

Modelling Interacting Epidemics in Overlapping Populations

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Abstract. Epidemic modelling is fundamental to our understanding of biological, social and technological spreading phenomena. As conceptual frameworks for epidemiology advance, it is important they are able to elucidate empirically-observed dynamic feedback phenomena involving interactions amongst pathogenic agents in the form of syndemic and counter-syndemic effects. In this paper we model the dynamics of two types of epidemics with syndemic and counter-syndemic interaction effects in multiple possibly-overlapping populations. We derive a Markov model whose fluid limit reduces to a set of coupled SIR-type ODEs. Its numerical solution reveals some interesting multimodal behaviours, as shown in our case studies.

Keywords: Epidemics, Social Networks, Syndemic, Counter-syndemic

1 Introduction

You think because you understand ‘one’ you must also understand ‘two’,
because one and one make two. But you must also understand ‘and’...

Rumi (13th century Persian Poet)

Epidemics of various kinds have been an important focus of study throughout human history. As health care standards have risen and information technology has advanced over the past half century, our preoccupation with epidemics of a biological nature has lessened while our obsession with epidemics of a social and technological nature has dramatically increased. This has been accompanied by a growing realisation that many of the epidemiological techniques used in the modelling of biological diseases can be readily transplanted into social and technological domains such as content and information diffusion, rumour spreading, gossiping protocols and viral marketing.

There is one recent but crucial respect in which our conceptual understanding of biological epidemics has advanced dramatically. In particular, it has become increasingly realised that it is important to study the interplay between

pathogenic agents and between pathogenic agents and their environment. The corresponding field of study is known as *synepidemiology* in which the subjects of study are *syndemics* and *counter-syndemics* [35]. A syndemic is a set of mutually reinforcing health problems whose combined impact is more devastating than sum of the health problems in isolation (e.g. the risk developing tuberculosis is estimated to be between 12–20 times high for people with HIV [21]), while a counter-syndemic concerns a set of mutually inhibiting health problems whose combined impact is not as high as the sum of the health problems in isolation (e.g. studies suggest that a measles infection can temporarily inhibit the replication of the HIV virus [27]). Very lately, there has been a growing awareness that syndemics may also exist in a technological context: e.g. the purchase of a smartphone may make the purchase of the corresponding accessories and applications more likely [30].

In this paper, we extend the well-known Susceptible-Infected-Recovered (SIR) compartmental epidemiological model to support the interplay of multiple interacting epidemics. Our focus is on a scenario of two potentially-interacting epidemics spreading across a set of overlapping subpopulations. In this context, we derive a Markov model which describes the state changes of an individual with respect to each epidemic and whose transition rates incorporate syndemic and counter-syndemic interactions. The fluid limit of this Markov model reduces to a set of coupled SIR-type ODEs, the solution of which describes the evolution of the number of individuals infected by each epidemic.

The remainder of this paper is organised as follows. Section 2 presents an historical perspective on conceptual frameworks and modelling efforts pertinent to the field of epidemic modelling in the biological, social and technological domains. Section 3 presents our approach in extending the SIR model to support interacting epidemics, while Section 4 presents case studies of two interacting SIR epidemics propagating through two intersecting populations with various degrees of overlap. Section 5 concludes and considers avenues for future work.

2 Background

Human societies have been ravaged by biological epidemics throughout history with recurrent deadly outbreaks of bubonic plague, smallpox, yellow fever, cholera and influenza [38]. As shown in Fig. 1, the predominant early theories of disease causation were mostly supernatural, astronomical or religious, with causal agents including evil spirits, planetary motion and divine retribution. From the Middle Ages until Victorian times, it was also believed that if one inhaled *miasmas* – toxic vapors that emanated from swamps or decaying organic matter – disease would result [32]. Progress towards a more scientific and data-based approach began to be made from 1600 onwards with the collection of the first public health statistics, by John Graunt (1620–1674) [11] and others. One of the most famous studies was by John Snow of the 1854 London Cholera epidemic [36] in which he identified a particular water pump as the likely source of the outbreak.

