

Concurrency at the Abstract Level

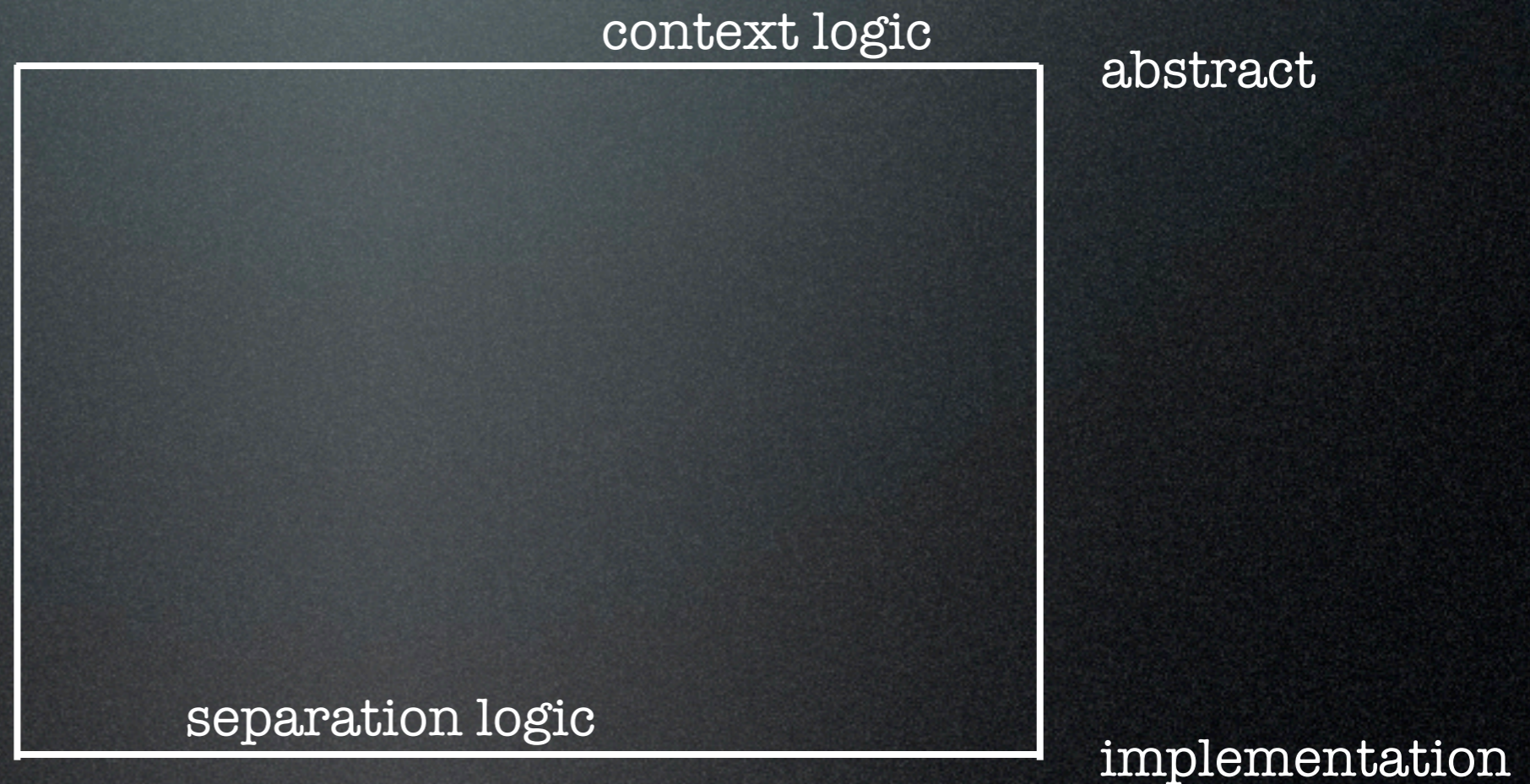


Mark Wheelhouse
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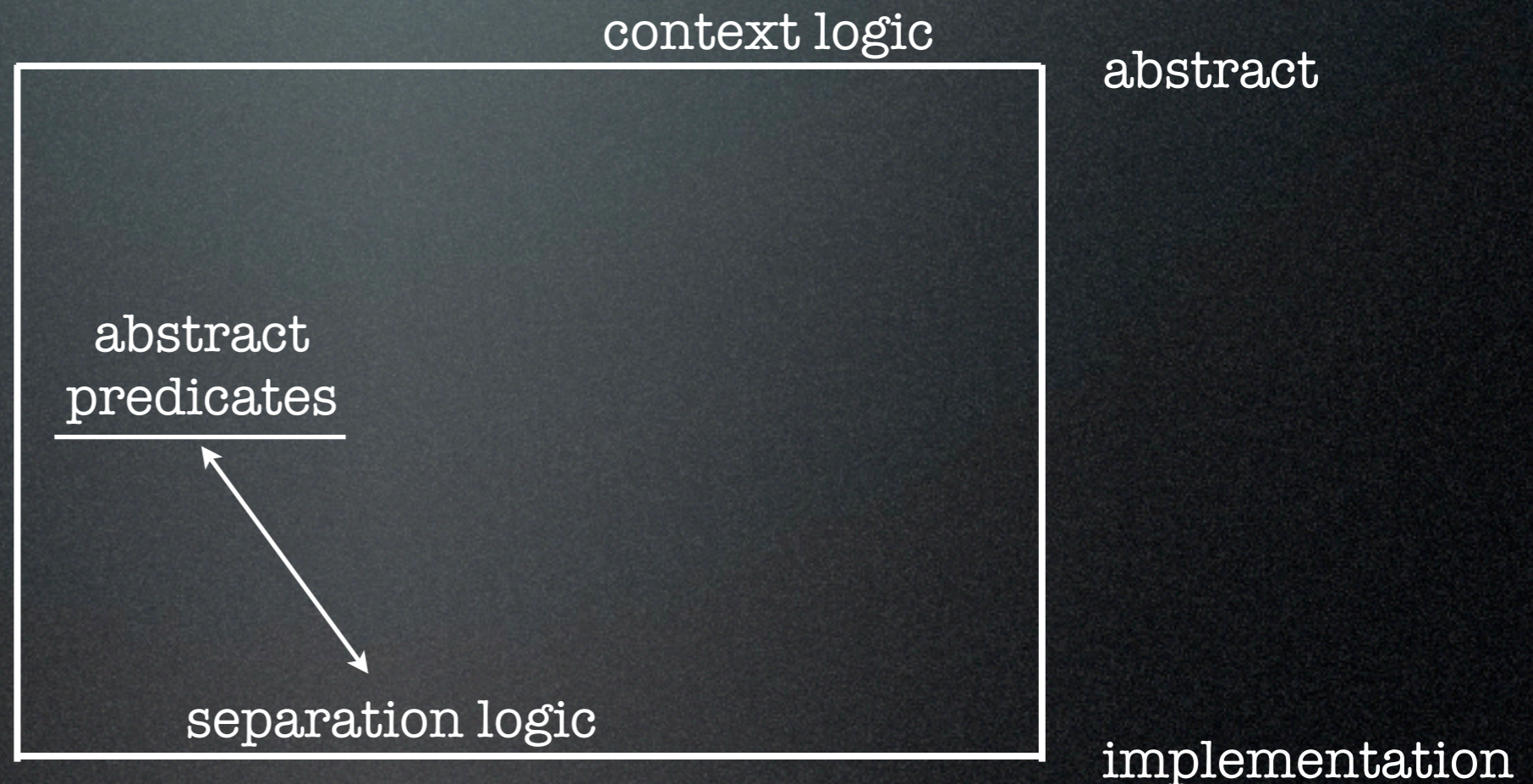
Imperial College London

