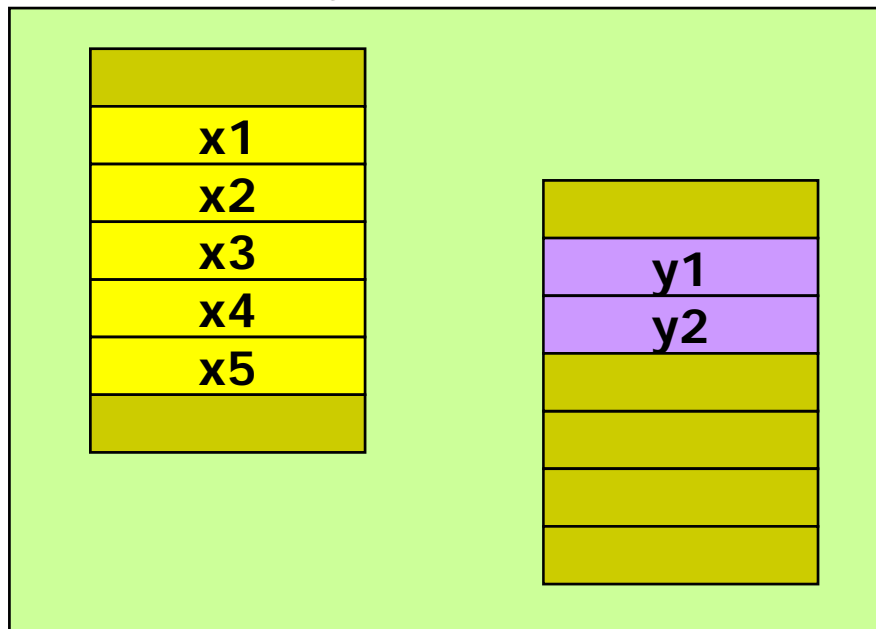
Predicate Registers



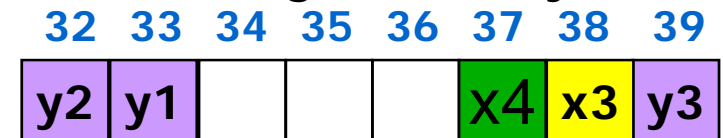
Software Pipelining Example in the IA-64

```
loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
```

Memory

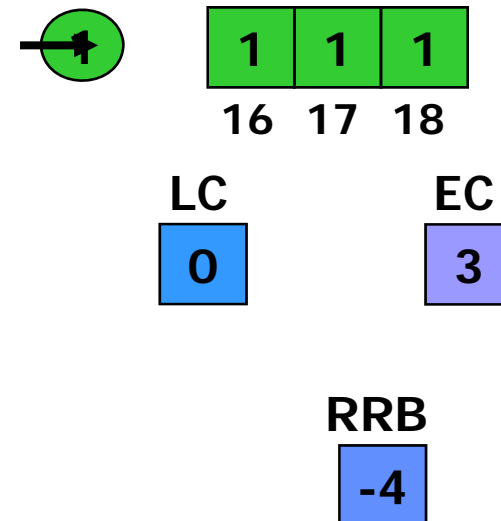


General Registers (Physical)



General Registers (Logical)

Predicate Registers

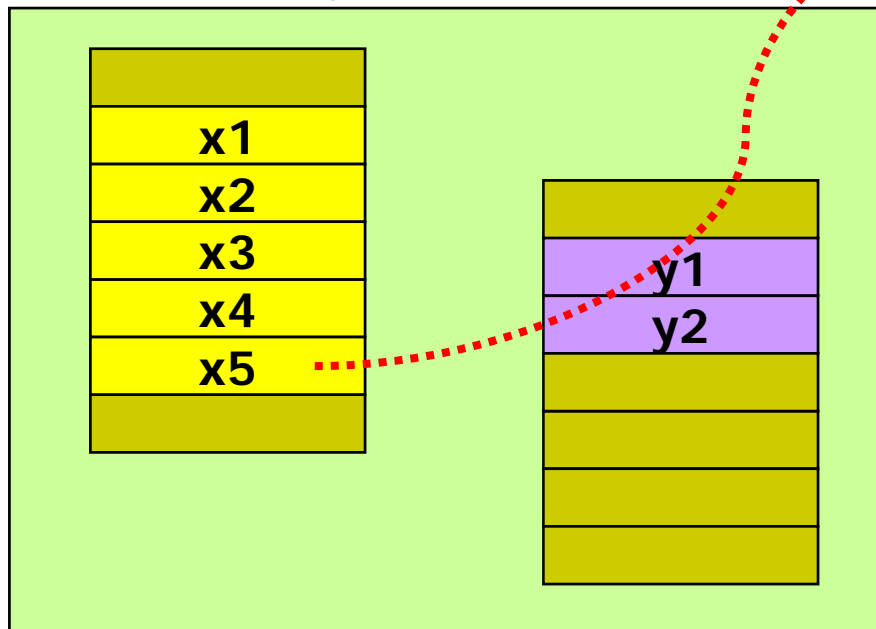


Software Pipelining Example in the IA-64

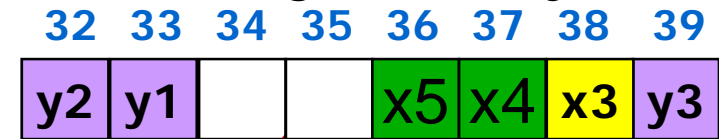
```

loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
    
```

Memory



General Registers (Physical)



General Registers (Logical)

Predicate Registers



16 17 18

LC



EC



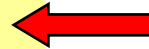
RRB



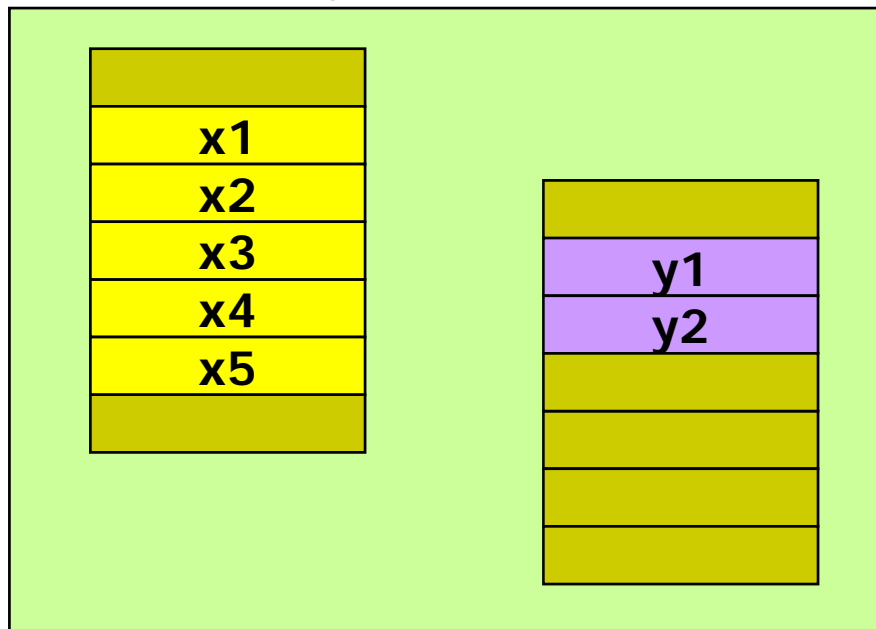
Software Pipelining Example in the IA-64

```

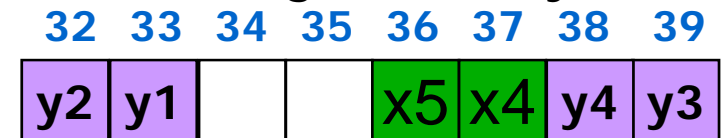
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
    
```



Memory

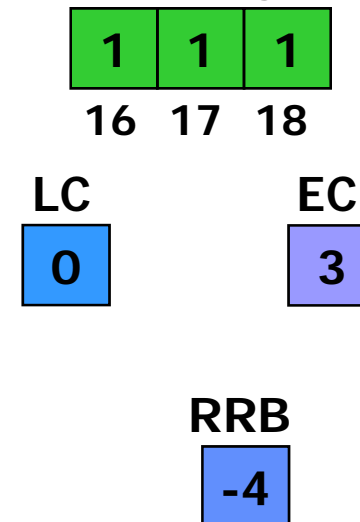


General Registers (Physical)



General Registers (Logical)

