Intersection Types for λ-Trees

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Abstract

We introduce a type assignment system which is parametric with respect to five families of trees obtained by evaluating λ-terms (Böhm trees, Lévy-Longo trees, ...). Then we prove, in an (almost) uniform way, that each type assignment system fully describes the observational equivalences induced by the corresponding tree representation of terms. More precisely, for each family of trees, two terms have the same tree if and only if they get assigned the same types in the corresponding type assignment system.

keywords: Böhm trees, approximants, intersection types.

1 Introduction

A theory of functions like the λ-calculus, which provides a foundation for the functional programming paradigm in computer science, can be seen, essentially, as a theory of 'programs'. This point of view leads naturally to the intuitive idea that the meaning of a λ-term (program) is represented by the amount of 'meaningful information' we can extract from that term by 'running it'. The formalization of 'the information' obtained from a term requires, first, the definition of what is, in a λ-term, a 'stable relevant minimal information' that is directly observable in the term. This is the token of information which cannot be altered by further reductions but can only be added upon. (As an example, the reader may think of the calculation of $\sqrt{2}$. The calculation process merely adds decimals to the already calculated decimal expansion).

If one organizes the stable relevant minimal information produced during a computation according to the order in which it is obtained, it is quite natural to get a tree representation of the information implicitly contained in the original term. This tree then embodies the total information hidden in the original term. There are many such tree representations in literature, depending on the possible notions of stable relevant minimal information; the most commonly used being *top* trees (or Berarducci trees [6]), *weak* trees (or Lévy-Longo trees [25]), *head* trees (or Böhm trees [4]), *eta* trees and *infinite eta* trees (*infinite eta* trees are in one-one correspondence with Nakajima trees [23]). Hence, the various notions of tree represent different notions of *meaning of a term* (in particular, they specify different notions of *undefined* value [20]).

This apparently vague intuition is substantiated by results starting with [29], which show that there exist precise correspondences between the tree representations of terms and the local structures (or, equivalently, the λ-theories) of certain λ-models ([4], Chapter 19). In particular, such correspondences amount to the fact that two λ-terms have the same tree representation if and only if they are equal in the λ-model. For example,

- the *infinite eta* trees represent the local structure of Scott's D_∞ model as defined in [26] (this result was proved in [29]);
- the *eta* trees represent the local structure of the inverse limit model defined in [12];
- the *head* trees represent the local structure of Scott's P_ω model as defined in [27] (a discussion on this topic can be found in [4], Chapter 19);
- the *weak* trees were introduced by Longo in [22] (following [21]), who proved that they represent the local structure of Engeler's models as defined in [17].

Orthogonally, the results about observational equivalences confirm this operational intuition of *dynamically* evolving meanings of terms incorporated in the tree representations. For instance, in [29] Wadsworth showed that two λ-terms M, N have the same *infinite eta* tree if and only if, for all contexts $C[\ ]$, the following holds:

$$C[M] \text{ has a head normal form if and only if } C[N] \text{ has a head normal form.}$$

The same property holds even considering *eta* trees and normal forms [18]. By adding a non-deterministic choice operator and an adequate numeral system to the pure calculus, we obtain a language which internally discriminates two λ-terms if and only if they have different *head* trees [14]. *Weak* trees correspond to the observational equivalence with respect to weak head normal forms in suitably enriched versions of the λ-calculus [25, 9, 16]. We can discriminate terms in the same way that top trees do, using two powerful δ-rules [15].

It is clear that most of the relevant properties of terms pertain, more or less strongly, to the field of *dynamics*, i.e., to their computational behaviour. This, however, does not mean that we have to, staying into a 'physics metaphor', disregard the *statics*: the objects of a theory of programs (before we 'run' them), are static entities and, as such, differently from the more or less ineffable *computations*, they can be 'handled'.

It would be very useful if these dynamic aspects could be analyzed with tools dealing with static entities like, for instance, *terms* and *types*.

All the results recalled above show that our dynamic world can be partially reduced to a world of trees. Trees are objects a bit more concrete than *computations*, but still not very manageable. Type assignment disciplines are typical static tools, much used in the programming practice to check decidable properties of programs. There are several results showing how very powerful typing disciplines can be devised that, at the (of course expected) price of being undecidable, can be used to analyze the dynamic world. For instance, the observational equivalences induced by a number of tree representations of terms can be mimicked by suitable type theories:

- Each inverse limit λ-model is isomorphic to a filter model, i.e., to a model in which the meaning of terms is a set of derivable intersection types [10].
- Two terms have the same *head* tree if and only if they have the same set of types in the standard intersection type discipline [5], as proved in [24].
- Two terms have the same *weak* tree if and only if they have the same set of types in the type discipline with union and intersection of [13], as proved in [16].
- Two terms have the same *top* tree if and only if they have the same set of types in a type assignment system with applicative types [7].

In the present paper we will design one type assignment system for each of the five families of trees mentioned above (more precisely, a type assignment system (almost) parametric with respect to these five families). For each family of trees we will show that two terms have the same tree, if and only if they get assigned the same types in the corresponding type assignment system.

This is a new result for the *eta* trees and the *infinite eta* trees. Moreover, our proof method unifies the earlier proofs mentioned above, while making the following improvements:

- we simplify the types of [24], since we do not consider type variables;
- we do not allow the union type constructor (which is considered in [16]);
- the applicative types are built starting from just one constant instead of two (this was the choice of [7]).

All the type systems we will introduce (apart from those that represent *top* trees) induce filter λ-models in the sense of [5]. Clearly, the theories of these filter models coincide with the equalities of the corresponding trees. So as by-product we obtain alternative proofs of the characterizations of the theories of Scott's D_∞ model [29] and of the filter λ-model [24]. Notice that these new proofs (unlike the original ones) are constructive, in the sense that, whenever two terms have different interpretations, we will build a compact element d of the model such that d approximates only the interpretation of one of the two terms. Indeed, d is the principal filter induced by a type which can be deduced only for one of the two terms.

The long-term goal of this research is to find answers to the question 'what can be added to the pure λ-calculus in order to internally discriminate terms having different trees?', which can be formulated for each family of trees.

Intersection type assignment systems played a crucial role in showing that observational equivalences in suitable extensions of λ-calculus are equivalent to *head* and *weak* tree equality [9, 14, 16]. We hope that similar results can be obtained for the other families of trees; this would justify the present choices. A very limited number of type constants and type constructors allows to search for a proof along the following lines. Suppose we were able to define, for each type α, a test term $\mathbf{T}_\alpha$ such that $\mathbf{T}_\alpha M$ converges if and only if M has type α. Then we would obtain an observational equivalence which coincides with the tree equality (see [8]).

Thisfor paper is organized as follows. In Section 2 we shall recall the various definitions of tree. We will introduce the notion of *approximant* in Section 3. In Section 4 we will describe the type assignment systems which will be used for our main result and we will give a theorem of approximation stating that a term has a type if and only if there exists an approximant of the term which has the same type. Section 5, instead, contains our main result: our type assignment systems can be used to analyze the observational behaviour represented by trees.

A preliminary version of this paper has appeared in [3], where almost all proofs were omitted.

Abbreviations

Below, we will use the following abbreviations for lambda terms.

$$\mathbf{Y} \equiv \lambda f.f((\lambda x.f(xx))(\lambda x.f(xx))) \qquad \mathbf{R} \equiv \lambda zxy.x(zzy)$$

$$\mathbf{I} \equiv \lambda x.x \qquad \mathbf{\Delta_n} \equiv \lambda x.\overbrace{x\ldots x}^{n}$$

$$\mathbf{\Omega_n} \equiv \overbrace{\mathbf{\Delta_n}\ldots\mathbf{\Delta_n}}^{n} \qquad \mathbf{\Delta_2^J} \equiv \lambda xy.xxy$$

2 Trees

In this section we recall the various notions of trees which can be obtained by evaluating λ-terms. As briefly discussed in the introduction, in order to describe trees, it is natural to formalise first the intuitive possible notions of *stable relevant minimal information* coming out of a computation (naturally inducing different notions of *meaningless term* [20]).

If during a computation the following terms appear, their underlined parts will remain stable during the rest (if any) of the computation: $\underline{x}M_1 \ldots M_m$, $\underline{\lambda x.}M$, $P\underline{@}Q$ (where @ is the explicit representation of the operation of application that is normally omitted, and P is a term which will never reduce to an abstraction). Having a *stable* part in a computation, however, does not necessarily mean that we consider it *relevant*. For instance, we could consider an abstraction $(\underline{\lambda x.}M)$ relevant only in case M is of the form $\lambda y_1 \ldots y_n.zN_1 \ldots N_m$ $(n,m \geq 0)$. This means that we can end up with different notions of *stable relevant minimal information*.

In order to formalise such notions it is possible to define for each notion a reduction relation such that:

i) if a term can produce stable relevant minimal information, we can get it by means of the given reduction relation;

ii) the computation process represented by the reduction relation stops once stable relevant minimal information is obtained.

In the following we will give a number of reduction relations for λ-terms present in the literature. All are proper restrictions of the usual $\beta\eta$-reduction relation. Syntax, basic notation of the λ-calculus and the usual conventions on variables to avoid explicit α-conversion are as in [4].

A term is a *strong zero term* if it is unsolvable and it cannot be reduced to a lambda abstraction by means of the reduction relation induced by the β-rule [6]. Such terms are called *unsolvables of order* 0 in [22] and *strongly unsolvables* in [1].

Definition 2.1 Given the following axioms and rules:

$$\begin{array}{llll}
(\beta) & (\lambda x.M)N & \rightarrow & M[N/x] \\
(\eta) & \lambda x.Mx & \rightarrow & M \qquad \text{if } x \notin FV(M) \\
(\nu) & M \rightarrow N & \Rightarrow & ML \rightarrow NL \\
(\nu)_{\mathtt{t}} & M \rightarrow N & \Rightarrow & ML \rightarrow NL \qquad \textit{(provided } M \textit{ is not a strong zero term)} \\
(\xi) & M \rightarrow N & \Rightarrow & \lambda x.M \rightarrow \lambda x.N
\end{array}$$

we can define the following reduction relations (RR) on λ-terms.

$$\begin{array}{rll}
(\textit{top reduction}) & \rightarrow_{\mathtt{t}} & \text{is the RR induced by } (\beta) \textit{ and } (\nu)_{\mathtt{t}} \\
(\textit{weak head reduction}) & \rightarrow_{\mathtt{w}} & \text{is the RR induced by } (\beta) \textit{ and } (\nu) \\
(\textit{head reduction}) & \rightarrow_{\mathtt{h}} & \text{is the RR induced by } (\beta),(\nu) \textit{ and } (\xi) \\
(\textit{eta head reduction}) & \rightarrow_{\mathtt{e}} & \text{is the RR induced by } (\beta),(\nu),(\xi) \textit{ and } (\eta).
\end{array}$$

The weak head reduction is better known as *lazy reduction* [1].

The sets of terms in normal form with respect to the above defined reduction relations can be described syntactically. Such description makes the different intended notions of stable minimal relevant information explicit.

Definition 2.2 *i*) A *top normal form*[1] is a term of one of the following three kinds:

a) an application term of the form $xM_1 \dots M_m$ $(m \geq 0)$;

b) an abstraction term $\lambda x.M$;

c) an application term of the form MN, where M is a strong zero term.

ii) A *weak head normal form* is a term of one of the following two kinds:

a) an application term of the form $xM_1 \dots M_m$ $(m \geq 0)$;

b) an abstraction term $\lambda x.M$.

iii) A *head normal form* is a term of the following kind:

a) $\lambda x_1 \dots x_n.yM_1 \dots M_m$ $(m, n \geq 0)$.

iv) An *eta head normal form* is a term of the following kind:

a) $\lambda x_1 \dots x_n.yM_1 \dots M_m$ $(m, n \geq 0)$, where $x_n \in FV(yM_1 \dots M_{m-1})$ or $x_n \not\equiv M_m$.

Notice that the sets of normal forms in the above definition are presented in a proper inclusion order, i.e., the set of top normal forms includes that of weak head normal forms, etc.

Example 2.3 *i*) For each $n \geq 2$, the term $\mathbf{\Omega_n}$ is an example of a strong zero term.

ii) $\mathbf{\Omega_2}$ is not a top normal form, while all $\mathbf{\Omega_n}$ (for $n \geq 3$) are top normal forms that cannot reduce to weak head normal forms.

iii) $\lambda x.\mathbf{\Omega_2}$ is a weak head normal form that cannot reduce to head normal form.

iv) $\mathbf{\Delta_2^I}$ is a head normal form but not an eta head normal form.

v) $\mathbf{Y}$ and $\lambda xy.x\mathbf{RR}y$ are eta head normal forms.

With this definition we can represent all the various related kinds of information we can distract from a term in tree notation. Given a term M, for each of the four reduction relations we can try to reduce M to normal form. If such a normal form does not exist, then no information is obtainable out of M and its tree is $\perp$. Otherwise, we will put the information thus obtained in a node and build the children of this node by repeating this process on the various subterms of the normal form. In case of head normal forms, this amounts to the usual construction of Böhm trees.

Definition 2.4 *i*) The *top tree* $\mathcal{T}_{\mathrm{t}}(M)$ of a term M is defined by cases as follows:

– if $M \to_{\mathrm{t}} xN_1 \dots N_m$ $(m \geq 0)$, then

$$\mathcal{T}_{\mathrm{t}}(M) = \begin{array}{ccc} & x & \\ \diagup & & \diagdown \\ \mathcal{T}_{\mathrm{t}}(N_1) & \dots & \mathcal{T}_{\mathrm{t}}(N_m) \end{array}$$

– if $M \to_{\mathrm{t}} \lambda x.N$, then

$$\mathcal{T}_{\mathrm{t}}(M) = \begin{array}{c} \lambda x \\ | \\ \mathcal{T}_{\mathrm{t}}(N) \end{array}$$

[1] Called *root stable form* in [19].

– if $M \to_{\mathtt{t}} NP$, where N is a strong zero term, then

$$\mathcal{T}_{\mathtt{t}}(M) = \begin{array}{ccc} & @ & \\ \diagup & & \diagdown \\ \mathcal{T}_{\mathtt{t}}(N) & & \mathcal{T}_{\mathtt{t}}(P) \end{array}$$

– otherwise: $\mathcal{T}_{\mathtt{t}}(M) = \bot$.

ii) The *weak tree* $\mathcal{T}_{\mathtt{w}}(M)$ of a term M is defined by cases as follows:

– if $M \to_{\mathtt{w}} xN_1 \ldots N_m$ $(m \geq 0)$, then

$$\mathcal{T}_{\mathtt{w}}(M) = \begin{array}{ccccc} & & x & & \\ & \diagup & & \diagdown & \\ \mathcal{T}_{\mathtt{w}}(N_1) & & \ldots & & \mathcal{T}_{\mathtt{w}}(N_m) \end{array}$$

– if $M \to_{\mathtt{w}} \lambda x.N$, then

$$\mathcal{T}_{\mathtt{w}}(M) = \begin{array}{c} \lambda x \\ | \\ \mathcal{T}_{\mathtt{w}}(N) \end{array}$$

– otherwise: $\mathcal{T}_{\mathtt{w}}(M) = \bot$.

iii) The *head tree* $\mathcal{T}_{\mathtt{h}}(M)$ of a term M is defined by cases as follows:

– if $M \to_{\mathtt{h}} \lambda x_1 \ldots x_n.yN_1 \ldots N_m$ $(n, m \geq 0)$, then

$$\mathcal{T}_{\mathtt{h}}(M) = \begin{array}{ccccc} & & \lambda x_1 \ldots x_n.y & & \\ & \diagup & & \diagdown & \\ \mathcal{T}_{\mathtt{h}}(N_1) & & \ldots & & \mathcal{T}_{\mathtt{h}}(N_m) \end{array}$$

– otherwise: $\mathcal{T}_{\mathtt{h}}(M) = \bot$.

iv) Let T be a head tree, i.e., $T \equiv \mathcal{T}_{\mathtt{h}}(M)$, for some M. The *η-normal form* of T, $\eta(T)$, is defined as follows:

– $$\eta\left(\begin{array}{ccccc} & & \lambda x_1 \ldots x_n.y & & \\ & \diagup & & \diagdown & \\ T_1 & & \ldots & & T_m \end{array}\right) = \begin{cases} \eta\left(\begin{array}{ccccc} & & \lambda x_1 \ldots x_{n-1}.y & & \\ & \diagup & & \diagdown & \\ T_1 & & \ldots & & T_{m-1} \end{array}\right) & \text{proviso } T_m \text{ is finite, } \eta(T_m) = x_n \neq y \text{ and } x_n \notin FV(T_i) \text{ for } 1 \leq i \leq m-1. \\ \begin{array}{ccccc} & & \lambda x_1 \ldots x_n.y & & \\ & \diagup & & \diagdown & \\ \eta(T_1) & & \ldots & & \eta(T_m) \end{array} & \text{otherwise} \end{cases}$$

– $\eta(\bot) = \bot$.

The *eta tree* $\mathcal{T}_{\mathtt{e}}(M)$ of a term M is defined as $\eta(\mathcal{T}_{\mathtt{h}}(M))$.

The condition 'T_m is finite' in the above definition is obviously necessary in order to make the latter sound, but it can be easily checked that, in its intended meaning, an η-normal form of a *head* tree can be a variable only when the tree is finite.

One might wonder why the *eta* tree of M is defined through the η-normal form of the *head* tree of M instead of using the η-normal form of M. As a matter of fact, considering trees instead of terms allows to do more η-reductions, essentially since the set of variables

$$
\begin{array}{rl}
\lambda zx.x(Pz) & \to_\beta \ \lambda xz.x((\lambda z.x(Pz))z)z \\
 & \to_\beta \ \lambda xz.x(x(Pz))z \\
 & \to_\beta \ \lambda xz.x(x((\lambda z.x(Pz))z))z \\
 & \to_\beta \ \lambda xz.x(x(x(Pz)))z \\
 & \to_\beta \\
 & \dots \\
 & \to_\beta \ \lambda xz.x(x(x(x(\cdots))))z
\end{array}
$$

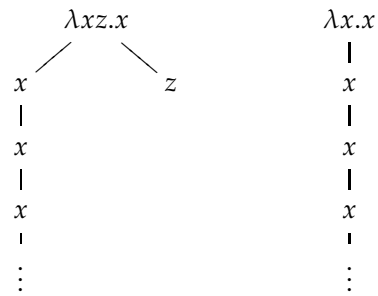


Figure 1: Reduction path, head tree and eta tree for $\lambda xz.x(Pz)z$, where $P \to_\beta \lambda z.x(Pz)$.

which occur free in $\mathcal{T}_{\mathtt{h}}(M)$ is a *subset* of the set of variables which occur free in M. This was already observed in [4], Remark 10.1.22. Borrowing the example given there, let P be such that $P \to_\beta \lambda z.x(Pz)$, then $\lambda xz.x(Pz)z$ has the reduction behaviour and *head* tree as shown in Figure 1. Now, since, as mentioned in [4], there "*z is pushed into infinity*", this tree contains only *one* z, and is therefore an η-redex. This is reflected by the fact that the *eta* tree of the term $\lambda xz.x(Pz)z$ is as in Figure 1.