Cambridge Concurrency Workshop - July 2010

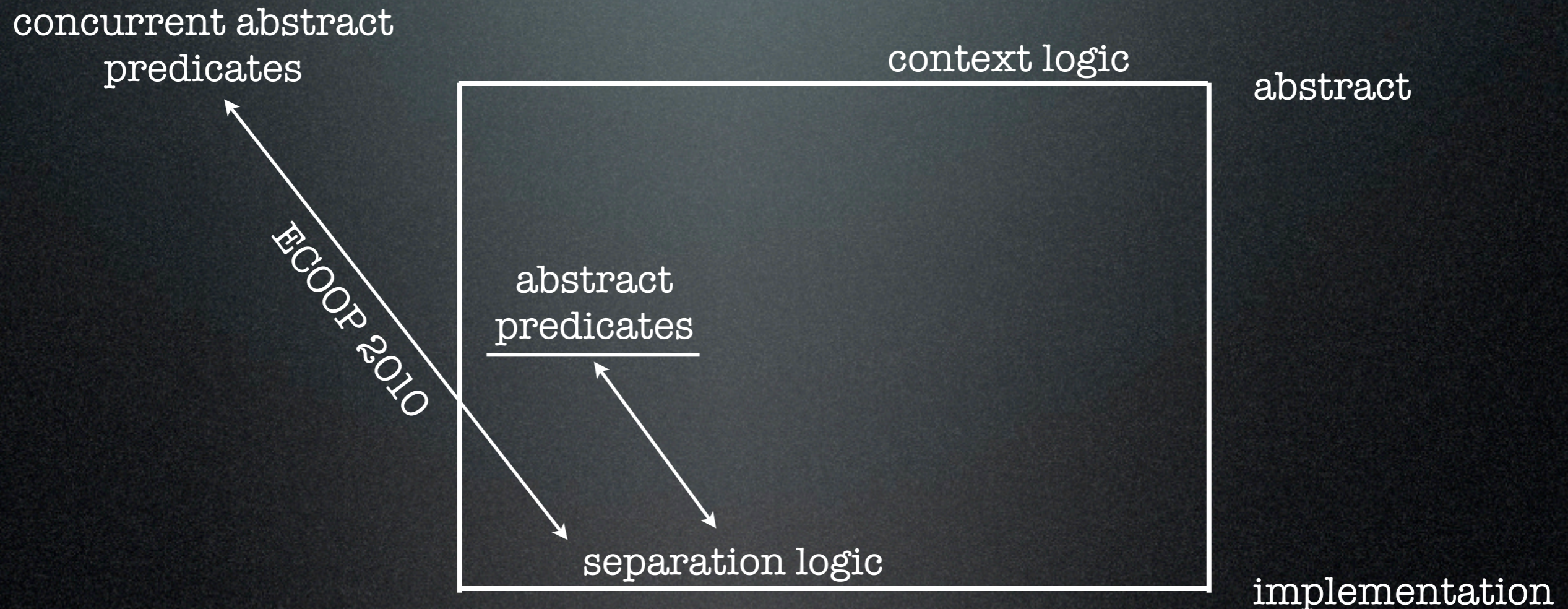
Abstraction Levels



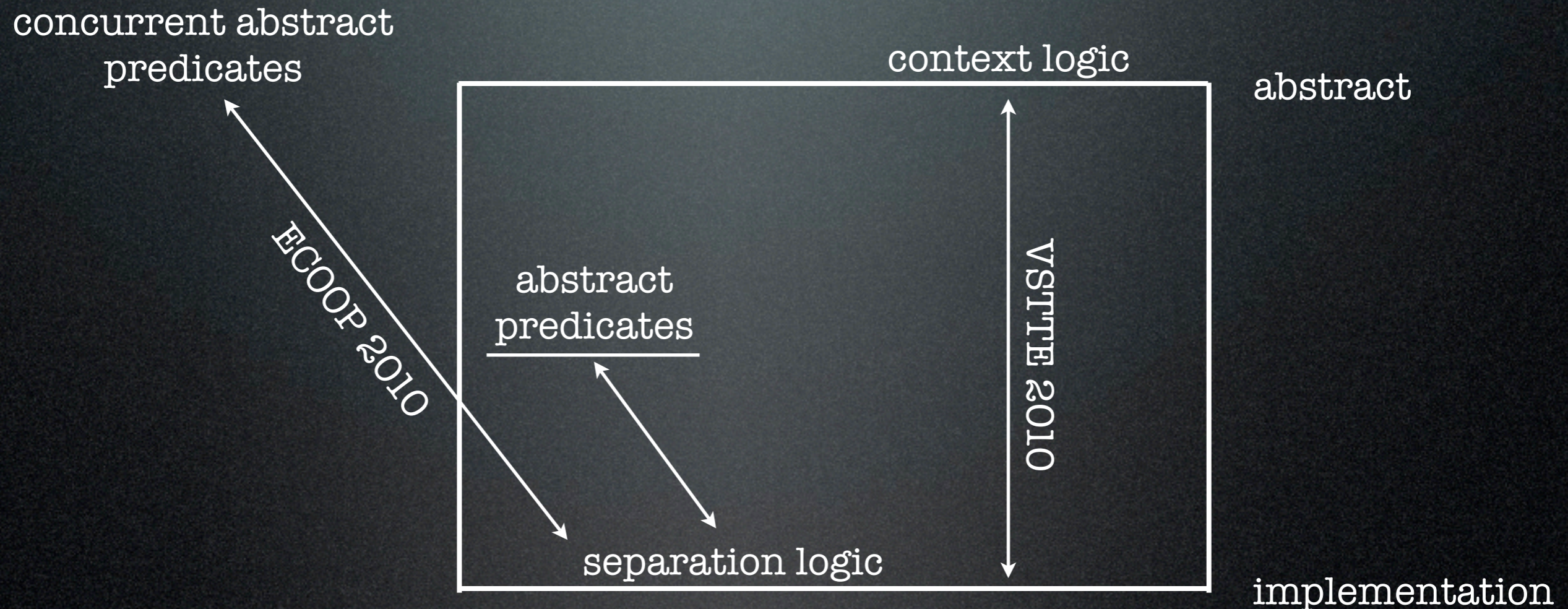
Abstraction Levels



Abstraction Levels



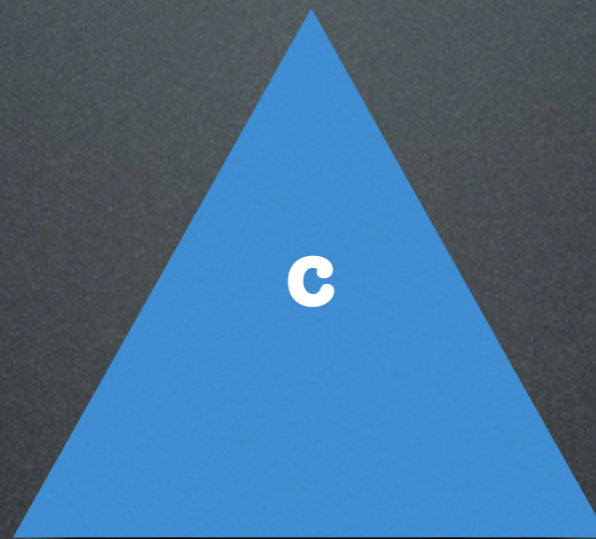
Abstraction Levels



Abstract Local Reasoning - Contexts

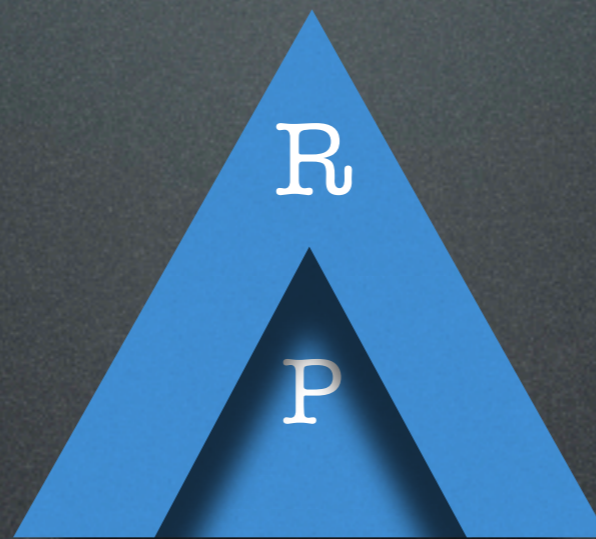
app not commutative

Abstract Local Reasoning - Contexts



app not commutative

Abstract Local Reasoning - Contexts



app not commutative

Abstract Local Reasoning - Contexts



separating application

app not commutative

Abstract Local Reasoning - Contexts



separating application

app not commutative

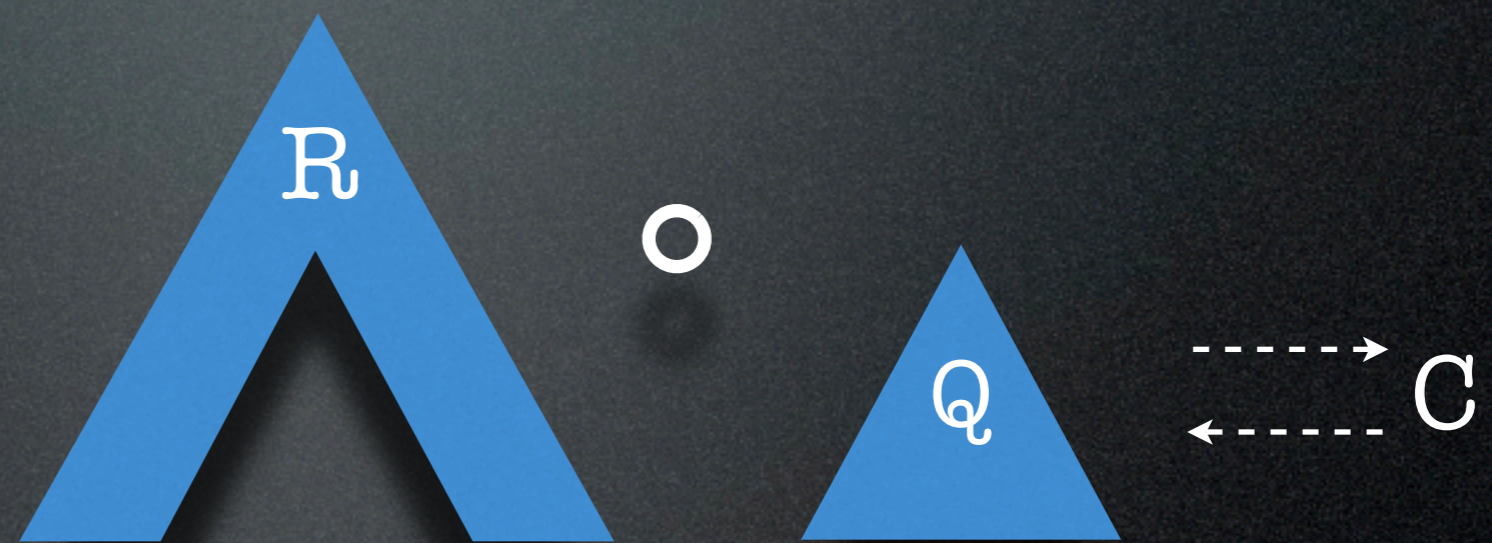
Abstract Local Reasoning - Contexts



separating application

app not commutative

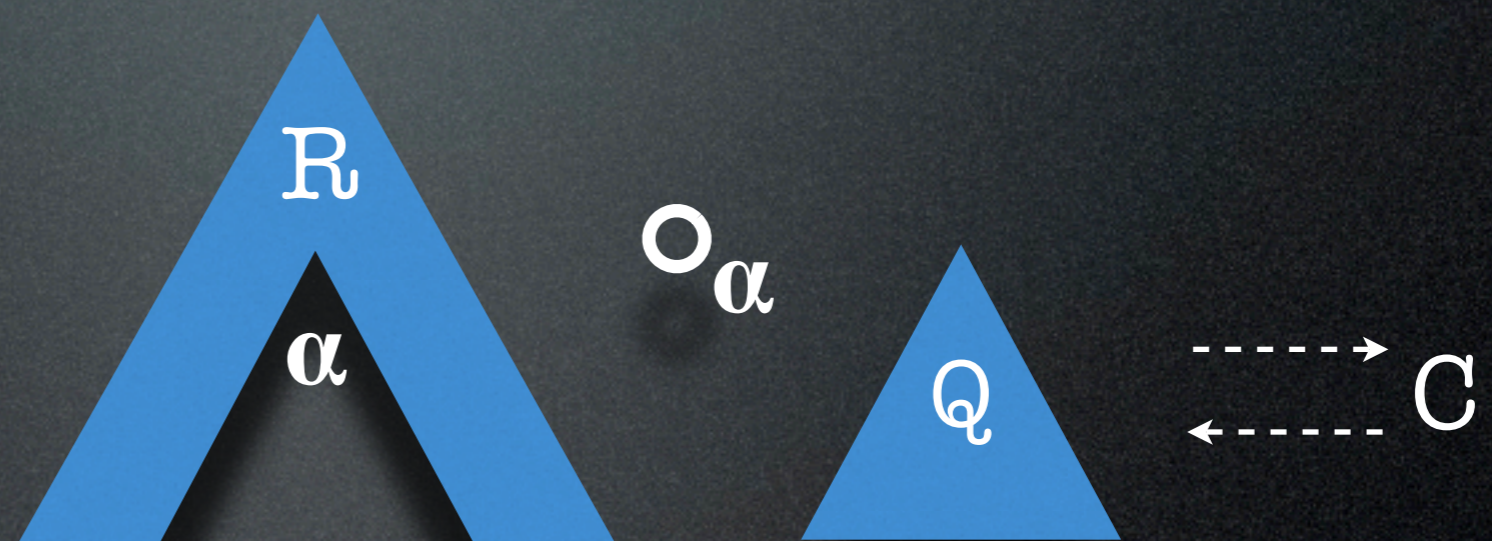
