

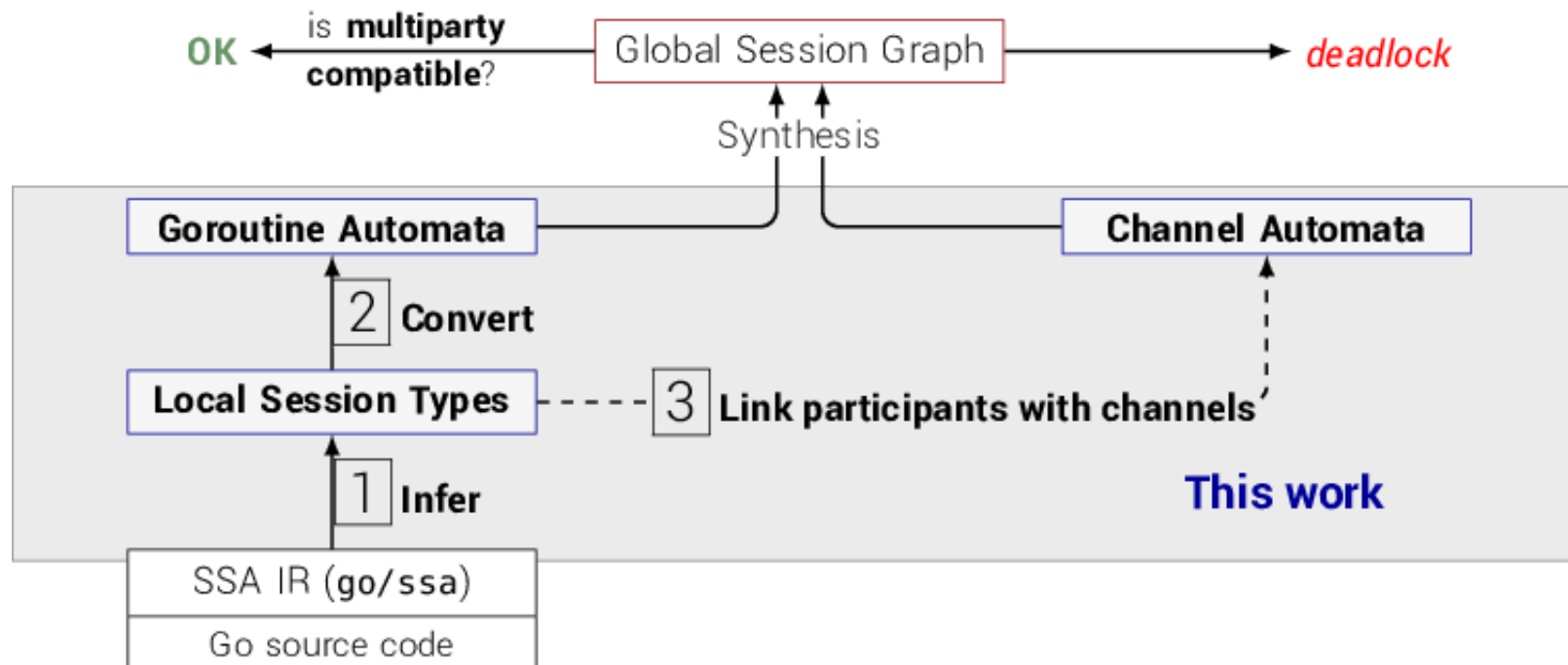
# Static Deadlock Detection for Go by Global Session Graph Synthesis

Nicholas Ng & Nobuko Yoshida

Department of Computing  
Imperial College London

# Contributions

- Static deadlock detection tool *dingo-hunter*
- Deadlock detection based on session types
- **Infer** session types as Communicating Automata
- **Synthesise** global session graphs from CA



# Go and Concurrency

- Developed by Google for multi-core programming
- Concurrency model built on CSP (process calculi)
- Message-passing **communication** over channels

*" Do not communicate by sharing memory; instead, share memory by communicating. "*

-- Effective Go (developer guide)

# Go concurrency: Goroutines and Channels

- Goroutines: lightweight threads
- Channels: bounded queues (default size 0)
- Go concurrency = compose goroutines & coordinate with channels

```
func deepThought(replyCh chan int) {  
    time.Sleep(75 * time.Millisecond)  
    replyCh <- 42  
}  
  
func main() {  
    ch := make(chan int)  
    go deepThought(ch)  
    answer := <-ch  
    fmt.Printf("The answer is %d\n", answer)  
}
```

Run

# Concurrency Problems

- Deadlocks 😞
- *Some* goroutines are blocked waiting forever

```
func deepThought(replyCh chan int) {  
    time.Sleep(75 * time.Millisecond)  
    replyCh <- 42  
}  
  
func main() {  
    ch := make(chan int)  
    go deepThought(ch)  
    answer := <-ch  
    fmt.Printf("The answer is %d\n", answer)  
}
```

Run

# fatal error: all goroutines are asleep - deadlock!

- Go has a *runtime* [deadlock detector](https://github.com/golang/go/blob/d2c81ad84776edfb4c790666f1d80554b4393d46/src/runtime/proc.go#L3243)

(<https://github.com/golang/go/blob/d2c81ad84776edfb4c790666f1d80554b4393d46/src/runtime/proc.go#L3243>)

- No. of running goroutines: if  $run > 0 \rightarrow$  OK ✓; if  $run == 0 \rightarrow$  deadlock ☹️

```
// From Go source code - https://github.com/golang/go
// File runtime/proc.go

func checkdead() {
    ...
    // -1 for sysmon
    run := sched.mcount - sched.nmiddle - sched.nmiddlelocked - 1
    if run > 0 {
        return
    }
    ...
    getg().m.throwing = -1 // do not dump full stacks
    throw("all goroutines are asleep - deadlock!")
}
```

