

Modular Abstractions of Reactive Nodes using Disjunctive Invariants

David MONNIAUX and Martin BODIN

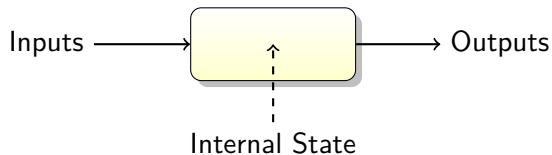
December 5, 2011

1/18



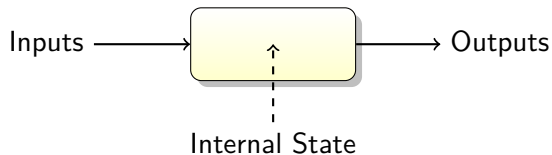
- 1 Goal
 - Reactive Nodes
 - Approximating a reactive node
- 2 Seeking an Invariant
 - Predicate Abstraction
 - Algorithm
 - Building the transitions
- 3 Improvements

- A reactive node (LUSTRE, SCADE, SAO, SIMULINK) :



- It is an automaton.
- The internal state is usually given by some variables's values.
⇒ Exponential number of state.

- A reactive node (LUSTRE, SCADE, SAO, SIMULINK) :

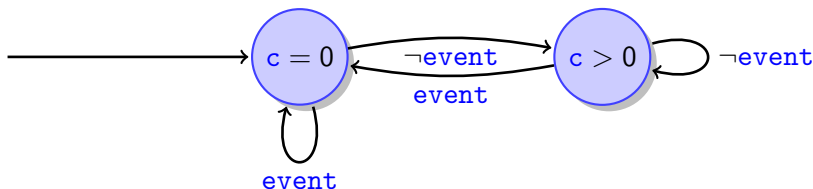


- It is an automaton.
- The internal state is usually given by some variables's values.
⇒ Exponential number of state.

```

1 node timer (event : bool) returns (c : int);
2 let c = 0 ->
3     (if event then 0
4     else pre c + 1) ;
5 tel.

```



Goal:

- Abstract a reactive node \longrightarrow an automaton.
- A bounded number of states.

Abstraction:

- It over-approximates the behavior of the node.
- We loose determinism.

Node Hierarchy:

- Modular analysis.
- Compositional analysis.

Building an automaton

Process steps:

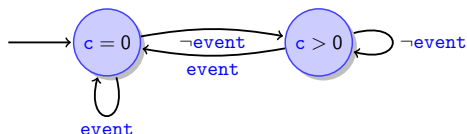
- 1 Decompose an over-approximation of the reachable states as a union of n abstract states.
- 2 Compute which transitions are possible between those abstract states.

What we need

- **Reachable states** \longleftarrow Solvers.
SAT-solvers and SMT-solvers (*satisfiability modulo theory*).
 \mathcal{NP} -complete, but some tools (like YICES) try to do it efficiently.
- **Entry point** \longrightarrow A finite set of predicates π_1, \dots, π_m .
They will be used to build the abstract states.
 \rightarrow We more or less know what the invariant shall look like.

What we need

- **Reachable states** \longleftarrow Solvers.
SAT-solvers and SMT-solvers (*satisfiability modulo theory*).
 \mathcal{NP} -complete, but some tools (like YICES) try to do it efficiently.
- **Entry point** \longrightarrow A finite set of predicates π_1, \dots, π_m .
They will be used to build the abstract states.
 \rightarrow We more or less know what the invariant shall look like.



$$n = 2$$

$$\{\pi_1, \pi_2, \pi_3\} = \{c = 0, c < 0, c > 0\}$$

$$C_1 \equiv c = 0$$

$$C_2 \equiv c > 0$$

- An abstract state is given by a conjunction C_i of predicates.

$$C_i = \bigwedge_{j=1}^m (b_{i,j} \Rightarrow \pi_j)$$

- We seek an invariant of the form $\mathcal{T} = \bigvee_{i=1}^n C_i$. (n is given.)
 $\implies 2^{nm}$ possibilities for the Booleans $b_{i,j}$.

Some formulae used by the algorithm:

- The constraints $\forall \sigma, F$ over the variables (given).
Typically, F states (among other things) that \mathcal{T} is an invariant.