Abstract Local Reasoning - Contexts



separating application

app not commutative

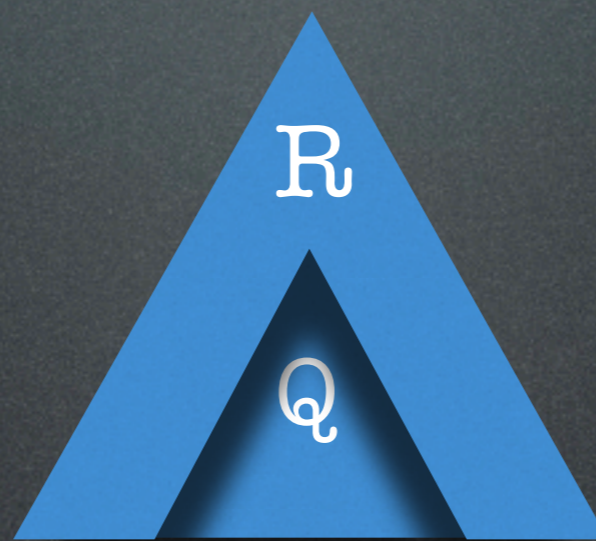
Abstract Local Reasoning - Contexts



separating application

app not commutative

Abstract Local Reasoning - Contexts

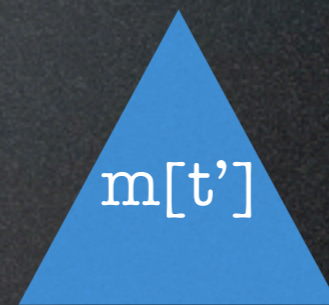


separating application

app not commutative

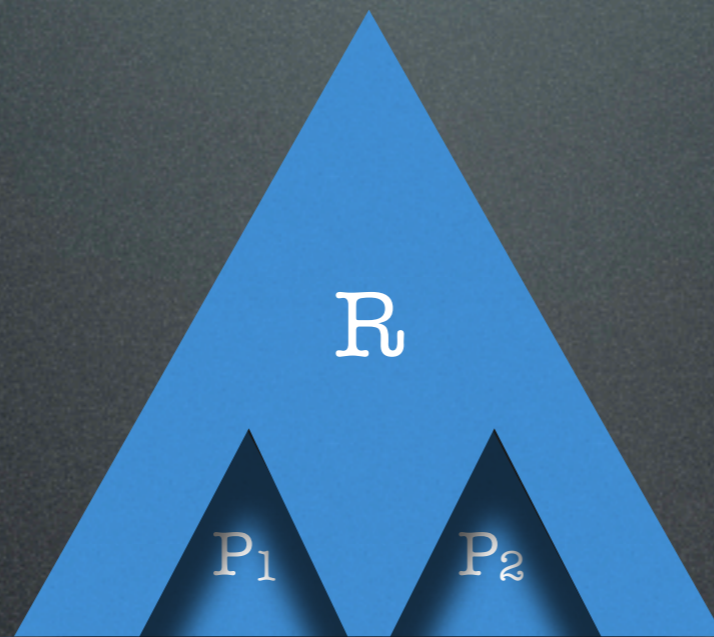
Reasoning About Concurrency

`deleteTree(n)` || `deleteTree(m)`

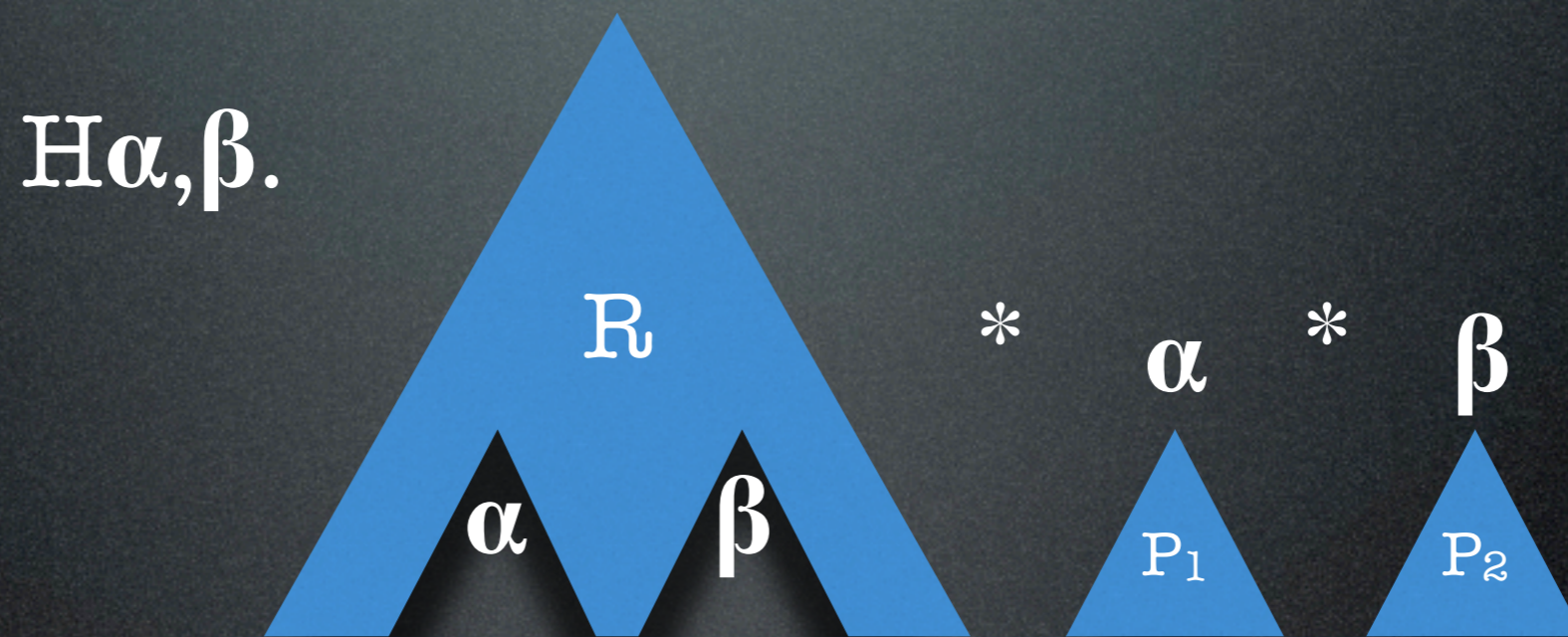


DOM IDs `n` & `m`

Abstract Local Reasoning - Segments



Abstract Local Reasoning - Segments



separating conjunction
abstract heap addresses
abstract wiring

Abstract Local Reasoning - Segments



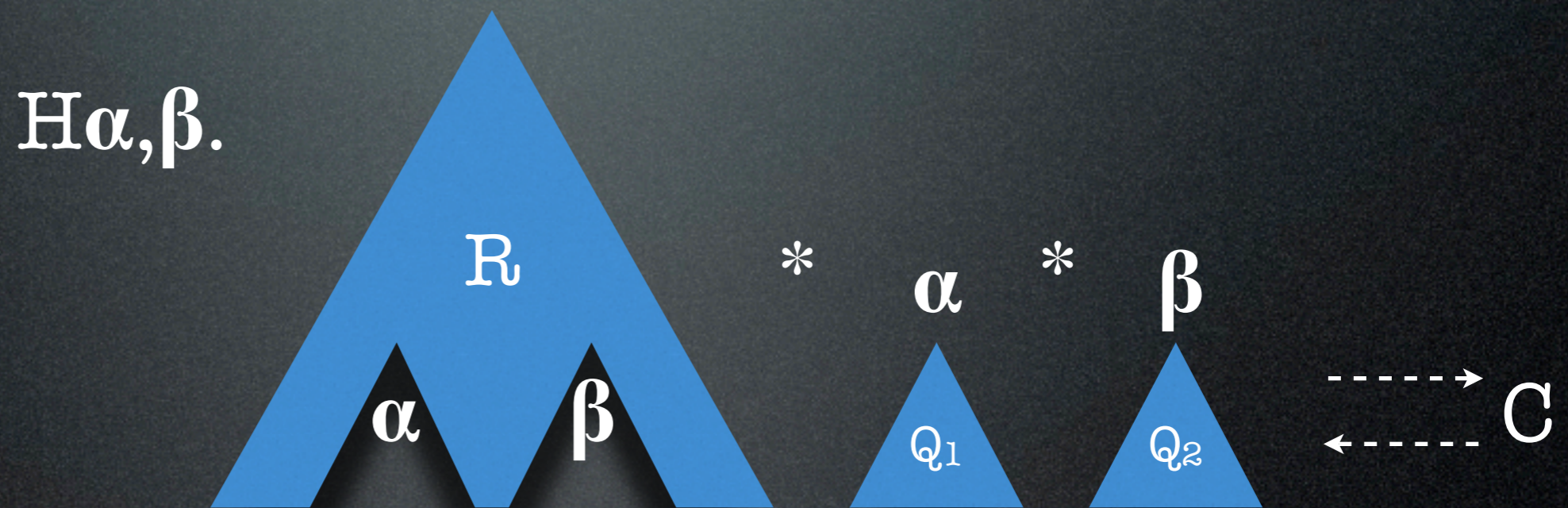
separating conjunction
abstract heap addresses