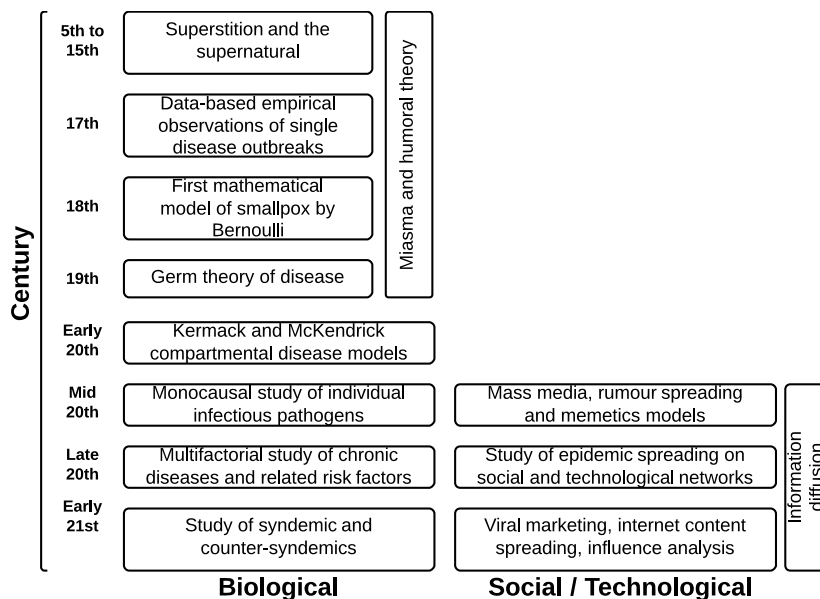


Fig. 1. The historical development of conceptual frameworks for epidemics

Predictive mathematical models for epidemics were relatively slow to develop, despite their utility in understanding, managing and forecasting epidemics. One of the earliest was by Daniel Bernoulli who carried out a study of the effects of smallpox vaccination in 1766 [9]. But arguably the most significant breakthrough came with the compartmental disease models proposed by Kermack and McKendrick in 1927 [19]. These elegantly express disease dynamics as coupled ODEs. The most well-known model is the Susceptible-Infected-Recovered (SIR) model. SIR features a closed population of individuals divided into three evolving sub-populations: $S(t)$ tracks those susceptible to become infected by the disease at time t , $I(t)$ tracks those infected by the disease with rate β and $R(t)$ tracks those who have recovered from the disease at rate γ .

The science of epidemiology has made rapid advances in recent times and has moved from monocausal studies of infectious diseases to multifactor studies of chronic diseases (e.g. obesity). It has become increasingly realised that many diseases feature a complex web of interconnected risk factors (the so-called *web of causation*), which may include relationships with other diseases and relationships between diseases and the environment. The latter point of view is central to the science of *synepidemiology* [12]. Related mathematical models have been concurrently evolving, with some studies of the dynamics of two possibly-dependent co-infections in single populations [4, 25].

Of course it is not only disease which spreads in an epidemic fashion and researchers have proved adept at progressively transplanting the corresponding theory into sociological and technological domains, especially those related to in-

formation diffusion. In the middle of the 20th century, spreading-process models for rumours, ideas and memes were proposed for the first time [5, 7, 13], followed by mathematical models of how information spreads under mass media dissemination [17, 23]. Various networks have subsequently come under the spotlight including computer networks [14], vehicular networks [39], mobile and ad-hoc networks [20], peer-to-peer file-sharing networks [22], mobile networks [34], wireless sensor networks [2, 6] and social networks [8, 16]. More recently, mathematical models were developed to yield insights into the dynamics of emerging infectious diseases from social and technological network data [3, 15, 18, 28, 29, 31]. There have also been studies analysing how user behaviour varies within user communities defined by a recommendation network [24], which creates *viral marketing* effects as well as studies about the role of centrality and influence in information diffusion within social networks [1, 26, 33, 37].

3 Epidemic Model

We focus on two interacting SIR (susceptible, infected, recovered) processes living on a finite set of overlapping subpopulations P_i constituting a population $P = \cup_i P_i$. For notational convenience, we introduce the partition \mathcal{P} of the population P induced by the overlapping sub-populations. For each part p in the partition, let its neighbourhood $\mathcal{N}(p)$ be a set of parts which includes p . Moreover, the size of the population of part p is denoted by $n(p)$.

Remark 1. The neighbourhood of any part will be used to relate an individual's view-of-the-world to its infection rate. To make this concrete, consider a simple example where there are two subpopulations with a non-empty intersection. These overlapping subpopulations induce a partition with 3 parts: the two parts of individuals that belong to one subpopulation and not to the other, and the part corresponding to the intersection. As individuals in the intersection belong to both sub-populations, their neighbourhood includes all parts. The individuals that only belong to a single sub-population only see their own sub-population. Their neighbourhood therefore consists of their own part and the intersection.

