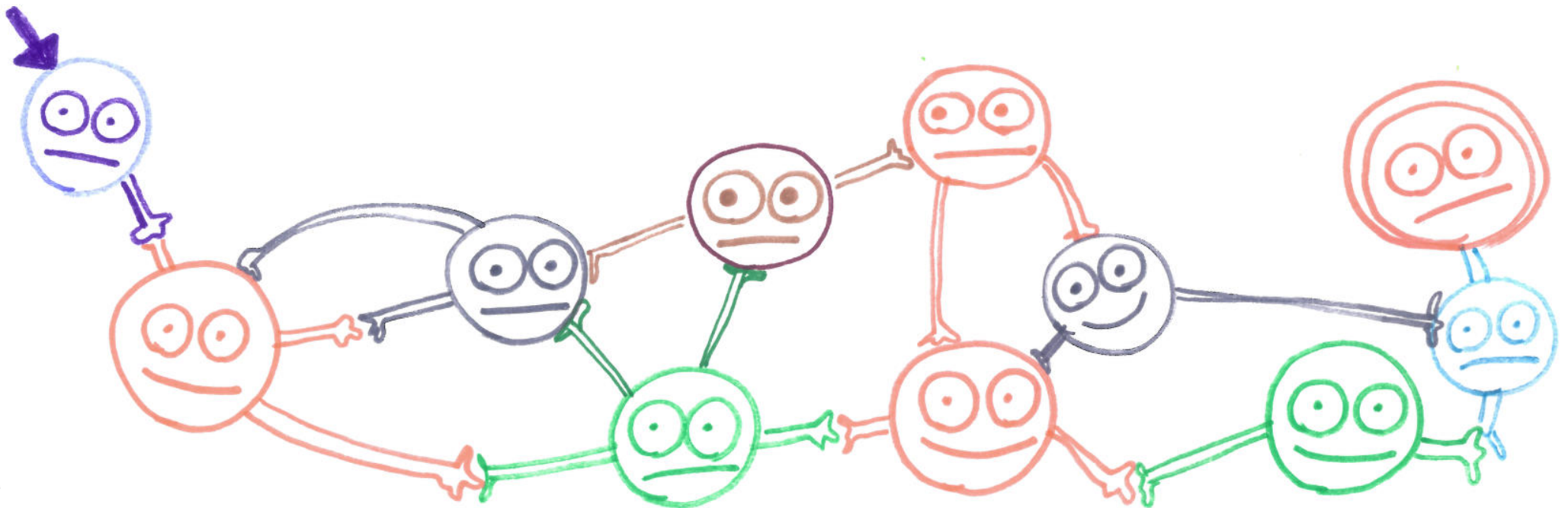


Multiparty Compatibility in Communicating Automata

Synthesis and Characterisation of Multiparty Session Types

Nobuko Yoshida

Pierre-Malo Denielóu



The Kohei Honda Prize for Distributed Systems Queen Mary, University of London

Posted with permission from QMUL on 17th Dec 2013. [Original article](#) written by Edmund Robinson.

This prize was instituted in 2013 and is awarded annually to one undergraduate student and one postgraduate student in recognition of their achievement in applying the highest quality scientific and engineering principles in the broad area of Distributed Systems. This is the area in which Dr Honda concentrated most of his teaching, and it is also the area in which he conducted his research. Its primary funding comes from a donation from his family, who wished to commemorate Dr Honda in this way. Additional funding has come from Dr Honda's own ETAPS Award. This prize is sponsored by Springer Verlag, and awarded annually by the ETAPS committee in recognition of an individual's research contribution. Dr Honda received the first such award posthumously, and the awarding panel expressed a wish that the funding be used to supplement this prize fund. The laudation for this award, written by Dr Honda's colleague, Prof Vladimiro Sassone is included later.

About Dr Honda

Kohei Honda was born and lived the first part of his life in Japan. Like many scientists he was fascinated by the idea of finding basic explanatory theories, like the physicists looking for grand unified theories of the universe. Kohei, though, was passionately interested in finding the right basic explanatory theory for the process of computation. Most academics agree that the basic theory



Winners 2013



Ms Anna Pawlicka

2013 winner (Undergraduate) source: QMUL



Mr. Valdmir Negacevshi

2013 winner (Postgraduate) source: QMUL

Selected Publications 2015/2016



- **[FPL'16]** Xinyu Niu , Nicholas Ng , Tomofumi Yuki , Shaojun Wang , NY, Wayne Luk : EURECA
Compilation: Automatic Optimisation of Cycle-Reconfigurable Circuits.
- **[ECOOP'16]** Alceste Scala, NY: Lightweight Session Programming in Scala
- **[CC'16]** Nicholas Ng, NY: Static Deadlock Detection for Concurrent Go by Global Session Graph Synthesis.
- **[FASE'16]** Raymond Hu, NY: Hybrid Session Verification through Endpoint API Generation.
- **[TACAS'16]** Julien Lange, NY: Characteristic Formulae for Session Types.
- **[ESOP'16]** Dimitrios Kouzapas, Jorge A. Pérez, NY: On the Relative Expressiveness of Higher-Order Session Processes.
- **[POPL'16]** Dominic Orchard, NY: Effects as sessions, sessions as effects .
- **[FSTTCS'15]** Romain Demangeon, NY: On the Expressiveness of Multiparty Session Types.
- **[OOPSLA'15]** Hugo A. López, Eduardo R. B. Marques, Francisco Martins, Nicholas Ng, César Santos, Vasco Thudichum Vasconcelos, NY: Protocol-Based Verification of Message-Passing Parallel Programs .
- **[CONCUR'15]** Dimitrios Kouzapas, Jorge A. Pérez, NY: Characteristic Bisimulations for Higher-Order Session Processes .
- **[CONCUR'15]** Laura Bocchi, Julien Lange, NY: Meeting Deadlines Together.
- **[CONCUR'15]** Marco Carbone, Fabrizio Montesi, Carsten Schürmann, NY: Multiparty Session Types as Coherence Proofs.
- **[CC'15]** Nicholas Ng, Jose G.F. Coutinho, NY: Protocols by Default: Safe MPI Code Generation based on Session Types.
- **[PPoPP'15]** Tiago Cogumbreiro, Raymond Hu, Francisco Martins, NY: Dynamic deadlock verification for general barrier synchronisation.
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OOI Collaboration

OOI OCEAN OBSERVATORY INITIATIVE CREATE ACCOUNT SIGN I

Location CURRENT LOCATION FILTER

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Last Viewed: 2011-12-15
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- Gorgonian Coral**
Last Modified: 2011-06-15
Last Viewed: 2011-12-15
Last Updated: 2011-12-30, 13.24
- Acoustic Release**
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Last Viewed: 2011-12-15
Last Updated: 2011-12-30, 13.24

POPULAR RESOURCES

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Last Updated: 2011-12-30, 13.24

UNUSUAL EVENTS

- Oregon Coast Wave Height**
Last Modified: 2011-06-15
Last Viewed: 2011-12-15
Last Updated: 2011-12-30, 13.24
- Water Surface Elevation**
Last Modified: 2011-06-15
Last Viewed: 2011-12-15
Last Updated: 2011-12-30, 13.24

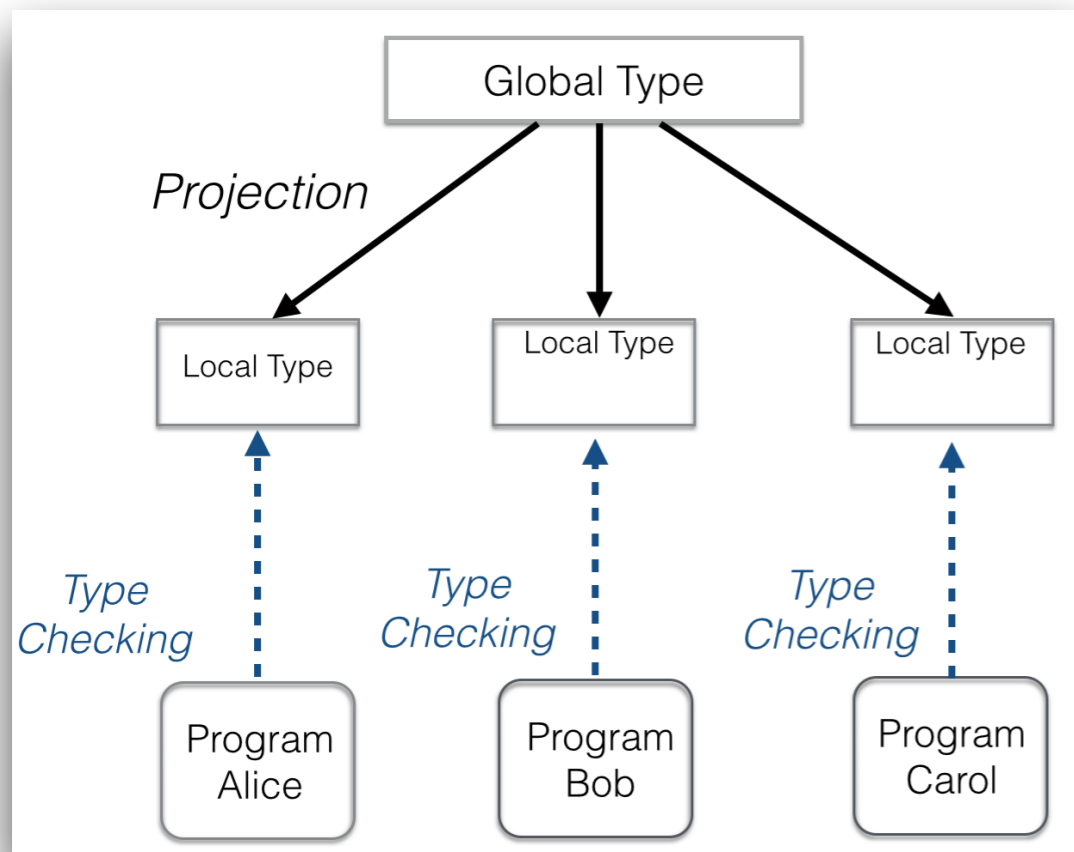
RECENT UPDATES

NAME	DATE	TYPE	EVENT	DESCRIPTION	NOTE
01 m Oregon Coast North Salinity	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
01 m California South 100m pH	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
01 m California South salinity	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
03 m Oregon North Turbidity	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
05 m Oregon South Temperature	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
20 m Oregon Coast Currents	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
01 h California South Seismology	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
01 h Oregon Coast South 1000m O ₂	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
02 h California Coast Seismology	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here
04 h California North Seismology	2012-01-10 23:55:55	Type	Event	Description goes here	Note goes here

FACEPAGE RELATED COMPOSITE STATUS

- **TCS'16:** Monitoring Networks through Multiparty Session Types. Laura Bocchi , Tzu-Chun Chen , Romain Demangeon , Kohei Honda , Nobuko Yoshida
- **LMCS'16:** Multiparty Session Actors. Romyana Neykova, Nobuko Yoshida
- **FMSD'15:** Practical interruptible conversations: Distributed dynamic verification with multiparty session types and Python. Romain Demangeon , Kohei Honda , Raymond Hu , Romyana Neykova , Nobuko Yoshida
- **TGC'13:** The Scribble Protocol Language. Nobuko Yoshida , Raymond Hu , Romyana Neykova , Nicholas Ng

Session Types Overview



- ▶ Global session type

$$G = A \rightarrow B : \langle U_1 \rangle . B \rightarrow C : \langle U_2 \rangle . C \rightarrow A : \langle U_3 \rangle$$

- ▶ Local session type

- ▶ Slice of global protocol relevant to one role
- ▶ Mechanically derived from a global protocol

$$T_A = !\langle B, U_1 \rangle . ?\langle C, U_3 \rangle$$

- ▶ Process language

- ▶ Execution model of I/O actions by session participants
- ▶ Mechanically derived from a global protocol

$$P_A = a[A](x) . x ! \langle B, u_1 \rangle . x ? (C, y)$$

- ▶ (Static) type checking for communication safety and progress

Scribble: Describing Multi Party Protocols

Scribble is a language to describe application-level protocols among communicating systems. A protocol represents an agreement on how participating systems interact with each other. Without a protocol, it is hard to do meaningful interaction: participants simply cannot communicate effectively, since they do not know when to expect the other parties to send data, or whether the other party is ready to receive data. However, having a description of a protocol has further benefits. It enables verification to ensure that the protocol can be implemented without resulting in unintended consequences, such as deadlocks.

Describe

Scribble is a language for describing multiparty protocols from a global, or endpoint neutral, perspective.

Verify

Scribble has a theoretical foundation, based on the Pi Calculus and Session Types, to ensure that protocols described using the language are sound, and do not suffer from deadlocks or livelocks.

Project

Endpoint projection is the term used for identifying the responsibility of a particular role (or endpoint) within a protocol.

Implement

Various options exist, including (a) using the endpoint projection for a role to generate a skeleton code, (b) using session type APIs to clearly describe the behaviour, and (c) statically verify the code against the projection.

Monitor

Use the endpoint projection for roles defined within a Scribble protocol, to monitor the activity of a particular endpoint, to ensure it correctly implements the expected behaviour.

Online tool : <http://scribble.doc.ic.ac.uk/>

```
1 module examples;
2
3 global protocol HelloWorld(role Me, role World) {
4     hello() from Me to World;
5     choice at World {
6         goodMorning1() from World to Me;
7     } or {
8         goodMorning1() from World to Me;
9     }
10 }
```

Load a sample 

Check

Protocol:

Role:

Project

Generate Graph

Interactions with Industries

Strange Loop

SEPTEMBER 15-17 2016 / PEABODY OPERA HOUSE / ST. LOUIS, MO



Nobuko Yoshida
Imperial College, London

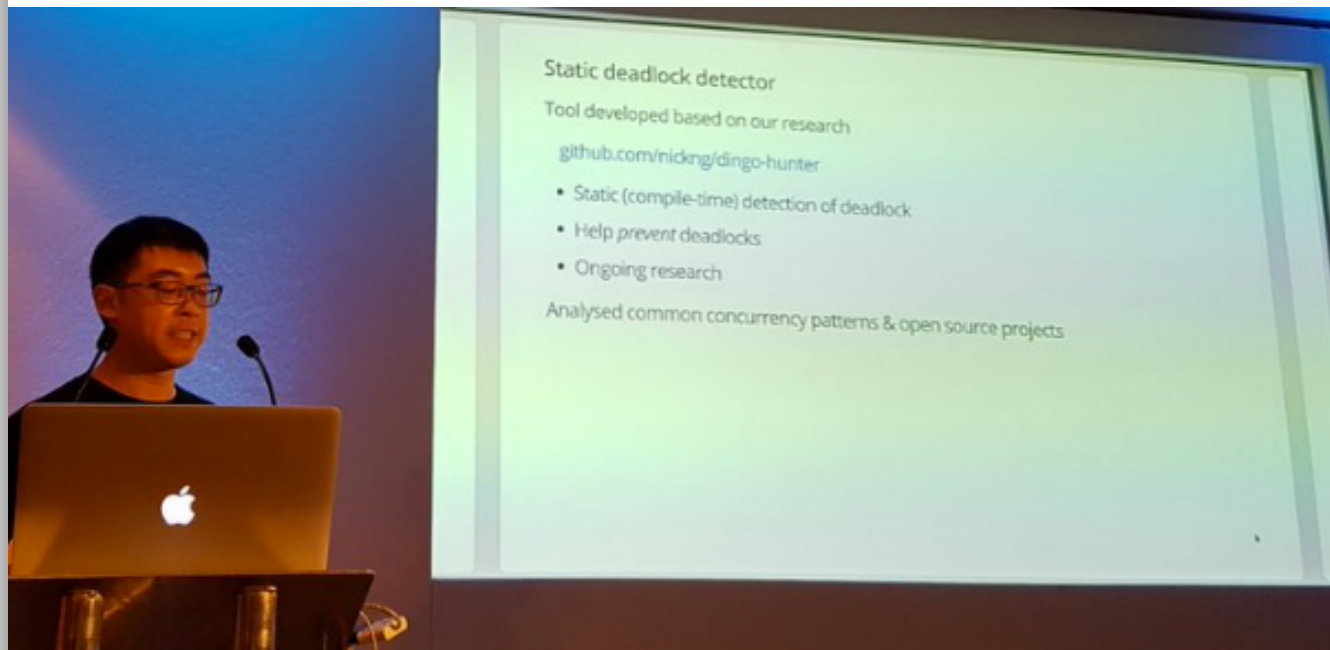


Adam Bowen @adamnbowen · Sep 15

I didn't even know that session types existed an hour ago, but thanks to Nobuko Yoshida's great talk at [#pwlconf](#), I want to learn more.