## Runtime deadlock detection

- No false positive
- Only if deadlock during execution
- Only **global** deadlocks: if ALL goroutines are blocked

# Defeating runtime deadlock detection

```
func Send(ch chan<- int) { ch <- 42 } // Send
func RecvAck(ch <-chan int, done chan<- int) { v := <-ch; done <- v } // Recv then Send

func main() {
    ch, done := make(chan int), make(chan int)
    go Send(ch)
    go RecvAck(ch, done)
    go RecvAck(ch, done) // OOPS

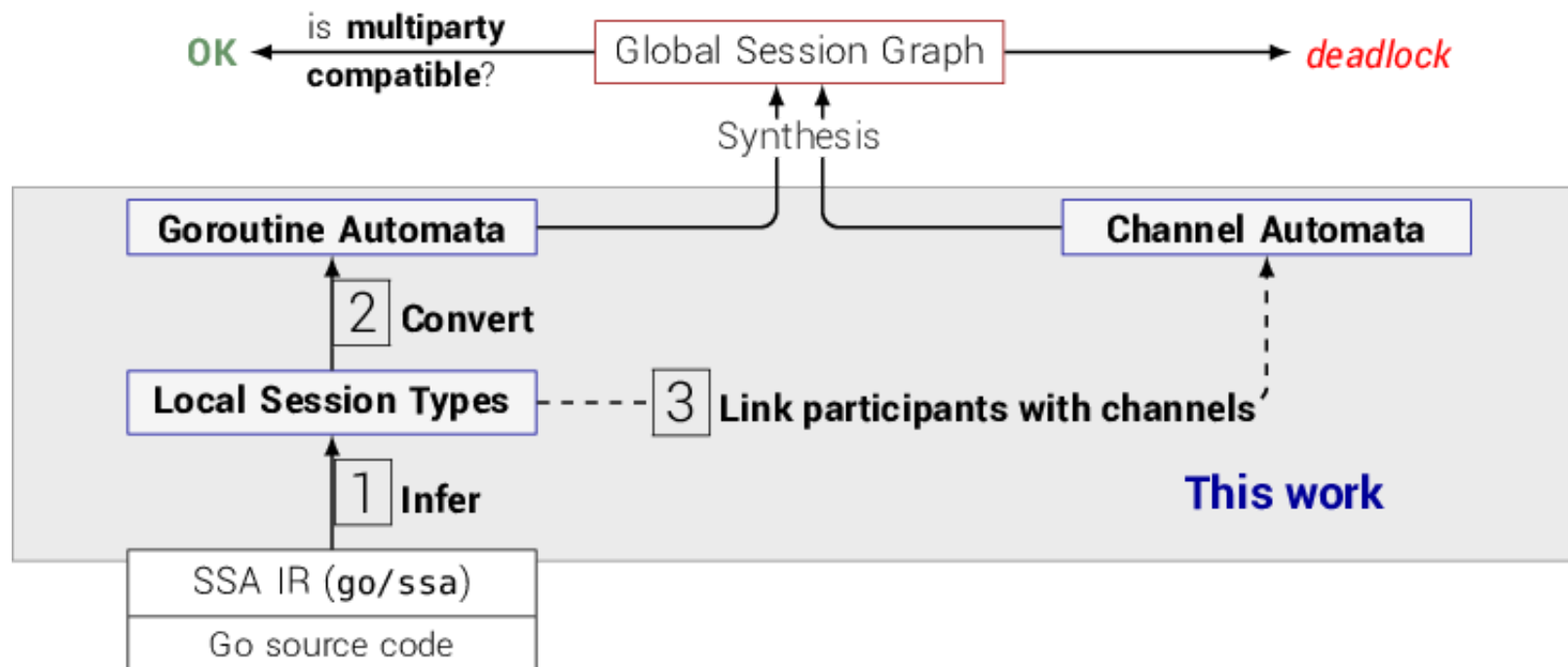
    // Anonymous goroutine: Some long running work (e.g. http service)
    go func() {
        for i := 0; i < 3; i++ {
            fmt.Println("Working #", i)
            time.Sleep(1 * time.Second)
        }
    }()
    result = <-done
    result = <-done // OOPS
    fmt.Println("Result is ", result)
}
```

Run

This will be our running example

# Static Analysis & Deadlock Detection by Global Graph Synthesis

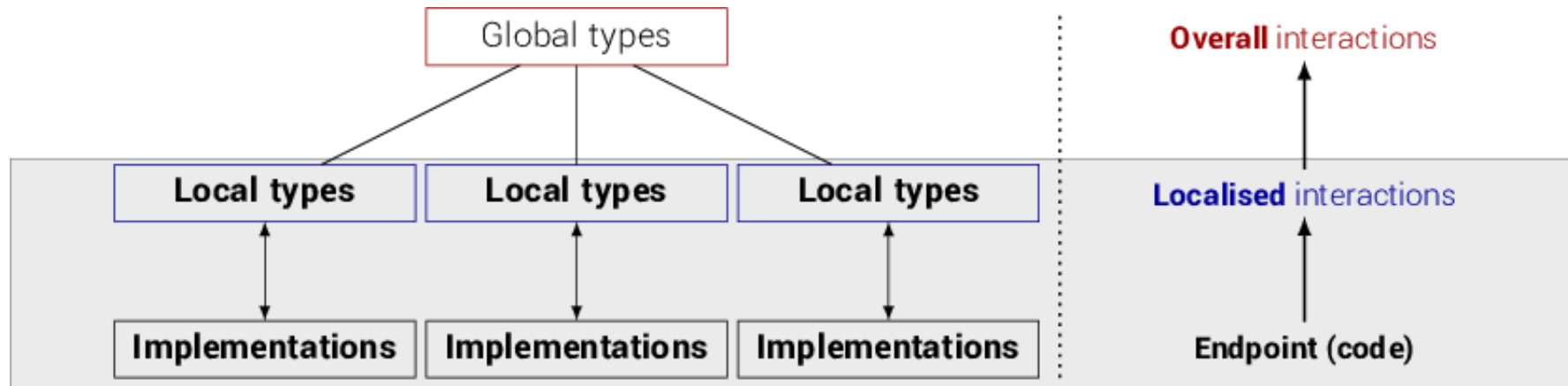
# Static Analysis & Deadlock Detection by Global Graph Synthesis