The idea is to “discover” step by step what constraints F yields for the state partition.

- A sequence of formulae H_k (computed) that represents the discovered constraints over the Booleans $b_{i,j}$.
Initially, $H_1 = \text{true}$.

A disjunctive inductive invariant, expressed by B .

$H := \text{true}$

Loop:

match $SAT(H)$ **with**

| $\text{UnSat} \rightarrow$ **return** No_Solution

| $\text{Sat}(B_{i,j}) \rightarrow$

match $SMT(\neg F[B/b])$ **with**

| $\text{UnSat} \rightarrow$ **return** $(\text{Solution } B)$

| $\text{Sat}(\Sigma) \rightarrow H := H \wedge F[\Sigma/\sigma]$

A disjunctive inductive invariant, expressed by B .

No set of states follows the constraints H .

$H := \text{true}$

Loop:

match $SAT(H)$ **with**

| UnSat \rightarrow **return** No_SOLUTION

| Sat($B_{i,j}$) \rightarrow

match $SMT(\neg F[B/b])$ **with**

| UnSat \rightarrow **return** (SOLUTION B)

| Sat(Σ) $\rightarrow H := H \wedge F[\Sigma/\sigma]$

A disjunctive inductive invariant, expressed by B .

$H := \text{true}$

Loop:

match $SAT(H)$ **with**

| UnSat \rightarrow **return** No_SOLUTION

| Sat($B_{i,j}$) \rightarrow

match $SMT(\neg F[B/b])$ **with**

| UnSat \rightarrow **return** (SOLUTION B)

| Sat(Σ) $\rightarrow H := H \wedge F[\Sigma/\sigma]$

No set of states follows the constraints H .

F is thus always true with this state partitioning.

A disjunctive inductive invariant, expressed by B .

$H := \text{true}$

Loop:

match $SAT(H)$ **with**

| UnSat \rightarrow **return** No_SOLUTION

| Sat($B_{i,j}$) \rightarrow

match $SMT(\neg F[B/b])$ **with**

| UnSat \rightarrow **return** (SOLUTION B)

| Sat(Σ) $\rightarrow H := H \wedge F[\Sigma/\sigma]$

No set of states follows the constraints H .

F is thus always true with this state partitioning.

Add the new discovered constraint and retry.

- This loop computes an invariant \rightarrow true is an invariant!
- We need a (*locally*) minimal invariant.
- After getting an invariant $B^{(0)}$, restart the algorithm with a new constraint: the new invariant $B^{(1)} \not\subseteq B^{(0)}$.

- This loop computes an invariant \rightarrow true is an invariant!
- We need a (*locally*) minimal invariant.

- After getting an invariant $B^{(0)}$, restart the algorithm with a new constraint: the new invariant $B^{(1)} \not\subseteq B^{(0)}$.

```

1  bool b;
2  int i = 0, a ; /* precondition a > 0 */
3  while ( i < a ) {
4      b = random ( ) ;
5      if (b)
6          i = i + 1;
7  }

```

$$\begin{aligned}
 F \triangleq & ((i = 0 \wedge a \geq 1) \implies \mathcal{T}(b, i, a)) \\
 & \wedge ((b' \wedge i' = i + 1) \vee (\neg b' \wedge i' = i)) \\
 & \wedge (\mathcal{T}(b, i, a) \implies (\mathcal{T}(b', i', a') \vee i' \geq a'))
 \end{aligned}$$

$$\begin{aligned}
 F \triangleq & ((i = 0 \wedge a \geq 1) \implies \mathcal{T}(b, i, a)) \\
 & \wedge ((b' \wedge i' = i + 1) \vee (\neg b' \wedge i' = i)) \\
 & \wedge (\mathcal{T}(b, i, a) \implies (\mathcal{T}(b', i', a') \vee i' \geq a'))
 \end{aligned}$$

We set $n = 2$ and the predicates

$$\{\pi_1, \dots, \pi_8\} \triangleq \{i = 0, i < 0, i > 0, i = a, i < a, i > a, b, \neg b\}.$$