DoC researcher to speak at Golang UK conference

by Vicky Kapogianni
20 July 2016



DoC researcher to speak at industry-focused Golang UK conference on results of concurrency research

[Click here to add content](#)



.@nicholascwng rocking on @GolangUKconf about static deadlock detection in [#golang](#) [#gouk16](#)



Interactions with Industries

F#unctional Londoners Meetup Group

6 days ago · 6:30 PM

Session Types with Fahd Abdeljallal



43 Members

Synopsis: Session types are a formalism to codify the structure of a communication, using types to specify the communication protocol used. This formalism provides the... [LEARN MORE](#)

Distributed Systems vs. Compositionality

Dr. Roland Kuhn
@rolandkuhn — CTO of Actyx

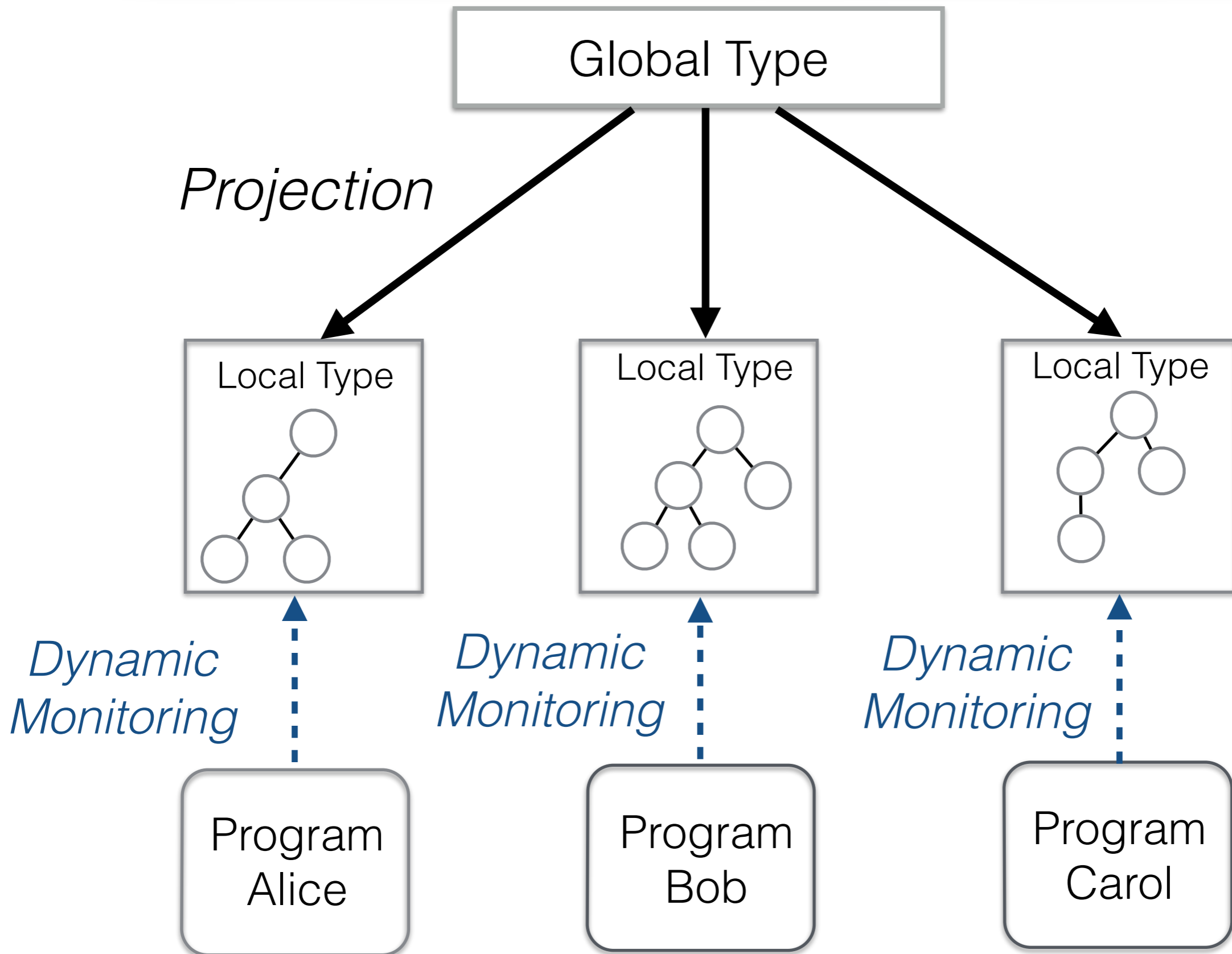
actyx

Current State

- behaviors can be composed both sequentially and concurrently
- effects are not yet tracked
- Scribble generator for Scala not yet there
- theoretical work at Imperial College, London (Prof. Nobuko Yoshida & Alceste Scalas)

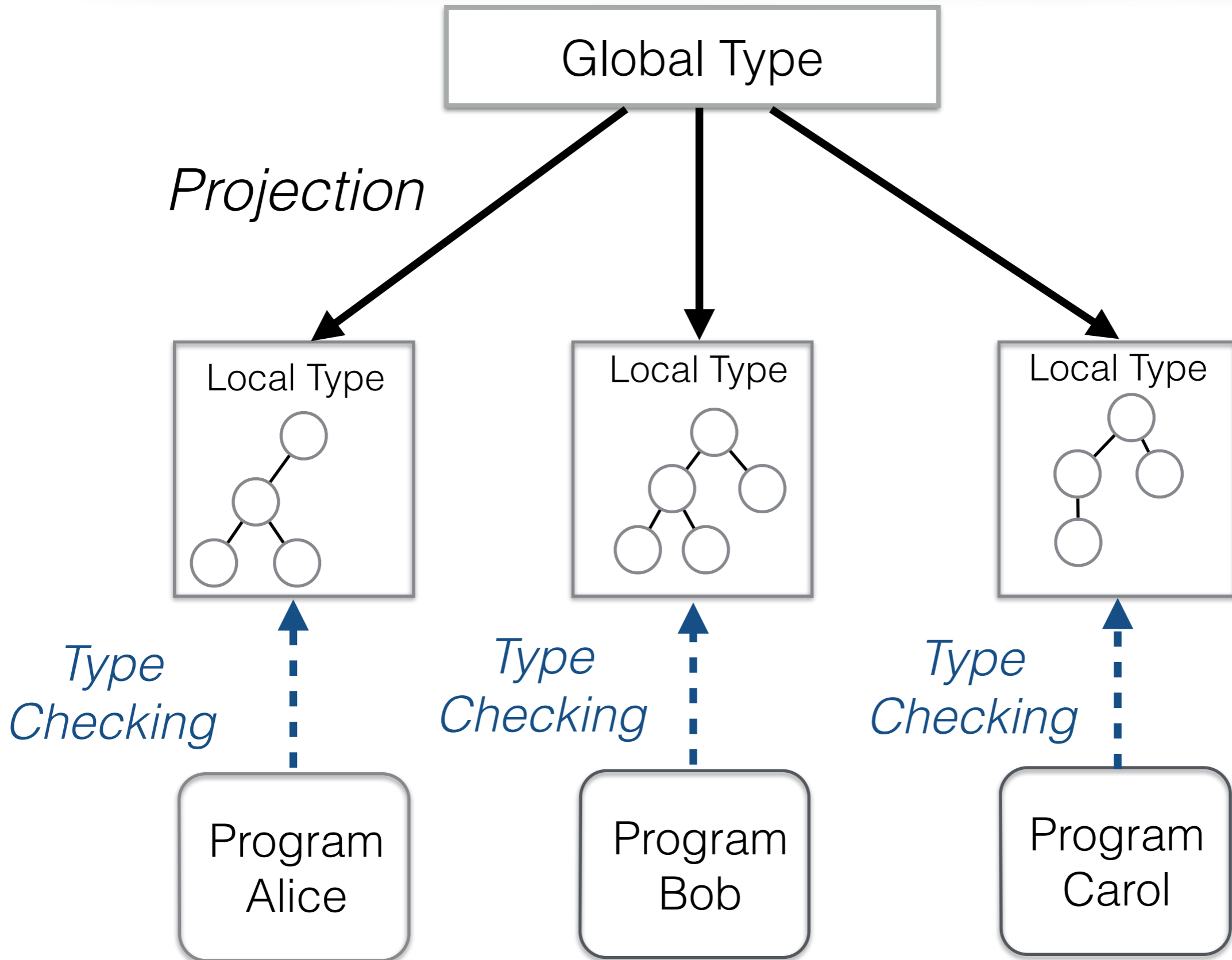
Dynamic Monitoring

[RV'13, COORDINATION'14, FMSSD'15]

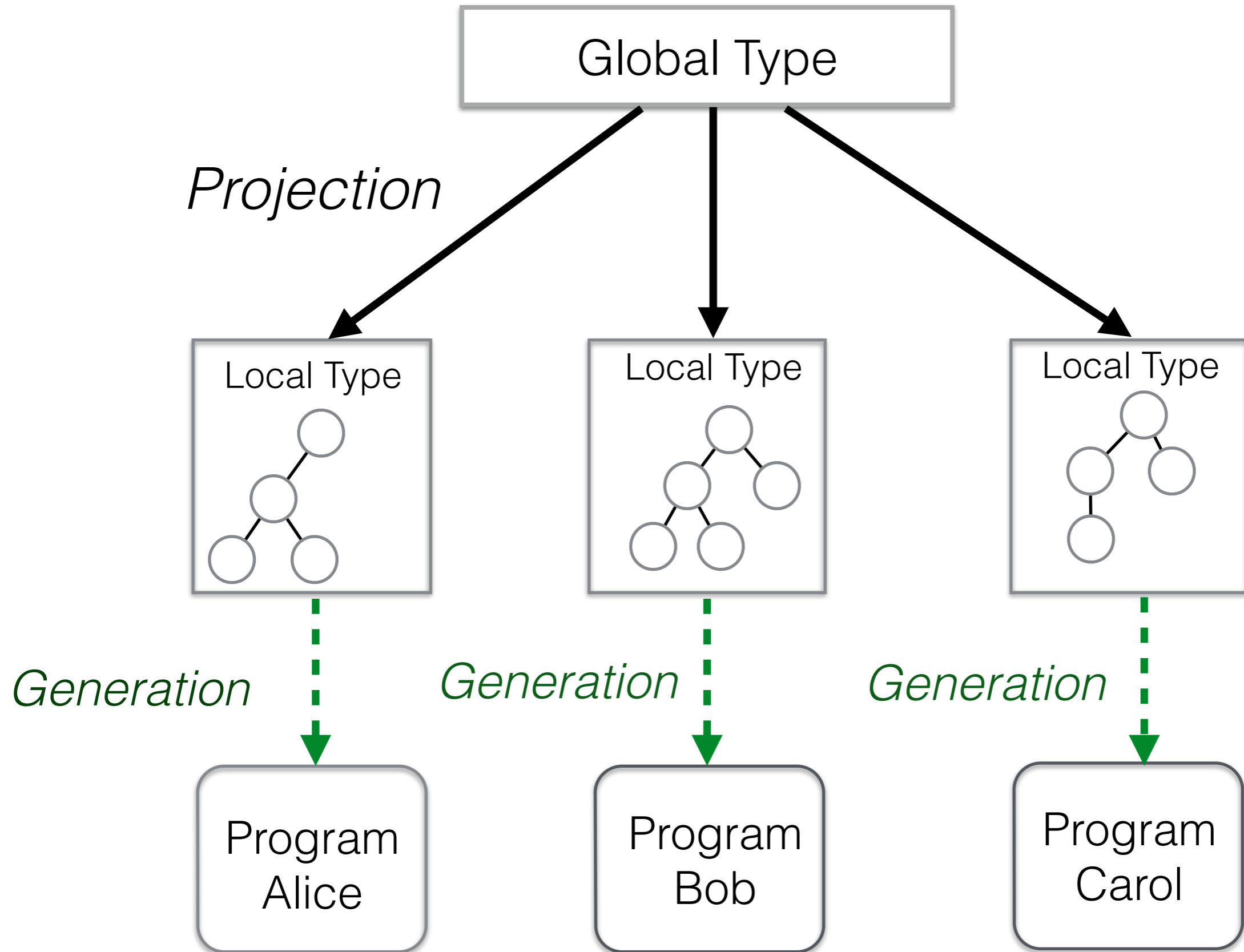


Type Checking

[ECOOP'16, OOPSLA'15, POPL'16]

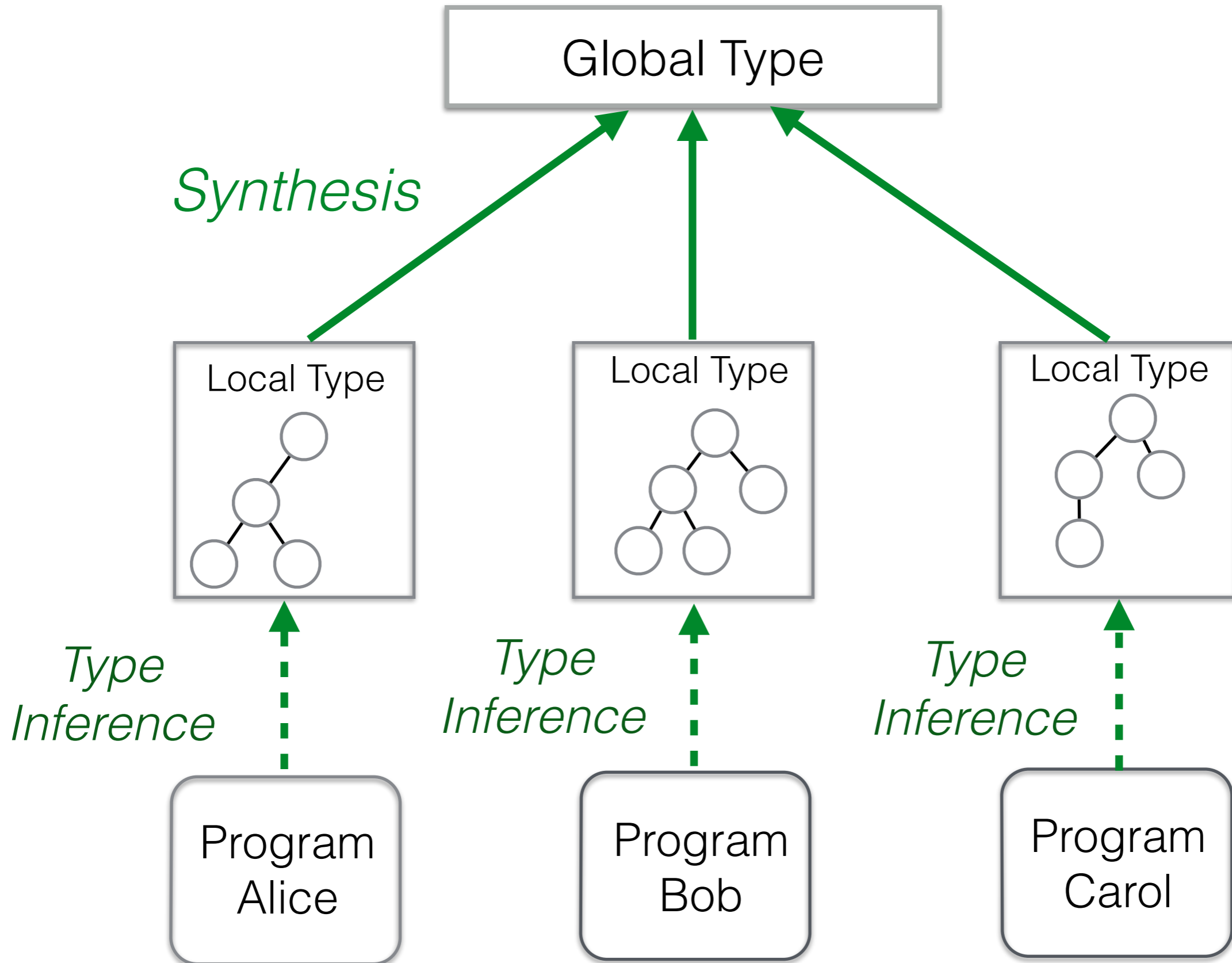


Code Generation [CC'15, FASE'16]



Synthesis

[ICALP'13, POPL'15, CONCUR'15, TACAS'16, CC'16]

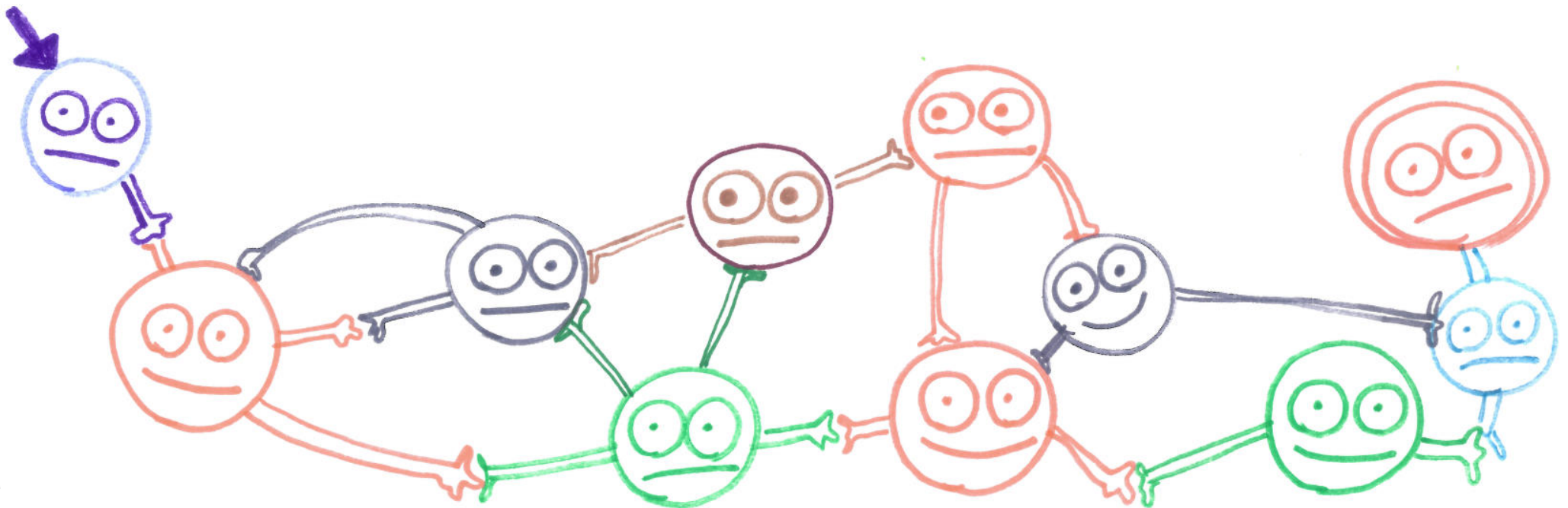


Multiparty Compatibility in Communicating Automata

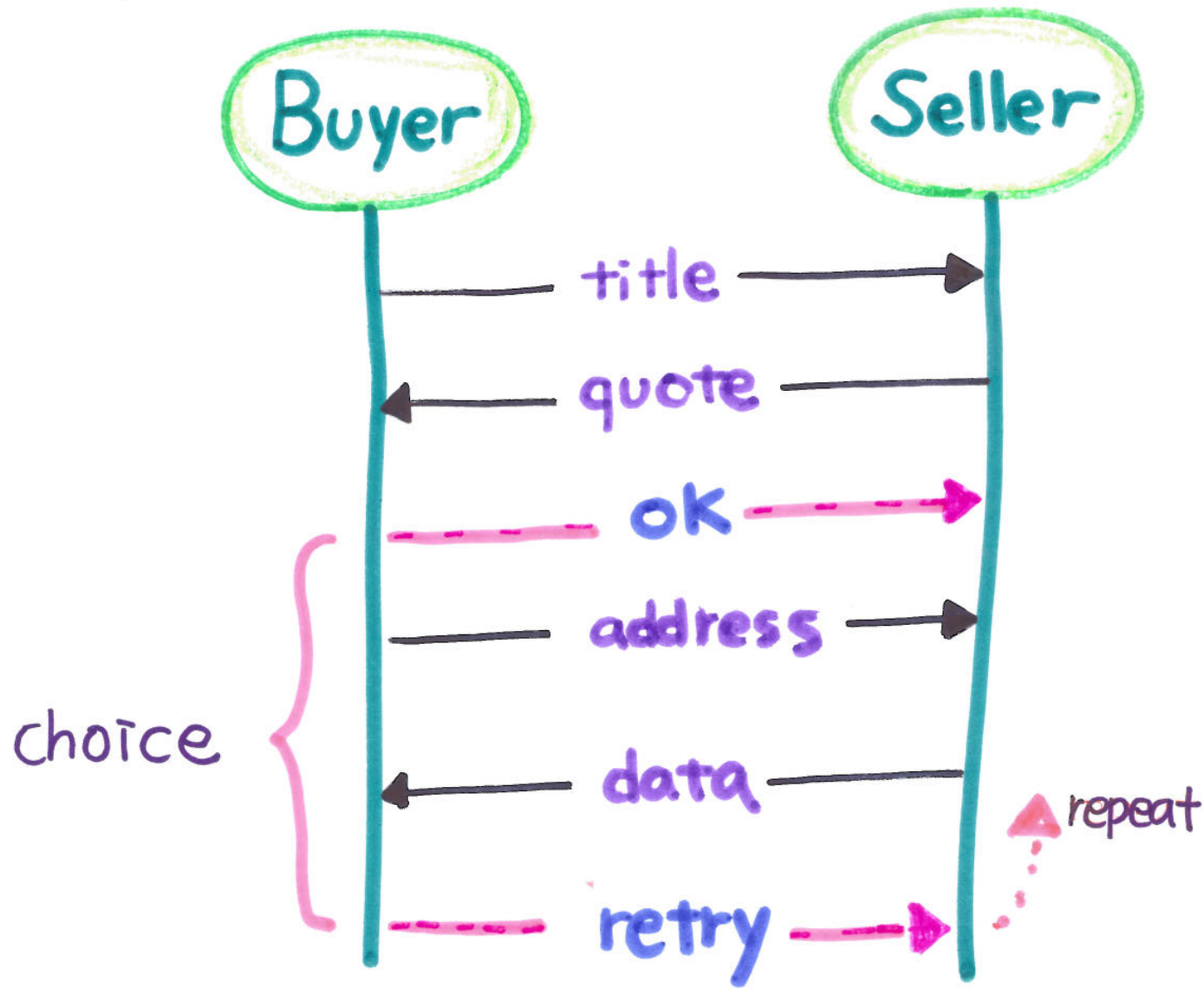
Synthesis and Characterisation of Multiparty Session Types