- Explore all branches (vs. only execution path for runtime checker)
- Approach based on **Multiparty Session Types** (MPST) [1]
- Guarantee communication-safety & **deadlock-freedom** for n-party interactions

[1]: Honda, Yoshida, Carbone, *Multiparty Asynchronous Session Types*, POPL'08, J. ACM

# The Multiparty Session Types (MPST) framework



- **Global Graph Synthesis** [2] local type(s)  $\longrightarrow$  global type
- Local types as *Communicating Automata* [3]
- Global types as *graphical choreographies*
- Safety guaranteed by **multiparty compatibility** property (global)

[2]: Lange, Tuosto, Yoshida, *From Communicating Machines to Graphical Choreographies*, POPL'15

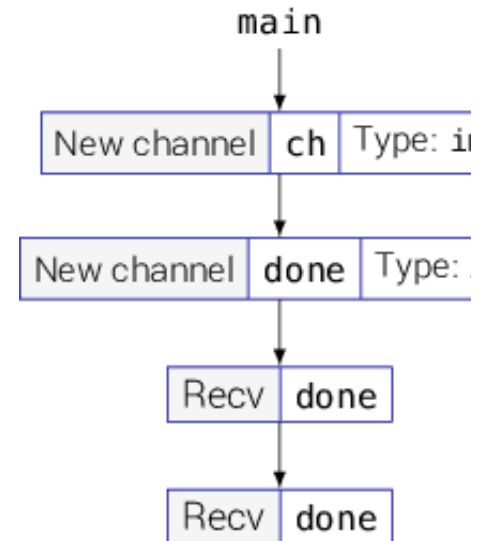
[3]: Brand, Zafiropulo, *On communicating finite-state machines*, J. ACM Vol. 30 No. 2, 1983

# Type inference from Go code

- Control flow graph as Finite State Machine (FSM), per goroutine
- + Communication primitives: `make(chan T)`, `send`, `receive`

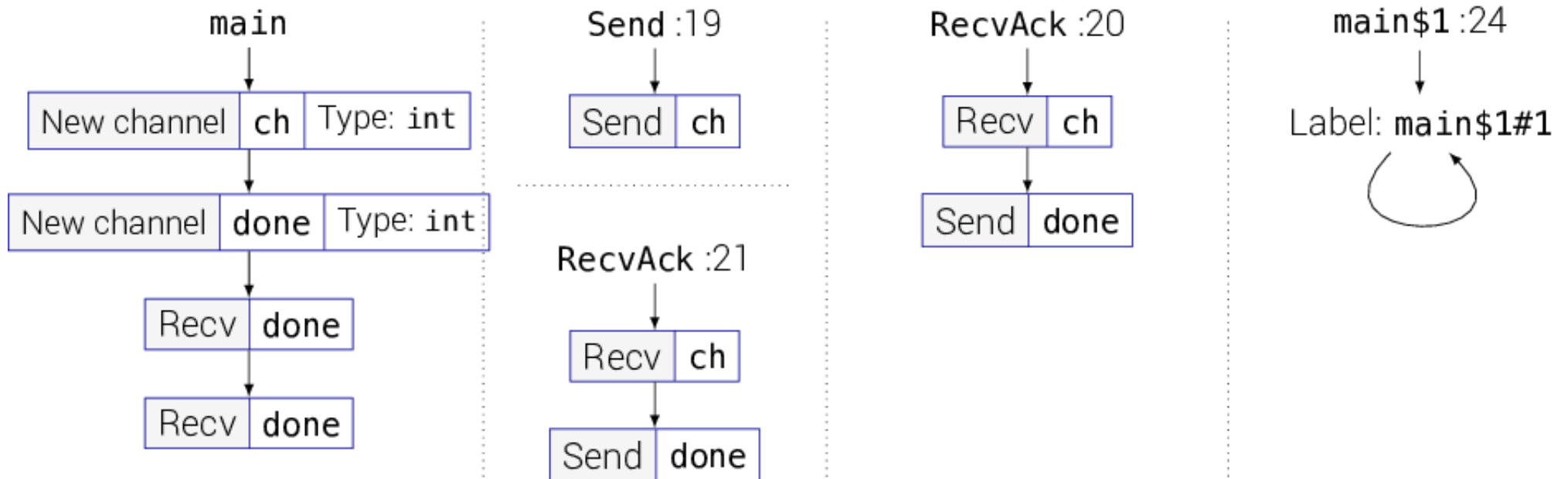
```
func main() {
    ch, done := make(chan int), make(chan int)
    go Send(ch)
    go RecvAck(ch, done)
    go RecvAck(ch, done) // OOPS

    // Anonymous goroutine: Some long running work (e.g. http service)
    go func() {
        for i := 0; i < 3; i++ {
            fmt.Println("Working #", i); time.Sleep(1 * time.Second)
        }
    }()
    result = <-done
    result = <-done // OOPS
    fmt.Println("Result is ", result)
}
```