Any individual of the population is susceptible to, infected by or recovered from any of two epidemics. The state of an individual is described by a pair (k, ℓ) , with $k, \ell \in \{s, i, r\}$, where s, i and r stand for susceptible, infected and recovered, respectively and where k and ℓ refer to the first and second epidemic, respectively. We consider a Markovian epidemic model and its fluid limit. At any point in time, the state of the Markov chain is described by the number of individuals in the different states and in the different parts.

Prior to introducing the Markov chain, some additional notation is required. Let $x_{(k,\ell)}^p$ be the number of individuals of part p that are in state (k, ℓ) , and let \mathbf{x} be the vector with elements $x_{(k,\ell)}^p$, for $p \in \mathcal{P}$ and $k, \ell \in \{s, i, r\}$. The state space \mathcal{X} of the Markov chain is defined as the set of vectors \mathbf{x} such that,

$$x_{(k,\ell)}^p \in \mathbb{N} = \{0, 1, 2, \dots\}, \quad \sum_{k,\ell \in \{s,i,r\}} x_{(k,\ell)}^p = n(p) \quad \text{for all } p \in \mathcal{P}.$$

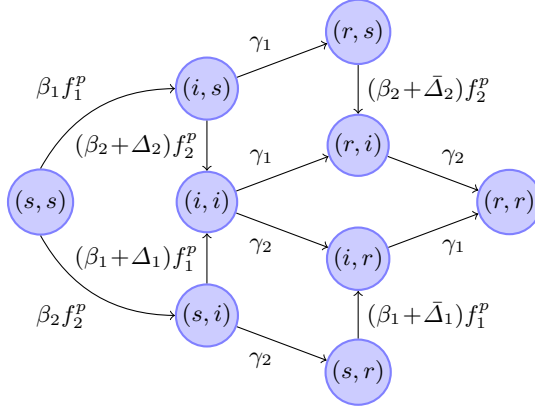


Fig. 2. Transition rates for an individual in part p .

Moreover, let $\mathbf{e}_{(k,\ell)}^p$, for $p \in \mathcal{P}$ and $k, \ell \in \{s, i, r\}$ be the obvious unit vectors of the state space \mathcal{X} . The following parameters describe the transition rates for changing states. An (s, s) -individual in part p gets infected by the first and second epidemics with rates $\beta_1 f_1^p(\mathbf{x})$ and $\beta_2 f_2^p(\mathbf{x})$, respectively. Here, $f_1^p(\mathbf{x})$ and $f_2^p(\mathbf{x})$ are the fractions of individuals that are infected by epidemic 1 and 2 in the neighbourhood of $p \in \mathcal{P}$,

$$f_1^p(\mathbf{x}) = \frac{\sum_{q \in \mathcal{N}(p)} (x_{(i,r)}^q + x_{(i,s)}^q + x_{(i,i)}^q)}{\sum_{q \in \mathcal{N}(p)} n(q)}, \quad (1)$$

$$f_2^p(\mathbf{x}) = \frac{\sum_{q \in \mathcal{N}(p)} (x_{(r,i)}^q + x_{(s,i)}^q + x_{(i,i)}^q)}{\sum_{q \in \mathcal{N}(p)} n(q)}. \quad (2)$$

If such an individual is already infected by or has already recovered from the other epidemic, the infection rate is modified. An (s, i) individual in part p gets infected by the first epidemic with rate $(\beta_1 + \Delta_1) f_1^p(\mathbf{x})$, while an (s, r) individual gets infected by the first epidemic with rate $(\beta_1 + \Delta_1) f_1^p(\mathbf{x})$. Modified infection rates are defined likewise for the second epidemic. Finally, the recovery rates of an individual from epidemic 1 and 2 are constant and equal to γ_1 and γ_2 , respectively. For clarity, the transition rates for an individual in part p are depicted in Figure 2. The infinitesimal generator \mathcal{A} of this Markov chain is:

$$\begin{aligned} \mathcal{A}g(\mathbf{x}) = & \sum_{p \in \mathcal{P}} \left(\beta_1 f_1^p(\mathbf{x}) x_{(s,s)}^p [g(\mathbf{x} - \mathbf{e}_{(s,s)}^p + \mathbf{e}_{(i,s)}^p) - g(\mathbf{x})] \right. \\ & + \beta_2 f_2^p(\mathbf{x}) x_{(s,s)}^p [g(\mathbf{x} - \mathbf{e}_{(s,s)}^p + \mathbf{e}_{(s,i)}^p) - g(\mathbf{x})] \\ & + (\beta_1 + \Delta_1) f_1^p(\mathbf{x}) x_{(s,i)}^p [g(\mathbf{x} - \mathbf{e}_{(s,i)}^p + \mathbf{e}_{(i,i)}^p) - g(\mathbf{x})] \\ & \left. + (\beta_2 + \Delta_2) f_2^p(\mathbf{x}) x_{(i,s)}^p [g(\mathbf{x} - \mathbf{e}_{(i,s)}^p + \mathbf{e}_{(i,i)}^p) - g(\mathbf{x})] \right) \end{aligned}$$