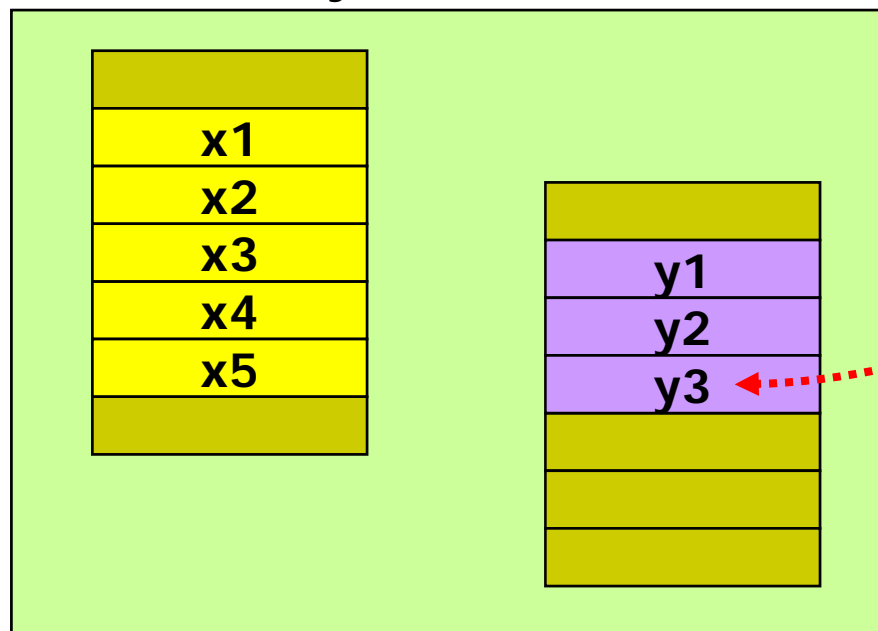
Predicate Registers



Software Pipelining Example in the IA-64

```
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	x4	y4	y3

General Registers (Logical)

Predicate Registers

1	1	1
---	---	---

16 17 18

LC

0

EC

3

RRB

-4

Hidden slides...

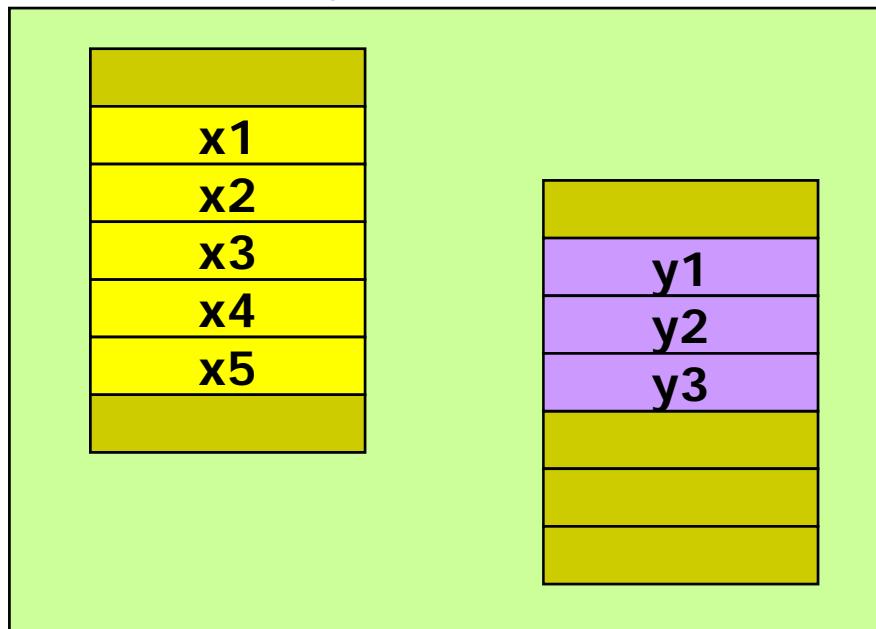
- ▀ Some hidden slides are not in handout
- ▀ We continue with start of pipeline drain phase

Software Pipelining Example in the IA-64

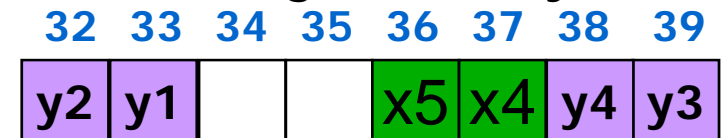
```

loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory

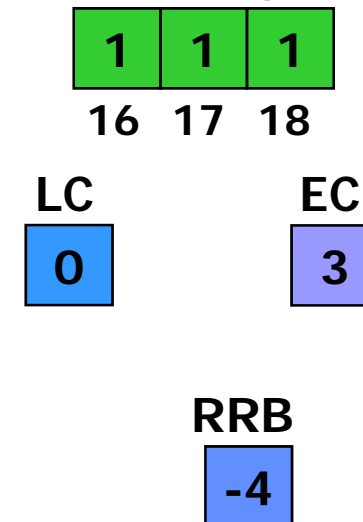


General Registers (Physical)



General Registers (Logical)

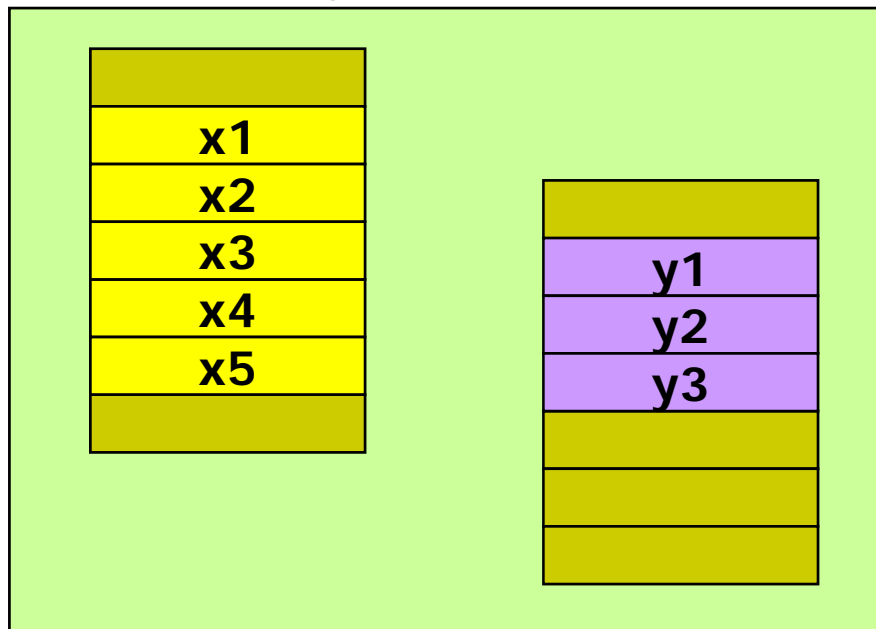
Predicate Registers



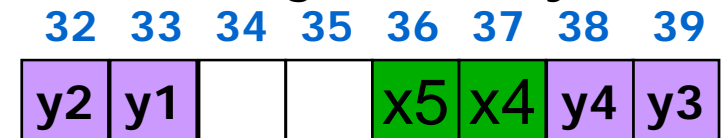
Software Pipelining Example in the IA-64

```
loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
```

Memory

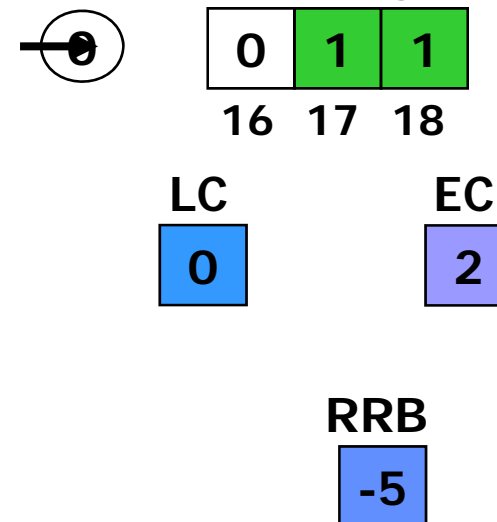


General Registers (Physical)



General Registers (Logical)

