Mach Learn DOI 10.1007/s10994-013-5358-3

Meta-interpretive learning: application to grammatical inference

Stephen H. Muggleton · Dianhuan Lin · Niels Pahlavi · Alireza Tamaddoni-Nezhad

Received: 15 December 2012 / Accepted: 12 April 2013 © The Author(s)

Abstract Despite early interest Predicate Invention has lately been under-explored within ILP. We develop a framework in which predicate invention and recursive generalisations are 20 implemented using abduction with respect to a meta-interpreter. The approach is based on 21 a previously unexplored case of Inverse Entailment for Grammatical Inference of Regular 22 languages. Every abduced grammar H is represented by a conjunction of existentially quan-23 tified atomic formulae. Thus $\neg H$ is a universally quantified clause representing a denial. The 24 hypothesis space of solutions for $\neg H$ can be ordered by θ -subsumption. We show that the 25 representation can be mapped to a fragment of Higher-Order Datalog in which atomic for-26 mulae in H are projections of first-order definite clause grammar rules and the existentially 27 quantified variables are projections of first-order predicate symbols. This allows predicate 28 invention to be effected by the introduction of first-order variables. Previous work by Inoue 29 and Furukawa used abduction and meta-level reasoning to invent predicates representing 30 propositions. By contrast, the present paper uses abduction with a meta-interpretive frame-31 work to invent relations. We describe the implementations of Meta-interpretive Learning 32 (MIL) using two different declarative representations: Prolog and Answer Set Program-33 ming (ASP). We compare these implementations against a state-of-the-art ILP system MC-34 TopLog using the dataset of learning Regular and Context-Free grammars as well learning 35 a simplified natural language grammar and a grammatical description of a staircase. Exper-36 iments indicate that on randomly chosen grammars, the two implementations have signif-37 icantly higher accuracies than MC-TopLog. In terms of running time, Metagol is overall 38 fastest in these tasks. Experiments indicate that the Prolog implementation is competitive 39 with the ASP one due to its ability to encode a strong procedural bias. We demonstrate 40 that MIL can be applied to learning natural grammars. In this case experiments indicate 41 that increasing the available background knowledge, reduces the running time. Additionally 42 ASP_M (ASP using a meta-interpreter) is shown to have a speed advantage over Metagol 43 when background knowledge is sparse. We also demonstrate that by combining Metagol_P 44

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Editors: Fabricio Riguzzi and Filip Zelezny.

S.H. Muggleton (🖾) · D. Lin · N. Pahlavi · A. Tamaddoni-Nezhad

⁴⁸ Department of Computing, Imperial College London, London, UK

⁴⁹ e-mail: s.muggleton@imperial.ac.uk

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Journal ID: 10994, Article ID: 5358, Date: 2013-04-22, Proof No: 1

(Metagol with a Regular grammar meta-interpreter) and Metagol_{CF} (Context-Free metainterpreter) we can formulate a system, Metagol_{RCF}, which can change representation by firstly assuming the target to be Regular, and then failing this, switch to assuming it to be Context-Free. Metagol_{RCF} runs up to 100 times faster than Metagol_{CF} on grammars chosen randomly from Regular and non-Regular Context-Free grammars.

Keywords Inductive logic programming · Meta-interpretative learning · Predicate invention · Recursion · Grammatical inference

1 Introduction

Consider the problem of using an ILP system to learn a Regular grammar which accepts all and only those binary sequences containing an even number of 1s (see Fig. 1). Since the 1950s automaton-based learning algorithms have existed (Moore 1956) which inductively infer Regular languages, such as Parity, from positive and negative examples. If we try to learn Parity using an ILP system the obvious representation of the target would be a Definite Clause Grammar (DCG) (see Fig. 1a). However, if the ILP system were provided with examples for the predicate q_0 then the predicate q_1 would need to be invented since the only single state finite acceptor consistent with the examples would accept all finite strings consisting of 0s and 1s. It is widely accepted that Predicate Invention is a hard and under-explored topic within ILP (Muggleton et al. 2011), and indeed state-of-the-art ILP systems, including MC-TopLog (Muggleton et al. 2012) and Progol (Muggleton 1995; Muggleton and Bryant 2000), are unable to learn grammars such as *Parity* in the form of a DCG using only first-order (non-metalogical) background knowledge since these systems do not support Predicate Invention. However, note that in Fig. 1a each clause of the DCG has one of the following two forms.

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$$Q([1, [1]) \leftarrow Q([C|x], y) \leftarrow P(x, y)$$

where Q, C, P are the only symbols which vary between the clauses. Figure 1b shows 82 how these two forms of clauses above can be captured within the two clauses of a recur-83 sive meta-interpreter parse/3 which uses the auxiliary predicates acceptor/1 and delta1/312 84 to instantiate the predicate symbols and constants from the original DCG. The predicates 85 acceptor/1 and delta1/3 can each be interpreted as Higher-Order Datalog (Muggleton and 86 Pahlavi 2012) predicates since they take arguments which are predicate symbols q_0, q_1 from 87 the DCG. By making acceptor/1 and delta1/3 abducible, Parity, and indeed any other Regu-88 lar grammar, could in principle be learned from ground instances of *parse/1* using abduction. 89 The paper explores this form of learning with respect to a meta-interpreter. 90

We show that such abductively inferred grammars are a special case of Inverse Entail-91 ment. We also show that the hypothesis space forms a lattice ordered by subsumption. The 92 extensions of this use of abduction with respect to a meta-interpreter lead to a new class 93 of inductive algorithm for learning Regular and Context-Free languages. The new approach 94

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⁹⁶ ¹Note that in the theory of automata (Hopcroft and Ullman 1979) *delta1/3* corresponds to the transition function of the finite acceptor shown in Fig. 1a. 97

⁹⁸ ²Considering *delta1/3* as an arity 3 ground relation, if c, k are bounds on the number of terminals and non-

⁹⁹ terminals respectively then the number of possible definitions for *delta1/3* is 2^{ck^2} .

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104	(a)
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118	Fig. 1

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	Finite acceptor		Pro	Production rules			Definite Clause Grammar (DCG)		
a)				$egin{array}{c} q_0 \ q_0 \ q_0 \ q_0 \ q_1 \ q_1 \end{array}$	$\begin{array}{c} \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \\ \rightarrow \end{array}$	$\begin{array}{c} 0 \ q_0 \\ 1 \ q_1 \\ 0 \ q_1 \\ 1 \ q_0 \end{array}$	$egin{array}{c} q_0([], \ q_0([0], \ q_0([1], \ q_1([0], \ q_1([1], \ q_1([$	[]) A], B) A], B) A], B) A], B)	$\leftarrow \\ \leftarrow q_0(A, B) \\ \leftarrow q_1(A, B) \\ \leftarrow q_1(A, B) \\ \leftarrow q_0(A, B) \\ \leftarrow q_0(A, B)$
	E^+	E^{-}		Meta-	inter	preter		Gı	ound facts
b)	λ 0 11 000 011 101	1 01 10 001 010 100 111	parse parse parse	$parse(S) \leftarrow parse(q0, S, [])$ $parse(Q, [], []) \leftarrow accepton$ $parse(Q, [C X], Y) \leftarrow$ $delta1(Q, C)$ $parse(P, X, Y)$). r(Q). , P), Y).	accep delta1 delta1 delta1 delta1	$tor(q0) \leftarrow (q0, 0, q0) \leftarrow (q0, 1, q1) \leftarrow (q1, 0, q1) \leftarrow (q1, 1, q0) \leftarrow (q1, 1, q) \leftarrow ($