Finally, the fifth family of trees we shall consider in this paper is the family of the *infinite η-normal forms* of *head* trees (and hence of *eta* trees as well), as defined in [4]. In order to give the definition of *infinite η-normal form*, we need first to recall briefly the definition of *infinite η-expansion* of a variable. Given a variable x, one can consider a (possibly infinite) tree resulting by the limit of a series of expansions like the following:

$$x \ {}_\eta\!\leftarrow \ \mathcal{T}_{\mathtt{h}}(\lambda y_0.xy_0) \ \ {}_\eta\!\leftarrow \ \mathcal{T}_{\mathtt{h}}(\lambda y_0.x(\lambda y_1.y_0y_1)) \ \ {}_\eta\!\leftarrow \ \dots$$

We denote that T is a (possibly infinite) η-expansion of x by $T \geq_\eta x$.

The definition of $\geq_\eta$ requires a formalization of the notion of labeled tree which is given in Definition 5.15 in the Appendix.

Definition 2.5 Let T be a *head* tree, i.e., $T \equiv \mathcal{T}_{\mathtt{h}}(M)$, for some M. The *infinite η-normal form* of T, $\eta_\infty(T)$, is defined as follows:

- $$\eta_\infty\left(\begin{array}{c} \lambda x_1 \dots x_n.y \\ T_1 \quad \dots \quad T_m \end{array}\right) = \begin{cases} \eta_\infty\left(\begin{array}{c} \lambda x_1 \dots x_{n-1}.y \\ T_1 \quad \dots \quad T_{m-1} \end{array}\right) & \text{proviso } T_m \geq_\eta x_n, \ x_n \neq y \text{ and } x_n \notin FV(T_i), \text{ for } 1 \leq i \leq m-1 \\ \begin{array}{c} \lambda x_1 \dots x_n.y \\ \eta_\infty(T_1) \quad \dots \quad \eta_\infty(T_m) \end{array} & \text{otherwise} \end{cases}$$
- $\eta_\infty(\bot) = \bot$.

The *infinite eta tree* $\mathcal{T}_{\mathtt{i}}(M)$ of a term M is defined as $\eta_\infty(\mathcal{T}_{\mathtt{h}}(M))$.

As mentioned in the introduction, the interest of the tree representations above is that they mimic the local structure (or, equivalently, the λ-theory) of different λ-models.

Example 2.6 In Figure 2 we give a few examples of the trees defined above (using the terms of Example 2.3). They show how trees become less discriminating as we use reduction relations with more rules.

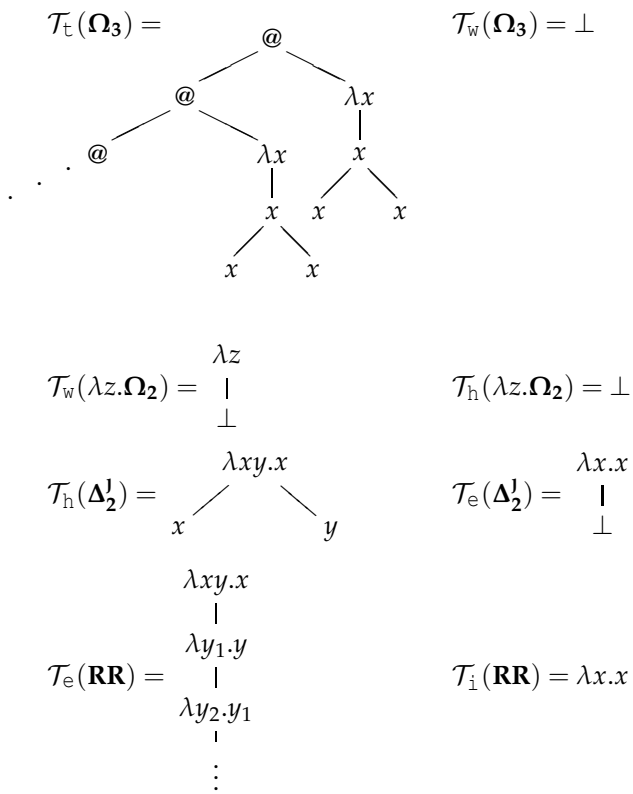


Figure 2: Trees for Example 2.6

We will use $\mathcal{T}_\varphi$, with $\varphi \in \{\mathtt{t},\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$, to denote the set of trees $\mathcal{T}_\varphi(M)$, for some $M \in \Lambda$. Moreover, 'φ-tree' will be short for any tree belonging to $\mathcal{T}_\varphi$. Unless mentioned otherwise, we will assume φ to range over $\{\mathtt{t},\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$.

3 Approximants

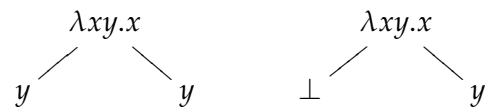
It is possible to associate, for any possible notion of stable minimal relevant information, a set of approximants to a λ-term. As usual when dealing with (possibly) infinite structures, one can consider their finite approximations. Consider two possible approaches to the definition of approximations of a term M.

- Consider all possible finite trees obtained by pruning the φ-tree of M (constant $\bot$ is used to represent the (possibly infinite) parts of the trees that have been pruned). Call all these pruned trees φ-approximants of M.
- Consider all possible terms that occur in φ-reduction sequences starting from M (for $\varphi \in \{\mathtt{w},\mathtt{h}\}$, we should also extend the notion of $\rightarrow_\varphi$-reduction to $\Lambda_\bot$ by adding the clause $\bot M \rightarrow \bot$, and add $\lambda x.\bot \rightarrow \bot$ for $\varphi \in \{\mathtt{h}\}$), and calculate their direct approximants (a direct approximant for N is obtained from N by (recursively) replacing (potential) φ-redexes, like $\bot M$ and $\lambda x.\bot$, by $\bot$; to clarify this, one could see this a generalization of $\beta\bot$-reduction [4]). The φ-approximants of M are now all terms in normal form – with respect to suitable notions of normal form – including $\bot$ that are smaller than those direct approximants.

In the context of β-reduction, these approaches coincide, i.e., for any term M yield the same set.

In the presence of rule (η), both definitions give rise to problems. First of all, in a system with η-reduction, no longer every pruned subtree of the normal form is in normal form itself, a property that holds in a system with just β-reduction. This is caused by the fact that *the number of free occurrences* of a variable will normally decrease by pruning, which affects whether or not a term is an η-redex.

Example 3.1 Take the term $\lambda xy.xyy$. The tree below on the left is the *eta* tree of this term, the one on the right is obtained by pruning the first y.



The term in the right-hand tree, $\lambda xy.x\bot y$, is η-reducible.

Also, in the context of η-reduction, the two approaches no longer coincide. For example, take $\mathbf{P}$ as defined above. Collecting 'all pruned subtrees' of the *eta* tree of $\lambda xz.x(\mathbf{P}z)z$ yields the set

$$\{\bot, \lambda x.x\bot, \lambda x.x(x\bot), \lambda x.x(x(x\bot)), \ldots\}$$

whereas 'calculate the direct approximants of terms that occur in reduction sequences that start from $\lambda zx.x(\mathbf{P}z)z$' would yield $\{\bot\}$. To understand this, notice that

- none of the reducts of $\lambda xz.x(\mathbf{P}z)z$ is an η-redex, since in all those terms, z appears twice, and
- replacing the redex $\mathbf{P}z$ by $\bot$ in each reduct creates a term that is an η-redex; therefore, for all terms in the sequence, its direct $\beta\eta$-approximant would be $\bot$.

The first set is obviously a better collection of approximants of the infinite tree. Therefore we choose the first approach to define the set of approximants.

Let $\Lambda_\bot$ be the set of terms obtained by adding the symbol $\bot$ to the syntax of the pure λ-calculus. Clearly the tree representations generalise to terms in $\Lambda_\bot$ by assuming $\mathcal{T}_\varphi(\bot) = \bot$. This leaves the set of trees unchanged, i.e., for all $M \in \Lambda_\bot$, there is an $M' \in \Lambda$ such that $\mathcal{T}_\varphi(M) = \mathcal{T}_\varphi(M')$. In fact, M' can be obtained from M by substituting $\mathbf{\Omega_2}$ for $\bot$.

Definition 3.2 We inductively define the set $\mathcal{A}_\varphi \subseteq \Lambda_\bot$ of approximate normal forms as follows

i) $\mathcal{A}_{\mathtt{t}}$ is the smallest subset of $\Lambda_\bot$ such that
  a) if $A_1, \ldots, A_n \in \mathcal{A}_{\mathtt{t}}$, then $xA_1 \ldots A_n \in \mathcal{A}_{\mathtt{t}}$ and $\bot A_1 \ldots A_n \in \mathcal{A}_{\mathtt{t}}$ $(n \geq 0)$,
  b) if $A \in \mathcal{A}_{\mathtt{t}}$, then $\lambda x.A \in \mathcal{A}_{\mathtt{t}}$.

ii) $\mathcal{A}_{\mathtt{w}}$ is the smallest subset of $\Lambda_\bot$ such that
  a) $\bot \in \mathcal{A}_{\mathtt{w}}$,
  b) if $A_1, \ldots, A_n \in \mathcal{A}_{\mathtt{w}}$, then $xA_1 \ldots A_n \in \mathcal{A}_{\mathtt{w}}$ $(n \geq 0)$,
  c) if $A \in \mathcal{A}_{\mathtt{w}}$, then $\lambda x.A \in \mathcal{A}_{\mathtt{w}}$.

iii) $\mathcal{A}_{\mathtt{h}}$ is the smallest subset of $\Lambda_\bot$ such that
  a) $\bot \in \mathcal{A}_{\mathtt{h}}$,
  b) if $A_1, \ldots, A_n \in \mathcal{A}_{\mathtt{h}}$, then $\lambda y_1 \ldots y_m.xA_1 \ldots A_n \in \mathcal{A}_{\mathtt{h}}$ $(m, n \geq 0)$.

iv) $\mathcal{A}_{\mathtt{e}} = \mathcal{A}_{\mathtt{i}} = \mathcal{A}_{\mathtt{h}}$.

We denote the set of approximate normal forms with at most n symbols by $\mathcal{A}_\varphi^{(n)}$.

Let $(M)_\varphi^{(h)}$, where $M \in \Lambda_\perp$, denote the approximate normal form whose φ-tree is the tree obtained out of $\mathcal{T}_\varphi(M)$ by pruning it at height h and inserting the constant $\perp$ as leaves at the end of the cut edges. The formal definition of $(M)_\varphi^{(h)}$ is given in the Appendix (Definition 5.16).

It is straightforward to verify that $(M)_\varphi^{(h)} \in \mathcal{A}_\varphi$, for all M. For instance, by looking at $\mathcal{T}_{\mathtt{t}}(\mathbf{\Delta_3\Delta_3})$ described above, it is easy to see that $(\mathbf{\Delta_3\Delta_3})_{\mathtt{t}}^{(h)}$, for $h = 0,1,2,3$, are respectively $\perp$, $\perp\perp$, $\perp\perp(\lambda x.\perp)$ and $\perp\perp(\lambda x.\perp)(\lambda x.x\perp\perp)$.

There is a natural partial order between approximants which can be easily formalised by induction.

Definition 3.3 The relation $\preceq_\varphi$ is the least partial order on $\mathcal{A}_\varphi$, such that:

i) $\perp \preceq_\varphi A$;

ii) if $A \preceq_\varphi A'$, then $\lambda x.A \preceq_\varphi \lambda x.A'$;

iii) if $A \preceq_\varphi A'$ and $B \preceq_\varphi B'$, then $AB \preceq_\varphi A'B'$.

It is easy to verify that $(M)_\varphi^{(h)} \preceq_\varphi (M)_\varphi^{(h+1)}$, for all h. Moreover, pruning trees preserves this order, i.e., if $A \preceq_\varphi B$, then $(A)_\varphi^{(h)} \preceq_\varphi (B)_\varphi^{(h)}$, for all h.

It is possible to associate to a λ-term, for any possible notion of stable minimal relevant information, the set of its approximants, that is the set of all the finite approximations of its corresponding tree.

Definition 3.4 The *set $\mathcal{A}_\varphi(M)$ of approximants of $M \in \Lambda$ with respect to the reduction relation φ* is defined by:

$$\mathcal{A}_\varphi(M) = \{A \in \mathcal{A}_\varphi \mid \exists h.A \preceq_\varphi (M)_\varphi^{(h)}\}.$$

Example 3.5 • $\mathcal{A}_{\mathtt{t}}(x(\mathbf{\Omega}_3\mathbf{I})(\mathbf{II}))$ contains, for example, approximants like

$$\perp, x\perp\perp, x(\perp\mathbf{I})\mathbf{I}, x(\perp\mathbf{\Delta}_3\mathbf{I})\mathbf{I}, x(\perp\mathbf{\Delta}_3\mathbf{\Delta}_3\mathbf{I})\mathbf{I}.$$

- $\mathcal{A}_{\mathtt{w}}(\mathbf{I}) = \{\perp, \lambda x.\perp, \mathbf{I}\}$ while $\mathcal{A}_{\mathtt{h}}(\mathbf{I}) = \mathcal{A}_{\mathtt{e}}(\mathbf{I}) = \{\perp, \mathbf{I}\}$.
- $\mathcal{A}_{\mathtt{h}}(\lambda xy.xy) = \{\perp, \lambda xy.x\perp, \lambda xy.xy\}$ while $\mathcal{A}_{\mathtt{e}}(\lambda xy.xy) = \{\perp, \mathbf{I}\}$.
- For any term P such that $P \to_\beta \lambda z.x(Pz)$,

$$\mathcal{A}_{\mathtt{e}}(\lambda xz.x(Pz)z) = \{\perp, \lambda x.x\perp, \lambda x.x(x\perp), \ldots\}$$

- $\mathcal{A}_{\mathtt{i}}(\mathbf{RR}) = \{\perp, \mathbf{I}\}$, while both sets $\mathcal{A}_{\mathtt{h}}(\mathbf{RR})$ and $\mathcal{A}_{\mathtt{e}}(\mathbf{RR})$ are infinite and contain, for instance, $\perp, \lambda xy.x\perp$, and $\lambda xy.x(\lambda y_1.y\perp)$.

Lemma 3.6 The set *$\mathcal{A}_\varphi(M)$ is an ideal, i.e., it is downward closed and directed with respect to $\preceq_\varphi$.*

Proof: $\mathcal{A}_\varphi(M)$ is downward closed by definition. The fact that $\mathcal{A}_\varphi(M)$ is directed, for all M, follows from the observation that $(M)_\varphi^{(h)} \preceq_\varphi (M)_\varphi^{(k)}$ whenever $h \leq k$. □

Lemma 3.7 If $(M)_\varphi^{(h)} \preceq_\varphi A$ where $A \in \mathcal{A}_\varphi(M)$ then $(M)_\varphi^{(h)} \equiv (A)_\varphi^{(h)}$.

Proof: By Definition 3.4, $A \in \mathcal{A}_\varphi(M)$ implies $A \preceq_\varphi (M)_\varphi^{(k)}$, for some $k \geq h$. By construction, $(M)_\varphi^{(h)} \equiv ((M)_\varphi^{(k)})_\varphi^{(h)}$. From $(M)_\varphi^{(h)} \preceq_\varphi A \preceq_\varphi (M)_\varphi^{(k)}$ we get $(M)_\varphi^{(h)} \preceq_\varphi (A)_\varphi^{(h)} \preceq_\varphi ((M)_\varphi^{(k)})_\varphi^{(h)}$, so

we conclude $(M)_\varphi^{(h)} \equiv (A)_\varphi^{(h)}$. □

It is natural to expect that our different notions of trees and approximants represent the very same concepts, that is, they formalise the same observational behaviour of λ-terms.

Theorem 3.8 *For any M, N:*

$$\mathcal{T}_\varphi(M) = \mathcal{T}_\varphi(N) \text{ if and only if } \mathcal{A}_\varphi(M) = \mathcal{A}_\varphi(N).$$

Proof: $(\Leftarrow)$: Reasoning towards a contradiction, we assume that $\mathcal{A}_\varphi(M) = \mathcal{A}_\varphi(N)$ and $(M)_\varphi^{(h)} \not\equiv (N)_\varphi^{(h)}$, for some h. We get $(M)_\varphi^{(h)} \in \mathcal{A}_\varphi(N)$, i.e., by definition $(M)_\varphi^{(h)} \preceq (N)_\varphi^{(k)}$, for some k. We can assume, without loss of generality, that $h \leq k$. Since $(N)_\varphi^{(k)} \in \mathcal{A}_\varphi(M)$, by Lemma 3.7, we obtain $(M)_\varphi^{(h)} \equiv ((N)_\varphi^{(k)})_\varphi^{(h)}$. Now $h \leq k$ implies $(N)_\varphi^{(h)} \equiv ((N)_\varphi^{(k)})_\varphi^{(h)}$ and we are done.

$(\Rightarrow)$: Easy, by definition of $\mathcal{A}_\varphi$ (Definition 3.4). □

It is possible to show that $\mathcal{T}_\varphi(M)$ is the least upper-bound of $\mathcal{A}_\varphi(M)$ with respect to $\preceq_\varphi$. We omit the proof of this property here, since it plays no role in this paper.

It is possible to extend each partial order $\preceq_\varphi$ to a partial order $\sqsubseteq_\varphi$, by naturally inducing an equivalence relation on sets of approximants. This can be proved to coincide with the identity relation on sets of approximants and hence, by Theorem 3.8, to coincide with the identity on trees.

Definition 3.9 *i*) The relation $\sqsubseteq_{\mathtt{t}}$ is the least partial order on $\mathcal{A}_{\mathtt{t}}$ that satisfies clauses (a), (b), and (c) of $\preceq_{\mathtt{t}}$ and, moreover:

d) $\bot A_1 \ldots A_n \sqsubseteq_{\mathtt{t}} x$.

ii) For $\varphi \in \{\mathtt{w}, \mathtt{h}\}$ the relation $\sqsubseteq_\varphi$ is the least partial order on $\mathcal{A}_\varphi$ which satisfies clauses (a), (b), and (c) of $\preceq_\varphi$ and, moreover:

e) $\lambda y.xA_1 \ldots A_n y \sqsubseteq_\varphi xA_1 \ldots A_n$, for all variables $y \notin FV(xA_1 \ldots A_n)$.

iii) For $\varphi \in \{\mathtt{e}, \mathtt{i}\}$ the relation $\sqsubseteq_\varphi$ is the least partial order on $\mathcal{A}_\varphi$ that satisfies clauses (a), (b), (c), and (*ii.e*) of $\sqsubseteq_{\mathtt{w}}$ and, moreover:

f) $xA_1 \ldots A_n \sqsubseteq_\varphi \lambda y.xA_1 \ldots A_n \bot$, where $x \neq y$.