Predicate Registers

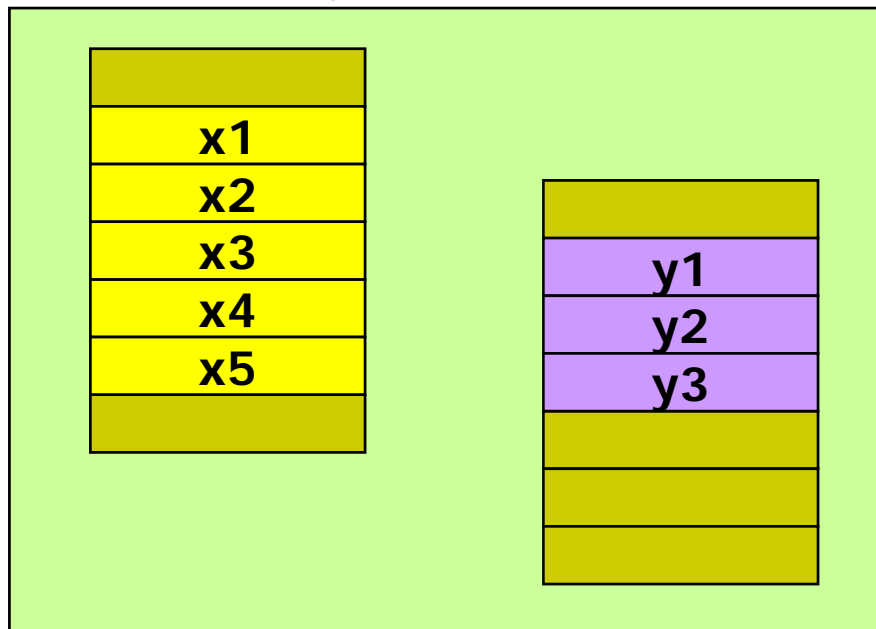


Software Pipelining Example in the IA-64

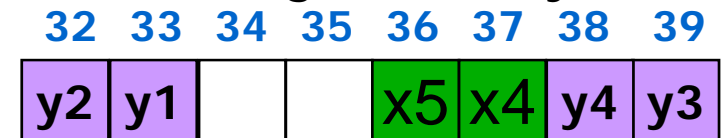
```

loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory

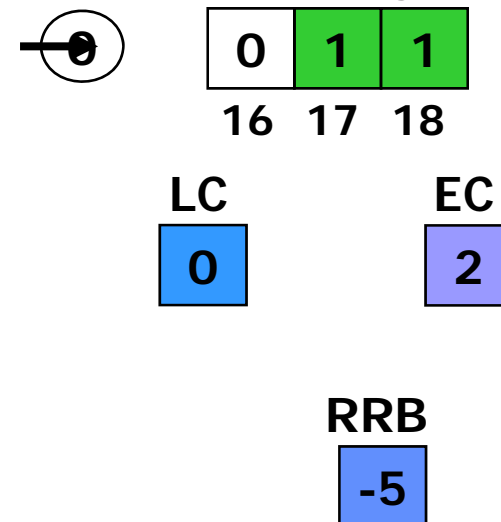


General Registers (Physical)



General Registers (Logical)

Predicate Registers

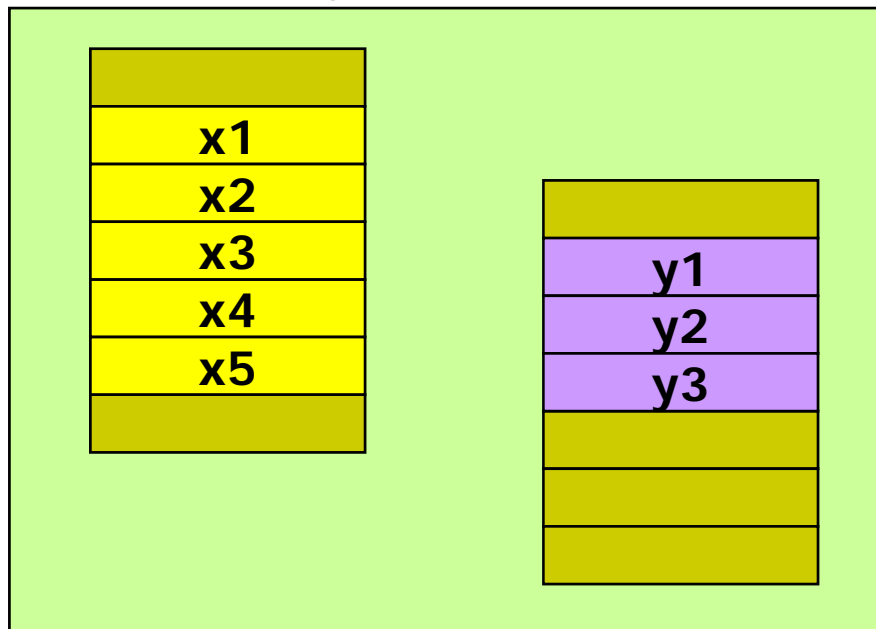


Software Pipelining Example in the IA-64

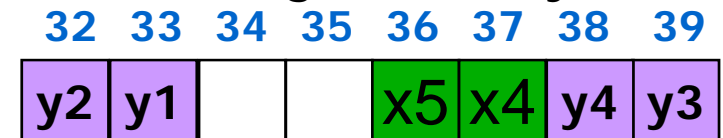
```
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
```



Memory

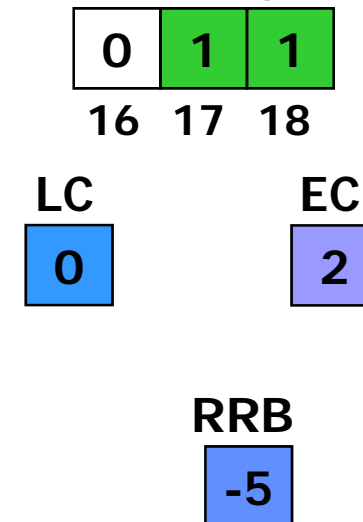


General Registers (Physical)



General Registers (Logical)

Predicate Registers



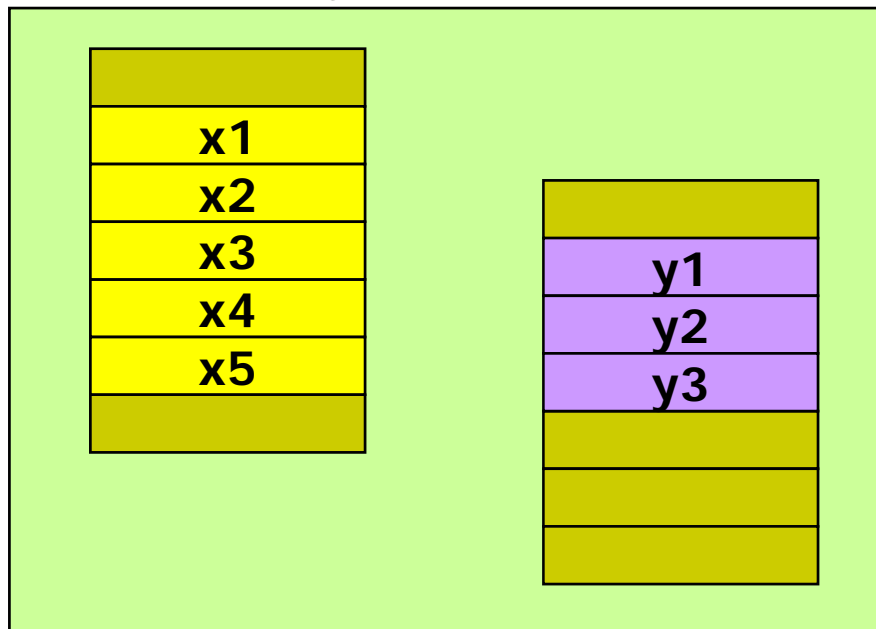
Software Pipelining Example in the IA-64

```

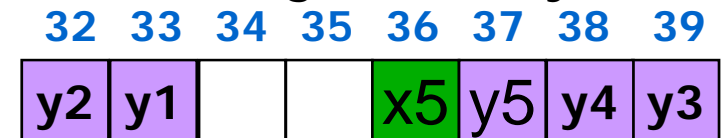
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
    
```



Memory

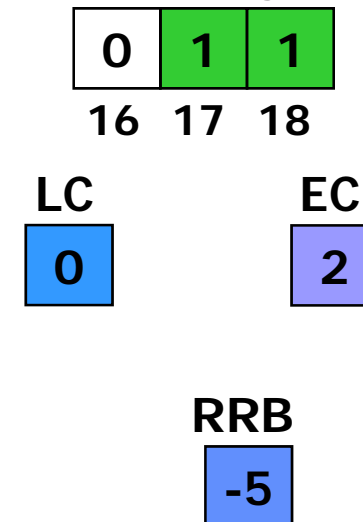


General Registers (Physical)



General Registers (Logical)

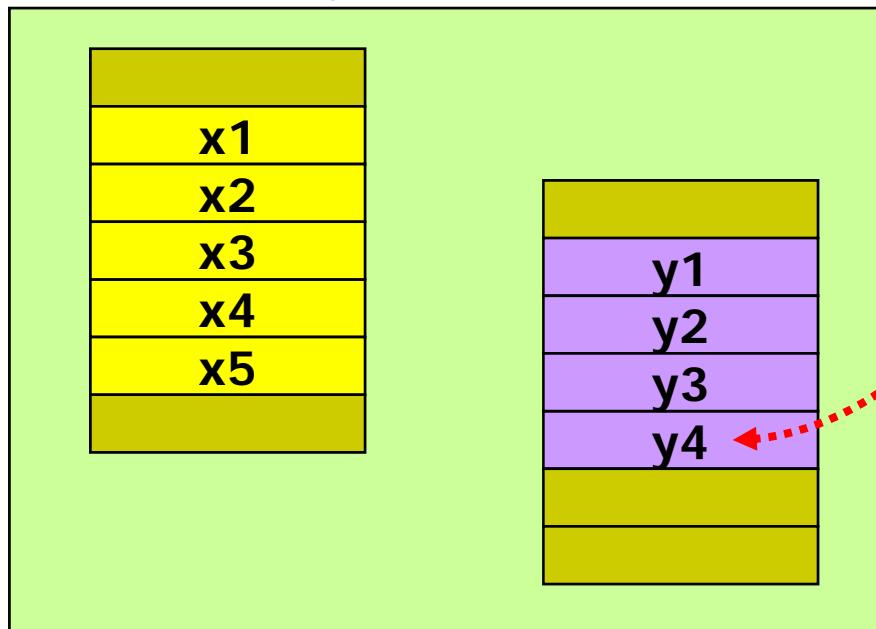
Predicate Registers



Software Pipelining Example in the IA-64