Nobuko Yoshida

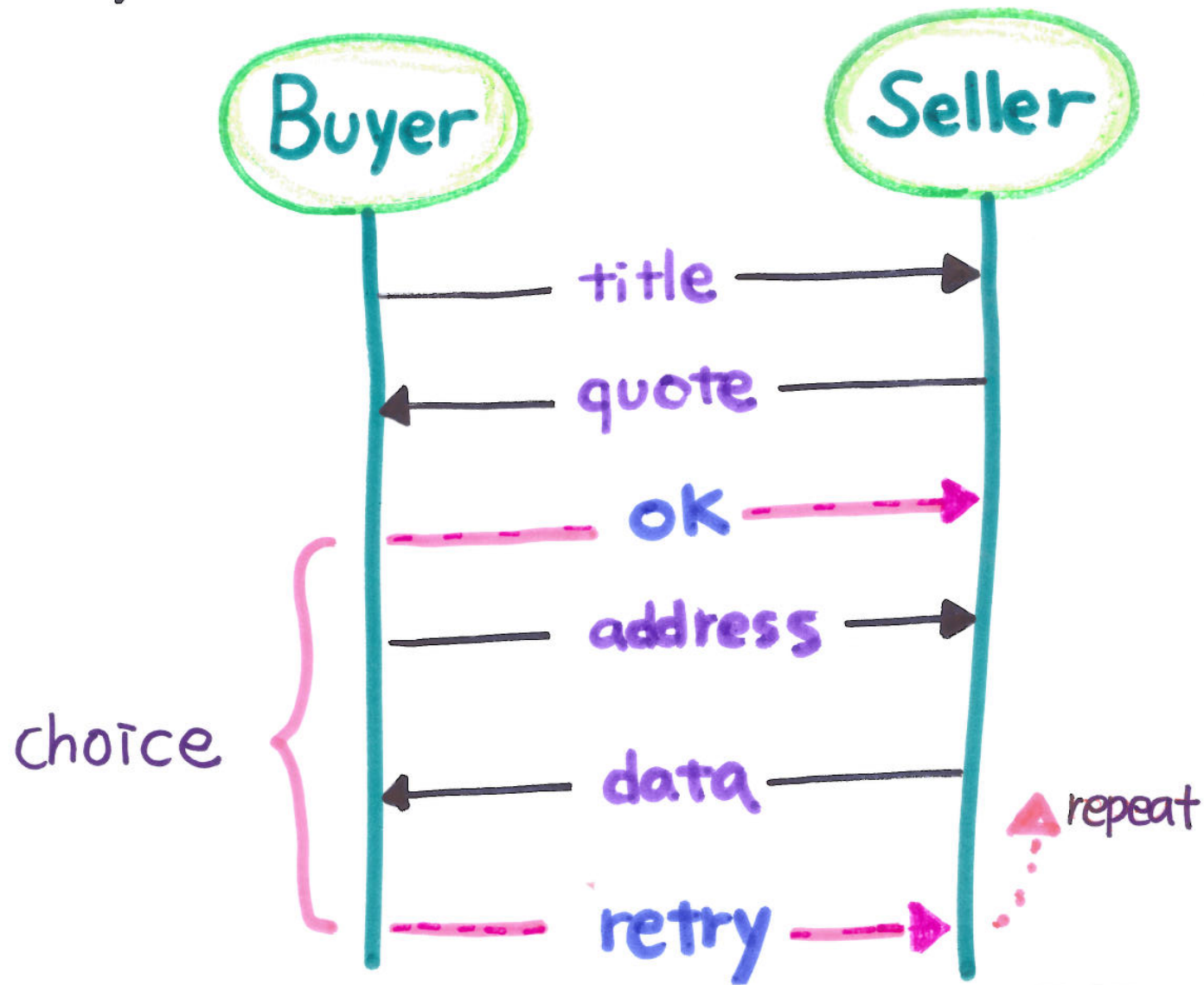
Pierre-Malo Denielou



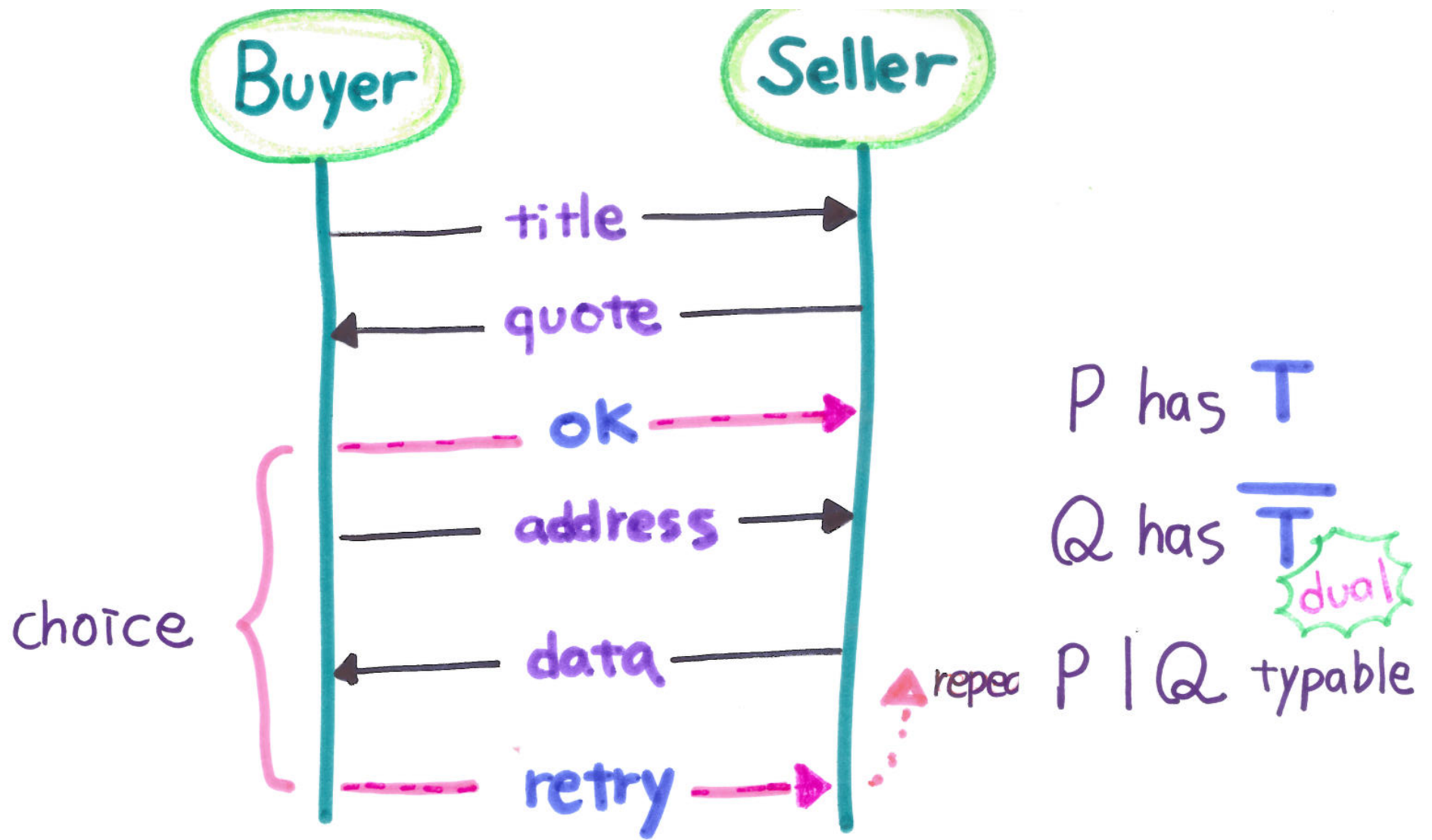
Binary Session Types: Buyer - Seller Protocol



Binary Session Types: Buyer - Seller Protocol



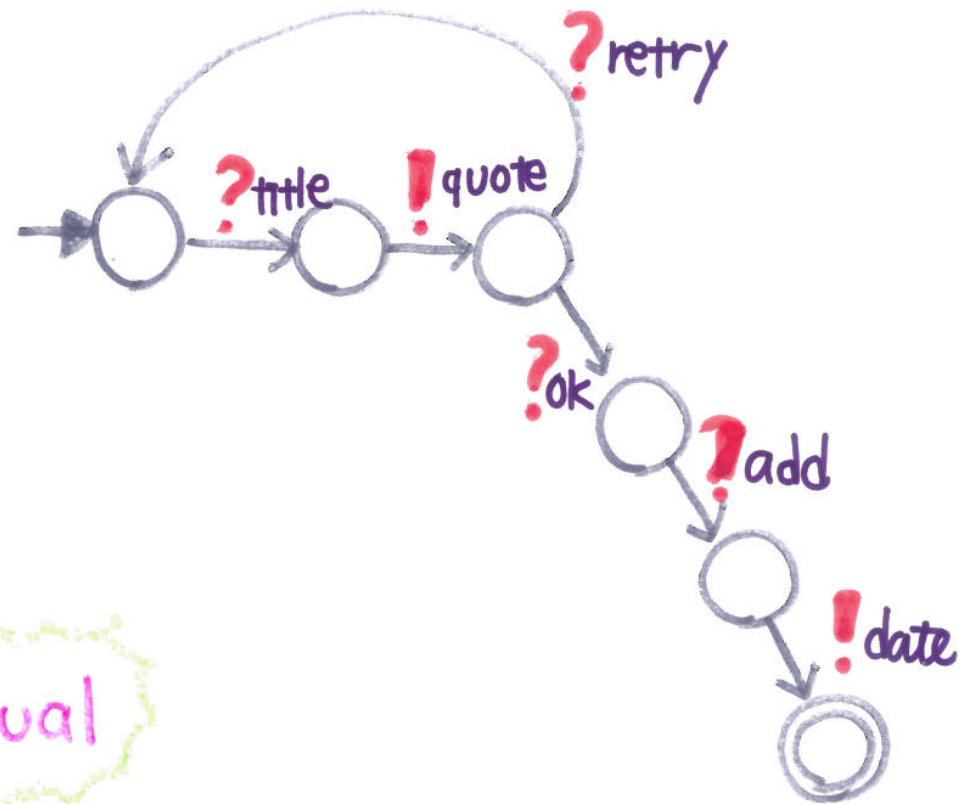
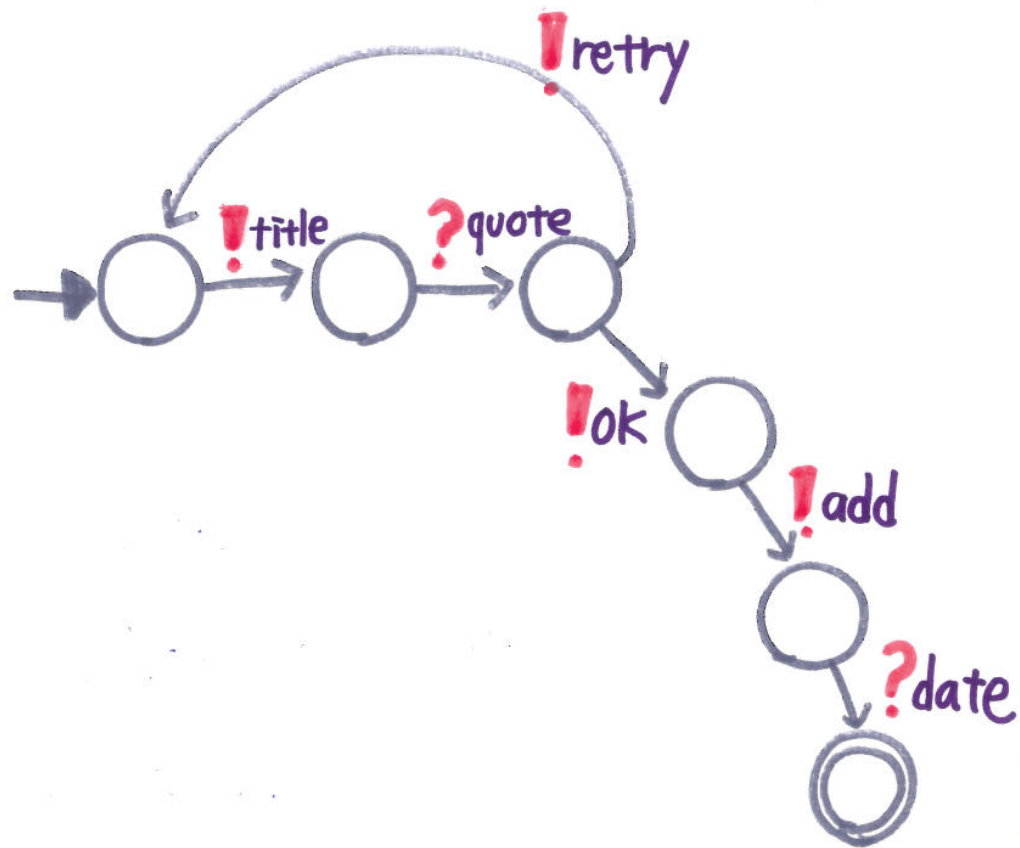
nt! Title ; ? Quote ; ! { ok: ! Add ; ? Date, retry: t }



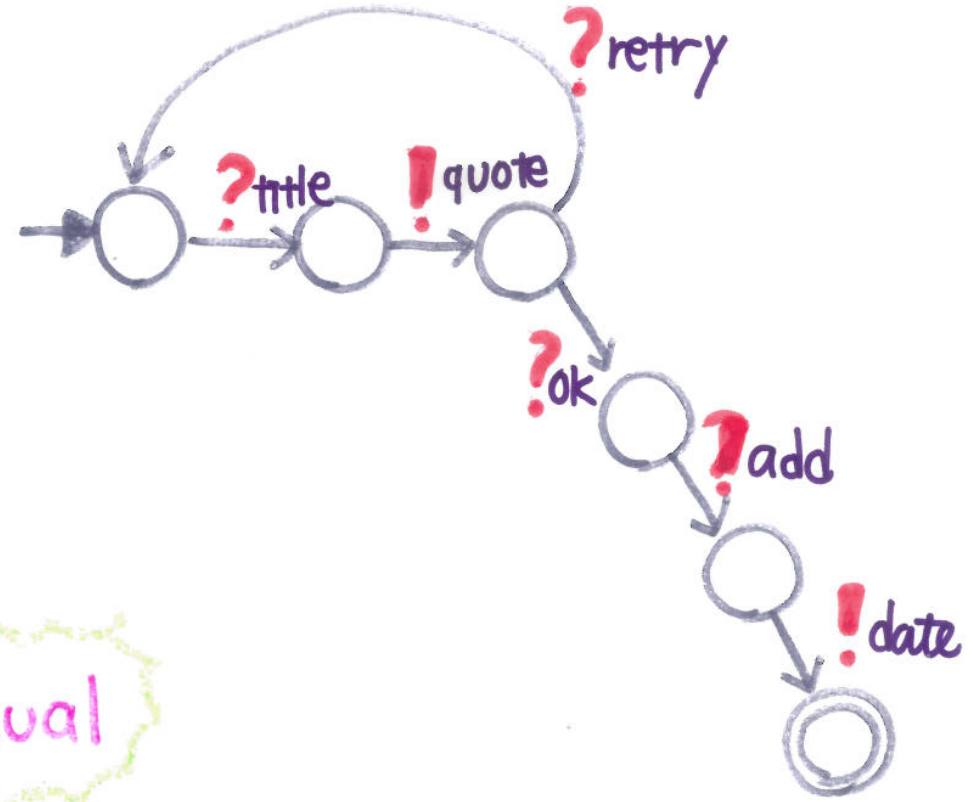
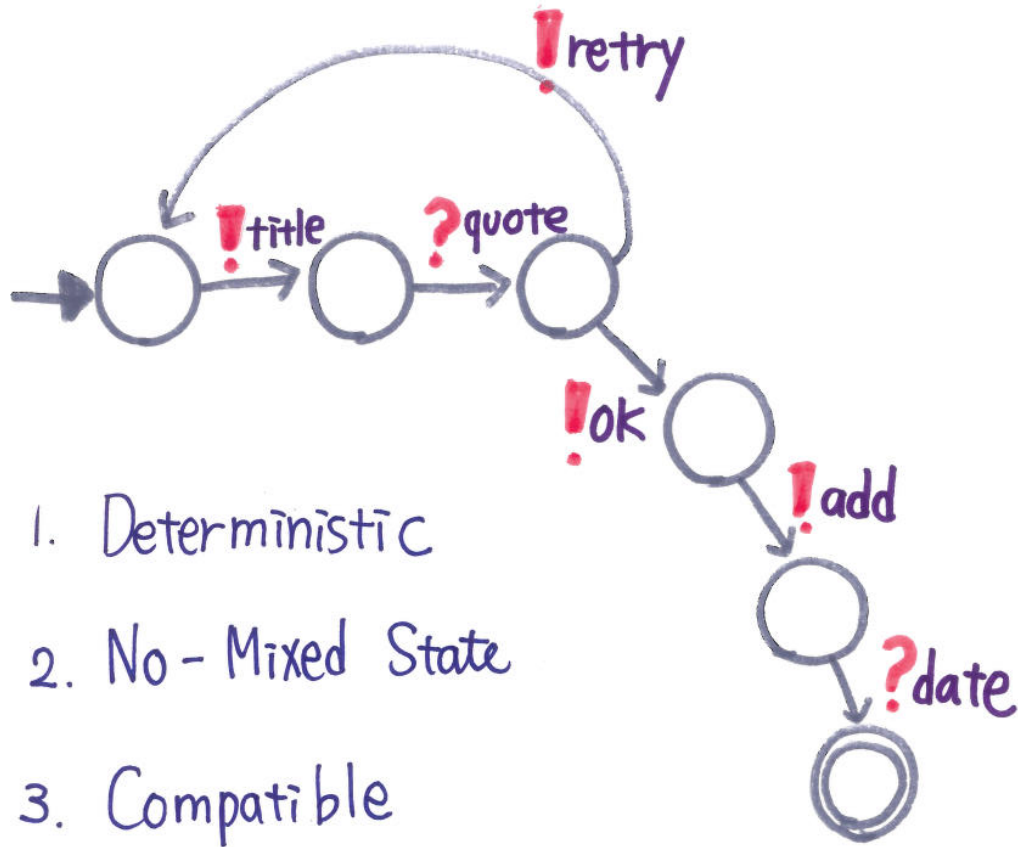
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Communicating Automata [1980s]