Fig. 1 (a) Parity acceptor with associated production rules, DCG; (b) positive examples (E^+) and negative examples (E^-) , Meta-interpreter and ground facts representing the Parity grammar

121 blurs the normal distinctions between abductive and inductive techniques (see Flach and 122 Kakas 2000). Usually abduction is thought of as providing an explanation in the form of a 123 set of ground facts while induction provides an explanation in the form of a set of universally 124 quantified rules. However, the meta-interpreter in Fig. 1b can be viewed as projecting the 125 universally quantified rules in Fig. 1a onto the ground facts associated with acceptor/l and 126 delta1/3 in Fig. 1b. In this way abducing these ground facts with respect to a meta-interpreter 127 is equivalent to induction, since it is trivial to map the ground acceptor/1 and delta1/3 facts 128 back to the original universally quantified DCG rules. 129

In this paper, we show that the MIL framework can be directly implemented using declarative techniques such as Prolog and Answer Set Programming (ASP). In this way, the search for an hypothesis in a learning task is delegated to the search engine in Prolog or ASP. Although existing abductive systems can achieve predicate invention if loaded with the metainterpreter introduced in this paper, a direct implementation of MIL has the following advantages.

 As a declarative machine learning (De Raedt 2012) approach, it can make use of the advances in solvers. For example, techniques ASP solvers such as Clasp (Gebser et al. 2007) compete favourably in international competitions. Recently Clasp has been extended to Unclasp (Andres et al. 2012) which is highly efficiency for optimisation tasks. This advance is exploited in the experiments of this paper, as we use Unclasp for our experiments.

142 2. As demonstrated by the experiments in this paper, direct implementation of the approach 143 using a meta-interpreter has increased efficiency due to an ordered search in the case of 144 Prolog and effective pruning in the case of ASP. While existing abductive systems like 145 SOLAR (Nabeshima et al. 2010), A-System (Kakas et al. 2001) and MC-TopLog do not 146 have an ordered search, but instead enumerate all hypotheses that are consistent with the 147 data. 148 3. The resulting hypotheses achieve higher predictive due to global optimisation, as opposed 149 to the greedy covering algorithm used in many systems including MC-TopLog.

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The paper is structured as follows. Section 2 introduces the theoretical framework for MIL and its application to grammatical inference. We then describe implementations for a variant of Metagol, ASP_M (ASP using a meta-interpreter). In Sect. 4 the performance of these systems is compared experimentally against MC-Toplog on Regular and Context-Free grammar learning problems. In Sect. 5 we describe related work. Lastly we conclude and describe directions for further work in Sect. 6.

2 MIL framework

2.1 Logical notation

A variable is represented by an upper case letter followed by a string of lower case letters and digits. A function symbol or predicate symbol is a lower case letter followed by a string of lower case letters and digits. The arity of a function or predicate symbol is the number of arguments it takes. A constant is a function or predicate symbol which has arity zero. Variables and constants are terms, and a function symbol immediately followed by a bracketed *n*-tuple of terms is a term. Thus f(g(X), h) is a term when f, g and h are function symbols and X is a variable. A predicate symbol immediately followed by a bracketed *n*-tuple of terms is called an atomic formula. The negation symbol is \neg . Both A and \neg A are literals whenever A is an atomic formula. In this case A is called a positive literal and $\neg A$ is called a negative literal. A finite set (possibly empty) of literals is called a clause. A clause represents the disjunction of its literals. Thus the clause $\{A_1, A_2, \dots, \neg A_i, \neg A_{i+1}, \dots\}$ can be equivalently represented as $(A_1 \lor A_2 \lor \ldots \neg A_i \lor \neg A_{i+1} \lor \ldots)$ or $A_1, A_2, \ldots \leftarrow A_i, A_{i+1}, \ldots$ A Horn clause is a clause which contains at most one positive literal. A Horn clause is unit if and only if it contains exactly one literal. A denial or goal is a Horn clause which contains no positive literals. A definite clause is a Horn clause which contains exactly one positive literal. The positive literal in a definite clause is called the head of the clause while the negative literals are collectively called the body of the clause. A unit clause is positive if it contains a head and no body. A unit clause is negative if it contains one literal in the body. A set of clauses is called a clausal theory. A clausal theory represents the conjunction of its clauses. Thus the clausal theory $\{C_1, C_2, \ldots\}$ can be equivalently represented as $(C_1 \land C_2 \land \cdots)$. A clausal theory in which all predicates have arity at most one is called monadic. A clausal theory in which all predicates have arity at most two is called dyadic. A clausal theory in which each clause is Horn is called a Horn logic program. A logic program is said to be 186 definite in the case it contains only definite clauses. A logic program is said to be a Datalog 187 program if it contains no function symbols other than constants. A Datalog program is said 188 to be higher-order in the case that it contains at least one constant predicate symbol which is 189 the argument of a term. Literals, clauses and clausal theories are all well-formed-formulae 190 (wffs) in which the variables are assumed to be universally quantified. Let E be a wff or 191 term. E is said to be ground if and only if it contains no variables. The process of replacing 192 (existential) variables by constants is called Skolemisation. The unique constants are called 193 Skolem constants. Let C and D be clauses. We say that $C \succeq_{\theta} D$ or C θ -subsumes D if and 194 only if there exists a substitution θ such that $C\theta \subseteq D$.

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2.2 Formal language notation

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¹⁹⁸ Let Σ be a finite alphabet. Σ^* is the infinite set of strings made up of zero or more letters ¹⁹⁹ from Σ . λ is the empty string. uv is the concatenation of strings u and v. |u| is the length of ²⁰⁰

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string u. A language L is any subset of Σ^* . Let v be a set of non-terminal symbols disjoint from Σ . A production rule $r = LHS \rightarrow RHS$ is well-formed in the case that $LHS \in (v \cup \Sigma)^*$, $RHS \in (v \cup \Sigma \cup \lambda)^*$ and when applied replaces *LHS* by *RHS* in a given string. A grammar G is a pair (s, R) consisting of a start symbol $s \in v$ and a finite set of production rules R. A grammar is Regular Chomsky-normal in the case that it contains only production rules of the form $S \to \lambda$ or $S \to aB$ where $S, B \in v$ and $a \in \Sigma$. A grammar is Linear Context-Free in the case that it contains only Regular Chomsky-normal production rules or rules of the form $S \to Ab$ where $S, A \in v$ and $b \in \Sigma$. A grammar is Context-Free in the case that it contains only Linear Context-Free Chomsky-normal production rules or rules of the form $S \to AB$ where S, A, $B \in v$.³ A Context-Free grammar is said to be deterministic in the case that it does not contain two Regular Chomsky-normal production rules $S \rightarrow aB$ and $S \to aC$ where $B \neq C$. A sentence $\sigma \in \Sigma^*$ is in L(G) iff given a start symbol $S \in v$ there exists a sequence of production rule applications $S \rightarrow_{R_1} \cdots \rightarrow_{R_n} \sigma$ where $R_i \in G$. A language L is Regular, Linear Context-free or Context-Free in the case there exists a grammar G for which L = L(G) where G is Regular, Linear Context-Free or Context-Free respectively. According to the Context-Free Pumping Lemma (Hopcroft and Ullman 1979), if a language L is Context-Free, then there exists some integer $p \ge 1$ such that any string s in L with $|s| \ge p$ (where p is a constant) can be written as s = uvxyz with substrings u, v, x, y and z, such that $|vxy| \le p$, $|vy| \ge 1$ and $uv^n xy^n z$ is in L for every integer $n \ge 0$.