```
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	y5	y4	y3

General Registers (Logical)

Predicate Registers

0	1	1
16	17	18

LC

0

EC

2

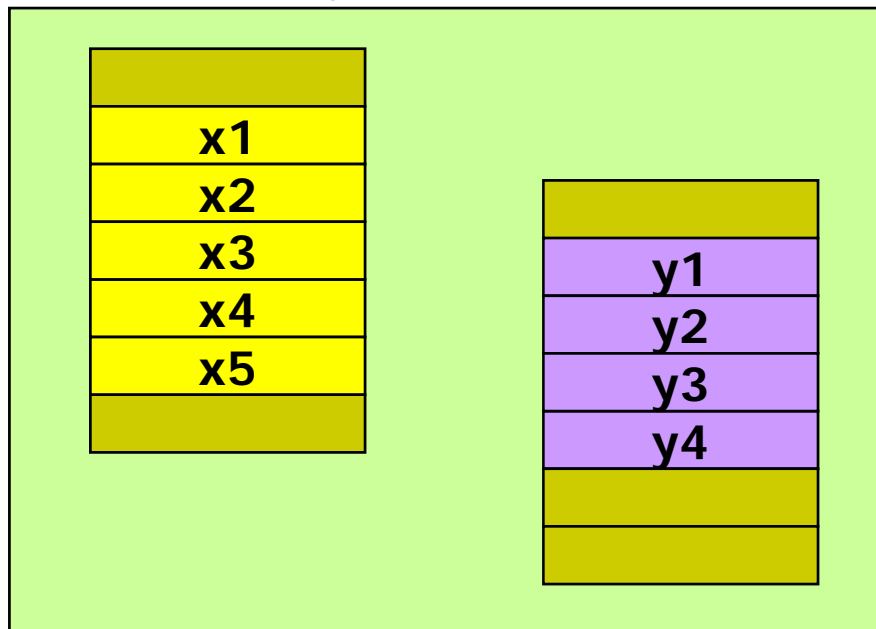
RRB

-5

Software Pipelining Example in the IA-64

```
loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	y5	y4	y3

General Registers (Logical)

Predicate Registers

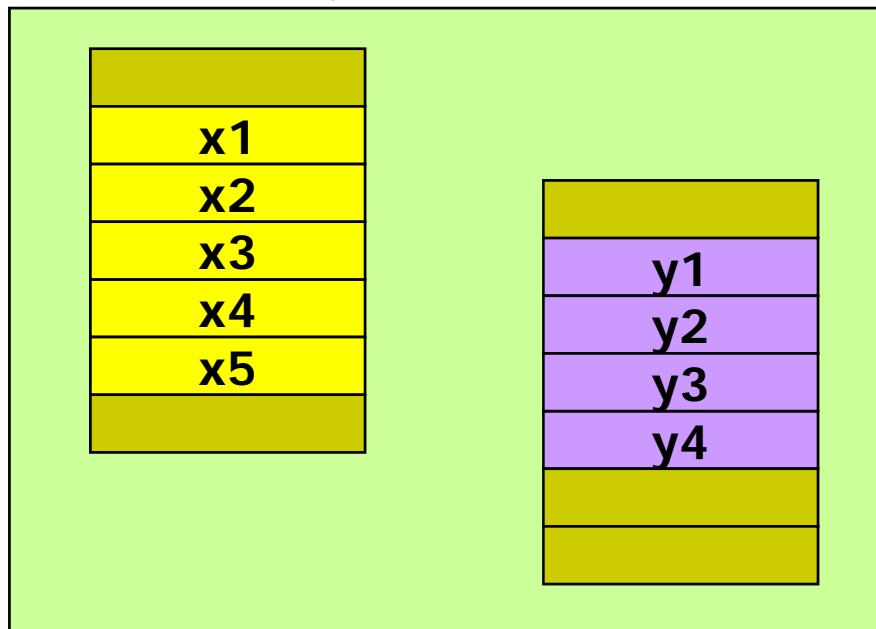
0	1	1
16	17	18
LC		EC
0		2
		RRB
		-5

Software Pipelining Example in the IA-64

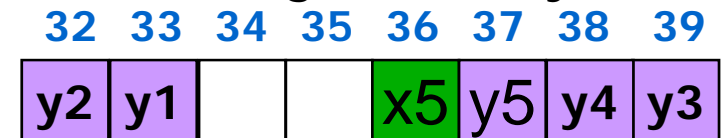
```

loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory

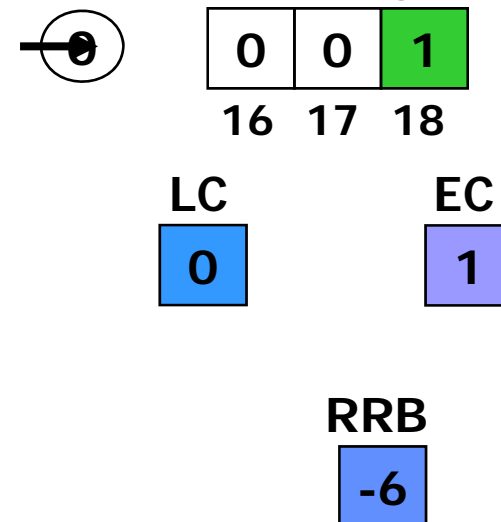


General Registers (Physical)



General Registers (Logical)

Predicate Registers



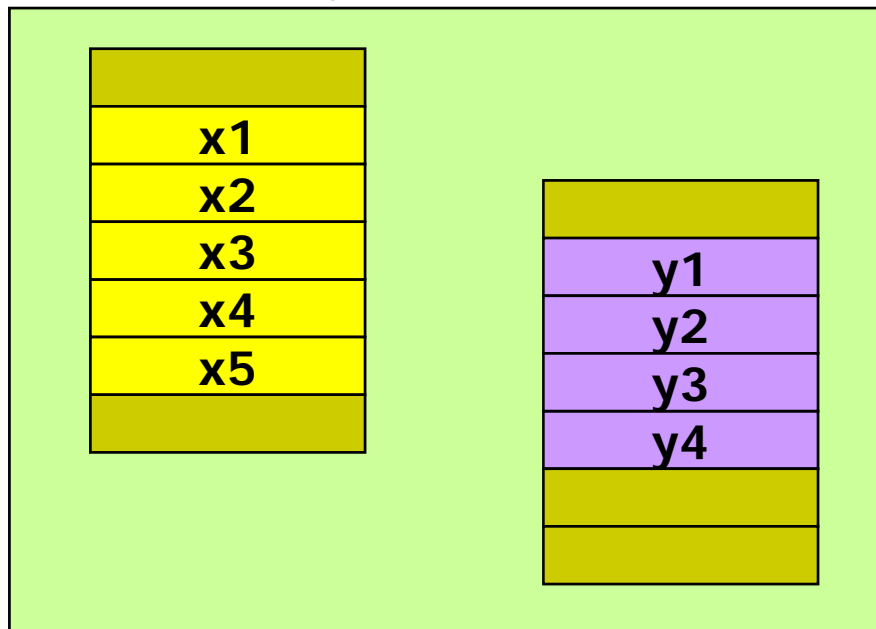
Software Pipelining Example in the IA-64

```

loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35, 1
      br.ctop loop
    
```



Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	y5	y4	y3

General Registers (Logical)