Note that $A \to_\eta B$ implies $A \sqsubseteq_\varphi B$, for $\varphi \in \{\mathtt{w}, \mathtt{h}, \mathtt{e}, \mathtt{i}\}$ and $B \sqsubseteq_\varphi A$, for $\varphi \in \{\mathtt{e}, \mathtt{i}\}$. Moreover, we can show that

$$xA_1 \ldots A_n \sqsubseteq_\varphi \lambda y_1 \ldots y_m.xA_1 \ldots A_n \underbrace{\bot \ldots \bot}_{m}$$

whenever $x \notin \{y_1, \ldots, y_m\}$, for $\varphi \in \{\mathtt{e}, \mathtt{i}\}$. In fact, by clause (f) above, for any $k \geq 0$, we have

$$xA_1 \ldots A_n \underbrace{\bot \ldots \bot}_{k-1} \sqsubseteq_\varphi \lambda y_k.xA_1 \ldots A_n \underbrace{\bot \ldots \bot}_{k}.$$

By Definition 3.3(b) we get

$$\lambda y_1 \ldots y_{k-1}.xA_1 \ldots A_n \underbrace{\bot \ldots \bot}_{k-1} \sqsubseteq_\varphi \lambda y_1 \ldots y_k.xA_1 \ldots A_n \underbrace{\bot \ldots \bot}_{k}.$$

Then, by all such inequalities with $k \leq m$, we are done by transitivity.

It is useful to remark that pruning trees does not preserve these new orders. For instance, $\lambda y.xy \sqsubseteq_\varphi x$, but

$$(\lambda y.xy)_\varphi^{(1)} \equiv \lambda y.x\bot \not\sqsubseteq_\varphi (x)_\varphi^{(1)} \equiv x$$

where $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$. We have a weaker property, namely that if h is the height of the φ-tree of A and $A \sqsubseteq_\varphi B$, then $(A)_\varphi^{(k)} \sqsubseteq_\varphi (B)_\varphi^{(k)}$, for all $k \geq h$.

Definition 3.10 For any two terms M and N, we define: $\mathcal{A}_\varphi(M) \simeq_\varphi \mathcal{A}_\varphi(N)$ if and only if, for all $A \in \mathcal{A}_\varphi(M)$, there is $B \in \mathcal{A}_\varphi(N)$ such that $A \sqsubseteq_\varphi B$.

Lemma 3.11 If $A, B \in \mathcal{A}_\varphi(M)$ and $A \sqsubseteq_\varphi B$, then $A \preceq_\varphi B$.

Proof: If $A, B \in \mathcal{A}_\varphi(M)$ then $A \preceq_\varphi (M)_\varphi^{(h)}$ and $B \preceq_\varphi (M)_\varphi^{(k)}$, for some $h,k \geq 0$. Let $p = max\{h,k\}$. Then $A \preceq_\varphi (M)_\varphi^{(p)}$ and $B \preceq_\varphi (M)_\varphi^{(p)}$. This means that A and B can be obtained from $(M)_\varphi^{(p)}$ by replacing subterms by $\bot$. Therefore, B cannot be obtained from A either by replacing an occurrence of $\bot A_1 \ldots A_n$ with $n \geq 1$ by x, or by η-reduction, or by replacing an occurrence of $xA_1 \ldots A_n$ by $\lambda y.xA_1 \ldots A_n\bot$. So we can conclude that $A \preceq_\varphi B$. □

Lemma 3.12 If $\mathcal{A}_\varphi(M) \simeq_\varphi \mathcal{A}_\varphi(N)$, then $\mathcal{A}_\varphi(M) = \mathcal{A}_\varphi(N)$ and $\mathcal{T}_\varphi(M) = \mathcal{T}_\varphi(N)$.

Proof: Reasoning towards a contradiction, assume that for all $A \in \mathcal{A}_\varphi(M)$ there is a $B \in \mathcal{A}_\varphi(N)$ such that $A \sqsubseteq_\varphi B$ (and vice versa). Let $A \in \mathcal{A}_\varphi(M)$ be such that $A \notin \mathcal{A}_\varphi(N)$. Without loss of generality we can assume $A \equiv (M)_\varphi^{(h)}$, for some h. By hypothesis we find $B \in \mathcal{A}_\varphi(N)$ such that $A \sqsubseteq_\varphi B$ and $A' \in \mathcal{A}_\varphi(M)$ such that $B \sqsubseteq_\varphi A'$. We get $A \sqsubseteq_\varphi A'$ which, by Lemma 3.11, implies $A \preceq_\varphi A'$. Thus, by Lemma 3.7, $A \equiv (A')_\varphi^{(h)}$. From $A \sqsubseteq_\varphi B \sqsubseteq_\varphi A'$ we get $A \sqsubseteq_\varphi (B)_\varphi^{(h)} \sqsubseteq_\varphi (A')_\varphi^{(h)}$. Hence $A \equiv (B)_\varphi^{(h)}$ and we can conclude $A \in \mathcal{A}_\varphi(N)$. □

The main motivation for the introduction of '$\sqsubseteq_\varphi$' is that it is compatible with the typing that we shall present in the next section.

4 Types and type assignment systems

As stated in the introduction, our static tools to analyze trees (or, equivalently, their corresponding sets of approximants) will be type assignment systems, in particular type assignment systems based on intersection type-like disciplines.

In type assignment systems one derives statements of the form $M : \alpha$, where a term M gets assigned a type α that represents a certain finite information about M. Roughly speaking, a type will be used as a description of a particular notion of normal form. Hence, it is not possible to use a unique set of types to deal with all the trees defined in the previous section. We shall need, instead, three sets of types: $\mathsf{T}_\mathtt{t}$ to characterize $\mathcal{T}_\mathtt{t}$, $\mathsf{T}_\mathtt{wh}$ to characterize $\mathcal{T}_\mathtt{w}$ and $\mathcal{T}_\mathtt{h}$, and $\mathsf{T}_\mathtt{ei}$ to characterize $\mathcal{T}_\mathtt{e}$ and $\mathcal{T}_\mathtt{i}$.

After defining these sets of types, in this section we shall define an order '$\leq_\varphi$' on types that is parametrized by the notion of tree. Then – parametrized by this order – our type assignment systems will be defined (almost) uniformly for all notions of tree. All these type assignment systems deal correctly with a term that carries no information: $\mathcal{T}_\varphi(M) = \bot$ if and only if the universal type ω is the only type that the system related to $\mathcal{T}_\varphi$ can assign to M.

In the following, we shall use the following notation: if $\varphi \in \{\mathtt{t},\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$, then

$$\bar{\varphi} = \begin{cases} \mathtt{t} & \text{if } \varphi = \mathtt{t} \\ \mathtt{wh} & \text{if } \varphi = \mathtt{w} \text{ or } \varphi = \mathtt{h} \\ \mathtt{ei} & \text{if } \varphi = \mathtt{e} \text{ or } \varphi = \mathtt{i}. \end{cases}$$

Again, unless mentioned otherwise, we will assume $\bar{\varphi} \in \{\mathtt{t},\mathtt{wh},\mathtt{ei}\}$.

4.1 Types

We start with $\mathsf{T}_{\mathtt{t}}$. To describe a top normal form which is the application of two terms, following [7] we will introduce a particular type constructor: the application $\alpha\beta$ of two types α and β. In the intended interpretation a term has type $\alpha\beta$ if its top normal form is the application of two terms, the first one of type α and the second one of type β. We differ from [7] in that we will build types starting only from the unique constant ω, i.e., we won't introduce a new type constant to be interpreted as the set of all strong zero terms.

Some care has to be taken when introducing applicative types, since we have to prevent the presence of inconsistent types. For example, $\omega\omega$ expresses that a top normal form is the application of two terms, the first one being a strong zero term, whereas $\omega\to\omega$ expresses that a top normal form is an abstraction. So we need to prevent their intersection $\omega\omega\wedge(\omega\to\omega)$. Also the type $(\omega\to\omega)\omega$ is meaningless: no top normal form is the application of an abstraction to a term.

We are thus lead to consider a set of 'pretypes' and a smaller set of 'applicative-intersection types', where some obviously inconsistent types, like the ones above, are forbidden. The definition of the set of types is not immediate since, after excluding $\omega\omega\wedge(\omega\to\omega)$ and $(\omega\to\omega)\omega$, we must still decide whether a finite intersection like $(\alpha_1\to\beta_1)\wedge\ldots\wedge(\alpha_n\to\beta_n)$ is empty. The decisive idea comes from Scott's theory of information systems [28]: consistent inputs should give consistent outputs. So, if we interpret the above intersection as the step function which gives an output in $\bigwedge_{i\in I}\beta_i$ whenever the input is in $\bigwedge_{i\in I}\alpha_i$ (where I is a subset of $\{1,\ldots,n\}$), then we must require that if $\bigwedge_{i\in I}\beta_i$ is empty, so is $\bigwedge_{i\in I}\alpha_i$. The definition of types is then obtained by restricting the set of pretypes according to Scott's prescription. This excludes for instance $(\omega\to(\omega\to\omega))\wedge(\omega\to\omega\omega)$, because given an input in ω we would get an output in $(\omega\to\omega)\wedge\omega\omega$, which is impossible since the latter is not a type.

Definition 4.1 (Pretypes) The set PT of *pretypes* is the set of syntactic expressions inductively defined by:

i) $\omega \in \mathsf{PT}$ (atomic type),

ii) If $\alpha,\beta \in \mathsf{PT}$, then $(\alpha\to\beta)$, $(\alpha\beta)$ and $(\alpha\wedge\beta)$ are in PT.

As usual, in writing types, we assume the following precedence between operators: *application*, *intersection*, *arrow*; we will omit parentheses accordingly. Moreover, we will use $\alpha\to\beta^n\to\gamma$ as short-hand notation for $\alpha\to\underbrace{\beta\to\ldots\to\beta}_{n}\to\gamma$, and $\beta^n\to\gamma$ for $\underbrace{\beta\to\ldots\to\beta}_{n}\to\gamma$.

Definition 4.2 ($\mathsf{T}_{\mathtt{t}}$) Given $\alpha \in \mathsf{PT}$, we define two predicates '$\alpha \in \mathsf{T}_{\mathtt{t}}$' and '$\alpha \notin \mathsf{T}_{\mathtt{t}}$' by simultaneous induction on α, by stipulating that $\alpha \in \mathsf{T}_{\mathtt{t}}$ if and only if one of the following conditions holds (and $\alpha \notin \mathsf{T}_{\mathtt{t}}$ if and only if all the conditions do not hold):

(Universal kind)	α is ω.
(Arrow kind)	α is a finite intersection of the form $\bigwedge_{i\in I}(\alpha_i \to \beta_i)$, where $\alpha_i, \beta_i \in \mathsf{T}_{\mathtt{t}}$ and, for all $J \subseteq I$, either $\bigwedge_{j\in J}\beta_j \in \mathsf{T}_{\mathtt{t}}$ or $\bigwedge_{j\in J}\alpha_j \notin \mathsf{T}_{\mathtt{t}}$.
(Applicative kind)	α is $\omega\beta$, where $\beta \in \mathsf{T}_{\mathtt{t}}$, or α is a finite intersection of the form $\bigwedge_{i\in I}\alpha_i\beta_i$, where $\bigwedge_{i\in I}\beta_i \in \mathsf{T}_{\mathtt{t}}$, and $\bigwedge_{i\in I}\alpha_i \in \mathsf{T}_{\mathtt{t}}$ is of applicative or universal kind.

If $\alpha \in \mathsf{T}_{\mathtt{t}}$, then $\omega\wedge\alpha \in \mathsf{T}_{\mathtt{t}}$: the kind of $\omega\wedge\alpha$ is defined to be the kind of α.

In what follows, we will consider only types. Also, α,β,γ will range over types of any kind, σ,τ,ρ will range over types of arrow kind (*arrow types*), π,μ,ν will range over types of applicative kind (*applicative types*). Applicative types are only used in the definition of top types.

Without applicative types all the intersections are meaningful. So the definition of $\mathsf{T}_{\mathtt{wh}}$ and $\mathsf{T}_{\mathtt{ei}}$ can be given in a direct way. However, for weak head normal forms and head normal forms, we need to have a new constant, ζ, representing λ-free terms: the constant ω is not enough, as shown by Sangiorgi in [25]. In fact, [25] proves that Δ_2 and $\lambda x.x(\lambda y.xy)$ have the same types when types are built starting from ω using arrow and intersection type constructors. Clearly, these terms have different *weak* and *head* trees. Roughly speaking, ζ can be seen as the collapse of all applicative types.

Definition 4.3 ($\mathsf{T}_{\mathtt{wh}}$) The set of types $\mathsf{T}_{\mathtt{wh}}$ is inductively defined by

i) $\omega,\zeta \in \mathsf{T}_{\mathtt{wh}}$ (atomic types),

ii) $\alpha,\beta \in \mathsf{T}_{\mathtt{wh}}$ imply $(\alpha\to\beta),(\alpha\wedge\beta) \in \mathsf{T}_{\mathtt{wh}}$.

In order to define $\mathsf{T}_{\mathtt{ei}}$, since terms are considered modulo η, we are forced to equate all atomic types ω,ζ to intersections of arrow types (see [12]). This means that another type constant, ϑ, is needed. In fact, the equations $\zeta = \zeta\to\zeta$ and $\zeta = \omega\to\zeta$ give rise, respectively, to Scott's and Park's D_∞-models as proved in [10]. And the λ-theories of these models are both different from the equality of eta trees.

Definition 4.4 ($\mathsf{T}_{\mathtt{ei}}$) The set of types $\mathsf{T}_{\mathtt{ei}}$ is inductively defined by

i) $\omega,\zeta,\vartheta \in \mathsf{T}_{\mathtt{ei}}$ (atomic types),

ii) $\alpha,\beta \in \mathsf{T}_{\mathtt{ei}}$ imply $(\alpha\to\beta),(\alpha\wedge\beta) \in \mathsf{T}_{\mathtt{ei}}$.

4.2 Type preorders

On the sets of types of the previous subsection we will define five preorder relations which all take the meaning of ω as universal type, of $\to$ as function space constructor, and of $\wedge$ as intersection into account. The particular properties of these five preorders make them suitable to describe the different trees.

The preorder $\leq_{\mathtt{t}}$, defined on $\mathsf{T}_{\mathtt{t}}$, reflects the interpretation of applicative types. The preorder $\leq_{\mathtt{h}}$, defined on $\mathsf{T}_{\mathtt{wh}}$, equates ω to $\omega\to\omega$, since we want to take the fact that a term like $\lambda x.\bot$ can never be obtained from a head-tree into account. The preorders $\leq_{\mathtt{e}}$ and $\leq_{\mathtt{i}}$ equate all atomic types to arrow types. They differ since, in $\leq_{\mathtt{i}}$, the left-hand subtype of such an arrow type is always ω, while this is not true for $\leq_{\mathtt{e}}$. This difference is essential in order to be able to mimic either infinite or finite η-reductions, as we shall see later.

Definition 4.5 *i*) We define $\leq_{\mathtt{t}}$ as the smallest binary relation over $\mathsf{T}_{\mathtt{t}}$ such that:

a) it is a preorder in which $\wedge$ is the meet and ω is the top;[2]

the arrow satisfies:

b) $\alpha\to\omega \leq \omega\to\omega$;

c) $(\alpha\to\beta)\wedge(\alpha\to\gamma) \leq \alpha\to\beta\wedge\gamma$;

d) $\alpha \geq \alpha'$ and $\beta \leq \beta'$ imply $\alpha\to\beta \leq \alpha'\to\beta'$;

the applicative types satisfy:

e) $\pi\alpha\wedge\pi'\alpha' \leq (\pi\wedge\pi')(\alpha\wedge\alpha')$;

f) $\pi \leq \pi'$ and $\alpha \leq \alpha'$ imply $\pi\alpha \leq \pi'\alpha'$.

ii) We define $\leq_{\mathtt{w}}$ as the smallest binary relation over $\mathsf{T}_{\mathtt{wh}}$ that satisfies the clauses (*i.a*) to (*i.d*) above.

iii) We define $\leq_{\mathtt{h}}$ as the smallest binary relation over $\mathsf{T}_{\mathtt{wh}}$ that satisfies the clauses (*i.a*), (*i.c*) and (*i.d*) above and, moreover:

g) $\omega \leq \omega\to\omega$.

iv) We define $\leq_{\mathtt{e}}$ as the smallest binary relation over $\mathsf{T}_{\mathtt{ei}}$ that satisfies the clauses (*i.a*), (*i.c*), (*i.d*) and (*iii.g*) above and, moreover:

h) $\zeta \leq \vartheta\to\zeta \leq \zeta$;

i) $\vartheta \leq \zeta\to\vartheta \leq \vartheta$.

v) Let $\leq_{\mathtt{i}}$ be the smallest binary relation over $\mathsf{T}_{\mathtt{ei}}$ which satisfies the clauses (*i.a*), (*i.c*), (*i.d*) and (*iii.g*) above and, moreover:

j) $\zeta \leq \omega\to\zeta \leq \zeta$;

k) $\vartheta \leq \omega\to\vartheta \leq \vartheta$.

'$\alpha =_\varphi \beta$' is short for '$\alpha \leq_\varphi \beta$ and $\beta \leq_\varphi \alpha$'.

Notice that clause (*i.b*) is derivable from clause (*iii.g*), so it is safe to eliminate clause (*i.b*) from the definitions of $\leq_{\mathtt{h}}, \leq_{\mathtt{e}}$, and $\leq_{\mathtt{i}}$.

Example 4.6 • $\omega\wedge\alpha =_\varphi \alpha$, for every type $\alpha \in \mathsf{T}_{\bar{\varphi}}$.

- $(\omega\to\omega)\wedge\sigma =_{\mathtt{t}} \sigma$, for every arrow type $\sigma \in \mathsf{T}_{\mathtt{t}}$.
- $(\omega\to\omega)\wedge\alpha =_\varphi \alpha$, for every type $\alpha \in \mathsf{T}_{\bar{\varphi}}$ (but for the case $\alpha =_{\mathtt{w}} \omega$ when $\varphi = \mathtt{w}$) where $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$.
- $\omega\omega\wedge\pi =_{\mathtt{t}} \pi$, for every applicative type $\pi \in \mathsf{T}_{\mathtt{t}}$.

We need to consider some properties of $\leq_{\mathtt{t}}$ already proved in [7] for the sets of types and the preorder relations there introduced.

Lemma 4.7 *i) If $\bigwedge_{i\in I}(\alpha_i\to\beta_i) \leq_{\mathtt{t}} \gamma <_{\mathtt{t}} \omega$, or $\gamma \leq_{\mathtt{t}} \bigwedge_{i\in I}(\alpha_i\to\beta_i)$, then γ is an arrow type.*

ii) If $\pi \leq_{\mathtt{t}} \alpha <_{\mathtt{t}} \omega$, or $\alpha \leq_{\mathtt{t}} \pi$, then α is an applicative type.

iii) $\pi\alpha \leq_{\mathtt{t}} \pi'\alpha'$ implies $\pi \leq_{\mathtt{t}} \pi'$ and $\alpha \leq_{\mathtt{t}} \alpha'$.

iv) $\pi\alpha\wedge\pi'\alpha' =_{\mathtt{t}} (\pi\wedge\pi')(\alpha\wedge\alpha')$.

v) For any applicative type π, $\pi =_{\mathtt{t}} \omega\alpha_1\ldots\alpha_n$, for some $n,\alpha_1,\ldots,\alpha_n$.

vi) Assume $\beta \leq_{\mathtt{t}} \alpha_1$ and $\beta \leq_{\mathtt{t}} \alpha_2$. If $\beta \in \mathsf{T}_{\mathtt{t}}$, then $\alpha_1\wedge\alpha_2 \in \mathsf{T}_{\mathtt{t}}$.