2.3 Framework

The Meta-Interpretive Learning (MIL) setting is a variant of the normal setting for ILP.

Definition 1 (Meta-Interpretive Learning setting) A Meta-Interpretive Learning (MIL) problem consists of *Input* = $\langle B, E \rangle$ and *Output* = H where the background knowledge $B = B_M \cup B_A$. B_M is a definite logic program⁴ representing a meta-interpreter and B_A and H are ground definite Higher-Order Datalog programs consisting of positive unit clauses. The predicate symbol constants in B_A and H are represented by Skolem constants. The examples are $E = \langle E^+, E^- \rangle$ where E^+ is a ground logic program consisting of positive unit clauses and E^- is a ground logic program consisting of negative unit clauses. The *Input* and *Output* are such that $B, H \models E^+$ and for all e^- in $E^-, B, H \nvDash e^-$.

Inverse Entailment can be applied to allow H to be derived from B and E^+ as follows.

$$B, H \models E^+$$

$$, \neg E^+ \models \neg H$$
(1)

Since both *H* and E^+ can each be treated as conjunctions of ground atoms containing Skolem constants in place of existential variables, it follows that $\neg H$ and $\neg E^+$ are universally quantified denials where the variables come from replacing Skolem constants by unique variables. We now define the concept of a Meta-interpretive learner.

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- ²²⁴ ³This is an adaptation of Chomsky-normal form Context-free, which only permits productions of the form
- 246 $S \to \lambda, S \to a \text{ and } S \to AB.$

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 ⁴Note that the meta-interpreter shown in Fig. 1b is a definite logic program. Such a meta-interpreter is only a part of implementations such as those described later in Sect. 3. Within such an implementation negation-by-failure is used to implement operations such as abduction, so the implementation as a whole is not a definite logic program. However, this does not affect this definition or the later propositions which use it.



Fig. 2 Parity example where B_M is the Meta-interpreter shown in Fig. 1b, $B_A = \emptyset$ and E^+ , $\neg E^+$, E^- , H, $\neg H$, are as shown above. '\$0' and '\$1' in H are Skolem constants replacing existentially quantified variables

Definition 2 (Meta-interpretive learner) Let $\mathcal{H}_{B,E}$ represent the complete set of abductive hypotheses H for the MIL setting of Definition 1. Algorithm A is said to be a Meta-interpretive learner iff for all B, E such that H is the output of Algorithm A given B and E as inputs, it is the case that $H \in \mathcal{H}_{B,E}$.

Example 1 (Parity example) Let $B = \langle B_M, B_A \rangle$, $E = \langle E^+, E^- \rangle$ and $H \in \mathcal{H}_{B,E}$ represents the parity grammar. Figure 2 shows *H* as a possible output of a Meta-interpretive learner.

275 Note that this example of abduction produces Predicate Invention by introducing Skolem 276 constants representing new predicate symbols. By contrast an ILP system such as Progol 277 uses Inverse Entailment (Muggleton 1995) to construct a single clause from a single ex-278 ample, while a Meta-interpretive learner uses Inverse Entailment to construct the set of 279 all clauses H as the abductive solution to a single goal $\neg E^+$ using E^- as integrity con-280 straints. In the example the hypothesised grammar H corresponds to the first-order DCG 281 from Fig. 1a, which contains both invented predicates and mutual recursion. Neither pred-282 icate invention nor mutual recursion can be achieved with DCGs in this way using ILP 283 systems such as Progol or MC-TopLog. 284

286 2.4 Lattice properties of hypothesis space

288 In this section we investigate orderings over MIL hypotheses.

Definition 3 ($\succeq_{B,E}$ relation in MIL) Within the MIL setting we say that $H \succeq_{B,E} H'$ in the case that $H, H' \in \mathcal{H}_{B,E}$ and $\neg H' \succeq_{\theta} \neg H$.

We now show that $\succeq_{B,E}$ forms a quasi-ordering and a lattice.

Proposition 1 (Quasi-ordering) Within the MIL setting $\langle \mathcal{H}_{B,E}, \succeq_{B,E} \rangle$ forms a quasiordering.

Proof Follows from the fact that $\langle \{\neg H : H \in \mathcal{H}_{B,E}\}, \succeq_{\theta} \rangle$ forms a quasi-ordering since each ¬*H* is a clause (Nienhuys-Cheng and de Wolf 1997). □

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Proposition 2 (Lattice) Within the MIL setting $\langle \mathcal{H}_{B,E}, \succeq_{B,E} \rangle$ forms a lattice.

Proof Follows from the fact that $\langle \{\neg H : H \in \mathcal{H}_{B,E}\}, \succeq_{\theta} \rangle$ forms a lattice since each $\neg H$ is a clause (Nienhuys-Cheng and de Wolf 1997).

We now show that this ordering has a unique top element.

Proposition 3 (Unique \top element) Within the MIL setting there exists $\top \in \mathcal{H}_{B,E}$ such that for all $H \in \mathcal{H}_{B,E}$ we have $\top \succeq_{B,E} H$ and \top is unique up to renaming of Skolem constants.

Proof Let $\neg H' = \bigvee_{H \in \mathcal{H}_{B,E}} \neg H$ and $\neg \top = \neg H' \theta_v$ where v is a variable and $\theta_v = \{u/v : u \text{ variable in } \neg H'\}$. By construction for each $H \in \mathcal{H}_{B,E}$ it follows that $\neg \top \succeq_{\theta} \neg H$ with substitution θ_v . Therefore for all $H \in \mathcal{H}_{B,E}$ we have $\top \succeq_{B,E} H$ and \top is unique up to renaming of Skolem constants.

This proposition can be illustrated with a grammar example.

Example 2 (Subsumption example) In terms of the Meta-interpreter of Fig. 1a the universal grammar $\{0, 1\}^*$ can be expressed using $\top = \{(acceptor(\$0) \leftarrow), (delta1(\$0, 0, \$0) \leftarrow), (delta1(\$0, 1, \$0) \leftarrow)\}$. Letting *H* represent the Parity grammar from Example 1 it is clear that $\neg H \succeq_{\theta} \neg \top$ and so $\top \succeq_{B,E} H$. So unlike the subsumption relation between universally quantified clauses, binding all the (existentially quantified) variables in *H* to each other produces a maximally general grammar \top .

We now show the circumstances under which a unique bottom element of the lattice can be constructed using Plotkin's lgg algorithm.

Proposition 4 (Unique \perp element) In the case that $\mathcal{H}_{B,E}$ is finite up to renaming of Skolem constants there exists $\perp \in \mathcal{H}_{B,E}$ such that for all $H \in \mathcal{H}_{B,E}$ we have $H \succeq_{B,E} \perp$ and \perp is unique up to renaming of Skolem constants.

Proof Since $\mathcal{H}_{B,E}$ is finite $\neg \bot = lgg(\{\neg H : H \in \mathcal{H}_{B,E}\})$ where lgg is Plotkin's algorithm for computing the least general generalisation of a set of clauses under subsumption (Plotkin 1969).

For most purposes the construction of the unique bottom clause is intractable since the cardinality of the lgg clause increases exponentially in the cardinality of $\mathcal{H}_{B,E}$. We now show a method for reducing hypotheses.

2.5 Reduction of hypotheses

Proposition 5 (Logical reduction of hypotheses) Suppose H' is an hypothesis in the MIL setting and $\neg H$ is the result of applying Plotkin's clause reduction algorithm⁵ (Plotkin 1969) to $\neg H'$. Then H is a reduced hypothesis equivalent to H'.