Predicate Registers

0	0	1
16	17	18

LC

0

EC

1

RRB

-6

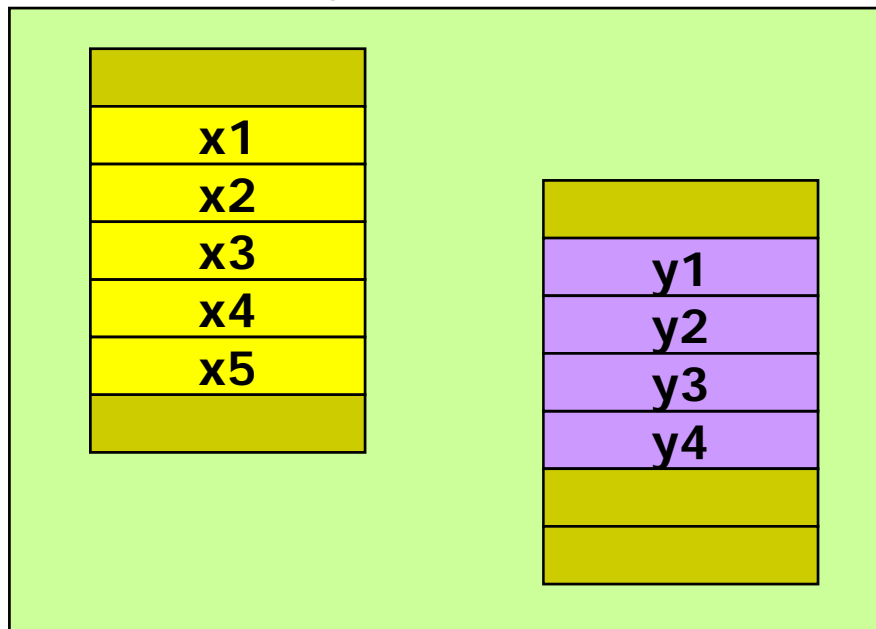
Software Pipelining Example in the IA-64

```

loop:
(p16)  ldl r32  = [r12], 1
(p17)  add r34  = 1, r33
(p18)  stl [r13] = r35,1
      br.ctop loop
    
```



Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	y5	y4	y3

General Registers (Logical)

Predicate Registers

0	0	1
---	---	---

16 17 18

LC

0

EC

1

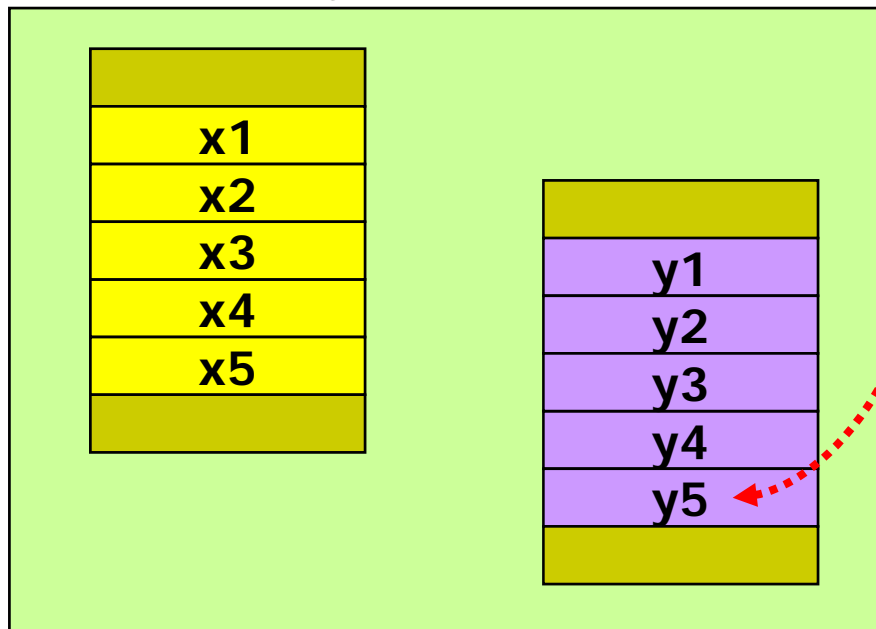
RRB

-6

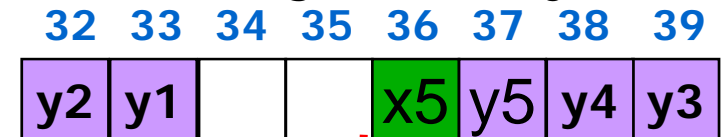
Software Pipelining Example in the IA-64

```
loop:  
(p16) ldl r32    = [r12], 1  
(p17) add r34    = 1, r33  
(p18) stl [r13]  = r35, 1  
      br.ctop loop
```

Memory

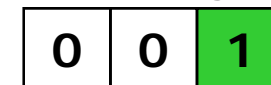


General Registers (Physical)



General Registers (Logical)

Predicate Registers



16 17 18

LC



EC



RRB

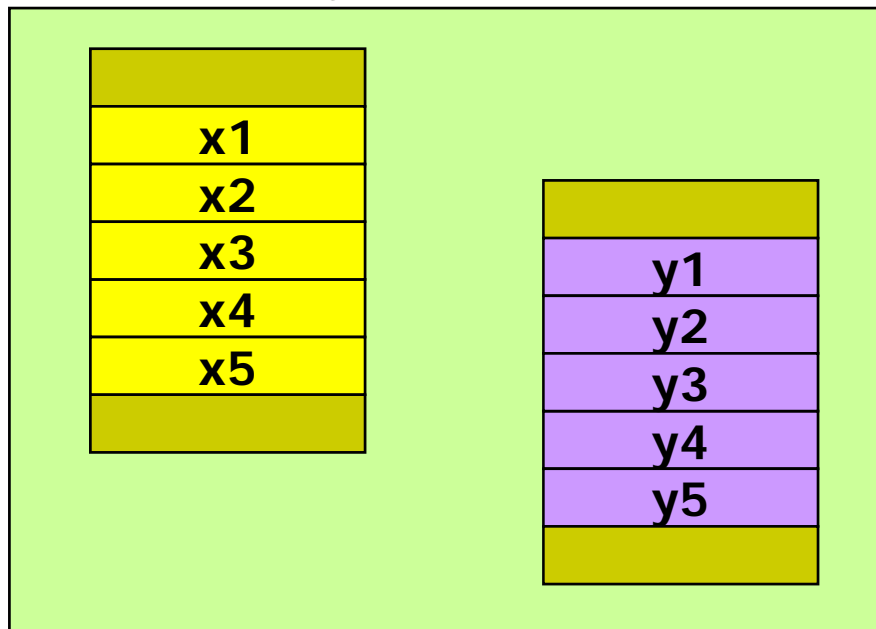


Software Pipelining Example in the IA-64

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loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	y5	y4	y3

General Registers (Logical)

