

# **Inductive Learning of Answer Set Programs**

**Mark Law, Alessandra Russo and Krysia Broda**

# Inductive Logic Programming

The task of Inductive Logic Programming (ILP) is to find a hypothesis  $H$  which “explains” a set of positive and negative examples ( $E^+$  and  $E^-$ ) with respect to a background knowledge  $B$ .

The work on nonmonotonic ILP under the Answer Set/Stable Model semantics has mostly been limited to learning normal logic programs and is usually restricted to **either** brave **or** cautious reasoning.

Our new learning task, Learning from Answer Sets, incorporates **both** brave **and** cautious reasoning with the aim of learning Answer Set Programs containing normal rules, choice rules and constraints.

## Sudoku Example

*+ve*

4		1	2
2			
		4	1
1			3

(a)

*-ve*

		3	
2			
	3		
1		1	

(b)

*-ve*

1		4	
	2	3	
			1
1			2

(c)

*complete*

4	3	1	2
2	1	3	4
3	2	4	1
1	4	2	3

(d)

```

1 { value(1, C), value(2, C), value(3, C), value(4, C) } 1 :- cell(C).
:- value(V, C1), value(V, C2), same_row(C1, C2).
:- value(V, C1), value(V, C2), same_block(C1, C2).
:- value(V, C1), value(V, C2), same_col(C1, C2).
  
```

## Comparison with related works under the Answer Set semantics

Learning Task	Normal Rules	Choice Rules	Constraints	Classical negation	Brave	Cautious	Algorithm for optimal solutions
<i>Brave Induction</i> [Sakama, Inoue 2009]	✓	✓	✗	✓	✓	✗	✗
<i>Cautious Induction</i> [Sakama, Inoue 2009]	✓	✓	✗	✓	✗	✓	✗
<i>XHAIL</i> [Ray 2009] & ASPAL [Corapi, Russo, Lupu 2011]	✓	✗	✗	✗	✓	✗	✓
<i>Induction of Stable Models</i> [Otero 2001]	✓	✗	✗	✗	✓	✗	✗
<i>Induction from Answer Sets</i> [Sakama 2005]	✓	✗	✓	✓	✓	✓	✗
LAS	✓	✓	✓	✗	✓	✓	✓

## Learning from Answer Sets

A partial interpretation  $E$  is a pair of sets of atoms  $\langle E^{inc}, E^{exc} \rangle$  called the *inclusions* and *exclusions* respectively.

An Answer Set  $A$  *extends*  $\langle E^{inc}, E^{exc} \rangle$  if and only if:  $E^{inc} \subseteq A$  and  $E^{exc} \cap A = \emptyset$ .

A *Learning from Answer Sets task* is a tuple  $T = \langle B, S_M, E^+, E^- \rangle$  where  $B$  is an ASP program,  $S_M$  is the search space defined by a language bias  $M$ ,  $E^+$  and  $E^-$  are sets of partial interpretations.

A hypothesis  $H \in ILP_{LAS} \langle B, S_M, E^+, E^- \rangle$  if and only if:

1.  $H \subseteq S_M$
2.  $\forall e^+ \in E^+ \exists A \in AS(B \cup H)$  st  $A$  extends  $e^+$
3.  $\forall e^- \in E^- \nexists A \in AS(B \cup H)$  st  $A$  extends  $e^-$

## Inductive Learning of Answer Set Programs

A hypothesis  $H \in \text{positive\_solutions}\langle B, S_M, E^+, E^- \rangle$  if and only if:

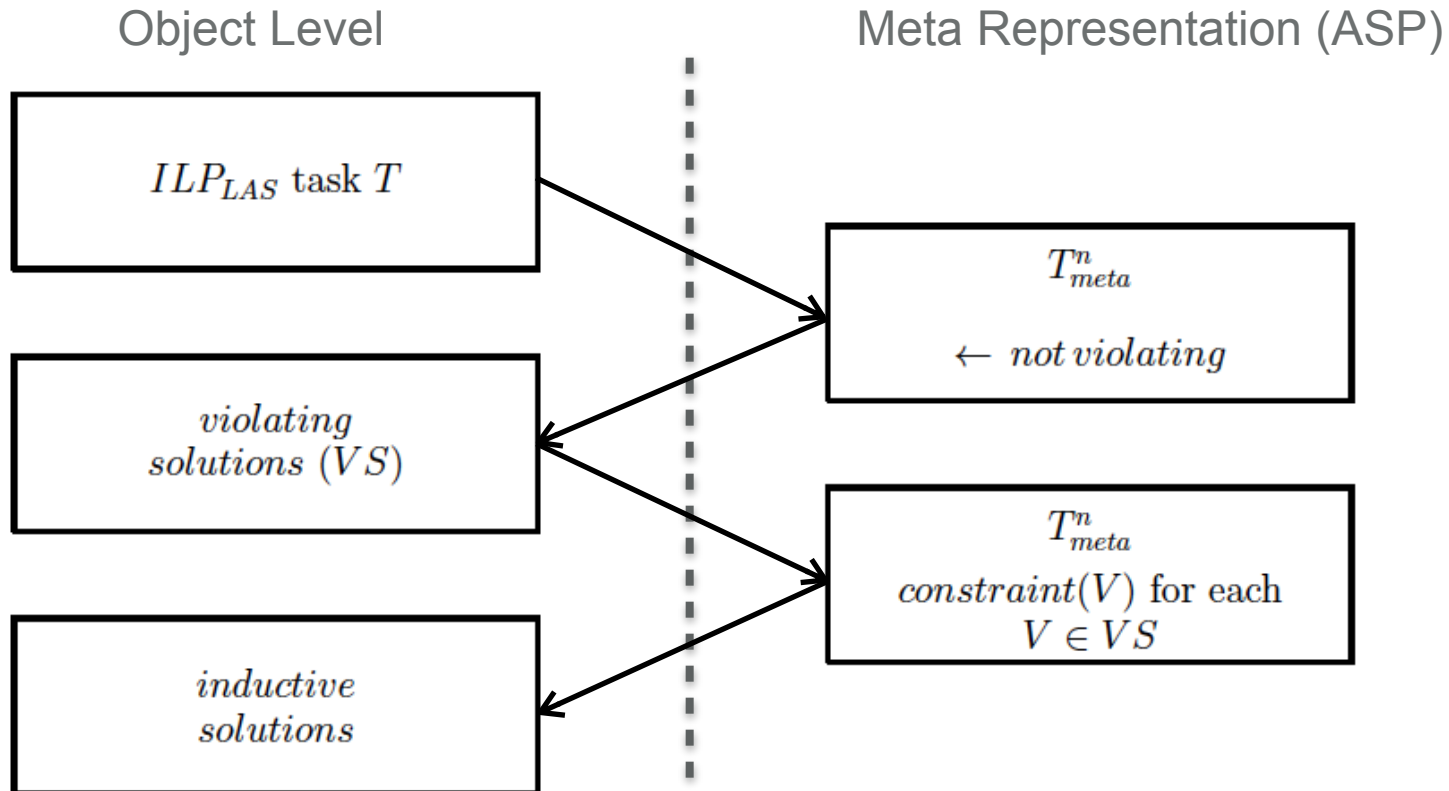
1.  $H \subseteq S_M$
2.  $\forall e^+ \in E^+ \exists A \in AS(B \cup H)$  st  $A$  extends  $e^+$