Proof: *i*) – (*iii*) By induction on the definition of $\leq_{\mathtt{t}}$.

[2] The explicit axioms and rules are $\alpha \leq \alpha$, $\alpha \leq \beta$ and $\beta \leq \gamma$ imply $\alpha \leq \gamma$, $\alpha \leq \alpha\wedge\alpha$, $\alpha\wedge\beta \leq \alpha$, $\alpha\wedge\beta \leq \beta$, $\alpha \leq \alpha'$ and $\beta \leq \beta'$ imply $\alpha\wedge\beta \leq \alpha'\wedge\beta'$, and $\alpha \leq \omega$.

iv) In fact, $\pi\alpha\wedge\pi'\alpha' \leq_{\mathtt{t}} (\pi\wedge\pi')(\alpha\wedge\alpha')$ follows from clause (*i.e*) of Definition 4.5. The converse follows from clause (*i.f*) of the same definition and the fact that $\beta \leq_{\mathtt{t}} \gamma$ and $\beta \leq_{\mathtt{t}} \delta$ imply $\beta \leq_{\mathtt{t}} \gamma\wedge\delta$.

v) First observe that $\omega\wedge\pi =_{\mathtt{t}} \pi$ for all types π. Then, by (*iv*), we are done.

vi) By cases, using (*i*) – (*iii*). □

All the pre-orders we introduced enjoy the following two properties which can be shown by induction on $\leq_\varphi$. The first property says that an arrow type terminating with an atom is $\wedge$-prime[3]. The second essentially says that the sets of types that are filters represent the space of continuous functions (see [10]).

Lemma 4.8 *i) If $\alpha\wedge\beta \leq_\varphi \gamma_1\to\ldots\to\gamma_n\to\delta$, where δ is atomic and $n \geq 0$, then either $\alpha \leq_\varphi \gamma_1\to\ldots\to\gamma_n\to\delta$ or $\beta \leq_\varphi \gamma_1\to\ldots\to\gamma_n\to\delta$.*

ii) If $\bigwedge_{i\in I}(\alpha_i\to\beta_i) \leq_\varphi \alpha\to\beta$, where $\beta \neq_\varphi \omega$, then for some $J \subseteq I$ $\alpha \leq_\varphi \bigwedge_{j\in J}\alpha_j$ and $\bigwedge_{j\in J}\beta_j \leq_\varphi \beta$.

As an immediate consequence of Lemma 4.8(*ii*) we get that $\alpha\to\beta \leq_\varphi \gamma\to\delta$ implies $\gamma \leq_\varphi \alpha$ and $\beta \leq_\varphi \delta$.

4.3 Type assignment systems

For each preorder introduced in the previous subsection, we will define a type assignment system associating λ-terms to types belonging to the domain of the preorder. As said at the beginning of this section, these systems can be defined *almost* uniformly. In fact, there are six rules which are common to all systems and which are standard in intersection type disciplines. The type assignment systems $\vdash_\varphi$ ($\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$) are defined by six such rules, and instantiating rule ($\leq_\varphi$) with the corresponding preorder. However, to define $\vdash_{\mathtt{t}}$ we have to deal with applicative types, and hence we need two extra rules: (ωapp) and (app).

These rules for applicative types allow to deduce the type $\alpha\beta$ for the application MN when M has type α, N has type β and M is a strong zero term. Moreover, a rule ($\beta{-}exp$) is needed as well, since applicative types are not invariant under β-expansion of subjects. For example, without ($\beta{-}exp$) we derive $\vdash_{\mathtt{t}} \mathbf{\Omega_2 I} : \omega(\omega\to\omega)$, but we cannot derive $\vdash_{\mathtt{t}} (\lambda xy.y\mathbf{\Delta}_2 x)\mathbf{I\Delta}_2 : \omega(\omega\to\omega)$.

A *basis* Γ is a (finite or infinite) set of statements of the shape $x{:}\alpha$, with distinct variables as subjects. In writing $\Gamma, x{:}\alpha$ we assume that x does not occur in Γ. We denote by $\mathcal{B}_{\mathtt{t}}$, $\mathcal{B}_{\mathtt{wh}}$, $\mathcal{B}_{\mathtt{ei}}$ the sets of bases whose predicates belong to $\mathsf{T}_{\mathtt{t}}$, $\mathsf{T}_{\mathtt{wh}}$, and $\mathsf{T}_{\mathtt{ei}}$, respectively.

Definition 4.9 (Type assignment systems) Consider the rules of Figure 3:

i) The type assignment system $\vdash_{\mathtt{t}}$ is defined by the rules (Ax), (ω), ($\to I$), ($\to E$), ($\wedge I$), (ωapp), (app), ($\beta{-}exp$), and ($\leq_{\mathtt{t}}$), where $\Gamma \in \mathcal{B}_{\mathtt{t}}$, $\pi \in \mathsf{T}_{\mathtt{t}}$ is an applicative type, and $\alpha,\beta \in \mathsf{T}_{\mathtt{t}}$.

ii) The type assignment system $\vdash_\varphi$, for $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$ is defined by the rules (Ax), (ω), ($\to I$), ($\to E$), ($\wedge I$), and ($\leq_\varphi$), where $\Gamma \in \mathcal{B}_{\bar\varphi}$ and $\alpha,\beta \in \mathsf{T}_{\bar\varphi}$.

Example 4.10 • $\vdash_{\mathtt{t}} \mathbf{\Omega_3} : \omega(\omega\to\omega)$, whereas, in all other systems, any type deducible for $\mathbf{\Omega_3}$ is equivalent to ω.

• $\vdash_\varphi \lambda x.\mathbf{\Omega_2} : \omega\to\omega$, for $\varphi \in \{\mathtt{t},\mathtt{w}\}$, whereas, in all other systems, any type deducible for $\lambda x.\mathbf{\Omega_2}$ is equivalent to ω.

[3] A type γ is called $\wedge$-prime, if and only if $\alpha\wedge\beta \leq \gamma$ implies $\alpha \leq \gamma$ or $\beta \leq \gamma$.

$$(Ax)\quad \frac{}{\Gamma, x{:}\alpha \vdash x : \alpha} \qquad\qquad (\omega)\quad \frac{}{\Gamma \vdash M : \omega}$$

$$(\to I)\quad \frac{\Gamma, x{:}\alpha \vdash M : \beta}{\Gamma \vdash \lambda x.M : \alpha \to \beta} \qquad\qquad (\to E)\quad \frac{\Gamma \vdash M : \alpha \to \beta \qquad \Gamma \vdash N : \alpha}{\Gamma \vdash MN : \beta}$$

$$(\wedge I)\quad \frac{\Gamma \vdash M : \alpha \qquad \Gamma \vdash M : \beta}{\Gamma \vdash M : \alpha \wedge \beta} \qquad\qquad (\leq_\varphi)\quad \frac{\Gamma \vdash M : \alpha \qquad \alpha \leq_\varphi \beta}{\Gamma \vdash M : \beta}$$

$$(\beta{-}exp)\quad \frac{\Gamma \vdash N : \alpha \qquad M \to_\beta N}{\Gamma \vdash M : \alpha} \qquad\qquad (app)\quad \frac{\Gamma \vdash M : \pi \qquad \Gamma \vdash N : \alpha}{\Gamma \vdash MN : \pi\alpha}$$

$$(\omega app)\quad \frac{M \text{ is a strong zero term} \qquad \Gamma \vdash N : \alpha}{\Gamma \vdash MN : \omega\alpha}$$

Note: M, N are terms of $\Lambda_\perp$, and, in $(\beta{-}exp)$, the relation $\to_\beta$ is the *full* β-reduction, i.e., the symmetric, transitive and compatible closure of rule (β).

Figure 3: Derivation rules

- $\vdash_\varphi \mathbf{\Delta_2} : \zeta \wedge (\zeta \to \zeta) \to \zeta$ for $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$, and also $\vdash_\varphi \mathbf{\Delta_2}^\eta : \zeta \wedge (\zeta \to \zeta) \to \zeta$, for $\varphi \in \{\mathtt{e},\mathtt{i}\}$, whereas the latter statement is not deducible for $\varphi \in \{\mathtt{t},\mathtt{w},\mathtt{h}\}$.
- $\vdash_\varphi \mathbf{I} : \zeta \to \zeta$, for $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$, and also $\vdash_\mathtt{i} \mathbf{RR} : \zeta \to \zeta$, whereas the latter statement is not deducible in all other systems.

Remark 4.11 At a first glance one could wonder whether, in the definition of $\vdash_\mathtt{t}$, it is possible to eliminate rule $(\beta{-}exp)$ by replacing rule (ωapp) by a rule like

$$(\omega app')\quad \frac{M \to_\beta ZN \qquad Z \text{ is a strong zero term} \qquad \Gamma \vdash N : \alpha}{\Gamma \vdash M : \omega\alpha}$$

This is not the case. In fact, it is easy to check that $(\lambda y.x(y\mathbf{\Delta_2}\mathbf{I}))\mathbf{\Delta_2} \to_\beta x(\mathbf{\Omega_2}\mathbf{I})$ and $x{:}\omega\omega \to \alpha \vdash_\mathtt{t} x(\mathbf{\Omega_2}\mathbf{I}) : \alpha$. However, without rule $(\beta{-}exp)$, we cannot derive $x{:}\omega\omega \to \alpha \vdash_\mathtt{t} (\lambda y.x(y\mathbf{\Delta_2}\mathbf{I}))\mathbf{\Delta_2} : \alpha$.

Since terms are considered modulo α-conversion, the weakening rule is admissible. Moreover, as usual, we have $\Gamma_{|M} \vdash_\varphi M : \alpha$ whenever $\Gamma \vdash_\varphi M : \alpha$, where $\Gamma_{|M} = \{x{:}\beta \in \Gamma \mid x \in FV(M)\}$[4].

We define $Dom(\Gamma) = \{x \mid x{:}\alpha \in \Gamma \text{ and } \alpha \neq \omega\}$ and we assume $x{:}\omega \in \Gamma$ whenever $x \notin Dom(\Gamma)$. This is sound in view of rule (ω).

We want to consider unions of bases taking the intersections of the types with the same subjects. Since not all intersections of types in $\mathsf{T}_\mathtt{t}$ are types, we need to allow in this case only unions of compatible bases, according to the following definition. For the other sets of types, any two arbitrary bases are compatible.

Definition 4.12 We say that two bases $\Gamma, \Gamma' \in \mathcal{B}_{\bar\varphi}$ are *compatible* if and only if $x{:}\alpha \in \Gamma$ and $x{:}\beta \in \Gamma'$ imply $\alpha \wedge \beta \in \mathsf{T}_{\bar\varphi}$. If Γ and Γ' are compatible, we define their union $\uplus$ as

$$\Gamma \uplus \Gamma' = \{x{:}\alpha \wedge \beta \mid x{:}\alpha \in \Gamma \text{ and } x{:}\beta \in \Gamma'\}.$$

Notice that $x{:}\alpha \wedge \omega \in \Gamma \uplus \Gamma'$ whenever $x{:}\alpha \in \Gamma$ and $x \notin Dom(\Gamma')$, since by convention we get $x{:}\omega \in \Gamma'$. Similarly, when $x{:}\beta \in \Gamma'$ and $x \notin Dom(\Gamma)$.

[4] For rule $(\beta{-}exp)$ note that $M \to_\beta N$ implies $FV(N) \subseteq FV(M)$.

As expected, we have generation lemmas for all the given type assignment systems. To avoid the use of rule $(\beta{-}exp)$, the generation lemma for $\vdash_{\mathsf{t}}$ considers approximate normal forms instead of arbitrary terms.

Lemma 4.13 (Generation Lemma for $\vdash_{\mathsf{t}}$) *Let $A \in \mathcal{A}_{\mathsf{t}}$.*

i) $\Gamma \vdash_{\mathsf{t}} \bot : \alpha$ implies $\alpha =_{\mathsf{t}} \omega$;

ii) If $\Gamma \vdash_{\mathsf{t}} A : \alpha$, $\alpha \neq_{\mathsf{t}} \omega$, and

a) $A \equiv x$, then $x{:}\beta \in \Gamma$ for some $\beta \leq_{\mathsf{t}} \alpha$;

b) $A \equiv \lambda x.A'$, then $\alpha =_{\mathsf{t}} \bigwedge_{i\in I}(\alpha_i{\to}\beta_i)$ and, for $i \in I$, $\Gamma, x{:}\alpha_i \vdash_{\mathsf{t}} A' : \beta_i$;

c) $A \equiv xA_1 \ldots A_nA'$, then there exists β such that $\Gamma \vdash_{\mathsf{t}} A' : \beta$, and either $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \beta{\to}\alpha$, or $\alpha \geq_{\mathsf{t}} \pi\beta$ and $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \pi$, for some π;

d) $A \equiv \bot A_1 \ldots A_nA'$, then there is β such that $\Gamma \vdash_{\mathsf{t}} A' : \beta$, $\alpha \geq_{\mathsf{t}} \pi\beta$ and $\Gamma \vdash_{\mathsf{t}} \bot A_1 \ldots A_n : \pi$, for some π;

iii) If $\Gamma \vdash_{\mathsf{t}} A : \alpha$ and $\Gamma \vdash_{\mathsf{t}} A : \beta$, then $\alpha{\wedge}\beta \in \mathsf{T}_{\mathsf{t}}$.

Proof: The proof for (*i*) is immediate. We prove (*ii*) and (*iii*) by simultaneous induction on A, showing each time first (*ii*) by a secondary induction on derivations.

$(A \equiv x)$: (*ii.a*): Follows easily by induction on derivations, using the transitivity of $\leq_{\mathsf{t}}$.

(*iii*): Follows from (*ii.a*) and Lemma 4.7(*vi*).

$(A \equiv \lambda x.A')$: (*ii.b*): Proved by induction on derivations. If the last applied rule is $(\leq_{\mathsf{t}})$, $\alpha =_{\mathsf{t}} \bigwedge_{i\in I}(\alpha_i{\to}\beta_i)$ follows from Lemma 4.7(*i*) and $\Gamma, x{:}\alpha_i \vdash_{\mathsf{t}} A' : \beta_i$ follows from Lemma 4.8(*ii*).

(*iii*): Let, by (*ii.b*), $\alpha =_{\mathsf{t}} \bigwedge_{i\in I}(\alpha_i{\to}\beta_i)$, $\beta =_{\mathsf{t}} \bigwedge_{j\in J}(\alpha_j{\to}\beta_j)$. Consider $K \subseteq I \cup J$: if $\bigwedge_{k\in K}\alpha_k \notin \mathsf{T}_{\mathsf{t}}$ there is no problem. If $\bigwedge_{k\in K}\alpha_k \in \mathsf{T}_{\mathsf{t}}$, we have by (*ii.b*) that $\Gamma, x{:}\alpha_k \vdash_{\mathsf{t}} A' : \beta_k$, for all $k \in K$, therefore using rule $\leq_{\mathsf{t}}$ we have $\Gamma, x{:}\bigwedge_{k\in K}\alpha_k \vdash_{\mathsf{t}} A' : \beta_k$, for all $k \in K$. This implies, by induction, $\bigwedge_{k\in K}\beta_k \in \mathsf{T}_{\mathsf{t}}$, so we conclude $\alpha{\wedge}\beta \in \mathsf{T}_{\mathsf{t}}$.

$(A \equiv xA_1 \ldots A_nA')$: ((*ii.c*)): By induction on derivations. The only interesting case is when the last applied rule is $(\wedge I)$

$$(\wedge I)\quad \frac{\Gamma \vdash_{\mathsf{t}} A : \alpha_1 \qquad \Gamma \vdash_{\mathsf{t}} A : \alpha_2}{\Gamma \vdash_{\mathsf{t}} A : \alpha_1{\wedge}\alpha_2}.$$

By the second induction, there are β_i $(i = 1,2)$, such that $\Gamma \vdash_{\mathsf{t}} A' : \beta_i$, and either $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \beta_i{\to}\alpha_i$, or $\alpha_i \geq_{\mathsf{t}} \pi_i\beta_i$ and $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \pi_i$, for some π_i. By induction on (*iii*), we cannot have $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \beta_1{\to}\alpha_1$ and $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \pi_2$, or $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \beta_2{\to}\alpha_2$ and $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \pi_1$. Moreover, we get $\beta_1{\wedge}\beta_2 \in \mathsf{T}_{\mathsf{t}}$ and either $(\beta_1{\to}\alpha_1){\wedge}(\beta_2{\to}\alpha_2) \in \mathsf{T}_{\mathsf{t}}$ or $\pi_1{\wedge}\pi_2 \in \mathsf{T}_{\mathsf{t}}$. Therefore, using rules $(\leq_{\mathsf{t}})$ and $(\wedge I)$, $\Gamma \vdash_{\mathsf{t}} A' : \beta_1{\wedge}\beta_2$ and either $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \beta_1{\wedge}\beta_2{\to}\alpha_1{\wedge}\alpha_2$ or $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \pi_1{\wedge}\pi_2$.

(*iii*): Let $\Gamma \vdash_{\mathsf{t}} A : \alpha_1$ and $\Gamma \vdash_{\mathsf{t}} A : \alpha_2$. By induction on (*ii.c*) there are β_i, for $i = 1,2$ such that $\Gamma \vdash_{\mathsf{t}} A' : \beta_i$, and either $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \beta_i{\to}\alpha_i$, or $\Gamma \vdash_{\mathsf{t}} xA_1 \ldots A_n : \pi_i$ and $\alpha_i \geq_{\mathsf{t}} \pi_i\beta_i$,, for some π_i. So we can conclude as above that $\beta_1{\wedge}\beta_2 \in \mathsf{T}_{\mathsf{t}}$ and either $(\beta_1{\to}\alpha_1){\wedge}(\beta_2{\to}\alpha_2) \in \mathsf{T}_{\mathsf{t}}$ or $\pi_1{\wedge}\pi_2 \in \mathsf{T}_{\mathsf{t}}$. This implies either $\alpha_1{\wedge}\alpha_2 \in \mathsf{T}_{\mathsf{t}}$ or $(\pi_1{\wedge}\pi_2)(\beta_1{\wedge}\beta_2) \in \mathsf{T}_{\mathsf{t}}$. In the second case we get $(\pi_1{\wedge}\pi_2)(\beta_1{\wedge}\beta_2) \leq_{\mathsf{t}} \pi_1\beta_1{\wedge}\pi_2\beta_2$ by Lemma 4.7(*iv*). This implies $(\pi_1{\wedge}\pi_2)(\beta_1{\wedge}\beta_2) \leq_{\mathsf{t}} \alpha_1{\wedge}\alpha_2$, so we can conclude $\alpha_1{\wedge}\alpha_2 \in \mathsf{T}_{\mathsf{t}}$ by Lemma 4.7(*vi*).

The set of types deducible in $\vdash_{\varphi}$ for approximate normal forms is not decreasing with respect to the order relation $\preceq_{\varphi}$ between approximate normal forms. From this we easily obtain a consistency property between the types deducible for the approximants of the same term in

$\vdash_{\mathtt{t}}$.