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⁴⁶ ⁵This algorithm iteratively remove logically redundant literals from a clause until no redundant clauses remain.

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Language	Meta-interpreter	Example	L
type		Grammar	
	$parse(S) \leftarrow parse(Q, S, []).$	$S \rightarrow 0 S$	
(a) D	$parse(Q, X, X) \leftarrow acceptor(Q).$	$S \rightarrow 1 T$	$0^{+1^{+}}$
(a) K	$parse(Q, [C X], Y) \leftarrow delta1(Q, C, P),$	$T \rightarrow \lambda$	0.1.
	parse(P, X, Y).	$T \rightarrow 1 T$	
	$parse(S) \leftarrow parse(Q, S, []).$		
	$parse(Q, X, X) \leftarrow acceptor(Q).$		
	$parse(Q, [C X], Y) \leftarrow delta1(Q, C, P),$	C , 1	
(b) CF	parse(P, X, Y).	$S \rightarrow \lambda$	
	$parse(Q, X, Y) \leftarrow delta2(Q, P, C),$	$3 \rightarrow I \ 3$	$(0^n 1^n)^*$
	parse(P, X, [C Y]).	$I \to 0 \ 0 \ U$	
	$parse(Q, X, Y) \leftarrow delta3(Q, P, R),$	$U \rightarrow I \ 1$	
	parse(P, X, Z),		
	parse(R, Z, Y).		

Fig. 3 Meta-interpreters, Chomsky-normal form grammars and languages for (a) Regular (R) and (b) Context-Free (CF) languages

Proof Follows from the fact that $\neg H'$ is θ -subsumption equivalent to $\neg H$ by construction.

Example 3 (Reduction example) Let $H' = H \cup \{r\}$ where H is the Parity grammar from Fig. 2 and $r = (delta1(\$0, 0, \$2) \leftarrow)$ represents an additional redundant grammar rule. Now Plotkin's reduction algorithm would reduce $\neg H'$ to the equivalent clause $\neg H$ and consequently grammar H is a reduced equivalent form of H.

In the following section we show the existence of a compact bottom hypothesis in the case of MIL for Regular languages.

2.6 Framework applied to grammar learning

Figure 3 shows how the Meta-interpreter for Regular Grammars can be extended to Context-Free Grammars.

The Chomsky language types form an inclusion hierarchy in which Regular \subseteq Context-Free. Algorithms for learning the Regular languages have been widely studied since the 1970s within the topic of Grammatical Inference (de la Higuera 2005). Many of these start with a prefix tree acceptor, and then progressively merge the states.

Proposition 6 (Unique \perp for Regular languages) Prefix trees act as a compact bottom theory in the MIL setting for Regular languages.

³⁹¹ Proof Follows from the fact that all deterministic Regular grammars which include the posi-³⁹² tive examples can be formed by merging the arcs of a prefix tree acceptor (Muggleton 1990). ³⁹³ Merging the arcs of the prefix tree is achieved by unifying the delta1 atoms in $\neg H$ within ³⁹⁴ the MIL setting. \Box ³⁹⁵ *Example 4* (Prefix tree) Assume the MIL setting with B_M being the meta-interpreter for

Regular languages. Let $E^+ = \{parse([1, 1]), parse([1, 1, 0])\}$ then $\bot = \{delta1(\$0, 1, \$1), delta1(\$1, 1, \$2), acceptor(\$2), delta1(\$2, 0, \$3), acceptor(\$3)\}$ represents the prefix tree automaton.

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parse(S,G1,G2) :- parse(s(0),S,[],G1,G2).

parse(Q,X,X,G1,G2) :- abduce(acceptor(Q),G1,G2). parse(Q,[C|X],Y,G1,G2) :- Skolem(P), abduce(delta1(Q,C,P),G1,G3), parse(P,X,Y,G3,G2).

abduce(X,G,G) :- member(X,G). abduce(X,G,[X|G]) :- not(member(X,G)).

Skolem(s(0)). Skolem(s(1))....

Fig. 4 no $Metagol_R$

Proposition 7 (\perp for Context-Free languages) Any bottom theory \perp for a Context-Free language contains a set of delta1 atoms representing a Regular prefix tree.

Proof Follows from the fact that the Regular subset of MIL hypotheses are all subsumed by $\neg \bot_R$ where \bot_R represents the Regular prefix tree.

3 Implementations

In this section, we describe the implementations of Meta-interpretive Learning (MIL) using two different declarative languages: Prolog and Answer Set Programming (ASP). The resulting systems are called Metagol⁶ and ASP_M,⁷ respectively.

3.1 Implementation in Prolog

⁴²⁸ ⁴²⁹ The systems $Metagol_R$, $Metagol_{CF}$, and $Metagol_{RCF}$ are three simple Prolog implementa-⁴³⁰ tions of MIL.

3.1.1 Metagol_R

433 434 Before introducing Metagol_R, we first explain its simplified version noMetagol_R (non-435 optimising Metagol_R) as shown in Fig. 4. The system noMetagol_R is based on the following 436 abductive variant of the Regular Meta-interpreter from Fig. 3 (the standard definition of

member/2 is omitted for brevity).

The abduced atoms are simply accumulated in the extra variables G1, G2, G3. The term s(0) represents the start symbol and a finite set of Skolem constants is provided by the monadic predicate *Skolem*. Hypotheses are now the answer substitutions of a goal such as the following.

:- parse([],[],G1), parse([0],G1,G2), parse([0,0],G2,G3), parse([1,1],G3,G4),	% Pos
parse([0,0,0],G4,G5), parse([0,1,1],G5,G6), parse([1,0,1],G6,G),	
not(parse([1],G,G)), not(parse([0,1],G,G)).	% Neg

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⁴⁴⁷ ⁶*Metagol* is MIL encoded within YAP Prolog. The name comes from the combination of *Meta-* and *gol*,
⁴⁴⁸ where *Meta-* corresponds to the Meta-Interpreter, and *gol* is the reverse of *log* which is short for logic.

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⁴⁴⁹ ⁷The name ASP_M is MIL encoded within an ASP solver. ⁴⁵⁰

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parse(S,G1,G2,S1,S2,K1,K2) :- parse(s(0),S,[],G1,G2,S1,S2,K1,K2).

parse(Q,X,X,G1,G2,S,S,K1,K2) :- abduce(acceptor(Q),G1,G2,K1,K2). parse(Q,[C|X],Y,G1,G2,S1,S2,K1,K2) :- Skolem(P,S1,S3), abduce(delta1(Q,C,P),G1,G3,K3,K2), parse(P,X,Y,G3,G2,S3,S2,K3,K2).

abduce(X,G,G,K,K) :- member(X,G).abduce(X,G,[X|G],s(K),K) := not(member(X,G)).

Skolem(s(N),[s(Pre)|SkolemConsts],[s(N),s(Pre)|SkolemConsts]):- N is Pre+1 Skolem(S,SkolemConsts,SkolemConsts):-member(S,SkolemConsts).

Fig. 5 Metagol_R

Note that each of the positive examples are provided sequentially within the goal and the resulting grammar is then tested for non-coverage of each of the negative examples. The final grammar returned in the variable G is a solution which covers all positives and none of the negatives. In the case shown above the first hypothesis found by Prolog is as follows.

> G = [delta1(s(1),0,s(1)), delta1(s(1),1,s(0)), delta1(s(0),1,s(1)),delta1(s(0),0,s(0)),acceptor(s(0))]

This hypothesis correctly represents the Parity acceptor of Fig. 1. All other consistent hypotheses can be generated by making Prolog backtrack through the SLD proof space.