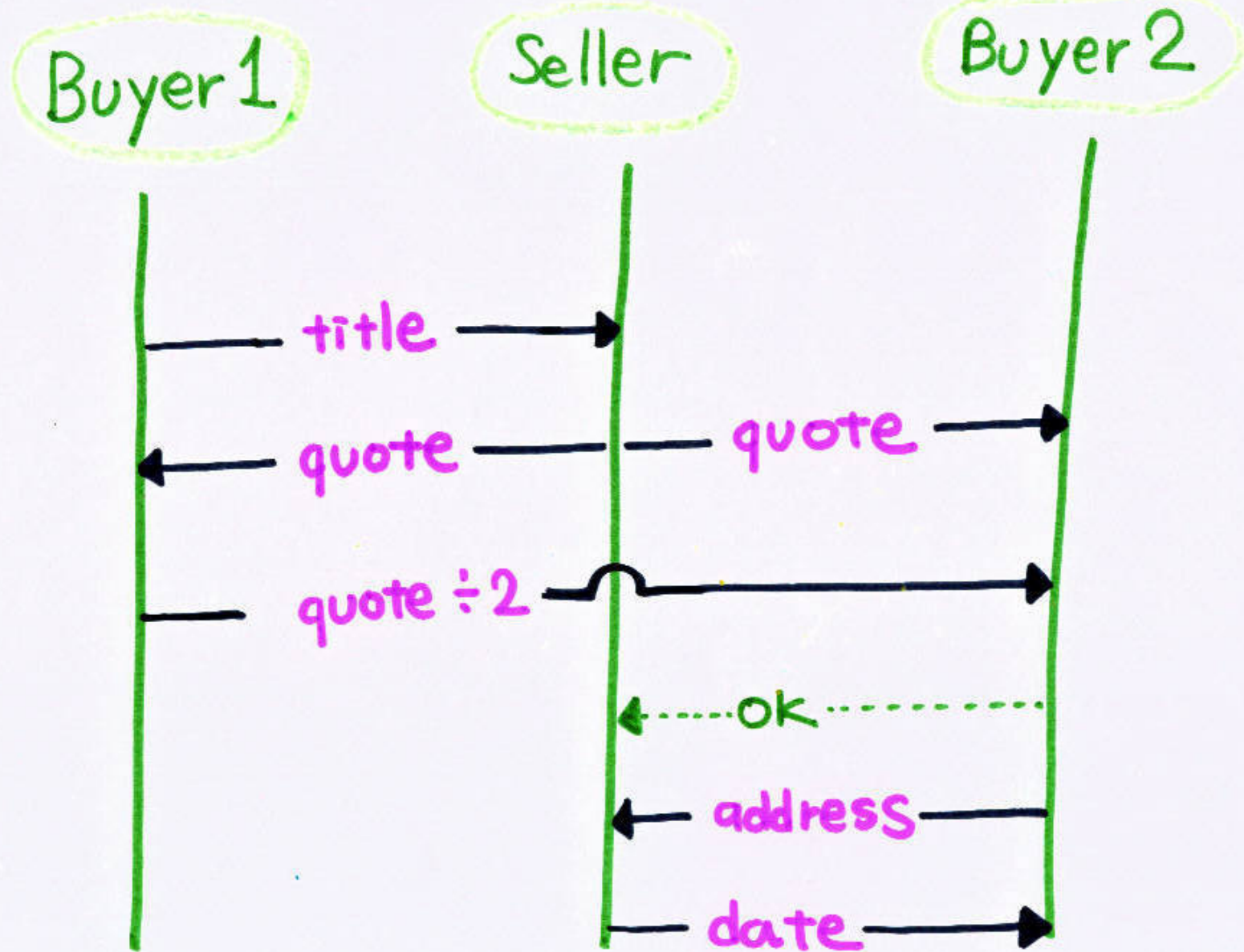


dual



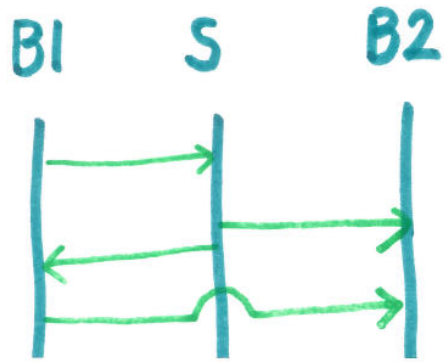
[Gouda et al 1986] Two compatible machines without mixed states which are deterministic satisfy deadlock-freedom.

Multiparty Session Types



Multi party Session Types

[Honda, Yoshida, Carbone 2008]



ⓐ

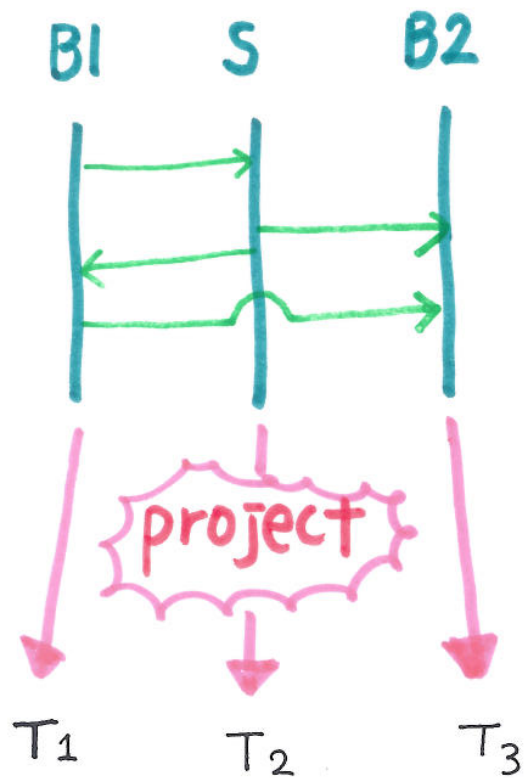
$BI \rightarrow S$ Int.

$S \rightarrow B2$ Char

STEP 1

Write Global Type

Multiparty Session Types [Honda, Yoshida, Carbone 2008]



\textcircled{G} $B1 \rightarrow S$ Int.
 $S \rightarrow B2$ Char

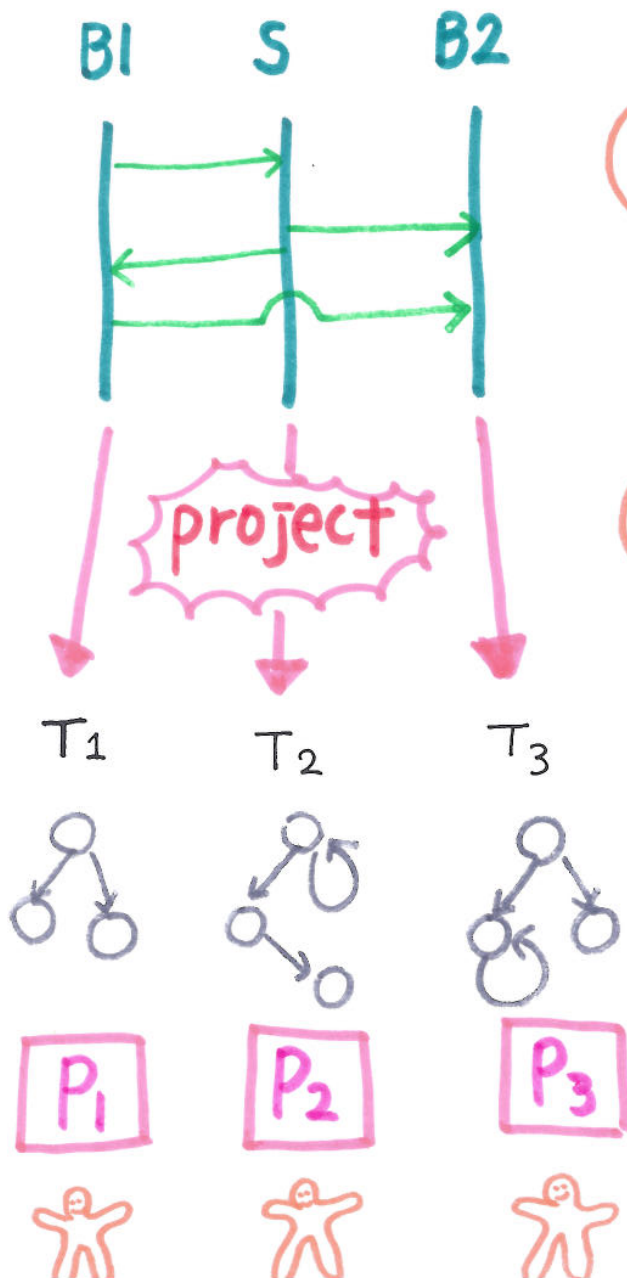
\textcircled{T} $B1?Int. B2!Char$

STEP 1
Write Global Type

STEP 2
Project to Local Types

Multi party Session Types

[Honda, Yoshida, Carbone 2008]



(G)

$B1 \rightarrow S$ Int.

$S \rightarrow B2$ Char

STEP 1

Write Global Type

(T)

$B1?Int. B2!Char$

STEP 2

Project to Local Type

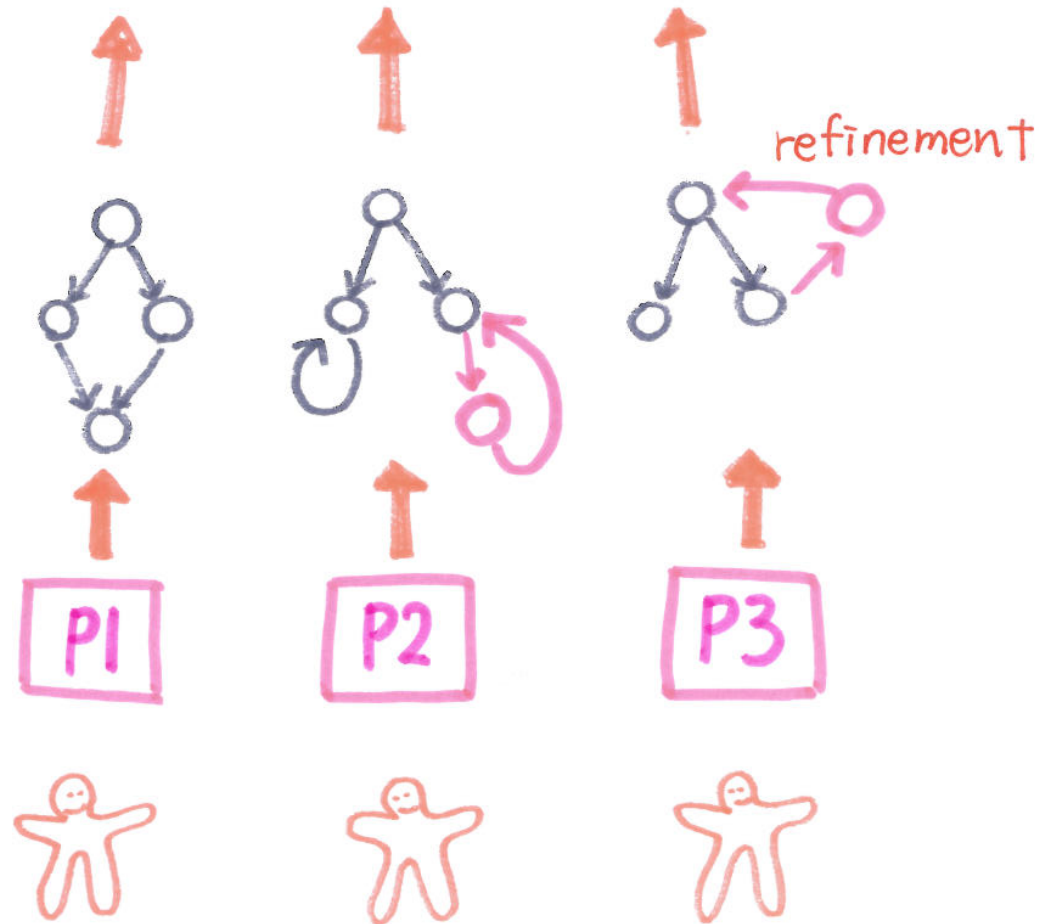
STEP 3

- Static Check
- Generate Code
- Run-time check

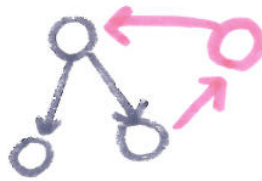
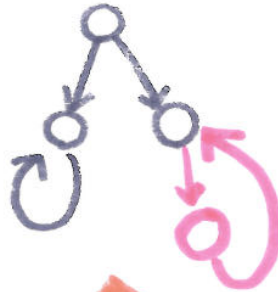
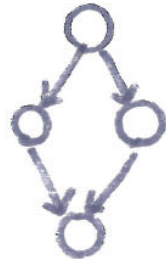
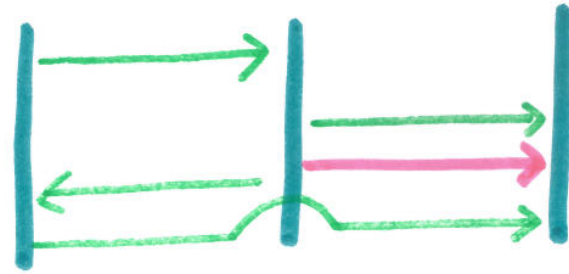
(P)

$B1?(x). B2!<"apple">$





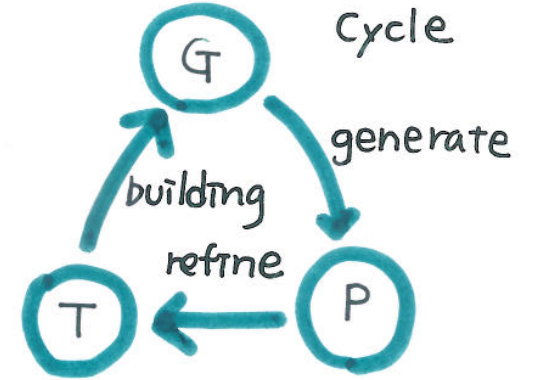
BI S B2



refinement



Software Development Cycle



- Optimisation
- refinement
- inference
- Testing

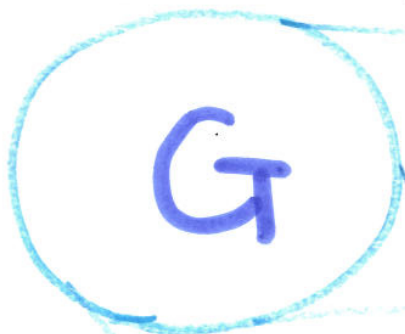
Aims

Building and Understanding

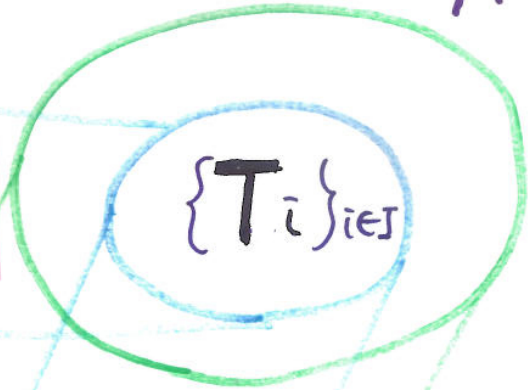
- Building Global Types from Communicating Automata (CA)
- Sound and Complete Characterisation of CA which can Build Global Types \Rightarrow Multiparty Compatibility