# Inferred local session types

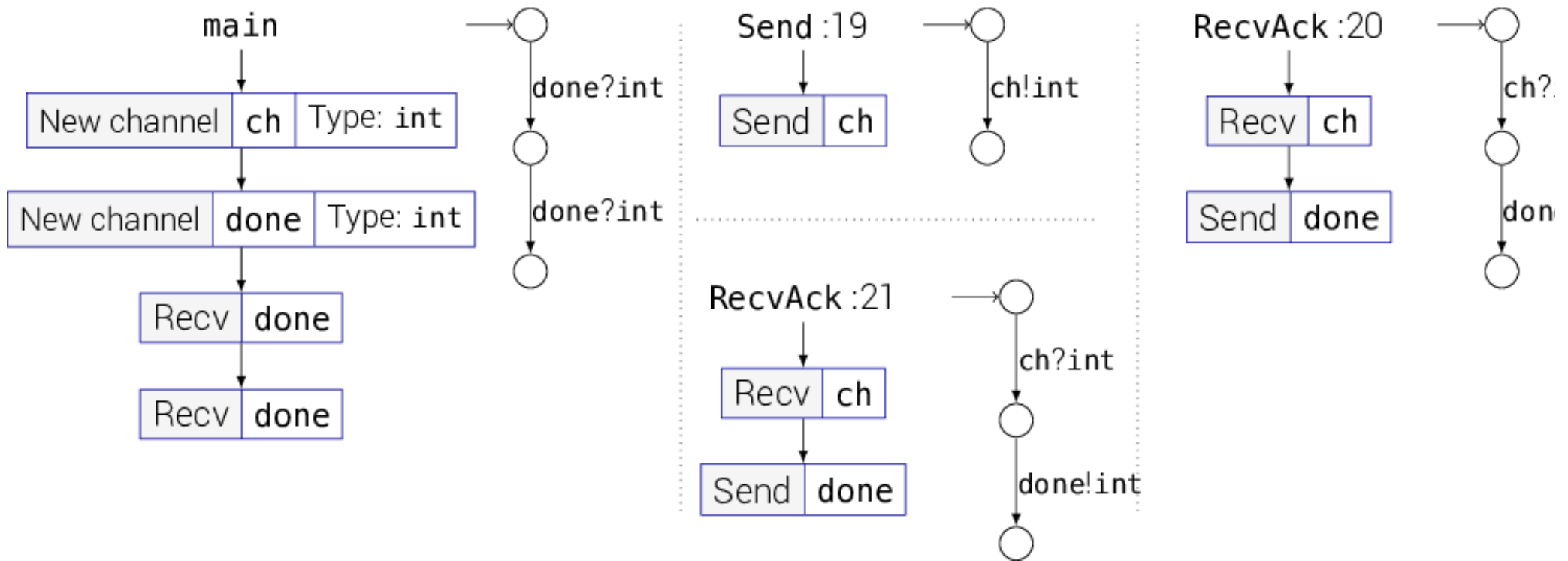
- For simplicity: real variable names
- Note: `main$1 : 24` (work anonymous function) has no communication



Variable names: `ch = main.t0`, `done = main.t1`

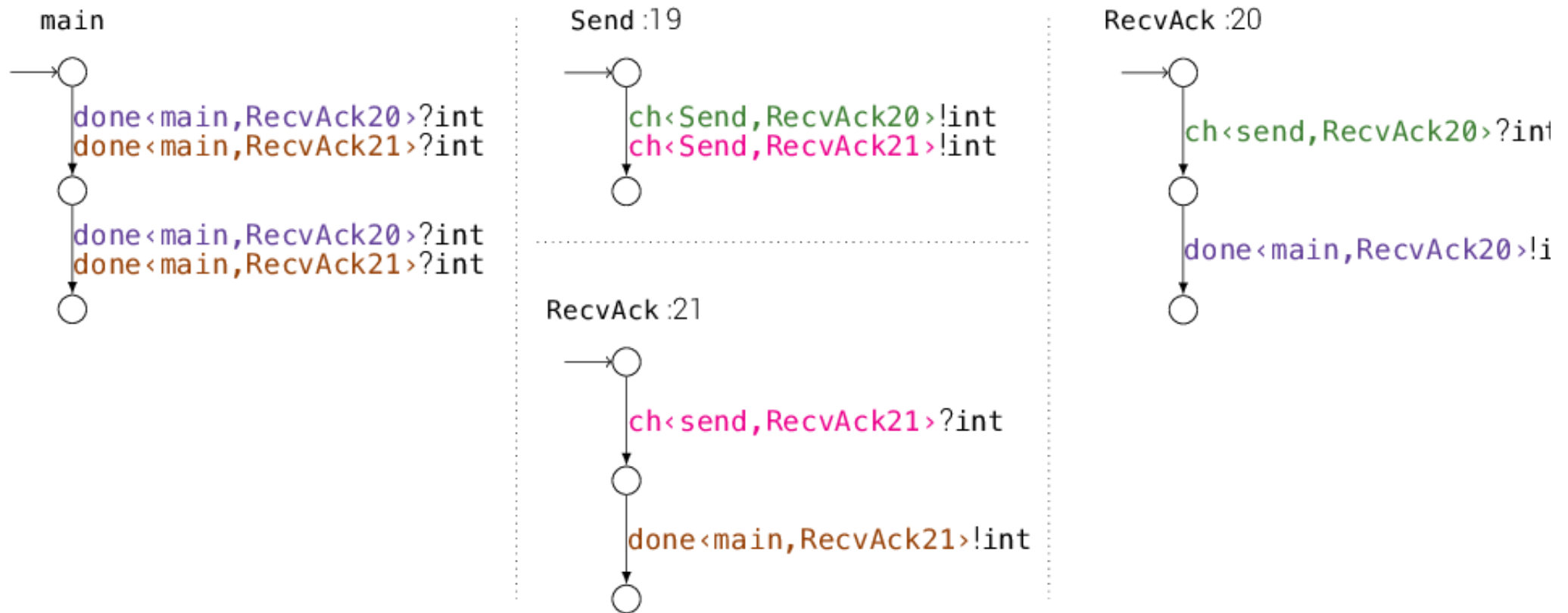
# Inferred Local Types to Goroutine Automata