$$\begin{aligned}
& + (\beta_1 + \bar{\Delta}_1) f_1^p(\mathbf{x}) x_{(s,r)}^p [g(\mathbf{x} - \mathbf{e}_{(s,r)}^p + \mathbf{e}_{(i,r)}^p) - g(\mathbf{x})] \\
& + (\beta_2 + \bar{\Delta}_2) f_2^p(\mathbf{x}) x_{(r,s)}^p [g(\mathbf{x} - \mathbf{e}_{(r,s)}^p + \mathbf{e}_{(r,i)}^p) - g(\mathbf{x})] \\
& + \gamma_1 x_{(i,s)}^p [g(\mathbf{x} - \mathbf{e}_{(i,s)}^p + \mathbf{e}_{(r,s)}^p) - g(\mathbf{x})] \\
& + \gamma_1 x_{(i,i)}^p [g(\mathbf{x} - \mathbf{e}_{(i,i)}^p + \mathbf{e}_{(r,i)}^p) - g(\mathbf{x})] \\
& + \gamma_1 x_{(i,r)}^p [g(\mathbf{x} - \mathbf{e}_{(i,r)}^p + \mathbf{e}_{(r,r)}^p) - g(\mathbf{x})] \\
& + \gamma_2 x_{(s,i)}^p [g(\mathbf{x} - \mathbf{e}_{(s,i)}^p + \mathbf{e}_{(s,r)}^p) - g(\mathbf{x})] \\
& + \gamma_2 x_{(i,i)}^p [g(\mathbf{x} - \mathbf{e}_{(i,i)}^p + \mathbf{e}_{(i,r)}^p) - g(\mathbf{x})] \\
& + \gamma_2 x_{(r,i)}^p [g(\mathbf{x} - \mathbf{e}_{(r,i)}^p + \mathbf{e}_{(r,r)}^p) - g(\mathbf{x})], \tag{3}
\end{aligned}$$

for $\mathbf{x} \in \mathcal{X}$. Due to the considerable size of the state space \mathcal{X} , even for modest population sizes, direct computation of either transient or stationary distributions is quite forbidding. As we are mainly interested in the dynamics when the population is large, we focus on the fluid limit of the process. However, the original Markov chain will also be simulated and compared with the fluid limits.

More specifically, we consider a sequence of Markov chains with generators \mathcal{A}_N such that the population size is N for the N th Markov chain and we keep track of the fractions of populations, such that components of the state space \mathcal{X}_N of the N th Markov chain live on a lattice with step size $1/N$, and the unit vectors have size $1/N$ as well. By contrast, the transition rates increase by N as we need to translate from population fractions to population sizes. Setting $\epsilon := 1/N$, we get the following generator:

$$\begin{aligned}
\mathcal{A}_{\epsilon^{-1}} g(\mathbf{x}) = \epsilon^{-1} \sum_{p \in \mathcal{P}} & \left(\beta_1 f_1^p(\mathbf{x}) x_{(s,s)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(s,s)}^p + \epsilon \mathbf{e}_{(i,s)}^p) - g(\mathbf{x})] \right. \\
& + \beta_2 f_2^p(\mathbf{x}) x_{(s,s)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(s,s)}^p + \epsilon \mathbf{e}_{(s,i)}^p) - g(\mathbf{x})] \\
& + (\beta_1 + \Delta_1) f_1^p(\mathbf{x}) x_{(s,i)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(s,i)}^p + \epsilon \mathbf{e}_{(i,i)}^p) - g(\mathbf{x})] \\
& + (\beta_2 + \Delta_2) f_2^p(\mathbf{x}) x_{(i,s)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(i,s)}^p + \epsilon \mathbf{e}_{(i,i)}^p) - g(\mathbf{x})] \\
& + (\beta_1 + \bar{\Delta}_1) f_1^p(\mathbf{x}) x_{(s,r)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(s,r)}^p + \epsilon \mathbf{e}_{(i,r)}^p) - g(\mathbf{x})] \\
& + (\beta_2 + \bar{\Delta}_2) f_2^p(\mathbf{x}) x_{(r,s)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(r,s)}^p + \epsilon \mathbf{e}_{(r,i)}^p) - g(\mathbf{x})] \\
& + \gamma_1 x_{(i,s)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(i,s)}^p + \epsilon \mathbf{e}_{(r,s)}^p) - g(\mathbf{x})] \\
& + \gamma_1 x_{(i,i)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(i,i)}^p + \epsilon \mathbf{e}_{(r,i)}^p) - g(\mathbf{x})] \\
& + \gamma_1 x_{(i,r)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(i,r)}^p + \epsilon \mathbf{e}_{(r,r)}^p) - g(\mathbf{x})] \\
& + \gamma_2 x_{(s,i)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(s,i)}^p + \epsilon \mathbf{e}_{(s,r)}^p) - g(\mathbf{x})] \\
& + \gamma_2 x_{(i,i)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(i,i)}^p + \epsilon \mathbf{e}_{(i,r)}^p) - g(\mathbf{x})] \\
& \left. + \gamma_2 x_{(r,i)}^p [g(\mathbf{x} - \epsilon \mathbf{e}_{(r,i)}^p + \epsilon \mathbf{e}_{(r,r)}^p) - g(\mathbf{x})] \right). \tag{4}
\end{aligned}$$

