COMP50006 Compilers - Exercise 4: Register allocation using graph colouring

Introduction

The idea of using graph colouring for register allocation is covered at the end of Chapter 5 of the lecture notes. However, a good way to understand it is to work through this exercise.

Consider the following sequence of assignments:

```
A = 100;
S1:
P1:
      B = 200:
S2:
P2:
S3:
      C = A + B;
P3:
S4:
      D = A * 2;
P4:
S5:
      E = B * 2;
P5:
      F = D - C;
S6:
P6:
      G = E + F;
S7:
P7:
```

We are interested in using registers for all the variables in this code sequence. Notice that we can minimise the number of registers needed by reusing them.

For example, A and F could both be stored in the same register. We don't need a register for F until after the last statement to use A. There are several such instances in this sequence.

Definition: live range

The live range of a variable is the set of program points after which the variable must be safely stored.

Example 1: The live range of A consists of {P1, P2, P3}.

Example 2: The live range of D consists of {P4, P5}

Example 3: The live range of F consists of {P6}.

Subtlety: Can the same register be used for both D and A?

The answer is yes: storage for D is only needed after the value of A has been read. The two live ranges do not intersect.

(as we will see later, $A \in \text{liveIn}(S4)$, and $D \in \text{liveOut}(S4)$).

Definition: interference

Two variables *interfere* if their live ranges overlap.

Example 1: The live ranges of A and F do not overlap.

Example 2: The live ranges of A and B do overlap.

Example 3: The live ranges of A and D do not overlap.

Definition: interference graph

The interference graph for a program consists of

- nodes for each of the variables which have to be allocated to a register (in this example {A, B, C, D, E, F, G}), and
- arcs between each pair of nodes whose live ranges overlap.

Definition: Colouring

A graph colouring is an assignment of colours to nodes. A graph colouring is valid if no pair of nodes which are linked by an arc carry the same colour.

Exercise 4.1: Simple example

Construct the interference graph for the variables A, B, C, D, E, F and G in the example program fragment above. Colour the graph using the minimum possible number of colours, and use this colouring to assign each variable to a register. Give the final code after register allocation.

Exercise 4.2: Register allocation using graph colouring, real example

Consider the following program fragment:

```
VAR A : ARRAY [0..99] OF INTEGER;

PROCEDURE P(i, j, size : INTEGER)

VAR k, tmp : INTEGER;

BEGIN

FOR k := 0 TO size-1 DO

tmp := A[i+k];

A[i+k] := A[j+k];

A[j+k] := tmp;

END

END
```

The compiler's intermediate representation of the body of the procedure is as follows:

```
t1 := size-1
        k := 0
L1:
        cmp k,t1
        bgt End
        t2 := Address(A)+i
        t3 := t2+k
        tmp := LoadIndirect(t3)
        t4 := Address(A)+j
        t5 := t4+k
        t6 := LoadIndirect(t5)
        StoreIndirect(t6, t3)
        StoreIndirect(tmp, t5)
        k := k+1
        jmp L1
End:
```

- 1. Construct the register interference graph for the variables t1, t2, t3, t4, t5, t6, k and tmp.
- 2. Show how the interference graph colouring algorithm can be used to minimise the number of registers needed in this procedure.
- 3. What other possible optimisations are possible in this procedure? Write very brief notes on how such optimisations might be implemented.

Paul Kelly Imperial College January 2023