- Local session types  $\implies$  *Communicating Automata*
- Receive** is ? transition, **Send** is ! transition



# Channel Automata

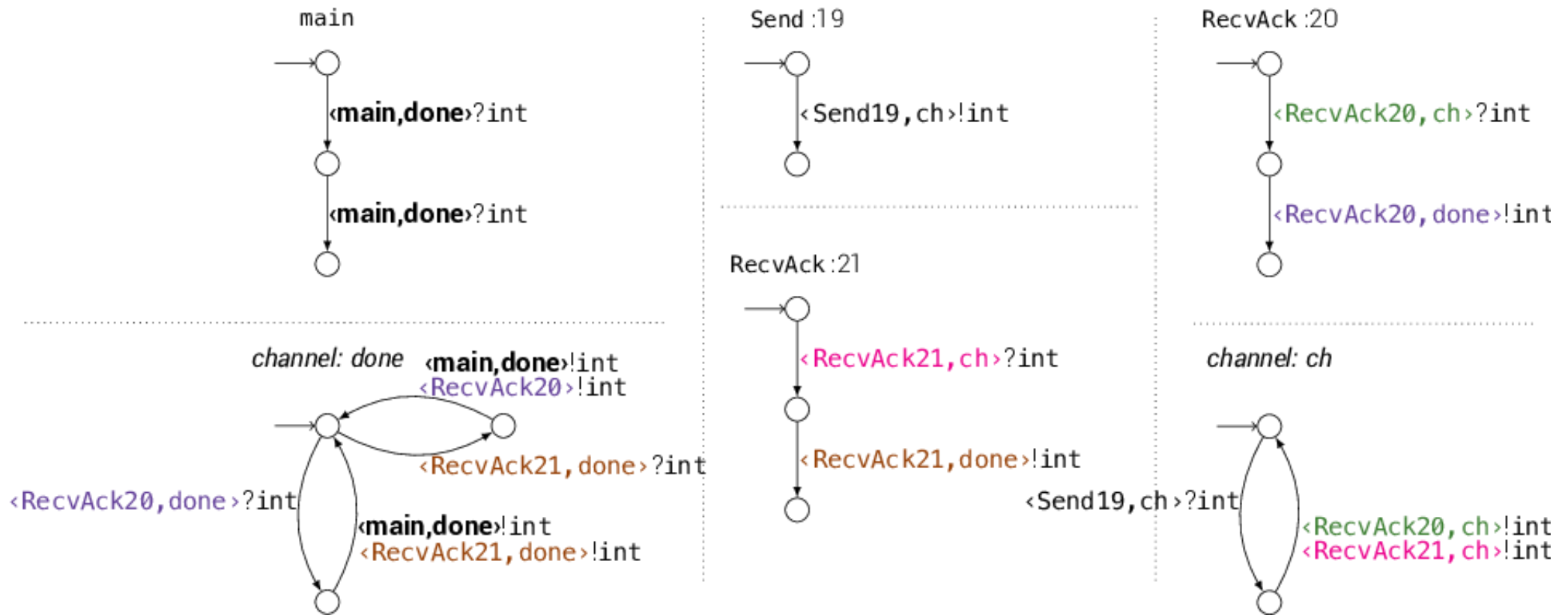
- Channels in **Communicating Automata** - *fixed* point-to-point links
- **Go channels** - *shared*, do not represent *fixed* endpoint
- 2 goroutines writing to same channel valid ✓



Note: Go channels valid regardless of the deadlock

# Channel Automata

- Channel Automata defers selection to a machine (for each channel)
- Unbuffered channel  $q_0 \rightarrow \text{receive} \rightarrow \text{send} \rightarrow q_0$



Channel Automata *done* & *ch* (only essential transitions)

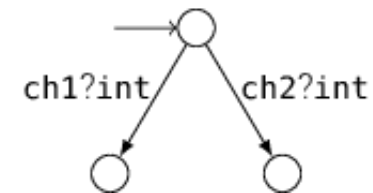
## Bonus: Select non-deterministic choice

- Switch-case for communication

```
func main() {  
    ch1, ch2 := make(chan int), make(chan int)  
    go calc(ch1)  
    go calc(ch2)  
    select {  
    case ans := <-ch1:  
        fmt.Println("Answer from ch1: ", ans)  
    case ans := <-ch2:  
        fmt.Println("Answer from ch2: ", ans)  
    }  
}
```