Global Type

Local Types

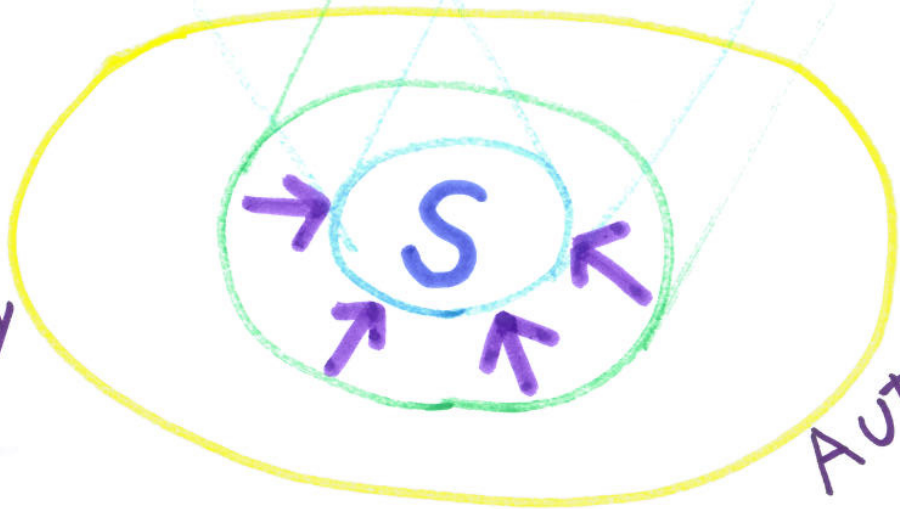


① $G \approx \{T_i\}_{i \in I}$



basic

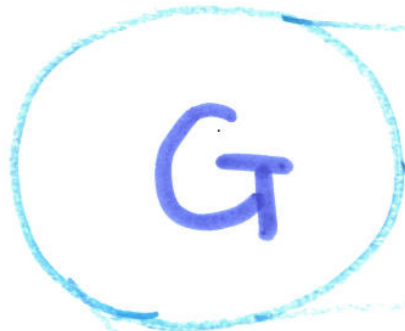
← multiparty compatibility



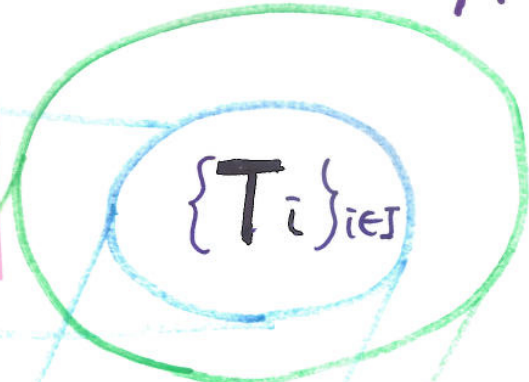
Automata $\{M_p\}_{p \in P}$

Global Type

Local Types



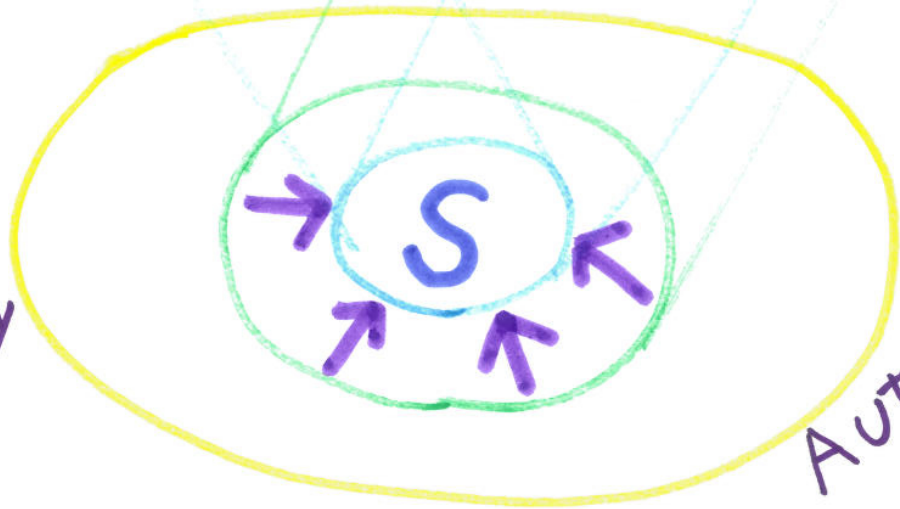
①
 $G \approx \{T_i\}_{i \in I}$



basic

②
 $T_i \approx M_i$

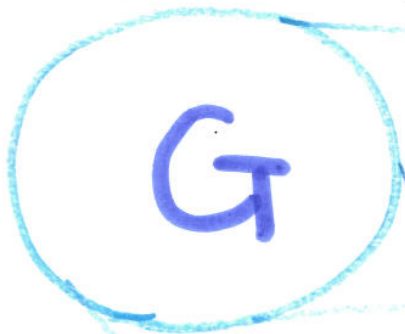
← multiparty compatibility



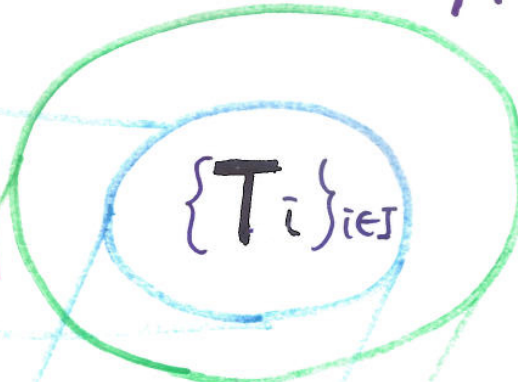
Automata $\{M_p\}_{p \in P}$

Global Type

Local Types



① $G \approx \{T_i\}_{i \in I}$

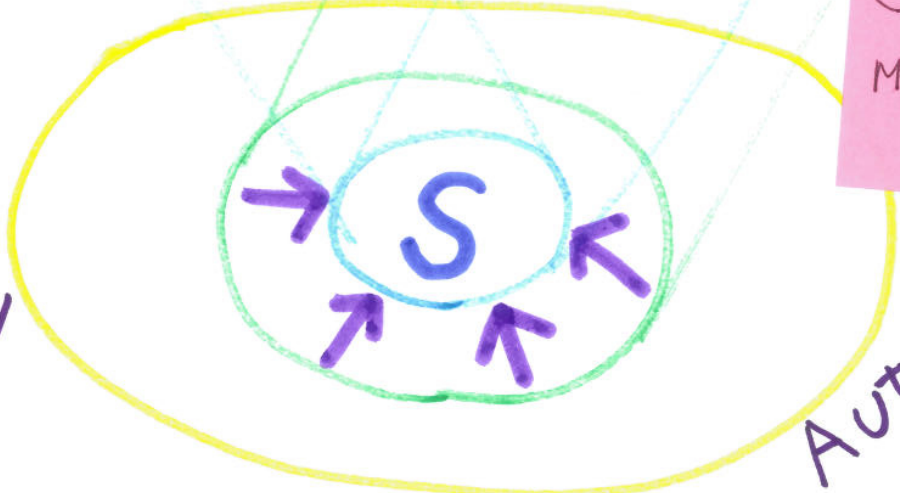


basic

② $T_i \approx M_i$

Multiparty Compatible
 $\{M_i\}_{i \in I}$ is safe

← multiparty compatibility

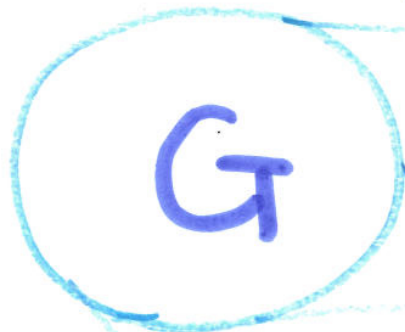


③ $\{T_i\}_{i \in I}$
Multiparty Compatible

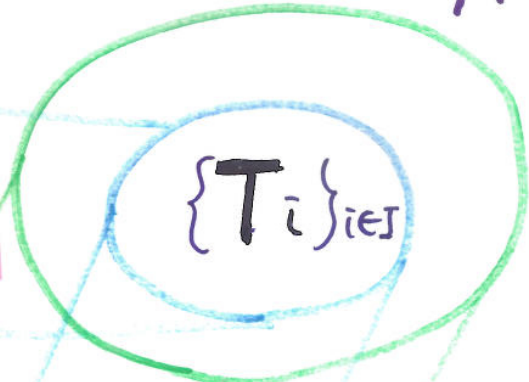
Automata $\{M_p\}_{p \in P}$

Global Type

Local Types



① $G \approx \{T_i\}_{i \in I}$



basic

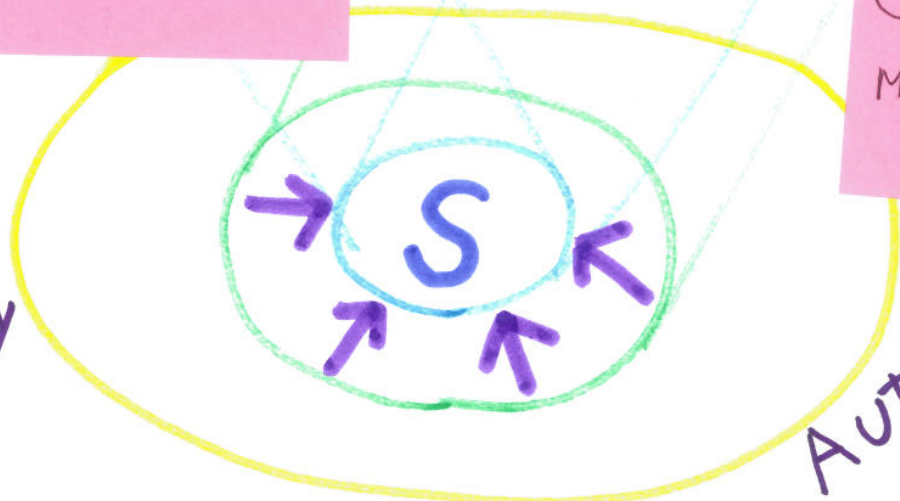
② $T_i \approx M_i$

④ Build G from $\{M_i\}_{i \in I}$

Multiparty Compatible
 $\{M_i\}_{i \in I}$ is safe

← multiparty compatibility

③ $\{T_i\}_{i \in I}$ Multiparty Compatible



Automata $\{M_p\}_{p \in P}$

Global Type

Local Types

G

①

$$G \approx \{T_i\}_{i \in I}$$

$\{T_i\}_{i \in I}$

basic

⑤ G realises
all traces in
 $\{M_i\}_{i \in I}$

②

$$T_i \approx M_i$$

④ Build

G from $\{M_i\}_{i \in I}$

Multiparty
Compatible
 $\{M_i\}_{i \in I}$ is safe

③ $\{T_i\}_{i \in I}$
Multiparty
Compatible

← multiparty
compatibility

S

Automata
 $\{M_p\}_{p \in P}$

Global Types

Local Types

$G ::= P \rightarrow P' : \{ a_j. G_j \}_{j \in J}$

| mt. G

| t

| end

$T ::= P ! \{ a_j. T_j \}_{j \in J}$

| $P ? \{ a_j. T_j \}_{j \in J}$

| mt. T

| t

| end

P, P', \dots Participant

a, b, c Σ Alphabet

Projection from G onto q $G \upharpoonright q$

$$(P \rightarrow P' : \{a_j, G_j\}_{j \in J}) \upharpoonright q$$

$$= \begin{cases} P \upharpoonright \{a_j, G_j \upharpoonright q\}_{j \in J} & q = P \\ P' \upharpoonright \{a_j, G_j \upharpoonright q\}_{j \in J} & q = P' \\ G_i \upharpoonright q = G_j \upharpoonright q & \forall j \in J \text{ otherwise} \end{cases}$$

Projection from Γ onto ϱ $\Gamma \upharpoonright \varrho$

$$(P \rightarrow P' : \{a_j. \Gamma_j\}_{j \in J}) \upharpoonright \varrho$$

$$= \begin{cases} P ! \{a_j. \Gamma_j \upharpoonright \varrho\}_{j \in J} & \varrho = P \\ P ? \{a_j. \Gamma_j \upharpoonright \varrho\}_{j \in J} & \varrho = P' \\ \Gamma_1 \upharpoonright \varrho = \Gamma_j \upharpoonright \varrho & \forall j \in J \text{ otherwise} \end{cases}$$

Bad $A \rightarrow B : \{\underline{a}. C \rightarrow D : \underline{c}, \underline{b}. C \rightarrow D : \underline{d}\}$

Good $A \rightarrow B : \{\underline{a}. C \rightarrow D : \underline{c}, \underline{b}. C \rightarrow D : \underline{c}\}$

LTS Local Types

$$l ::= pq!a \mid pq?a$$

$$q! \{a_i. T_i\}_{i \in I} \xrightarrow{pq!a_i} T_i$$

$$q? \{a_i. T_i\}_{i \in I} \xrightarrow{qp?a_i} T_i$$

$$\frac{T[mt. T/t] \xrightarrow{l} T'}{mt. T \xrightarrow{l} T'}$$

$(\vec{T}; \vec{w})$

W_{pq}
queue

Send $T_p \xrightarrow{pq!l} T_p' \Rightarrow$

$$(\dots T_p \dots ; \dots W_{pq} \dots) \xrightarrow{pq!l} (\dots T_p' \dots ; \dots W_{pq} \cdot l \dots)$$

Receive $T_q \xrightarrow{pq?l} T_q' \Rightarrow$

$$(\dots T_q \dots ; \dots l \cdot W_{pq} \dots) \xrightarrow{pq?l} (\dots T_q' \dots ; \dots W_{pq} \dots)$$

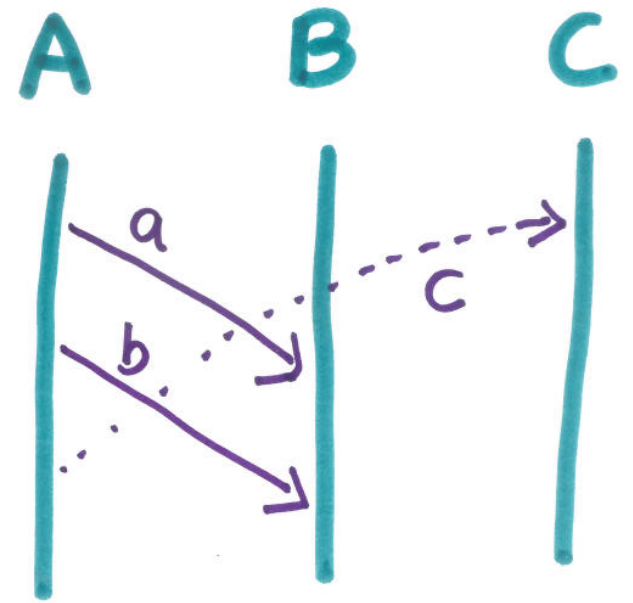
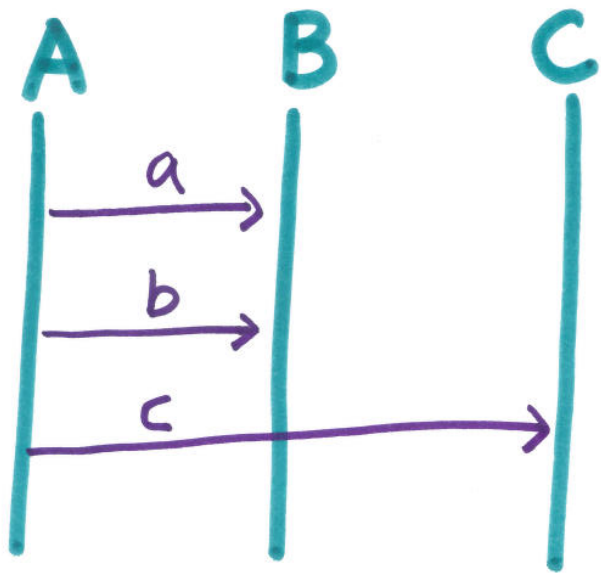
LTS Global Types

$$p \rightsquigarrow p' : \bar{j} \{a_i. G_i\}_{i \in I}$$

put $p \rightarrow p' : \{a_i. G_i\}_{i \in I} \xrightarrow{pp'!a_{\bar{j}}} p \rightsquigarrow p' : \bar{j} \{a_i. G_i\}_{i \in I}$

get $p \rightsquigarrow p' : \bar{j} \{a_i. G_i\}_{i \in I} \xrightarrow{pp'?a_{\bar{j}}} G_{\bar{j}}$

$$\frac{\forall j \in I \quad G_j \xrightarrow{\ell} G'_j \quad p, q \notin \text{sub}(\ell) \quad q \notin \text{sub}(\ell) \quad \forall i \in I \setminus \bar{j} \quad G'_i = G_i}{p \rightarrow p' : \{a_i. G_i\}_{i \in I} \xrightarrow{\ell} p \rightarrow p' : \{a_i. G'_i\}_{i \in I} \quad p \rightsquigarrow q : \bar{j} \{a_i. G_i\}_{i \in I} \xrightarrow{\ell} p \rightsquigarrow q : \bar{j} \{a_i. G'_i\}_{i \in I}}$$



$A \rightarrow B:a . A \rightarrow B:b . A \rightarrow C:c$

↓ **AB!a** OUT

$A \rightsquigarrow B:a . A \rightarrow B:b . A \rightarrow C:c$

↓ **AB?a** IN

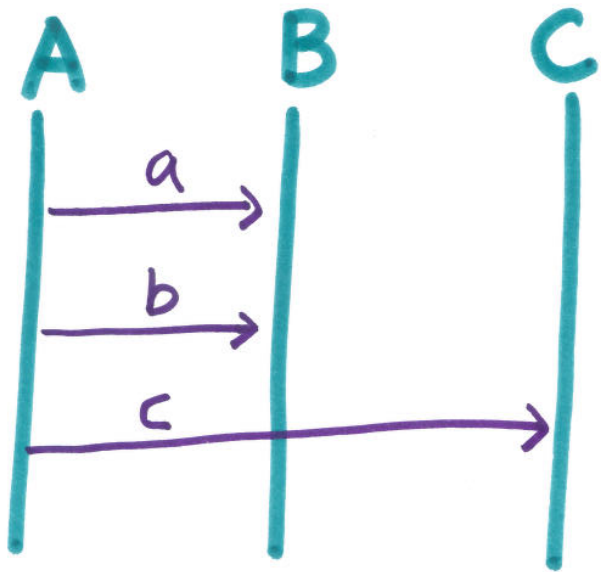
$A \rightarrow B:b \quad A \rightarrow C:c$

↓ **AB!b** OUT

$A \rightsquigarrow B:b \quad A \rightarrow C:c$

↓ **AB?b** IN

$A \rightarrow C:c$



$A \rightarrow B:a. A \rightarrow B:b. A \rightarrow C:c$

↓ $AB!a$ OUT

$A \rightsquigarrow B:a. A \rightarrow B:b. A \rightarrow C:c$

↓ $AB?a$ IN

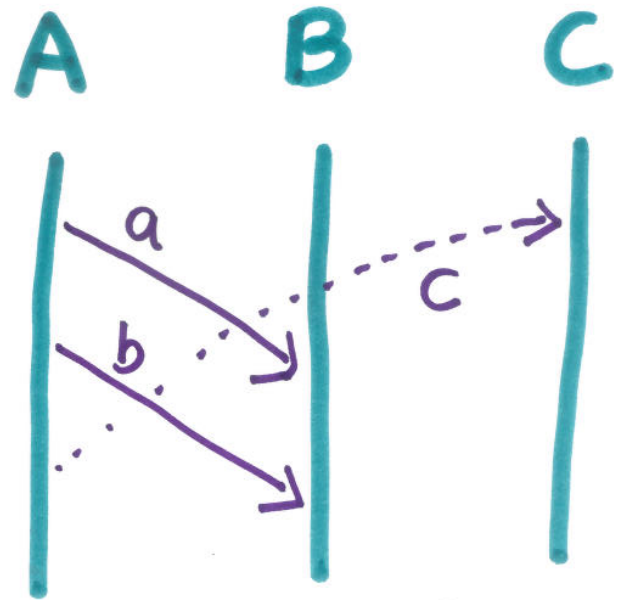
$A \rightarrow B:b. A \rightarrow C:c$

↓ $AB!b$ OUT

$A \rightsquigarrow B:b. A \rightarrow C:c$

↓ $AB?b$ IN

$A \rightarrow C:c$



$A \rightarrow B:a. A \rightarrow B:b. A \rightarrow C:c$

↓ $AB!a$ OUT

↓ $AB!b$ OUT

↓ $AC!c$ OUT

$A \rightsquigarrow B:a. A \rightsquigarrow B:b. A \rightsquigarrow C:c$

↓ $AC?c$ IN

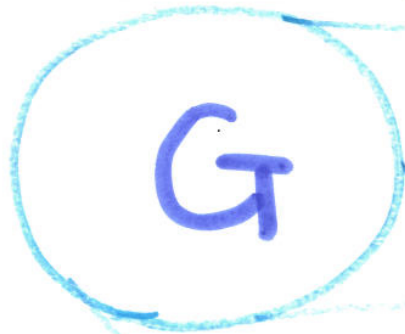
$A \rightsquigarrow B:a. A \rightsquigarrow B:b$

↓ $AB?a$ IN

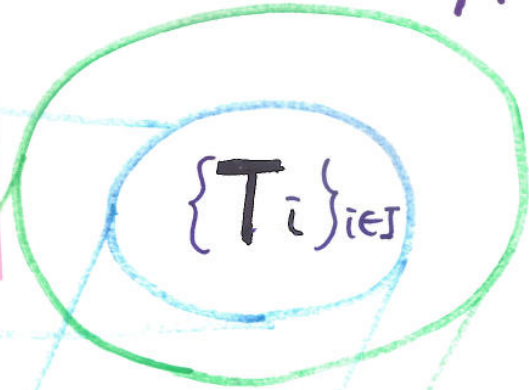
$A \rightsquigarrow B:b$

Global Type

Local Types



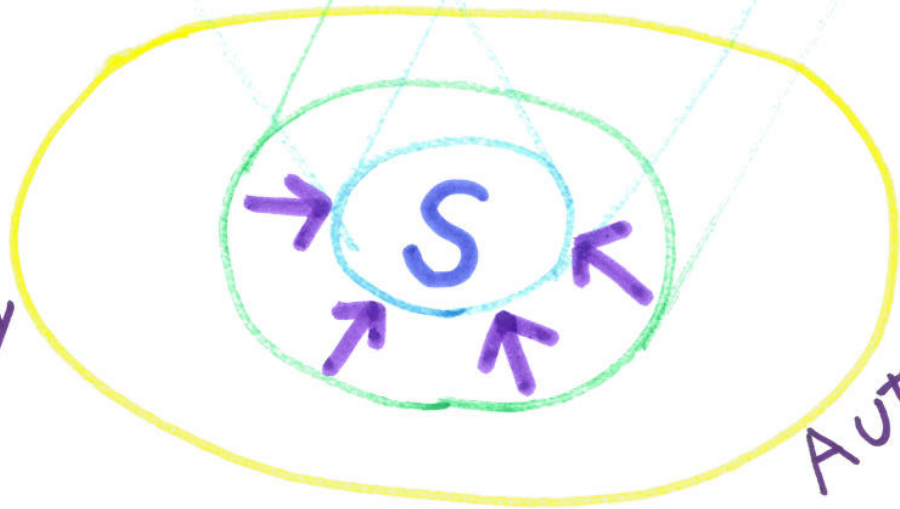
①
 $G \approx \{T_i\}_{i \in I}$



basic

②
 $T_i \approx M_i$

← multiparty compatibility



Automata $\{M_p\}_{p \in P}$

CFSMs [1980-] ITU notation SDL · MSCS ...