A hypothesis  $H \in \text{violating\_solutions}\langle B, S_M, E^+, E^- \rangle$  if and only if:

1.  $H \subseteq S_M$
2.  $\forall e^+ \in E^+ \exists A \in AS(B \cup H)$  st  $A$  extends  $e^+$
3.  $\exists e^- \in E^- \exists A \in AS(B \cup H)$  st  $A$  extends  $e^-$

$$\begin{aligned} ILP_{LAS}\langle B, S_M, E^+, E^- \rangle \\ = \text{positive\_solutions}\langle B, S_M, E^+, E^- \rangle \setminus \text{violating\_solutions}\langle B, S_M, E^+, E^- \rangle \end{aligned}$$

# Inductive Learning of Answer Sets



$n$ : a given hypothesis length

$T_{meta}^n$ : ASP task program (a meta representation of the task  $T$ )

## Inductive Learning of Answer Sets

---

### Algorithm 1 ILASP

---

```
procedure ILASP( $T$ )  
   $solutions = []$   
  for  $n = 0$ ;  $solutions.empty$ ;  $n++$  do  
     $vs = AS(T_{meta}^n \cup \{\leftarrow \text{not violating}; \text{ex(negative).}\})$   
     $ps = AS(T_{meta}^n \cup \{\text{constraint}(meta^{-1}(V)) : V \in vs\})$   
     $solutions = \{meta^{-1}(A) : A \in ps\}$   
  end for  
  return  $solutions$   
end procedure
```

---

$T_{meta}^n$ : ASP task program (a meta representation of the task  $T$ )

$vs$ : violating solutions

$ps$ : positive solutions



## Comparison with related works

$$ILP_{brave}\langle B, E \rangle$$



$$ILP_{ASPAL/XHAIL}\langle B, \langle E, \emptyset \rangle \rangle$$

---

$$ILP_{ASPAL/XHAIL}\langle B, \langle E^+, E^- \rangle \rangle$$



$$ILP_{stable\_models}\langle B, \{ \langle E^+, E^- \rangle \} \rangle$$

---

$$ILP_{stable\_models}\langle B, \{ \langle E_1^+, E_1^- \rangle \dots \{ \langle E_n^+, E_n^- \rangle \} \} \rangle$$



$$ILP_{LAS}\langle B, \{ \langle E_1^+, E_1^- \rangle \dots \{ \langle E_n^+, E_n^- \rangle \}, \emptyset \} \rangle$$

---

$$ILP_{LAS}\langle B, E^+, E^- \rangle$$

## Comparison with related works

$$ILP_{cautious} \langle B, \{e_1, \dots, e_n\} \rangle$$



$$ILP_{LAS} \langle B, \emptyset, \{ \langle \emptyset, \{e_1\} \rangle \dots \langle \emptyset, \{e_n\} \rangle \} \rangle$$

## Current work: modification of ILASP

- For some classes of problem there could be many violating solutions before we find an inductive solution.
- The sudoku example is one such problem, with 413044 before the first inductive solution it takes over 14 minutes to solve with ILASP.
- In fact, many of these are violating for the same reason (they share Answer Sets which extend negative examples).
- With our new system based on ruling out classes of hypothesis, we need only 7 classes and the problem is solved in less than a second.

## Other current work

- Expand the subset of ASP that we can learn
  - conditions, weighted aggregates etc.
  - weak constraints/optimisation statements
- Real applications
  - Ideally not achievable by other ILP tasks
  - Will motivate the work from a practical point of view
  - Measure the accuracy of the learning task