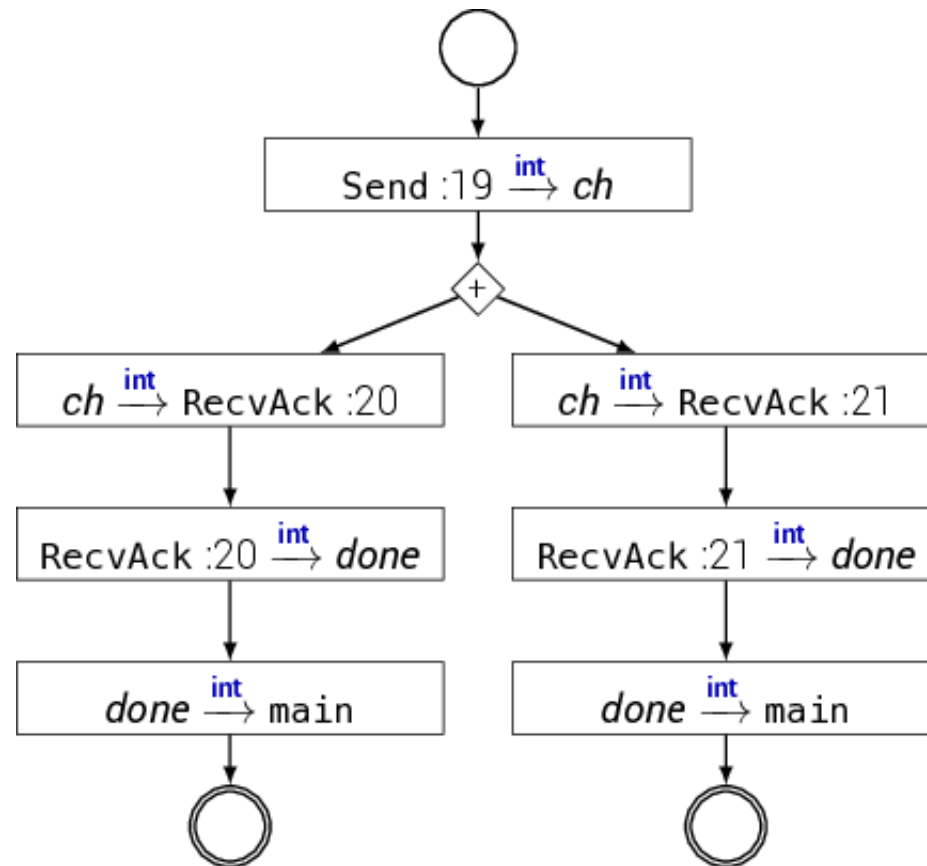
Run

Select (non-deterministic choice)



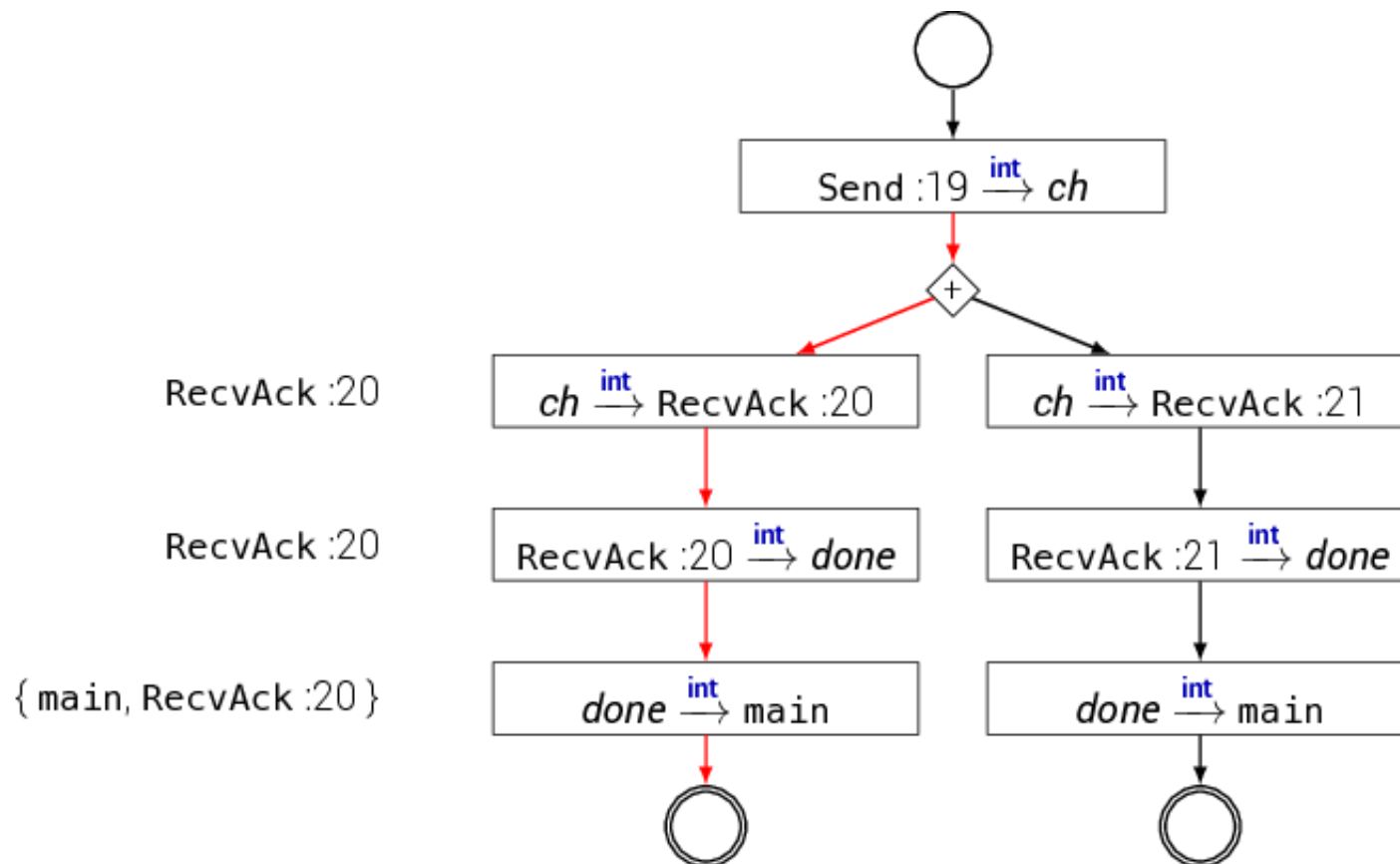
# Global Graph Synthesis

- Join both automata to get overall **global** graph
- All synchronous transitions,  $A: ch!int + B: ch?int$  becomes  $A \rightarrow B: int$



# Global Graph Synthesis: What is safe?

- **Multiparty Compatibility** property on global graph
- **Representability** All [Goroutine] automata are "represented" in global graph
- **Branching condition** Branches are propagated to all machines in choice