Def A CFSM $M = (Q, C, q_0, \Sigma, \delta)$

Q a finite set of states

$C = \{ pq \in \text{Participant}^2 \mid p \neq q \}$

q_0 initial state

Σ a finite alphabet of messages

$\delta \subseteq Q \times (C \times \{!, ?\} \times \Sigma) \times Q$ a finite set of transitions

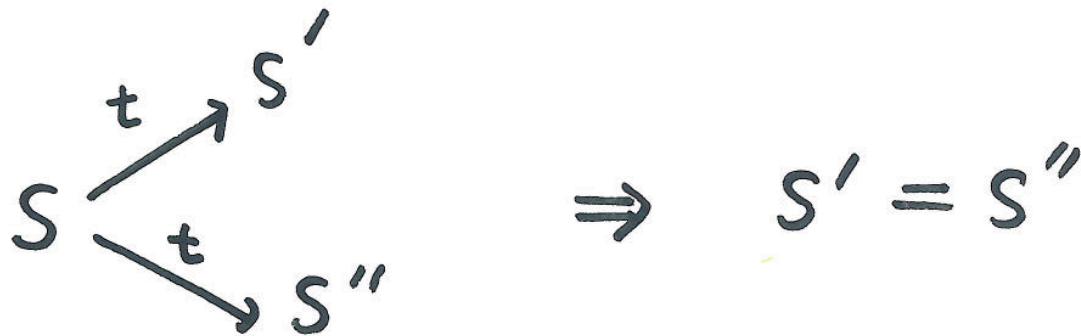
Def CS $S = (M_p)_{p \in \text{Participant}}$

$S \xrightarrow{t} S'$ configuration $S = (\vec{q}; \vec{w})$
states queues

Send
 $(\dots q_p \dots; \dots w_{pq} \dots) \xrightarrow{pq!l} (\dots q'_p; \dots w_{pq} \cdot l \dots)$

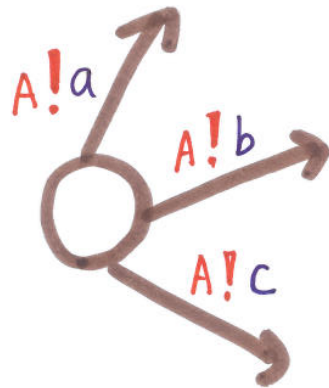
Receive
 $(\dots q_q \dots; \dots l \cdot w_{pq} \dots) \xrightarrow{pq?l} (\dots q'_q \dots; \dots w_{pq} \dots)$

Deterministic CFSM



Basic CFSMs

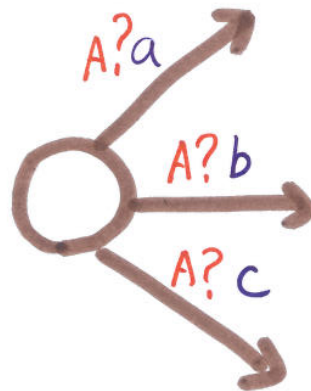
A CFSM is **Basic** if **deterministic**
directed, has **no mixed states**



sending



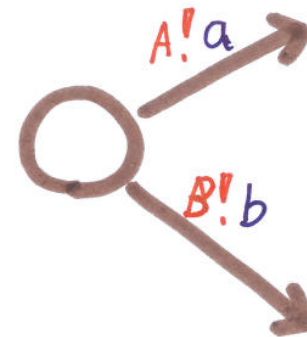
$$T = A!\{a, b, c\}$$



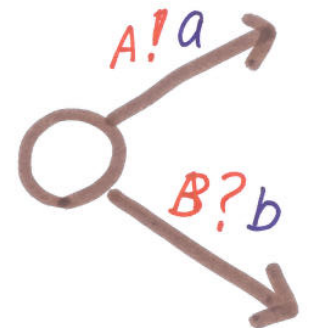
receiving



$$A?\{a, b, c\}$$



non
directed



mixed



Theorem 1 $\text{Tr}(G) \approx \text{Tr}(\{G \upharpoonright P\}_{P \in \text{Participant}})$

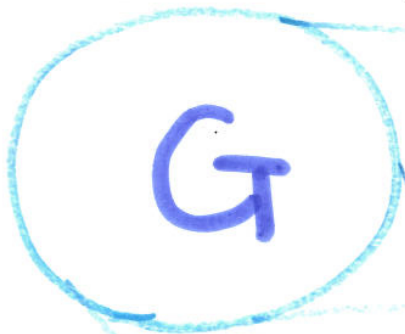
Soundness and Completeness between
a global type and ^{projected} local types

Theorem 2 $\text{Tr}(T) \approx \text{Tr}(A(T))_{T \text{ basic}}$

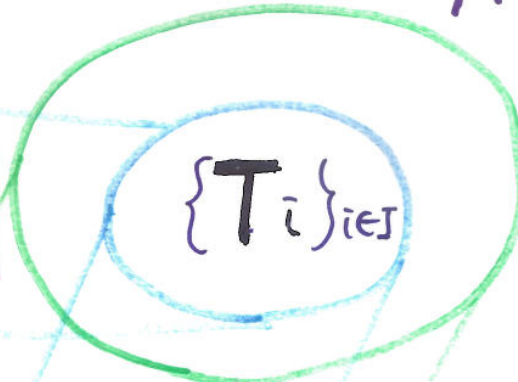
Soundness and Completeness between
a local type and a basic CFSM of T

Global Type

Local Types



① $G \approx \{T_i\}_{i \in I}$

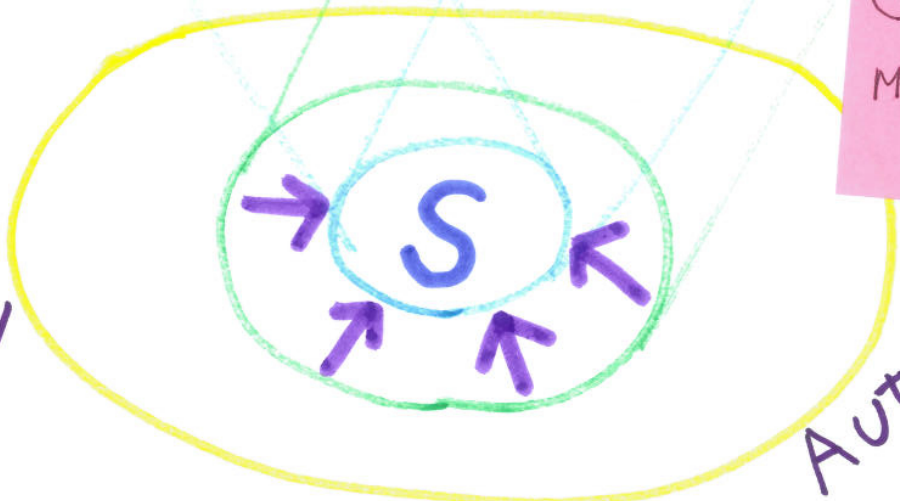


basic

② $T_i \approx M_i$

Multiparty Compatible
 $\{M_i\}_{i \in I}$ is safe

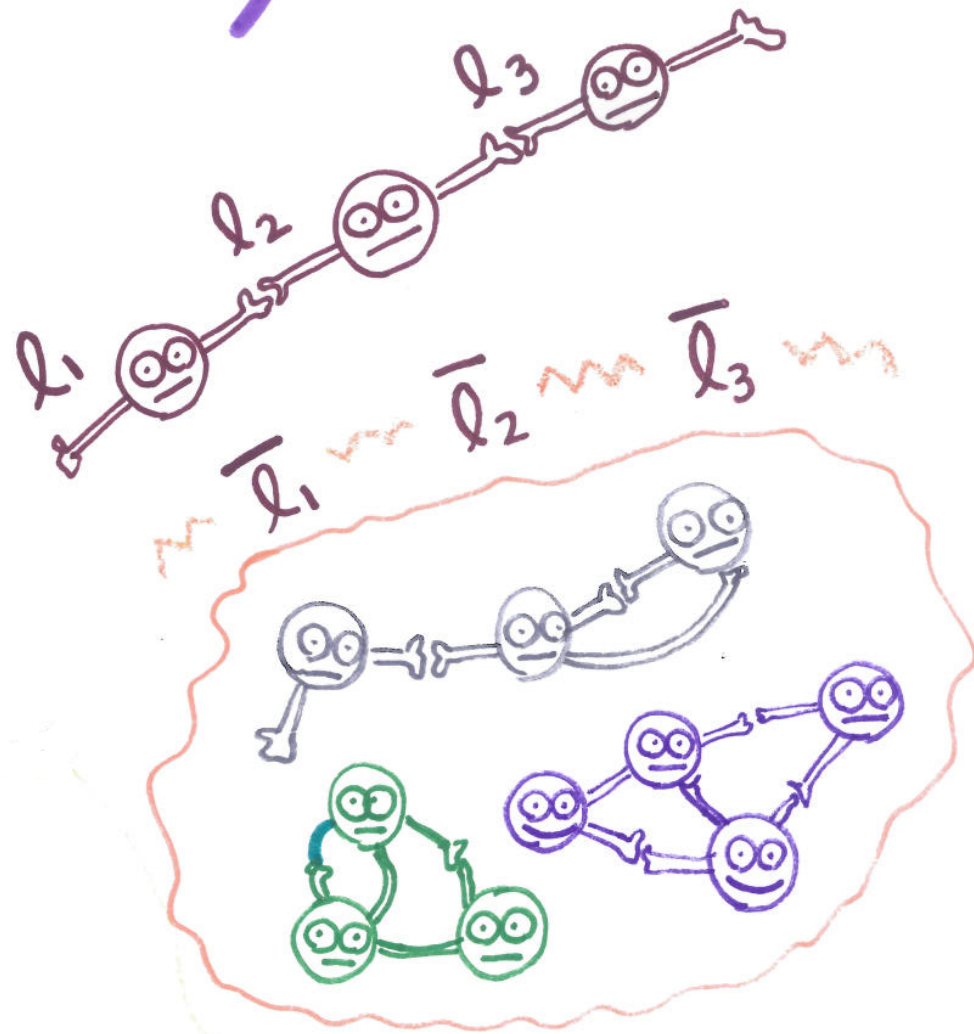
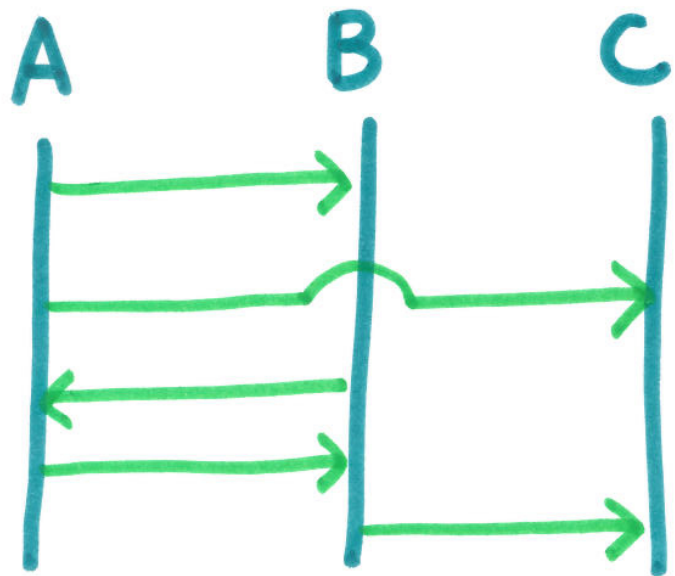
← multiparty compatibility



③ $\{T_i\}_{i \in I}$
Multiparty Compatible

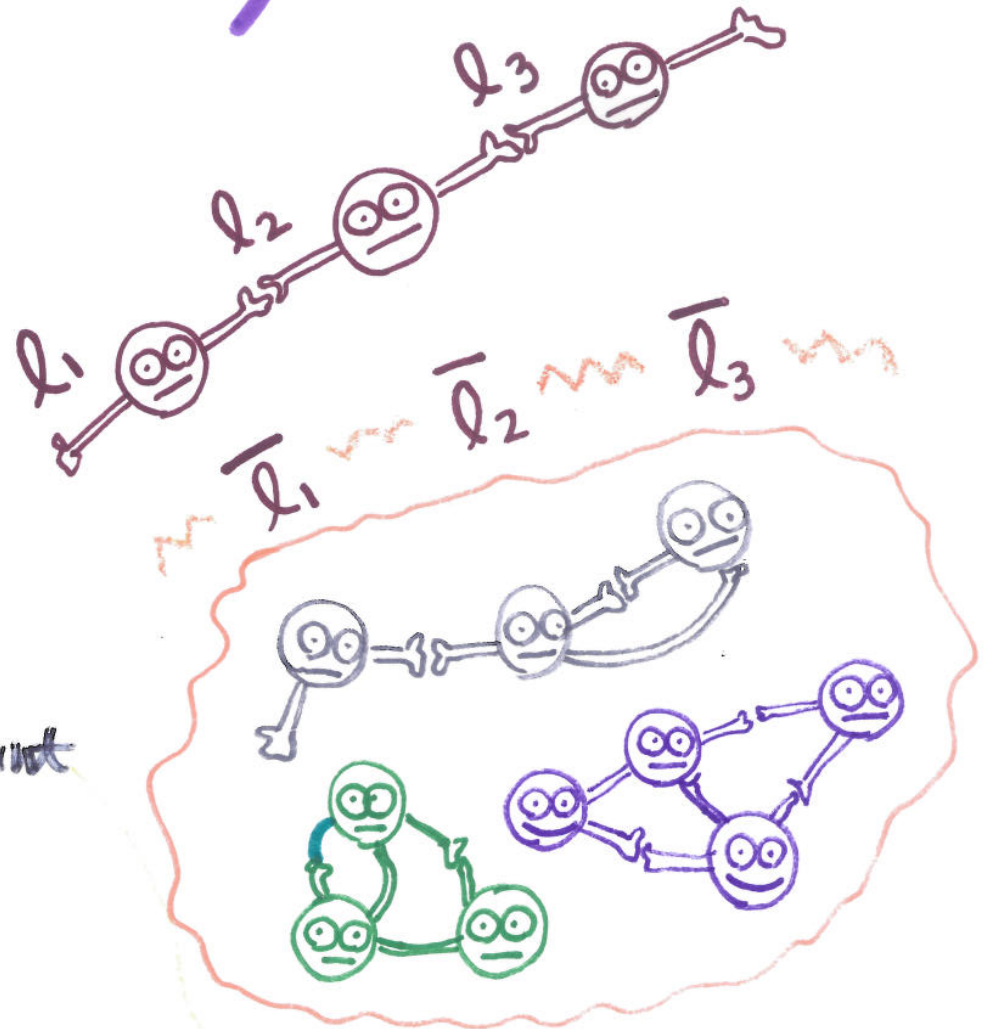
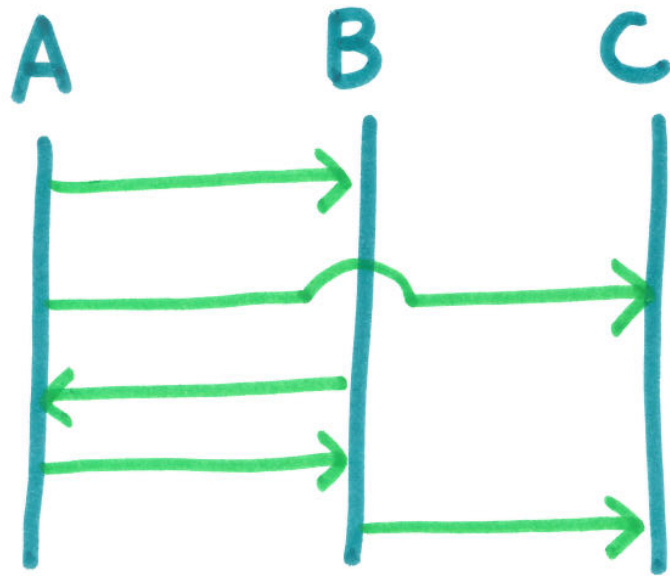
Automata $\{M_p\}_{p \in P}$

Multiparty Compatibility



[Faint handwritten notes in pencil, mostly illegible.]

Multiparty Compatibility



Def $S = (M_p)_{p \in \text{Participant}}$

$\forall s$. $s_0 \rightsquigarrow s$
1-buffer execution

if M_i does action l

then $(M_{\bar{j}})_{\bar{j} \in P \setminus i}$ do action \bar{l}
 after some \rightsquigarrow

Theorem (Safety) Suppose S is basic and multiparty compatible.
Then S is free from the following errors. Let $S = (\vec{q}; \vec{w})$

Deadlock if $\vec{w} = \vec{\epsilon}$ and not final, each q_p is receiving

Ophan Message all q are final, but $\vec{w} \neq \vec{\epsilon}$

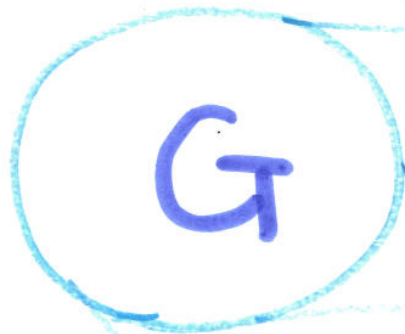
Unspecified Reception $(q_p, p \stackrel{?}{\underline{a}}, q'_p)$ implies $|w_{pq}| > 1$ and $w_{pq} \notin \underline{a} \cdot \Sigma^*$

Proposition Soundness $A(\{G \upharpoonright_p\}_{p \in \text{Participant}})$ is
multiparty compatible. projection

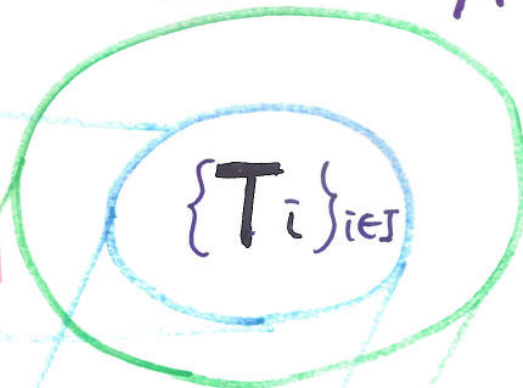
Proposition Multiparty Compatibility is decidable.