We can deduce the (candidate) fluid limit by Taylor expansion of this generator around $\epsilon = 0$, from which we find a limiting generator of the form

$\hat{\mathcal{A}}g = \mathbf{h}(\mathbf{x}) \cdot \nabla g$, for a certain $9|\mathcal{P}|$ -dimensional vector function \mathbf{h} . Note that a generator of this form corresponds to a deterministic process satisfying the system of differential equations $\dot{\mathbf{x}}(t) = \mathbf{h}(\mathbf{x}(t))$.

In order to prove this limit rigourously, it needs to be checked that both the pre-limit processes and the limit process are Feller processes [10], which basically boils down to checking the so-called Hille-Yosida conditions. We believe that a careful proof of this statement falls outside the scope of this paper, but remark that due to the compactness of the state space (in the prelimit as well as in the limit), the proof is not as involved as is sometimes the case. Below we detail the set of differential equations, where we have dropped the dependence of t for notational convenience.

After some manipulations we find the following fluid limit which not only generalises syndemics in a single population but also epidemics on a stratified population:

$$\begin{aligned}
\dot{x}_{(s,s)}^p &= -\beta_1 y_1^p x_{(s,s)}^p - \beta_2 y_2^p x_{(s,s)}^p \\
\dot{x}_{(i,s)}^p &= \beta_1 y_1^p x_{(s,s)}^p - (\beta_2 + \Delta_2) y_2^p x_{(i,s)}^p - \gamma_1 x_{(i,s)}^p \\
\dot{x}_{(s,i)}^p &= \beta_2 y_2^p x_{(s,s)}^p - (\beta_1 + \Delta_1) y_1^p x_{(s,i)}^p - \gamma_2 x_{(s,i)}^p \\
\dot{x}_{(i,i)}^p &= (\beta_2 + \Delta_2) y_2^p x_{(i,s)}^p + (\beta_1 + \Delta_1) y_1^p x_{(s,i)}^p - (\gamma_1 + \gamma_2) x_{(i,i)}^p \\
\dot{x}_{(r,s)}^p &= \gamma_1 x_{(i,s)}^p - (\beta_2 + \bar{\Delta}_2) y_2^p x_{(r,s)}^p \\
\dot{x}_{(r,i)}^p &= (\beta_2 + \bar{\Delta}_2) y_2^p x_{(r,s)}^p + \gamma_1 x_{(i,i)}^p - \gamma_2 x_{(r,i)}^p \\
\dot{x}_{(i,r)}^p &= (\beta_1 + \bar{\Delta}_1) y_1^p x_{(s,r)}^p + \gamma_2 x_{(i,i)}^p - \gamma_1 x_{(i,r)}^p \\
\dot{x}_{(s,r)}^p &= \gamma_2 x_{(s,i)}^p - (\beta_1 + \bar{\Delta}_1) y_1^p x_{(s,r)}^p \\
\dot{x}_{(r,r)}^p &= \gamma_1 x_{(i,r)}^p + \gamma_2 x_{(r,i)}^p \\
y_1^p &= \frac{\sum_{q \in \mathcal{N}(p)} (x_{(i,s)}^q + x_{(i,i)}^q + x_{(i,r)}^q)}{\sum_{q \in \mathcal{N}(p)} \nu(p)} \\
y_2^p &= \frac{\sum_{q \in \mathcal{N}(p)} (x_{(s,i)}^q + x_{(i,i)}^q + x_{(r,i)}^q)}{\sum_{q \in \mathcal{N}(p)} \nu(q)},
\end{aligned}$$

for $p \in \mathcal{P}$. The fractions y_1^p and y_2^p were introduced in the set of ODEs to simplify notation: $y_i^p(t)$ is the fraction of individuals that are infected by epidemic i in the neighbourhood of p .