H	$SAT(H)$: invariant candidate	$SMT(\neg F[B/b])$
true	$(i = 0 \wedge i = a \wedge b) \vee (i = 0 \wedge i = a \wedge \neg b)$	$i = 0, a = 1, b = \perp$
$F(0, 1, \perp)$	$(i = 0 \wedge i = a \wedge b) \vee (i = 0 \wedge i < a \wedge b)$	$i = 0, a = -1, b = \perp$
	\vdots	
H_6	$(i = 0 \wedge i < a) \vee i > 0$	<i>accepted!</i>

Thus $I_1 = (i = 0 \wedge i < a) \vee i > 0$ is an invariant, but we want a minimal one. We thus restart the algorithm.

$$\begin{aligned}
 F \triangleq & ((i = 0 \wedge a \geq 1) \implies \mathcal{T}(b, i, a)) \\
 & \wedge ((b' \wedge i' = i + 1) \vee (\neg b' \wedge i' = i)) \\
 & \wedge (\mathcal{T}(b, i, a) \implies (\mathcal{T}(b', i', a') \vee i' \geq a'))
 \end{aligned}$$

We set $n = 2$ and the predicates

$$\{\pi_1, \dots, \pi_8\} \triangleq \{i = 0, i < 0, i > 0, i = a, i < a, i > a, b, \neg b\}.$$

H	$SAT(H)$: invariant candidate	$SMT(\neg F[B/b])$
true	$(i = 0 \wedge i = a \wedge b) \vee (i = 0 \wedge i = a \wedge \neg b)$	$i = 0, a = 1, b = \perp$
$F(0, 1, \perp)$	$(i = 0 \wedge i = a \wedge b) \vee (i = 0 \wedge i < a \wedge b)$	$i = 0, a = -1, b = \perp$
	\vdots	
H_6	$(i = 0 \wedge i < a) \vee i > 0$	<i>accepted!</i>

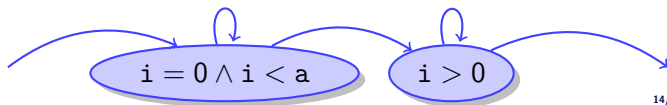
Thus $I_1 = (i = 0 \wedge i < a) \vee i > 0$ is an invariant, but we want a minimal one. We thus restart the algorithm.

- When adding the new condition $I_2 \not\subseteq I_1$, we get within two steps that no new solution exists.
- Thus $I_1 = (i = 0 \wedge i < a) \vee i > 0$ was already a minimal one.

```

1  bool b;
2  int i = 0, a ; /* precondition a > 0 */
3  while ( i < a ) {
4      b = random ( ) ;
5      if (b)
6          i = i + 1;
7  }

```



A state: a conjunction C_i of predicates.



There exists a transition from the state i to the state j iff there exists variables following C_i whose next variables follows C_j .

Using *quantifier elimination* on $\exists \sigma, \sigma', C_i(\sigma) \wedge C_j(\sigma') \wedge T(\sigma, \sigma')$, we can precise the transition by a condition on inputs.

→ MJOLLNIR tool.

Idea: modifying $F \longrightarrow$ add any constraint we want.

- \rightarrow implement different languages (adding precondition, postconditions, ...).
- \rightarrow Used to decrease the number of time SMT-solvers are called (*but this increases their computation time*).

- **Removal of Permutations**

We add a canonical ordering for the disjunction $C_1 \wedge \dots \wedge C_n$.

- **Satisfiability of Conjunctions**

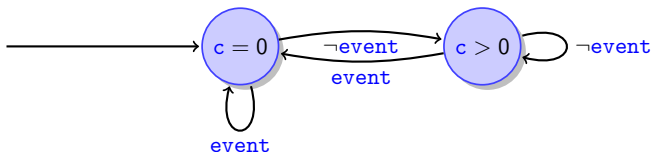
We add the condition that each C_i is satisfiable. (require a SMT-solver.)

- **Removal of Subsumed Disjuncts**

We require that no C_i is subsumed by an other C_j .

Reactive node + Set of predicates \longrightarrow invariant

- \longrightarrow inductive disjunctive invariant \Rightarrow decomposition in states
- \longrightarrow labelling of transitions by quantifier elimination
- \longrightarrow automaton:



- \longrightarrow easy to change and optimize.