Global Type

Local Types



① $G \approx \{T_i\}_{i \in I}$



basic

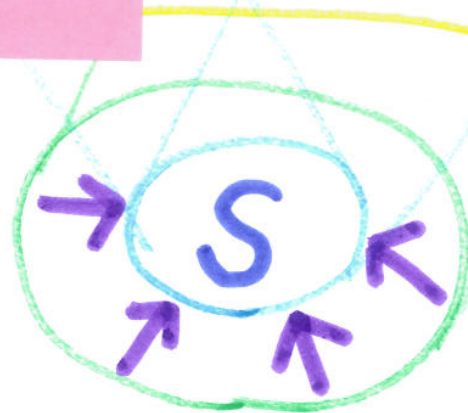
② $T_i \approx M_i$

④ Build G from $\{M_i\}_{i \in I}$

Multiparty Compatible
 $\{M_i\}_{i \in I}$ is safe

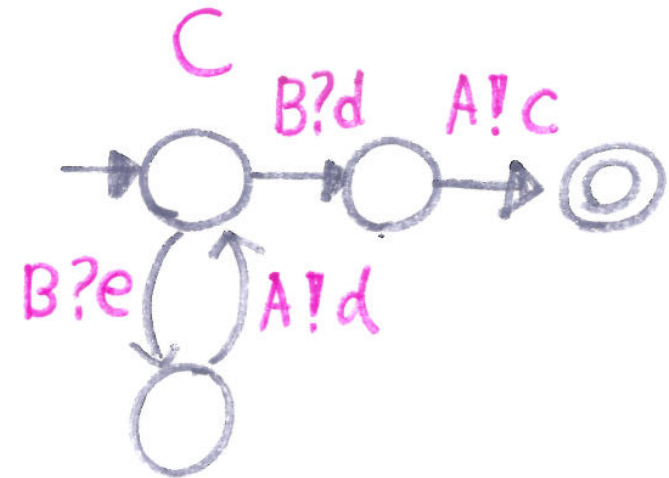
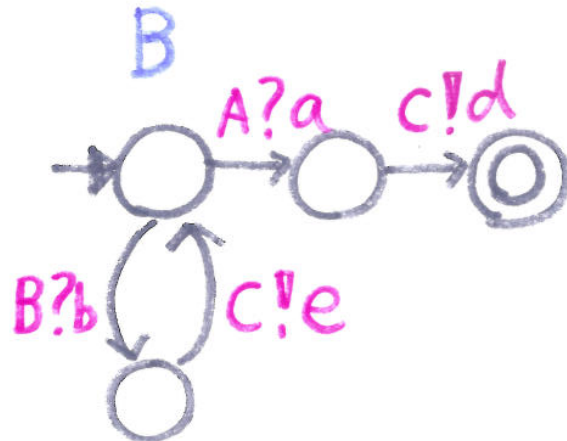
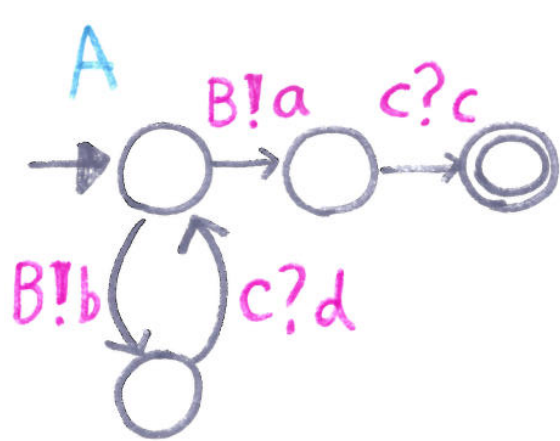
← multiparty compatibility

③ $\{T_i\}_{i \in I}$ Multiparty Compatible



Automata $\{M_p\}_{p \in P}$

Synthesis

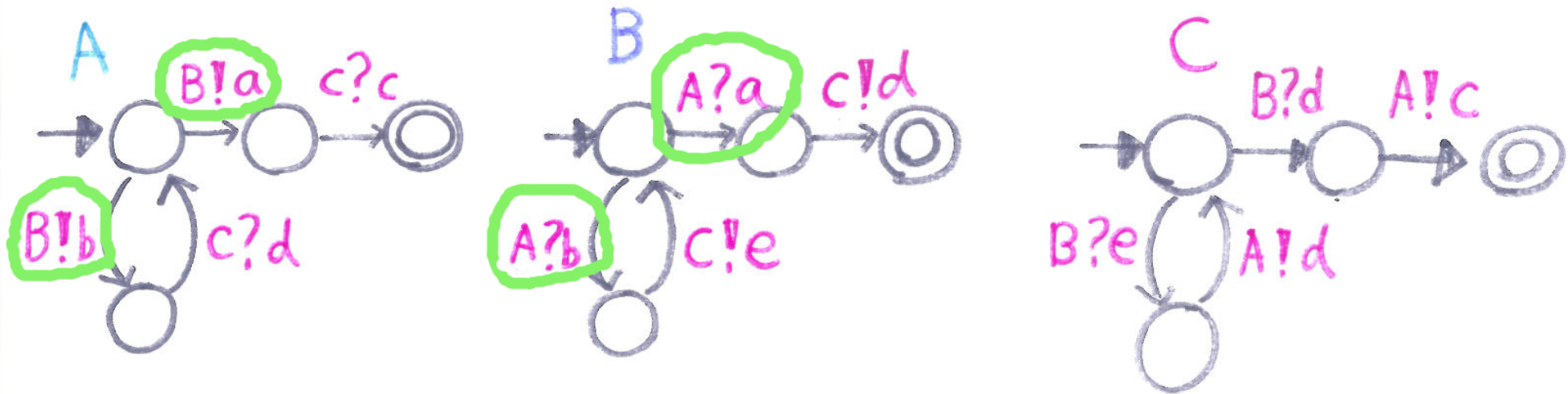


$\mu t . A \rightarrow B : \{ a . B \rightarrow C : \{ d . C \rightarrow A : \{ c : end \} \}$
 $b . B \rightarrow C : \{ e . C \rightarrow A : \{ d : t \} \} \}$

Theorem Suppose S is basic and compatible.

Then there is an algorithm to build a well-formed G .

Synthesis

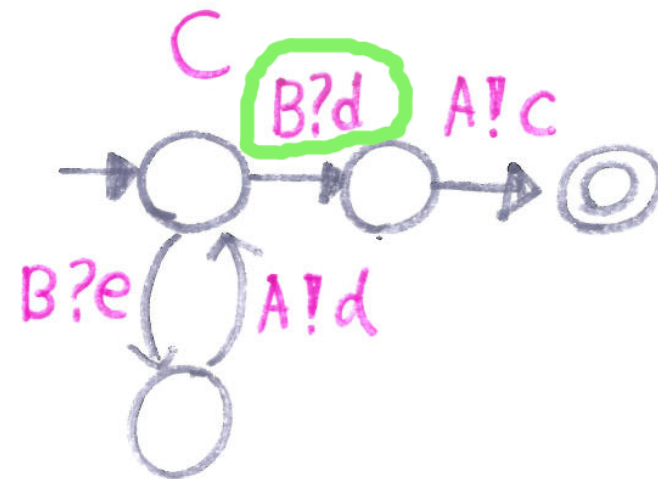
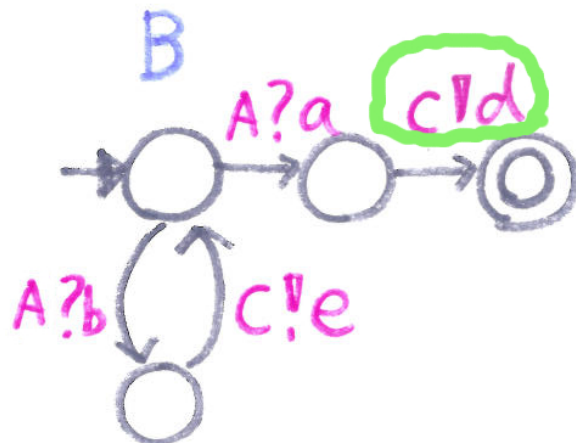
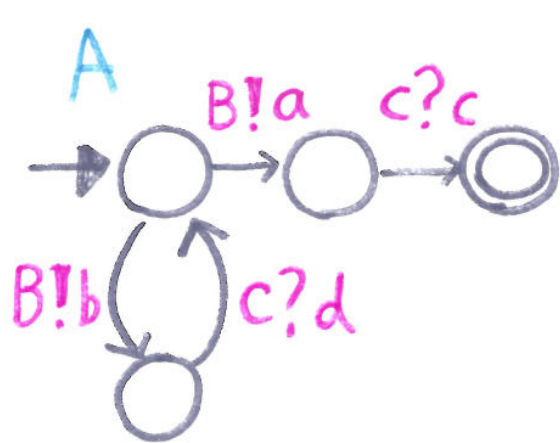


mt. $A \rightarrow B$: { a. $B \rightarrow C$: { d. $C \rightarrow A$: { c: end } }
 b. $B \rightarrow C$: { e. $C \rightarrow A$: { d: t } } }

Theorem Suppose S is basic and compatible.

Then there is an algorithm to build a well-formed G .

Synthesis

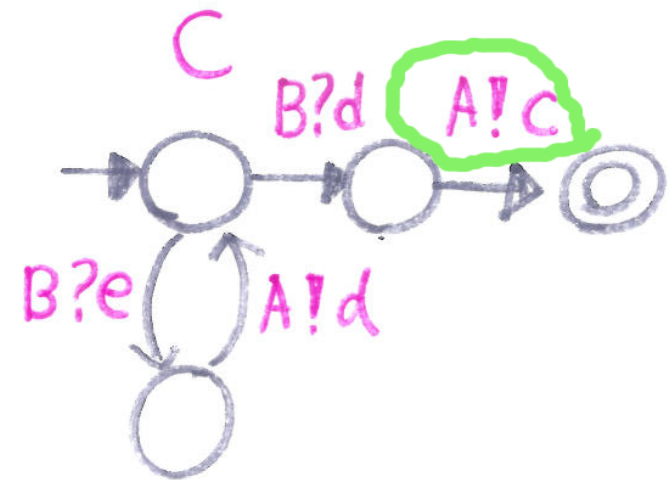
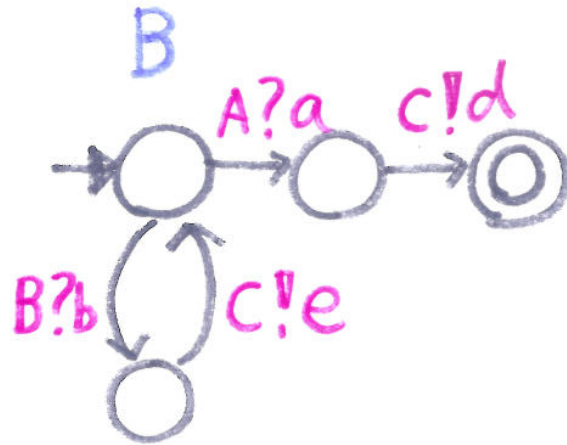
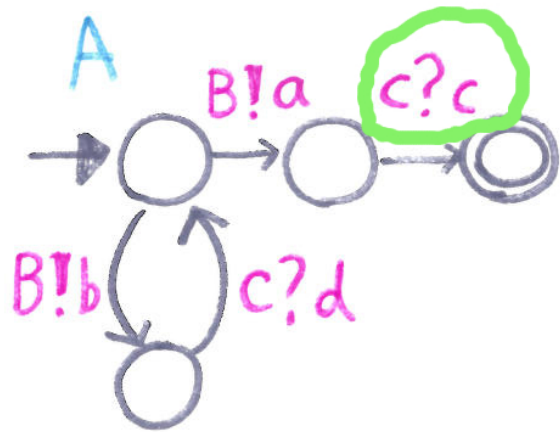


$\mu t . A \rightarrow B : \{ a . B \rightarrow C : \{ d . C \rightarrow A : \{ c : \text{end} \} \}$
 $b . B \rightarrow C : \{ e . C \rightarrow A : \{ d : t \} \} \}$

Theorem Suppose S is basic and compatible.

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Synthesis

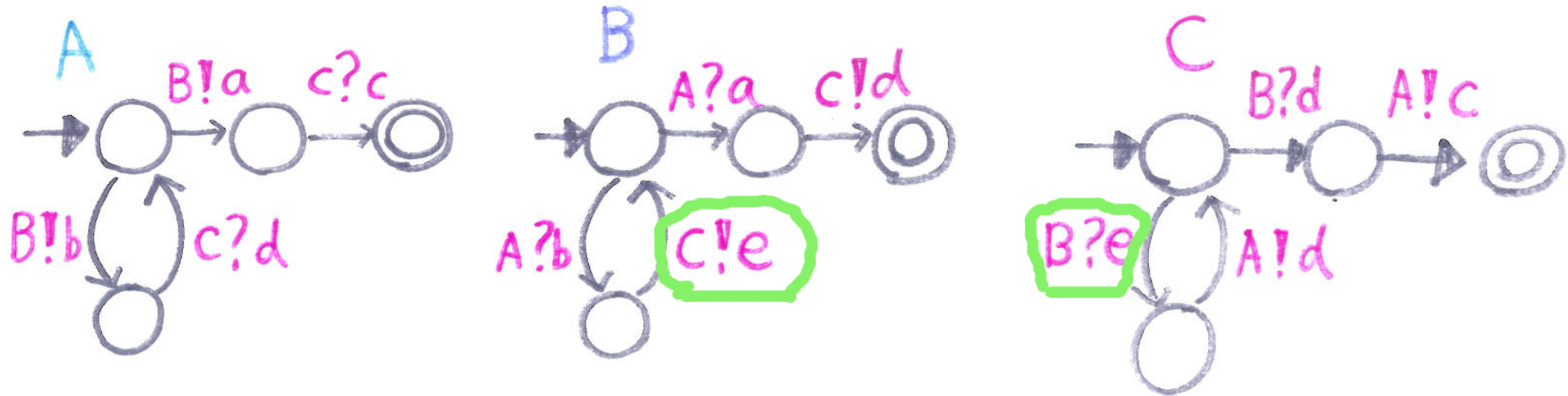


$\mu t . A \rightarrow B : \{ a . B \rightarrow C : \{ d . \underline{C \rightarrow A} : \{ \underline{c} : \text{end} \} \} \}$
 $b . B \rightarrow C : \{ e . C \rightarrow A : \{ d : t \} \} \}$

Theorem Suppose S is basic and compatible.

Then there is an algorithm to build a well-formed G .

Synthesis

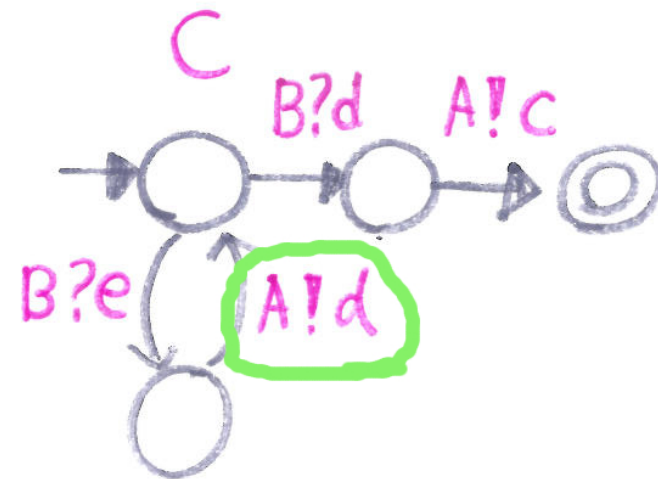
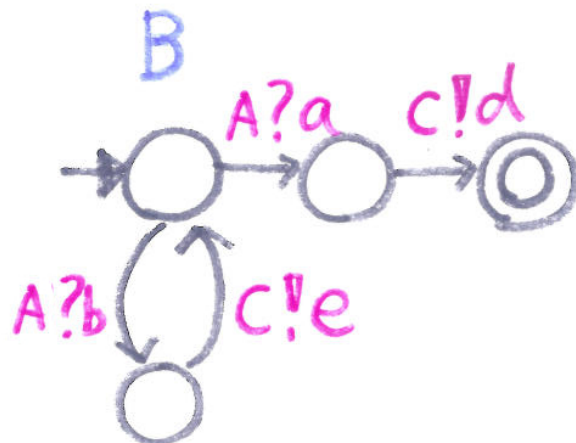
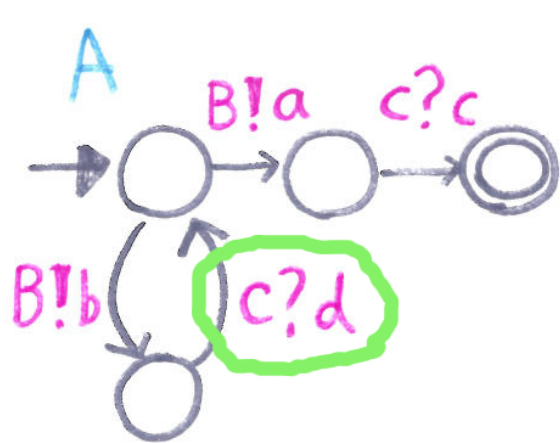


$\mu t . A \rightarrow B : \{ a . B \rightarrow C : \{ d . C \rightarrow A : \{ c : \text{end} \} \}$
 $b . \underline{B \rightarrow C} : \{ e . C \rightarrow A : \{ d : t \} \} \}$

Theorem Suppose S is basic and compatible.

Then there is an algorithm to build a well-formed G .

Synthesis

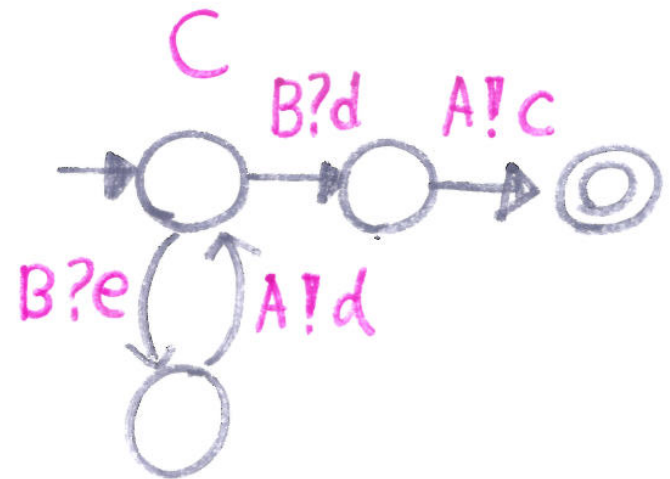
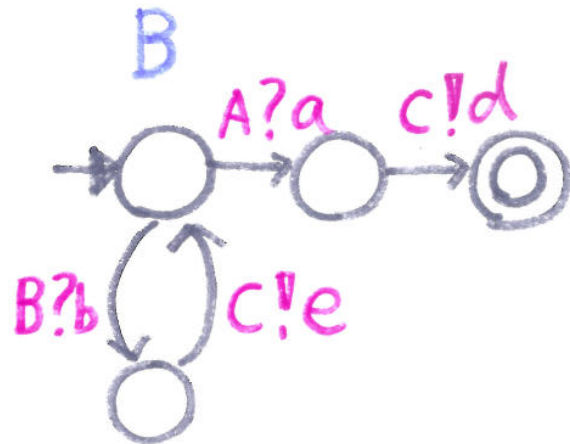
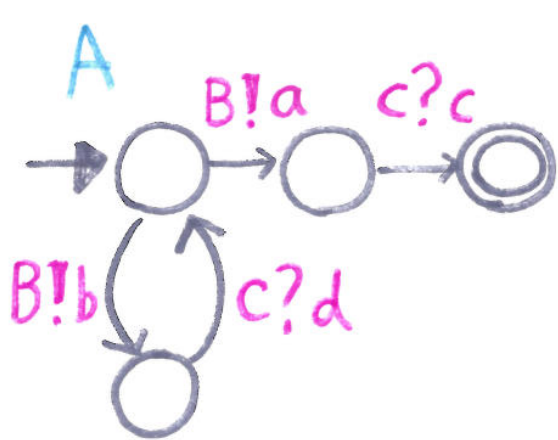


mt. $A \rightarrow B : \{ a. B \rightarrow C : \{ d. C \rightarrow A : \{ c : \text{end} \} \}$
 $b. B \rightarrow C : \{ e. C \rightarrow A : \{ d, t \} \} \}$

Theorem Suppose S is basic and compatible.

Then there is an algorithm to build a well-formed G .