 $Metagol_R$ We will now explain the following procedural biases, which extends noMetagol_{*R*} to Metagol_{*R*}.

Minimal hypothesis Occam's razor suggests to select the shortest hypothesis that fits the data. Therefore we introduce the clause bound into Metagol_R so that the search starts from shorter hypotheses. In Metagol_R (Fig. 5) the variables K, K1, K2 and K3 are related to the clause bound. They are instantiated with Peano numbers $(s(0), s(1), \ldots)$ representing a bound on the maximum number of abduced clauses. Thus the second clause of abduce/5 fails once K1 has a value of 0. K1 is iteratively increased until an hypothesis is found within that bound. The search thus guarantees finding an hypothesis with minimal description length.

Specific-to-General Within the MIL setting an hypothesis H_s is said to be more specific than H_g in the case that $\neg H_s \succeq_{\theta} \neg H_g$, as explained in Sect. 2.4. Therefore H_s is a refinement of H_g by renaming with new Skolem constants. In Metagol_R the Skolem constants are enumerated by the program of Skolem/3. The first clause of Skolem/3 introduces a new Skolem constant, while the second clause of Skolem/3 provides a Skolem constant that has already been used in the deriving hypothesis. Due to Prolog's procedural semantics, the first clause of *Skolem*/3 will be tried before the second one, thus H_s , that is, the one with more Skolem constants, will be considered before H_g .⁸ Switching the order of the two clauses in Skolem/3 will result in a general-to-specific search. In that case, the universal grammar will be considered first, since it is maximally general and can be expressed with only one Skolem constant (see Example 2).

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⁸Provided H_g and H_s are within the same clause bound.

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Fig. 6 Metagol_{RCF}

metagolRCF(G):- metagolR(G). metagolRCF(G):- metagolCF(G).

 $Metagol_{CF}$ The Metagol_{CF} system is based on an abductive variant of the Context-Free Meta-interpreter from Fig. 3, though we omit the full Prolog description due to space restrictions. Once more, abduction is carried out with respect to a single goal as in Metagol_R.

 $Metagol_{RCF}$ The Metagol_{*RCF*} system simply combines Metagol_{*R*} and Metagol_{*CF*} sequentially, as shown below in Fig. 6. Due to Prolog's procedural semantics, the hypothesis returned will be Regular in the case Metagol_{*R*} finds a consistent grammar and otherwise will be the result of Metagol_{*CF*}.

3.2 Implementation in Answer Set Programming (ASP)

Compared to Prolog, ASP not only has advantages in handling non-monotonic reasoning, but also has higher efficiency in tackling search problems (Gebser et al. 2012). The systems ASP_{MR} and ASP_{MCF} are two simple ASP implementations of Meta-interpretive learning. Each sequence is encoded as a set of facts. For example, the positive example posEx(Seq2, [1, 1]) is encoded in the second line in Fig. 7, where seq2 is the ID of the sequence and the predicate seqT(SeqID, P, T) means the sequence has a terminal T at position P. The meta-interpretive parser uses position to mark a substring, rather than storing the substring in a list. The goal of finding an hypothesis that covers all positive examples and none of the negatives is encoded as an integrity constraint.

525 ASP_{MR} The program in Fig. 8 is an ASP implementation of the Regular Meta-interpreter 526 in Fig. 3. It is sectioned into parts describing generating, defining, testing, optimising, and 527 displaying. The generating part specifies the hypothesis space as a set of facts about delta1/3 528 and acceptor/1. ASP choice rules are used to indicate that any subset of this set is allowed 529 in the answer sets of this program. The defining part corresponds to the Regular Meta-530 interpreter. The testing part contains an integrity constraint saying that an answer set of this 531 program should contain production rules which parse all positive examples and no negative 532 examples. The display part restricts the output to containing only predicates delta1/3 and 533 acceptor/1, which corresponds to the hypothesis. 534

In order to find a minimal hypothesis like that in $Metagol_R$, the optimisation component in ASP is used. Although the use of optimisation increases the computational complexity (Gebser et al. 2012), it improves⁹ the predictive accuracy of the hypothesis. An optimisation statement like the one in Fig. 8 specifies the objective function to be optimised. The weight following each atom is part of the objective function. In our case, the objective function

posEx(e1). length(e1,2). seqT(e1,0,0). seqT(e1,1,0).

negEx(e4). length(e4,2). seqT(e4,0,0). seqT(e4,1,1)

posEx(e2). length(e2,3). seqT(e2,0,1). seqT(e2,1,0). seqT(e2,2,1).

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 negEx(e4,[0,1]).
 negEx

 Fig. 7
 ASP representation of examples

posEx(e1,[0,0])

posEx(e2,[1,0,1]) negEx(e3,[1]).

List

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 ⁹Occam's razor suggests that simpler hypotheses have higher predictive power. This is further supported by Sect. 4 about experiments, where the non-minimal hypotheses suggested by MC-TopLog have lower predictive accuracies than the minimal ones hypothesised by ASP_M and Metagol.

negEx(e3). length(e3,1). seqT(e3,0,1).

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% Instances #const maxNumSkolemConstants=1. Skolem(0..maxNumSkolemConstants). terminal(0;1). % Generate: specify the hypothesis space {acceptor(NT):Skolem(NT)}. {delta1(NT1,T,NT2):Skolem(NT1):terminal(T):Skolem(NT2)}. % Defining Part parse(ExID,MaxLengh,MaxLengh,NT):- length(ExID,MaxLengh),acceptor(NT) parse(ExID,Position1,Position2,NT1):- seqT(ExID,Position1,T), delta1(NT1,T,NT2), parse(ExID,Position1+1,Position2,NT2). % Integrity constraint :- negEx(ExID),length(ExID,MaxLengh),parse(ExID,0,MaxLengh,0)). :- posEx(ExID),length(ExID,MaxLengh),not parse(ExID,0,MaxLengh,0). 568 % Optimisation #minimize [delta1(NT1,T,NT2):Skolem(NT1):terminal(T):Skolem(NT2)=1, 569 570 acceptor(NT):Skolem(NT)=1]. % Displaying 572 #hide. #show delta1/3. #show acceptor/1. 575 Fig. 8 ASPMR 577 578 corresponds to the description length of an hypothesis. Therefore the weight is set to 1 for 579 each atom, meaning the description length of a unit clause is 1. 580 Most ASP solvers do not support variables directly, therefore a grounder is needed for 582 transforming the input program with first-order variables into an equivalent ground program. 583 Then an ASP solver can be applied to find an answer set that satisfies all the constraints. The hypothesised grammar will be part of the returned answer set. In the case shown above the 585 first hypothesis returned by ASP is the same as the one found by Metagol and correctly 586 represents the Parity acceptor of Fig. 1. ASP solvers use efficient constraint handling techniques to efficiently find stable models known as answer sets. This computational mechanism is very different from that of Prolog, leading to their different implementations, in particular, in the use of iterative deep-590 ening. In addition, the bound on clauses puts an implicit limit on Skolem constants, since the number of Skolem constants in a derived hypothesis is at most the number of clauses it 592 contains. Therefore Metagol_R is immune to the number of Skolem constants pre-specified 593 in the background knowledge. By contrast, ASP_{MR} is largely affected by the number of 594 Skolem constants due to its bottom-up search. Therefore ASP_{MR} has to put an explicit 595 bound on the number of Skolem constants. More specifically, the second line of 'Generate'

596 $\{delta1(NT1, T, NT2): Skolem(NT1): terminal(T): Skolem(NT2)\}\$ has a default size of 597 $T * NT^2$, where T corresponds to the number of terminals and NT denote the number 598 of Skolem constants. While a cardinality constraint on this set does not always reduce the 599 search space, because it can lead to a quadratic blow-up in search space (Gebser et al. 2012) 600

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when the cardinality constraint is translated into normal logic program during the grounding stage. Additionally, ASP solvers' build-in optimisation component is handy for finding a global minimal hypothesis. Thus ASP_{MR} does not use iterative deepening on the clause bound like that in Metagol_P for finding a global minimal hypothesis.