Predicate Registers

0	0	1
---	---	---

16 17 18

LC

0

EC

1

RRB

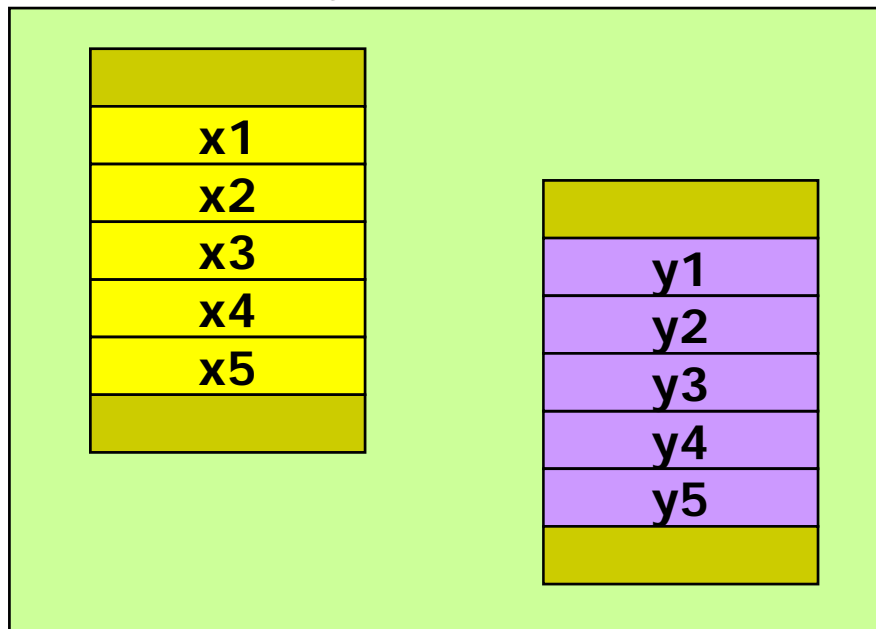
-6

Software Pipelining Example in the IA-64

```

loop:
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(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory



General Registers (Physical)

32	33	34	35	36	37	38	39
y2	y1			x5	y5	y4	y3

General Registers (Logical)

Predicate Registers

0	0	1
16	17	18

LC

0

EC

1

RRB

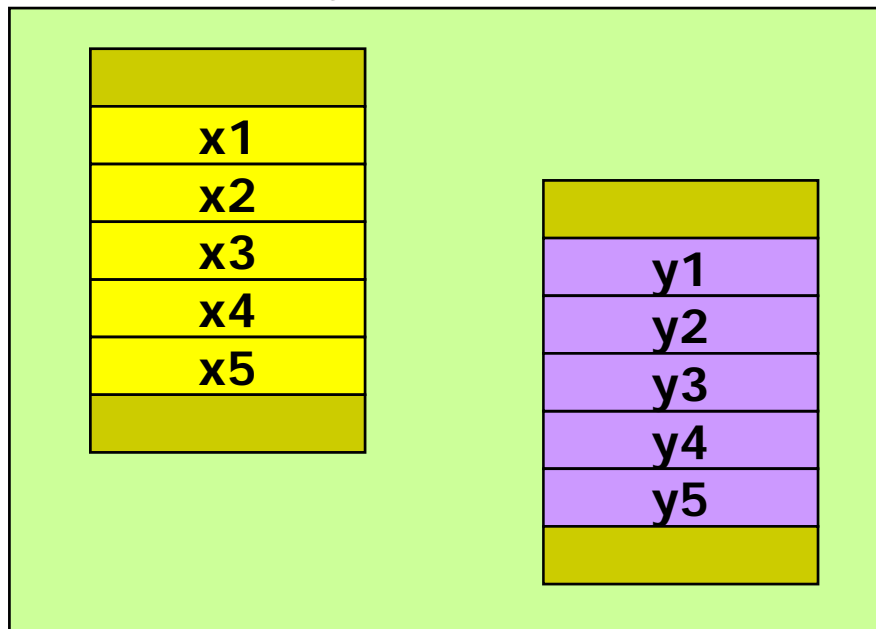
-6

Software Pipelining Example in the IA-64

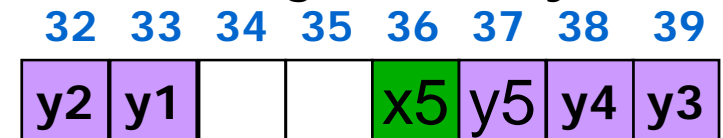
```

loop:
(p16)  ldl r32    = [r12], 1
(p17)  add r34    = 1, r33
(p18)  stl [r13]  = r35,1
      br.ctop loop
    