Lemma 4.14 *i) If $\Gamma \vdash_\varphi A : \alpha$ and $A \preceq_\varphi A'$, then $\Gamma \vdash_\varphi A' : \alpha$.*

ii) If $A, A' \in \mathcal{A}_{\mathtt{t}}(M)$, then a basis $\Gamma \in \mathcal{B}_{\mathtt{t}}$ cannot assign an arrow type to A and an applicative type to A'.

Proof: *i*) By induction on the definition of $\preceq_\varphi$.

ii) Since '$\preceq_{\mathtt{t}}$' is directed (Lemma 3.6), reasoning towards a contradiction we would get a single approximate normal form which has both an arrow and an applicative type. This is impossible by Lemma 4.13(*iii*) because the intersection of an applicative type and an arrow type is not a type. □

Lemma 4.15 (Generation Lemma for $\vdash_\varphi$) *Let $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$.*

i) $\Gamma \vdash_\varphi \bot : \alpha$ implies $\alpha =_\varphi \omega$;

ii) $\Gamma \vdash_\varphi x : \alpha$ if and only if $x{:}\beta \in \Gamma$, for some $\beta \leq_\varphi \alpha$;

iii) $\Gamma \vdash_\varphi \lambda x.M : \alpha$ (and $\alpha \neq_{\mathtt{w}} \omega$ when $\varphi = \mathtt{w}$) if and only if $\alpha =_\varphi \bigwedge_{i\in I}(\alpha_i \to \beta_i)$ and, for $i \in I$, $\Gamma, x{:}\alpha_i \vdash_\varphi M : \beta_i$;

iv) $\Gamma \vdash_\varphi MN : \alpha$ if and only if there is β such that $\Gamma \vdash_\varphi M : \beta \to \alpha$, and $\Gamma \vdash_\varphi N : \beta$.

Proof: All points can be shown by standard induction on the structure of derivations, using Lemma 4.8(*ii*) for (*iii*). □

With a standard proof we can show that rule $(\beta{-}exp)$ is admissible in the systems $\vdash_\varphi$, for $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$. Moreover, types are preserved by η expansion in $\vdash_{\mathtt{e}}$ and $\vdash_{\mathtt{i}}$.

Theorem 4.16 *i) Let $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$. Then $\Gamma \vdash_\varphi M[N/x] : \alpha$ implies $\Gamma \vdash_\varphi (\lambda x.M)N : \alpha$.*

ii) Let $\varphi \in \{\mathtt{e},\mathtt{i}\}$. Then $\Gamma \vdash_\varphi M : \alpha$ and $x \notin FV(M)$ imply $\Gamma \vdash_\varphi \lambda x.Mx : \alpha$.

iii) Let $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$. Then $\Gamma \vdash_\varphi N : \alpha$ and $M \to_\beta N$ imply $\Gamma \vdash_\varphi M : \alpha$.

iv) Let $\varphi \in \{\mathtt{e},\mathtt{i}\}$. Then $\Gamma \vdash_\varphi N : \alpha$ and $M \to_\eta N$ imply $\Gamma \vdash_\varphi M : \alpha$.

Proof: *i*) Let $\Gamma_i \vdash_\varphi N : \beta_i$, for $1 \leq i \leq n$ and $n \geq 0$, be al the statements whose subject is N in a derivation of $\Gamma \vdash_\varphi M[N/x] : \alpha$. Notice that $\Gamma \subseteq \Gamma_i$ but $\Gamma_{|N} = \Gamma_{i|N}$, for all $1 \leq i \leq n$. So we can derive $\Gamma \vdash_\varphi N : \bigwedge_{1\leq i\leq n}\beta_i$, with the convention that $\bigwedge_{1\leq i\leq n}\beta_i = \omega$ whenever $n = 0$. One can easily see, by induction on M, that $\Gamma, x{:}\bigwedge_{1\leq i\leq n}\beta_i \vdash_\varphi M : \alpha$. Then, by rule $(\to I)$, we get $\Gamma \vdash_\varphi \lambda x.M : \bigwedge_{1\leq i\leq n}\beta_i \to \alpha$. Hence, by rule $(\to I)$, we can conclude $\Gamma \vdash_\varphi (\lambda x.M)N : \alpha$.

ii) By easy induction on α, taking into account that each atomic type is equal to an arrow type in the preorders $\leq_{\mathtt{e}}$ and $\leq_{\mathtt{i}}$.

iii) – (*iv*) By straightforward induction, using, respectively, (*i*) and (*ii*). □

For the type assignment system $\vdash_{\mathtt{i}}$ we need a further property dealing with the types we can deduce for the terms whose infinite eta tree is just one variable. The notion of strict types comes in handy [2].

Definition 4.17 The set of *strict types* $\mathsf{ST} \subseteq \mathsf{T}_{\mathtt{ei}}$ is the minimal set such that:

i) $\omega, \zeta, \vartheta \in \mathsf{ST}$,

ii) $\alpha, \beta_1, \ldots, \beta_n \in \mathsf{ST}$, $n \geq 1 \Rightarrow \beta_1 \wedge \ldots \wedge \beta_n \to \alpha \in \mathsf{ST}$.

Property 4.18 *For all types $\alpha \in \mathsf{T}_{\mathtt{ei}}$, there is a set of strict types $\beta_1, \ldots, \beta_n \in \mathsf{ST}$ such that $\alpha =_{\mathtt{i}} \beta_1 \wedge \ldots \wedge \beta_n$.*

Proof: By induction on α. Observe that $\gamma{\to}\delta_1{\wedge}\delta_2 =_{\mathtt{i}} (\gamma{\to}\delta_1){\wedge}(\gamma{\to}\delta_2)$. □

We will now introduce a measure on types which gives us, for each equivalence class, the number of symbols occurring in the shortest strict type.

Definition 4.19 *i*) Define $|\ | : \mathsf{T}_{\mathtt{ei}} \to \mathbb{N}$ by:

a) $|\omega| = |\zeta| = |\vartheta| = 1$,

b) $|\alpha{\to}\beta| = |\alpha{\wedge}\beta| = |\alpha| + |\beta| + 1$.

ii) Define $||\ || : \mathsf{T}_{\mathtt{ei}} \to \mathbb{N}$ by $||\alpha|| = min\{|\beta| \mid \beta \in \mathsf{ST} \text{ and } \beta =_{\mathtt{i}} \alpha\}$.

Theorem 4.20 *Let $\mathcal{T}_{\mathtt{i}}(M) \geq_\eta x$.*

i) $x{:}\alpha \vdash_{\mathtt{i}} M : \alpha$.

ii) If $\Gamma \vdash_{\mathtt{i}} x : \alpha$ then $\Gamma \vdash_{\mathtt{i}} M : \alpha$.

Proof: i) By induction on $||\alpha||$. Notice that $\mathcal{T}_{\mathtt{i}}(M) \geq_\eta x$ implies

$$M =_\beta \lambda y_1 \ldots y_n.xM_1 \ldots M_n$$

where $\mathcal{T}_{\mathtt{i}}(M_i) \geq_\eta y_i$, for $1 \leq i \leq n$ and $n \geq 0$.

- If $||\alpha|| = 1$ then $\alpha =_{\mathtt{i}} \omega$, $\alpha =_{\mathtt{i}} \zeta$ or $\alpha =_{\mathtt{i}} \vartheta$. The case $\alpha =_{\mathtt{i}} \omega$ is trivial. Otherwise, we derive $\vdash_{\mathtt{i}} M_i : \omega$, for $i \leq i \leq n$, by rule (ω) and we conclude $x{:}\xi \vdash_{\mathtt{i}} M : \xi$, for $\xi \in \{\zeta, \vartheta\}$, using rules $(\leq_{\mathtt{i}})$, $(\to E)$, and $(\to I)$, since $\zeta =_{\mathtt{i}} \omega^n{\to}\zeta$ and $\vartheta =_{\mathtt{i}} \omega^n{\to}\vartheta$.
- For the induction step, by Proposition 4.18, we can assume, without loss of generality, that α is a strict type. We distinguish two subcases.
  - $\alpha =_{\mathtt{i}} \beta_1{\to}\ldots{\to}\beta_n{\to}\gamma$ with $||\alpha|| = ||\beta_1|| + \ldots + ||\beta_n|| + ||\gamma|| + n$ By induction $y_i{:}\beta_i \vdash_{\mathtt{i}} M_i : \beta_i$, for $1 \leq i \leq n$, and so we obtain $x{:}\alpha \vdash_{\mathtt{i}} M : \alpha$, using rules $(\leq_{\mathtt{i}})$, $(\to E)$, and $(\to I)$.
  - $\alpha =_{\mathtt{i}} \beta_1{\to}\ldots{\to}\beta_m{\to}\xi$ with $m < n$, $\xi \in \{\zeta, \vartheta\}$ and $||\alpha|| = ||\beta_1|| + \ldots + ||\beta_m|| + m + 1$. Also, by induction, $y_i{:}\beta_i \vdash_{\mathtt{i}} M_i : \beta_i$, for $1 \leq i \leq m$. Moreover, by rule (ω), we get $\vdash_{\mathtt{i}} M_i : \omega$, for $m + 1 \leq i \leq n$. We conclude as in previous case, since $\alpha = \beta_1{\to}\ldots{\to}\beta_m{\to}\omega^{n-m}{\to}\xi$.

ii) Follows easily from (*i*) and Lemma 4.15(*ii*). □

4.4 Approximation theorems

Our type assignment systems enjoy the approximation property, i.e., we can deduce a type for a term M if and only if we can deduce this type for an approximant of M, with respect to the relative notion of approximant (Theorem 4.25). Such a theorem, interesting in its own right, will be used in the next section to show that our type assignment systems are tools to analyze the observational behaviour represented by trees.

We prove the Approximation Theorem by means of a variant of Tait's 'computability' technique. We define sets of 'approximable' and 'computable' terms. The computable terms are defined by induction on types (Definition 4.21), and every computable term is shown to be approximable (Lemma 4.23(*ii*)). Using induction on type derivations, we show that every term is computable for the appropriate type (Lemma 4.24).

It is useful to have a short-hand notation for the property we want to show. We define '$\mathsf{App}_\varphi(\Gamma, \alpha, M)$' as an abbreviation for '$\exists A \in \mathcal{A}_\varphi(M).\Gamma \vdash_\varphi A : \alpha$'.

Definition 4.21 We define the predicate $\mathsf{Comp}_\varphi(\Gamma,\alpha,M)$ by induction on $\alpha \in \mathsf{T}_{\bar{\varphi}}$ as follows:

i) $\mathsf{Comp}_\varphi(\Gamma,\omega,M)$ is always true;

ii) $\mathsf{Comp}_{\mathtt{t}}(\Gamma,\pi,M)$, if and only if $\mathsf{App}_{\mathtt{t}}(\Gamma,\pi,M)$, for every type π of applicative kind;

iii) $\mathsf{Comp}_\varphi(\Gamma,\zeta,M)$, if and only if $\mathsf{App}_\varphi(\Gamma,\zeta,M)$, for $\varphi \in \{\mathtt{w},\mathtt{h}\}$;

iv) $\mathsf{Comp}_{\mathtt{e}}(\Gamma,\zeta,M)$, if and only if $\mathsf{App}_{\mathtt{e}}(\Gamma,\zeta,M)$ and, moreover, for all Γ' and N, $\mathsf{App}_{\mathtt{e}}(\Gamma',\vartheta,N)$ implies $\mathsf{App}_{\mathtt{e}}(\Gamma \uplus \Gamma',\zeta,MN)$;

v) $\mathsf{Comp}_{\mathtt{i}}(\Gamma,\zeta,M)$, if and only if $\mathsf{App}_{\mathtt{i}}(\Gamma,\zeta,M)$ and, moreover, for all N, $\mathsf{App}_{\mathtt{i}}(\Gamma,\zeta,MN)$;

vi) $\mathsf{Comp}_{\mathtt{e}}(\Gamma,\vartheta,M)$, if and only if $\mathsf{App}_{\mathtt{e}}(\Gamma,\vartheta,M)$ and, moreover, for all Γ' and N, $\mathsf{App}_{\mathtt{e}}(\Gamma',\zeta,N)$ implies $\mathsf{App}_{\mathtt{e}}(\Gamma \uplus \Gamma',\vartheta,MN)$;

vii) $\mathsf{Comp}_{\mathtt{i}}(\Gamma,\vartheta,M)$, if and only if $\mathsf{App}_{\mathtt{i}}(\Gamma,\vartheta,M)$ and, moreover, for all N, $\mathsf{App}_{\mathtt{i}}(\Gamma,\vartheta,MN)$;

viii) $\mathsf{Comp}_\varphi(\Gamma,\alpha\to\beta,M)$, if and only if $\mathsf{App}_\varphi(\Gamma,\omega\to\omega,M)$, and, moreover, for all N and Γ' such that Γ and Γ' are compatible bases, $\mathsf{Comp}_\varphi(\Gamma',\alpha,N)$ implies $\mathsf{Comp}_\varphi(\Gamma \uplus \Gamma',\beta,MN)$, when $\varphi \in \{\mathtt{t},\mathtt{w}\}$;

ix) $\mathsf{Comp}_\varphi(\Gamma,\alpha\to\beta,M)$, if and only if, for all Γ' and N, $\mathsf{Comp}_\varphi(\Gamma',\alpha,N)$ implies $\mathsf{Comp}_\varphi(\Gamma \uplus \Gamma',\beta,MN)$, when $\varphi \in \{\mathtt{h},\mathtt{e},\mathtt{i}\}$;

x) $\mathsf{Comp}_\varphi(\Gamma,\alpha\wedge\beta,M)$ if and only if $\mathsf{Comp}_\varphi(\Gamma,\alpha,M)$ and $\mathsf{Comp}_\varphi(\Gamma,\beta,M)$.

The predicates App_φ and Comp_φ agree with the typing rule $(\leq_\varphi)$ and depend only on the equivalence classes of terms modulo β-conversion.

Lemma 4.22 *i) If $\alpha \leq_\varphi \beta$ and $\mathsf{Comp}_\varphi(\Gamma,\alpha,M)$, then $\mathsf{Comp}_\varphi(\Gamma,\beta,M)$*[5].

ii) If $M =_\beta M'$, then $\mathsf{App}_\varphi(\Gamma,\alpha,M)$ if and only if $\mathsf{App}_\varphi(\Gamma,\alpha,M')$, and $\mathsf{Comp}_\varphi(\Gamma,\alpha,M)$ if and only if $\mathsf{Comp}_\varphi(\Gamma,\alpha,M')$.

iii) Let $z \notin FV(M)$ and $\Gamma' = \Gamma,z{:}\alpha$. Then $\mathsf{App}_\varphi(\Gamma,\alpha\to\beta,M)$, provided both $\mathsf{App}_\varphi(\Gamma',\beta,Mz)$ and $\mathsf{App}_\varphi(\Gamma,\omega\to\omega,M)$.

Proof: *i*) By easy induction on the definition of $\leq_\varphi$.

ii) For $\mathsf{App}_\varphi(\ )$, it suffices to observe that two β-convertible terms have the same approximants. For $\mathsf{Comp}_\varphi(\ )$, we reason by induction on types.

iii) We consider only the case $\varphi = \mathtt{t}$. The proof of the other cases is similar and simpler. Note that $\mathsf{App}_\varphi(\Gamma,\omega\to\omega,M)$ is always true for $\varphi \in \{\mathtt{h},\mathtt{e},\mathtt{i}\}$, since in this case $\omega =_\varphi \omega\to\omega$.

Assume that $A \in \mathcal{A}_{\mathtt{t}}(Mz)$, $\Gamma' \vdash_{\mathtt{t}} A : \beta$, and $\Gamma \vdash_{\mathtt{t}} A' : \omega\to\omega$, for some $A' \in \mathcal{A}_{\mathtt{t}}(M)$. We must prove that there exists an $\widehat{A} \in \mathcal{A}_{\mathtt{t}}(M)$ such that $\Gamma \vdash_{\mathtt{t}} \widehat{A} : \alpha\to\beta$.

If $\beta =_{\mathtt{t}} \omega$, one has $\Gamma \vdash_{\mathtt{t}} A' : \alpha\to\omega$, since $\alpha \leq_{\mathtt{t}} \omega$; hence $\widehat{A} \equiv A'$. If M is β-convertible to an abstraction, then $\lambda z.Mz =_\beta M$ and we can choose $\widehat{A} \equiv \lambda z.A$.

If $A \equiv xA_1 \ldots A_n Z$, we take $\widehat{A} \equiv xA_1 \ldots A_n$. Indeed, since $\Gamma' \vdash_{\mathtt{t}} A : \beta$, it follows from Lemma 4.13(*ii.c*) that either $\beta \geq_{\mathtt{t}} \pi\gamma$ and $\Gamma' \vdash_{\mathtt{t}} \widehat{A} : \pi$, or $\Gamma' \vdash_{\mathtt{t}} \widehat{A} : \gamma\to\beta$, for some γ with $\Gamma' \vdash_{\mathtt{t}} Z : \gamma$. Notice that $z \notin FV(M)$ implies $z \notin \widehat{A}$, so we get either $\Gamma \vdash_{\mathtt{t}} \widehat{A} : \pi$, or $\Gamma \vdash_{\mathtt{t}} \widehat{A} : \gamma\to\beta$. The condition $\Gamma \vdash_{\mathtt{t}} A' : \omega\to\omega$ forbids $\Gamma \vdash_{\mathtt{t}} \widehat{A} : \pi$ by Lemma 4.14(*ii*). As an approximant of z, the term Z is either z or $\bot$, and in both cases we must have $\alpha \leq_{\mathtt{t}} \gamma$. Thus we get $\Gamma \vdash_{\mathtt{t}} \widehat{A} : \alpha\to\beta$, as desired.

The case $A \equiv \bot A_1 \ldots A_n Z$ is excluded by Lemmas 4.13(*ii.d*) and 4.14(*ii*). □

We can now show that computability implies approximability.

[5] The same property trivially holds for $\mathsf{App}_\varphi(\ )$.

Lemma 4.23 For all $\Gamma \in \mathcal{B}_{\bar{\varphi}}$, $\alpha \in \mathsf{T}_{\bar{\varphi}}$, $L_1, \ldots, L_n$ $(0 \leq n)$, and M:

i) $\mathsf{App}_\varphi(\Gamma, \alpha, xL_1 \ldots L_n) \Rightarrow \mathsf{Comp}_\varphi(\Gamma, \alpha, xL_1 \ldots L_n)$;

ii) $\mathsf{Comp}_\varphi(\Gamma, \alpha, M) \Rightarrow \mathsf{App}_\varphi(\Gamma, \alpha, M)$.

Proof: We prove (*i*) and (*ii*) by simultaneous induction on α.

