

The full π -calculus: simple and expressive

π -Refresh. What we know so far?

- We have studied the asynchronous monadic π -calculus
 - no continuation on the output (asynchronous) $\bar{u}\langle v\rangle.P$
 - only one value is communicated (monadic) $\bar{u}\langle v\rangle$

$P, Q ::=$	processes
0	nil process
$P \mid Q$	parallel composition of P and Q
$(\nu a)P$	generation of a with scope P (also called <i>restriction</i>)
$!P$	replication of P , i.e. infinite parallel composition $P \mid P \mid P \mid \dots$
$\bar{u}\langle v\rangle$	output of v on channel u
$u(x).P$	input of <i>distinct</i> variables x on u , with continuation P

π -calculus: simple, but expressive

- Why expressive:
 - encoding data structures
 - encoding polyadic communication with monadic primitives
 - encoding synchronous communication with asynchronous (Honda/Tokoro, Boudol)
 - encoding choice (Nestmann, Palamidessi)
 - encoding recursion
 - encoding Higher order functions

Today you will learn how to master that expressiveness ... !!!

Synchronous π -calculus

- It is time to add continuation on output: $\bar{u}\langle v\rangle.P$
- We can define the synchronous calculus as follows:

$$\bar{a}\langle b\rangle.P \mid a(x).Q \longrightarrow P \mid Q\{b/x\}$$



Q: Can we simulate synchronous communication with asynchronous?

Hint: we need additional messages

Basic Encoding Definition

- $\llbracket P \rrbracket = Q$ is a function (mapping) from P to Q .
- A good mapping should be homomorphic.
 - $\llbracket 0 \rrbracket = 0$
 - $\llbracket P \mid Q \rrbracket = \llbracket P \rrbracket \mid \llbracket Q \rrbracket$
 - $\llbracket (\nu a)P \rrbracket = (\nu a)\llbracket P \rrbracket$
 - $\llbracket !P \rrbracket = !\llbracket P \rrbracket$
- Question:
 - $\llbracket \bar{a}\langle b \rangle.P \rrbracket = \text{some asynchronous } \pi\text{-term}$
 - $\llbracket a(x).P \rrbracket = \text{some asynchronous } \pi\text{-term}$

Synchronous π -calculus

Synchronous



$$\llbracket \bar{u}\langle v \rangle . P \rrbracket = (\nu c)(\bar{u}\langle c \rangle \mid c(y).(\bar{y}\langle v \rangle \mid \llbracket P \rrbracket))$$

$$\llbracket u(x).P \rrbracket = u(y).(\nu d)(\bar{y}\langle d \rangle \mid d(x).\llbracket P \rrbracket)$$

Asynchronous



$$\text{where } y \notin fv(P), c \notin fn(P)$$

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- Note: $\llbracket P \rrbracket$ represents the formal notation for the encoding of P

- Example:

$$\begin{aligned} \llbracket \bar{b}\langle e \rangle . P \rrbracket \mid \llbracket b(x).Q \rrbracket &\longrightarrow (\nu c)(c(y).(\bar{y}\langle e \rangle \mid \llbracket P \rrbracket) \mid (\nu d)(\bar{c}\langle d \rangle \mid d(x).\llbracket Q \rrbracket)) \\ &\longrightarrow (\nu d)(\bar{d}\langle e \rangle \mid \llbracket P \rrbracket \mid d(x).\llbracket Q \rrbracket) \longrightarrow \llbracket P \rrbracket \mid \llbracket Q \rrbracket\{e/x\} \end{aligned}$$

- How it works:
 - The channel u is used to exchange a private name c
 - The meaning of u is that the receiver will be engaged in the rendez-vous with the sender
 - The sender confirms on c by sending the private channel d
 - Now the actual transmission can occur on the channel d

Polyadic π -calculus

- Monadic channels carry exactly one name: $\bar{u}\langle v \rangle, u(x)$
- Polyadic channels carry a vector of names:

$$P ::= \begin{array}{ll} u(x_1, \dots, x_n).P & \text{input} \\ \bar{u}\langle v_1, \dots, v_n \rangle.P & \text{output} \end{array}$$

- We can communicate multiple values at the same time
- Reduction Rule:

$$\bar{a}\langle c_1, \dots, c_n \rangle.P \mid a(x_1, \dots, x_n).Q \longrightarrow P \mid Q\{\tilde{c}/\tilde{x}\}$$



Is there an encoding from polyadic to monadic channels?