```

Memory

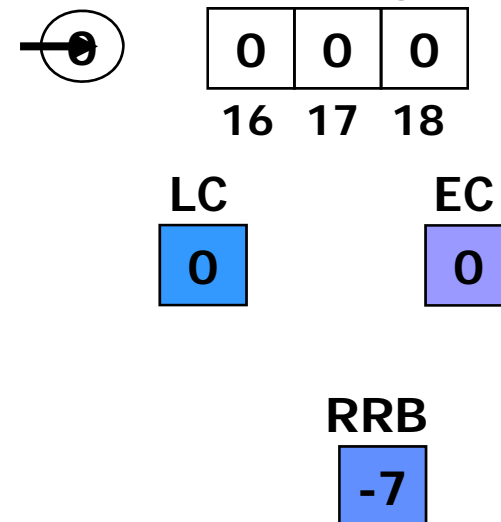


General Registers (Physical)



General Registers (Logical)

Predicate Registers



Caches

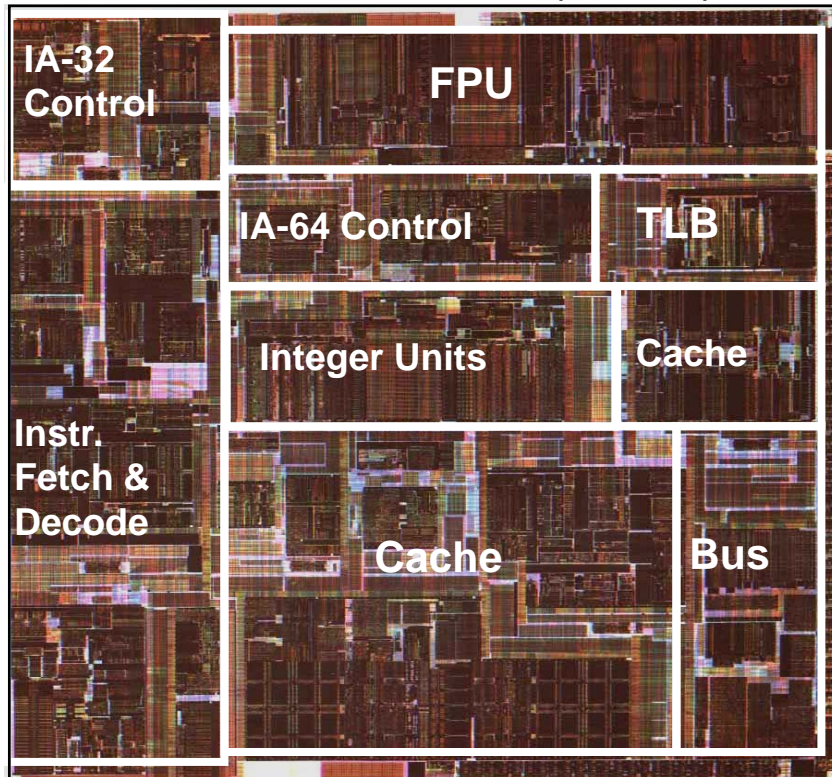
- 32KB L1 (2 cycle)
- 96KB L2 (7 cycle)
- 2 or 4 MB L3 (off chip)

133 MHz 64-bit bus

SpecFP: 711

SpecInt: 404

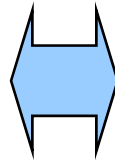
36-bit addresses (64GB)



Core Processor Die

Itanium™ Processor Silicon

(Copyright: Intel at Hotchips '00)



4 x 1MB L3 cache

Itanium™ Machine Characteristics

(Copyright: Intel at Hotchips '00)

Frequency	800 MHz
Transistor Count	25.4M CPU; 295M L3
Process	0.18u CMOS, 6 metal layer
Package	Organic Land Grid Array
Machine Width	6 insts/clock (4 ALU/MM, 2 Ld/St, 2 FP, 3 Br)
Registers	14 ported 128 GR & 128 FR; 64 Predicates
Speculation	32 entry ALAT, Exception Deferral
Branch Prediction	Multilevel 4-stage Prediction Hierarchy
FP Compute Bandwidth	3.2 GFlops (DP/EP); 6.4 GFlops (SP)
Memory -> FP Bandwidth	4 DP (8 SP) operands/clock
Virtual Memory Support	64 entry ITLB, 32/96 2-level DTLB, VHPT
L2/L1 Cache	Dual ported 96K Unified & 16KD; 16KI
L2/L1 Latency	6 / 2 clocks
L3 Cache	4MB, 4-way s.a., BW of 12.8 GB/sec;
System Bus	2.1 GB/sec; 4-way Glueless MP Scalable to large (512+ proc) systems

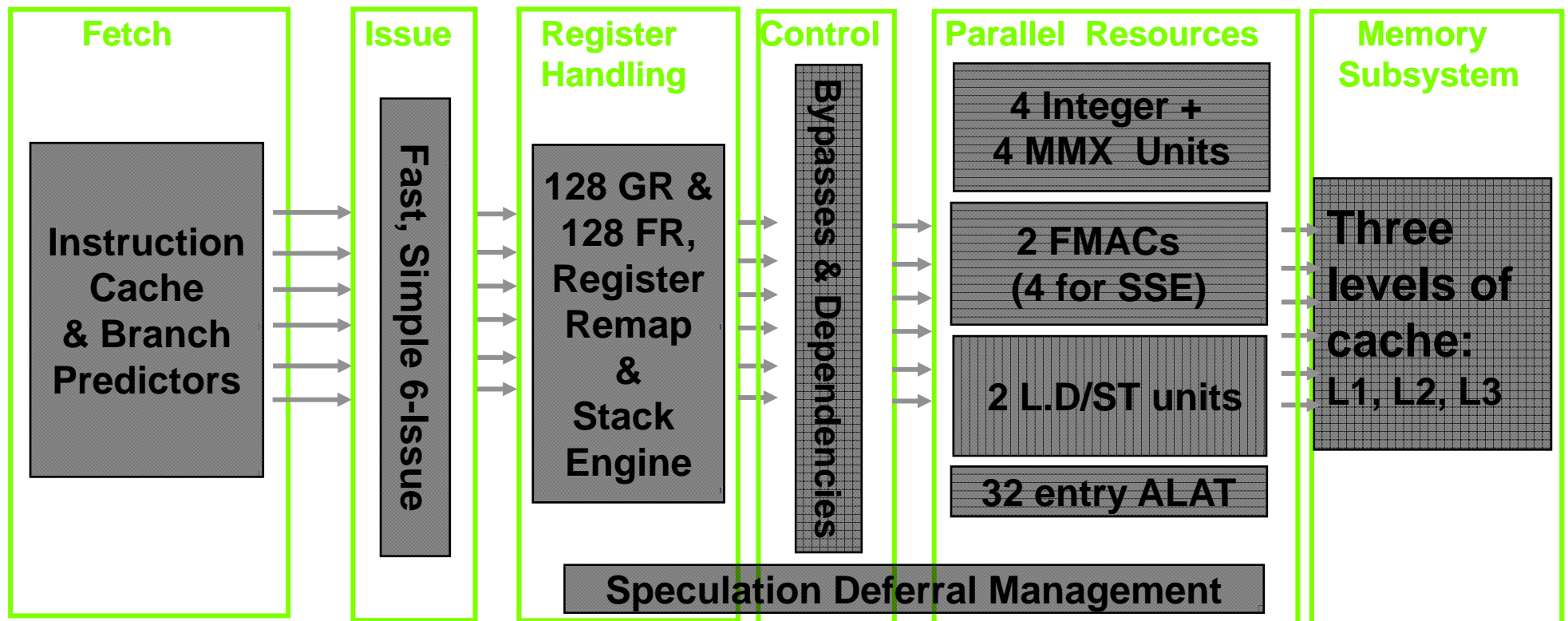
Itanium™ EPIC Design Maximizes SW-HW Synergy

(Copyright: Intel at Hotchips '00)

Architecture Features programmed by compiler:

Branch Hints	Explicit Parallelism	Register Stack & Rotation	Predication	Data & Control Speculation	Memory Hints
---------------------	-----------------------------	--------------------------------------	--------------------	---------------------------------------	---------------------

Micro-architecture Features in hardware:



10 Stage In-Order Core Pipeline

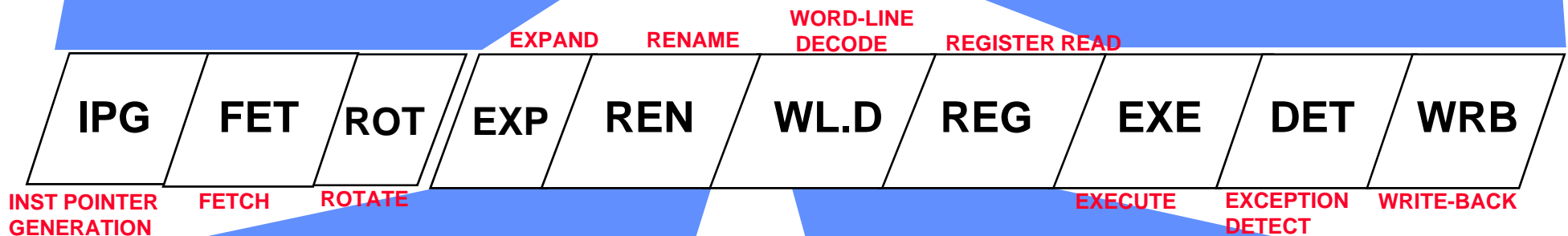
(Copyright: Intel at Hotchips '00)

Front End

- Pre-fetch/Fetch of up to 6 instructions/cycle
- Hierarchy of branch predictors
- Decoupling buffer

Execution

- 4 single cycle ALUs, 2 Id/str
- Advanced load control
- Predicate delivery & branch
- Nat/Exception/Retirement



Instruction Delivery

- Dispersal of up to 6 instructions on 9 ports
- Reg. remapping
- Reg. stack engine

Operand Delivery

- Reg read + Bypasses
- Register scoreboard
- Predicated dependencies

Itanium processor 10-stage pipeline

- Front-end (stages IPG, Fetch, and Rotate):
prefetches up to 32 bytes per clock (2 bundles)
into a prefetch buffer, which can hold up to 8
bundles (24 instructions)
 - Branch prediction is done using a multilevel adaptive predictor like P6 microarchitecture
- Instruction delivery (stages EXP and REN):
distributes up to 6 instructions to the 9
functional units
 - Implements registers renaming for both rotation and register stacking.

Itanium processor 10-stage pipeline

- ▶ **Operand delivery (WLD and REG):** accesses register file, performs register bypassing, accesses and updates a register scoreboard, and checks predicate dependences.
 - ▶ Scoreboard used to detect when individual instructions can proceed, so that a stall of 1 instruction in a bundle need not cause the entire bundle to stall
- ▶ **Execution (EXE, DET, and WRB):** executes instructions through ALUs and load/store units, detects exceptions and posts NaTs, retires instructions and performs write-back
 - ▶ Deferred exception handling for speculative instructions is supported by providing the equivalent of poison bits, called NaTs for Not a Thing, for the GPRs (which makes the GPRs effectively 65 bits wide), and NaT Val (Not a Thing Value) for FPRs (already 82 bits wide)

Itanium 2

Caches

- 32KB L1 (1 cycle)
- 256KB L2 (5 cycle)
- 3 MB L3 (on chip)

200 MHz 128-bit Bus

SpecFP: 1356

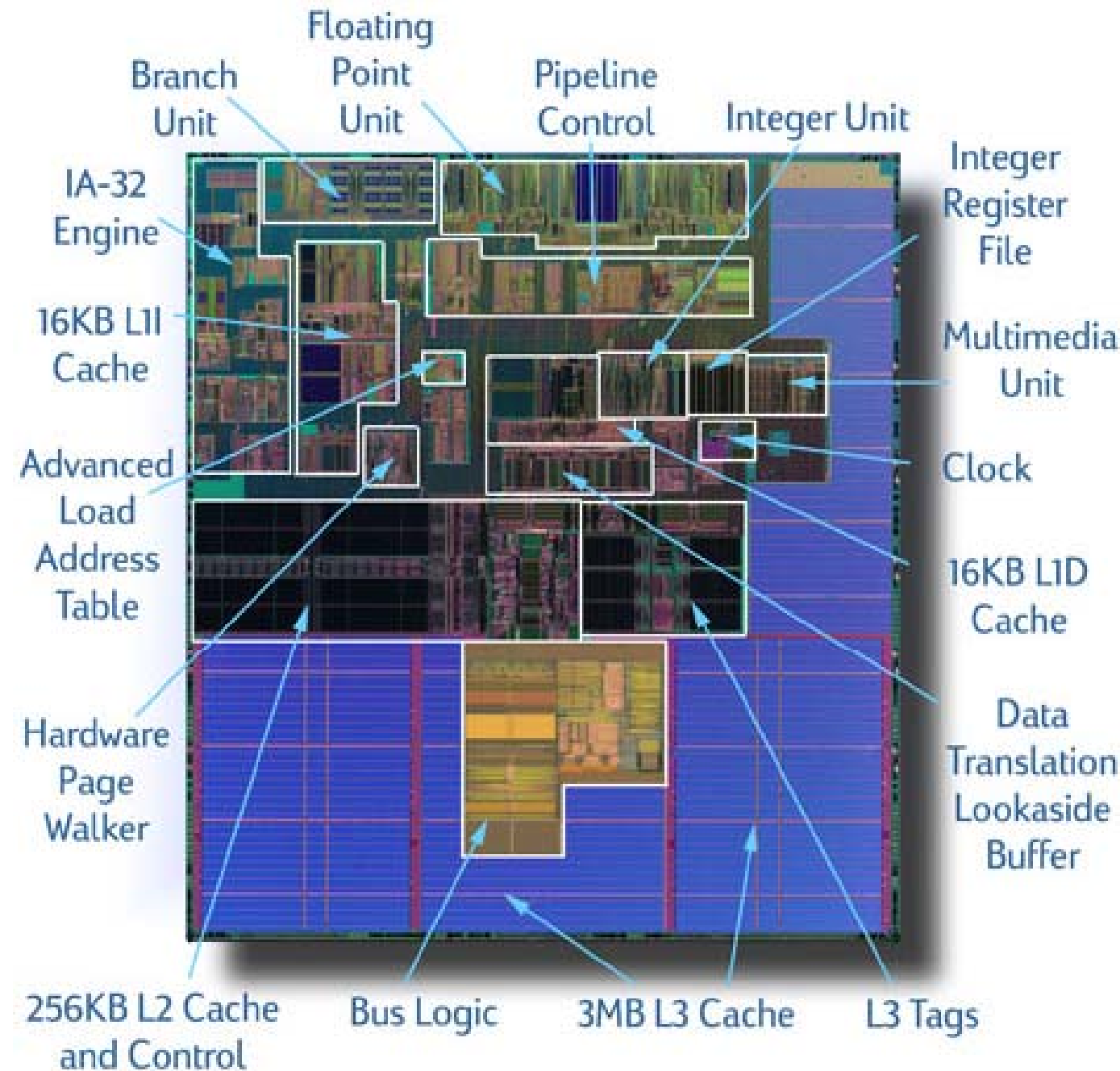
SpecInt: 810

44-bit addresses
(18TB)

221M transistors

19.5 x 21.6 mm

http://cpus.hp.com/technical_references/



Comments on Itanium

- Remarkably, the Itanium has many of the features more commonly associated with the dynamically-scheduled pipelines
 - strong emphasis on branch prediction, register renaming, scoreboarding, a deep pipeline with many stages before execution (to handle instruction alignment, renaming, etc.), and several stages following execution to handle exception detection
- Surprising that an approach whose goal is to rely on compiler technology and simpler HW seems to be at least as complex as dynamically scheduled processors!

EPIC/IA-64/Itanium principles

Start loads early

- advance loads - move above stores when alias analysis is incomplete
- speculative loads - move above branches

Predication to eliminate many conditional branches

- 64 predicate registers
- almost every instruction is predicated

register rich

- 128 integer registers (64 bits each)
- 128 floating-point registers

Independence architecture

- VLIW flavor, but fully interlocked (i.e., no delay slots)
- three 41-bit instruction syllables per 128-bit "bundle"
- each bundle contains 5 "template bits" which specify independence of following syllables (within bundle and between bundles)

unbundled branch architecture

- eight branch registers
- multiway branches

Rotating register files

- lower 48 of the predicate registers rotate
- lower 96 of the integer registers rotate

Itanium Timeline

- 1981: Bob Rau leads Polycyclic Architecture project at TRW/ESL
- 1983: Josh Fisher describes ELI-512 VLIW design and trace scheduling
- 1983-1988: Rau at Cydrome works on VLIW design called Cydra-5, but company folds 1988
- 1984-1990: Fisher at Multiflow works on VLIW design called Trace, but company folds 1990