Synthesis



$\mu t . A \rightarrow B : \{ a . B \rightarrow C : \{ d . C \rightarrow A : \{ c : end \} \}$
 $b . B \rightarrow C : \{ e . C \rightarrow A : \{ d : t \} \} \}$

Theorem

Problem!

S is ba

1-bound

$Tr(G) \approx 1$

compatible.

Then there is an algorithm to

$Tr(S)$

well-formed G .

Lemma If S is basic and multiparty compatible, then $\text{Tr}(S_1) \approx_1 \text{Tr}(S_2)$ implies $\text{Tr}(S_1) \approx \text{Tr}(S_2)$

Theorem Completeness

$$\begin{aligned} \text{Tr}(G) &\approx \text{Tr}(\{T_i\}_{i \in I}) && \text{Global} \approx \text{Local} \\ &\approx \text{Tr}(\{A(T_i)\}_{i \in I}) && \text{Local} \approx \text{CFSM} \\ &\approx_1 \text{Tr}(S) && \text{Synthesis} \\ &\approx \text{Tr}(S) && \text{Lemma} \end{aligned}$$

Suppose S is basic and compatible. Then there exists G s.t. $G \approx S$. If G is projectable, then there exists a multiparty compatible basic S s.t. S is safe and $G \approx S$.

Global Type

Local Types

G

①

$$G \approx \{T_i\}_{i \in I}$$

$\{T_i\}_{i \in I}$

basic

⑤ G realises
all traces in
 $\{M_i\}_{i \in I}$

②

$$T_i \approx M_i$$

④ Build

G from $\{M_i\}_{i \in I}$

Multiparty
Compatible
 $\{M_i\}_{i \in I}$ is safe

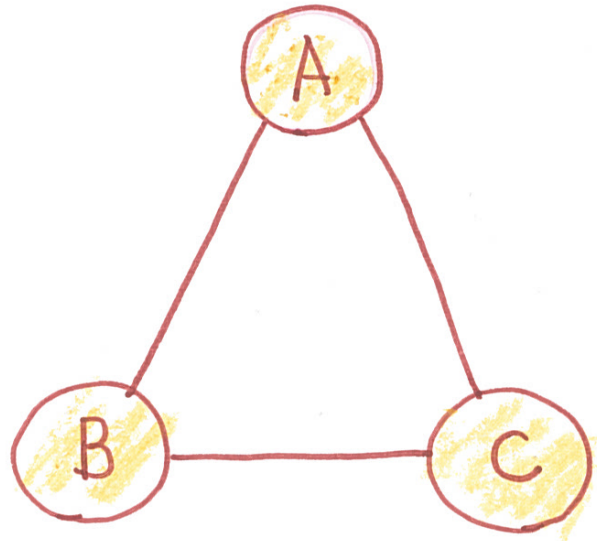
③ $\{T_i\}_{i \in I}$
Multiparty
Compatible

← multiparty
compatibility

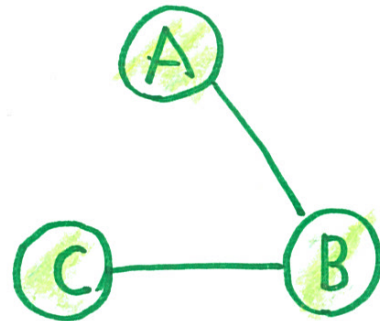
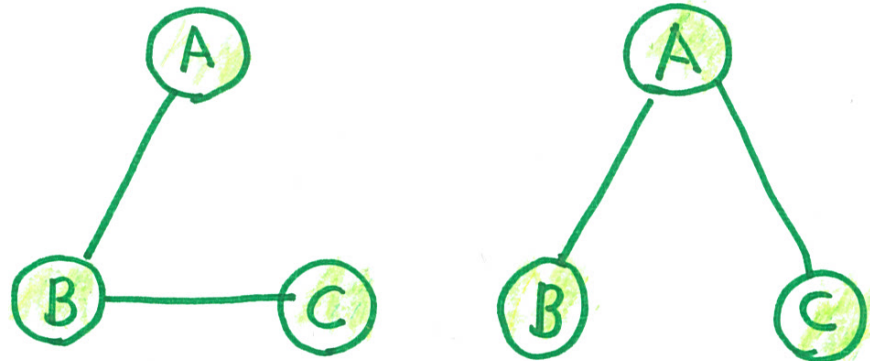
S

Automata
 $\{M_p\}_{p \in P}$

Interconnectability of Session Logical Processes



Multi Party



Linear Logical Session

cf. [1995] Specification Structures and Proposition as Types

Mapping and Fusing

Linear Logic

cut-free process

$x(z). \bar{y}\langle 1 \rangle$

Multi party

Thread
same participants

$\underline{S[P][Q]}(z). \underline{S[P][r]}\langle 1 \rangle$

Partial Global Type

$p \rightsquigarrow q \langle \text{Nat} \rangle ; p \rightsquigarrow r \langle \text{Int} \rangle$

Fuse Compositionally

Logic — Binary

$P \vdash \Delta, x:A \quad Q \vdash \Delta', x:A^+$

$(\nu x)(P | Q) \vdash \Delta, \Delta'$

$F(p \rightsquigarrow q \langle \text{Int} \rangle, p \rightsquigarrow r \langle \text{Bool} \rangle, r \rightsquigarrow p \langle \text{Bool} \rangle, r \rightsquigarrow s \langle \text{Nat} \rangle)$

$= p \rightsquigarrow q \langle \text{Int} \rangle, p \rightsquigarrow r \langle \text{Bool} \rangle, r \rightsquigarrow s \langle \text{Nat} \rangle.$

Mapping and Fusing

Linear Logic

cut-free process

$x(z). \bar{y}\langle 1 \rangle$

Multi party

Thread
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$\underline{S[P][Q]}(z). \underline{S[P][r]}\langle 1 \rangle$

Partial Global Type

$p \rightsquigarrow q \langle \text{Nat} \rangle ; p \rightsquigarrow r \langle \text{Int} \rangle$

Fuse Compositionally

Logic — Binary

$P \vdash \Delta, x:A \quad Q \vdash \Delta', x:A^+$

$(\nu x)(P | Q) \vdash \Delta, \Delta'$

$F(p \rightsquigarrow q \langle \text{Int} \rangle, p \rightsquigarrow r \langle \text{Bool} \rangle, r \rightsquigarrow p \langle \text{Bool} \rangle, r \rightsquigarrow s \langle \text{Nat} \rangle)$

$= p \rightsquigarrow q \langle \text{Int} \rangle, p \rightsquigarrow r \langle \text{Bool} \rangle, r \rightsquigarrow s \langle \text{Nat} \rangle.$

Theorem (uniqueness)

There is only one unique mapping from LL to Mp which preserves "cut-free process" (modulo bijective renaming)

Theorem (Interconnection Network)

ING : interconnection graph (NODES: PARTICIPANTS, EDGES $p \leftrightarrow q$)
in LL is acyclic.

proof

Fuse is acyclic. and Fused Global Types are Partial Multiparty Compatible

Results

- ① No name passing LL \rightarrow MP with a single session
- ② Delegation \rightarrow Several MPs
- ③ Replications \rightarrow No difference

[Multi cut by PMC]

$P \vdash \Delta, \underbrace{x_1:A_1, \dots, x_n:A_n}_G$

$Q \vdash \Delta', \underbrace{x_1:A_1^\perp, \dots, x_n:A_n^\perp}_{G'}$

G

G'

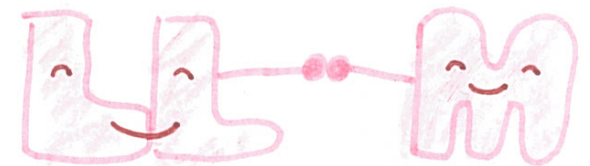
partial MC
fusible

$(\nu \tilde{x})(P | Q) \vdash \Delta, \Delta'$

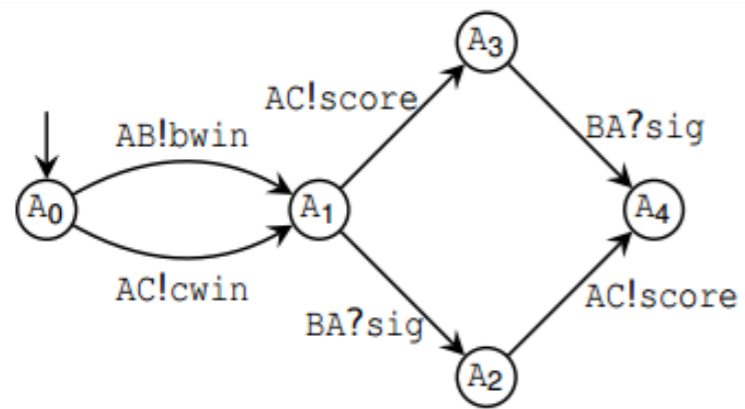
Theorem No Deadlock · Terminations

Cf. • More Typable Terms than [Concur'15 / Concur'16]
since PMC is more fine-grained.

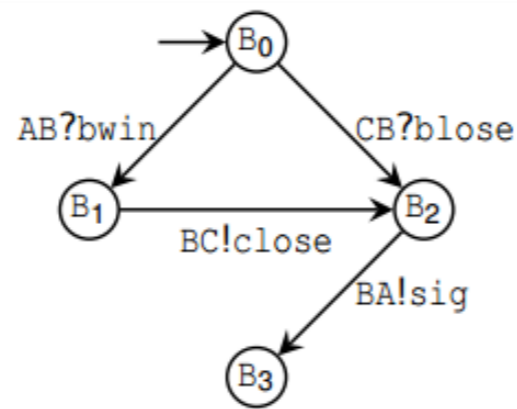
• No Need of Mediator or Annotations



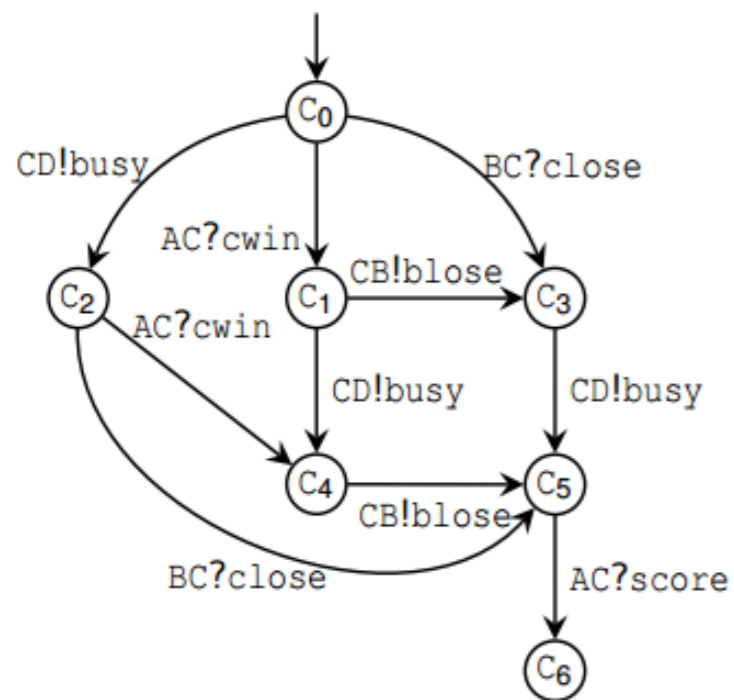
From Communicating Machines to Graphical Choreographies [POPL'15, CONCUR'15]



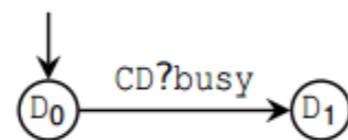
Alice



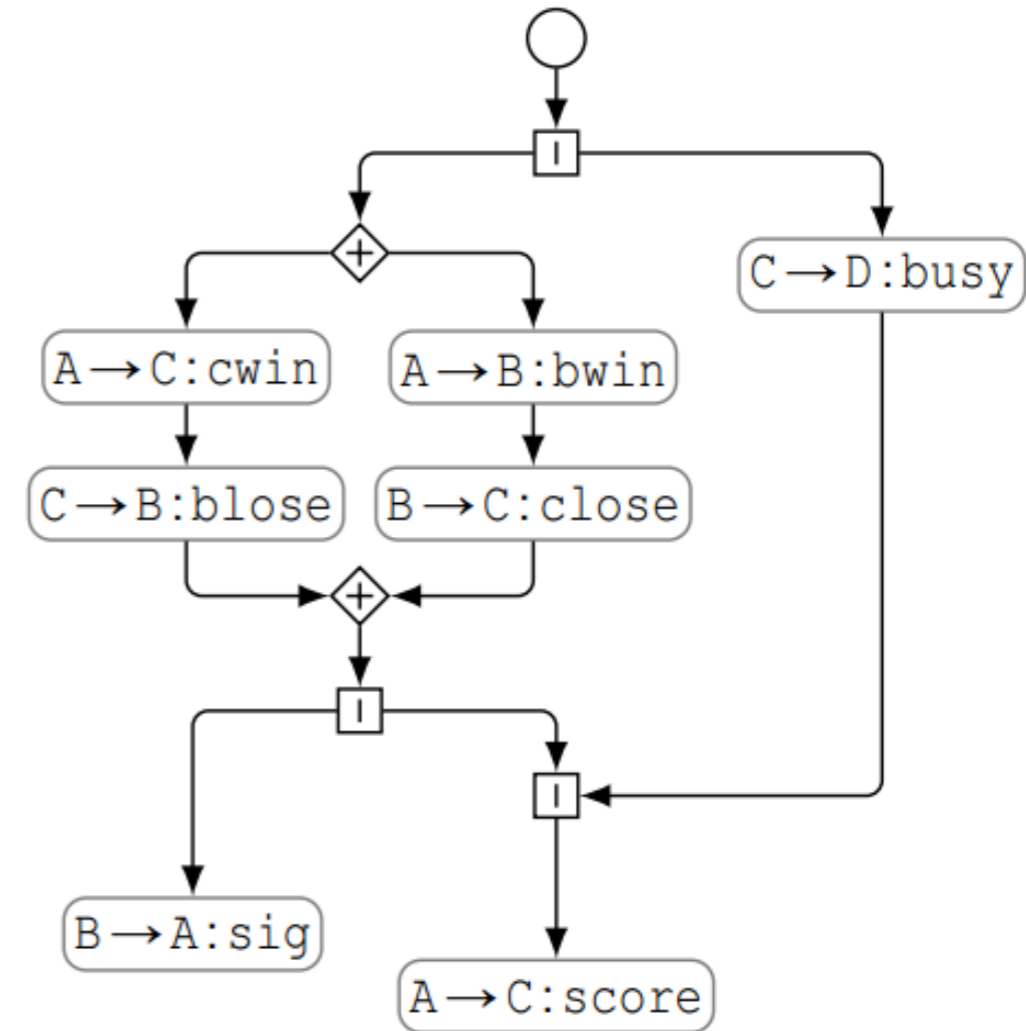
Bob



Carol



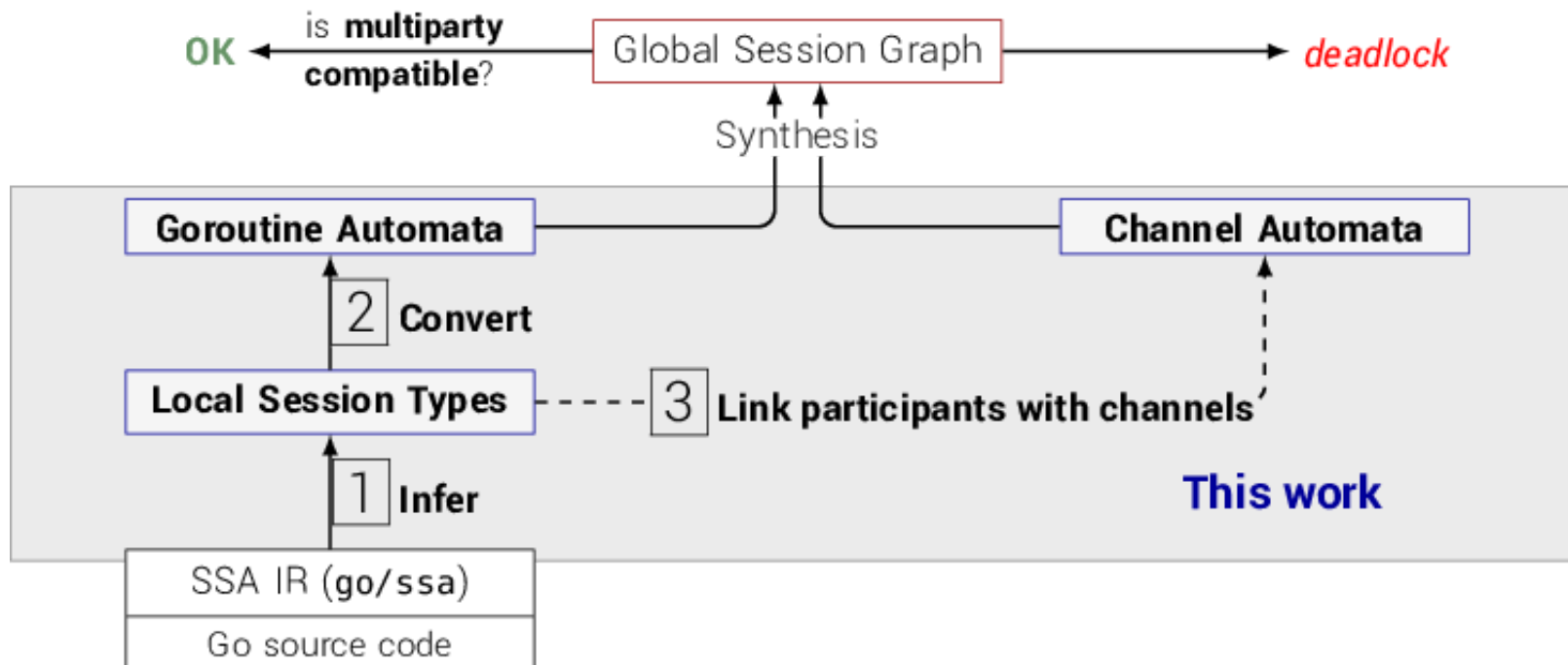
Dave



[ESOP'10,ESOP'12,CONCUR'12,CONCUR'14]

Contributions

- Static deadlock detection tool *dingo-hunter*
- Deadlock detection based on session types
- **Infer** session types as Communicating Automata
- **Synthesise** global session graphs from CA



Go and Concurrency

- Developed by Google for multi-core programming
- Concurrency model built on CSP (process calculi)
- Message-passing **communication** over channels

" Do not communicate by sharing memory; instead, share memory by communicating. "

-- Effective Go (developer guide)

Java API Generation [FASE'16]



RFC 821

August 1982
Simple Mail Transfer Protocol

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□

channels

C

ioifaces

EndSocket.java

Smtplib_C_1_Future.java

Smtplib_C_1.java

Smtplib_C_10.java

Smtplib_C_11_Cases.java

Smtplib_C_11_Handler.java

Smtplib_C_11.java

Smtplib_C_12.java

```
.send(Smtplib.S, new DataLine("Session  
.send(Smtplib.S, new EndOfData())  
.receive(Smtplib.S, Smtplib._250, new Buf  
.S
```

● send(S role, Mail m) : Smtplib_C_11 - Smtplib_C_10

● send(S role, Quit m) : EndSocket - Smtplib_C_10