abstract wiring

Abstract Local Reasoning - Segments



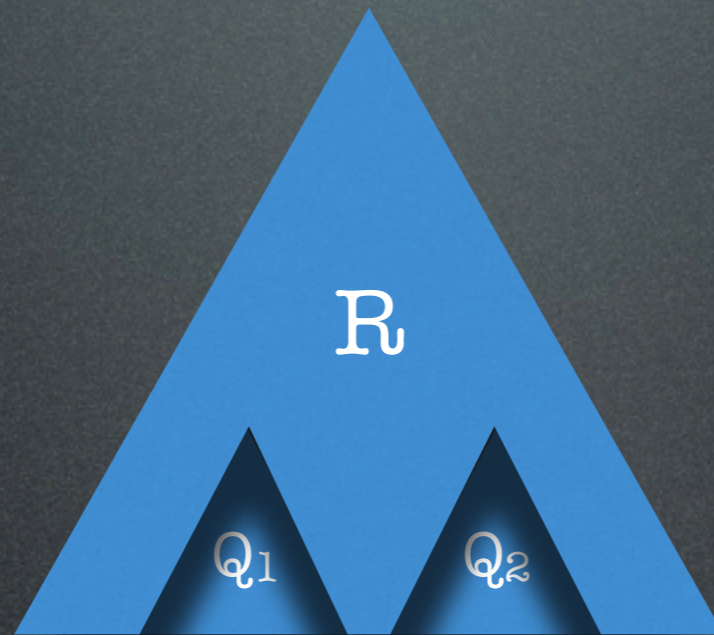
separating conjunction
abstract heap addresses
abstract wiring

Abstract Local Reasoning - Segments



separating conjunction
abstract heap addresses
abstract wiring

Abstract Local Reasoning - Segments



separating conjunction
abstract heap addresses
abstract wiring

Concurrent Update Language

skip

C ; C

x := Exp

if B then C else C

C_{Basic}

while B do C

C || C

res r in C

with r when B do C

Tree Segments

tree context $\mathbf{c} ::= \mathbf{0} \mid \mathbf{x} \mid \mathbf{n}[\mathbf{c}] \mid \mathbf{c} \otimes \mathbf{c}$

tree segment $\mathbf{s} ::= \emptyset \mid \mathbf{x} \leftarrow \mathbf{c} \mid \mathbf{s} + \mathbf{s} \mid (\mathbf{x})(\mathbf{s})$

Unique node identifiers \mathbf{n}

Unique free hole addresses \mathbf{x}

Unique free hole labels \mathbf{x}

+ associative & commutative with unit \emptyset

\otimes associative with unit \emptyset

restriction familar
from pi calculus

Tree Segments

tree context $\mathbf{c} ::= \mathbf{0} \mid \mathbf{x} \mid \mathbf{n}[\mathbf{c}] \mid \mathbf{c} \otimes \mathbf{c}$

tree segment $\mathbf{s} ::= \emptyset \mid \mathbf{x} \leftarrow \mathbf{c} \mid \mathbf{s} + \mathbf{s} \mid (\mathbf{x})(\mathbf{s})$

Unique node identifiers \mathbf{n}

Unique free hole addresses \mathbf{x}

Unique free hole labels \mathbf{x}

+ associative & commutative with unit \emptyset

\otimes associative with unit \emptyset

& no cycles!

restriction familar
from pi calculus

Tree Segment Formulae

emp no segments.