ASP_{MCF} Similar to Metagol_{CF}, the ASP_{MCF} system is based on a variant of the Context-Free Meta-interpreter from Fig. 3. However, there is no equivalent ASP implementation to Metagol_{RCF}. Since Metagol_{RCF} exploits the procedural semantics of Prolog programs, while there is no similar procedural semantics for ASP programs.

4 Experiments

In this section we describe experiments on learning Regular, Context-Free and a simplified natural language grammar. It was shown in Sect. 1 that ILP systems cannot learn grammars in a DCG representation with predicate invention. However, an ILP system given a metainterpreter as part of background knowledge becomes capable of doing predicate invention. In the experiments described below, the performance of a state-of-the-art ILP system MC-TopLog, loaded with suitable meta-interpretive background, is compared against variants of Metagol and ASP_M as described in Sect. 3. MC-TopLog is chosen for this comparison since it can learn multiple dependent clauses from examples (unlike say Progol). This is a necessary ability for grammar learning tasks. In the final experiment we show how MIL can be used to learn a definition of a staircase. This indicates the applicability of MIL in more general learning applications beyond grammar learning. All datasets and learning systems used in these experiments are available at http://ilp.doc.ic.ac.uk/metagol.

4.1 Learning regular languages

We investigate the following Null hypotheses.

Null Hypothesis 1.1 Metagol_R, ASP_{MR} and a state-of-the-art ILP system cannot learn randomly chosen Regular languages.

Null Hypothesis 1.2 Metagol_R and ASP_{MR} cannot outperform a state-of-the-art ILP system on learning randomly chosen Regular languages.

Null Hypothesis 1.3 Metagol_R can not outperform ASP_{MR} on learning randomly chosen Regular languages.

4.1.1 Materials and methods

Randomly chosen deterministic Regular grammars were generated by sampling from a Stochastic Logic Program (SLP) (Muggleton 1996) which defined the space of target grammars. More specifically, the SLP used for sampling consists of a meta-interpreter and all possible grammars. Then the following steps were conducted. Firstly, an integer i $(1 \le i \le 3)$ was randomly sampled. This integer corresponds to the number of seed examples.¹⁰ Secondly, the query "sample(parse(Seq,Grammar))" returned one sequence as well as the grammar that parse this sequence. Thirdly, the grammars were aggregated by issuing the query

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¹⁰The parsing of seed examples requires all rules in the grammar. 650

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Table 1 Average and Maximum lengths of sampled examples for		RG1	RG2	CFG3	CFG4
datasets R1, R2, CFG3 and CFG4	Average \pm STD	6.15 ± 4.06	11.43 ± 10.47	5.89 ± 3.08	11.02 ± 9.79
	Maximum	15	78	15	68

'sample(parse(Seq,Grammar))" *i* times. Finally, each generated grammar was reduced using Plotkin's reduction algorithm (see Sect. 2.5) to remove redundancy and equivalent non-terminals. Non-deterministic and finite language grammars were discarded. Sampling of examples was also done using an SLP. Sampling was with replacement.

In this experiment, we used two different datasets sampled from different distributions. In dataset RG1, the examples were randomly chosen from Σ^* for $\Sigma = \{a, b\}$, while in RG2 $\Sigma = \{a, b, c\}$. RG2 has longer sequence lengths, as shown by Table 1. Both datasets contains 200 randomly chosen Regular grammars. We compared the performance of Metagol_{*R*}, ASP_{MR} and MC-TopLog on learning Regular grammars using RG1. Only Metagol_{*R*} and ASP_{MR} were compared on RG2, since MC-TopLog failed to terminate due to the longer sequence examples. The performance was evaluated on predictive accuracies and running time.¹¹ The results were averaged over 200 randomly sampled grammars. For each sample, we used a fixed test set of size 1000. The size of training set varied from 2 to 50 in RG1 and from 4 to 100 in RG2.

4.1.2 Results and discussion

As shown by Fig. 9(a), all three systems have predictive accuracies significantly higher than default. Therefore Null hypothesis 1.1 is refuted. MC-TopLog is not usually able to carry out predicate invention, but is enabled to do so by the inclusion of a meta-interpreter as background knowledge.

678 As shown in Fig. 9(b), MC-TopLog's running time is considerably longer than Metagol_R 679 and ASP_{MR}. MC-TopLog has slightly lower predictive accuracies than both Metagol_R and 680 ASP_{MR}. The difference is statistically significant according to a t-test (p < 0.01). There-681 fore, Null hypothesis 1.2 is refuted with respect to both predictive accuracy and running 682 time. MC-TopLog's longer running time is due to the fact that it enumerates all candidate 683 hypotheses within the version space. By contrast, both Metagol_{*P*} and ASP_{MR} do not traverse 684 the entire space. In particular, ASP solver like Clasp incorporate effective optimisation tech-685 niques based on branch-and-bound algorithms (Gebser et al. 2007). The larger hypothesis 686 space leads to lower accuracy in MC-TopLog. This is consistent with the Blumer Bound 687 (Blumer et al. 1989), according to which the error bound decreases with the size of the hy-688 pothesis space. Moreover, MC-TopLog's accuracy is also affected by its covering algorithm 689 which is greedy and does not guarantee finding a global optimal. By contrast, both Metagol_R 690 and ASP_{MR} find an hypothesis which is minimal in terms of description length. Figure 11 691 compares the different hypothesis suggested by the three systems. MC-TopLog's hypoth-692 esis $H_{mcTopLog}$ is longer than both of Metagol_R and ASP_{MR}. By contrast, both Metagol_R 693 and ASP_{MR} derive the one with minimal description length, although they are not exactly 694 the same. $H_{metagolR}$ is more specific than H_{aspMR} due to the specific-to-general search in 695 Metagol_R. In this example, $H_{metagolR}$ is the same as the target hypothesis. 696

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⁶⁹⁸ ¹¹The running times of Metagol_R and ASP_{MR} are measured in terms of getting the first minimal hypothesis, ⁶⁹⁹ rather than all minimal hypotheses.

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Fig. 9 Average (**a**) predictive accuracies and (**b**) running times for Null hypothesis 1 (Regular) on short sequence examples (RG1)



Figure 9(b) indicates that Metagol_{*R*} has considerably lower running time than ASP_{MR} , and the difference increases when examples are long, as shown in Fig. 10(b). $Metagol_R$ also has slightly higher accuracy than ASP_{MR} . A *t*-test suggests that their difference in accuracy is statistically significant (p < 0.01) as one is consistently higher than the other. Therefore, Null hypothesis 1.3 is refuted with respect to both predictive accuracy and running time. The reasons that $Metagol_R$ is faster than ASP_{MR} on learning regular languages are: (1) $Metagol_R$, as a Prolog implementation, can use forms of procedural bias which cannot be defined declaratively in ASP since the search in ASP is not affected by the order of clauses in the logic program; (2) there are few constraints in the learning task so that efficient constraint handling techniques in ASP do not increase efficiency.