Let's Try

- For every complex problem there is a simple solution ... that is wrong :)

$$\llbracket u(x_1, \dots, x_n).P \rrbracket = u(x_1).u(x_2)\dots u(x_n).\llbracket P \rrbracket$$

$$\llbracket \bar{u}\langle v_1, \dots, v_n \rangle.P \rrbracket = \bar{u}\langle v_1 \rangle.\bar{u}\langle v_2 \rangle \dots \bar{u}\langle v_n \rangle.\llbracket P \rrbracket$$

- Why the above encoding is ... wrong ?
- **Hint:** encode two processes in parallel sending on the same channel

$$\llbracket a(x_1, x_2).P_1 \mid a(x_3, x_4).P_2 \mid \bar{a}\langle c_1, c_2 \rangle.P_3 \rrbracket$$

Encoding Polyadic π -calculus

$$\llbracket a(x_1, x_2).P_1 \rrbracket \mid \llbracket a(x_3, x_4).P_2 \rrbracket \mid \llbracket \bar{a}\langle c_1, c_2 \rangle.P_3 \rrbracket = \\ a(x_1).a(x_2).\llbracket P_1 \rrbracket \mid a(x_3).a(x_4).\llbracket P_2 \rrbracket \mid \bar{a}\langle c_1 \rangle.\bar{a}\langle c_2 \rangle.\llbracket P_3 \rrbracket = R$$

- This reduction is fine:

$$R \longrightarrow \llbracket P \rrbracket \{c_1/x_1, c_2/x_2\} \mid a(x_3, x_4).\llbracket P_2 \rrbracket \mid \llbracket P_3 \rrbracket$$

- But this is a mess:

$$R \longrightarrow a(x_2).\llbracket P_1 \rrbracket \{c_1/x_1\} \mid a(x_4).\llbracket P_2 \rrbracket \{c_2/x_3\} \mid \llbracket P_3 \rrbracket$$



Lets try again

Any Ideas?

Another approach

- Use new binding
- We need private channel for each tuple

$$\llbracket u(x_1, \dots, x_n).P \rrbracket = u(\mathbf{z}).\mathbf{z}(x_1)\dots\mathbf{z}(x_n).\llbracket P \rrbracket$$

$$\llbracket \bar{u}\langle v_1, \dots, v_n \rangle.P \rrbracket = (\nu \mathbf{c})\bar{u}\langle \mathbf{c} \rangle.\bar{\mathbf{c}}\langle v_1 \rangle\dots\bar{\mathbf{c}}\langle v_n \rangle.\llbracket P \rrbracket$$

- We still haven't finished? We need a condition ...

Let's put it all together

	Monadic	Polyadic
Asynchronous	$\bar{u}\langle v \rangle$ $u(x).P$	$\bar{u}\langle v_1, \dots v_n \rangle$ $u(x_1, \dots x_n).P_1$
Synchronous	$\bar{u}\langle v \rangle.P$ $u(x).P$	$\bar{u}\langle v_1, \dots v_n \rangle.P_1$ $u(x_1, \dots x_n).P_1$

Adding more constructs ... Choice

In the asynchronous π -calculus there is no built-in choice operator $+$. Yet, we can represent *internal nondeterminism*.

$$P \oplus Q \stackrel{\text{df}}{=} (\nu a)(\bar{a} \mid a.P \mid a.Q) \quad \text{where } a \notin \text{fn}(P \mid Q)$$

There are two possible reductions:

- either $P \oplus Q \longrightarrow P \mid (\nu a)a.Q$
- or $P \oplus Q \longrightarrow (\nu a)a.P \mid Q$

Intuitively, since $(\nu a)a.Q$ and $(\nu a)a.P$ cannot reduce, the processes above are equivalent respectively to P and to Q .