- 1988: Dick Lampman at HP hires Bob Rau and Mike Schlansker from Cydrome and also gets IP rights from Cydrome
- 1989: Rau & Schlansker begin FAST (Fine-grained Architecture & Software Technologies) research project at HP; later develop HP PlayDoh architecture
- 1990-1993: Bill Worley leads PA-WW (Precision Architecture Wide-Word) effort at HP Labs to be successor to PA-RISC architecture; also called SP-PA (Super-Parallel Processor Architecture) & SWS (SuperWorkStation)
- HP hires Josh Fisher, input to PA-WW
- Input to PA-WW from Hitachi team, led by Yasuyuki Okada
- 1991: Hans Mulder joins Intel to start work on a 64-bit architecture
- 1992: Worley recommends HP seek a semiconductor manufacturing partner
- 1993: HP starts effort to develop PA-WW as a product
- Dec 1993: HP investigates partnership with Intel
- June 1994: announcement of cooperation between HP & Intel; PA-WW starting point for joint design; John Crawford of Intel leads joint team
- 1997: the term EPIC is coined
- Oct 1997: Microprocessor Forum presentations by Intel and HP
- July 1998: Carole Dulong of Intel, "The IA-64 Architecture at Work," IEEE Computer
- Feb 1999: release of ISA details of IA-64
- 2001: Intel marketing prefers IPF (Itanium Processor Family) to IA-64
- May 2001 - Itanium (Merced)
- July 2002 - Itanium 2 (McKinley)
- Aug 2004: "Itanium sales fall \$13.4bn shy of \$14bn forecast" (The Register)
- Dec 2004: HP transfers last of Itanium development to Intel

Itanium - rumours exaggerated?



- NASA's 10,240-processor Columbia supercomputer is built from 20 Altix systems, each powered by 512 Intel Itanium 2 processors. Peak performance 42.7 TeraFlops. Runs Linux. (Image courtesy of Silicon Graphics, Inc.)
- SGI has similar contracts at
 - Japan Atomic Energy Research Institute (JAERI) (2048 processors eventually)
 - Leibniz Rechenzentrum Computing Center (LRZ) at the Bavarian Academy of Sciences and Humanities, Munich (3328 processors eventually)

Top 20 SPEC systems

Top 20 SPECint2000

#	MHz	Processor	int peak	int base	Full results	MHz	Processor	fp peak	fp base	Full results
1	2933	Core 2 Duo EE	3119	3108	HTML	2300	POWER5+	3642	3369	HTML
2	3000	Xeon 51xx	3102	3089	HTML	1600	DC Itanium 2	3098	3098	HTML
3	2666	Core 2 Duo	2848	2844	HTML	3000	Xeon 51xx	3056	2811	HTML
4	2660	Xeon 30xx	2835	2826	HTML	2933	Core 2 Duo EE	3050	3048	HTML
5	3000	Opteron	2119	1942	HTML	2660	Xeon 30xx	3044	2763	HTML
6	2800	Athlon 64 FX	2061	1923	HTML	1600	Itanium 2	3017	3017	HTML
7	2800	Opteron AM2	1960	1749	HTML	2667	Core 2 Duo	2850	2847	HTML
8	2300	POWER5+	1900	1820	HTML	1900	POWER5	2796	2585	HTML
9	3733	Pentium 4 E	1872	1870	HTML	3000	Opteron	2497	2260	HTML
10	3800	Pentium 4 Xeon	1856	1854	HTML	2800	Opteron AM2	2462	2230	HTML
11	2260	Pentium M	1839	1812	HTML	3733	Pentium 4 E	2283	2280	HTML
12	3600	Pentium D	1814	1810	HTML	2800	Athlon 64 FX	2261	2086	HTML
13	2167	Core Duo	1804	1796	HTML	2700	PowerPC 970MP	2259	2060	HTML
14	3600	Pentium 4	1774	1772	HTML	2160	SPARC64 V	2236	2094	HTML
15	3466	Pentium 4 EE	1772	1701	HTML	3730	Pentium 4 Xeon	2150	2063	HTML
16	2700	PowerPC 970MP	1706	1623	HTML	3600	Pentium D	2077	2073	HTML
17	2600	Athlon 64	1706	1612	HTML	3600	Pentium 4	2015	2009	HTML
18	2000	Pentium 4 Xeon LV	1668	1663	HTML	2600	Athlon 64	1829	1700	HTML
19	2160	SPARC64 V	1620	1501	HTML	1700	POWER4+	1776	1642	HTML
20	1600	Itanium 2	1590	1590	HTML	3466	Pentium 4 EE	1724	1719	HTML

With Auto-parallelisation

Top 20 SPECint2000

#	MHz	Processor	int peak	int base	Full results	MHz	Processor	fp peak	fp base	Full results
1						2100	POWER5+	4051	3210	HTML
2						3000	Opteron	3538	2851	HTML
3						2600	Opteron AM2	3338	2711	HTML
4						1200	UltraSPARC III Cu	1344	1074	HTML

Top 20 SPECfp2000

**Aces Hardware
analysis of SPEC
benchmark data
[http://www.aces
hardware.com/S
PECmine/top.jsp](http://www.aceshardware.com/SPECmine/top.jsp)**

<http://www.spec.org/cpu2006/results/cpu2006.html>

Summary#1: Hardware versus Software Speculation Mechanisms

- To speculate extensively, must be able to disambiguate memory references
 - Much easier in HW than in SW for code with pointers
- HW-based speculation works better when control flow is unpredictable, and when HW-based branch prediction is superior to SW-based branch prediction done at compile time
 - Mispredictions mean wasted speculation
- HW-based speculation maintains precise exception model even for speculated instructions
- HW-based speculation does not require compensation or bookkeeping code

Summary#2: Hardware versus Software Speculation Mechanisms

cont'd

- Compiler-based approaches may benefit from the ability to see further in the code sequence, resulting in better code scheduling
- HW-based speculation with dynamic scheduling does not require different code sequences to achieve good performance for different implementations of an architecture
 - ➡ may be the most important in the long run?

Summary #3: Software Scheduling

- ▶ Instruction Level Parallelism (ILP) found either by compiler or hardware.
- ▶ Loop level parallelism is easiest to see
 - ▶ SW dependencies/compiler sophistication determine if compiler can unroll loops
 - ▶ Memory dependencies hardest to determine => Memory disambiguation
 - ▶ Very sophisticated transformations available
- ▶ Trace Scheduling to Parallelize If statements
- ▶ Superscalar and VLIW: $CPI < 1$ ($IPC > 1$)
 - ▶ Dynamic issue vs. Static issue
 - ▶ More instructions issue at same time => larger hazard penalty
 - ▶ Limitation is often number of instructions that you can successfully fetch and decode per cycle