- α is an atomic or an applicative type. Both (*i*) and (*ii*) are true by definition of Comp and the equalities $\vartheta =_{\mathtt{e}} \zeta \to \vartheta$, $\zeta =_{\mathtt{e}} \vartheta \to \zeta$, $\vartheta =_{\mathtt{i}} \omega \to \vartheta$, and $\zeta =_{\mathtt{i}} \omega \to \zeta$.
- $\alpha \equiv \alpha_1 \to \alpha_2$.
  - *i)* Assume $\mathsf{App}_\varphi(\Gamma, \alpha, xL_1 \ldots L_n)$. Then there is an $A \in \mathcal{A}_\varphi(xL_1 \ldots L_n)$ with $\Gamma \vdash_\varphi A : \alpha_1 \to \alpha_2$. This implies $\Gamma \vdash_\varphi A : \omega \to \omega$ by rule $(\leq_\varphi)$, so, in particular, $\mathsf{App}_\varphi(\Gamma, \omega \to \omega, xL_1 \ldots L_n)$; this will be useful when $\varphi \in \{\mathtt{t}, \mathtt{w}\}$. Clearly, A can be taken of the form $xA_1 \ldots A_n$, where A_i is an approximant of L_i $(i \leq n)$.
    We need to show that $\mathsf{Comp}_\varphi(\Gamma, \alpha_1 \to \alpha_2, xL_1 \ldots L_n)$. Let Γ' be compatible with Γ, and assume $\mathsf{Comp}_\varphi(\Gamma', \alpha_1, N)$, and $\mathsf{App}_\varphi(\Gamma', \alpha_1, N)$ follows by induction on (*ii*). Hence, there is an approximant $B \in \mathcal{A}_\varphi(N)$ of type α_1 in the context Γ'. Then $AB \equiv xA_1 \ldots A_n B$ is an approximant of $xL_1 \ldots L_n N$, and $\Gamma \uplus \Gamma' \vdash AB : \alpha_2$. Thus $\mathsf{Comp}_\varphi(\Gamma \uplus \Gamma', \alpha_2, xL_1 \ldots L_n N)$ follows by induction on (*i*).
  - *ii)* Suppose $\mathsf{Comp}_\varphi(\Gamma, \alpha_1 \to \alpha_2, M)$. Now $\mathsf{App}_\varphi(\Gamma, \omega \to \omega, M)$ follows by definition (this is necessary only for $\varphi \in \{\mathtt{t}, \mathtt{w}\}$ and will be needed in the last of the following implications). Let $\Gamma' = \Gamma, z{:}\alpha_1$, where z is fresh. Since $\{z{:}\alpha_1\} \vdash_\varphi z : \alpha_1$, and $z \in \mathcal{A}_\varphi(z)$, we have $\mathsf{Comp}_\varphi(\{z{:}\alpha_1\}, \alpha_1, z)$ by induction on(*i*). Then we have

$$\begin{array}{lll} \mathsf{Comp}_\varphi(\{z{:}\alpha_1\}, \alpha_1, z) & \Rightarrow & \text{(by definition of } \mathsf{Comp}) \\ \mathsf{Comp}_\varphi(\Gamma', \alpha_2, Mz) & \Rightarrow & \text{(by induction on } ii) \\ \mathsf{App}_\varphi(\Gamma', \alpha_2, Mz) & \Rightarrow & \text{(by Lemma 4.22(}iii)) \\ \mathsf{App}_\varphi(\Gamma, \alpha_1 \to \alpha_2, M). & & \end{array}$$

- $\alpha \equiv \alpha_1 \wedge \alpha_2$.
  - *i)* We need that if $\Gamma \vdash_\varphi A : \alpha_1 \wedge \alpha_2$, then $\Gamma \vdash_\varphi A : \alpha_1$ and $\Gamma \vdash_\varphi A : \alpha_2$, which follows by rule $(\leq_\varphi)$.
  - *ii)* We need that any two approximations have a common join (refinement) (see Lemma 3.6), and that if A' refines A, A' has all the types of A in any basis (Lemma 4.14(*i*)). □

Lemma 4.24 Let $\Gamma = \{x_1{:}\beta_1, \ldots, x_n{:}\beta_n\} \in \mathcal{B}_{\bar{\varphi}}$ and $\Gamma \vdash_\varphi M : \alpha$. Assume, for $i \leq n$, $\mathsf{Comp}_\varphi(\Gamma_i, \beta_i, N_i)$. Define $\Gamma' = \biguplus_{i=1}^n \Gamma_i$. Then $\mathsf{Comp}_\varphi(\Gamma', \alpha, M[\overline{N/x}])$, where $[\overline{N/x}]$ is shorthand for $[N_1/x_1, \ldots, N_n/x_n]$.

Proof: By induction on the derivation for $\Gamma \vdash_\varphi M : \alpha$. Cases (Ax) and (ω) are immediate. Cases $(\to E)$ and $(\wedge I)$ follow by induction. Case $(\leq_\varphi)$ follows by induction and Lemma 4.22(*i*). For $\varphi = \mathtt{t}$, case $(\beta{-}exp)$ follows by induction and Lemma 4.22(*ii*).

For $(\to I)$, let $M \equiv \lambda y.P$ and $\alpha \equiv \alpha_1 \to \alpha_2$, then $\Gamma, y{:}\alpha_1 \vdash_\varphi P : \alpha_2$. Since $\lambda y.\bot$ is an approximant of $(\lambda y.P)[\overline{N/x}]$ of type $\omega \to \omega$, we have $\mathsf{App}_\varphi(\Gamma, \omega \to \omega, M[\overline{N/x}])$ (this is useful only for $\varphi \in \{\mathtt{t}, \mathtt{w}\}$).

Suppose $\mathsf{Comp}_\varphi(\Gamma'', \alpha_1, Q)$. Then, by induction

$$\mathsf{Comp}_\varphi(\Gamma' \uplus \Gamma'', \alpha_2, P[Q/y, \overline{N/x}]).$$

We can assume, without loss of generality, that $y \notin FV(N_1 \ldots N_n)$ and, therefore,

$$P[Q/y, \overline{N/x}] \equiv P[\overline{N/x}][Q/y] \text{ and } (\lambda y.P[\overline{N/x}])Q \equiv ((\lambda y.P)[\overline{N/x}])Q.$$

By the invariance of computability under β-conversion (Lemma 4.22(*ii*)), we have $\mathsf{Comp}_\varphi(\Gamma' \uplus \Gamma'', \alpha_2, ((\lambda y.P)[\overline{N/x}])Q)$, and hence

$$\mathsf{Comp}_\varphi(\Gamma', \alpha_1 \to \alpha_2, (\lambda y.P)[\overline{N/x}]).$$

For $\vdash_{\mathtt{t}}$ we need to consider also rules (ωapp) and (app). We will give the proof for (app), the proof for (ωapp) is similar and simpler. For rule (app), assume $M \equiv PQ$ and $\alpha \equiv \pi\gamma$. We get $\mathsf{Comp}_{\mathtt{t}}(\Gamma', \pi, P[\overline{N/x}])$ and $\mathsf{Comp}_{\mathtt{t}}(\Gamma', \gamma, Q[\overline{N/x}])$ by induction. Then, by Lemma 4.23(*ii*), $\mathsf{App}_{\mathtt{t}}(\Gamma', \pi, P[\overline{N/x}])$ and $\mathsf{App}_{\mathtt{t}}(\Gamma', \gamma, Q[\overline{N/x}])$. This means $\Gamma' \vdash_{\mathtt{t}} A : \pi$ for some $A \in \mathcal{A}_{\mathtt{t}}(P[\overline{N/x}])$ and $\Gamma' \vdash_{\mathtt{t}} A' : \gamma$ for some $A' \in \mathcal{A}_{\mathtt{t}}(Q[\overline{N/x}])$. Notice that, by Lemma 4.13(*ii.b*), A cannot be an abstraction, so $AA' \in \mathcal{A}_{\mathtt{t}}(M[\overline{N/x}])$. Moreover, we derive $\Gamma' \vdash_{\mathtt{t}} AA' : \pi\gamma$, so we conclude $\mathsf{Comp}_{\mathtt{t}}(\Gamma', \pi\gamma, M[\overline{N/x}])$. □

We can now prove the approximation theorem.

Theorem 4.25 (Approximation Theorem) *$\Gamma \vdash_\varphi M : \alpha$ if and only if there is $A \in \mathcal{A}_\varphi(M)$ such that $\Gamma \vdash_\varphi A : \alpha$.*

Proof: ($\Rightarrow$): Since $\mathsf{App}_\varphi(\{x{:}\beta\}, \beta, x)$ holds for any x and β, and, by Lemma 4.23(*i*), we have $\mathsf{Comp}_\varphi(\{x{:}\beta\}, \beta, x)$. We can apply Lemma 4.24 for the identity substitution to obtain $\mathsf{Comp}_\varphi(\Gamma, \alpha, M)$. We conclude using Lemma 4.23(*ii*).

($\Leftarrow$): Without loss of generality we can assume that $A \equiv (M)_\varphi^{(h)}$, for some h.

- For $\varphi \in \{\mathtt{t}, \mathtt{w}, \mathtt{h}\}$, this implies, by Definition 2.4, that there is M' such that $M \to_\beta M'$ and A is obtained from M' by replacing some subterm by $\bot$. So we get $\Gamma \vdash_\varphi M' : \alpha$, and $\Gamma \vdash_\varphi M : \alpha$ follows from rule ($\beta{-}exp$), which is admissible in $\vdash_\varphi$ for $\varphi \in \{\mathtt{w}, \mathtt{h}\}$ by Theorem 4.16(*iii*).
- For $\varphi = \mathtt{e}$, by Definition 2.4, there is M' such that $M \to_\beta M'$ and A is obtained from M' by replacing some subterm by $\bot$ and by η-reduction. Then, since types are preserved by η-expansion in $\vdash_{\mathtt{e}}$ as proved in Theorem 4.16(*iv*), $\Gamma \vdash_{\mathtt{e}} M' : \alpha$. We conclude as in previous case.
- For $\varphi = \mathtt{i}$, by Definition 2.5, there is M' such that $M \to_\beta M'$ and A is obtained from M' by:
  - replacing some subterm by $\bot$;
  - η-reduction;
  - replacing some subterm N such that $\mathcal{T}_{\mathtt{i}}(N) \geq_\eta x$ by x.

  So we get $\Gamma \vdash_{\mathtt{i}} M' : \alpha$, by Theorem 4.16(*iv*) and by Theorem 4.20(*ii*). □

5 Correspondence between trees and typings

In this section we will present the main result of the paper, namely that our type assignment systems can be used to analyze the observational behaviour represented by trees. As recalled in the introduction, similar results are present in the literature for particular notions of tree.

Ronchi della Rocca [24] proved that two terms have the same Böhm tree if and only if they have the same set of types in the standard intersection type discipline [5]. The proof of [24] is based on the notion of principal type of an approximate normal form, which is a type completely describing the approximate normal form. Principal types (as defined in [11] and used in [24]) need an infinity of type variables and this agrees with the type syntax of [5].

Another related paper is [16]: it proves that two terms have the same Lévy-Longo tree [22] if and only if they have the same set of types in the type discipline with union and intersection of [13]. Also [16] uses the notion of principal types, but it gets rid of type variables by replacing them by suitable constant types which depend on the terms involved. Lastly, [7] proves this correspondence in the case of Berarducci trees for a type assignment system quite similar to $\vdash_{\mathtt{t}}$ by taking advantage from the presence of applicative types.

In the following we shall provide an (almost) uniform proof for a theorem which considers other trees besides those of the results recalled above. More precisely, we shall prove that $\vdash_\varphi$ derives the same types for two terms M, N if and only if M, N have the same φ-trees.

In order to prove this property, we follow an approach similar to [16] and to [7] in that we do not allow an infinite set of type variables. The expressive power needed for our purposes and that could be provided by an infinity of type variables can be obtained instead by defining, as we shall do, an infinite set of constant types. These constants will also allow to define the characteristic pairs $\langle$*basis; type*$\rangle$ for approximate normal forms.

The key idea is that characteristic pairs give sufficient information to discriminate between approximate normal forms obtained by pruning (in a suitable way) different trees.

We introduce three different sets of type constants, one for each set of types ($\mathsf{T}_{\mathtt{t}}$, $\mathsf{T}_{\mathtt{wh}}$ and $\mathsf{T}_{\mathtt{ei}}$). It is easy to verify that each of these constants belong to the corresponding set of types.

Definition 5.1 *i*) Let $\theta = (\omega\omega{\to}\omega{\to}\omega){\wedge}((\omega{\to}\omega){\to}\omega\omega)$. We define ϕ_0 as the type $\omega\theta$ and, for $i \geq 0$, $\phi_{i+1} \equiv \omega(\phi_i\theta)$.

ii) Define $\psi_i^{(n)} = (\zeta{\to}\omega^i{\to}\zeta{\to}\omega^{n-i}{\to}\zeta){\wedge}\zeta$, for all $i \leq n$.

iii) Define $\chi_i^{(n)} = \zeta{\to}\vartheta^i{\to}\zeta{\to}\vartheta^{n-i}{\to}\zeta{\to}\vartheta{\wedge}\zeta$, for all $i \leq n$.

The following lemma states that for some properties we shall need in our proofs, the type constants defined above behave as type variables.

Lemma 5.2 i) If $\phi_i\alpha_1\ldots\alpha_m \leq_{\mathtt{t}} \phi_j\beta_1\ldots\beta_n$ and $\alpha_l \not\leq_{\mathtt{t}} \theta$, $\alpha_l \not\leq_{\mathtt{t}} \phi_k\theta$, where $1 \leq l \leq m$ and $k \geq 0$, then $i = j$, $m = n$ and $\alpha_l \leq_{\mathtt{t}} \beta_l$, for $1 \leq l \leq m$.

ii) Let $\varphi \in \{\mathtt{w},\mathtt{h}\}$, then

$$\bigwedge_{i\in I}(\alpha_1^{(i)}{\to}\ldots{\to}\alpha_{n_i}^{(i)}{\to}\psi_i^{(n)}) \leq_\varphi \beta_1{\to}\ldots{\to}\beta_m{\to}\psi_j^{(n)},$$

and $n_i \leq n$, for all $i \in I$, imply $j \in I, n_j = m$ and $\beta_l \leq_\varphi \alpha_l^{(j)}$, for $1 \leq l \leq m$.

iii) Let $\varphi \in \{\mathtt{e},\mathtt{i}\}$, then

$$\bigwedge_{i\in I}(\alpha_1^{(i)}{\to}\ldots{\to}\alpha_{n_i}^{(i)}{\to}\zeta^n{\to}\chi_i^{(n)}) \leq_\varphi \beta_1{\to}\ldots{\to}\beta_m{\to}\zeta^{n-k}{\to}\chi_j^{(n)}$$

implies $j \in I$, $n_j = m-k$, $\beta_h \leq_\varphi \alpha_h^{(j)}$, for $1 \leq h \leq n_j$, and $\beta_h \leq_\varphi \zeta$, for $n_j + 1 \leq h \leq m$.

Proof: i) We first show that $m = n$. Assuming $m > n$, by Lemma 4.7(*iii*), we get $\phi_i\alpha_1\ldots\alpha_{m-n} \leq_{\mathtt{t}} \phi_j$, which implies $\alpha_{m-n} \leq_{\mathtt{t}} \theta$, whenever $j = 0$, and $\alpha_{m-n} \leq_{\mathtt{t}} \phi_{j-1}\theta$, whenever $j > 0$. Both inequalities are false by assumption. Assuming $m < n$, we get $\phi_i \leq_{\mathtt{t}} \phi_j\beta_1\ldots\beta_{n-m}$, which implies $\omega \leq_{\mathtt{t}} \phi_j\beta_1\ldots\beta_{n-m-1}$, which is false.

If $m = n$, we have $\alpha_l \leq_{\mathtt{t}} \beta_l$, for $1 \leq l \leq m$, and $\phi_i \leq_{\mathtt{t}} \phi_j$. If $i = 0$ and $j > 0$, we get $\theta \leq_{\mathtt{t}} \phi_{j-1}\theta$. If $i > 0$ and $j = 0$, we get $\phi_{i-1}\theta \leq_{\mathtt{t}} \theta$. Both inequalities are false since arrow types are incomparable with applicative types. If $i > 0$ and $j > 0$, we get $\phi_{i-1}\theta \leq_{\mathtt{t}} \phi_{j-1}\theta$, i.e., $\phi_{i-1} \leq_{\mathtt{t}} \phi_{j-1}$. We conclude that $i = j$.

ii) Note that

$$\bigwedge_{i\in I}(\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\psi_i^{(n)}) \leq_\varphi \beta_1\to\ldots\to\beta_m\to\psi_j^{(n)}$$

implies

$$\bigwedge_{i\in I}(\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\psi_i^{(n)}) \leq_\varphi \beta_1\to\ldots\to\beta_m\to\zeta\to\omega^j\to\zeta\to\omega^{n-j}\to\zeta.$$

By Lemma 4.8(*i*) and clause (*i.c*) of Definition 4.5, for some i either

$$\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\zeta \leq_\varphi \beta_1\to\ldots\to\beta_m\to\zeta\to\omega^j\to\zeta\to\omega^{n-j}\to\zeta \tag{1}$$

or

$$\begin{array}{l} l\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\zeta\to\omega^i\to\zeta\to\omega^{n-i}\to\zeta \leq_\varphi \\ l\beta_1\to\ldots\to\beta_m\to\zeta\to\omega^j\to\zeta\to\omega^{n-j}\to\zeta. \end{array}$$

The type inclusion (1) is impossible, since, by Lemma 4.8(*ii*), it requires $n_i = m+n+2$. To satisfy (5), we get $n_i + n = m + n$, i.e., $n_i = m$. Moreover, $i = j$: in fact, assuming $i \neq j$ we obtain, by Lemma 4.8(*ii*), $\omega \leq_\varphi \zeta$, which is false. The conclusion follows from Lemma 4.8(*ii*).

iii) Notice that

$$\bigwedge_{i\in I}(\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\zeta^n\to\chi_i^{(n)}) \leq_\varphi \beta_1\to\ldots\to\beta_m\to\zeta^{n-k}\to\chi_j^{(n)}$$

implies, by Lemma 4.8(*i*), for some i,

$$\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\zeta^n\to\chi_i^{(n)} \leq_\varphi \beta_1\to\ldots\to\beta_m\to\zeta^{n-k}\to\chi_j^{(n)}.$$

By Definition 5.1(*iii*), we get

$$\begin{array}{l} l\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\zeta^n\to\zeta\to\vartheta^i\to\zeta\to\vartheta^{n-i}\to\zeta\to\vartheta\wedge\zeta \leq_\varphi \\ l\beta_1\to\ldots\to\beta_m\to\zeta^{n-k}\to\zeta\to\vartheta^j\to\zeta\to\vartheta^{n-j}\to\zeta\to\vartheta\wedge\zeta. \end{array}$$

To satisfy (5), we get $n_i = m-k$, and $i = j$. In fact, assuming $n_i \neq m-k$ or $i \neq j$ we obtain, by Lemma 4.8(*ii*), $\vartheta \leq_\varphi \zeta$, or $\zeta \leq_\varphi \vartheta$, which are both false. The conclusion follows from Lemma 4.8(*ii*). □

We need to consider special kinds of bases which allow to distinguish occurrences of different variables or even different occurrences of the same variable. More precisely, in the presence of applicative types it suffices to give different types to occurrences of different variables, but in all other cases we need to give also different types to different occurrences of the same variable.