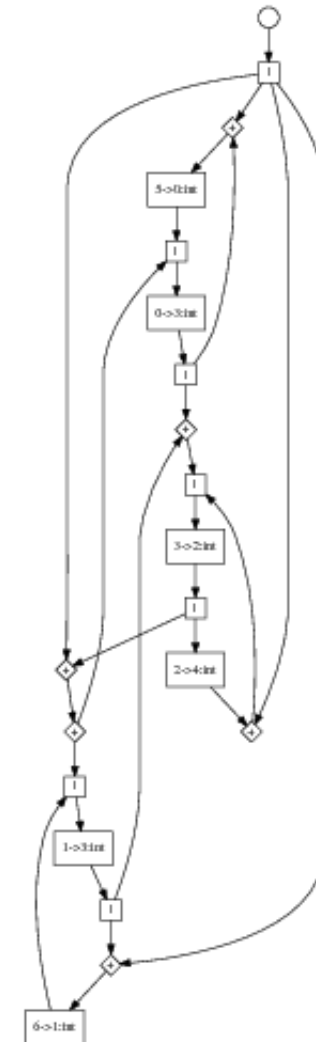


# Fan-in pattern

- Merging pattern with select

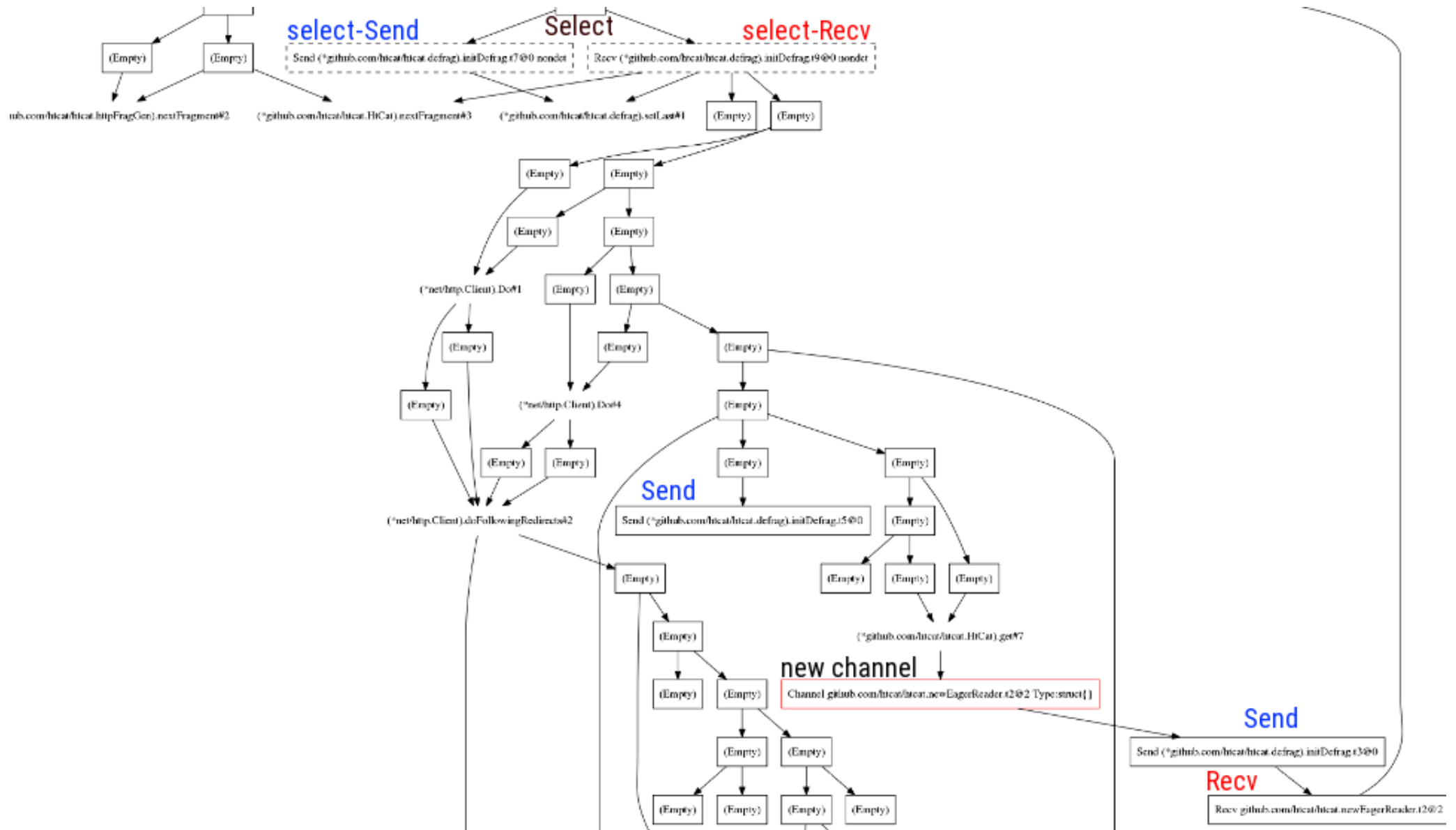
```
func fanin(input1, input2 <-chan int) <-chan int {  
    c := make(chan int)  
    go func() {  
        for {  
            select {  
            case s := <-input1:  
                c <- s  
            case s := <-input2:  
                c <- s  
            }  
        }  
    }()  
    return c  
}
```

Run





# Bigger example: htcats - Concurrent HTTP GETs



[github.com:htcat/htcat](https://github.com/htcat/htcat) (<https://github.com/htcat/htcat>) (721 LoC)

## Bigger example: htcats - Concurrent HTTP GETs

- 7xx lines
- 9632 nodes
- 11 Goroutine Automata / 8 Channel Automata
- Safe ✓
- Error handling code: conditional new goroutine

```
if err != nil {  
    go cat.d.cancel(err)  
    return  
}
```