Branching and Selection

- Structured external choice in the polyadic synchronous π -calculus:

$$P ::= \dots \mid u \triangleright \{l_1 : P_1 \parallel \dots \parallel l_n : P_n\} \mid u \triangleleft l.P$$

- We have labels (ranged over $l, l', \dots$)
- The branching waits for the selector to select a label
- The reduction is:

$$a \triangleright \{l_1 : P_1 \parallel \dots \parallel l_n : P_n\} \mid a \triangleleft l_k.P \longrightarrow P_k \mid P \quad (1 \leq k \leq n)$$

Is there an encoding into the polyadic synchronous π -calculus

Branching and selection



The encoding of branching and selection into the polyadic synchronous π -calculus is defined as follows.

- $\llbracket 0 \rrbracket = 0$, $\llbracket P \mid Q \rrbracket = \llbracket P \rrbracket \mid \llbracket Q \rrbracket$, $\llbracket (\nu a)P \rrbracket = (\nu a)\llbracket P \rrbracket$, $\llbracket !P \rrbracket = !\llbracket P \rrbracket$,
- $\llbracket \bar{u}\langle \tilde{v} \rangle \rrbracket = \bar{u}\langle \tilde{v} \rangle$, $\llbracket u(\tilde{x}).P \rrbracket = u(\tilde{x}).\llbracket P \rrbracket$, and

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$$\llbracket u \triangleright \{l_1 : P_1 \parallel l_2 : P_2\} \rrbracket = u(x).(\nu c_1, c_2)(\bar{x}\langle c_1, c_2 \rangle \mid c_1.\llbracket P_1 \rrbracket \mid c_2.\llbracket P_2 \rrbracket)$$

$$\llbracket u \triangleleft l_1.P \rrbracket = (\nu c)(\bar{u}\langle c \rangle \mid c(z_1, z_2).\bar{z}_1.\llbracket P \rrbracket)$$

$$\llbracket u \triangleleft l_2.P \rrbracket = (\nu c)(\bar{u}\langle c \rangle \mid c(z_1, z_2).\bar{z}_2.\llbracket P \rrbracket)$$

- We still haven't finished? We need a condition ...

Recursion

- We have
 - recursive definition $A(\tilde{x}) \stackrel{\text{df}}{=} Q$
 - a process P which uses this definition, by calling $A\langle\tilde{v}\rangle$
- How to encode that behaviour in the asynchronous π -calculus ?
- Theorem to the rescue:
 - Theorem: Any process involving recursive definitions is representable using replication, and conversely replication is redundant in the presence of recursion.
 - Tricky: we also need restriction

Recursion vs Replication

Using replication and restriction we can encode recursive definitions. Suppose we have the recursive definition $A(\tilde{x}) \stackrel{\text{df}}{=} Q$ and a process P which uses this definition, by calling $A\langle\tilde{v}\rangle$. We can encode this behaviour in the asynchronous π -calculus as follows:

1. choose a fresh channel name a not occurring in P or Q ;
2. let P_a and Q_a be P and Q , where each recursive call of the form $A\langle\tilde{v}\rangle$ is replaced by an output process $\bar{a}\langle\tilde{v}\rangle$;
3. replace P by $(\nu a)(P_a \mid !a(\tilde{x}).Q_a)$

For example, consider the recursive definition and the reduction

$$\begin{aligned} \text{BufferNext}(x) &\stackrel{\text{df}}{=} x(y).(\bar{x}\langle y \rangle \mid \text{BufferNext}\langle y \rangle) \\ \bar{b}\langle c \rangle \mid \text{BufferNext}\langle b \rangle &\longrightarrow \bar{b}\langle c \rangle \mid \text{BufferNext}\langle c \rangle \end{aligned}$$

with their non-recursive version

$$\begin{aligned} \text{BufferNext}_a &\stackrel{\text{df}}{=} x(y).(\bar{x}\langle y \rangle \mid \bar{a}\langle y \rangle) \\ (\nu a)(\bar{b}\langle c \rangle \mid \bar{a}\langle b \rangle \mid !a(x).\text{BufferNext}_a) &\xrightarrow{*} (\nu a)(\bar{b}\langle c \rangle \mid \bar{a}\langle c \rangle \mid !a(x).\text{BufferNext}_a) \end{aligned}$$