Both Metagol_{*R*} and ASP_{MR}'s running times appear to increase linearly with the number of examples. By contrast, MC-TopLog's running time appears to be unaffected by the number of examples. MC-TopLog's running time is determined by the size of the hypothesis space it enumerates, which depends on the lengths of examples. It therefore fails to learn from RG2 which has longer sequences (see Table 1).

4.2 Learning context-free languages

745 We investigate the following Null hypotheses.

Null Hypothesis 2.1 Metagol_{CF}, ASP_{MCF} and a state-of-the-art ILP system cannot learn
 randomly chosen Context-Free languages.

Null Hypothesis 2.2 Metagol_{CF} and ASP_{MCF} cannot outperform a state-of-the-art ILP system on learning randomly chosen Context-Free languages.

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4.2.1 Materials and methods

Randomly chosen Context-Free grammars were generated using an SLP and reduced using
Plotkin's reduction algorithm (see Sect. 2.5). Grammars were removed if they corresponded
to finite languages or could be recognised using the pumping lemma for Context-Free grammars. However, not all Regular grammars can be filtered in this way, since it is undecidable whether a Context-Free grammar is Regular. More specifically, if a grammar is not
pumpable, then it is definitely Regular, while a pumpable grammar is not necessarily nonRegular.

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/91	E^+	E^{-}	$H_{metagolR}$	H_{aspMR}	$H_{mcTopLog}$
792					$s \rightarrow a s$
793			$s \rightarrow a s$	$s \rightarrow a s$	$s \rightarrow a s$
794	aa	abab	$s \rightarrow u s_1$	$s \rightarrow u s_1$	$3 \rightarrow 1$
795	aba	aabaa	$s_1 \rightarrow b \ s_1$	$s_1 \rightarrow b \ s_1$	$s \rightarrow b s_1$
796	abbba	baaababaa	$s_1 \rightarrow a \ s_2$	$s_1 \rightarrow a s$	$s_1 \rightarrow a \ s_2$
797			$s_2 \rightarrow$	$s \rightarrow$	$s_2 \rightarrow$
798					$s_1 \rightarrow b \ s$

799 **Fig. 11** Hypothesis comparison

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Fig. 12 Average (a) predictive accuracies and (b) running times for Null hypothesis 2 (Context-free) on short sequence examples (CFG3)



The examples were generated in the same way as that in the Regular-language experiment. There were two datasets, each containing 200 samples. Details are shown in Table 1. The comparisons of Metagol_{CF}, ASP_{MCF} and MC-TopLog on learning Context-Free grammars was done using only dataset CFG3 since MC-TopLog failed to terminate on CFG4 with long-sequence examples. The evaluation method was the same as that for learning regular languages.

4.2.2 Results and discussion

As shown in Fig. 12(a), all three systems derive hypotheses with predictive accuracies considerably higher than default. Therefore Null hypotheses 2.1 is refuted. Compared to MC-TopLog, both Metagol_{CF} and ASP_{MCF} have consistently higher averaged predictive accu-840 racies. This is again explained by the Blumer Bound since MC-TopLog considers a larger 841 hypothesis space. Metagol_{CF} conducts a bounded search using a bottom clause so that it is 842 feasible even though the version space is potentially infinite. ASP solvers can also deal with 843 infinite spaces. 844

Null hypothesis 2.2 is refuted with respect to both running time and predictive accuracy. 845 846 The predictive accuracies of Metagol_{CF} and ASP_{MCF}, have no significant difference on ei-847 ther dataset, as shown by the graphs in Figs. 12(a) and 13(a), since both derive globally 848 optimal solutions. However, Metagol_{CF} has shorter running time due to its procedural bias. 849 Therefore Null hypothesis 2.3 is refuted. 850

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⁸⁹⁷ Note also in Fig. 14(b), that the running times of $Metagol_{CF}$ are significantly higher than ⁸⁹⁸ Metagol_{*RCF*}. This can be explained by the fact that when the target grammar is Regular, ⁸⁹⁹ Context-Free grammars were still considered.

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Metagol_N and ASP_{MN} are two systems resulting from the application of Metagol and ASP_M in learning a simplified natural language grammar. We investigate the following Null hypotheses. MC-TopLog was not included for comparison since its search time was excessive in these learning tasks.

- Null Hypothesis 4.1 Metagol_N and ASP_{MN} cannot learn a simplified natural language grammar.
- Null Hypothesis 4.2 Metagol_N cannot outperform ASP_{MN} on learning a simplified natural language grammar.
- Null Hypothesis 4.3 The provision of background knowledge does not improve learning accuracies and efficiency.
- 4.4.1 Materials and methods

The training examples come from the same domain considered in Muggleton et al. (2012) and consist of 50 sentences such as "a ball hits the small dog". Half the examples are posi-tive and half negative, resulting in a default accuracy of 50 %. The complete target grammar rules for parsing the training examples are given in Fig. 15. Each learning task is generated by randomly removing a set of clauses. The left-out clauses become the target to be recon-structed. For each size of leave-out, we sampled ten times. For each sample, the predictive

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Definite Clause Grammar	Production rules
$s(S1, S2) \leftarrow np(S1, S3), vp(S3, S4), np(S4, S2).$	$s \rightarrow s4 s_1$
$s(S1, S2) \leftarrow np(S1, S3), vp(S3, S4), np(S4, S5),$	$s_1 \rightarrow s5 s4$
prep(S5, S6), np(S6, S2).	$s_1 \rightarrow s5 s2$
	$s2 \rightarrow s4 s3$
	$s3 \rightarrow prep \ s4$
$np(S1, S2) \leftarrow det(S1, S3), noun(S3, S2).$	$s4 \rightarrow det noun$
$np(S1, S2) \leftarrow det(S1, S3), adj(S3, S4), noun(S4, S2).$	$s4 \rightarrow det \ s6$
	$s6 \rightarrow adj noun$
$vp(S1, S2) \leftarrow verb(S1, S2).$	$s5 \rightarrow verb$
$vp(S1, S2) \leftarrow verb(S1, S3), prep(S3, S2).$	$s5 \rightarrow verb prep$

Fig. 15 Target theory for simplified natural language grammar



accuracies were computed by 10-fold cross validation.¹² The results plotted on the figure are averaged over all leave-out samples.

4.4.2 Results and discussion

The predictive accuracies and running times are plotted in Figs. 16 and 17 respectively. The x-axis corresponds to the percentage of remaining production rules. More specifically, 0 % corresponds to the case when $B_A = \emptyset$, while 90 % means 9 out of 10 production rules remain. Figure 16 shows that the predictive accuracies of both $Metagol_N$ and ASP_{MN} are significantly higher than default, therefore Null hypothesis 4.1 is refuted.

Although there is no significant difference between $Metagol_N$ and ASP_{MN} in terms of predictive accuracy, ASP_{MN} takes much shorter running time than $Metagol_N$ when more 989 than half of the production rules are missing (x < 50 %). However, the expanded version 990 for 50 % $\leq x \leq$ 90 % in Fig. 17(b) shows that ASP_{MN} becomes slower than Metagol_N when 991 background knowledge is less sparse. Therefore, Null hypothesis 4.2 is refuted since when 992 more than 70 % of the production rules remain Metagol_N has significantly shorter running 993 time than ASP_{MN} without sacrificing its predictive accuracy. This is due to the procedural 994 bias encoded in Metagol_N. 995

The running times of both $Metagol_N$ and ASP_{MN} decrease dramatically with the increase 996 of background knowledge. The predictive accuracies increase with increasing background 997 998

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¹²The size of available examples is 50, therefore not large enough for reserving a subset as test set. 1000

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 s_4 corresponds to np in natural grammars and s_3 is closed to vp. Similarly in H_A , s_3 and s_6 corresponds to vp and np respectively.