# Conclusion

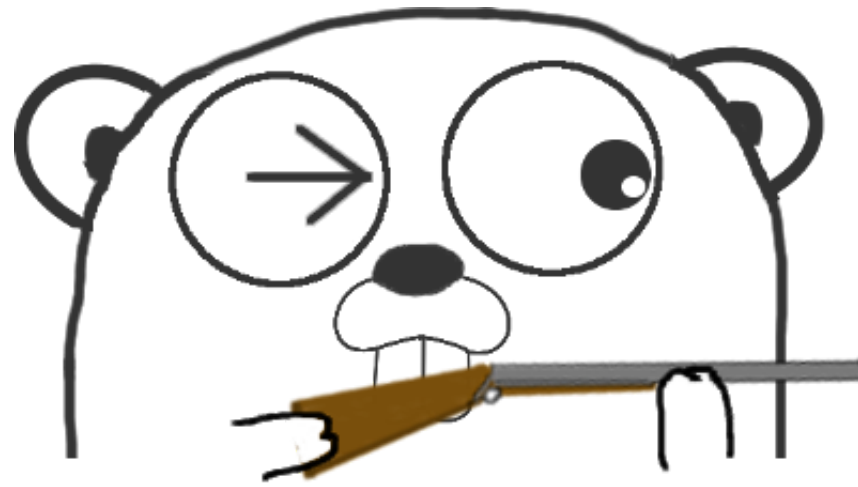
- Static analysis tool for Go
- Detect deadlock through global session graph synthesis
- Applied to open source code base

## Static analysis tool

- [github.com/nickng/dingo-hunter](https://github.com/nickng/dingo-hunter) (<https://github.com/nickng/dingo-hunter>)

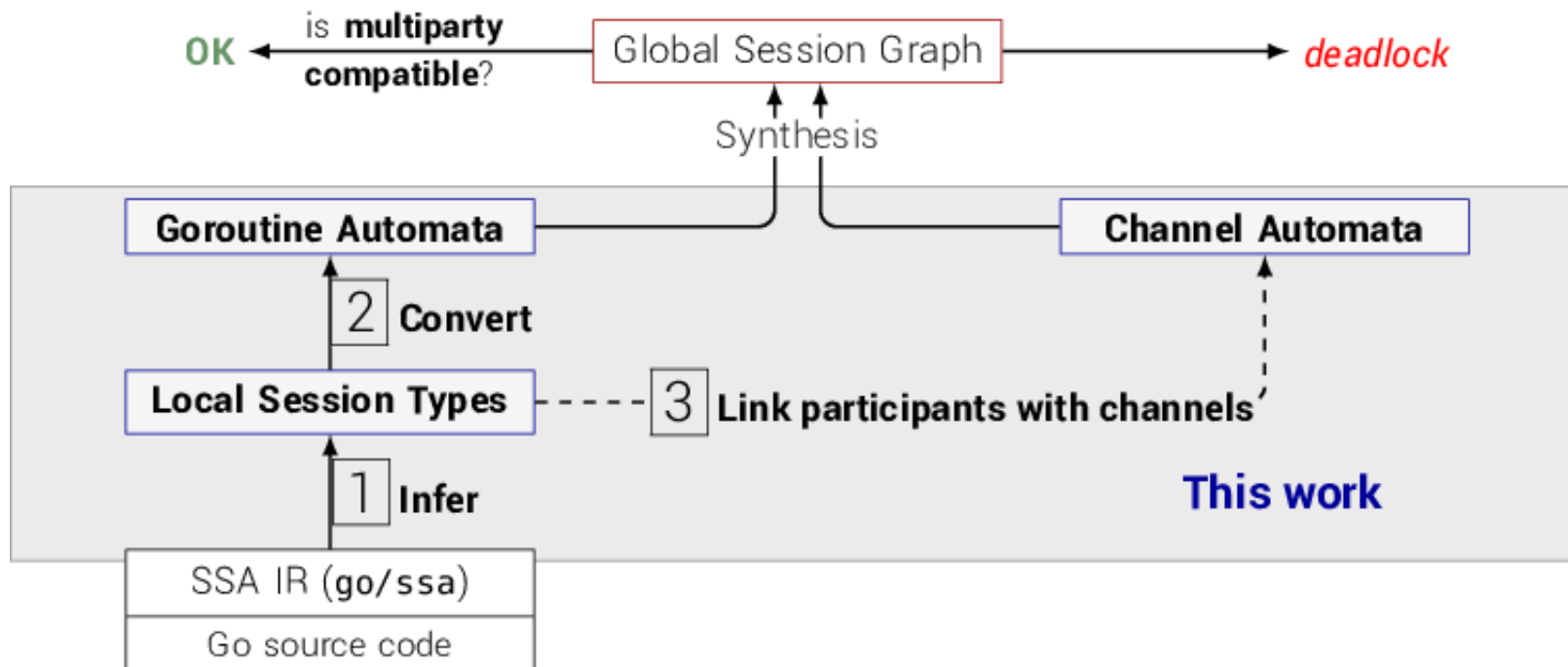
## Synthesis tool (POPL'15 artifact)

- [bitbucket.org/julien-lange/gmc-synthesis](https://bitbucket.org/julien-lange/gmc-synthesis) (<https://bitbucket.org/julien-lange/gmc-synthesis>)



# Future Work

- Buffered channels asynchronous communication over channels
- Dynamic patterns Expand bounded ranges (e.g. for  $i:=0; i<10; i++ \{ \dots \}$ )



# Thank you

Nicholas Ng & Nobuko Yoshida

Department of Computing  
Imperial College London

[{nickng,n.yoshida}@imperial.ac.uk](mailto:{nickng,n.yoshida}@imperial.ac.uk)  (mailto:%7bnickng,n.yoshida%7d@imperial.ac.uk)

<http://mrg.doc.ic.ac.uk> (http://mrg.doc.ic.ac.uk)