$\alpha \leftarrow T$ tree segment satisfying T
at address α .

$P * Q$ separating conjunction.
disjoint segments P and Q .

$H\alpha.P$ hiding quantifier
 α restricted in P

standard pi-calc hiding
restriction + freshness
(existence not enough)

Sequential Abstract Local Reasoning

Fault Avoiding

Partial Correctness: $\{ P \} C \{ Q \}$

Small Axioms

$\{ \alpha \leftarrow \mathbf{n}[t] \}$
`deleteTree(n)`

$\{ \alpha \leftarrow \mathbf{0} \}$

$\{ \alpha \leftarrow \mathbf{n}[\gamma] * \beta \leftarrow \mathbf{m}[t] \}$
`append(n, m)`

$\{ \alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{m}[t]] * \beta \leftarrow \mathbf{0} \}$

Frame Rules

$$\begin{array}{c} \text{Separation} \\ \text{Frame} \end{array} \quad \frac{\{P\} \ C \ \{Q\}}{\{R * P\} \ C \ \{R * Q\}}$$

$$\begin{array}{c} \text{Hiding} \\ \text{Introduction} \end{array} \quad \frac{\{P\} \ C \ \{Q\}}{\{H\alpha.P\} \ C \ \{H\alpha.Q\}}$$

(Derived)

Local Reasoning



Local Reasoning

$H_{\alpha, \beta}$.



Local Reasoning

$H_{\alpha, \beta}$



Local Reasoning

$H_{\alpha, \beta}$



Local Reasoning

$H_{\alpha, \beta}$



Local Reasoning

$H_{\alpha, \beta}$

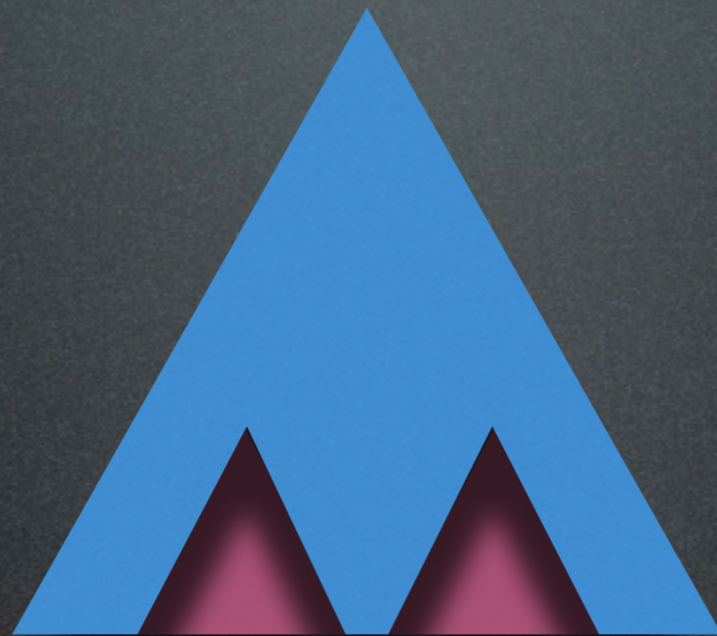


Local Reasoning

$H_{\alpha, \beta}$.



Local Reasoning



Concurrent Abstract Local Reasoning

Disjoint Concurrency

$$\Gamma \vdash \{ P_1 \} C_1 \{ Q_1 \}$$
$$\Gamma \vdash \{ P_2 \} C_2 \{ Q_2 \}$$

$$\Gamma \vdash \{ P_1 * P_2 \} C_1 || C_2 \{ Q_1 * Q_2 \}$$

PAR

Disjoint Concurrency Example

deleteTree(**n**)

deleteTree(**m**)

Disjoint Concurrency Example

$\{ \alpha \leftarrow \mathbf{n}[\mathbf{t}] * \beta \leftarrow \mathbf{m}[\mathbf{t}'] \}$

deleteTree(**n**)

deleteTree(**m**)

Disjoint Concurrency Example

$\{ \alpha \leftarrow \mathbf{n}[\mathbf{t}] * \beta \leftarrow \mathbf{m}[\mathbf{t}'] \}$

$\{ \alpha \leftarrow \mathbf{n}[\mathbf{t}] \}$

deleteTree(**n**)

$\{ \beta \leftarrow \mathbf{m}[\mathbf{t}'] \}$

deleteTree(**m**)

Disjoint Concurrency Example

$$\{ \alpha \leftarrow \mathbf{n}[t] * \beta \leftarrow \mathbf{m}[t'] \}$$
$$\{ \alpha \leftarrow \mathbf{n}[t] \}$$
$$\text{deleteTree}(\mathbf{n})$$
$$\{ \alpha \leftarrow \mathbf{0} \}$$
$$\{ \beta \leftarrow \mathbf{m}[t'] \}$$
$$\text{deleteTree}(\mathbf{m})$$
$$\{ \beta \leftarrow \mathbf{0} \}$$

Disjoint Concurrency Example

$\{ \alpha \leftarrow \mathbf{n}[t] * \beta \leftarrow \mathbf{m}[t'] \}$

$\{ \alpha \leftarrow \mathbf{n}[t] \}$		$\{ \beta \leftarrow \mathbf{m}[t'] \}$
deleteTree(\mathbf{n})		deleteTree(\mathbf{m})
$\{ \alpha \leftarrow \mathbf{0} \}$		$\{ \beta \leftarrow \mathbf{0} \}$
$\{ \alpha \leftarrow \mathbf{0} * \beta \leftarrow \mathbf{0} \}$		