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 $staircase(Planes) \leftarrow n_of_parts(Planes, 4), \%$ there are 4 parts in Planes $member(C, Planes), distributed_along(C, axisX).$

Fig. 19 Non-recursive definition of staircase hypothesised by ALEPH (Partial)

First-order logic	Production rules
$staircase(Planes) \leftarrow s_1(Planes).$	staircase $\rightarrow s_1$
$staircase([X, Y, Z Planes]) \leftarrow s_1([X, Y, Z]),$	$staircase \rightarrow s_1 \ staircase$
staircase([Z Planes]).	
$s_1([X, Y, Z]) \leftarrow vertical(X, Z), horizontal(Z, Y)$	$s_1 \rightarrow vertical \ horizontal$

Fig. 20 Recursive definition of staircase hypothesised by MIL. s_1 is an invented predicate corresponding to the concept of *step*

4.5 Learning a definition of a staircase

The authors of Farid and Sammut (2012) have shown that ALEPH can learn a definition of a staircase for a rescue robot from visually-derived data. Part of such definition is shown in Fig. 19. This kind of definition is not entirely general since it does not involve recursion. We now demonstrate that MIL can be used to learn a general recursive definition of a staircase using predicate invention. A staircase can be represented by a set of ordered planes. For example, staircase([p1, p2, p3]) represents a staircase composed of three planes. Relational information from the camera indicates that *plane1* is vertical relative to *plane2*. This can be encoded as a delta rule *delta*4(*vertical*, p1, p2), where *vertical* is a non-terminal of a grammar and p1 and p2 are terminals. The meta-interpreter used in this experiment is a variant of the Context-Free Meta-interpreter from Fig. 3.

Training examples of staircases and their planar description were provided as input to both Metagol and ASP_M. The resulting hypothesis produced by both systems is shown in Fig. 20, where s_1 is an invented predicate corresponding to *step*. Due to its recursive form, this definition has shorter description length than those found by ALEPH. It is also general in its applicability and easily understood.

5 Related work

Grammatical inference (or grammatical induction) is the process of learning a grammar from
 a set of examples. It is closely related to the fields of machine learning as well as the theory of
 formal languages. It has numerous real-world applications including speech recognition (e.g.
 Stolcke 1995), computational linguistics (e.g. Florêncio 2002) and computational biology
 (e.g. Salvador and Benedi 2002).

The problem of learning or inferring Regular languages, which can be represented by deterministic finite state automata, has been well studied and efficient automaton-based learn-1092 ing algorithms have existed since the 1950s (Moore 1956). Some heuristic approaches to 1093 machine learning context-free grammars (Vanlehn and Ball 1987; Langley and Stromsten 2000) have been investigated, though the completeness of these approaches is unclear. Al-1095 though an efficient and complete approach exists for learning context-free grammars from 1096 parse trees (Sakakibara 1992), no comparable complete approach exists in the literature for learning context-free grammars from positive and negative samples of the language. Ac-1098 cording to a recent survey article learning context-free languages is widely believed to be intractable and the state of the art mainly consists of negative results (de la Higuera 2005). 1100

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There are some positive PAC (probably approximately correct) learning results concerning Regular languages (e.g. Denis 2001), but to the best of our knowledge, these have not been extended to the context-free case. The difficulty of learning context-free languages arises from a very large search space compared to regular languages.

ILP, among other learning methods, has previously been applied to grammatical inference (e.g. Boström 1998). However, as discussed in Sect. 1, ILP systems normally require predicate invention even for learning Regular languages. Predicate invention has been viewed as an important problem since the early days of ILP (e.g. Muggleton and Buntine 1988), but it is widely accepted to be a hard and under-explored topic within ILP (Muggleton et al. 2011). Although Cussens and Pulman (2000) has applied ALEPH for learning natural language grammar, its learning setting avoids predicate invention by assuming all predicates like np (noun phrase) are known in the background knowledge. Additionally, the entailment-incompleteness of ALEPH restricts the applicability of the approach.

In the Meta-interpretive Learning (MIL) framework introduced in this paper, predicate invention is done via abduction with respect to a meta-interpreter and by the introduction of first-order variables. This method is therefore related to other studies where abduction has been used for predicate invention. For instance, (Inoue et al. 2010) assumes background knowledge such as the following.

$$caused(X, Y) \leftarrow connected(X, Y).$$

 $caused(X, Y) \leftarrow connected(X, Z), caused(Z, Y).$

Here the predicates connected and caused are both meta-predicates for object-level propositions g and s. Given multiple observations such as caused(g, s) and caused(h, s) abduction can be used to generate an explanation

$\exists X (connected(g, X), connected(h, X), connected(X, s))$

in which X can be thought of as a new propositional predicate. One important feature of MIL, which makes it distinct from this approach, is that it introduces new predicate symbols which represent relations rather than new objects or propositions. In comparison to previous approaches to predicate invention one might question what is meant by the predicate symbols being *new*. In our case, we assume a source containing either a finite or an infinite source (e.g. the natural numbers) of uninterpreted predicate symbols. Rather than providing these implicitly in hidden code (as was the case in CIGOL (Muggleton and Buntine 1988)), we prefer to have these symbols explicitly defined as part of the Herbrand universe of the meta-interpreter. Abductive hypothesis formation then provides the interpretation for these otherwise uninterpreted symbols.

6 Conclusions and further work

This paper explores the theory, implementation and experimental application of a new framework (MIL) for machine learning by abduction with respect to a given Metainterpreter. We have demonstrated that the MIL framework can be implemented using a simple Prolog program or within a more sophisticated solver such as ASP. We have applied these implementations to the problem of inductive inference of grammars, where our ex-1148 periments indicate that they compete favourably in speed and accuracy with the state of the 1149 art ILP system MC-TopLog. The MIL framework has a number of advantages with respect 1150

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to the standard ILP framework. In particular, predicate invention and mutual recursion can be incorporated with ease by way of Skolem constants. The Meta-interpreter provides an efficient declarative bias mechanism for controlling the search for hypotheses, which takes advantage of the completeness of SLD resolution in Prolog. This mechanism is distinct from the use of first-order declarative bias in the form of a \top theory (Muggleton et al. 2010, 2012) since it is not assumed that the meta-interpreter entails each hypothesis.

The approach presented here is limited to learning grammars in the form of DCGs. Such grammars can be learned with predicates of arity at most 2. In future work we hope to deal with a number of extensions of this study. In particular, we would like to extend the applications of the MIL framework to non-grammar fragments of first-order logic. We have shown an example of non-grammar learning, but more general learning problem requires Monadic and Dyadic and higher arity fragments of first-order logic. We would like to incorporate a number of other features of ILP and SRL learning systems such as probabilistic parameters (similar to SRL) and noise handling.

Clearly devising an appropriate meta-interpreter for a fragment of logic other than those studied in this paper will require careful mathematical analysis. The situation may be compared to that within Support Vector Machines, in which certain mathematical properties have to be established for each new form of kernel function. Hopefully, over time, such a process will become more routine and it may be possible to provide end users with general tools which support this activity. In the ideal case, we would like in future work, to develop a meta-interpreter which is capable of implementing highly expressive, ideally Turing-complete, languages. Such a meta-interpreter might then be reasonably expected to learn effectively on arbitrary new problems without further manual revision of its meta-interpreter.

In closing we believe the MIL framework provides a promising and novel form of Inductive Logic Programming which avoids a number of the bottlenecks of existing approaches.

1178 1179 **References**

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