4 Case Studies

With the ODEs established we now focus on some numerical examples. To limit the number of parameters, we investigate the spread of two epidemics, say e_1 and e_2 , on two intersecting populations. For both epidemics, the spreading and recovery parameters are set to $\beta_i = 0.4$ and $\gamma_i = 0.1$ ($i = 1, 2$), respectively.

There are two populations. Population $P1$ constitutes 30% of the total population. The population $P2$ constitutes 70% of the total population. The fraction of the individuals in the intersection of both populations – referred to as the degree of overlap – is denoted by ν and assumed to be 0.01% unless indicated otherwise. For a fixed ν , $30\% - \nu/2$ and $70\% - \nu/2$ of the individuals are in $P1$ and not in $P2$ and in $P2$ and not in $P1$, respectively.

For all case studies $\bar{\Delta}_1 = \Delta_1$ and $\bar{\Delta}_2 = \Delta_2$. Epidemic e_1 begins in the non-intersecting population $P1$ at time 0, and epidemic e_2 begins in the non-intersecting population $P2$ at time 0. The initial number of infected individuals is 1% for each epidemic, and no individuals are infected by both epidemics at the start. With the parameters fixed, we now investigate how spreading of the epidemics is affected by (i) the size of the intersection, (ii) syndemic effects and (iii) counter-syndemic effects.

Case Study 1: Influence of Degree of Overlap Fig. 3 shows the influence of the degree of overlap ν between the populations on the spread of e_1 and e_2 . We see that the smaller the intersection, the more significant the delay of the propagation of the epidemics between the populations. With values of ν above 1%, the results are increasingly indistinguishable from epidemics spreading in a single population. The multimodality of the spread over time is quite apparent. The epidemics first reach their peak in the population in which they originated. Only after sufficiently many individuals in the intersection are affected, spreading in the other population starts, reaching its peak considerably later, even though the spreading mechanism is exactly the same in both populations and for both epidemics. Finally note that the first peak of e_2 is considerably higher than the first peak of e_1 while the opposite is observed for the second peak which is in line with the sizes of the populations the epidemics originate from.

Case Study 2: The Impact of Syndemic Effects Fig. 4 shows how syndemic effects affect the evolution of the epidemics. We consider three cases. For $\Delta_1 = \beta = 0.4$ and $\Delta_2 = 0$, the second epidemic reinforces spreading of the first. Specifically, if an individual is infected by the second epidemic, its infection rate for the first epidemic is doubled. For $\Delta_2 = \beta = 0.4$ and $\Delta_1 = 0$, the first epidemic reinforces spreading of the second in a similar manner. Finally, for $\Delta_1 = \Delta_2 = \beta = 0.4$, both epidemics reinforce each other. For $\Delta_1 = 0, \Delta_2 = 0.4$ for e_1 corresponds to the case where there are no syndemic effects on e_1 . Comparison with the other e_1 curves clearly reveals the syndemic effects. Particularly note that when both epidemics reinforce each other, the peak of e_1 is sooner and a little higher. This is explained by the fact that e_1 affects the spread of e_2 which in turn reinforces the spread of e_1 . Similar observations apply to e_2 .

Case study 3: The Impact of Counter-syndemic Effects Fig. 5 shows the impact of counter-syndemic effects. We consider three cases. For $\Delta_1 = -\beta = -0.4$ and $\Delta_2 = 0$, an individual infected by the second epidemic is immune to the