Concurrent Abstract Local Reasoning

Sharing Program State

$$\frac{\Gamma(r \rightarrow \Pi, \text{RI}) \vdash \{ P \} C \{ Q \}}{\Gamma \vdash \{ \text{HP}.\text{RI} * P \} \text{res } r \text{ in } C \{ \text{HP}.\text{RI} * Q \}} \text{RES}$$

$$\frac{\Gamma \vdash \{ \text{HP}.\text{RI} * P \} \wedge B \} C \{ \text{HP}.\text{RI} * Q \}}{\Gamma(r \rightarrow \Pi, \text{RI}) \vdash \{ P \} \text{with } r \text{ when } B \text{ do } C \{ Q \}} \text{CCR}$$

Shared State Example

```
res r in  
with r do <  
    a := getLeft(n)  
>  
deleteTree(a) | | with r do <  
    b := getRight(n)  
>  
deleteTree(b)
```

Shared State Example

$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$

res r in

with r do <
 a := getLeft(**n**)

>

deleteTree(a)

with r do <
 b := getRight(**n**)

>

deleteTree(b)

$\{ \alpha \leftarrow \mathbf{n}[\gamma] \}$

Shared State Example

$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$

res r in \langle

\vdots

\parallel

\vdots

\rangle

Shared State Example

$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$

$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$

res r in <

⋮

||

⋮

>

Shared State Example

$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$

$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$

res r in \langle

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$
 $\Pi = \beta, \delta$

\vdots

\vdots

\rangle

Shared State Example

$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$

$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$

res r in \langle
 $\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$

⋮

||

⋮

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$
 $\Pi = \beta, \delta$

\rangle

Shared State Example

$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$

$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$

res r in <

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

\vdots

$\{ \beta \leftarrow \mathbf{0} \}$

$\{ \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$

\vdots

$\{ \delta \leftarrow \mathbf{0} \}$

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$
 $\Pi = \beta, \delta$

>

Shared State Example

```

{  $\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}']$  }
{  $\exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}'])$  }
res r in <
{  $\beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']$  }
  {  $\beta \leftarrow \mathbf{p}[\mathbf{t}]$  } || {  $\delta \leftarrow \mathbf{q}[\mathbf{t}']$  }
    :
    :
  {  $\beta \leftarrow \mathbf{0}$  } || {  $\delta \leftarrow \mathbf{0}$  }
{  $\beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0}$  }
>

```

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$
 $\Pi = \beta, \delta$

Shared State Example

$$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$$
$$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$$

res r in \langle

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$	$\{ \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$
\vdots	\vdots
$\{ \beta \leftarrow \mathbf{0} \}$	$\{ \delta \leftarrow \mathbf{0} \}$

$\{ \beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0} \}$

\rangle

$$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0}) \}$$

RI = $\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$
 $\Pi = \beta, \delta$

Shared State Example

$$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$$
$$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$$

res r in \langle

$$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$$

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$		$\{ \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$
\vdots		\vdots
$\{ \beta \leftarrow \mathbf{0} \}$		$\{ \delta \leftarrow \mathbf{0} \}$

$$\{ \beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0} \}$$

\rangle

$$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0}) \}$$
$$\{ \alpha \leftarrow \mathbf{0} \otimes \mathbf{n}[\gamma] \otimes \mathbf{0} \}$$

RI = $\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$
 $\Pi = \beta, \delta$

Shared State Example

$$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$$
$$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}']) \}$$

res r in <

$$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] * \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$$

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$		$\{ \delta \leftarrow \mathbf{q}[\mathbf{t}'] \}$
---	--	---

⋮

⋮

$\{ \beta \leftarrow \mathbf{0} \}$		$\{ \delta \leftarrow \mathbf{0} \}$
-------------------------------------	--	--------------------------------------

$$\{ \beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0} \}$$

>

$$\{ \exists \beta, \delta. (\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{0} * \delta \leftarrow \mathbf{0}) \}$$
$$\{ \alpha \leftarrow \mathbf{0} \otimes \mathbf{n}[\gamma] \otimes \mathbf{0} \}$$
$$\{ \alpha \leftarrow \mathbf{n}[\gamma] \}$$
$$\begin{aligned} \text{RI} &= \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta \\ \Pi &= \beta, \delta \end{aligned}$$

Shared State Example

```
{  $\beta \leftarrow \mathbf{p}[\mathbf{t}]$  }  
with r do <
```

```
  a := getLeft(n)
```

```
>
```

```
deleteTree(a)  
{  $\beta \leftarrow \mathbf{0}$  }
```

```
RI =  $\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$   
 $\Pi = \beta, \delta$ 
```

Shared State Example

```
{  $\beta \leftarrow \mathbf{p}[\mathbf{t}]$  }  
with r do <  
  {  $\text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}])$  }
```

```
  a := getLeft(n)
```

```
>
```

```
deleteTree(a)  
{  $\beta \leftarrow \mathbf{0}$  }
```

```
RI =  $\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$   
 $\Pi = \beta, \delta$ 
```

Shared State Example

```
{  $\beta \leftarrow \mathbf{p}[\mathbf{t}]$  }  
with r do <  
  {  $\text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}])$  }  
  {  $\text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}])$  }  
  
  a := getLeft(n)  
  
>  
  
deleteTree(a)  
{  $\beta \leftarrow \mathbf{0}$  }
```

```
RI =  $\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$   
 $\Pi = \beta, \delta$ 
```


Shared State Example

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

with r do \langle

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta) \}$

$\mathbf{a} := \text{getLeft}(\mathbf{n})$

\rangle

$\text{deleteTree}(\mathbf{a})$

$\{ \beta \leftarrow \mathbf{0} \}$

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$

$\Pi = \beta, \delta$

Shared State Example

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

with r do \langle

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta) \}$

$\mathbf{a} := \text{getLeft}(\mathbf{n})$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta \wedge (\mathbf{a}=\mathbf{p})) \}$

\rangle

$\text{deleteTree}(\mathbf{a})$

$\{ \beta \leftarrow \mathbf{0} \}$

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$

$\Pi = \beta, \delta$

Shared State Example

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

with r do \langle

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta) \}$

$\mathbf{a} := \text{getLeft}(\mathbf{n})$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta \wedge (\mathbf{a}=\mathbf{p})) \}$

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\rangle

$\text{deleteTree}(\mathbf{a})$

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$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$

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Shared State Example

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

with r do \langle

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta) \}$

$\mathbf{a} := \text{getLeft}(\mathbf{n})$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta \wedge (\mathbf{a}=\mathbf{p})) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p})) \}$

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p})) \}$

\rangle

$\text{deleteTree}(\mathbf{a})$

$\{ \beta \leftarrow \mathbf{0} \}$

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$

$\Pi = \beta, \delta$

Shared State Example

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

with r do \langle

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta) \}$

$\mathbf{a} := \text{getLeft}(\mathbf{n})$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta \wedge (\mathbf{a}=\mathbf{p})) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p})) \}$