Definition 5.3 *i*) We define $\Gamma_{\mathtt{t}} \in \mathcal{B}_{\mathtt{t}}$ as the basis $\{x_n{:}\phi_n \mid n \in \mathbb{N}\}$.

ii) A basis $\Gamma \in \mathcal{B}_{\mathtt{wh}}$ is a *special basis (of degree n)* if each type declaration in Γ has the form $x{:}\bigwedge_{i\in I}(\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\psi_i^{(n)})$, where $n_i \leq n$, for all $i \in I$, and, moreover, each $\psi_i^{(n)}$ occurs only once as last type.

iii) $\Gamma \in \mathcal{B}_{\mathtt{ei}}$ is a *generalised special basis (of degree n)* if each type declaration in Γ has the form $x{:}\zeta$ or $x{:}\bigwedge_{i\in I}(\alpha_1^{(i)}\to\ldots\to\alpha_{n_i}^{(i)}\to\zeta^n\to\chi_i^{(n)})$, where $n_i \leq n$, for all $i \in I$, and, moreover, each $\chi_i^{(n)}$ occurs only once as last type.

Notice that $\Gamma_{\mathtt{t}}$ contains only applicative types, while special bases and generalised special bases contain only arrow types and atomic types. The feature of all these bases is that when we deduce from them a type which behaves like a variable for an approximate normal form, we can argue that the approximate normal form has a fixed shape, and that its components have fixed types.

Lemma 5.4 i) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} x_i A_1 \ldots A_n : \alpha$ and $\alpha \neq_{\mathtt{t}} \omega$, then α is an applicative type.

ii) For any approximate normal form A neither $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \theta$, nor $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \phi_i\theta$, for $i \geq 0$.

iii) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \phi_i$, then $A \equiv x_i$.

Proof: i) By induction on n. If $n = 0$, the thesis follows from Lemmas 4.13(*ii.a*) and 4.7(*ii*), since all types in $\Gamma_{\mathtt{t}}$ are applicative. Otherwise, by induction, $x_i A_1 \ldots A_{n-1}$ has only applicative types, and we obtain the thesis by Lemma (4.13)(*ii.c*).

ii) Assume $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \theta$. Then (*i*) forces A to be of the form $\lambda x.A'$. Recalling the definition of θ, we get, by Lemma 4.13(*ii.b*), $\Gamma_{\mathtt{t}}, x{:}\omega\omega \vdash_{\mathtt{t}} A' : \omega{\to}\omega$ and $\Gamma_{\mathtt{t}}, x{:}\omega{\to}\omega \vdash_{\mathtt{t}} A' : \omega\omega$. Then, since we can assign an applicative type to A', Lemma 4.13(*i*) and (*ii.b*) imply $A' \equiv yB_1 \ldots B_n$, for some $y, n, B_1, \ldots, B_n$. Hence, we get $\Gamma_{\mathtt{t}}, x{:}\omega\omega \vdash_{\mathtt{t}} y : \alpha_1{\to}\ldots{\to}\alpha_n{\to}\omega{\to}\omega$, for some $\alpha_1, \ldots, \alpha_n$. This is impossible by Lemma 4.13(*ii.a*) and Lemma 4.7(*ii*), since all types in $\Gamma_{\mathtt{t}}, x{:}\omega\omega$ are applicative.

Assume $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \phi_i\theta$, for some i. By Lemma 4.13(*ii.b*), we have $A \equiv x_j A_1 \ldots A_n$, for some $x_j, A_1, \ldots, A_n$. If $n = 0$ then, by Lemma 4.13(*ii.a*), we get $\phi_j \leq_{\mathtt{t}} \phi_i\theta$, which is impossible by Lemma 5.2(*i*). For $n > 0$, we have necessarily $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A_n : \theta$, which is impossible by the above.

iii) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \phi_i$ Lemma 4.13(*ii*) implies either (*.a*) $A \equiv \bot A_1 \ldots A_n A'$ or (*.b*) $A \equiv xA_1 \ldots A_n$, for some $A_1, \ldots, A_n, A', x$.

a) Then $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A' : \theta$, if $i = 0$, and $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A' : \phi_{i-1}\theta$, if $i > 0$, by Lemma 4.13(*ii.d*). Both cases are impossible by (*ii*).

b) If $n > 0$, then, by Lemma 4.13(*ii.c*), either we must deduce an arrow type for x from $\Gamma_{\mathtt{t}}$ – which is impossible by (*i*) – or A' must have type θ or $\phi_{i-1}\theta$. We conclude that $n = 0$ and $A \equiv x_i$, because if $A \equiv x_j$ we have $\phi_i \leq_{\mathtt{t}} \phi_j$ by Lemma 4.13(*ii.a*), which implies $i = j$ by Lemma 5.2(*i*). □

Lemma 5.5 i) Let $\varphi \in \{\mathtt{w}, \mathtt{h}\}$. If $A \in \mathcal{A}_\varphi$, $\Gamma = \Gamma' \uplus \{x{:}\alpha_1{\to}\ldots{\to}\alpha_m{\to}\psi_i^{(n)}\}$ is a special basis of degree n, and $\Gamma \vdash_\varphi A : \psi_i^{(n)}$, then $A \equiv xA_1 \ldots A_m$ and, for $1 \leq j \leq m$, $\Gamma \vdash_\varphi A_j : \alpha_j$.

ii) Let $\varphi \in \{\mathtt{e}, \mathtt{i}\}$. If $A \in \mathcal{A}_\varphi^{(n)}$, and $\Gamma \uplus \{x{:}\alpha_1{\to}\ldots{\to}\alpha_m{\to}\zeta^n{\to}\chi_i^{(n)}\}$ is a generalised special basis of degree n, and $\Gamma \vdash_\varphi A : \zeta^n{\to}\chi_i^{(n)}$, then, for some $k \geq 0$, there are $B_1, \ldots, B_k$, such that $A \equiv \lambda y_1 \ldots y_k.xA_1 \ldots A_m B_1 \ldots B_k$, with $x \notin \{y_1, \ldots, y_k\}$, $\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi A_j : \alpha_j$, for $1 \leq j \leq m$, and $\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi B_l : \zeta$, for $1 \leq l \leq k$.

Proof: i) From $\Gamma \vdash_\varphi A : \psi_i^{(n)}$ we get $\Gamma \vdash_\varphi A : \zeta$, so, by Lemma 4.15(*iii*), A cannot be an abstraction. Assume $A \equiv yA_1 \ldots A_p$. Then, by Lemma 4.15(*iv*), we have that $\Gamma \vdash_\varphi yA_1 \ldots A_p : \psi_i^{(n)}$ requires both $\Gamma \vdash_\varphi y : \beta_1{\to}\ldots{\to}\beta_p{\to}\psi_i^{(n)}$ as well as $\Gamma \vdash_\varphi A_j : \beta_j$, for some $\beta_1, \ldots, \beta_p$, $(1 \leq j \leq p)$. By definition of special bases, the statement with subject y must have a predicate like $\bigwedge_{l \in L}(\alpha_1^{(l)}{\to}\ldots{\to}\alpha_{n_l}^{(l)}{\to}\psi_l^{(n)})$. By Lemma 4.15(*ii*),

$$\bigwedge_{l \in L}(\alpha_1^{(l)}{\to}\ldots{\to}\alpha_{n_l}^{(l)}{\to}\psi_l^{(n)}) \leq_\varphi \beta_1{\to}\ldots{\to}\beta_p{\to}\psi_i^{(n)}.$$

By Lemma 5.2(*ii*), this implies $i \in L$, $n_i = p$ and $\beta_j \leq_\varphi \alpha_j^{(i)}$, for $1 \leq j \leq p$. By definition of special basis, $\psi_i^{(n)}$ can occur only once as last type, hence we conclude $x \equiv y$, $p = m$ and $\beta_j \leq \alpha_j$, for $1 \leq j \leq p$.

ii) Let $A \equiv \lambda y_1 \ldots y_k.zA_1 \ldots A_p$, where $k \leq n$, since $A \in \mathcal{A}_\varphi^{(n)}$. Then, by Lemma 4.15(*iii*), $\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi zA_1 \ldots A_p : \zeta^{n-k} \to \chi_i^{(n)}$. Now, to obtain $\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi zA_1 \ldots A_p : \zeta^{n-k} \to \chi_i^{(n)}$, by Lemma 4.15(*iv*) we need both

$$\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi z : \beta_1 \to \ldots \to \beta_p \to \zeta^{n-k} \to \chi_i^{(n)}$$

and

$$\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi A_j : \beta_j,$$

for some $\beta_1, \ldots, \beta_p$ $(1 \leq j \leq p)$. With a proof similar to that of the previous point, using Lemma 5.2(*iii*) instead of Lemma 5.2(*ii*), we conclude $x \equiv z$, $p = m + k$, $\beta_j \leq_\varphi \alpha_j$, for $1 \leq j \leq m$, and $\beta_j \leq_\varphi \zeta$, for $m + 1 \leq j \leq p$. □

We now associate to each approximate normal form $A \in \mathcal{A}_\varphi$ a basis $\Gamma \in \mathcal{B}_{\bar{\varphi}}$ and a type $\gamma \in \mathsf{T}_{\bar{\varphi}}$. We call the pair $\langle \Gamma; \gamma \rangle$ the φ-characteristic pair of A.

Definition 5.6 Let $A \in \mathcal{A}_{\mathtt{t}}$.

i) The $\mathtt{t}$-*characteristic type of* A, $\mathsf{ct}_{\mathtt{t}}(A)$, is defined as follows.

a) $\mathsf{ct}_{\mathtt{t}}(\lambda x_i.A) = \phi_i \to \mathsf{ct}_{\mathtt{t}}(A)$,

b) $\mathsf{ct}_{\mathtt{t}}(\bot A_1 \ldots A_n) = \omega \mathsf{ct}_{\mathtt{t}}(A_1) \ldots \mathsf{ct}_{\mathtt{t}}(A_n)$,

c) $\mathsf{ct}_{\mathtt{t}}(x_i A_1 \ldots A_n) = \phi_i \mathsf{ct}_{\mathtt{t}}(A_1) \ldots \mathsf{ct}_{\mathtt{t}}(A_n)$.

ii) The $\mathtt{t}$-*characteristic pair of* A, $\mathsf{cp}_{\mathtt{t}}(A)$, is $\langle \Gamma_{\mathtt{t}}; \mathsf{ct}_{\mathtt{t}}(A) \rangle$.

It is easy to verify that $\Gamma_{\mathtt{t}} \vdash_\varphi A : \mathsf{ct}_{\mathtt{t}}(A)$.

Definition 5.7 Let $A \in \mathcal{A}_\varphi^{(n)}$, for $\varphi \in \{\mathtt{w}, \mathtt{h}, \mathtt{e}, \mathtt{i}\}$. The φ-*characteristic pair of degree* n *of* A, $\mathsf{pp}_\varphi^{(n)}(A)$, is defined as follows.

i) $\mathsf{pp}_\varphi^{(n)}(\bot) = \langle \emptyset; \omega \rangle$

ii) If $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Gamma, x{:}\beta; \alpha \rangle$, then $\mathsf{pp}_\varphi^{(n)}(\lambda x.A) = \langle \Gamma; \beta \to \alpha \rangle$.

iii) If $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Gamma; \alpha \rangle$ and x does not occur in Γ, then $\mathsf{pp}_\varphi^{(n)}(\lambda x.A)$ is equal to $\langle \Gamma; \omega \to \alpha \rangle$.

iv) For $\varphi \in \{\mathtt{w}, \mathtt{h}\}$: assume $\mathsf{pp}_\varphi^{(n)}(A_i) = \langle \Gamma_i; \alpha_i \rangle$, for $i \leq k$, and let

$$\Gamma = \biguplus_{i=1}^{k} \Gamma_i \uplus \{x{:}\alpha_1 \to \ldots \to \alpha_k \to \psi_j^{(n)}\}$$

be a special basis of degree n. Then

$$\mathsf{pp}_\varphi^{(n)}(xA_1 \ldots A_k) = \langle \Gamma; \psi_j^{(n)} \rangle.$$

In particular, when $k = 0$, we obtain $\mathsf{pp}_\varphi^{(n)}(x) = \langle \{x{:}\psi_j^{(n)}\}; \psi_j^{(n)} \rangle$.

v) For $\varphi \in \{\mathtt{e},\mathtt{i}\}$: assume $\mathsf{pp}_\varphi^{(n)}(A_i) = \langle \Gamma_i;\alpha_i\rangle$, for $i \leq k$, and let

$$\Gamma = \biguplus_{i=1}^{k} \Gamma_i \uplus \{x{:}\alpha_1 \to \ldots \to \alpha_k \to \zeta^n \to \chi_j^{(n)}\}$$

be a generalised special basis of degree n, then

$$\mathsf{pp}_\varphi^{(n)}(xA_1 \ldots A_k) = \langle \Gamma;\zeta^n \to \chi_j^{(n)}\rangle.$$

In particular, when $k = 0$, we get $\mathsf{pp}_\varphi^{(n)}(x) = \langle \{x{:}\zeta^n \to \chi_j^{(n)}\};\zeta^n \to \chi_j^{(n)}\rangle$.

Notice that the φ-characteristic pair of an approximant, as defined above, is not uniquely determined. In fact, in order not to give too cumbersome a definition, we assumed that the definition comes implicitly equipped with a procedure for choosing names of type variables (the 'j'-subscripts), whenever needed. This choice can always be made in such a way the definition is uniquely determined and sound.

It is easy to verify that, if $A \in \mathcal{A}_\varphi^{(n)}$ and $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Gamma;\alpha\rangle$, then $\Gamma \vdash_{\mathtt{t}} A : \alpha$, for $\varphi \in \{\mathtt{w},\mathtt{h},\mathtt{e},\mathtt{i}\}$.

We can now prove that, in all cases, if the φ-characteristic pair of A is $\langle \Gamma;\gamma\rangle$ and $\Gamma \vdash_\varphi B : \gamma$ (and some conditions on the number of symbols of B or of $(B)_\varphi^{(h)}$, where h is the height of the tree of A, hold), then $A \sqsubseteq_\varphi B$, with $\sqsubseteq_\varphi$ as defined in Definition 3.9.

Lemma 5.8 i) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \alpha$ then $\alpha \not\leq_{\mathtt{t}} \theta$, $\alpha \not\leq_{\mathtt{t}} \phi_i\theta$, for all $i \geq 0$.

ii) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \pi\alpha$ and $\phi_i \not\leq_{\mathtt{t}} \pi\alpha$, for all i, then $A \equiv A_1A_2$ with $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A_1 : \pi$ and $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A_2 : \alpha$.

iii) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \phi_i \to \alpha$, then $A \equiv \lambda x_i.A'$ and $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A' : \alpha$.

iv) If $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} B : \mathsf{ct}_{\mathtt{t}}(A)$ then $A \sqsubseteq_{\mathtt{t}} B$.

Proof: i) Assume, reasoning towards a contradiction, that $\alpha \leq_{\mathtt{t}} \beta$, where either $\beta = \theta$, or $\beta = \phi_i\theta$. Then we get $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} A : \beta$, which is impossible by Lemma 5.4(*ii*).

ii) The approximate normal form A cannot be a variable by Lemma 4.13(*ii.a*), since $\phi_i \not\leq_{\mathtt{t}} \pi\alpha$, for all i. It cannot be an abstraction by Lemma 4.13(*ii.b*). Therefore A must be an application, i.e., $A \equiv A_1A_2$. Notice that A_1 cannot have an arrow type by Lemma 5.4(*i*). So we get the thesis using Lemma 4.13(*ii.c*), (*ii.d*) and (*ii.d*).

iii) By Lemma 5.4(*i*) and Lemma 4.13(*ii.d*), A can neither be a variable nor an application. So $A \equiv \lambda x_i.A'$ and we get the thesis by Lemma 4.13(*ii.b*).

iv) Suppose $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} B : \mathsf{ct}_{\mathtt{t}}(A)$. We prove that $A \sqsubseteq_{\mathtt{t}} B$ by induction on the structure of A.

- The crucial case is when $A \equiv \bot A_1 \ldots A_n$ ($n \geq 0$). Then $\mathsf{ct}_{\mathtt{t}}(A)$ has the form $\omega\alpha_1 \ldots \alpha_n$. If B has type $\mathsf{ct}_{\mathtt{t}}(A)$ in the basis $\Gamma_{\mathtt{t}}$, then, by (*ii*) and Lemma 4.13(*ii*), B must be of the form $xB_1 \ldots B_m$ or $xB_1 \ldots B_pB'_1 \ldots B'_n$ or $\bot B_1 \ldots B_pB'_1 \ldots B'_n$ where $0 \leq m < n$ and $0 \leq p$. In the first case, by (*ii*), for $i = 1,\ldots,m$, B_i has type α_{n-m+i} in $\Gamma_{\mathtt{t}}$. By induction, for $i = 1,\ldots,m$, $A_{n-m+i} \sqsubseteq_{\mathtt{t}} B_i$. Since $\bot A_1 \ldots A_{n-m} \sqsubseteq_{\mathtt{t}} x$ we infer that $A \sqsubseteq_{\mathtt{t}} B$. In the remaining cases, for $i = 1,\ldots,n$, B'_i has type α_i in $\Gamma_{\mathtt{t}}$. By induction, for $i = 1,\ldots,n$, $A_i \sqsubseteq_{\mathtt{t}} B'_i$. Since $\bot \sqsubseteq_{\mathtt{t}} xB_1 \ldots B_p$ and $\bot \sqsubseteq_{\mathtt{t}} \bot B_1 \ldots B_p$, we conclude again that $A \sqsubseteq_{\mathtt{t}} B$.
- If $A \equiv x_iA_1 \ldots A_n$ ($n \geq 0$), then $\mathsf{ct}_{\mathtt{t}}(A)$ has the form $\phi_i\alpha_1 \ldots \alpha_n$. If B has type $\mathsf{ct}_{\mathtt{t}}(A)$ in the basis $\Gamma_{\mathtt{t}}$, then by (2) and Lemma 4.13(*ii*), B must be either of the form (*.c.1*) $x_jB_1 \ldots B_m$ or (*.c.2*) $\bot B_1 \ldots B_m$.
  1) Then $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} B : \phi_i\alpha_1 \ldots \alpha_n$ implies $\phi_j\beta_1 \ldots \beta_m \leq_{\mathtt{t}} \phi_i\alpha_1 \ldots \alpha_n$, by Lemma 4.13(*ii.c*), for some β_l such that $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} B_l : \beta_l$ ($1 \leq l \leq m$). Notice that $\beta_l \not\leq_{\mathtt{t}} \theta$ and $\beta_l \not\leq_{\mathtt{t}} \phi_k\theta$ by (*i*). From this, by Lemma 5.2(*i*), we infer $i = j$, $m = n$ and $\beta_l \leq_{\mathtt{t}} \alpha_l$ for $1 \leq l \leq n$. Hence,

by induction, $A_l \sqsubseteq_{\mathtt{t}} B_l$, for $1 \leq l \leq n$, and this implies $A \sqsubseteq_{\mathtt{t}} B$.

2) Then $\omega\beta_1 \ldots \beta_m \leq_{\mathtt{t}} \phi_i\alpha_1 \ldots \alpha_n$, for some β_l $(1 \leq l \leq m)$ such that $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} B_l : \beta_l$. This case is impossible. In fact, if $m > n$ we get $\beta_{m-n} \leq_{\mathtt{t}} \theta$, whenever $i = 0$ and $\beta_{m-n} \leq_{\mathtt{t}} \phi_{i-1}\theta$, whenever $i > 0$. If $m \leq n$, we get $\omega \leq_{\mathtt{t}} \phi_i\alpha_1 \ldots \alpha_{n-m}$.