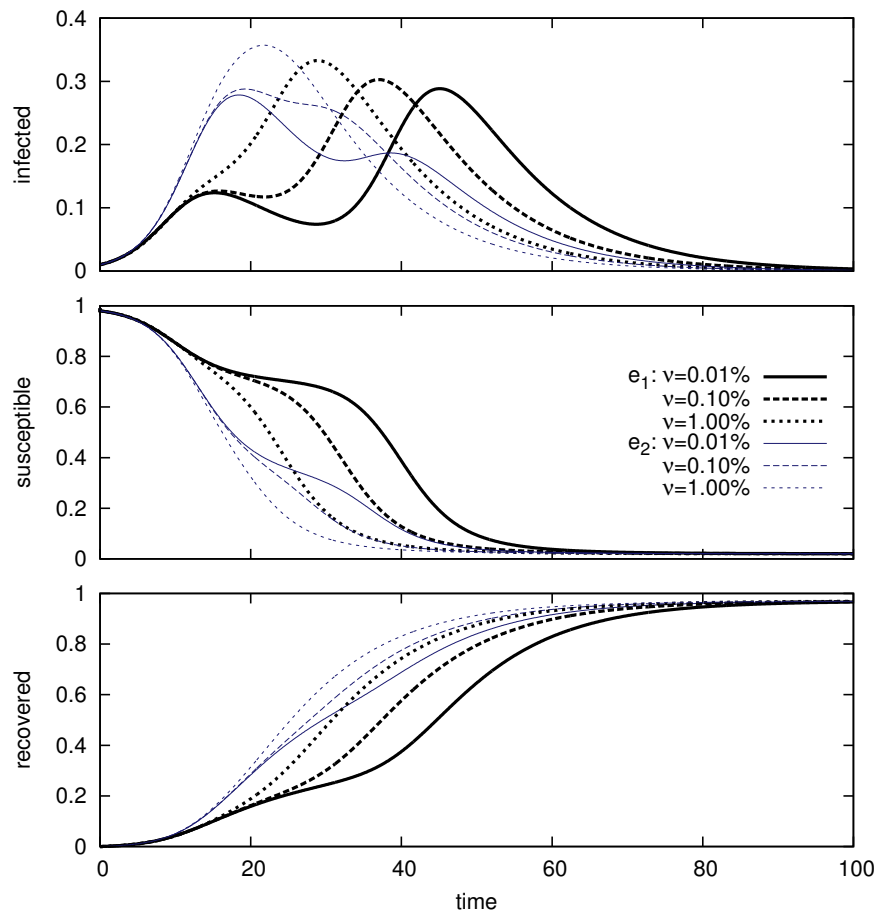


Fig. 3. Evolution of the fractions of infected, susceptible and recovered individuals for epidemics e_1 and e_2 and for different sizes of the intersection ν as indicated.

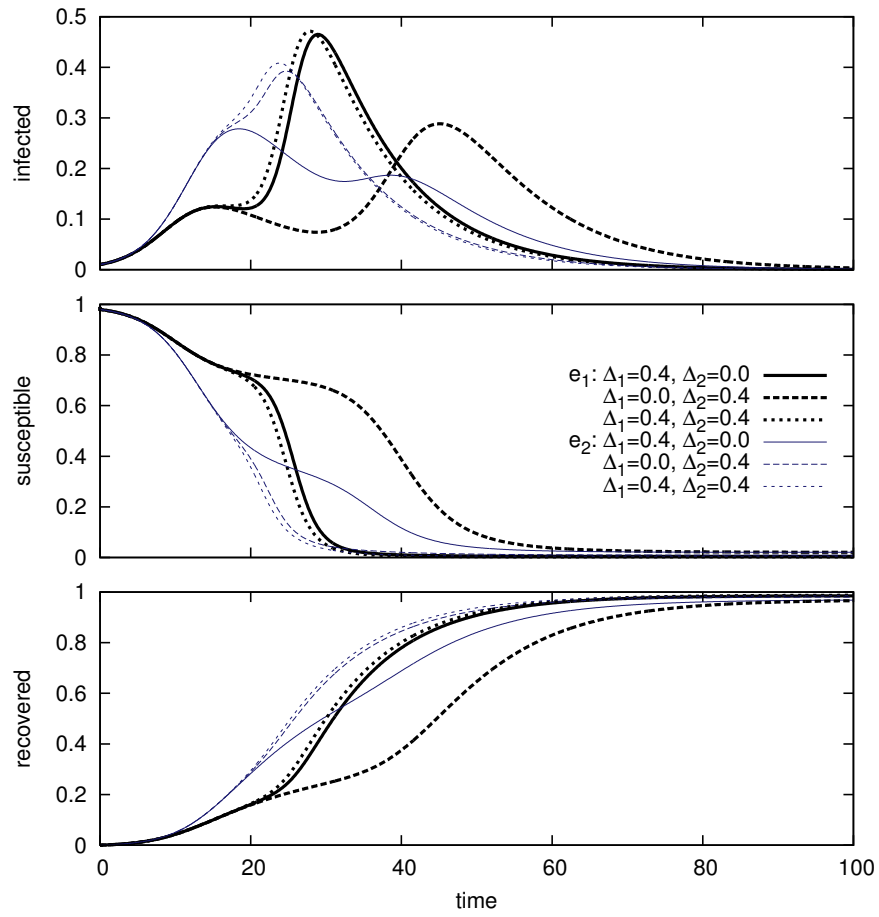


Fig. 4. Syndemic effects on the evolution of epidemics e_1 and e_2 .