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p})) \}$

\rangle

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p}) \}$

$\text{deleteTree}(\mathbf{a})$

$\{ \beta \leftarrow \mathbf{0} \}$

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$

$\Pi = \beta, \delta$

Shared State Example

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \}$

with r do \langle

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}]) \}$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta) \}$

$\mathbf{a} := \text{getLeft}(\mathbf{n})$

$\{ \text{H}\delta.(\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \delta \wedge (\mathbf{a}=\mathbf{p})) \}$

$\{ \text{H}\beta, \delta.(\alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta * \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p})) \}$

$\{ \text{H}\Pi.(\text{RI} * \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p})) \}$

\rangle

$\{ \beta \leftarrow \mathbf{p}[\mathbf{t}] \wedge (\mathbf{a}=\mathbf{p}) \}$

$\text{deleteTree}(\mathbf{a})$

$\{ \beta \leftarrow \mathbf{0} \}$

$\text{RI} = \alpha \leftarrow \beta \otimes \mathbf{n}[\gamma] \otimes \delta$

$\Pi = \beta, \delta$

More Shared State

```
res r in  
with r do <  
  a := getLeft(n)  
  append(n, a)  
>  
|  
with r do <  
  b := getRight(n)  
  append(n, b)  
>
```

More Shared State

$$\{ \alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] \}$$

res r in

with r do <
 a := getLeft(**n**)
 append(**n**, a)
>

with r do <
 b := getRight(**n**)
 append(**n**, b)
>

$$\left\{ \begin{array}{l} \alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{p}[\mathbf{t}] \otimes \mathbf{q}[\mathbf{t}']] \\ \quad \quad \quad \vee \\ \alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}'] \otimes \mathbf{p}[\mathbf{t}]] \end{array} \right\}$$

Resource Invariant

$$\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}']$$

∨

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{p}[\mathbf{t}]] \otimes \mathbf{q}[\mathbf{t}']$$

∨

$$\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}']]$$

∨

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{p}[\mathbf{t}] \otimes \mathbf{q}[\mathbf{t}']]$$

∨

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}']] \otimes \mathbf{p}[\mathbf{t}]$$

Adding Tokens

$$\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] * \text{t1} * \text{t2}$$

∨

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{p}[\mathbf{t}]] \otimes \mathbf{q}[\mathbf{t}'] * \text{t1} * \text{t2}$$

∨

$$\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}']] * \text{t1} * \text{t2}$$

∨

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{p}[\mathbf{t}] \otimes \mathbf{q}[\mathbf{t}']] * \text{t1} * \text{t2}$$

∨

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}']] \otimes \mathbf{p}[\mathbf{t}] * \text{t1} * \text{t2}$$

Adding Tokens



Adding Tokens

$$\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma] \otimes \mathbf{q}[\mathbf{t}'] * \text{t1} * \text{t2}$$

thread 1

$$\alpha \leftarrow \mathbf{n}[\gamma] \otimes \mathbf{p}[\mathbf{t}] \otimes \mathbf{q}[\mathbf{t}'] * \text{t1} * \text{t2}$$

t1

$$\alpha \leftarrow \mathbf{p}[\mathbf{t}] \otimes \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}']] * \text{t1} * \text{t2}$$

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{p}[\mathbf{t}] \otimes \mathbf{q}[\mathbf{t}']] * \text{t1} * \text{t2}$$

$$\alpha \leftarrow \mathbf{n}[\gamma \otimes \mathbf{q}[\mathbf{t}']] \otimes \mathbf{p}[\mathbf{t}] * \text{t1} * \text{t2}$$

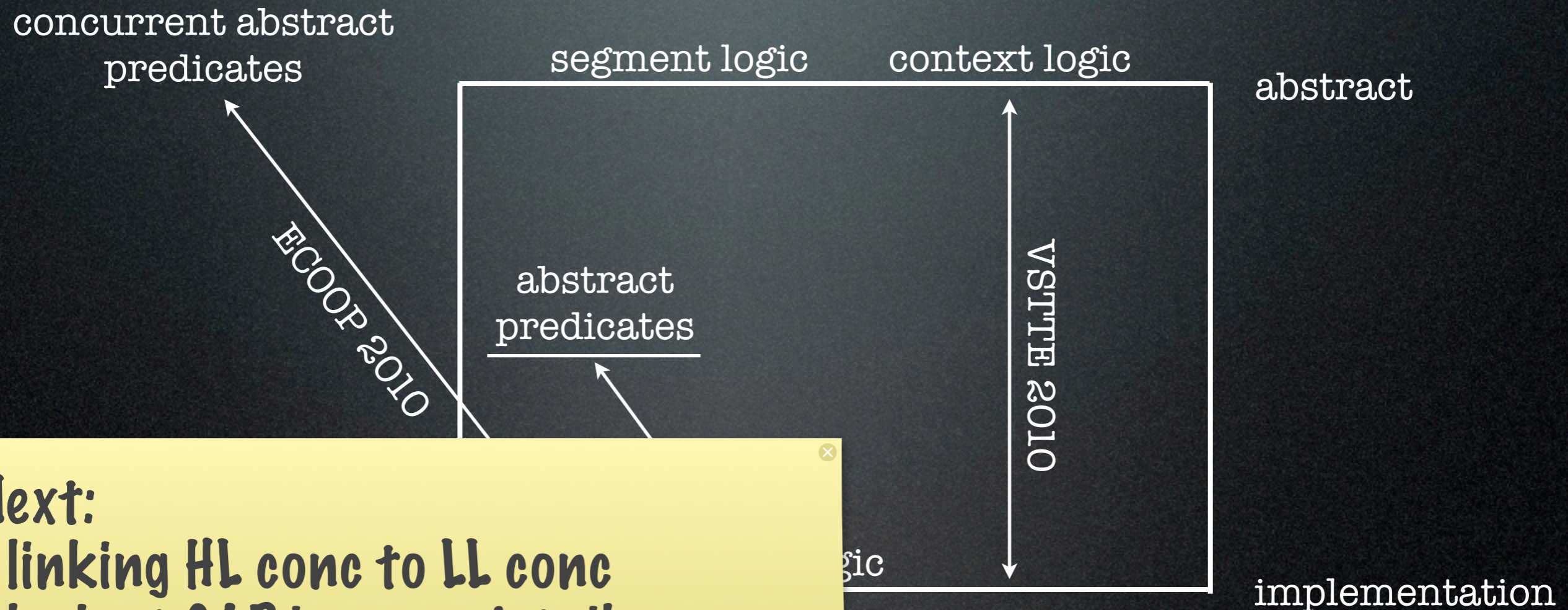
Adding Tokens



Adding Tokens



Abstraction Levels



Next:

- linking HL conc to LL conc
- look at CAP in more detail
- Dynamic Lock Creation
- Automated Invariant Generation