– If $A \equiv \lambda x_i.A'$, then $\mathsf{ct}_{\mathtt{t}}(A)$ has the form $\phi_i \to \alpha$. If B has type $\mathsf{ct}_{\mathtt{t}}(A)$ in $\Gamma_{\mathtt{t}}$ then B must be an abstraction $\lambda y.B'$ by Lemma 5.8(*iii*) and by a renaming of bound variables we can assume $y \equiv x_i$. Then $\Gamma_{\mathtt{t}} \vdash_{\mathtt{t}} B' : \alpha$ and induction applies.

– If $A \equiv \bot$ there is nothing to prove. □

Lemma 5.9 Let $\varphi \in \{\mathtt{w},\mathtt{h}\}$, $A \in \mathcal{A}_\varphi^{(n)}$ and $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Gamma;\alpha \rangle$. Then $B \in \mathcal{A}_\varphi$ and $\Gamma \vdash_\varphi B : \alpha$ imply $A \sqsubseteq_\varphi B$.

Proof: We prove by induction on A a stronger claim:

Let $A \in \mathcal{A}_\varphi^{(n)}$, $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Delta;\alpha \rangle$ and Γ be a special basis of degree n which contains Δ. Then $B \in \mathcal{A}_\varphi$ and $\Gamma \vdash_\varphi B : \alpha$ imply $A \sqsubseteq_\varphi B$.

The desired property is then obtained by taking $\Gamma = \Delta$.

- $A \equiv \lambda x.A'$. Then $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Delta;\beta\to\alpha \rangle$ and $\langle \Delta,x{:}\beta;\alpha \rangle = \mathsf{pp}(A')$, if $\beta \neq_\varphi \omega$, or $\langle \Delta;\alpha \rangle = \mathsf{pp}(A')$, otherwise. If $B \equiv \lambda x.B'$, then $\Gamma \vdash_\varphi B : \beta\to\alpha$ implies $\Gamma, x{:}\beta \vdash_\varphi B' : \alpha$ and we apply the induction hypothesis. If $B \equiv yB_1 \ldots B_m$, then $\Gamma \vdash_\varphi B : \beta\to\alpha$ implies $\Gamma \vdash_\varphi \lambda z.Bz : \beta\to\alpha$, where $z \notin FV(B)$. Therefore, from a previous case, $A \sqsubseteq_\varphi \lambda z.Bz$ and, by definition, $\lambda z.Bz \sqsubseteq_\varphi B$.
- $A \equiv xA_1 \ldots A_m$. Then $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Delta' \uplus \{x{:}\alpha_1\to \ldots \to\alpha_m\to\psi_i^{(n)}\};\psi_i^{(n)} \rangle$, where $\mathsf{pp}_\varphi^{(n)}(A_j) = \langle \Delta_j;\alpha_j \rangle$, for $1 \leq j \leq m$ and $\Delta' = \biguplus_{j=1}^m \Delta_j$. So, by Lemma 5.5(*i*), $B \equiv xB_1 \ldots B_m$ and $\Gamma \vdash_\varphi B_j : \alpha_j$, for $1 \leq j \leq m$. This implies, by induction, $A_j \sqsubseteq_\varphi B_j$, for $1 \leq j \leq m$, so we conclude $A \sqsubseteq_\varphi B$. □

Lemma 5.10 Assume $\varphi \in \{\mathtt{e},\mathtt{i}\}$, $A,B \in \mathcal{A}_\varphi$. Let h be the height of $\mathcal{T}_\varphi(A)$, and n be such that $A,(B)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$. Then $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Gamma;\alpha \rangle$ and $\Gamma \vdash_\varphi B : \alpha$ imply $A \sqsubseteq_\varphi B$.

Proof: We prove by induction on A a stronger claim:

Assume $A,B \in \mathcal{A}_\varphi$. Let h be such that $(A)_\varphi^{(h)} \equiv A$, and n be such that $A,(B)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$. Moreover, let $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Delta;\alpha \rangle$ and Γ be a generalised special basis of degree n that contains Δ. Then $\Gamma \vdash_\varphi B : \alpha$ implies $A \sqsubseteq_\varphi B$.

The desired property is then obtained by taking $\Gamma = \Delta$.

- $A \equiv \lambda x.A'$. Then $\mathsf{pp}_\varphi^{(n)}(A) = \langle \Delta;\beta\to\alpha \rangle$, and, if $\beta \neq_\varphi \omega$, then $\langle \Delta,x{:}\beta;\alpha \rangle = \mathsf{pp}(A')$, and $\langle \Delta;\alpha \rangle = \mathsf{pp}(A')$ otherwise. If $B \equiv \lambda x.B'$, then $\Gamma \vdash_\varphi B : \beta\to\alpha$ implies $\Gamma, x{:}\beta \vdash_\varphi B' : \alpha$ and we are done by induction. If $B \equiv yB_1 \ldots B_m$, then $\Gamma \vdash_\varphi B : \beta\to\alpha$ implies $\Gamma \vdash_\varphi \lambda z.Bz : \beta\to\alpha$, where $z \notin FV(B)$. Notice that, by Definitions 2.4 and 2.5, $\mathcal{T}_\varphi(\lambda z.Bz) = \mathcal{T}_\varphi(B)$, and, therefore, $(\lambda z.Bz)_\varphi^{(h)} = (B)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$. From the previous case we get $A \sqsubseteq_\varphi \lambda z.Bz$ and, by definition, $\lambda z.Bz \sqsubseteq_\varphi B$.
- $A \equiv xA_1 \ldots A_m$. Then

$$\mathsf{pp}_\varphi^{(n)}(A) = \langle \Delta' \uplus \{x{:}\alpha_1\to \ldots \to\alpha_m\to\zeta^n\to\chi_i^{(n)}\};\zeta^n\to\chi_i^{(n)} \rangle,$$

where $\mathsf{pp}_\varphi^{(n)}(A_j) = \langle \Delta_j;\alpha_j \rangle$ $(1 \leq j \leq m)$, and $\Delta' = \biguplus_{j=1}^m \Delta_j$. Then, by Lemma 5.5(*ii*), $B \equiv$

$\lambda y_1 \ldots y_k.xB_1 \ldots B_m C_1 \ldots C_k$, $\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi B_j : \alpha_j$, for $1 \leq j \leq m$, and $\Gamma \uplus \{y_1{:}\zeta, \ldots, y_k{:}\zeta\} \vdash_\varphi C_j : \zeta$, for $1 \leq j \leq k$. This implies, by induction, $A_j \sqsubseteq_\varphi B_j$, for $1 \leq j \leq m$, so we conclude, by definition, $A \sqsubseteq_\varphi B$. □

Theorem 5.11 (Main Theorem) *The following conditions are equivalent:*

i) $\mathcal{T}_\varphi(M) = \mathcal{T}_\varphi(N)$;

ii) $\Gamma \vdash_\varphi M : \alpha$ *if and only if* $\Gamma \vdash_\varphi N : \alpha$, *for all* Γ, α.

Proof: $((i) \Rightarrow (ii))$: If M and N have the same trees, then they have the same sets of approximate normal forms, and, therefore, the same types by the Approximation Theorem (Theorem 4.25).

$((ii) \Rightarrow (i))$: If $\mathcal{T}_\varphi(M) \neq \mathcal{T}_\varphi(N)$, then by Lemma 3.12 we can find an $A \in \mathcal{A}_\varphi(M)$ such that there is no $B \in \mathcal{A}_\varphi(N)$ such that $A \sqsubseteq_\varphi B$ (or vice versa).

- For $\varphi = \mathtt{t}$, $\Gamma_\mathtt{t} \vdash_\mathtt{t} M : \mathsf{ct}_\mathtt{t}(A)$ and $\Gamma_\mathtt{t} \nvdash_\mathtt{t} N : \mathsf{ct}_\mathtt{t}(A)$, by the Approximation Theorem (Theorem 4.25) and Lemma 5.8(*iv*).
- For $\varphi \in \{\mathtt{w}, \mathtt{h}\}$, let n be so big that $A \in \mathcal{A}_\varphi^{(n)}$ and $\langle \Gamma; \alpha \rangle = \mathsf{pp}_\varphi^{(n)}(A)$. We have by the Approximation Theorem (Theorem 4.25) and Lemma 5.9 that $\Gamma \vdash_\varphi M : \alpha$ and $\Gamma \nvdash_\varphi N : \alpha$.
- For $\varphi \in \{\mathtt{e}, \mathtt{i}\}$, let h be the height of $\mathcal{T}_\varphi(A)$ and n be so big that $A, (N)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$. This implies $(B)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$, for all $B \in \mathcal{A}(N)$. Moreover, let $\langle \Gamma; \alpha \rangle = \mathsf{pp}_\varphi^{(n)}(A)$. Then we have, by the Approximation Theorem (Theorem 4.25) and Lemma 5.10, $\Gamma \vdash_\varphi M : \alpha$ and $\Gamma \nvdash_\varphi N : \alpha$. □

In all cases, we get a discrimination algorithm, i.e., for two arbitrary terms M, N with different φ-trees, we can always find Γ and α such that $\Gamma \vdash_\varphi M : \alpha$ and $\Gamma \nvdash_\varphi N : \alpha$, or vice versa. The least easy case is that of $\varphi \in \{\mathtt{e}, \mathtt{i}\}$. In this case we take an approximate normal form A such that $A \in \mathcal{A}_\varphi(M)$ and there is no $B \in \mathcal{A}_\varphi(N)$ such that $A \sqsubseteq_\varphi B$ (or vice versa). Let h be the height of $\mathcal{T}_\varphi(A)$ and n be so big that $A, (N)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$. This implies $(B)_\varphi^{(h)} \in \mathcal{A}_\varphi^{(n)}$, for all $B \in \mathcal{A}(N)$. Now we can choose $\langle \Gamma; \alpha \rangle = \mathsf{pp}_\varphi^{(n)}(A)$.

Example 5.12
- $\bot\bot \in \mathcal{A}_\mathtt{t}(\mathbf{\Omega_3})$ and $\mathcal{A}_\mathtt{t}(\lambda z.\mathbf{\Omega_2}) = \{\bot, \lambda z.\bot\}$. Then $\mathsf{ct}_\mathtt{t}(\bot\bot) = \omega\omega$, and $\Gamma_\mathtt{t} \vdash_\mathtt{t} \mathbf{\Omega_3} : \omega\omega$, while $\Gamma_\mathtt{t} \nvdash_\mathtt{t} \lambda z.\mathbf{\Omega_2} : \omega\omega$.
- $\lambda z.\bot \in \mathcal{A}_\mathtt{t}(\lambda z.\mathbf{\Omega_2})$ and, for all $A \in \mathcal{A}_\mathtt{t}(\mathbf{\Omega_3})$, $\lambda z.\bot \not\sqsubseteq_\varphi A$. We observe that $\mathsf{ct}_\mathtt{t}(\lambda z.\bot) = \omega{\to}\omega$ and $\Gamma_\mathtt{t} \vdash_\mathtt{t} \lambda z.\mathbf{\Omega_2} : \omega{\to}\omega$, while $\Gamma_\mathtt{t} \nvdash_\mathtt{t} \mathbf{\Omega_3} : \omega{\to}\omega$.
- $\lambda z.\bot \in \mathcal{A}_\mathtt{w}(\lambda z.\mathbf{\Omega_2})$ and $\mathcal{A}_\mathtt{w}(\mathbf{\Omega_3}) = \{\bot\}$. We get $\mathsf{pp}_\mathtt{w}^{(3)}(\lambda z.\bot) = \langle \emptyset; \omega{\to}\omega \rangle$ and $\vdash_\mathtt{w} \lambda z.\mathbf{\Omega_2} : \omega{\to}\omega$, while $\nvdash_\mathtt{w} \mathbf{\Omega_3} : \omega{\to}\omega$.
- $\Delta_2 \in \mathcal{A}_\mathtt{h}(\Delta_2)$ and, for all $A \in \mathcal{A}_\mathtt{h}(\lambda x.x(\lambda y.xy))$, $\Delta_2 \not\sqsubseteq_\mathtt{h} A$. We get

$$\begin{array}{rcl} \mathsf{pp}_\mathtt{w}^{(4)}(\Delta_2) & = & \langle \emptyset; \psi_1^{(4)} \wedge (\psi_1^{(4)} {\to} \psi_2^{(4)}) {\to} \psi_2^{(4)} \rangle, \\ \vdash_\mathtt{h} \Delta_2 & : & \psi_1^{(4)} \wedge (\psi_1^{(4)} {\to} \psi_2^{(4)}) {\to} \psi_2^{(4)}, \text{ and} \\ \nvdash_\mathtt{h} \lambda x.x(\lambda y.xy) & : & \psi_1^{(4)} \wedge (\psi_1^{(4)} {\to} \psi_2^{(4)}) {\to} \psi_2^{(4)}. \end{array}$$

- $\mathbf{I} \in \mathcal{A}_\mathtt{e}(\mathbf{I})$ and, for all $A \in \mathcal{A}_\mathtt{e}(\mathbf{RR})$, $\mathbf{I} \not\sqsubseteq_\mathtt{e} A$. We get

$$\begin{array}{rcl} \mathsf{pp}_\mathtt{e}^{(3)}(\mathbf{I}) & = & \langle \emptyset; (\zeta^{(3)} {\to} \chi_1^{(3)}) {\to} \zeta^{(3)} {\to} \chi_1^{(3)} \rangle, \\ \vdash_\mathtt{e} \mathbf{I} & : & (\zeta^{(3)} {\to} \chi_1^{(3)}) {\to} \zeta^{(3)} {\to} \chi_1^{(3)}, \text{ and} \\ \nvdash_\mathtt{e} \mathbf{RR} & : & (\zeta^{(3)} {\to} \chi_1^{(3)}) {\to} \zeta^{(3)} {\to} \chi_1^{(3)}. \end{array}$$

- $\mathbf{I} \in \mathcal{A}_{\mathtt{i}}(\mathbf{RR})$ and, for all $A \in \mathcal{A}_{\mathtt{i}}(\mathbf{Y})$, $\mathbf{I} \not\sqsubseteq_{\mathtt{i}} A$. We get

$$\begin{array}{rcl} \mathsf{pp}_{\mathtt{i}}^{(3)}(\mathbf{I}) & = & \langle \emptyset; (\zeta^{(3)} \to \chi_1^{(3)} \to \zeta^{(3)} \to \chi_1^{(3)} \rangle), \\ \vdash_{\mathtt{i}} \mathbf{RR} & : & (\zeta^{(3)} \to \chi_1^{(3)} \to \zeta^{(3)} \to \chi_1^{(3)}), \text{ and} \\ \nvdash_{\mathtt{i}} \mathbf{Y} & : & (\zeta^{(3)} \to \chi_1^{(3)}) \to \zeta^{(3)} \to \chi_1^{(3)}. \end{array}$$

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Appendix

Definition 5.13 (Trees) *i*) A *tree* is a prefix-closed set of sequences of non-zero natural numbers such that, if $s.(n+1)$ belongs to a tree, then so does $s.n$.

ii) A *labeled tree* is a tree T equipped with a label function $\mathcal{L}_T : T \to L$, where L is the set of labels.

The set formed only by the empty sequence will denote the one-node tree, whereas the empty tree is denoted by the empty set. In the above definition, a node is identified with the path connecting it to the root.

We denote by $|s|$ the length of the sequence s. If $|s| = k$ and $h \leq k$, we can define $s_{|h}$ as the prefix of s of length h.

Definition 5.14 (Tree pruning) *i*) Given a tree T, we define $T_{|n}$, *the pruning of T at level n*, as the set of sequences in T of length $\leq n$, i.e.:

$$T_{|n} = \{s \in T \mid |s| \leq n\}.$$

Let T be a labeled tree. The label function $\mathcal{L}_{T_{|n}}$ of $T_{|n}$ is the obvious restriction of the label function of T.

ii) Given a labeled tree T and a function $f : L \to L$, where L is the set of labels of T, we define $T_{|n,f}$ as follows:

- the set of nodes of $T_{|n,f}$ coincides with that of $T_{|n}$.
- the label function $\mathcal{L}_{T_{|n,f}}$ is defined by $\mathcal{L}_{T_{|n,f}}(s) = \mathcal{L}_{T_{|n}}(s)$ if $|s| \leq n-1$, $\mathcal{L}_{T_{|n,f}}(s) = f(s)$ otherwise.

Let $L_{\mathtt{t}} = \{\bot, @, x, \lambda x \mid x \text{ is a variable }\}$, $L_{\mathtt{w}} = \{\bot, x, \lambda x \mid x \text{ is a variable }\}$, and $L_{\mathtt{h}} = L_{\mathtt{e}} = L_{\mathtt{i}} = \{\bot, \lambda y_1 \ldots y_n.x \mid y_1, \ldots, y_n, x \text{ are variables and } n \geq 0\}$. Then the φ-trees are labeled trees with sets of labels L_φ.

Definition 5.15 (Infinite η-expansion) Let T and T' be two head-trees and define $f(\lambda y_1 \ldots y_n.x) = x$ $(n \geq 0)$, $f(\bot) = \bot$. Then [6]

$$T \geq_\eta T' \Leftrightarrow \forall n.\eta(T_{|n,f}) = T'_{|n,f}.$$

Given a finite φ-tree T, it is easy to find the approximate normal form $A \in \mathcal{A}_\varphi$ such that $\mathcal{T}_\varphi(A)$ is T. For example, in the case of top trees we have the following mapping $\mathsf{m}_{\mathtt{t}} : \mathcal{T}_{\mathtt{t}} \to \mathcal{A}_{\mathtt{t}}$:f

$$\mathsf{m}_{\mathtt{t}}\left(\begin{array}{ccc} & x & \\ \diagup & & \diagdown \\ T_1 & \ldots & T_m \end{array}\right) = x\mathsf{m}_{\mathtt{t}}(T_1)\ldots\mathsf{m}_{\mathtt{t}}(T_m) \qquad \mathsf{m}_{\mathtt{t}}\left(\begin{array}{c} \lambda x \\ | \\ T \end{array}\right) = \lambda x.\mathsf{m}_{\mathtt{t}}(T)$$

$$\mathsf{m}_{\mathtt{t}}\left(\begin{array}{ccc} & @ & \\ \diagup & & \diagdown \\ T & & T' \end{array}\right) = \mathsf{m}_{\mathtt{t}}(T)\mathsf{m}_{\mathtt{t}}(T') \qquad \mathsf{m}_{\mathtt{t}}(\bot) = \bot.$$

The definitions of $\mathsf{m}_\varphi : \mathcal{A}_\varphi \to \mathcal{T}_\varphi$ for $\varphi \neq \mathtt{t}$ are similar.

Definition 5.16 (Cut with $\bot$) If g is the constant function always returning $\bot$, then $(M)_\varphi^{(h)}$, i.e., the approximate normal form whose tree is $\mathcal{T}_\varphi(M)_{|h,g}$, is defined by $(M)_\varphi^{(h)} = \mathsf{m}_\varphi(\mathcal{T}_\varphi(M)_{|h,g})$.

[6] The present definition of $\geq_\eta$ differs from the original ([4], Definition 10.2.10), but they coincide when T' is a single node whose label is a variable, and this is the only case used in the definition of infinite eta trees (Definition 2.5).