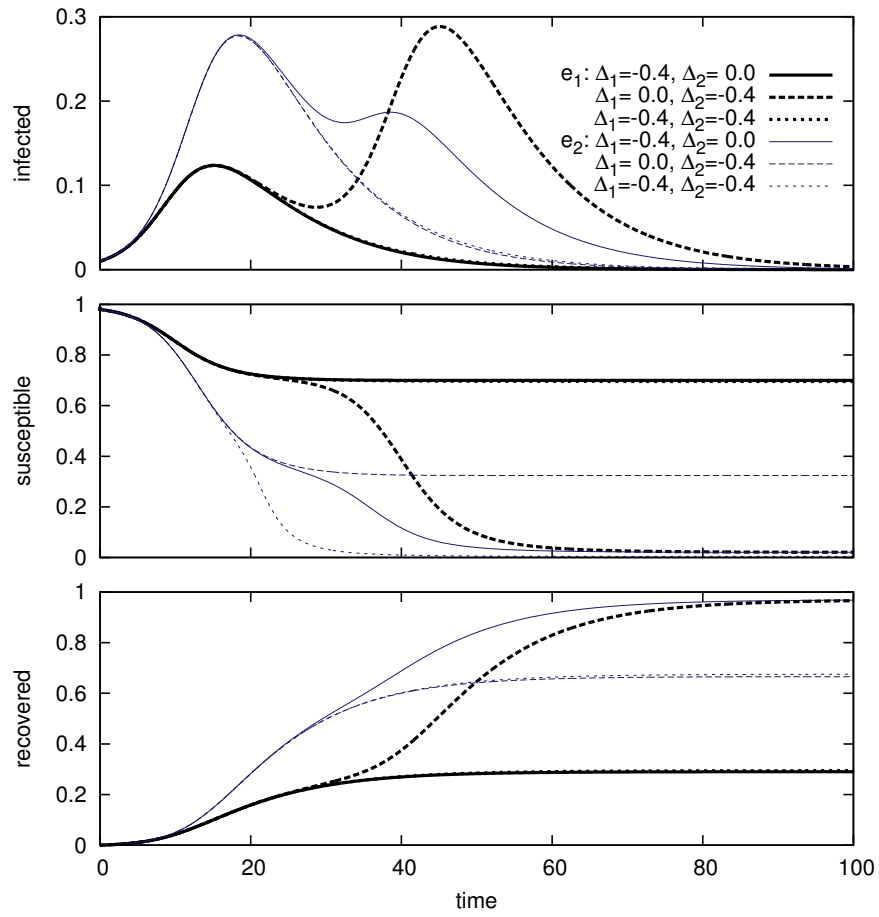


Fig. 5. Counter-syndemic effects on the evolution of epidemics e_1 and e_2 .

first epidemic. For $\Delta_2 = -\beta = -0.4$ and $\Delta_1 = 0$, an individual infected by the first epidemic is immune to the second epidemic. Finally, for $\Delta_1 = \Delta_2 = -\beta = -0.4$, immunity works both ways. As similar effects apply for both epidemics, we focus on e_1 . Clearly, for $\Delta_2 = -\beta = -0.4$ and $\Delta_1 = 0$, the first epidemic is not affected by syndemic effects. Hence, the e_1 curve for $\Delta_2 = -\beta = -0.4$ and $\Delta_1 = 0$ can be used as reference. Comparing this curve with the other e_1 curves clearly illustrates counter-syndemic effects. In fact, the second peak of the epidemic is no longer present. This is explained by noting that this peak was reached in the population where the second epidemic originates. By the time the first epidemic reaches this population, most of its individuals are already immune. Finally, note that a large proportion of the population remains susceptible to the first epidemic.

5 Conclusion

It is important that the sophistication of mathematical modelling techniques keeps pace with our evolving understanding of the dynamics of epidemic processes, especially as they become applied in myriad domains beyond the biological. Our present paper has made some progress in this direction by considering models of syndemic and counter-syndemic interactions between two SIR epidemics in multiple overlapping populations. The results from this kind of analysis can give insights into epidemic forecasting and optimal strategies for managing the response to outbreaks.

Much more remains to be done. For example, while the present work targets fluid limits, other scalings leading to diffusion limits may shed light on the variance of outcomes. In addition, our populations are assumed to be static when a more realistic model might assume some dynamic movement of individuals between populations (practically realised as facilities to join and leave populations). Practical case studies could also be carried out in application areas ranging from computer viruses to extreme ideologies.

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